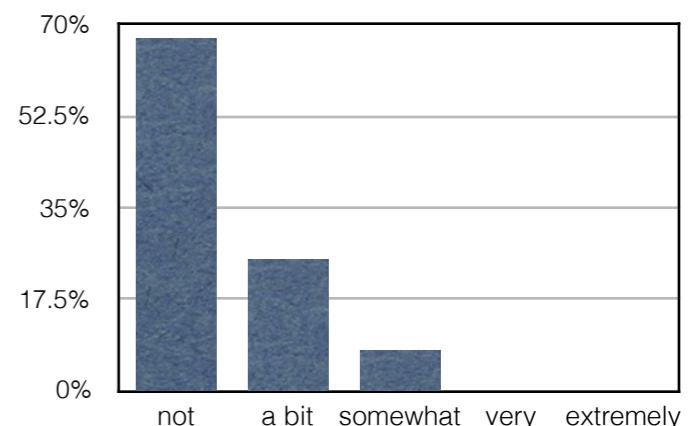


- Muddiest Points from Class 04/05

- “*Why do we need different boundaries for our U and V vectors. When allocating the arrays, one goes to M+1, N+2, and the other is M+2,N+1.*”
 - in the x-direction, u coincides with the boundary, while in the y-direction it doesn’t, requiring ghost cells
 - in the y-direction, v coincides with the boundary, while in the x-direction it doesn’t, requiring ghost cells
- “*If we are to visualize the flow using the streamfunction and vorticity, why aren’t we going to use that techniques to solve the Navier stokes equation?*”
 - we could, however we will learn techniques that are more general and easily applicable to 3D flows as well
- “*How computationally expensive is the vorticity-streamfunction formulation compared to the method we are going to be learning?*”
 - In 2D, the two are quite similar. In 3D, the new methods will always win
- “*Are there any major suggestions for making our code in Homework 10 as applicable to the final project as possible?*”
 - Not really, just use good coding practices: use functions/subroutines for repetitive tasks; don’t hard-code size of the mesh; etc.



