## Thymio Sensors list: prox.comm.tx {0,2047} total mb sensons: Sensors o prox.comm.rx prox.ground.delta[0-1] =reflected-ambiant prox 10 Hz prox.ground.reflected[0-1] {0...1023} prox.comm.enable(state) {0,1} prox.ground.ambient[0-1] {0...1023} 19 prox.horizontal[0-4] {0...~4300} prox 10 Hz [1] [1] [0] buttons 20 Hz which can be used (0,1) button.forward button.right {0,1} button.right pressed or released button.left {0,1} button.left pressed or released how? co rc5.address button.center {0,1} rc5.command button.center pres temperature [1/10 °C] temperature 1 Hz mic.threshold {0..255} mic.intensity {0..255} button.backward {0,1} button.backward pressed or released mic mic.intensity>mic.threshold sound.record(N) N: {0...32767}, record as 'rN.wav' N=-1, stop recording o acc[0-2] {-32...32}, 23=1g prox.horizontal[5-6] {0...~4300} prox 10 Hz tap shock detected

- + 5 front distance bentions interaction w/ costumes?
  + 2 back distance bentions interaction w/ externol observer (2)
  + 2 ground front bontons
- ① autonomus interaction ② dependent on wer

  \* 5 buttons -> interaction w/ external observer
- \* temperature \* microphone \* accessors moter 3x