

UTN-FRT
TÉCNICAS DIGITALES II
ING. ELECTRÓNICA

SISTEMA DE SEGURIDAD
ALARMA CON COMUNICACIÓN BLUETOOTH

GRUPO 8

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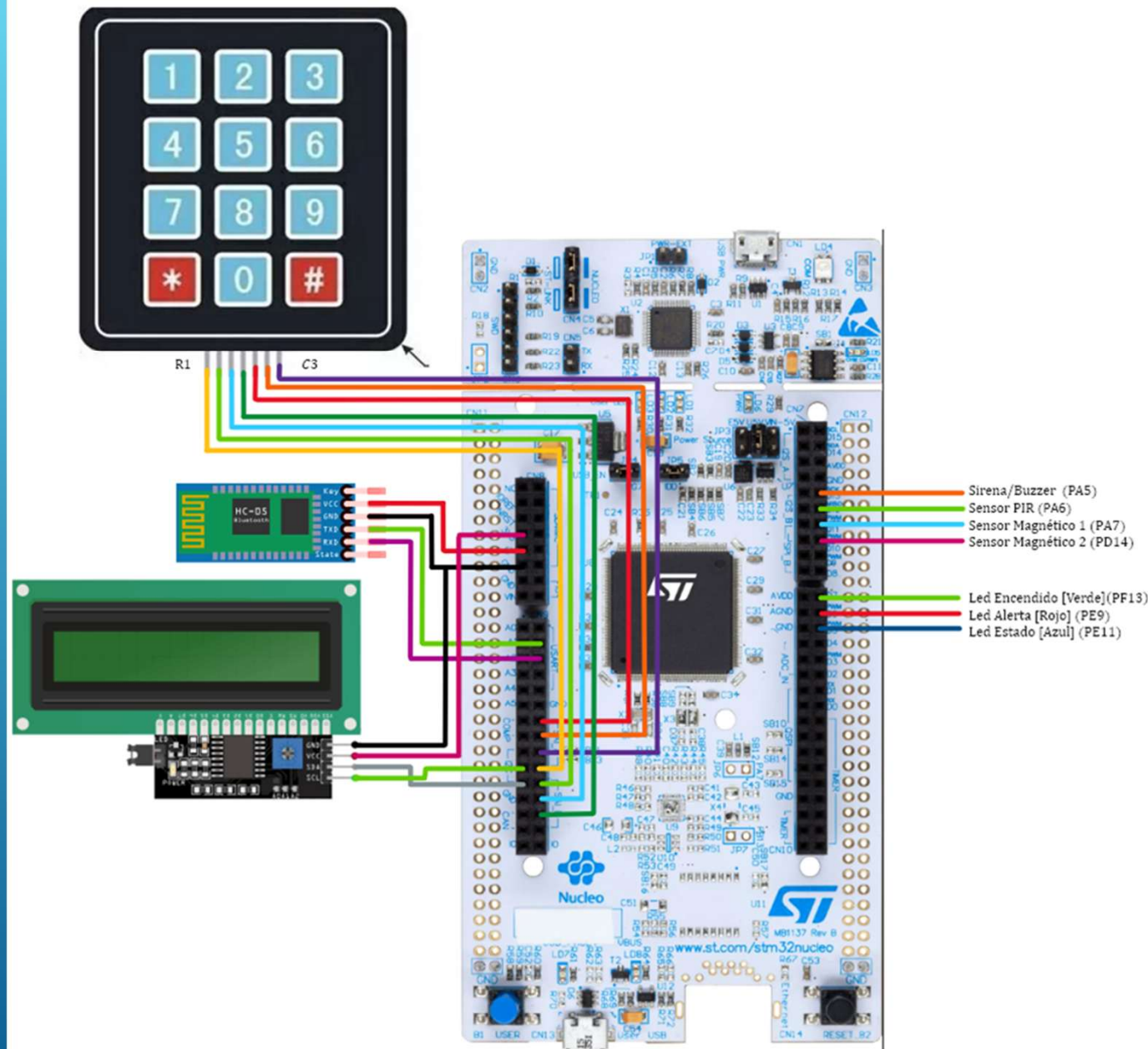
Profesor: Ing. Mansilla Ruben Dario

