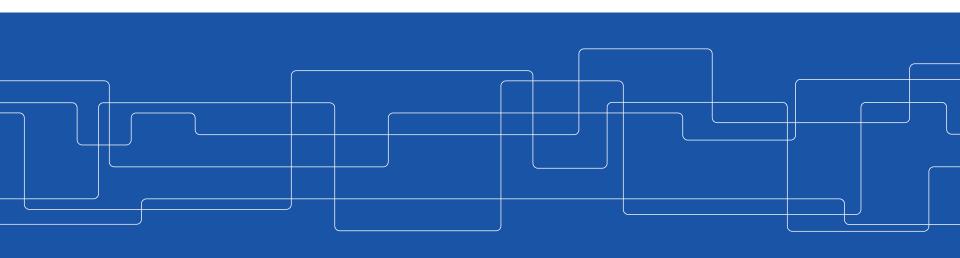


# Replication

Vladimir Vlassov and Johan Montelius





# Replication - why

#### Performance

- latency
- throughput

### Availability

service respond despite crashes

#### Fault tolerance

service consistent despite failures



# Challenge

A replicated service should, to the users, look like a non-replicated service.

What do we mean by "look like"?

- linearizable
- sequential consistency
- causal consistency
- eventual consistency



A replicated service is said to be *linearizable* if for any execution there is some interleaving of operations that:

- meets the specification of a non-replicated service
- matches the real time order of operations in the real execution

All operations seam to have happened: atomically, at the correct time, one after the other.

A register that provides lineraizability is called an atomic register



### Registers

#### Safe register

- If read does not overlap write, read returns the value written by the most recent write – the register is safe
- If read overlaps write, it returns any valid value

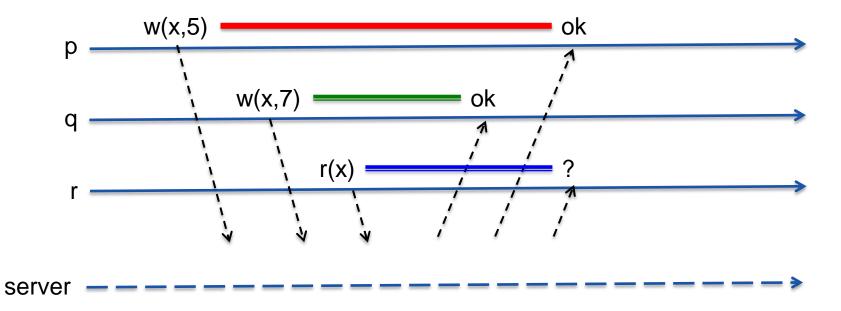
#### Regular register

- If read does not overlap write, the register is safe
- If read overlaps write, it returns either the old or the new value

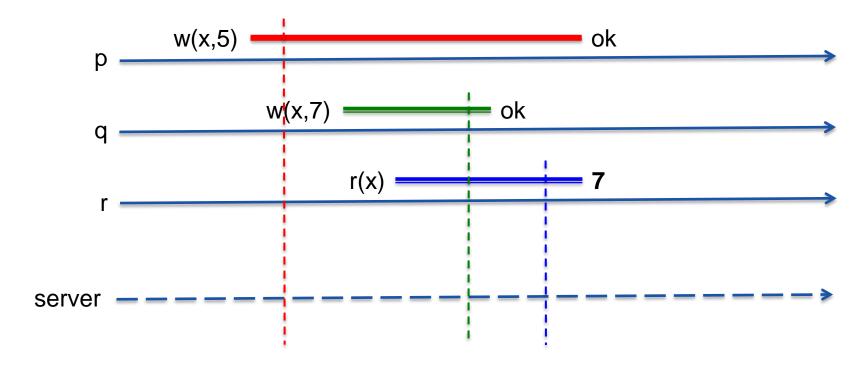
#### Atomic register (linearizable)

- If read does not overlap write, the register is safe
- If read overlaps with write, it returns either the old value or the new value but not newer than the next read

