

UTN-FRT
TÉCNICAS DIGITALES II
ING. ELECTRÓNICA

SISTEMA DE SEGURIDAD
ALARMA CON COMUNICACIÓN BLUETOOTH

GRUPO 8

Alumnos: Gao, Luciano

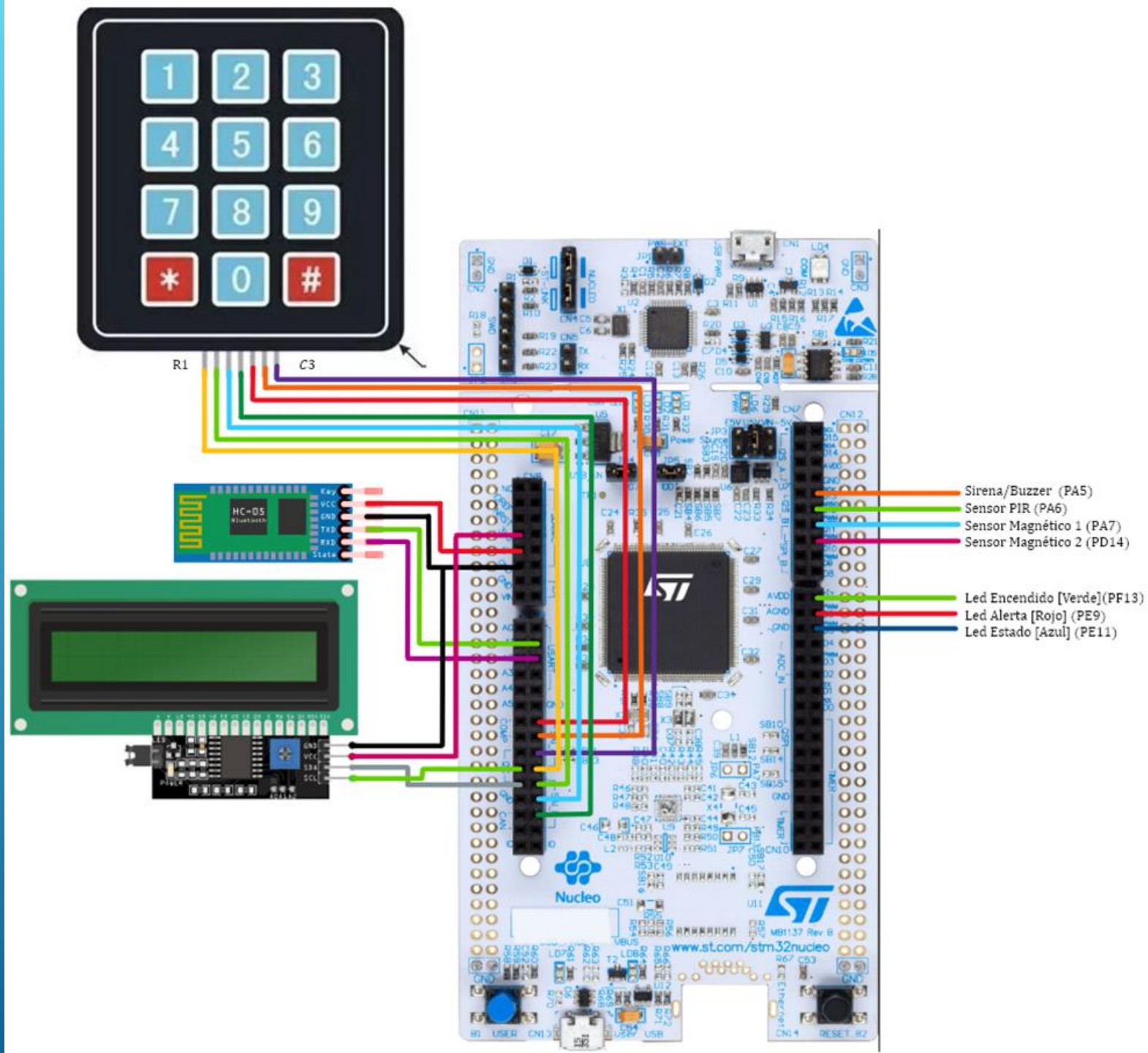
Jorrat, Tomás

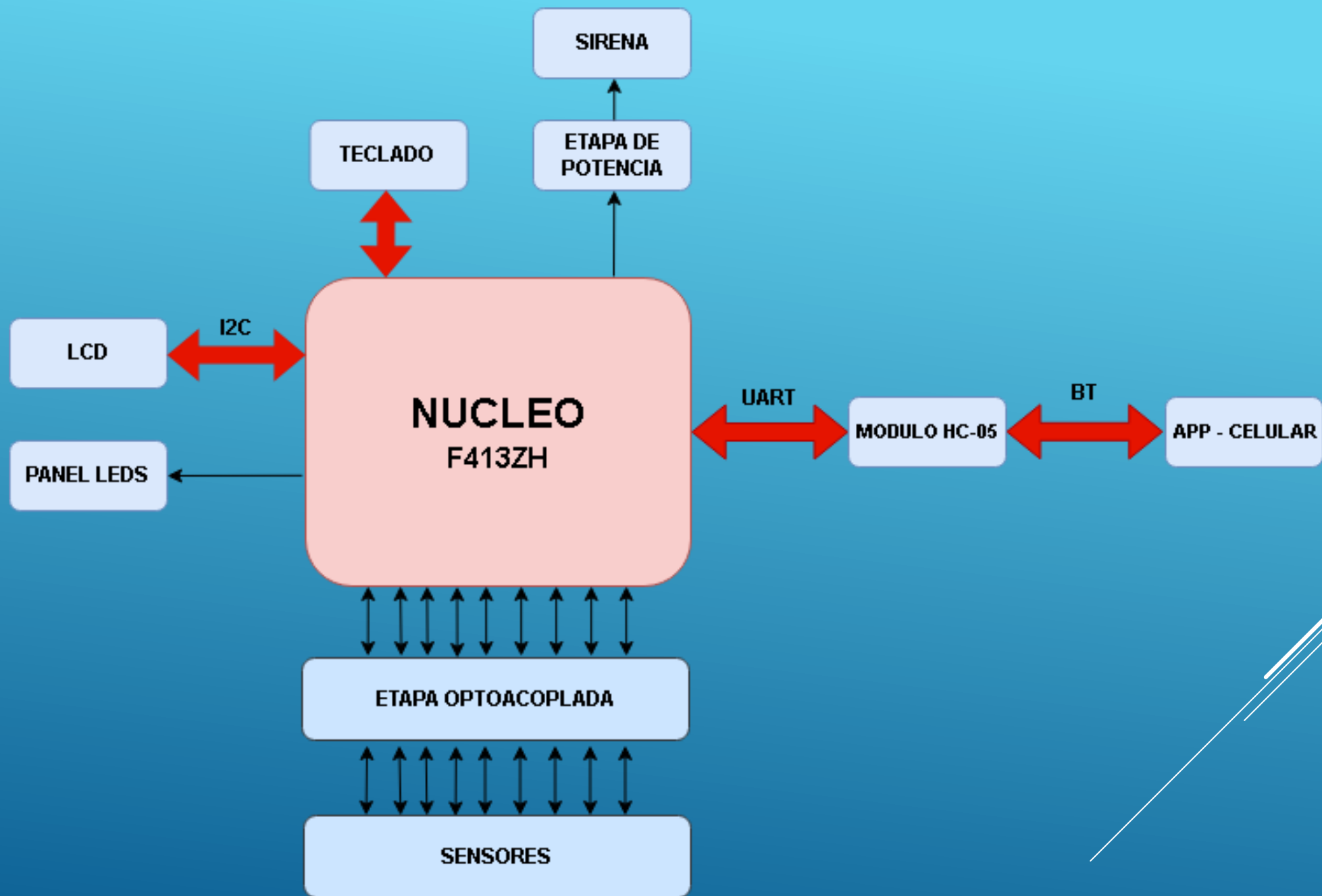
Mitre, Emilio