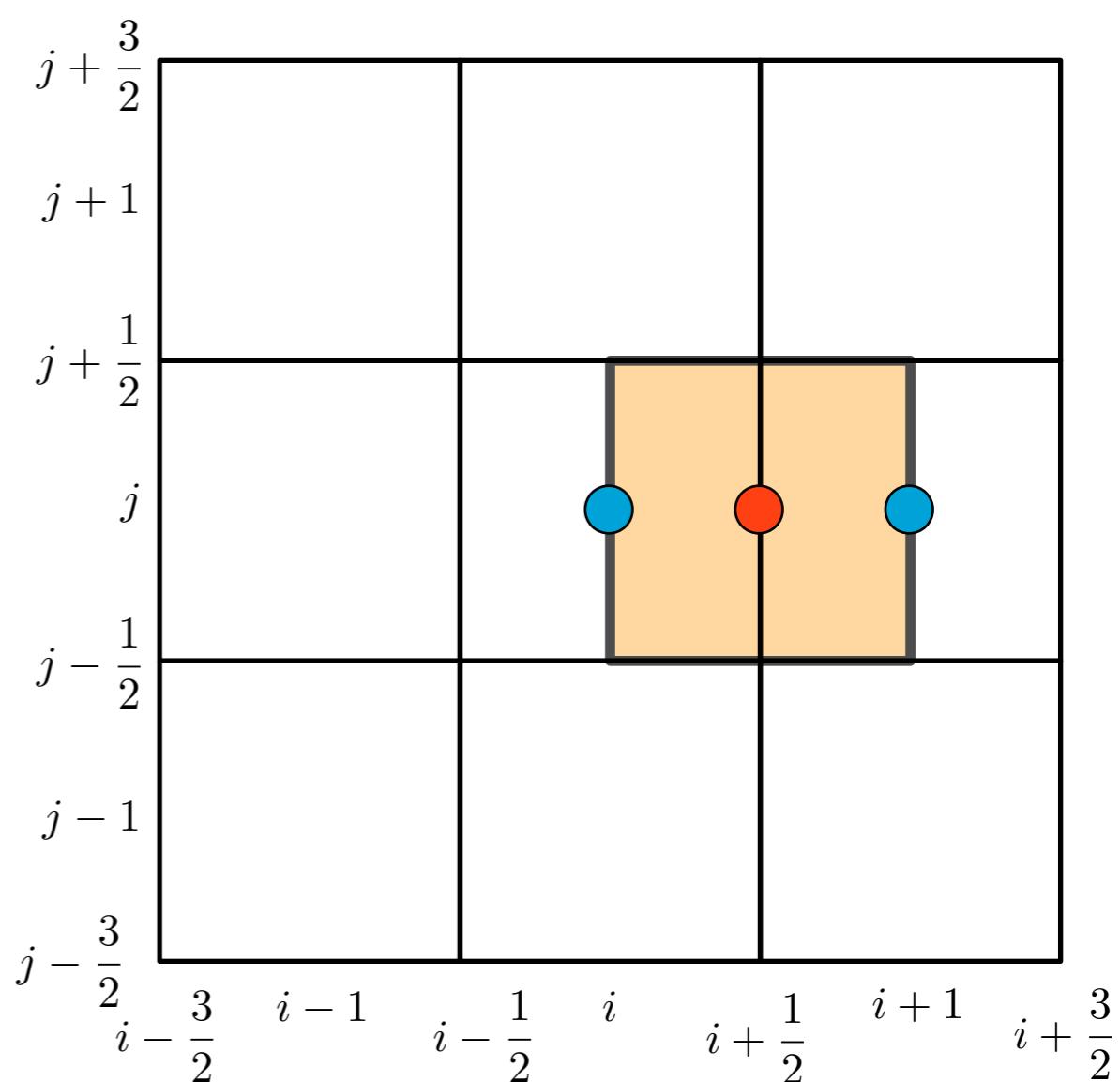
Navier-Stokes on Staggered Meshes

$$\frac{\partial u}{\partial t} + \frac{\partial uu}{\partial x} + \frac{\partial uv}{\partial y} = -\frac{\partial p}{\partial x} + \frac{1}{\text{Re}} \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right)$$

solve for $u_{i+1/2,j}$ as before. New term:

$$\frac{\partial p}{\partial x} \Big|_{i+\frac{1}{2},j} = \frac{p_{i+1,j} - p_{i,j}}{\Delta x} + O(\Delta x^2)$$

on staggered mesh: define p at cell center!



What's the pressure?

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0$$

← solenoidal velocity field

$$\frac{\partial u}{\partial t} + \frac{\partial uu}{\partial x} + \frac{\partial uv}{\partial y} = -\frac{\partial p}{\partial x} + \frac{1}{Re} \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right)$$

← need equation for p

$$\frac{\partial v}{\partial t} + u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} = -\frac{\partial p}{\partial y} + \frac{1}{Re} \left(\frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} \right)$$

in vector form:

$$\frac{\partial \vec{v}}{\partial t} = \underbrace{-\nabla \cdot (\vec{v}\vec{v})}_{N(\vec{v})} - \nabla p + \underbrace{\frac{1}{Re} \nabla^2 \vec{v}}_{L(\vec{v})}$$

$$\frac{\partial \vec{v}}{\partial t} = N(\vec{v}) - \nabla p + \frac{1}{Re} L(\vec{v}) \quad | \quad \text{take } \nabla \cdot$$

$$\frac{\partial}{\partial t} (\nabla \cdot \vec{v}) = \nabla \cdot N(\vec{v}) - \nabla^2 p + \frac{1}{Re} \nabla \cdot L(\vec{v})$$

$$\text{use continuity: } \nabla \cdot \vec{v} = 0 \quad \Rightarrow \quad \frac{\partial}{\partial t} (\nabla \cdot \vec{v}) = 0$$

$$\boxed{\nabla^2 p = \nabla \cdot N(\vec{v}) + \frac{1}{Re} \nabla \cdot L(\vec{v})}$$

pressure Poisson equation!

(in principle $\nabla \cdot L(\vec{v}) = 0$, since L is a linear operator, and $\nabla \cdot$ and L commute)

let's substitute everything in:

MAC: Marker and Cell Method

(Harlow & Welch 1965)

$$\frac{\partial u}{\partial t} + \frac{\partial uu}{\partial x} + \frac{\partial uv}{\partial y} = -\frac{\partial p}{\partial x} + \frac{1}{\text{Re}} \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right) \quad \text{use 2nd-order central on staggered mesh}$$

$$\frac{\partial u}{\partial t} \Big|_{i+\frac{1}{2},j} = \frac{u_{i+\frac{1}{2},j}^{n+1} - u_{i+\frac{1}{2},j}^n}{\Delta t} + O(\Delta t)$$

$$\frac{\partial p}{\partial x} \Big|_{i+\frac{1}{2},j} = \frac{p_{i+1,j} - p_{i,j}}{\Delta x} + O(\Delta x^2)$$

$$\frac{\partial uu}{\partial x} \Big|_{i+\frac{1}{2},j} = \frac{(u_{i+1,j})^2 - (u_{i,j})^2}{\Delta x} + O(\Delta x^2)$$

$$\frac{\partial uv}{\partial y} \Big|_{i+\frac{1}{2},j} = \frac{(uv)_{i+\frac{1}{2},j+\frac{1}{2}} - (uv)_{i+\frac{1}{2},j-\frac{1}{2}}}{\Delta y} + O(\Delta y^2)$$