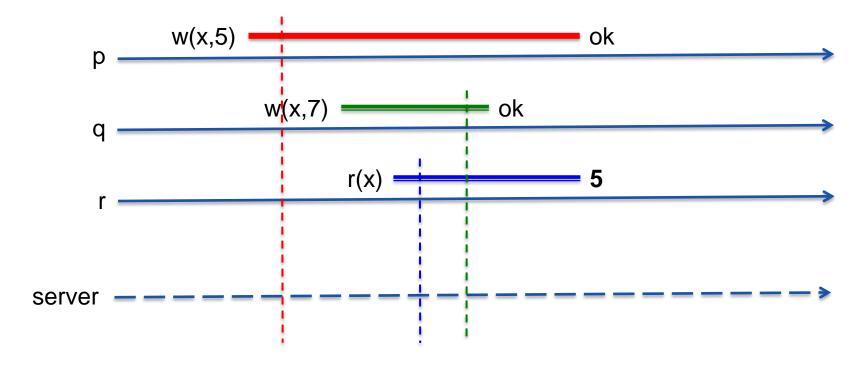




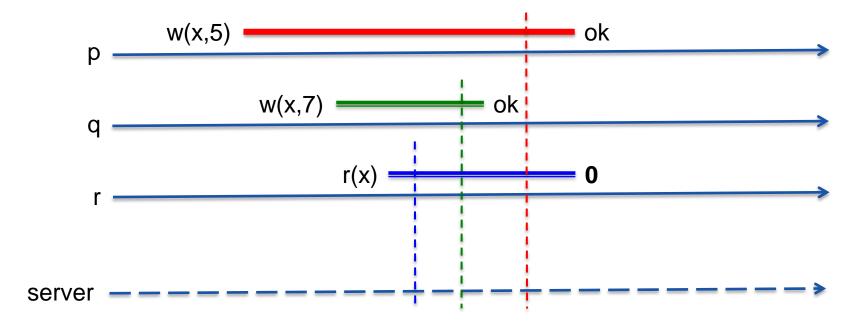








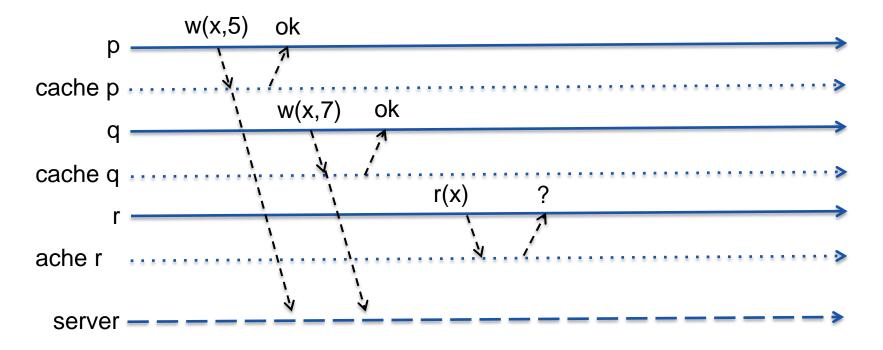




We guarantee that there is a sequence that makes sense.

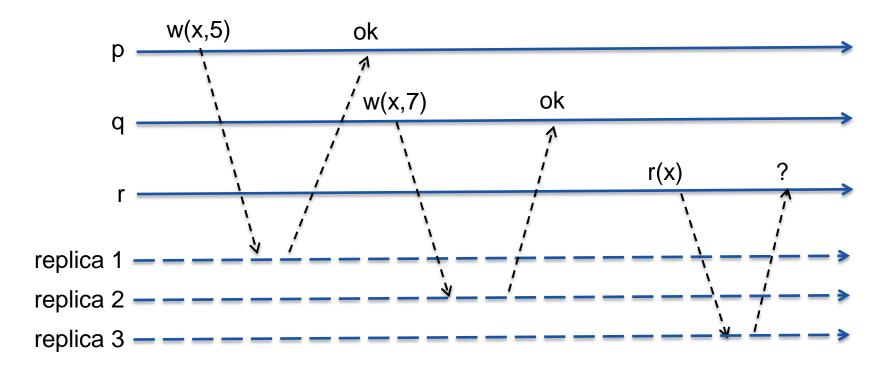


# Why would it not make sense?





### Why would it not make sense?





# **Sequential consistency**

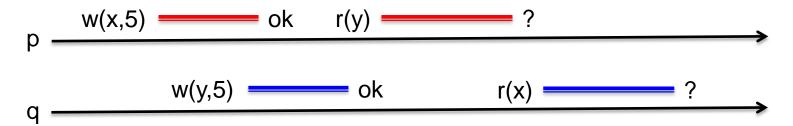
A replicated service is said to be **sequential consistent** if for any execution there is some interleaving of operations that:

- meets the specification of a non-replicated service
- matches the program order of operations in the real execution

Don't worry about real time as long as it make sense.