Profesor: Ing. Mansilla Ruben Dario

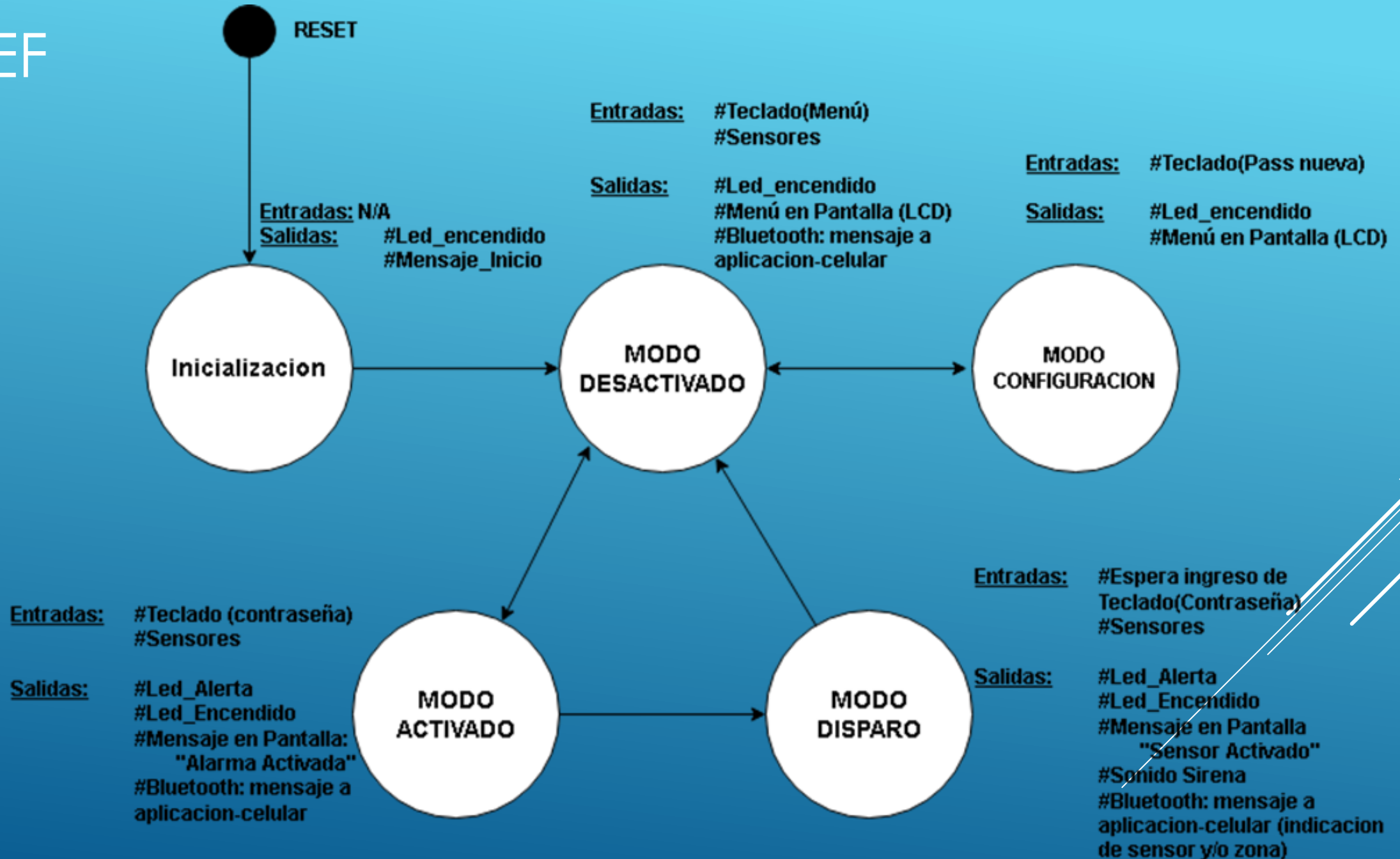
STM32-F413ZH

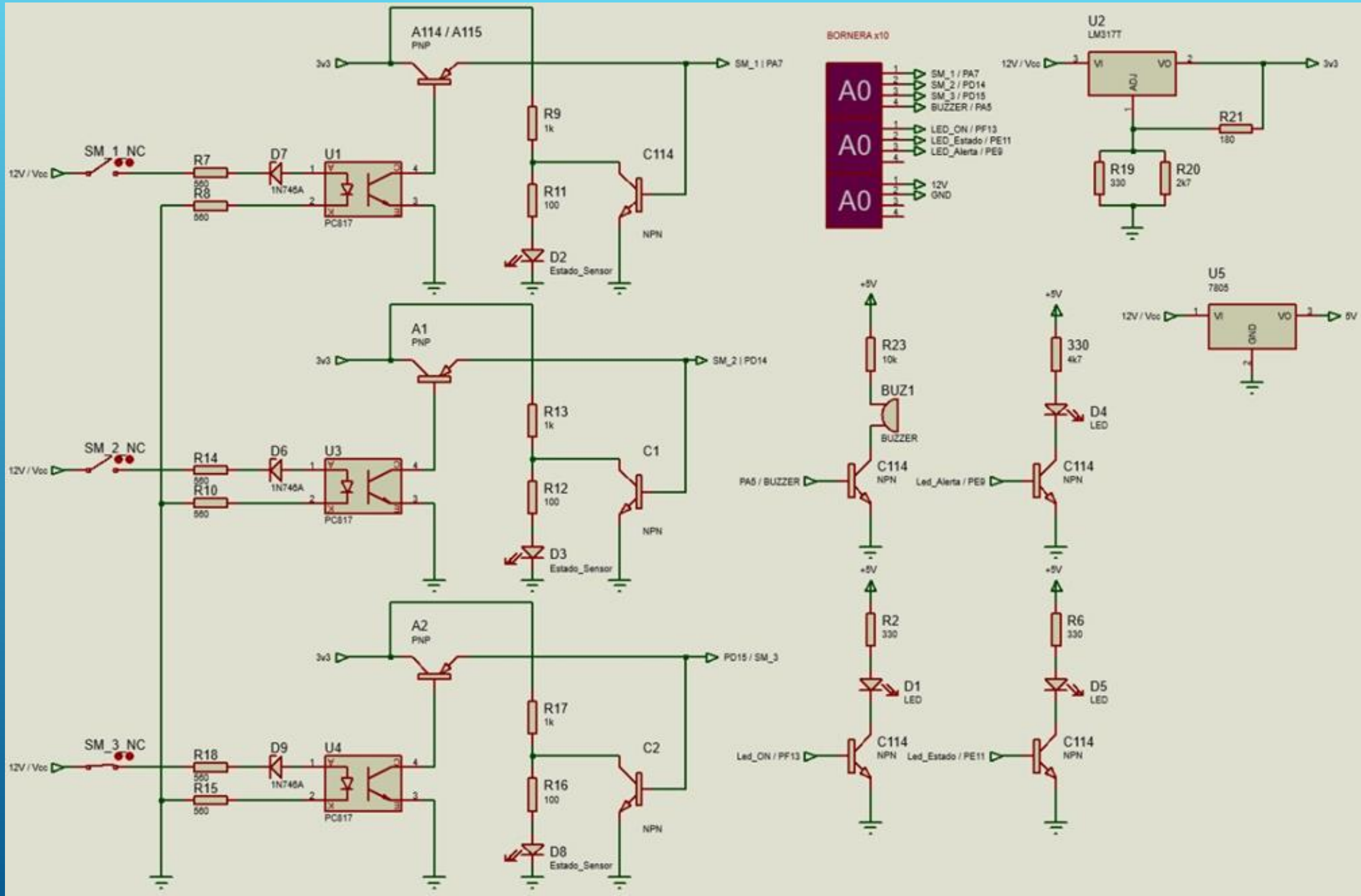
Teclado Matricial 4x3
Modulo Bluetooth HC-05
Pantalla LCD 16x2 - PCF8574
Sensor PIR HC-SR501
Sensor Magnético MS-14-BL