$$\frac{\partial^2 u}{\partial x^2} \Big|_{i+\frac{1}{2},j} = \frac{u_{i+\frac{3}{2},j} - 2u_{i+\frac{1}{2},j} + u_{i-\frac{1}{2},j}}{\Delta x^2} + O(\Delta x^2)$$

$$\frac{\partial^2 u}{\partial y^2} \Big|_{i+\frac{1}{2},j} = \frac{u_{i+\frac{1}{2},j+1} - 2u_{i+\frac{1}{2},j} + u_{i+\frac{1}{2},j-1}}{\Delta y^2} + O(\Delta y^2)$$

$$\begin{aligned} \frac{u_{i+\frac{1}{2},j}^{n+1} - u_{i+\frac{1}{2},j}^n}{\Delta t} + \frac{(u_{i+1,j}^n)^2 - (u_{i,j}^n)^2}{\Delta x} + \frac{(uv)_{i+\frac{1}{2},j+\frac{1}{2}}^n - (uv)_{i+\frac{1}{2},j-\frac{1}{2}}^n}{\Delta y} &= -\frac{p_{i+1,j}^n - p_{i,j}^n}{\Delta x} + \\ &+ \frac{1}{\text{Re}} \left(\frac{u_{i+\frac{3}{2},j}^n - 2u_{i+\frac{1}{2},j}^n + u_{i-\frac{1}{2},j}^n}{\Delta x^2} + \frac{u_{i+\frac{1}{2},j+1}^n - 2u_{i+\frac{1}{2},j}^n + u_{i+\frac{1}{2},j-1}^n}{\Delta y^2} \right) \end{aligned}$$

$$\begin{aligned} \frac{v_{i,j+\frac{1}{2}}^{n+1} - v_{i,j+\frac{1}{2}}^n}{\Delta t} + \frac{(uv)_{i+\frac{1}{2},j+\frac{1}{2}}^n - (uv)_{i-\frac{1}{2},j+\frac{1}{2}}^n}{\Delta x} + \frac{(v_{i,j+1}^n)^2 - (v_{i,j}^n)^2}{\Delta y} &= -\frac{p_{i,j+1}^n - p_{i,j}^n}{\Delta y} + \\ &+ \frac{1}{\text{Re}} \left(\frac{v_{i+1,j+\frac{1}{2}}^n - 2v_{i,j+\frac{1}{2}}^n + v_{i-1,j+\frac{1}{2}}^n}{\Delta x^2} + \frac{v_{i,j+\frac{3}{2}}^n - 2v_{i,j+\frac{1}{2}}^n + v_{i,j-\frac{1}{2}}^n}{\Delta y^2} \right) \end{aligned}$$

MAC: Marker and Cell Method

(Harlow & Welch 1965)

$$\frac{u_{i+\frac{1}{2},j}^{n+1} - u_{i+\frac{1}{2},j}^n}{\Delta t} + \frac{(u_{i+1,j}^n)^2 - (u_{i,j}^n)^2}{\Delta x} + \frac{(uv)_{i+\frac{1}{2},j+\frac{1}{2}}^n - (uv)_{i+\frac{1}{2},j-\frac{1}{2}}^n}{\Delta y} = -\frac{p_{i+1,j}^n - p_{i,j}^n}{\Delta x} + \\ + \frac{1}{Re} \left(\frac{u_{i+\frac{3}{2},j}^n - 2u_{i+\frac{1}{2},j}^n + u_{i-\frac{1}{2},j}^n}{\Delta x^2} + \frac{u_{i+\frac{1}{2},j+1}^n - 2u_{i+\frac{1}{2},j}^n + u_{i+\frac{1}{2},j-1}^n}{\Delta y^2} \right)$$

$$\frac{v_{i,j+\frac{1}{2}}^{n+1} - v_{i,j+\frac{1}{2}}^n}{\Delta t} + \frac{(uv)_{i+\frac{1}{2},j+\frac{1}{2}}^n - (uv)_{i-\frac{1}{2},j+\frac{1}{2}}^n}{\Delta x} + \frac{(v_{i,j+1}^n)^2 - (v_{i,j}^n)^2}{\Delta y} = -\frac{p_{i,j+1}^n - p_{i,j}^n}{\Delta y} + \\ + \frac{1}{Re} \left(\frac{v_{i+1,j+\frac{1}{2}}^n - 2v_{i,j+\frac{1}{2}}^n + v_{i-1,j+\frac{1}{2}}^n}{\Delta x^2} + \frac{v_{i,j+\frac{3}{2}}^n - 2v_{i,j+\frac{1}{2}}^n + v_{i,j-\frac{1}{2}}^n}{\Delta y^2} \right)$$

$$u_{i+\frac{1}{2},j}^{n+1} = u_{i+\frac{1}{2},j}^n + \Delta t \left(\Delta u_{i+\frac{1}{2},j}^n - \frac{p_{i+1,j}^n - p_{i,j}^n}{\Delta x} \right) \quad v_{i,j+\frac{1}{2}}^{n+1} = v_{i,j+\frac{1}{2}}^n + \Delta t \left(\Delta v_{i,j+\frac{1}{2}}^n - \frac{p_{i,j+1}^n - p_{i,j}^n}{\Delta y} \right)$$

