

## 1 Exercise 1

No “final solutions” are provided for these types of questions, since the whole point of them is to encourage you to express *briefly* but *clearly* and *in your own words* what you understand. As explained in the directions, definitions taken from text books or the internet do not reflect a good understanding if these terms, nor do extremely long explanations. Equations do not express the meaning of these, nor do literal word translations of equations show that you know what they mean. Instead, we are looking for clear evidence that you understand what each term means. Possible definitions for each term is provided below:

- (a) Direct elimination: A method to solve a system of equations that uses row operations to perform forward elimination in order to solve the system using backwards substitution.
- (b)  $LU$  Factorization: Solving method that factors the initial matrix into lower and upper matrices in order to simplify the solving the system into forward and backwards substitutions.
- (c) Inverse matrix: A matrix such that any square matrix multiplied by its inverse gives the identity matrix.
- (d) Symmetric matrix: Any matrix that if you switch the rows and the columns you do not change the matrix.
- (e) Transpose: A matrix operation that flips a matrix along its diagonal, i.e. switches its rows and columns.
- (f) Permutation: Matrix operations that change the rows of an another matrix by multiplying it by a set of permutation matrices which are composed of the rows of the identity matrix.
- (g) Inner product: A matrix operation that gives the projection of one matrix onto another.
- (h) Singular matrix: A square matrix without an inverse.

## 2 Exercise 2

Solve the following system of equations, showing all relevant steps and stating the method used to solve the system (e.g.,  $LU$  factorization, direct numerical solution, matrix elimination, etc.,). Furthermore, if a system has no solution state it has no solution and briefly describe why it has no solution.

- (a) The following system of equations can be solved using the inverse matrix approach, namely

$$\mathbf{x} = \mathbf{A}^{-1}\mathbf{b} \tag{1a}$$

therefore we need to obtain  $\mathbf{A}^{-1}$ . We can determine the inverse of matrix  $\mathbf{A}$  using the augmented matrix method. Where the matrix  $\mathbf{A}$  is augmented with the identity matrix

$\mathbf{I}$ , and row operations are performed until the left hand side of the augmented matrix is the identity matrix. Starting with the augmented matrix

$$\left[ \begin{array}{ccc|ccc} 1 & 3 & 1 & 1 & 0 & 0 \\ 4 & 0 & 2 & 0 & 1 & 0 \\ 1 & 3 & 4 & 0 & 0 & 1 \end{array} \right] \quad (1b)$$

Then we can take  $4r_1 - r_2$  to zero out the  $a_{21}$  term giving

$$\left[ \begin{array}{ccc|ccc} 1 & 3 & 1 & 1 & 0 & 0 \\ 0 & 12 & 2 & 4 & -1 & 0 \\ 1 & 3 & 4 & 0 & 0 & 1 \end{array} \right] \quad (1c)$$

Next, the  $a_{31}$  is zeroed out by performing  $r_1 - r_3$  giving

$$\left[ \begin{array}{ccc|ccc} 1 & 3 & 1 & 1 & 0 & 0 \\ 0 & 12 & 2 & 4 & -1 & 0 \\ 0 & 0 & -3 & 1 & 0 & -1 \end{array} \right] \quad (1d)$$

Now we continue zeroing out entries of  $\mathbf{A}$  moving up the matrix starting with  $a_{23}$  by performing  $-\frac{2}{3}r_3 - r_2$  giving

$$\left[ \begin{array}{ccc|ccc} 1 & 3 & 1 & 1 & 0 & 0 \\ 0 & -12 & 0 & -14/3 & 1 & 2/3 \\ 0 & 0 & -3 & 1 & 0 & -1 \end{array} \right] \quad (1e)$$

Moving up the third column we zero out  $a_{13}$  using  $-1/3r_3 - r_1$  giving

$$\left[ \begin{array}{ccc|ccc} -1 & -3 & 0 & -1/3 & 0 & -1/3 \\ 0 & -12 & 0 & -14/3 & 1 & 2/3 \\ 0 & 0 & -3 & 1 & 0 & -1 \end{array} \right] \quad (1f)$$