STM32-F413ZH

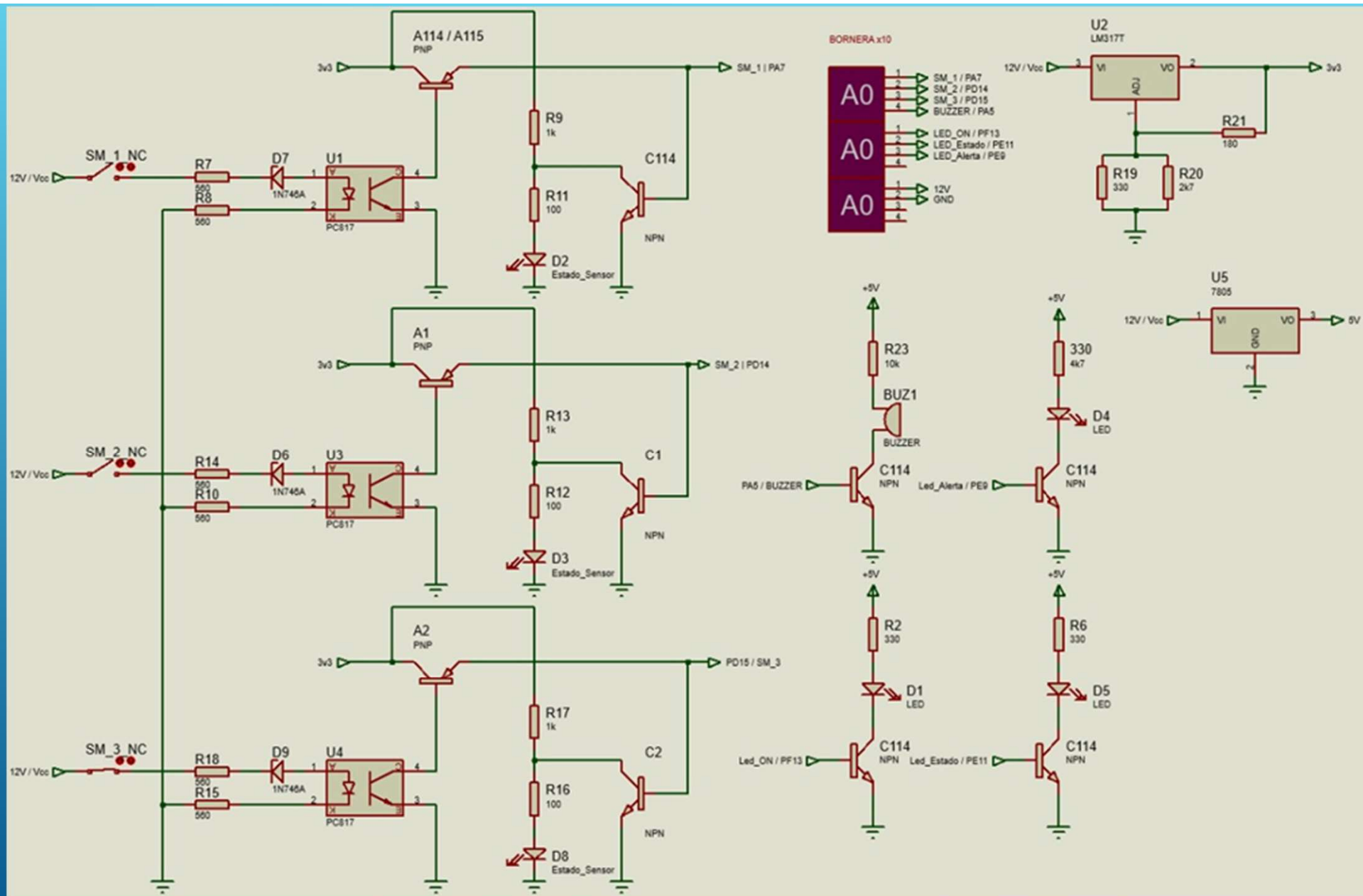
Teclado Matricial 4x3

Modulo Bluetooth HC-05