$$\Delta u_{i+\frac{1}{2},j}^n = -\frac{(u_{i+1,j}^n)^2 - (u_{i,j}^n)^2}{\Delta x} - \frac{(uv)_{i+\frac{1}{2},j+\frac{1}{2}}^n - (uv)_{i+\frac{1}{2},j-\frac{1}{2}}^n}{\Delta y} + \frac{1}{Re} \left(\frac{u_{i+\frac{3}{2},j}^n - 2u_{i+\frac{1}{2},j}^n + u_{i-\frac{1}{2},j}^n}{\Delta x^2} + \frac{u_{i+\frac{1}{2},j+1}^n - 2u_{i+\frac{1}{2},j}^n + u_{i+\frac{1}{2},j-1}^n}{\Delta y^2} \right) \\ \Delta v_{i,j+\frac{1}{2}}^n = -\frac{(uv)_{i+\frac{1}{2},j+\frac{1}{2}}^n - (uv)_{i-\frac{1}{2},j+\frac{1}{2}}^n}{\Delta x} - \frac{(v_{i,j+1}^n)^2 - (v_{i,j}^n)^2}{\Delta y} + \frac{1}{Re} \left(\frac{v_{i+1,j+\frac{1}{2}}^n - 2v_{i,j+\frac{1}{2}}^n + v_{i-1,j+\frac{1}{2}}^n}{\Delta x^2} + \frac{v_{i,j+\frac{3}{2}}^n - 2v_{i,j+\frac{1}{2}}^n + v_{i,j-\frac{1}{2}}^n}{\Delta y^2} \right)$$

MAC: Marker and Cell Method

(Harlow & Welch 1965)

$$u_{i+\frac{1}{2},j}^{n+1} = u_{i+\frac{1}{2},j}^n + \Delta t \left(\Delta u_{i+\frac{1}{2},j}^n - \frac{p_{i+1,j}^n - p_{i,j}^n}{\Delta x} \right)$$

$$v_{i,j+\frac{1}{2}}^{n+1} = v_{i,j+\frac{1}{2}}^n + \Delta t \left(\Delta v_{i,j+\frac{1}{2}}^n - \frac{p_{i,j+1}^n - p_{i,j}^n}{\Delta y} \right)$$

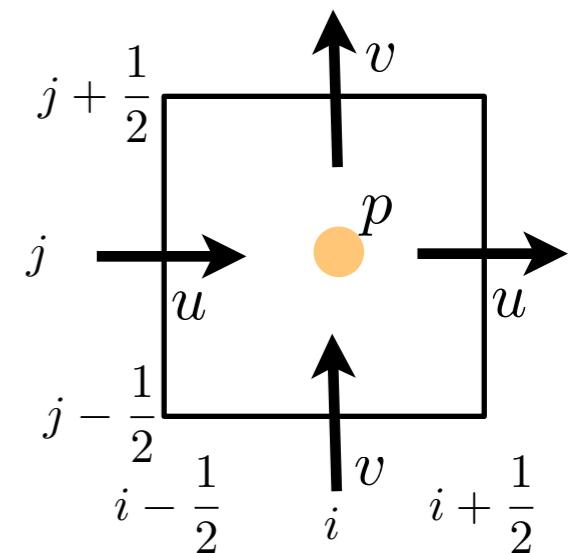
but what about pressure? we need it to solve the equations!

- let's enforce the continuity equation at t^{n+1}

$$(\nabla \cdot \vec{v})^{n+1} = 0$$

- but at what spatial location? @ location of pressure!

$$(\nabla \cdot \vec{v})_{i,j}^{n+1} = 0 \quad \frac{u_{i+\frac{1}{2},j}^{n+1} - u_{i-\frac{1}{2},j}^{n+1}}{\Delta x} + \frac{v_{i,j+\frac{1}{2}}^{n+1} - v_{i,j-\frac{1}{2}}^{n+1}}{\Delta y} = 0$$



$$\frac{u_{i+\frac{1}{2},j}^n + \Delta t \left(\Delta u_{i+\frac{1}{2},j}^n - \frac{p_{i+1,j}^n - p_{i,j}^n}{\Delta x} \right) - u_{i-\frac{1}{2},j}^n - \Delta t \left(\Delta u_{i-\frac{1}{2},j}^n - \frac{p_{i,j}^n - p_{i-1,j}^n}{\Delta x} \right)}{\Delta x} +$$

