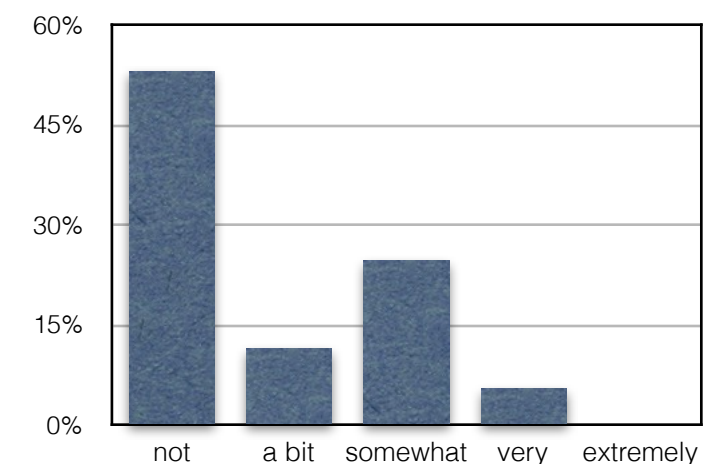


• Muddiest Points from Class 02/08

- *"I'm a bit confused how the multi-grid is any good once you get to a very few elements, like the lowest possible, two elements. I understand that would be very fast, but at that level is it even producing any useful results?"*
- *"Are we forsaking accuracy when we getting higher speed with the coarser mesh? If so why is accuracy not as important?"*
- *"To clarify: we're using the finer mesh to help minimize the error while using the coarser mesh to help increase the speed at which convergence occurs?"*
 - Multi-grid is exactly that: use coarser meshes to reduce the large wave number residuals quickly and use finer meshes to reduce the truncation errors to obtain an accurate solution quickly
- *"What is the exact meaning of "Don't code with matrices" ? When we are solving $A\phi=b$, we set ϕ as an array to calculate. Is this what your mean?"*
 - Do not think of arrays as matrices.
 - Don't code with matrices just means you should not solve systems of linear equations ($A\phi=b$) setting up a matrix A and using matrix operations
- *"I recall you had mentioned that we would only be doing the multi grid method in 1D. How do the double indices come into play in a 1D application?"*
 - I should have been more precise: We will only do multi-grid in 1D using the mesh type we covered so far.
 - We will do 2D multi-grid for a new mesh type we will cover today.
- *"How does this all lead int fluid analysis?"*
 - Poisson equations will enable us to calculate the pressure and stream function for fluid flows (later in the semester)



Multigrid

- How to code this?

- write iteration, prolongation, restriction as subroutines/functions
- could use recursive calls with dynamic memory allocations

OR

- pre-compute and store grid level support data for all grid levels in vectors $M(1:p)$, $N(1:p)$, $h(1:p)$

- do not make new arrays/variables for each grid level, instead use

$\text{rhs}(0:M(1), 0:N(1), 1:p) : \vec{f}, \vec{r}^{h \rightarrow 2h}, \vec{r}^{2h \rightarrow 4h}, \dots$