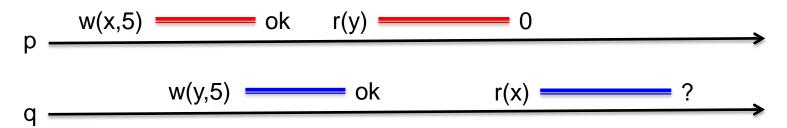


Assume x and y is initially set to 0



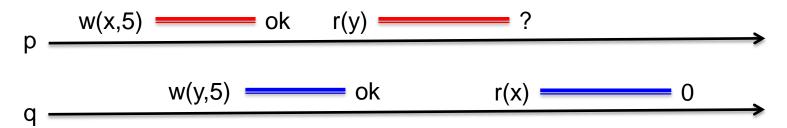


Assume x and y is initially set to 0



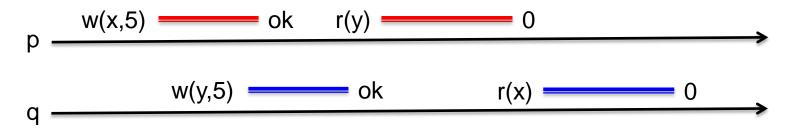


Assume x and y is initially set to 0





Assume x and y is initially set to 0

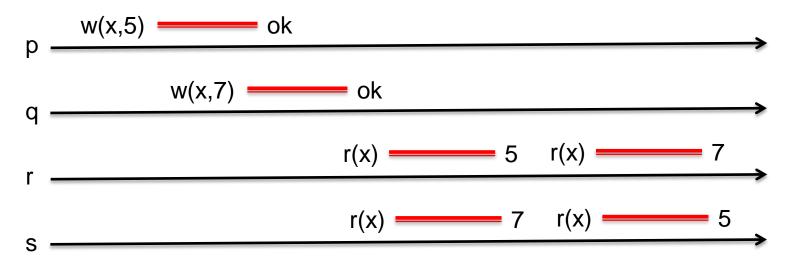


There should exist one total order of the operations that is consistent with the results.

Total Order Store: this is still ok in X86 architecture.



### Even more relaxed



As long as it make sense for each process.

Causal consistency, unordered operations could be seen in different order.



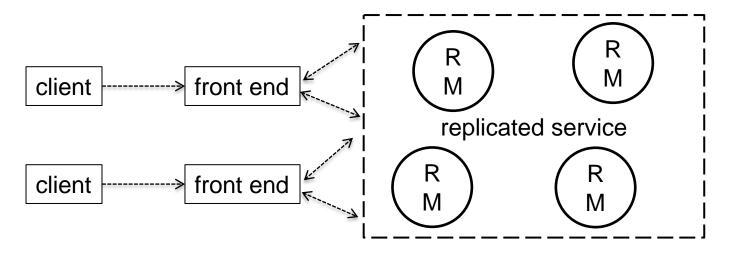
# **Eventual consistency**

There exist a total order that will eventually be visible to all.

More on this later.



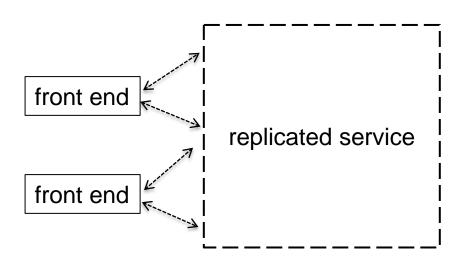
### Replication system model



- front end knows about replication scheme, could be implemented on the client side
- replica managers (RM) coordinate operations to guarantee consistency



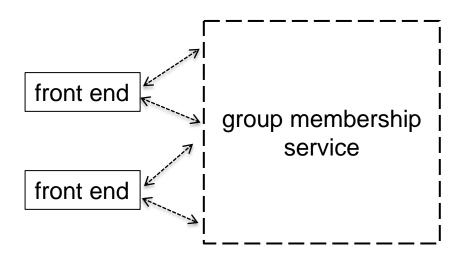
# Replication system model



- Request: from front end to one or more replicas
- Coordination: decide on order etc
- Execution: the actual execution of the request
- Agreement: agree on possible state change
- Response: reply received by frontend and delivered to client



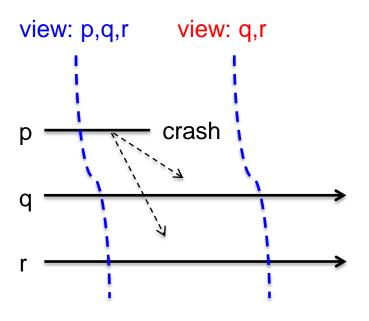
### **Group membership service**



- adding and removing nodes
- ordered multicast
- leader election
- view delivery



