CHIRALEX: theory

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I. INTRODUCTION

Essential parameters are kept in the *params* dictionary, which is passed throughout the program. It is used to construct all types of objects, from grids to the propagator object.

II. BASIS FUNCTIONS AND GRIDS

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A. Radial quadratures

B. Radial grid

The radial grid used to solve the TDSE is based on an underlying Gauss-Lobatto (GL) quadrature in an underlying Gauss-

$$S_k = \frac{1}{2} R_b \left(x_k + 1 \right) \tag{1}$$

Bin size must be determined empirically to ensure good convergence and stability of the results. Next, the scaled grid is copied and translated by the bin size to generate the full primitive radial grid G_{prim} :

$$r_{ik} = S_k + T_i, \qquad i = 0, 1, ..., Nb-1, k = 0, 1, ..., Nlobs-1$$

where $T_i=i\cdot R_b+\epsilon$. The constant shift ϵ (rshift keyword) is optional and by default is set to 0. The resulting grid 127 has the size $Nb\times Nlobs$ and contains boundary points 128 $r_{00}=\epsilon$ and $r_{Nb-1,Nlobs-1}=R_{max}$. The last point from 130 bin i and the first point from 130 the primitive grid.

The coupled grid G is generated by removing boundary points, plus merging duplicate points at bin boundaries in G_{prim} . Through these operations the size of the coupled grid is $Nr = Nb \times (Nlobs - 1) - 1$. Note that all indices start from 0 for python compatibility. For example $G_{00} = r_{01}$ and $G_{0,Nl-3} = r_{0,Nl-2}$. The boundary of the first

bin is at $G_{0,Nl-2}=r_{0,Nl-1}=r_{10}$. The last point in the coupled grid is $G_{Nb-1,Nl-3}=r_{Nb-1,Nl-2}$.

C. Radial basis functions

1. Interpolated radial functions

D. Angular basis functions

III. INDEX MAPPING

A natural choice for mapping the basis set indices is to 44 set the grid points as major dimension (changing last). 45 Such a choice offers a simple way of cutting the Hamilto-46 nian matrix at a given grid point by slicing the basis. 47 We name this convention as 'DVR' mapping. Bridge 48 functions, as discussed in IIB, are defined for indices 50 quence of such a choice is a near block-diagonal structure 51 of the Hamiltonian. Another common choice is to choose bridge functions as first in the bin (n=0), which results in 'arms' reaching out from bin i into bin i+1, as shown in ??. Another option given in the code is to select mapping in which the angular quantum numbers l, m are the ma-56 jor dimension. We name this convention 'SPECTRAL'. 57 The choice for mapping is determined by the 'map type' = 'DVR,SPECT' keyword. With the 'DVR' convention 58 59 the map is given as follows:

$$p(i,n,l,m)=\left(i\cdot(Nl-1)+n\right)\cdot\left(l_{max}+1\right)^2+l\cdot(l+1)+m \tag{3}$$
 owith $p(0,0,0,0)=0$. For $l_{max}=0$ we have $p(Nb-1,Nl-3,0,0)=Nb\times(Nl-1)-2$, which retrieves the size of the coupled radial grid/basis set. The map is stored in a numpy array ('maparray') and is saved in file. The ranges for the radial indices i and n are the same as for the coupled grid, i.e. $i=0,1,2,...Nb-1$ and $n=0,1,2,...,Nl-3$

59 IV. ROTATED ELECTROSTATIC POTENTIAL

for i = Nb - 1.

Each molecular-frame orientation gives different elecratrostatic potential as seen from the laboratory frame, in which the basis set is defined. This means that for each orientation one must generate generally a different Lebedev quadrature grid. Even if a global scheme is used,

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86

TABLE I. Example 'DVR' coupled basis set index mapping for Nb = 3, Nl = 3, lmax = 1

mux = 1.								
i	$ \mathbf{n} $	ξ	1	m	$ \mathbf{p}$			
0	0	0	0	0	0			
0	0	0	1	-1	1			
0	0	0	1	0	2			
0	0	0	1	+1	3			
0	1	1	0	0	$ _4$			
0	1	1	1	-1	5			
0	1	1	1	0	6			
0	1	1	1	+1	7			
2	0	$ _4$	1	0	18			
2	0	$ _4$	1	+1	19			

