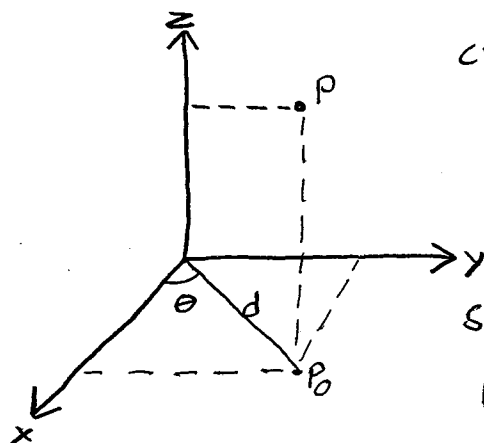
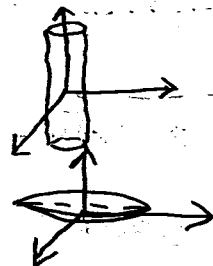


Back to the cylindrical and spherical coordinates.



cylindrical coordinates:

$$(x, y, z) \rightarrow (d, \theta, z)$$

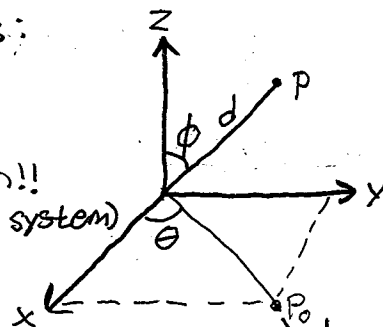


spherical coordinates:

$$(x, y, z) \rightarrow (d, \phi, \theta)$$

$$\begin{aligned} d &\geq 0 \\ 0 &\leq \theta \leq 2\pi \\ 0 &\leq \phi \leq \pi \end{aligned}$$

new position!!
(right handed system)

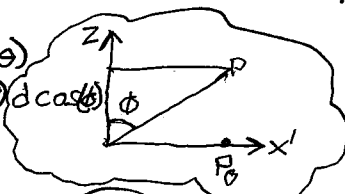


Problem: Given a point in spherical coordinates (d, ϕ, θ) , what are the cartesian coordinates for that point?

$$x = f_1(\theta, d, \phi) = \overline{OP_0} \cos \theta = d \sin(\phi) \cos(\theta)$$

$$y = f_2(\theta, d, \phi) = \overline{OP_0} \sin \theta = d \sin(\phi) \sin(\theta)$$

$$z = f_3(\theta, d, \phi) = f_3(d, \phi) = d \cos(\phi)$$



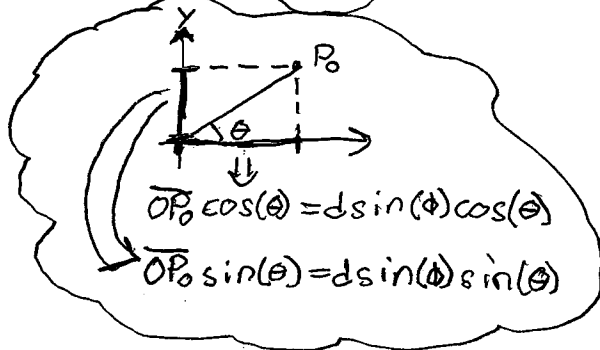
Question: We consider a system with spherical coordinates and a point P with coordinates $P = (2, \pi/3, \pi/2)$

Find the cartesian coordinates of P.

$$x = 2 \sin(\pi/3) \cos(\pi/2) = 2 \cdot \frac{\sqrt{3}}{2} \cdot 0 = 0$$

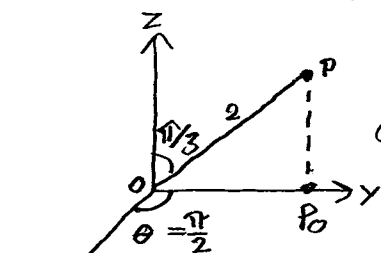
$$y = 2 \sin(\pi/3) \sin(\pi/2) = 2 \cdot \frac{\sqrt{3}}{2} \cdot 1 = \sqrt{3}$$

$$z = 2 \cos(\pi/3) = 2 \cdot \frac{1}{2} = 1$$



P lies on the plane $x=0$

Cartesian coordinates of P are $(0, 2 \sin(\pi/3), 2 \cos(\pi/3)) = (0, \sqrt{3}, 1)$

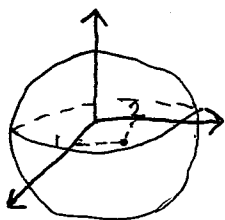


Next question: Show that the surface $p = 4 \sin(\phi) \sin(\theta) + 2 \sin(\phi) \cos(\theta)$ corresponds to

$$(x-1)^2 + (y-2)^2 + z^2 = 5$$

sphere with center $(1, 2, 0)$ and radius $\sqrt{5}$

(Not answered during lecture)