$\text{r}(0:M(1), 0:N(1), 1:p) : \vec{r}^h, \vec{r}^{2h}, \dots$

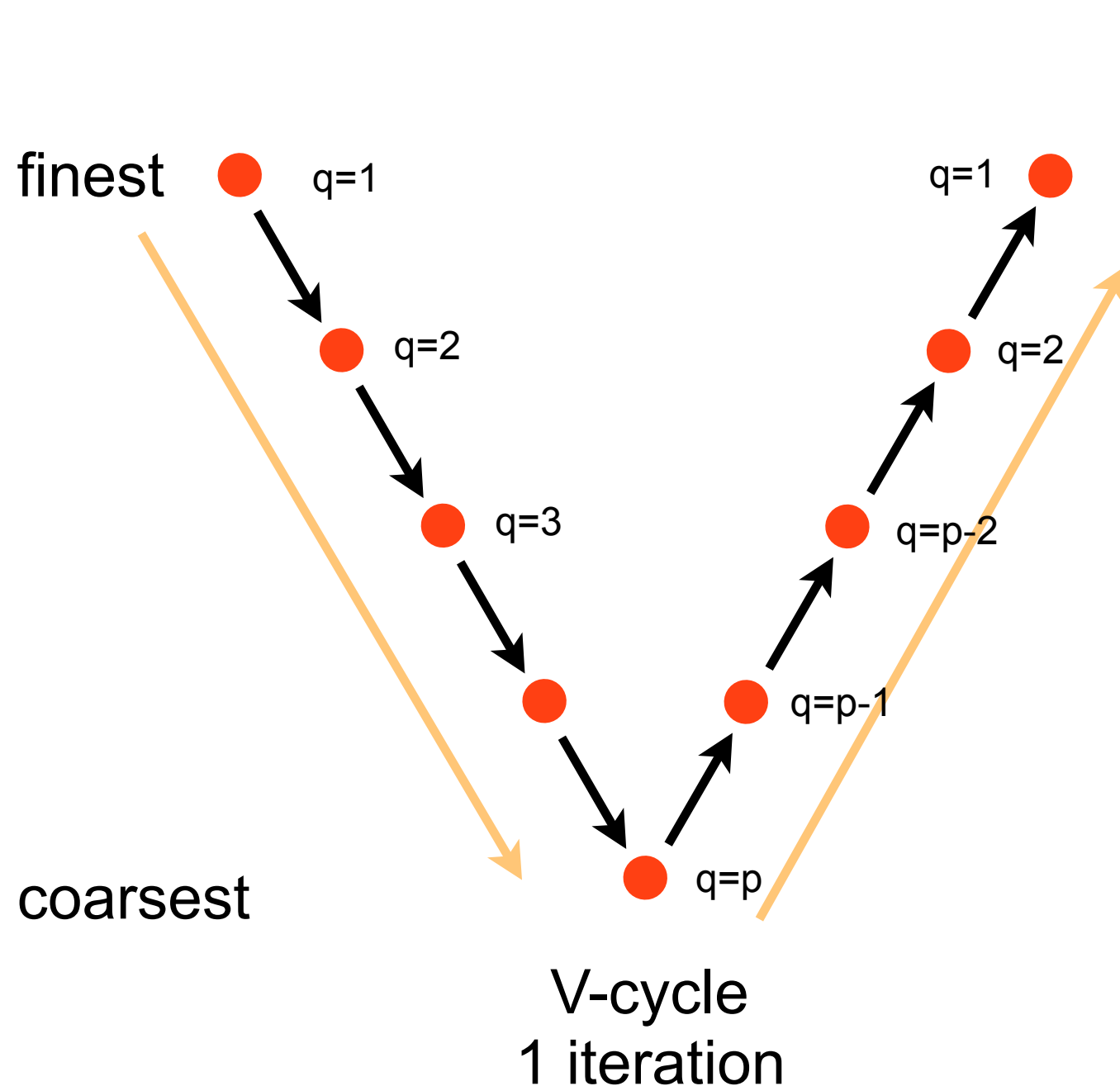
$\text{eps}(0:M(1), 0:N(1), 1:p) : \text{---}, \vec{\epsilon}^{2h}, \vec{\epsilon}^{4h}, \dots$

$\text{epsc}(0:M(1), 0:N(1), 1:p) : \vec{\epsilon}^{2h \rightarrow h}, \vec{\epsilon}^{4h \rightarrow 2h}, \dots$

- this wastes some memory but makes coding easier

Multigrid: V-cycle

- How to code single V-cycle iteration?



```
eps      = 0.0
phi      = GaussSeidel (phi,rhs(:,1),h(1),M(1))
r(:,1)   = calcResidual(phi,rhs(:,1),h(1),M(1))
```