Next we can zero  $a_{12}$  with  $1/4r_2 - r_1$  giving

$$\left[ \begin{array}{ccc|ccc} 1 & 0 & 0 & 1/6 & 1/4 & -1/6 \\ 0 & -12 & 0 & -14/3 & 1 & 2/3 \\ 0 & 0 & -3 & 1 & 0 & -1 \end{array} \right] \quad (1g)$$

Lastly we can multiply each trace entry by its reciprocal, i.e.,  $r_2 = -\frac{r_2}{12}$  and  $r_3 = -\frac{r_3}{3}$ , to finally get the inverse of matrix  $\mathbf{A}$ ,

$$\left[ \begin{array}{ccc|ccc} 1 & 0 & 0 & 1/6 & 1/4 & -1/6 \\ 0 & 1 & 0 & 7/18 & -1/12 & -1/18 \\ 0 & 0 & 1 & -1/3 & 0 & 1/3 \end{array} \right] \quad (1h)$$

Thus

$$\mathbf{x} = \mathbf{A}^{-1}\mathbf{b} = \left[ \begin{array}{ccc} 1/6 & 1/4 & -1/6 \\ 7/18 & -1/12 & -1/18 \\ -1/3 & 0 & 1/3 \end{array} \right] \begin{bmatrix} 5 \\ 6 \\ 3 \end{bmatrix} = \begin{bmatrix} 23/18 \\ 44/24 \\ -2/3 \end{bmatrix} \quad (1i)$$

(b) From the system of equations

$$\begin{bmatrix} 1 & 4 & 2 \\ 2 & 8 & 4 \\ 1 & 5 & 4 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix} \quad (2)$$

it is obvious that the second row is a linear combination of the first row, i.e.  $r_2 = 2r_1$ . Therefore the second equation in the system adds no new information, that we do not already have from the first row. Thus we have a system with three unknowns,  $x, y, z$ , and only two equations and cannot obtain an unique solution.

(c) The simplest way to solve the following system

$$\begin{bmatrix} 1 & 3 & 1 \\ 4 & 1 & 2 \\ 0 & 0 & 4 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix} \quad (3a)$$

is to use to use the first row to cancel out the first entry of the second row, i.e.  $4r_1 - r_2$ , giving

$$\begin{bmatrix} 1 & 3 & 1 \\ 0 & 11 & 2 \\ 0 & 0 & 4 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix} \quad (3b)$$

and then backwards substituting. Thus

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 15/44 \\ 3/22 \\ 1/4 \end{bmatrix} \quad (3c)$$

(d) The easiest way to solve this system of equations

$$\begin{bmatrix} 0 & 1 & 2 & 0 & 0 \\ 5 & 0 & 2 & 0 & 0 \\ 0 & 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 & 3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \\ 5 \end{bmatrix} \quad (4a)$$

is to swap the rows so that all the pivots are non-zero giving

$$\begin{bmatrix} 5 & 0 & 2 & 0 & 0 \\ 0 & 1 & 2 & 0 & 0 \\ 0 & 0 & 1 & 0 & 3 \\ 0 & 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \\ 5 \\ 3 \\ 4 \end{bmatrix} \quad (4b)$$

Now the system of equations can be solved quite easily using backwards substitution. Thus

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} 16/5 \\ 15 \\ -7 \\ -1 \\ 4 \end{bmatrix} \quad (5)$$

### 3 Exercise 3

The following system of equations

$$2x + 3y = 4 \quad (6a)$$

$$x + 2y = 5 \quad (6b)$$

can easily be solve by hand. First solve for  $x$  in terms of  $y$  in Eq. (6b),

$$x = 5 - 2y \quad (6c)$$

Next substitute  $x$  into Eq. (6a) to obtain a value for  $y$ , namely

$$2(-5 - 2y) + 3y = 4 \rightarrow y = 6 \quad (6d)$$

Thus

$$x = -7 \quad (6e)$$

$$y = 6 \quad (6f)$$

Furthermore, the solution can be verified by solving for  $y$  in both equations and plotting both curves and observing their intersection point, as shown in Fig (1).

