

SF1626 2018-09-06 #6

RED CURVE: $\vec{\gamma}_1(t)\vec{i} + \vec{\gamma}_2(t)\vec{j} + \vec{\gamma}_3(t)\vec{k} = f(\gamma_1(t), \gamma_2(t))$

LIES ON THE GRAPH OF $f(x, y)$

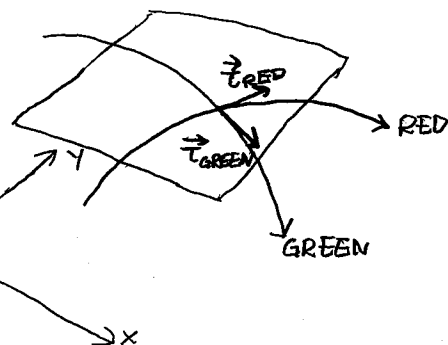
GREEN CURVE: $\vec{\gamma}_{\text{GREEN}}(t)$

$(a, b, f(a, b))$

$a\vec{i} + b\vec{j} + f(a, b)\vec{k}$

$$\vec{T}_{\text{RED}}(t) = \begin{pmatrix} \gamma_1'(t) \\ \gamma_2'(t) \\ \gamma_3'(t) \end{pmatrix}$$

$$\vec{T}_{\text{GREEN}}(y) = \begin{pmatrix} 0 \\ 1 \\ f_2(a, y) \end{pmatrix}$$



General tangent plane: $z = f_1(a, b)(x - a) + f_2(a, b)(y - b) + f(a, b)$

Normal line: $a\vec{i} + b\vec{j} + f(a, b)\vec{k} + t(n_1\vec{i} + n_2\vec{j} + n_3\vec{k})$

Higher-order derivatives

$$f_{11}(x, y) = \frac{\partial}{\partial x} f_1(x, y) \quad f_{12}(x, y) = \frac{\partial}{\partial y} f_1(x, y)$$

$$f_{21}(x, y) = \frac{\partial}{\partial x} f_2(x, y) \quad \dots \quad f_{321} = \frac{\partial}{\partial x} \left(\frac{\partial}{\partial y} \left(\frac{\partial}{\partial z} f \right) \right) (= f_{zyx})$$

$f_{xy}(a, b) = f_{yx}(a, b)$ if f_x, f_y, f_{xy} and f_{yx} are all continuous at (a, b)

Similarly $f_{xyx} = f_{xxy} = f_{yxx}$ if partial derivatives are continuous

Laplace and wave equation

Laplace equation for $(x, y) \rightarrow \mathbb{R}$: $u_{xx} + u_{yy} = 0$

If fulfilled then u is called harmonic

Wave equation for $(x, y, t) \rightarrow \mathbb{R}$: $u_{tt} = u_{xx} + u_{yy}$

$$\Delta f = 0$$

Δ Laplace operator

$$f_{xx} + f_{yy}$$

Ex. $f(x, y) = e^{kx} \cos(ky)$ Show that f solves the Laplace equation.

$$f_x = kf \Rightarrow f_{xx} = k^2 f \quad f_y = -ke^{kx} \sin(ky) \Rightarrow f_{yy} = -k^2 e^{kx} \cos(ky) = -k^2 f$$

$$\Rightarrow f_{xx} + f_{yy} = 0$$

Linear approximations

Tangent plane $L(x, y)$ of f at (a, b) as a function is called the linearization of f at (a, b)

$$L(x, y): z = f(a, b) + f_1(a, b)(x - a) + f_2(a, b)(y - b)$$

Similar things to Taylor-polynomials exist for multiple variables

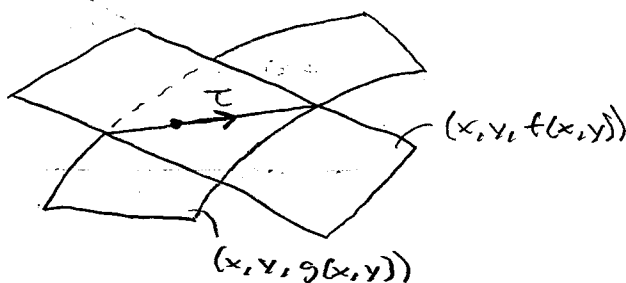
Given two functions $f(x,y)$, $g(x,y)$. Find the tangent to the intersection

$$\vec{n}_f = \nabla(z - f(x,y)) \text{ normal to } f$$

$$\vec{n}_g = \nabla(z - g(x,y)) \text{ normal to } g$$

$$\vec{T} \parallel \vec{n}_f \times \vec{n}_g$$

orthogonal to both normal vectors



$L(x,y)$ is an affine function. $L(x,y) = f(a,b)$ is a linear function of x and y

$L(a+h, b+k) \approx f(a,b)$; in general, L is a very good approximation of f near (a,b) .