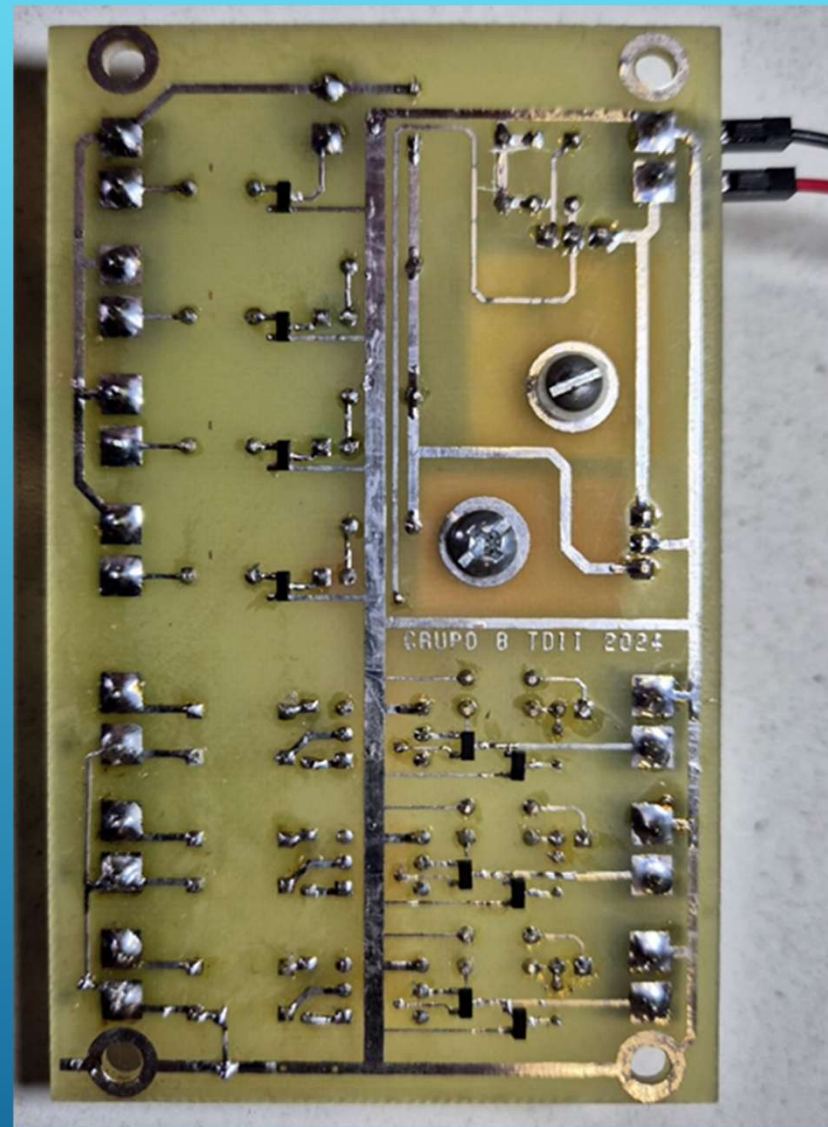
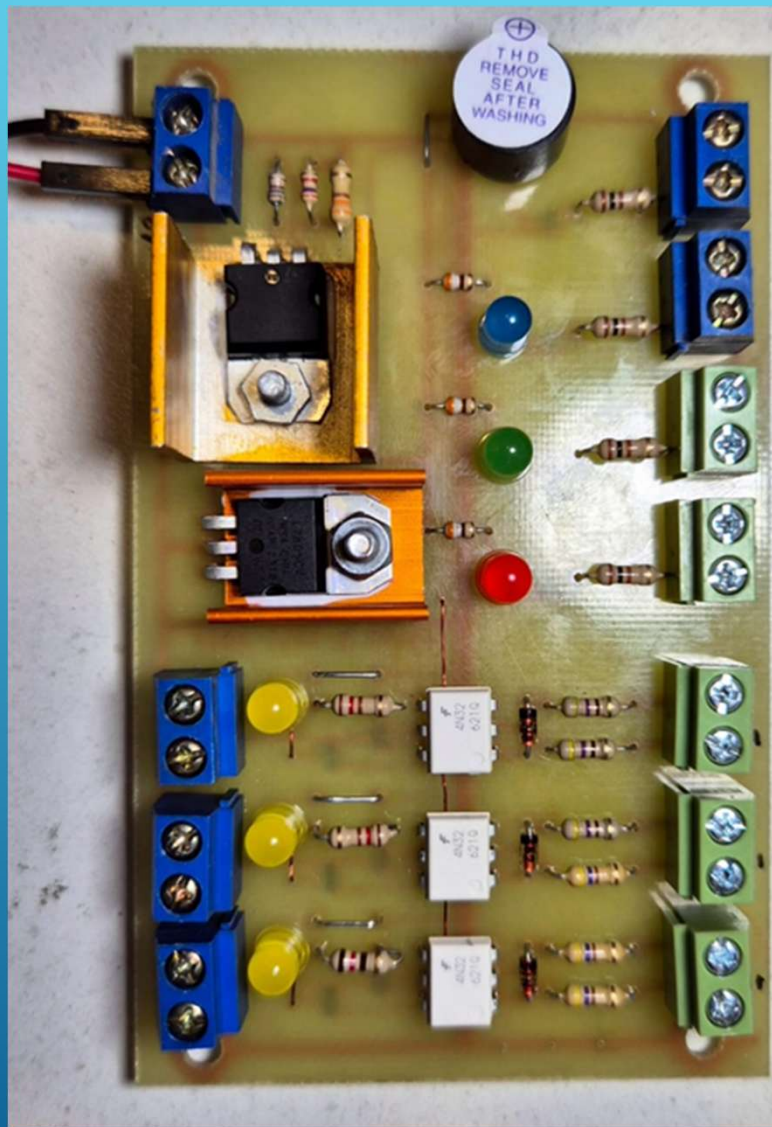
Pantalla LCD 16x2 - PCF8574