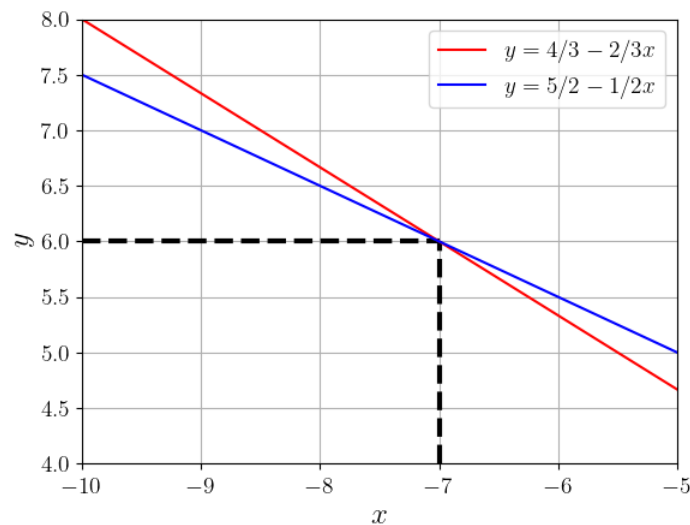


Figure 1: Verification plot for Exercise 3

Please see the Appendix for the full version of the verification code.

### 4 Exercise 4

Prove the following matrix properties:

(a) Prove the following:

$$(AB)^T = B^T A^T \quad (7a)$$

Start by defining two  $N \times N$  matrices  $\mathbf{A}$  and  $\mathbf{B}$ ,

$$\mathbf{A} = A_{ij} = \begin{bmatrix} a_{1,1} & a_{1,2} & \cdots & a_{1,n} \\ a_{2,1} & a_{2,2} & \cdots & a_{2,n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n,1} & a_{n,2} & \cdots & a_{n,n} \end{bmatrix} \quad (7b)$$

$$\mathbf{B} = B_{ij} = \begin{bmatrix} b_{1,1} & b_{1,2} & \cdots & b_{1,n} \\ b_{2,1} & b_{2,2} & \cdots & b_{2,n} \\ \vdots & \vdots & \ddots & \vdots \\ b_{n,1} & b_{n,2} & \cdots & b_{n,n} \end{bmatrix} \quad (7c)$$

which gives the following for the LHS of Eq. (7a)

$$AB = \underbrace{\sum_{k=1}^N A_{ik} B_{kj}}_{\equiv C_{ij}} = \begin{bmatrix} a_{1,1}b_{1,1} + a_{1,2}b_{2,1} & a_{1,1}b_{1,2} + a_{1,2}b_{2,2} & \cdots \\ a_{2,1}b_{1,1} + a_{2,2}b_{2,1} & a_{2,1}b_{1,2} + a_{2,2}b_{2,2} & \cdots \\ \vdots & \ddots & \vdots \end{bmatrix} \quad (7d)$$

Therefore,

$$C^T = \begin{bmatrix} a_{1,1}b_{1,1} + a_{1,2}b_{2,1} & a_{2,1}b_{1,1} + a_{2,2}b_{2,1} & \cdots \\ a_{1,1}b_{1,2} + a_{1,2}b_{2,2} & a_{2,1}b_{1,2} + a_{2,2}b_{2,2} & \cdots \\ \vdots & \ddots & \vdots \end{bmatrix} \quad (7e)$$

Next we can look at the RHS of Eq. (7a) where,

$$A^T = \begin{bmatrix} a_{1,1} & a_{1,2} & \cdots & a_{1,n} \\ a_{2,1} & a_{2,2} & \cdots & a_{2,n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n,1} & a_{n,2} & \cdots & a_{n,n} \end{bmatrix} \quad (7f)$$

$$B^T = \begin{bmatrix} b_{1,1} & b_{2,1} & \cdots & b_{n,1} \\ b_{1,2} & b_{2,2} & \cdots & b_{n,2} \\ \vdots & \vdots & \ddots & \vdots \\ b_{1,n} & b_{2,n} & \cdots & b_{n,n} \end{bmatrix} \quad (7g)$$