75 the values of the electrostatic potential will be different 114 formula: 76 at these points for each orientation. This is because the 77 lebedev grid is defined in the laboratory frame. Therefore 78 at this stage, a separate Psi4 calculation must be initial-79 ized for each orientation. I do not see a way around it 115 where so at the moment, other than performing multipole expansi sion and calculating the angular part (spherical tensor 82 form) of the potential analytically. But finding this expansion is costly, even more than running Psi4 for every 84 orientation.

KINETIC ENERGY OPERATOR

VI. POTENTIAL ENERGY OPERATOR

VII. HAMILTONIAN

The current paradigm assumes calculation of the 123 89 sparse Hamiltonian matrix and feeding this matrix into 124 $_{90}$ an eigensolver or propagator routine. In future versions, 125 91 for better computational performance it may be useful 92 not to calculate the Hamiltonian matrix, but rather code 93 the matrix-vector product only, as part of an interface 127 94 routine with appropriate iterative eigensolver. Due to 128 95 high degree of sparsity of the Hamiltonians appearing in 129 96 our calculations, it is sufficient to keep in memory the 130 whole sparse matrix.

We decided to keep the bound state Hamiltonian H_0 132 and the initial propagation Hamiltonian H_{init} as sepa- 133 rate entities, calculated independently. The computa- 134 101 tional overhead related to calculating the bound-state 135 102 part twice is marginal, as we assume that the full propa- 136 103 gation basis is much bigger than the basis for the bound 137 104 Hamiltonian $Nbas \gg Nbas0$. Future releases might re- 138 105 cycle the bound state KEO and POT and build only the 139 106 outside region Hamiltonian. 140

WAVEPACKET PROPAGATION

time grid

The time grid for the calculation is determined by the 109 110 input keywords:

TABLE II. Time grid keywords.

keyword	${f description}$	type
t0	start time	float
$t \max$	$_{ m end\ time}$	float
dt	time step	float
$time_units$	units	string
wfn saverate	save rate of the wavepacket	float

The generated grid is equidistant given by the following 113

$$t[i] = t_0 + i \cdot dt; \ i = 0, 1, 2, ..., Ntpts$$
 (4)

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$$Ntpts = \left\lceil \frac{t_{max} - t_0}{dt} \right\rceil \tag{5}$$

116 such that the array of time-points contains elements: t_{117} t[0], t[1], ..., t[Ntpts]. Note that the last point (tmax) is 118 included in the grid.

INPUT FILE

- molec name: name of the molecule (chiralium, h, h2s, etc.)
- matelem method: method of choice for the calculation of the potential energy matrix elements. Availability of methods given below depends on the chosen molecule.
 - analytic: use analytic formulas for the matrix elements
 - lebedev: use own implementation of the spherical Lebedev quadratures with fixed global quadrature level for all grid points defined in $sph_quad_global =$ "lebedev 119", "lebedev_131", etc.
 - lebedev adaptive: use own implementation of the spherical Lebedev quadratures with adaptive quadrature level, optimized for each grid point. Stopping condition is based on convergence criteria defined in sph quad tol tolerance (in a.u.) for the convergence of matrix elements with the maximal values of the l quantum number.

141	- quadpy: use the Quadpy library to calculate	150
142 143	the spherical integrals with Lebedev quadra- tures.	151
		15
144	- others: to be implemented.	15
145	• esp mode: method of choice for the calculation of	1 54
146	the cationic's core electrostatic potential.	155
147	- analytic: available only for the hydrogen atom	150
147	and some model systems.	157
148	· ·	158
149	- psi4: use psi4 quantum chemistry package for	

- calculate the ESP for all required points.
- anton: only available for the chiralium molecule. Read the precomputed potential kindly provided by A. Artemyev.
- $psi4_interpolated$: produce an interpolated ESP based on psi4 points.
- others: to be implemented. Any method one can imagine, including the use of other quantum chemistry software.