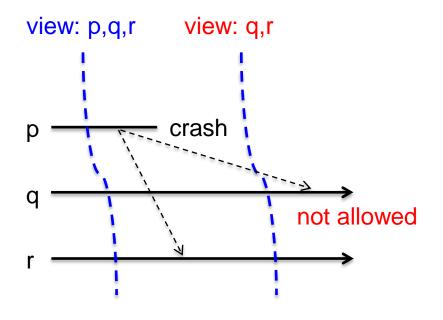
# View-synchronous group communication



- reliable multicast
- delivered in same view



### View-synchronous group communication



- reliable multicast
- delivered in same view
- never deliver from excluded node
- never deliver not yet included node

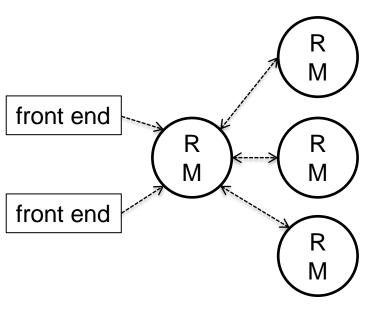


### Passive and active replication

- Passive replication: one primary server and several backup servers
- Active replication: servers on equal term



### **Passive replication**



- Request: front end sends request to primary
- Coordination: primary checks if it is a new request
- Execution: executes and stores response
- Agreement: sends updated state and reply to backup servers
- Response: sends reply to front-end



### What about crashes

#### Primary crashes:

- backups will receive new view with primary missing
- new primary is elected

#### if front end re-sends request

- either the reply is known and is resent
- or the execution proceeds as normal



# **Passive replication - consistency**

The primary replica manager will serialize all operations.

We can provide *linearizability*.



# Passive replication – Pros and cons

#### Pros

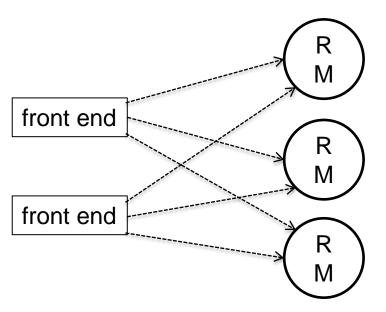
- All operations passes through a primary that linearize operations.
- Works even if execution is non-deterministic

#### Cons

- Delivering state change can be costly.
- Replicas under-utilized.
- View-synchrony and leader election could be expensive.



### **Active replication**



- Request: front end multicast to all
- Coordination: reliable total order delivery
- Execution: all replicas execute request
- Agreement: no need
- Response: all replicas reply to front end



# **Active replication - consistency**

#### Sequential consistency:

- All replicas execute the same sequence of operations.
- All replicas produce the same answer.

#### Linearizability:

- Total order multicast does not guarantee real-time order.
- Linearizability not guaranteed if front-end acknowledge operation before it has been processed by replicas.



# Active replication – Pros and cons

#### **Pros**

- No need to send state changes.
- No need to change existing servers.
- Read request could possibly be sent directly to replicas.
- Could survive Byzantine failures.

#### Cons:

- Requires total order multicast.
- Requires deterministic execution.



### **Availability**

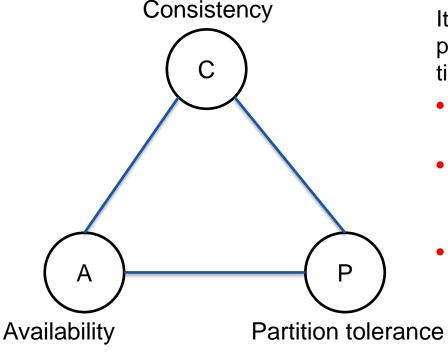
Both replication schemes require that servers are available.

If a server crashes it will take some time to detect and remove the faulty node.

Can we build a system that responds even if some nodes are not available?



### The CAP theorem



It is impossible for a distributed system to provide all three guarantees at the same time:

- Consistency (all nodes see the same data at the same time)
- Availability (every request receives a response about whether it succeeded or failed)
- Partition tolerance (the system continues to operate despite arbitrary partitioning due to network failures)



### The CAP theorem

You can not have a consistent and always available system if you're in an environment where you face network partitions.