PCB



Sensores Magneticos
Sensor PIR
Buzzer
Leds de estado



CONFIGURACIÓN DE PINES I/O

| | | | | | | |
|------|-----|------|------------------|-----------------------|-----|-----------------------|
| PA6 | n/a | n/a | Input mode | No pull-up and no ... | n/a | Sensor_PIR |
| PA7 | n/a | n/a | Input mode | No pull-up and no ... | n/a | Sensor_Magnetico_1 |
| PD14 | n/a | n/a | Input mode | No pull-up and no ... | n/a | Sensor_Magnetico_2 |
| PE2 | n/a | n/a | Input mode | Pull-up | n/a | C1 |
| PE4 | n/a | n/a | Input mode | Pull-up | n/a | C2 |
| PE5 | n/a | n/a | Input mode | Pull-up | n/a | C3 |
| PB0 | n/a | Low | Output Push Pull | No pull-up and no ... | Low | LD1 [Green] |
| PB7 | n/a | Low | Output Push Pull | No pull-up and no ... | Low | LD2 [Blue] |
| PB14 | n/a | Low | Output Push Pull | No pull-up and no ... | Low | LD3 [Red] |
| PE9 | n/a | Low | Output Push Pull | No pull-up and no ... | Low | Led_Alerta [Red] |
| PF13 | n/a | Low | Output Push Pull | No pull-up and no ... | Low | Led_Encendido [Green] |
| PE11 | n/a | Low | Output Push Pull | No pull-up and no ... | Low | Led_Estado [Blue] |
| PE6 | n/a | High | Output Push Pull | No pull-up and no ... | Low | R1 |
| PE3 | n/a | High | Output Push Pull | No pull-up and no ... | Low | R2 |
| PF8 | n/a | High | Output Push Pull | No pull-up and no ... | Low | R3 |
| PF7 | n/a | High | Output Push Pull | No pull-up and no ... | Low | R4 |
| PA5 | n/a | Low | Output Push Pull | Pull-down | Low | Sirena |

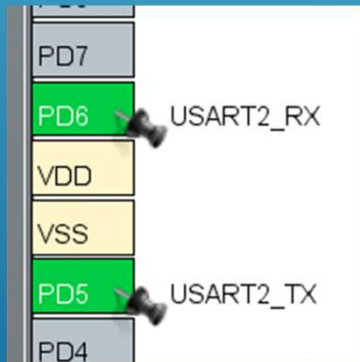
CONFIGURACIÓN DE MÓDULOS – USART2 - I2C2