Therefore,

$$B^T A^T = \begin{bmatrix} b_{1,1}a_{1,1} + b_{2,1}a_{1,2} & b_{1,1}a_{2,1} + b_{2,1}a_{2,2} & \cdots \\ b_{1,2}a_{1,1} + b_{2,2}a_{1,2} & b_{1,2}a_{2,1} + b_{2,2}a_{2,2} & \cdots \\ \vdots & \ddots & \vdots \end{bmatrix} \quad (7h)$$

which is equivalent to Eq. (7e).

(b) To prove the following

$$(A^{-1})^T = (A^T)^{-1} \quad (8a)$$

start with

$$A^{-1}A = I \quad (8b)$$

where from part(a) we know that

$$(A^{-1}A)^T = A^T (A^{-1})^T = I^T \quad (8c)$$

and since

$$I^T = I \quad (8d)$$

then

$$A^{-1}A = A^T (A^{-1})^T = I \quad (8e)$$

Thus

$$(A^{-1})^T = (A^T)^{-1} \quad (8f)$$

(c) Lets consider the following symmetric matrix

$$C = \begin{bmatrix} c_{1,1} & c_{1,2} & c_{1,3} & \cdots & c_{1,n} \\ c_{1,2} & c_{2,2} & c_{2,3} & \cdots & c_{2,n} \\ c_{1,3} & c_{2,3} & c_{3,3} & \cdots & c_{3,n} \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ c_{1,n} & c_{2,n} & c_{3,n} & \cdots & c_{n,n} \end{bmatrix} \quad (9a)$$

where for in index notation  $C_{ij} = C_{ji}$ . Therefore,

$$C^T = \begin{bmatrix} c_{1,1} & c_{1,2} & c_{1,3} & \cdots & c_{1,n} \\ c_{1,2} & c_{2,2} & c_{2,3} & \cdots & c_{2,n} \\ c_{1,3} & c_{2,3} & c_{3,3} & \cdots & c_{3,n} \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ c_{1,n} & c_{2,n} & c_{3,n} & \cdots & c_{n,n} \end{bmatrix} = C \quad (9b)$$

## 5 Exercise 5

*Still need to do*

## 6 Exercise 6

The following algorithm was used to perform the  $LU$  factorization

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**Algorithm 1:**  $LU$  Factorization
 

---

**Result:** Factoring matrix  $A$  into  $L$  and  $U$

**Input :**  $A$

**Output:**  $L, U$

```

1  $L = I(3)$ 
2  $U = A$ 
3 for  $k$  in  $\text{range}(0, M-1)$  do
4   for  $j$  in  $\text{range}(k+1, M)$  do
5      $L[J,K] = U[J,K]/U[K,K]$ 
6      $U[J,K:] = U[J,K:] - L[J,K]*U[K,K:]$ 
7      $U[J,K] = 0.0$ 
8   end
9 end
```

---

Secondly, we can plot the number of points versus computational time, as seen in Fig .(2), where we see how important it is to use built in Python packages.

