

**Homework #9 - Due: April 8th, at the beginning of class**

Please submit result graphs together with either handwritten or printed out descriptions, equations, and answers at the beginning of class. Combine all code you used to solve the problems into a single text file, and upload the text file to Blackboard using the SafeAssign mechanism. No credit will be given, if your code is not uploaded as a text file using SafeAssign. Also ensure that your code contains adequate comments. Add a printout of all code as an **appendix** to your submission.

**Problem 1** (AEE 471: Core Course Outcome #2)

Consider the 1D Burgers equation for the unknown  $u = u(x, t)$ ,

$$\frac{\partial u}{\partial t} + \frac{\partial \left( \frac{u^2}{2} \right)}{\partial x} = 0, \quad 0 \leq x \leq 2, \quad (1)$$

with initial condition

$$u(x, 0) = 0.25 + 0.5 \sin(\pi x) \quad (2)$$

and periodic boundary conditions on a cell centered mesh of  $M$  equally sized elements.

- Determine  $u(x, t = 0.15)$  using a first order TVD scheme for  $M = 40$ . Plot the correct weak solution vs  $x$  together with the initial solution, and give the solution at  $t = 0.15$  in a table together with  $x_i$ . To help you debug your code, the file `tvd1.txt` available on Blackboard contains data for the first 4 time steps using  $M = 20$  and a time step  $\Delta t$  that is 10% of the maximum stable time step.
- Determine the correct weak solution for  $u(x, t = 2)$  using a first order TVD scheme for  $M = 40$ . Add the solution to the plot and table of a).
- Demonstrate the spatial order accuracy of the first order TVD scheme by performing a mesh refinement study for the solution at  $t = 0.15$  based on the  $L_\infty$  and  $L_1$  norms of the error. Present the error norms together with the observed order of convergence,  $M$ , and Courant number (or  $\Delta t$ ) in a table. Make sure that errors from the root finding algorithm for the exact solution and temporal errors do not mask spatial errors. Use at least 3 different meshes with  $r = 2$ . The exact solution to Eq. (1) up to the point where the shock forms is given by

$$u_{ex}(x, t) = u(x - ut, 0), \quad (3)$$

which can be solved by any standard root finding algorithm (see MAE384).

- Required for MAE561, Bonus for AEE471: Repeat tasks (a) and (c) using a 2nd order TVD scheme. To help you debug your code, the file `tvd2.txt` available on Blackboard contains data for the first 4 time steps using  $M = 20$  and a time step  $\Delta t$  that is 10% of the maximum stable time step.

*Required submission:*

- 1 clearly annotated plot of  $u$  as a function of  $x$  at  $t = 0, 0.15$ , and  $2$  using a 1st-order TVD method for  $M = 40$ ;
- 1 table containing  $x$  and the solution  $u$  at  $t = 0, 0.15$ , and  $2$  using a first order TVD method for  $M = 40$ ;
- 1 table containing results of mesh refinement study (at least 3 meshes with  $r = 2$ ) including  $M$ , Courant number or  $\Delta t$ ,  $L_\infty$  and  $L_1$  norms of the error, and observed order of convergence for each norm.
- all code used uploaded to Blackboard's SafeAssign link. The code must contain a stable time step calculation.

*MAE561:*

- 1 clearly annotated plot of  $u$  as a function of  $x$  at  $t = 0, 0.15$ , and  $2$  using a 2nd-order TVD method for  $M = 40$ ;
- 1 table containing  $x$  and the solution  $u$  at  $t = 0, 0.15$ , and  $2$  using a 2nd-order TVD method for  $M = 40$ ;
- 1 table containing results of mesh refinement study (at least 3 meshes with  $r = 2$ ) including  $M$ , Courant number or  $\Delta t$ ,  $L_\infty$  and  $L_1$  norms of the error, and observed order of convergence for each norm for 2nd-order TVD method.