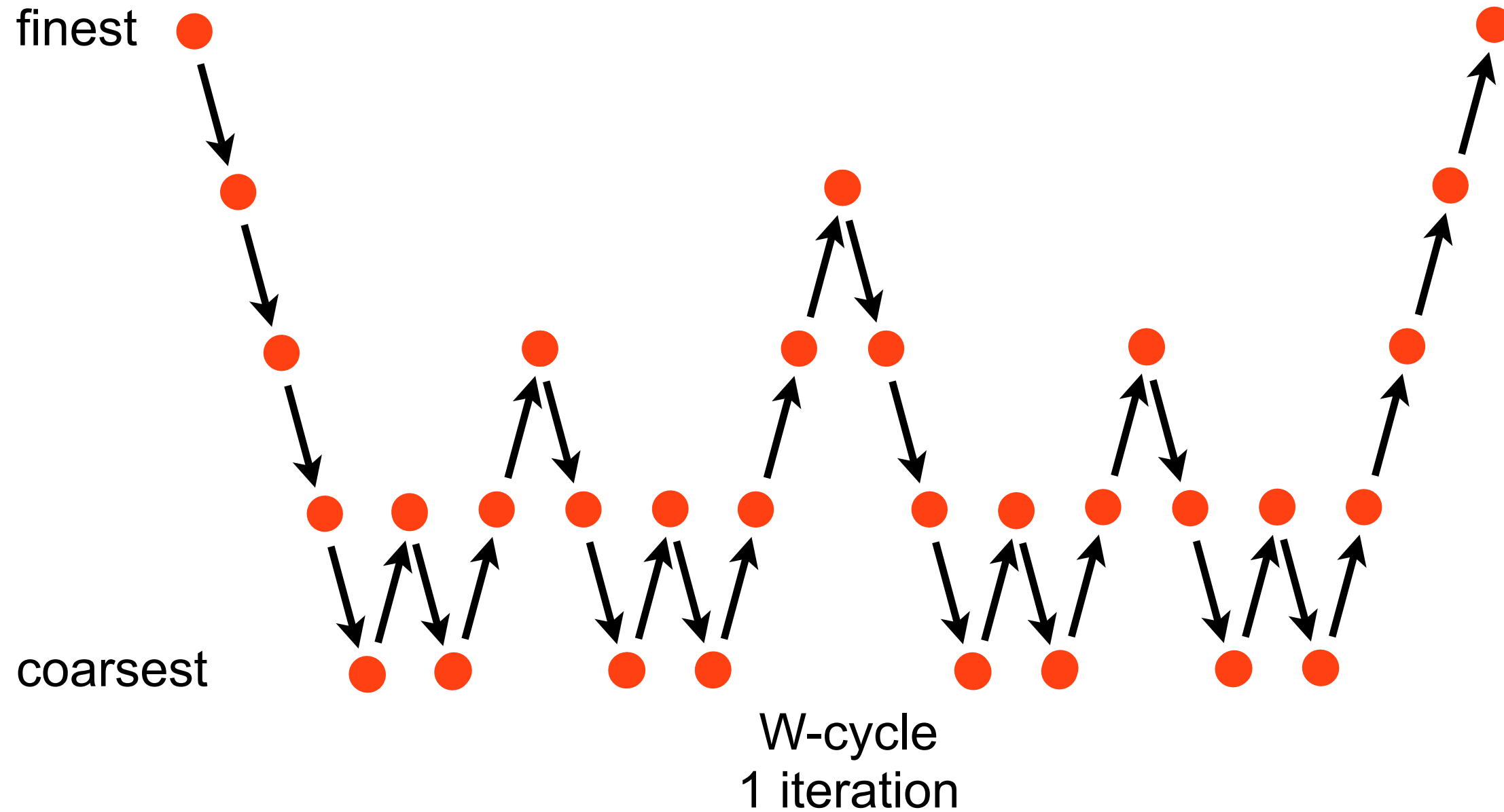
```
loop q from 2 to p
  rhs(:,q) = restrict      (r(:,q-1),M(q))
  eps(:,q) = GaussSeidel (eps(:,q),rhs(:,q),
                          h(q),M(q))
  r(:,q)   = calcResidual(eps(:,q),rhs(:,q),
                          h(q),M(q))
end loop q
```

```
loop q from p-1 to 2
  epsc(:,q) = prolong(eps(:,q+1),M(q))
  eps(:,q)  = correct(eps(:,q),epsc(:,q),M(q))
  eps(:,q)  = GaussSeidel(eps(:,q),rhs(:,q),
                          h(q),M(q))
end loop q
```

```
epsc(:,1) = prolong(eps(:,2),M(1))
phi       = correct(phi,epsc(:,1),M(1))
```

