

•  $\frac{\partial \phi_i}{\partial x_j} = ?$   
(last lecture)

$$F_\omega(x_1, \dots, x_j, \dots, x_m, \phi_1(x_1, \dots, x_m), \dots, \phi_i(x_1, \dots, x_m), \dots) = 0$$

$$\frac{d}{dx_j} F_\omega = \frac{\partial F_\omega}{\partial x_j} + \sum_{\ell=1}^n \frac{\partial F_\omega}{\partial y_\ell} \frac{\partial \phi_\ell}{\partial x_j} = 0, \ell = 1, 2, \dots, n$$

$$\left( \frac{\partial F_\omega}{\partial y_\ell} \right)_{\ell, j} D\phi = - \left( \frac{\partial F_\omega}{\partial x_j} \right)_{j, j}$$

## Extreme values

We work with:  $U \subset \mathbb{R}^n \rightarrow \mathbb{R}$  Important:

- Def<sup>n</sup>  $(a, b)$  is a critical point of  $f$  if  $\nabla f(a, b) = 0$
- $f$  attains an extreme value (max or min) at a critical point, singular point or a boundary point
- The Hessian matrix of a function
- How to use the Hessian matrix to classify the critical point of  $f$ .
- The definition of a saddle point of  $f$ .

(same sign)

All directional derivatives must have a positive/negative derivative at a point for that point to be a minimum/maximum.

Examples of different extremums in highlights on GitHub.

Classifying interior critical points by the Hessian matrix of  $f$

$$f(x, y) \quad \vec{a} \in \mathbb{R}^2 \quad f(\vec{a}) \quad \vec{a} + t\vec{h} \text{ --- a line in the domain } f(\vec{a} + t\vec{h})$$

The function  $g(t) := f(\vec{a} + t\vec{h})$  is a single variable function that reveals how the value of  $f$  changes along the curve  $\vec{a} + t\vec{h}$

- $a$  is an interior critical point of  $f$ :

$$g'(t) = (\vec{h} \cdot \nabla) f(\vec{a} + t\vec{h}) h_1 h_j = \vec{h}^T \mathcal{H}(\vec{a} + t\vec{h}) \vec{h} = h_1 f_1(\vec{a} + t\vec{h}) + h_2 f_2(\vec{a} + t\vec{h}) + \dots$$

- Classify the interior critical points by  $g''$ :

$$g''(t) = (\vec{h} \cdot \nabla)^2 f = \sum_{i=1}^n \sum_{j=1}^n f_{ij}(\vec{a} + t\vec{h}) h_i h_j = \vec{h}^T \mathcal{H}(\vec{a} + t\vec{h}) \vec{h}$$

$$f: \mathbb{R}^n \rightarrow \mathbb{R}$$

$$\begin{array}{l} \vec{a} \in \mathbb{R}^n \\ \vec{h} \in \mathbb{R}^n \end{array} \left. \begin{array}{l} \text{column} \\ \text{vectors} \end{array} \right\}$$

the line:  $\vec{a} + t\vec{h}$

The restriction of  $f$  along the curve

$$g(t) = f(\vec{a} + t\vec{h})$$

$$g''(0) = \vec{h}^T H \vec{h}$$

The Hessian matrix of  $f$

$$H(\vec{x}) := \begin{pmatrix} f_{11} & f_{12} & \dots & f_{1n} \\ f_{21} & f_{22} & \dots & f_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ f_{n1} & f_{n2} & \dots & f_{nn} \end{pmatrix}$$

- For every  $\vec{x}$ ,  $H(\vec{x})$  is a square matrix (symmetric if  $f$  has continuous partial derivatives up to at least second order)
- $f$  has a local minimum at  $\vec{a}$  if  $g''(0) > 0$  for every possible  $\vec{h}$ ; i.e. if  $H$  is positive definite
- A matrix is positive (negative) definite if all its eigenvalues are positive (negative)

$$\text{Ex } f(x, y, z) = x^2y + y^2z + z^2 - 2x$$

CRITICAL PT:

$$\nabla f(x, y, z) = \vec{0} = \begin{pmatrix} f_x \\ f_y \\ f_z \end{pmatrix} = \begin{pmatrix} 2xy - 2 \\ x^2 + 2yz \\ y^2 + 2z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\Rightarrow P = (1, 1, -\frac{1}{2})$$

$$H(x, y, z) = \begin{pmatrix} f_{xx} & f_{xy} & f_{xz} \\ f_{yx} & f_{yy} & f_{yz} \\ f_{zx} & f_{zy} & f_{zz} \end{pmatrix} = \begin{pmatrix} 2y & 2x & 0 \\ 2x & 2z & 2y \\ 0 & 2y & 2 \end{pmatrix} \quad H(P) = \begin{pmatrix} 2 & 2 & 0 \\ 2 & -1 & 2 \\ 0 & 2 & 2 \end{pmatrix}$$

$$\text{Eigen values} = \begin{pmatrix} -2, 701, \dots \\ 2 \\ 3, 701, \dots \end{pmatrix}$$

$$\text{Ex } f(x, y) := 1 - x$$

- Interior critical point? NO

$$\nabla f = \begin{pmatrix} -1 \\ 0 \end{pmatrix}$$

- Singular point? NO

- Boundary point?

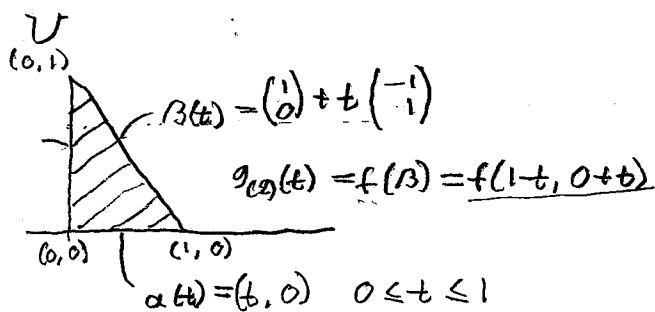
Boundary:  $(\cos(t), \sin(t))$

$$g(t) = f(\cos(t), \sin(t))$$

$$g'(t) = f_1(-\sin(t)) + f_2(\cos(t))$$

$$\sin(t) = 0, \quad t = 0 \text{ (bc min)} \text{ or } t = \pi \text{ (bc max)}$$

$$g''(t) = \cos(t) \quad \cos(0) = 1 > 0$$



$$g(t) = f(t, \alpha(t))$$