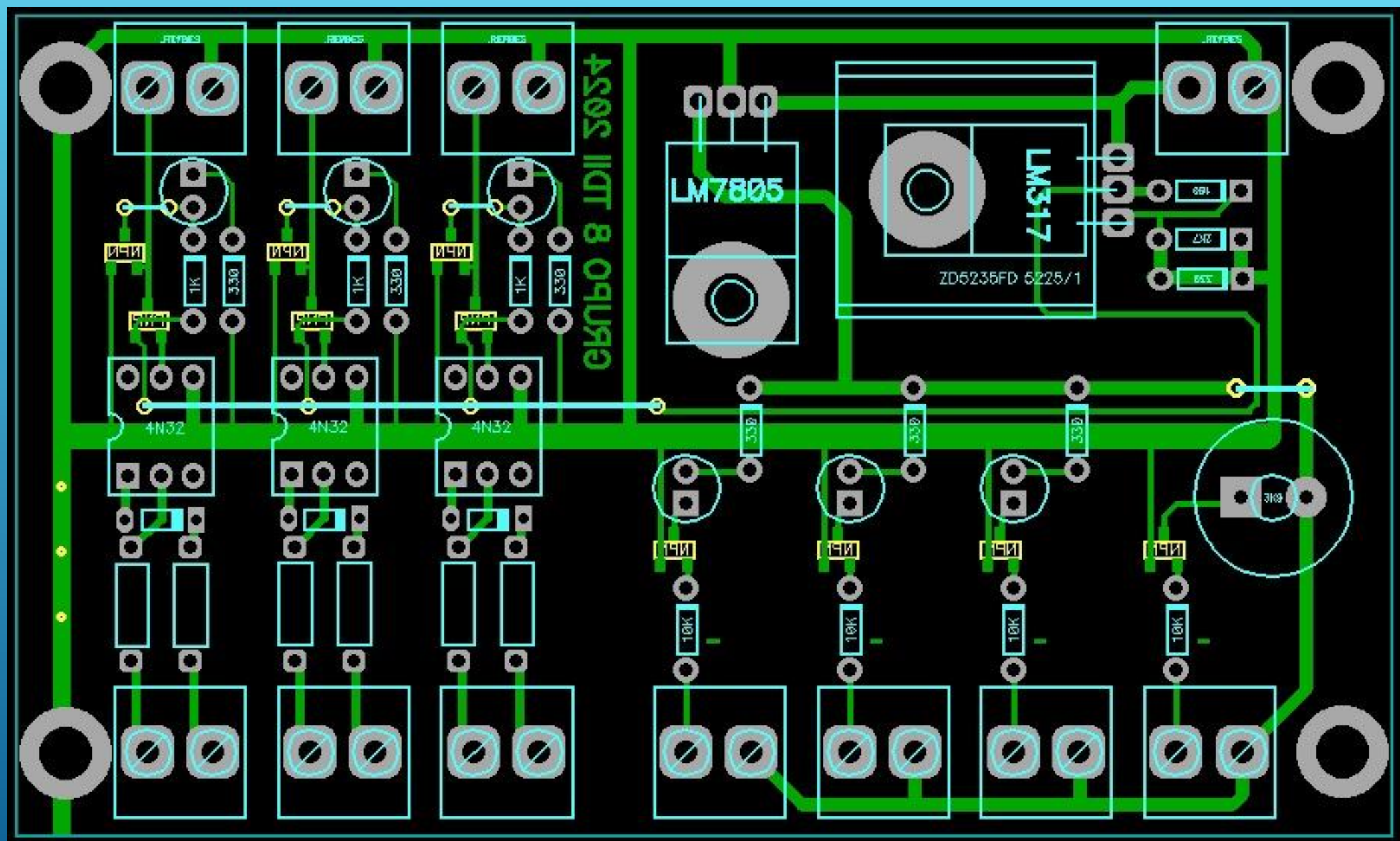




MEF