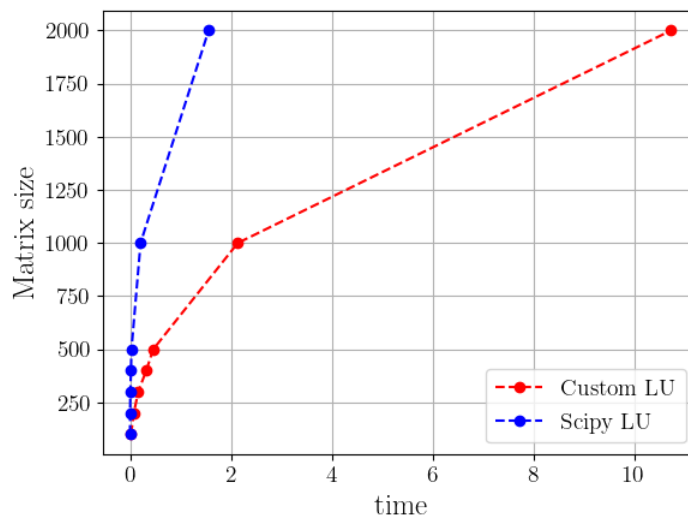


Figure 2: Performance study of user defined  $LU$  factorization tool

For an example of the complete code please refer to the Appendix.

## 7 Exercise 7

*Still need to do*

## 8 Exercise 8

*Still need to do*

## 9 Appendix

### 9.1 Exercise 3 verification code

```

1 #!/usr/bin/env python3
2 """=====
3 Purpose:
4     Verification of exercise 3
5
6 Author:
7     Emilio Torres
8 ===== """
9 #=====
10 # Preamble                                     #
11 #=====
12 #-----
13 # Python packages                             #
14 #-----
15 import sys
16 import os
17 from subprocess import call
18 from numpy import *
19 import matplotlib.pyplot as plt
20 #-----
21 # User packages                               #
22 #-----
23 from ales_post.plot_settings import plot_setting
24 #=====
25 # Main preamble                               #
26 #=====
27 if __name__ == '__main__':
28     #-----
29     # Main preamble                           #
30     #-----
31     call(['clear'])
32     sep = os.sep
33     pwd = os.getcwd()
34     media_path = pwd + '%c..%cmedia%c'          %(sep, sep, sep)
35     #-----

```



```

36 # Domain variables                                     #
37 #-----#
38 x = linspace(-10, -5, 100)
39 y1 = 4./3. - 2./3*x
40 y2 = 5./2.-x/2.
41 #-----#
42 # Plotting solution                                     #
43 #-----#
44 plot_setting()
45 plt.plot([-10,-7], [6,6], 'k--', lw = 3.0)
46 plt.plot([-7,-7], [4,6], 'k--', lw = 3.0)
47 plt.plot(x,y1,'r', lw=1.5, label = '$y = 4/3 - 2/3 x$')
48 plt.plot(x,y2,'b', lw=1.5, label = '$y = 5/2 - 1/2 x$')
49 #-----#
50 # Plot settings                                         #
51 #-----#
52 plt.legend(loc=0)
53 plt.ylabel('$y$')
54 plt.xlabel('$x$')
55 plt.grid()
56 plt.xlim([-10,-5])
57 plt.ylim([4,8])
58 plt.savefig(media_path + 'exercise-3.png')
59 plt.close()
60
61 print('**** Successful run ****')
62 sys.exit(0)

```

## 9.2 Exercise 5 *LU* factorization

```

1 #!/usr/bin/env python3
2 """=====
3 Purpose:
4     The purpose pf this script is to build subroutines to perform the
5     following:
6         1. LU factorization
7         2. Matrix inverse
8
9     **** Note:
10         This is pseudo code to help with Assignment 1
11
12 Author:
13     Emilio Torres
14 ===== """
15 #=====#
16 # Preamble                                     #
17 #=====#
18 #-----#
19 # Python packages                             #
20 #-----#
21 import os
22 import sys
23 from subprocess import call
24 import time