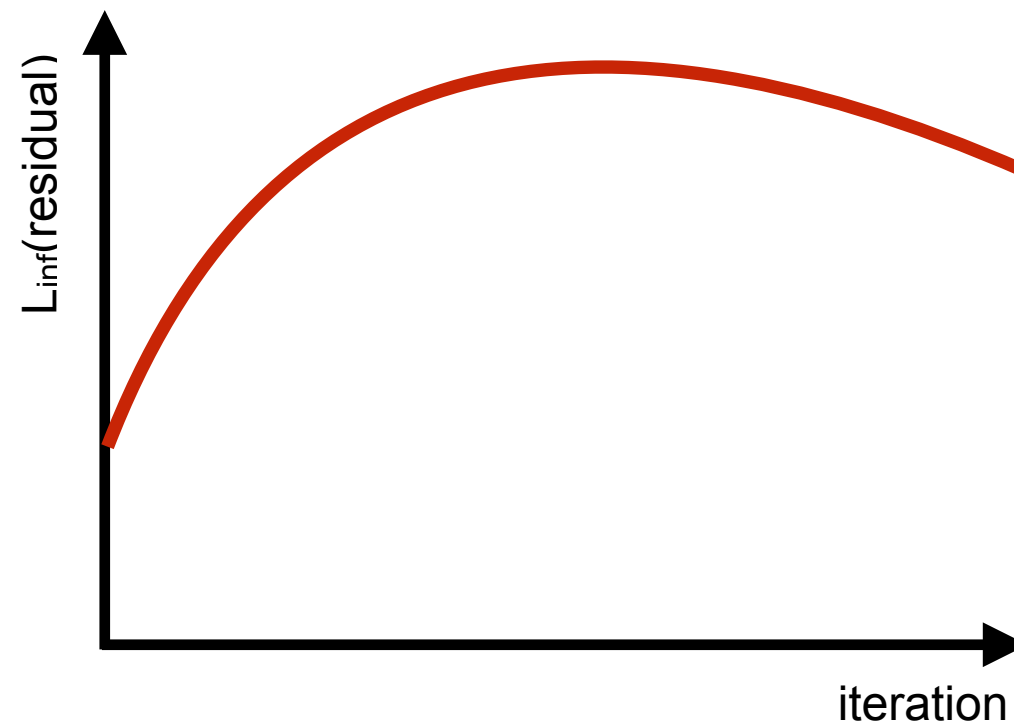
comment: rhs(:,1) must contain PDE right hand side

Multigrid: W-Cycle



- Challenge Question:

For an iterative method, e.g., Gauss Seidel, the following $L_{\infty}(\text{residual})$ vs iteration plot is obtained



Does the increase in residual norm indicate there is an error in the code?

A: Yes

B: No

Show of hands

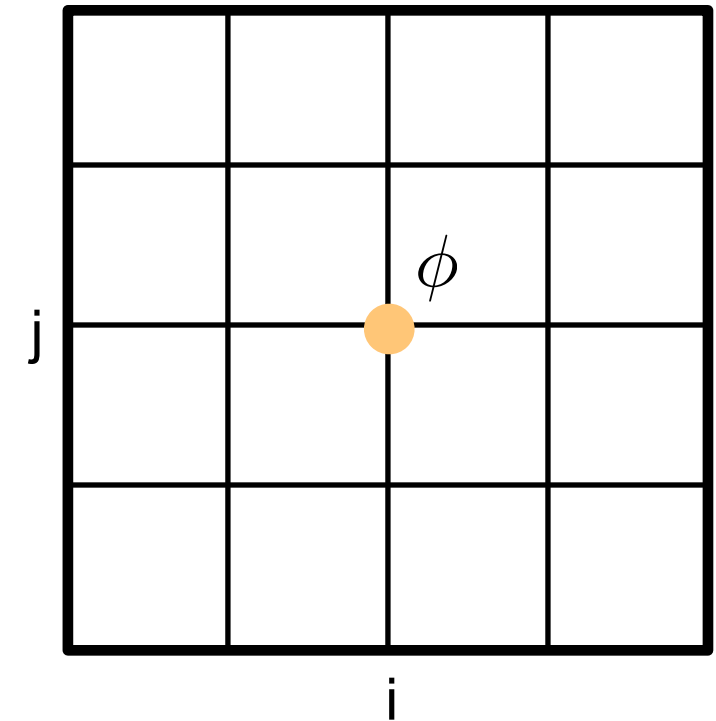
Discuss (1-2 mins)