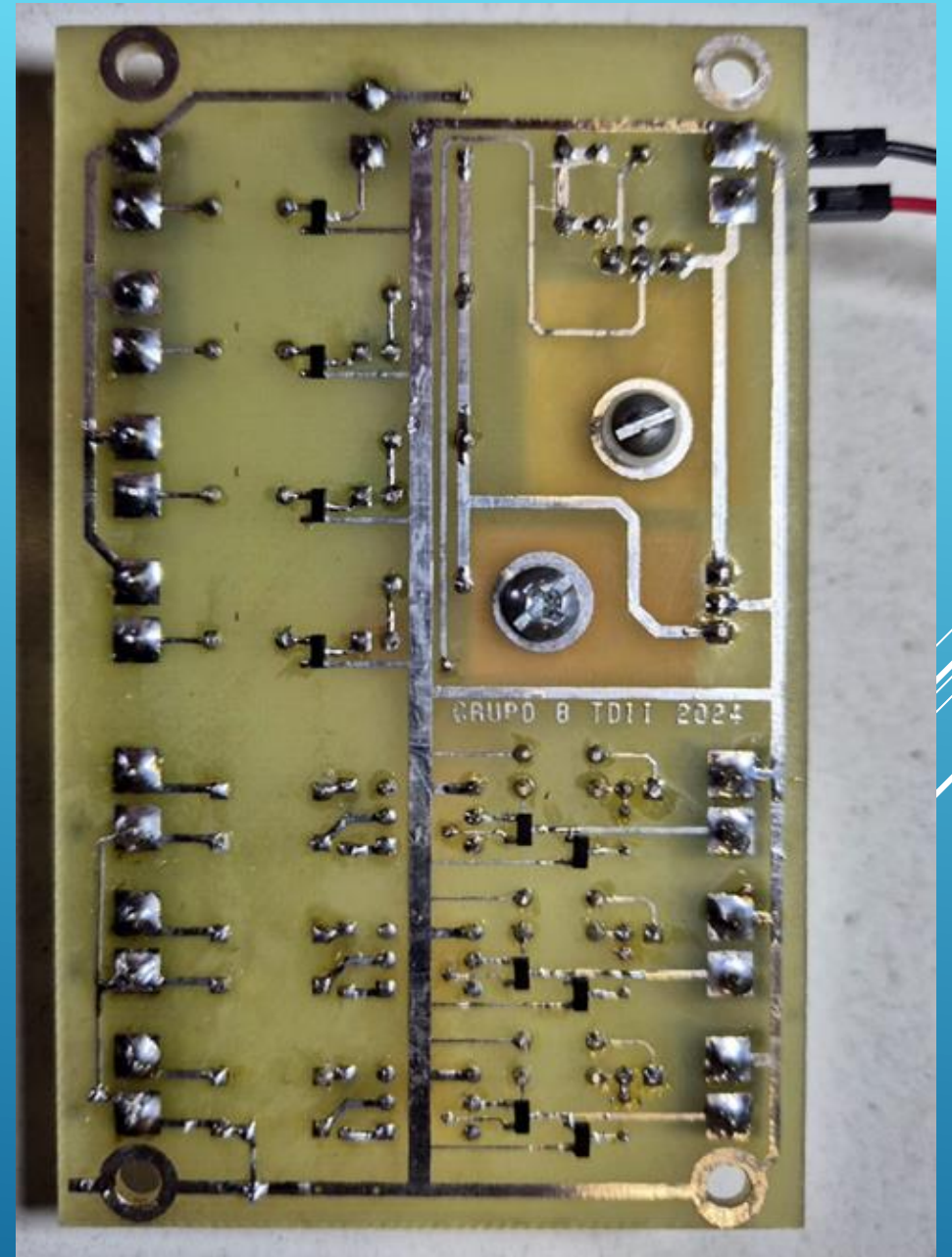
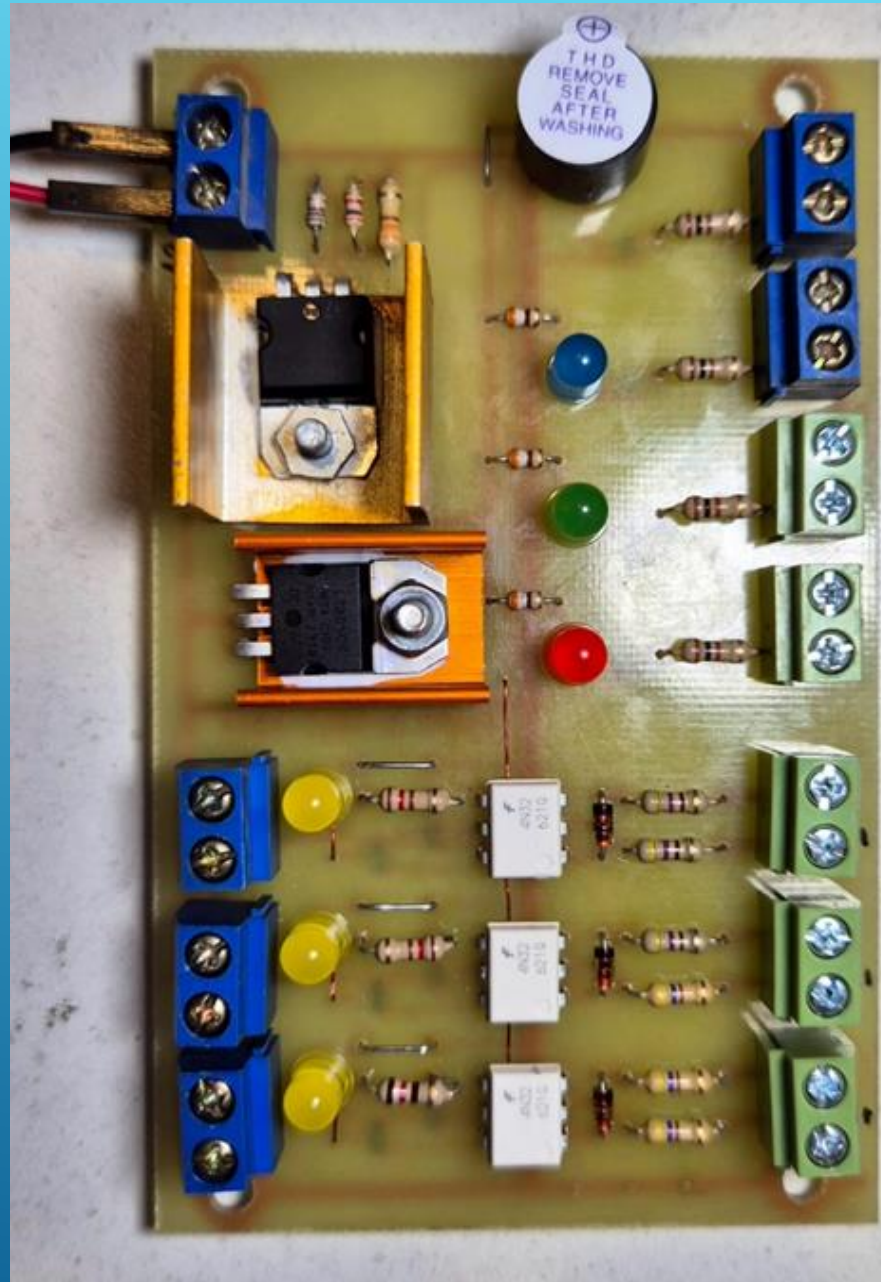
PCB:

Sensores Magneticos

Sensor PIR

Buzzer

Leds de estado

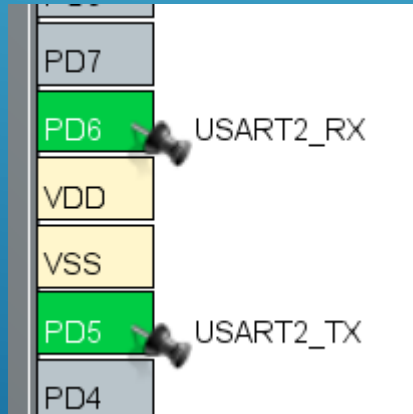


CONFIGURACIÓN DE PINES I/O

PA6	n/a	n/a	Input mode	No pull-up and no ...	n/a	Sensor_PIR
PA7	n/a	n/a	Input mode	No pull-up and no ...	n/a	Sensor_Magnetico_1
PD14	n/a	n/a	Input mode	No pull-up and no ...	n/a	Sensor_Magnetico_2
PE2	n/a	n/a	Input mode	Pull-up	n/a	C1
PE4	n/a	n/a	Input mode	Pull-up	n/a	C2
PE5	n/a	n/a	Input mode	Pull-up	n/a	C3
PB0	n/a	Low	Output Push Pull	No pull-up and no ...	Low	LD1 [Green]
PB7	n/a	Low	Output Push Pull	No pull-up and no ...	Low	LD2 [Blue]
PB14	n/a	Low	Output Push Pull	No pull-up and no ...	Low	LD3 [Red]
PE9	n/a	Low	Output Push Pull	No pull-up and no ...	Low	Led_Alerta [Red]
PF13	n/a	Low	Output Push Pull	No pull-up and no ...	Low	Led_Encendido [Green]
PE11	n/a	Low	Output Push Pull	No pull-up and no ...	Low	Led_Estado [Blue]
PE6	n/a	High	Output Push Pull	No pull-up and no ...	Low	R1
PE3	n/a	High	Output Push Pull	No pull-up and no ...	Low	R2
PF8	n/a	High	Output Push Pull	No pull-up and no ...	Low	R3
PF7	n/a	High	Output Push Pull	No pull-up and no ...	Low	R4
PA5	n/a	Low	Output Push Pull	Pull-down	Low	Sirena

CONFIGURACIÓN DE MÓDULOS – USART2 - I2C2

I2C2_SDA PF0
I2C2_SCL PF1



Mode Asynchronous

Hardware Flow Control (RS232) Disable

Master Features

I2C Speed Mode Standard Mode
I2C Clock Speed (Hz) 100000

Slave Features

Clock No Stretch Mode Disabled
Primary Address Length selection 7-bit
Dual Address Acknowledged Disabled
Primary slave address 0
General Call address detection Disabled