When there is a network partition:

- limit operations i.e. some operations are not available,
- continue, but record all operations that could cause an inconsistency.

When the system re-connects: merge operations performed in separate partitions.



### The CAP theorem

An alternative is to relax consistency.

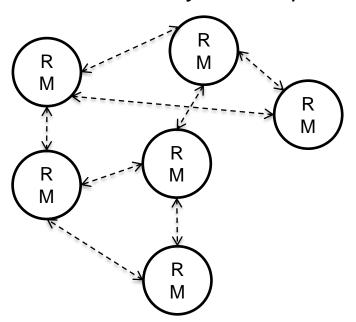
BASE: Basic Availability, Soft-state, Eventual consistency

Used by many large scale key-value stores and replicated distributed services



### **Gossip architecture**

What if we only need to provide causal consistency?



- replica managers interchange update messages
- updates propagate through the network
- sequential consistency not guaranteed
- we want to provide causal consistency



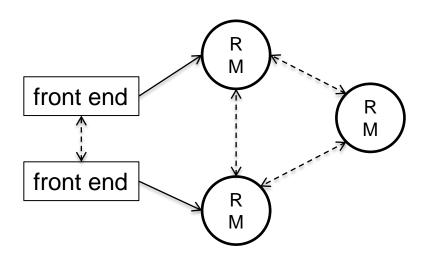
#### **Vector clocks**

A vector clock with one index per replica manager.

Each update will be tagged with a vector clock timestamp.

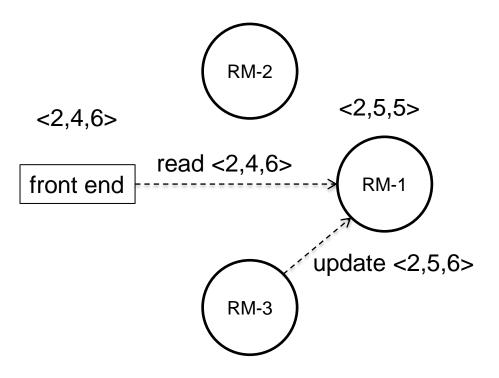
Some updates are concurrent!





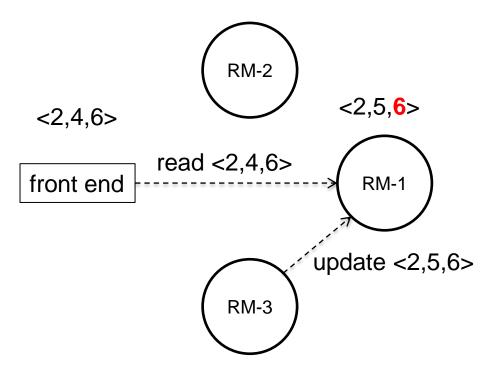
- one index per replica manager
- front ends keep vector clocks
- replica mangers apply updates in order
- causal consistency guaranteed





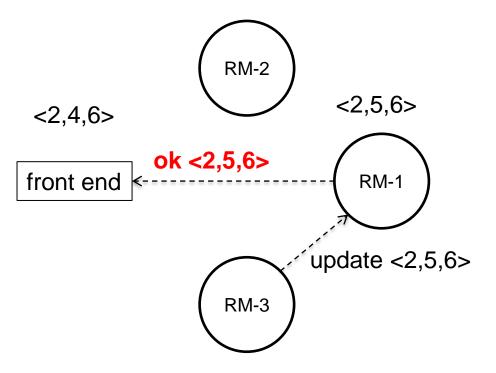
- send a query with timestamp
- check current time, wait for updates
- update will arrive





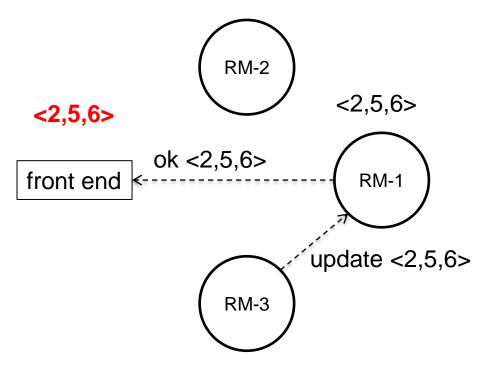
- send a query with timestamp
- check current time, wait for updates
- update will arrive
- update state and clock





- send a query with timestamp
- check current time, wait for updates
- update will arrive
- update state and clock
- reply





- send a query with timestamp
- check current time, wait for updates
- update will arrive
- update state and clock
- reply
- update state and clock