Show of hands

Next: need to revisit meshing

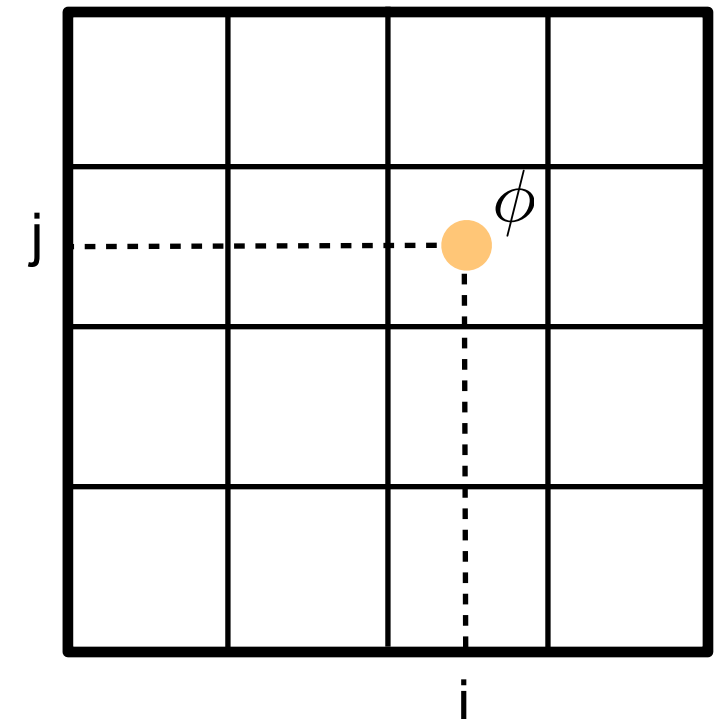
- until now, we have used the following meshes
 - variables are located at the intersection of grid lines

node based mesh



- but, we could also locate variables @ cell centers!

cell centered mesh



- index i, j refers to cell (element) center

How do cell centered meshes impact boundary conditions?

- **Dirichlet boundary:**

- there's no longer a variable located on the boundary to set to the given Dirichlet value
- Trick: add a “virtual” **ghost cell** outside the boundary
- choose the ghost cells' value such that an interpolation to the boundary location with appropriate order is equal to the Dirichlet value

- Example: 2nd-order

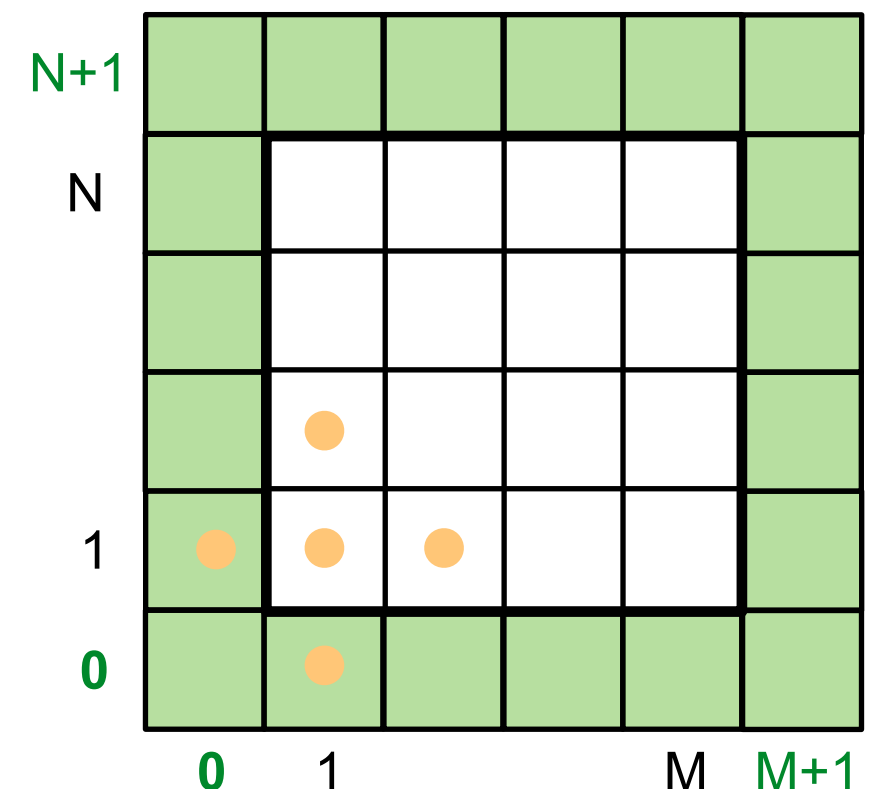
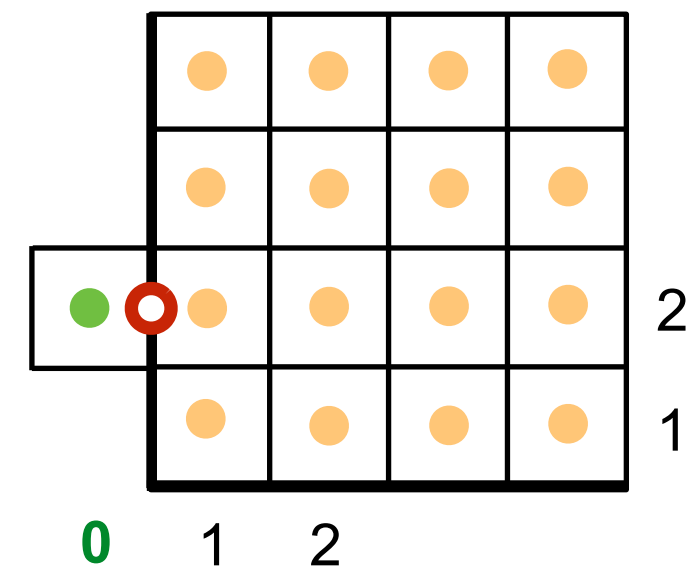
$$\phi_{bc,j} = \frac{\phi_{0,j} + \phi_{1,j}}{2} \Rightarrow \phi_{0,j} = 2\phi_{bc,j} - \phi_{1,j}$$