Basic Parameters

Baud Rate 9600 Bits/s
Word Length 8 Bits (including Parity)
Parity None
Stop Bits 1

Advanced Parameters

Data Direction Receive and Transmit
Over Sampling 16 Samples

SOFTWARE – MAIN.C

```
while (1)
{
    key = keypad_getkey();
    switch (currentState){
        case MAIN_MENU:
            if (key != '\0') HandleMainMenuInput(key);
            break;
        case ALARM_MENU:
            if (key != '\0') HandleAlarmMenuInput(key);
            break;
        case CHANGE_PASS_MENU:
        case TEST_ALARM_MENU:
        case ACTIVE_ALARM:
            CheckSensors();
            break;
    }
    /* USER CODE END WHILE */

    /* USER CODE BEGIN 3 */
}
/* USER CODE END 3 */
```

```
/* USER CODE BEGIN PFP */
void DisplayMainMenu();
void HandleMainMenuInput(char key);
void DisplayAlarmMenu();
void HandleAlarmMenuInput(char key);
void RequestPassword(void (*onSuccess)(void), void (*onFailure)(void));
void ActivateAlarm();
void DeactivateAlarm();
void DisplayChangePassMenu();
void ConfirmNewPassword();
void HandleSubMenu();
void TestAlarm();
extern void AlarmTriggered();
void IncorrectPassword();
void HandleActiveAlarm(char key);
void CheckSensors();
void CheckAlarmDeactivation(char key);
```

```
// Menu Principal
// Manejo del menu principal
// Menu de activacion de alarma
// Manejo del menu de activacion de alarma
// Pedir la contraseña
// Secuencia de activacion
// Secuencia de desactivacion
// Menu de cambio de contraseña
// Contraseña nueva
// Submenu del principal
// Prueba de alarma
// Disparo de alarma
// Contraseña incorrecta
// Manejo de la activacion de la alarma
// Control del estado de sensores
// Control para desactivar la alarma
```

1. Activar *.Mas
2. Cambiar Pass

#. Volver
3. Prueba

1. Sist. Completo
2. Sin sensor Mov

API_BT

```

/*****
 * @brief:  Enviar un mensaje a HC-05
 * @param:  char message (cadena de carecteres)
 * @retval: void
 *****/

void BT_SendMessage(char *message) {
    HAL_UART_Transmit(&huart2, (uint8_t *)message, strlen(message), HAL_MAX_DELAY);
}

```

```
BT_SendMessage("🚨 Alarma activada! \r\n");
```

API_KEYPAD

```
char keypad_getkey() {
    for (int i = 0; i < ROWS; i++) {
        // Poner todas las filas en alto excepto la actual
        for (int k = 0; k < ROWS; k++) {
            HAL_GPIO_WritePin(rowPorts[k], rowPins[k], (i == k) ? GPIO_PIN_RESET : GPIO_PIN_SET);
        }

        // Leer columnas
        for (int j = 0; j < COLS; j++) {
            if (HAL_GPIO_ReadPin(colPorts[j], colPins[j]) == GPIO_PIN_RESET) {
                HAL_Delay(50); // Anti-rebote
                while (HAL_GPIO_ReadPin(colPorts[j], colPins[j]) == GPIO_PIN_RESET);
                return keymap[i][j];
            }
        }
    }
    return '\0'; // No se presionó ninguna tecla
}
```

```
key = keypad_getkey();
if (key != '\0') {
    if (key == '*') { // Si presiona "*", vuelve al menú principal
        lcd_clear();
        lcd_set_cursor(0, 0);
        lcd_print("Operacion");
        lcd_set_cursor(1, 0);
        lcd_print("Cancelada");
        while(!delayRead(&LCD_Muestro)){
            // Espacio para ejecutar tareas mientras muestra el mensaje anterior
        }
        DisplayMainMenu(); // Volver al menú principal
        return;
    }
    if (key >= '0' && key <= '9' && inputIndex < 4) {
        inputBuffer[inputIndex++] = key;
        lcd_set_cursor(1, 10 + inputIndex - 1);
        lcd_print("*");
    } else if (key == '#') { // Cuando se presiona "#", verifica la clave
```


FIN

- ▶ Repositorio GRUPO 8:
https://github.com/TomasJorrat/AFP_5_GRUPO_8_2024
- ▶ https://github.com/emiliomitre/Grupo_8_TDII_2024