I2C2_SDA

PF0

I2C2_SCL

PF1



Mode Asynchronous

Hardware Flow Control (RS232) Disable

Master Features

I2C Speed Mode

Standard Mode

I2C Clock Speed (Hz)

100000

Slave Features

Clock No Stretch Mode

Disabled

Primary Address Length selection

7-bit

Dual Address Acknowledged

Disabled

Primary slave address

0

General Call address detection

Disabled

Basic Parameters

Baud Rate

9600 Bits/s

Word Length

8 Bits (including Parity)

Parity

None

Stop Bits

1

Advanced Parameters

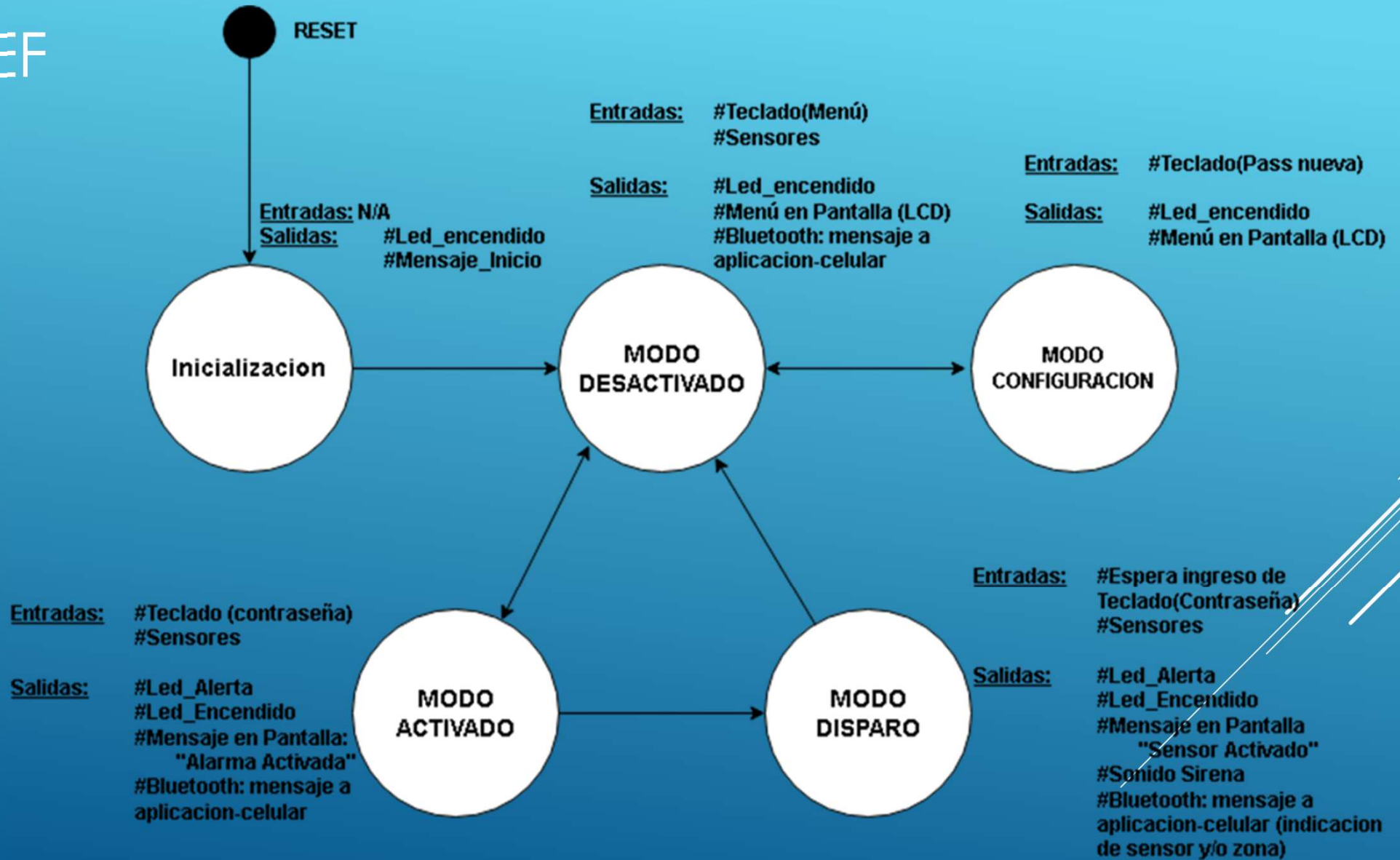
Data Direction

Receive and Transmit

Over Sampling

16 Samples

MEF



SOFTWARE – MAIN.C

```
while (1)
{
    key = keypad_getkey();
    switch (currentState){
        case MAIN_MENU:
            if (key != '\0') HandleMainMenuInput(key);
            break;
        case ALARM_MENU:
            if (key != '\0') HandleAlarmMenuInput(key);
            break;
        case CHANGE_PASS_MENU:
        case TEST_ALARM_MENU:
        case ACTIVE_ALARM:
            CheckSensors();
            break;
    }
    /* USER CODE END WHILE */

    /* USER CODE BEGIN 3 */
}
/* USER CODE END 3 */
```

```
/* USER CODE BEGIN PFP */
void DisplayMainMenu();
void HandleMainMenuInput(char key);
void DisplayAlarmMenu();
void HandleAlarmMenuInput(char key);
void RequestPassword(void (*onSuccess)(void), void (*onFailure)(void));
void ActivateAlarm();
void DeactivateAlarm();
void DisplayChangePassMenu();
void ConfirmNewPassword();
void HandleSubMenu();
void TestAlarm();
extern void AlarmTriggered();
void IncorrectPassword();
void HandleActiveAlarm(char key);
void CheckSensors();
void CheckAlarmDeactivation(char key);
```

```
// Menu Principal
// Manejo del menu principal
// Menu de activacion de alarma
// Manejo del menu de activacion de alarma
// Pedir la contraseña
// Secuencia de activacion
// Secuencia de desactivacion
// Menu de cambio de contraseña
// Contraseña nueva
// Submenu del principal
// Prueba de alarma
// Disparo de alarma
// Contraseña incorrecta
// Manejo de la activacion de la alarma