- extends the mesh by a layer of ghost cells all around

`phi(0:M+1,0:N+1)`

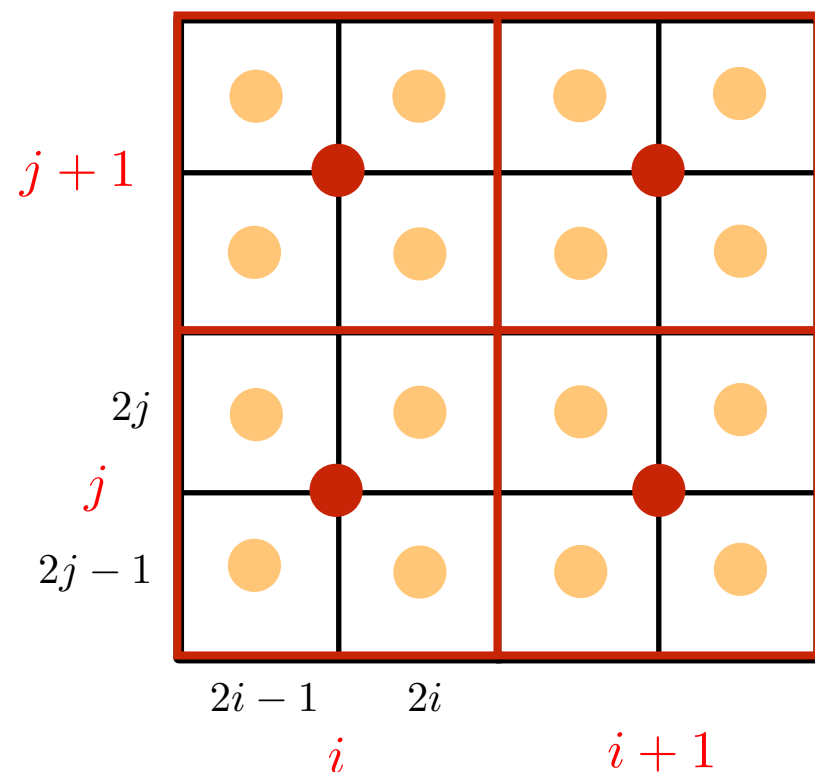
- Benefit: can use regular stencil even adjacent to boundaries with ghost cell values

```
for j=1:N
  for i=1:M
```



How do cell centered meshes impact Multigrid methods?