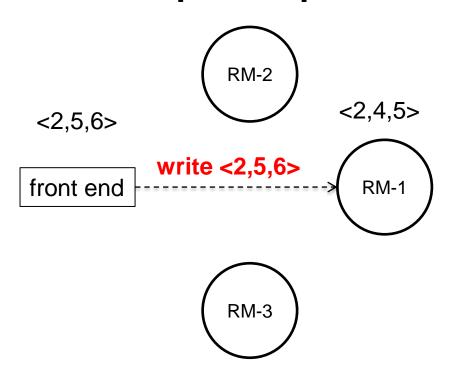
# The replica manager

The replica manager has a *hold-back queue*, operations that are too early to execute.

As updates arrive the replica will execute updates, and pending read operations.

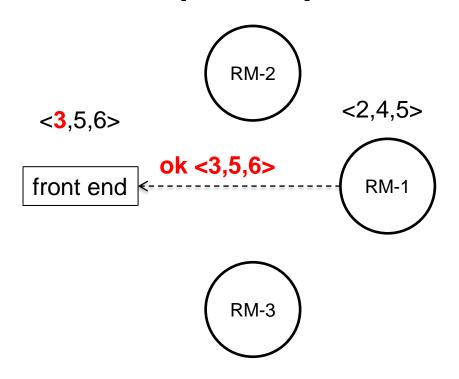
Updates are partially ordered.





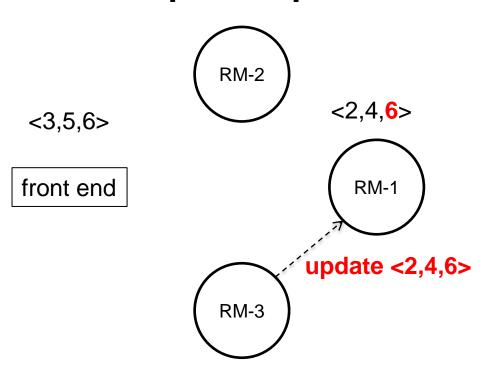
operation with timestamp





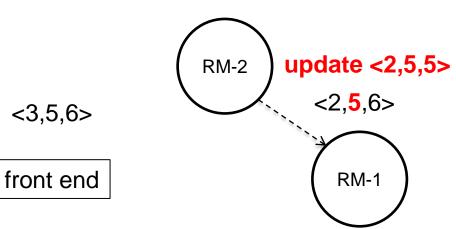
- operation with timestamp
- reply with unique timestamp



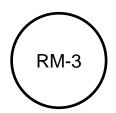


- operation with timestamp
- reply with unique timestamp
- wait for updates

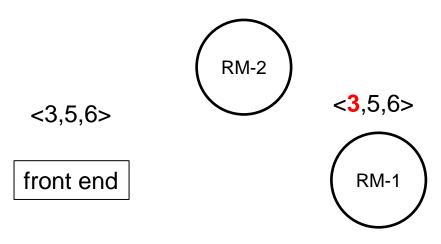




- operation with timestamp
- reply with unique timestamp
- wait for updates







RM-3

- operation with timestamp
- reply with unique timestamp
- wait for updates
- perform write when safe



### **Implementation**

**Read operations**: on hold until safe to answer.

#### **Update operations** from front end.

- front end adds unique id
- replica checks that it is not a duplicate
- replica replies with unique timestamp
- placed in update log

#### Gossip operations

- interchange part of update log with partners
- place in update log
- provide information on which message a replica has seen
- remove applied operations that has been seen by all replicas

#### **Execute operations**

- apply stable operations
- in *happen before* order



# Stable operations and order of execution

- An operation in the log is stable if its time stamp, as provided by the front end, is less than or equal to the value timestamp.
- Operations must be executed in the order as described by the replica managers in their replies to the front ends.



### Causal, forced and immediate

Sometimes we would like to have stronger consistency guarantees:

- Forced: total order in relation to other forced updates.
- Immediate: total order in relation to all updates.

Will of course require that we do some more book keeping.



## **Gossip architectures**

- How many replicas can we have?
- Have hundreds of read-only replicas and a handful of update replicas.
- Will an application cope with causal consistency only?
- How eager should the gossiping be?
- False ordering we order things that are not necessarily in causal relation to each other.



## Summary

- Replication: performance, availability, fault tolerance
- Consistency: linearizable, sequential consistency, ...
- Passive or active replication
- The CAP theorem
- Gossip architectures for causal consistency