$$\frac{v_{i,j+\frac{1}{2}}^n + \Delta t \left(\Delta v_{i,j+\frac{1}{2}}^n - \frac{p_{i,j+1}^n - p_{i,j}^n}{\Delta y} \right) - v_{i,j-\frac{1}{2}}^n - \Delta t \left(\Delta v_{i,j-\frac{1}{2}}^n - \frac{p_{i,j}^n - p_{i,j-1}^n}{\Delta y} \right)}{\Delta y} = 0$$

$$\frac{u_{i+\frac{1}{2},j}^n - u_{i-\frac{1}{2},j}^n}{\Delta x} + \frac{v_{i,j+\frac{1}{2}}^n - v_{i,j-\frac{1}{2}}^n}{\Delta y} + \Delta t \left(\frac{\Delta u_{i+\frac{1}{2},j}^n - \Delta u_{i-\frac{1}{2},j}^n}{\Delta x} + \frac{\Delta v_{i,j+\frac{1}{2}}^n - \Delta v_{i,j-\frac{1}{2}}^n}{\Delta y} \right)$$

$$- \Delta t \left(\frac{p_{i+1,j}^n - 2p_{i,j}^n + p_{i-1,j}^n}{\Delta x^2} + \frac{p_{i,j+1}^n - 2p_{i,j}^n + p_{i,j-1}^n}{\Delta y^2} \right) = 0$$

MAC: Marker and Cell Method

(Harlow & Welch 1965)

$$\frac{u_{i+\frac{1}{2},j}^n - u_{i-\frac{1}{2},j}^n}{\Delta x} + \frac{v_{i,j+\frac{1}{2}}^n - v_{i,j-\frac{1}{2}}^n}{\Delta y} + \Delta t \left(\frac{\Delta u_{i+\frac{1}{2},j}^n - \Delta u_{i-\frac{1}{2},j}^n}{\Delta x} + \frac{\Delta v_{i,j+\frac{1}{2}}^n - \Delta v_{i,j-\frac{1}{2}}^n}{\Delta y} \right) \\ - \Delta t \left(\frac{p_{i+1,j}^n - 2p_{i,j}^n + p_{i-1,j}^n}{\Delta x^2} + \frac{p_{i,j+1}^n - 2p_{i,j}^n + p_{i,j-1}^n}{\Delta y^2} \right) = 0$$

$$\frac{p_{i+1,j}^n - 2p_{i,j}^n + p_{i-1,j}^n}{\Delta x^2} + \frac{p_{i,j+1}^n - 2p_{i,j}^n + p_{i,j-1}^n}{\Delta y^2} = \frac{\delta_x^2 p_{i,j}^n}{\Delta x^2} + \frac{\delta_y^2 p_{i,j}^n}{\Delta y^2} = \\ \frac{1}{\Delta t} \left(\frac{u_{i+\frac{1}{2},j}^n - u_{i-\frac{1}{2},j}^n}{\Delta x} + \frac{v_{i,j+\frac{1}{2}}^n - v_{i,j-\frac{1}{2}}^n}{\Delta y} \right) + \frac{\Delta u_{i+\frac{1}{2},j}^n - \Delta u_{i-\frac{1}{2},j}^n}{\Delta x} + \frac{\Delta v_{i,j+\frac{1}{2}}^n - \Delta v_{i,j-\frac{1}{2}}^n}{\Delta y}$$

Poisson equation for p with known right hand side!

However, right hand side is quite tedious:

$$\Delta u_{i+\frac{1}{2},j}^n = -\frac{(u_{i+1,j}^n)^2 - (u_{i,j}^n)^2}{\Delta x} - \frac{(uv)_{i+\frac{1}{2},j+\frac{1}{2}}^n - (uv)_{i+\frac{1}{2},j-\frac{1}{2}}^n}{\Delta y} + \frac{1}{\text{Re}} \left(\frac{u_{i+\frac{3}{2},j}^n - 2u_{i+\frac{1}{2},j}^n + u_{i-\frac{1}{2},j}^n}{\Delta x^2} + \frac{u_{i+\frac{1}{2},j+1}^n - 2u_{i+\frac{1}{2},j}^n + u_{i+\frac{1}{2},j-1}^n}{\Delta y^2} \right) \\ \Delta v_{i,j+\frac{1}{2}}^n = -\frac{(uv)_{i+\frac{1}{2},j+\frac{1}{2}}^n - (uv)_{i-\frac{1}{2},j+\frac{1}{2}}^n}{\Delta x} - \frac{(v_{i,j+1}^n)^2 - (v_{i,j}^n)^2}{\Delta y} + \frac{1}{\text{Re}} \left(\frac{v_{i+1,j+\frac{1}{2}}^n - 2v_{i,j+\frac{1}{2}}^n + v_{i-1,j+\frac{1}{2}}^n}{\Delta x^2} + \frac{v_{i,j+\frac{3}{2}}^n - 2v_{i,j+\frac{1}{2}}^n + v_{i,j-\frac{1}{2}}^n}{\Delta y^2} \right)$$

MAC: Marker and Cell Method

(Harlow & Welch 1965)