- **Prolongation**



here: i, j are coarse grid indices

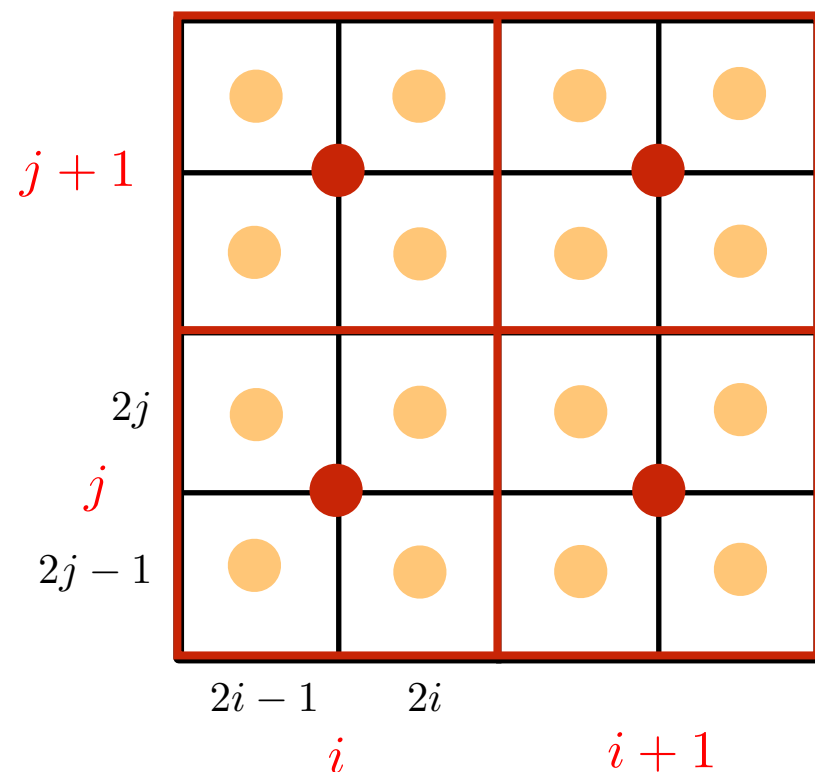
- Option #1: Constant “interpolation”

$$\epsilon_{2i-1:2i, 2j-1:2j}^{2h \rightarrow h} = \epsilon_i^{2h} \quad i = 1, 2, \dots, M^{2h}, \quad j = 1, 2, \dots, M^{2h}$$

- Option #2: Bilinear interpolation

How do cell centered meshes impact Multigrid methods?

- **Restriction** (needs to be adjoint of Prolongation)



here: i, j are coarse grid indices

- Option #1: Adjoint to constant “interpolation”

$$r_{i,j}^{h \rightarrow 2h} = \frac{1}{4} \sum_{j'=2j-1}^{2j} \sum_{i'=2i-1}^{2i} r_{i',j'}^h \quad i = 1, 2, \dots, M^{2h}, \quad j = 1, 2, \dots, M^{2h}$$

- Option #2: Adjoint to bilinear interpolation

- Finally, a comment on Poisson equation with all Neumann boundaries

$$\frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} = f(x, y) \qquad \frac{\partial \phi}{\partial n} \Big|_{bc} = g(x, y)$$

- if $\phi(x, y)$ is a solution, so is $\phi(x, y) + \text{const}$
- iterative solution may “drift”
- this is usually not a problem for convergence checks, since these use the residual

$$r(x, y) = f(x, y) - \left(\frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} \right)$$

- but, excessive “drift” may cause finite precision problems, since it can lead to differences of large numbers
- Fix: subtract the mean of ϕ from ϕ after convergence or after some number of iterations

$$\phi_{i,j} \rightarrow \phi_{i,j} - \frac{1}{MN} \sum_{j=1}^N \sum_{i=1}^M \phi_{i,j}$$

- Challenge Question:

Solve $\frac{\partial^2 \varphi}{\partial x^2} = \sin(x)$ on domain $0 \leq x \leq 2\pi$ with bc $\varphi(0) = \varphi(2\pi) = 0$

with second order central differences using Gauss-Seidel and initial guess $\varphi^{(0)} = 0$

Question: Is the exact solution to the PDE $\varphi(x) = -\sin(x)$ the solution to the Gauss-Seidel method after infinitely many iterations?

A: Yes

B: No

C: No Idea

Show of Hands

Discuss (1-2mins). (also discuss why)

Show of Hands