Problem: Given (x, y, z) , how do we find the corresponding (d, ϕ, θ) ?

$$d = \sqrt{x^2 + y^2 + z^2} \quad (\text{length of segment } \overline{OP})$$

$$\cos(\phi) = \frac{z}{d} = \frac{z}{\sqrt{x^2 + y^2 + z^2}} \Rightarrow \phi = \arccos\left(\frac{z}{\sqrt{x^2 + y^2 + z^2}}\right)$$

$$\tan(\theta) = \frac{y}{x} \Rightarrow \theta = \arctan\left(\frac{y}{x}\right)$$

$$\Rightarrow \begin{cases} d = \sqrt{x^2 + y^2 + z^2} \\ \phi = \arccos\left(\frac{z}{\sqrt{x^2 + y^2 + z^2}}\right) \\ \theta = \arctan(y/x) \end{cases}$$

Sections 11.1, 11.2

Position of the particle can be (mathematically) described by a vector

$$f(t) = \vec{r}(t) = \begin{matrix} \text{vector} \\ \text{valued} \\ \text{function} \end{matrix}$$

$$= (r_1(t), r_2(t), r_3(t)) = r_1(t)\vec{i} + r_2(t)\vec{j} + r_3(t)\vec{k}$$

Given the vector-valued function $\vec{r}(t) = (x(t), y(t), z(t))$

velocity: $\frac{d}{dt}\vec{r}(t) = (x'(t), y'(t), z'(t)) = \vec{r}'(t)$
 tangent vector to the curve at the time t .

magnitude of the velocity: $|\vec{r}'(t)| = \text{length of the vector } \vec{r}'(t)$

$$= \sqrt{(x')^2(t) + (y')^2(t) + (z')^2(t)}$$

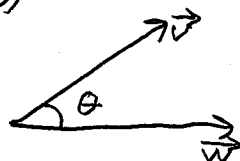
Acceleration: $\vec{r}''(t) = (x''(t), y''(t), z''(t))$

Given two vectors $\vec{v} = (v_1, v_2, v_3)$, $\vec{w} = (w_1, w_2, w_3)$, then the DOT-PRODUCT (OR SCALAR PRODUCT) is defined as:

$$\vec{v} \cdot \vec{w} := v_1 w_1 + v_2 w_2 + v_3 w_3 = |\vec{v}| |\vec{w}| \cos(\theta)$$

$$\vec{v} \cdot \vec{v} = v_1^2 + v_2^2 + v_3^2 = |\vec{v}|^2$$

$$\Rightarrow |\vec{v}| = \sqrt{\vec{v} \cdot \vec{v}}$$



$$\vec{v}(t) = (v_1(t), v_2(t), v_3(t)), \quad \vec{w}(t) = (w_1(t), w_2(t), w_3(t))$$

$$\frac{d}{dt} \vec{v}(t) \cdot \vec{w}(t) = \frac{d}{dt} [v_1(t)w_1(t) + v_2(t)w_2(t) + v_3(t)w_3(t)] = \underbrace{v_1'(t)w_1(t) + v_1(t)w_1'(t)}_{v_1'(t)w_1(t) + v_1(t)w_1'(t)} + \underbrace{v_2'(t)w_2(t) + v_2(t)w_2'(t)}_{v_2'(t)w_2(t) + v_2(t)w_2'(t)} + \underbrace{v_3'(t)w_3(t) + v_3(t)w_3'(t)}_{v_3'(t)w_3(t) + v_3(t)w_3'(t)}$$

$$= \underbrace{\vec{v}'(t) \cdot \vec{w}(t)}_{\vec{v}'(t) \cdot \vec{w}(t)} + \underbrace{\vec{v}(t) \cdot \vec{w}'(t)}_{\vec{v}(t) \cdot \vec{w}'(t)}$$

$$\Rightarrow \textcircled{1} \frac{d}{dt} \vec{v} \cdot \vec{w} = \vec{v}' \cdot \vec{w} + \vec{v} \cdot \vec{w}'$$

$$\frac{d}{dt} |\vec{v}(t)| = \frac{d}{dt} \sqrt{v_1^2(t) + v_2^2(t) + v_3^2(t)}$$

$$= \frac{1}{2\sqrt{v_1^2(t) + v_2^2(t) + v_3^2(t)}} \cdot \frac{d}{dt} (v_1^2(t) + v_2^2(t) + v_3^2(t))$$

$$= \frac{1}{2\underbrace{(\sqrt{v_1^2(t) + v_2^2(t) + v_3^2(t)})}_{|\vec{v}|}} (2v_1(t)v_1'(t) + 2v_2(t)v_2'(t) + 2v_3(t)v_3'(t)) = \frac{1}{|\vec{v}|} \vec{v} \cdot \vec{v}'$$

$$\Rightarrow \textcircled{2} \frac{d}{dt} |\vec{v}| = \frac{\vec{v} \cdot \vec{v}'}{|\vec{v}|}$$