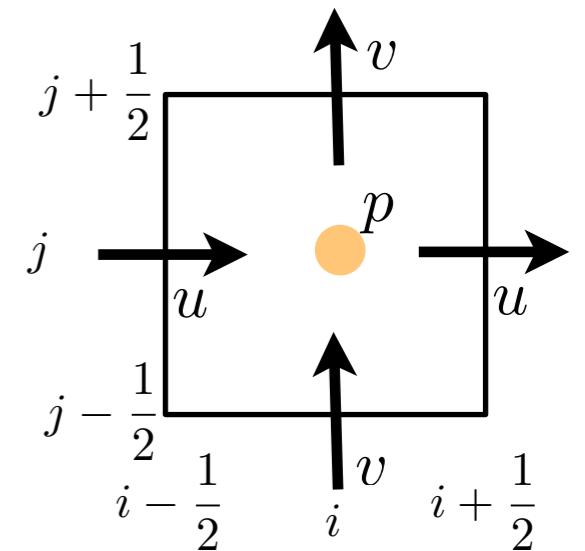
but what about pressure? we need it to solve the equations!

- let's enforce the continuity equation at t^{n+1}

$$(\nabla \cdot \vec{v})^{n+1} = 0$$

- but at what spatial location? @ location of pressure!

$$(\nabla \cdot \vec{v})_{i,j}^{n+1} = 0$$



$$\frac{\delta_x^2 p_{i,j}^n}{\Delta x^2} + \frac{\delta_y^2 p_{i,j}^n}{\Delta y^2} = \frac{1}{\Delta t} \left(\frac{u_{i+\frac{1}{2},j}^n - u_{i-\frac{1}{2},j}^n}{\Delta x} + \frac{v_{i,j+\frac{1}{2}}^n - v_{i,j-\frac{1}{2}}^n}{\Delta y} \right) + \frac{\Delta u_{i+\frac{1}{2},j}^n - \Delta u_{i-\frac{1}{2},j}^n}{\Delta x} + \frac{\Delta v_{i,j+\frac{1}{2}}^n - \Delta v_{i,j-\frac{1}{2}}^n}{\Delta y}$$

Solution Procedure

- initialize velocity fields
- • solve Poisson equation in interior $\Rightarrow p^n$
- solve momentum equations in interior (viscous Burger's + pressure term) $\Rightarrow u^{n+1}, v^{n+1}$

But what about boundary conditions? for velocity: staggered mesh (see Class 23)

MAC: Marker and Cell Method

(Harlow & Welch 1965)

boundary conditions for pressure Poisson equation?

General approach:

- 1) write divergence constraint at t^{n+1} for all boundary adjacent interior cells in discrete form
- 2) for all velocities on the boundary, use boundary conditions
- 3) for all other velocities use momentum equations

- we want $(\nabla \cdot \vec{v})_{i,1}^{n+1} = 0$

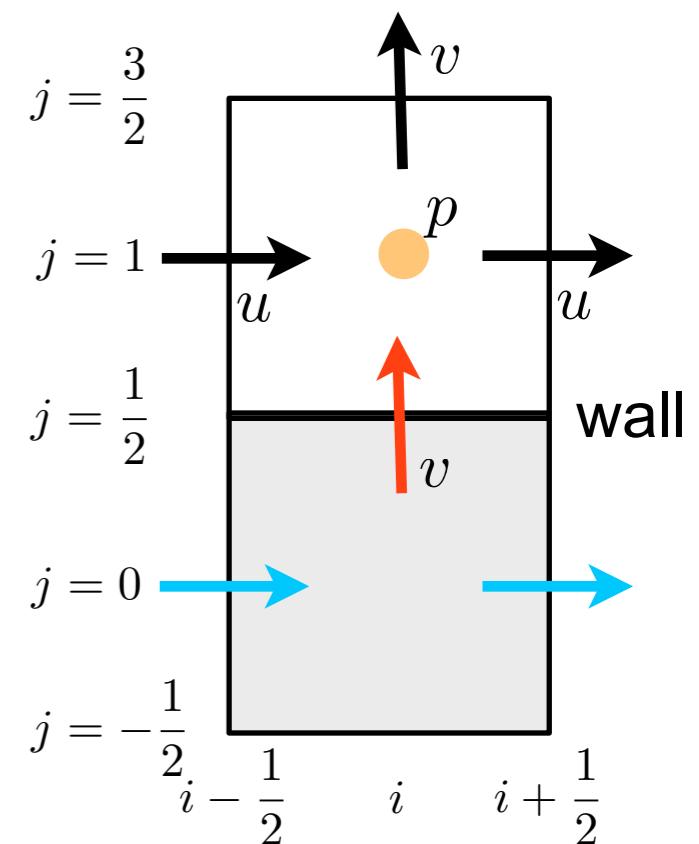
$$\frac{u_{i+\frac{1}{2},1}^{n+1} - u_{i-\frac{1}{2},1}^{n+1}}{\Delta x} + \frac{v_{i,\frac{3}{2}}^{n+1} - v_{i,\frac{1}{2}}^{n+1}}{\Delta y} = 0$$