```

```

25 from numpy import copy, identity, random, zeros
26 import scipy.linalg as la
27 import matplotlib.pyplot as plt
28 #=====
29 # User defined functions                                     #
30 #=====
31 #-----
32 # Pretty print matrix                                     #
33 #-----
34 def print_matrix(
35     mat,                      # input matrix
36     var_str):
37
38     """ Pretty printing a matrix """
39     #-----
40     # Looping over columns and rows                         #
41     #-----
42     out = ''                # initialize string
43     for I in range(0, mat.shape[0]):
44         for J in range(0, mat.shape[1]):
45             out += '%12.5f'      %(mat[I,J])
46             out += '\n'
47     print(var_str)
48     print(out)
49 #-----
50 # Plotting settings                                       #
51 #-----
52 def plot_setting():
53
54     """ Useful plotting settings """
55     #-----
56     # Plotting settings                                     #
57     #-----
58     plt.rc('text', usetex=True)
59     plt.rc('font', family='serif')
60     SMALL_SIZE = 14
61     MEDIUM_SIZE = 18
62     BIGGER_SIZE = 20
63     plt.rc('font', size=SMALL_SIZE)
64     plt.rc('axes', titlesize=SMALL_SIZE)
65     plt.rc('axes', labelsiz=SMALL_SIZE)
66     plt.rc('xtick', labelsiz=SMALL_SIZE)
67     plt.rc('ytick', labelsiz=SMALL_SIZE)
68     plt.rc('legend', fontsize=SMALL_SIZE)
69     plt.rc('figure', titlesize=BIGGER_SIZE)
70 #-----
71 # LU factorization                                         #
72 #-----
73 def LU_factorization(
74     mat):
75     # input matrix
76
77     """ Calculating the LU factorization of the input vector """
78     #-----
79     # Preallocating matrices                               #
80     #-----

```

```

80 M = mat.shape[0]          # matrix size
81 U = copy(mat)             # make sure you copy matrix (No!!! U = mat )
82 L = identity(M)           # Initialize L with the identity matrix
83 #-----#
84 # Cheking it is error matrix                                     #
85 #-----#
86 if not mat.shape[0] == mat.shape[1]:
87     print('Input matrix must be square')
88     print('Input --> [%i, %i]' % (mat.shape[0], mat.shape[1]))
89     sys.exit(8)
90 #-----#
91 # Calculating both L and U                                       #
92 #-----#
93 for K in range(0, M-1):
94     for J in range(K+1, M):
95         L[J,K] = U[J,K]/U[K,K]
96         U[J,K:] = U[J,K:] - L[J,K]*U[K,K:]
97         U[J,K] = 0.0
98
99     return L, U
100 #=====#
101 # Main                                                            #
102 #=====#
103 if __name__ == '__main__':
104     #-----#
105     # Main preamble                                              #
106     #-----#
107     call(['clear'])
108     sep = os.sep
109     pwd = os.getcwd()
110     media_path = pwd + '%c..%cmedia%c' % (sep, sep, sep)
111     #-----#
112     # Testing LU                                                  #
113     #-----#
114     A = random.rand(3,3)
115     (Lower,Upper) = LU_factorization(A)
116     print_matrix(Lower, 'L')
117     print_matrix(Upper, 'U')
118     print_matrix(A - (Lower@Upper), 'A-LU')
119     #-----#
120     # Time study                                                  #
121     #-----#
122     N = [100, 200, 300, 400, 500, 1000, 2000]
123     times = zeros(len(N))
124     times2 = zeros(len(N))
125     for k, i in enumerate(N):
126         A = random.rand(i,i)          # random matrix
127         tic = time.time()              # start time
128         (Lower,Upper) = LU_factorization(A) # LU
129         toc = time.time()              # end time
130         times[k] = toc-tic             # time elapsed
131         tic = time.time()
132         (p, l, u) = la.lu(A)
133         toc = time.time()
134         times2[k] = toc-tic

```

```
135 #-----#
136 # Plotting the solutions                                     #
137 #-----#
138 plot_setting()
139 plt.plot(times, N, 'ro--', lw=1.5, label='Custom LU')
140 plt.plot(times2, N, 'bo--', lw=1.5, label='Scipy LU')
141 #-----#
142 # Plot settings                                             #
143 #-----#
144 plt.ylabel('Matrix size')
145 plt.xlabel('time')
146 plt.grid(True)
147 plt.legend(loc=0)
148 plt.savefig(media_path + 'exercise-6.png')
149 plt.close()
150
151 print('**** Successful run ****')
152 sys.exit(0)
```