// Control del estado de sensores
// Control para desactivar la alarma
```


API_BT

```
/* *****  
 * @brief:  Enviar un mensaje a HC-05  
 * @param:  char message (cadena de carecteres)  
 * @retval: void  
 * *****  
  
void BT_SendMessage(char *message) {  
    HAL_UART_Transmit(&huart2, (uint8_t *)message, strlen(message), HAL_MAX_DELAY);  
}
```

```
BT_SendMessage("🚨 Alarma activada! \r\n");
```

API_KEYPAD

```
char keypad_getkey() {  
    for (int i = 0; i < ROWS; i++) {  
        // Poner todas las filas en alto excepto la actual  
        for (int k = 0; k < ROWS; k++) {  
            HAL_GPIO_WritePin(rowPorts[k], rowPins[k], (i == k) ? GPIO_PIN_RESET : GPIO_PIN_SET);  
        }  
  
        // Leer columnas  
        for (int j = 0; j < COLS; j++) {  
            if (HAL_GPIO_ReadPin(colPorts[j], colPins[j]) == GPIO_PIN_RESET) {  
                HAL_Delay(50); // Anti-rebote  
                while (HAL_GPIO_ReadPin(colPorts[j], colPins[j]) == GPIO_PIN_RESET);  
                return keymap[i][j];  
            }  
        }  
    }  
    return '\0'; // No se presionó ninguna tecla  
}
```

```

key = keypad_getkey();
if (key != '\0') {
    if (key == '*') {                                // Si presiona "*", vuelve al menú principal
        lcd_clear();
        lcd_set_cursor(0, 0);
        lcd_print("Operacion");
        lcd_set_cursor(1, 0);
        lcd_print("Cancelada");
        while(!delayRead(&LCD_Muestro)){
            // Espacio para ejecutar tareas mientras muestra el mensaje anterior
        }
        DisplayMainMenu();                            // Volver al menú principal
        return;
    }
    if (key >= '0' && key <= '9' && inputIndex < 4) {
        inputBuffer[inputIndex++] = key;
        lcd_set_cursor(1, 10 + inputIndex - 1);
        lcd_print("*");
    } else if (key == '#') {                          // Cuando se presiona "#", verifica la clave

```

FIN

- ▶ Repositorio GRUPO 8:
https://github.com/TomasJorrat/AFP_5_GRUPO_8_2024