- use boundary condition for velocity and momentum eqs.

$$\begin{aligned} & \frac{u_{i+\frac{1}{2},1}^n - u_{i-\frac{1}{2},1}^n}{\Delta x} + \frac{v_{i,\frac{3}{2}}^n - v_{i,\frac{1}{2}}^{n+1}}{\Delta y} + \\ & \Delta t \left[\left(\frac{\Delta u_{i+\frac{1}{2},1}^n - \Delta u_{i-\frac{1}{2},1}^n}{\Delta x} + \frac{\Delta v_{i,\frac{3}{2}}^n}{\Delta y} \right) - \frac{\delta_x^2 p_{i,j}^n}{\Delta x^2} - \frac{p_{i,2}^n - p_{i,1}^n}{\Delta y^2} \right] = 0 \end{aligned}$$

⇒ never need to use ghost cell pressures!

Example: bottom wall



MAC: Marker and Cell Method

(Harlow & Welch 1965)

BUT: this requires a change in the code depending on the location of the cell to be updated

⇒ UGLY ⇒ let's try to avoid this by introducing ghost cell pressures

Idea: project momentum equations onto boundary normal direction \vec{n}

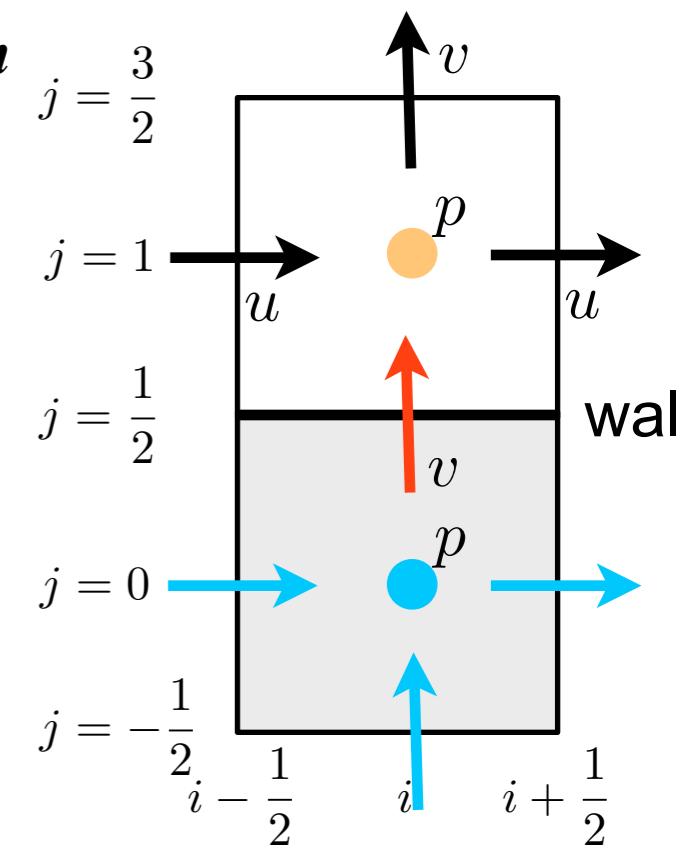
$$[\dots] \quad \nabla p \cdot \vec{n} = \frac{1}{\text{Re}} \frac{\partial^2 \vec{v}}{\partial l_n^2} \cdot \vec{n}$$

 l_n : normal arclength

Example: bottom wall

$$(\nabla p \cdot \vec{n})_{i, \frac{1}{2}} = \left. \frac{\partial p}{\partial y} \right|_{i, \frac{1}{2}} = \frac{p_{i,1} - p_{i,0}}{\Delta y}$$

$$\frac{1}{\text{Re}} \left(\frac{\partial^2 \vec{v}}{\partial l_n^2} \cdot \vec{n} \right)_{i, \frac{1}{2}} = \frac{1}{\text{Re}} \left. \frac{\partial^2 v}{\partial y^2} \right|_{i, \frac{1}{2}} = \frac{1}{\text{Re}} \frac{v_{i, \frac{3}{2}} - 2v_{i, \frac{1}{2}} + v_{i, -\frac{1}{2}}}{\Delta y^2}$$



- we also know the velocity on the boundary and the divergence free constraint!

$$v_{i, \frac{1}{2}} = 0 \quad \text{and} \quad (\nabla \cdot \vec{v})_{i, \frac{1}{2}} = 0 \quad u @ \text{wall} = \text{const.}$$

$$\left(\frac{\partial u}{\partial x} \right)_{i, \frac{1}{2}} + \left(\frac{\partial v}{\partial y} \right)_{i, \frac{1}{2}} = 0 \quad \Rightarrow \quad \frac{v_{i, \frac{3}{2}} - v_{i, -\frac{1}{2}}}{2\Delta y} = 0 \quad \Rightarrow \quad v_{i, -\frac{1}{2}} = v_{i, \frac{3}{2}}$$

$$\frac{p_{i,1} - p_{i,0}}{\Delta y} = \frac{1}{\text{Re}} \left(\frac{2v_{i, \frac{3}{2}}}{\Delta y^2} \right) \quad \Rightarrow \quad p_{i,0} = p_{i,1} - \frac{2}{\text{Re}} \frac{v_{i, \frac{3}{2}}}{\Delta y}$$

similar for other boundaries

Fractional Step Method

(Chorin 1965)

Idea: Split momentum equations into separate parts

⇒ since we have no pressure evolution equation, split pressure from the rest:

$$\frac{\partial \vec{v}}{\partial t} = N(\vec{v}) + \frac{1}{\text{Re}} L(\vec{v}) \quad : \quad \vec{v}^n \rightarrow \vec{v}^*$$

$$\frac{\partial \vec{v}}{\partial t} = -\nabla p \quad : \quad \vec{v}^* \rightarrow \vec{v}^{n+1}$$

What are the implications of this split?

- Excursion into Linear Algebra:
 - ▶ let's introduce the space of all vector functions
 - ▶ for incompressible, unsteady flow, the velocity must evolve in the **subspace** of solenoidal functions ($\nabla \cdot \vec{v} = 0$)
 - ▶ when we update $\vec{v}^n \rightarrow \vec{v}^*$, then \vec{v}^* is not necessarily in that subspace anymore, even if \vec{v}^n was!
 - ▶ How do we get it back into the subspace? **projection**
 - ▶ that's exactly what $\vec{v}^* \rightarrow \vec{v}^{n+1}$ does!

Fractional Step Method

Some very important consequences of this thinking:

- p is not determined by a convection/diffusion equation!
- p is solely used to project \vec{v}^* into the subspace of solenoidal functions!
 - ⇒ thus p is not really a pressure, but rather a Lagrange multiplier
 - ⇒ to make this distinction clear, let's call it φ

$$\frac{\partial \vec{v}}{\partial t} = N(\vec{v}) + \frac{1}{\text{Re}} L(\vec{v}) \quad : \quad \vec{v}^n \rightarrow \vec{v}^*$$

$$\frac{\partial \vec{v}}{\partial t} = -\nabla \varphi \quad : \quad \vec{v}^* \rightarrow \vec{v}^{n+1}$$

Fractional Step Method by Kim & Moin (1985)

- step 1: use Adams Bashforth for nonlinear terms and Crank-Nicholson for linear terms

$$\frac{\vec{v}_{i,j}^* - \vec{v}_{i,j}^n}{\Delta t} = \frac{3}{2} \vec{H}_{i,j}^n - \frac{1}{2} \vec{H}_{i,j}^{n-1} + \frac{1}{2} \frac{1}{\text{Re}} \left(\frac{\partial_x^2}{\Delta x^2} + \frac{\partial_y^2}{\Delta y^2} \right) (\vec{v}_{i,j}^* + \vec{v}_{i,j}^n)$$

⇒ use ADI to solve

- step 2: pressure Poisson equation

$$\frac{\partial \vec{v}}{\partial t} = -\nabla \varphi^{n+1} \quad \frac{\vec{v}^{n+1} - \vec{v}^*}{\Delta t} = -\text{grad } \varphi^{n+1} \quad |\text{div}(\dots)$$

$$\frac{\text{div } \vec{v}^{n+1} - \text{div } \vec{v}^*}{\Delta t} = -\text{div} (\text{grad } \varphi^{n+1})$$

$$\text{div} (\text{grad } \varphi^{n+1}) = \frac{1}{\Delta t} \text{div} (\vec{v}^*)$$

- step 3: project into solenoidal subspace

$$\vec{v}^{n+1} = \vec{v}^* - \Delta t \text{ grad } \varphi^{n+1}$$

CRUCIAL : You **MUST** use the same discrete grad and div operators in step 2 & 3!

⇒ ∇^2 must be build as $\text{div}(\text{grad})$, for example

$$\delta_x^2 = (\varphi_{i+1,j} - \varphi_{i,j}) - (\varphi_{i,j} - \varphi_{i-1,j})$$

Fractional Step Method by Kim & Moin (1985)

But still need to define boundary conditions!

- for step 1: use velocity boundary conditions on staggered mesh
- for step 2: use zero gradient Neumann condition for ϕ

Neumann for ϕ :

velocity:

$$\varphi_{i,0}^{n+1} = \varphi_{i,1}^{n+1}$$

$$v_{i,\frac{1}{2}}^* = v_{i,\frac{1}{2}}^{n+1}$$