Later, if f can be approximated "well enough" by L , we say that f is differentiable

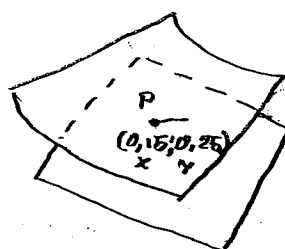
ex. $f(x,y) = \sqrt{2x^2 + e^{2y}}$ find partial derivatives:

Find the tangent plane to f
at the point $(0.15; 0.25)$

x y

$$f_x = \frac{\partial x}{\partial f(x,y)}$$

$$f_y = \frac{\partial y}{\partial f(x,y)}$$



The plane is a good approximation to the curve near the point P .

tangent plane:

$$L(x,y) = f(a,b) + f_x(a,b)(x-a) + f_y(a,b)(y-b)$$

Defⁿ 5 Let $L(x,y)$ be the linearization of f at (a,b)

We say that $f(x,y)$ is differentiable at the point (a,b) if:

$$\lim_{(h,k) \rightarrow (0,0)} \left(\frac{L(x+h, y+k) - f(a,b)}{\sqrt{h^2 + k^2}} \right) = 0$$

This means that the difference between $L(x+h, y+k)$ and $f(a,b)$ approaches zero "faster" than $\sqrt{h^2 + k^2}$ approaches zero, as $(h,k) \rightarrow (0,0)$

Mean Value Theorem

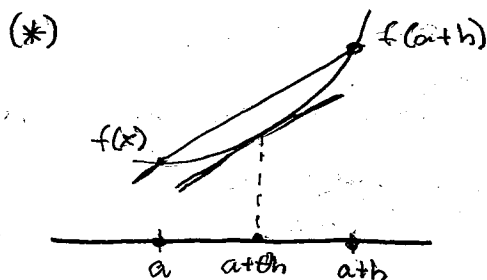
If $f_1(x,y)$ and $f_2(x,y)$ are constants in a neighborhood of the point (a,b) and if $|h|$ and $|k|$ are sufficiently small, then there exist θ_1 and θ_2 between 0 and 1 such that

$$f(a+h, b+k) - f(a,b) = h \cdot f_x(a + \theta_1 h, b + k) + k f_y(a, b + \theta_2 k)$$

see image (*) (next page)

Theorem 4

If $f_1(x,y)$ and $f_2(x,y)$ are continuous in a neighborhood of (a,b) , then f is differentiable at (a,b)



Differentials

The differential of $f(x, y)$ is defined as $df: \mathbb{R}^2 \times \mathbb{R}^2 \rightarrow \mathbb{R}$

$$df \equiv df(x, y, dx, dy) := f_x(x, y)dx + f_y(x, y)dy$$

Compare df to the linearization of f around (x, y)

$$L(x+dx, y+dy) := f(x, y) + f_1(x, y)dx + f_2(x, y)dy \leftarrow \text{Almost like Taylor-polynomials (SF1625)}$$

It approximates the change of f

General formulas for $f: \mathbb{R}^n \rightarrow \mathbb{R}^m$

$$y_1 = f(x_1, x_2, \dots, x_n) \quad (1)$$

$$y_2 = f(x_1, x_2, \dots, x_n) \quad (2)$$

$$y_m = f(x_1, x_2, \dots, x_n) \quad (m)$$

The Jacobian matrix of f

$$Df(x) = \left(\frac{\partial f_i}{\partial x_j}(x) \right) \equiv \begin{pmatrix} \frac{\partial f_1}{\partial x_1} & \frac{\partial f_1}{\partial x_2} & \dots & \frac{\partial f_1}{\partial x_n} \\ \frac{\partial f_2}{\partial x_1} & & & \\ \vdots & \ddots & & \vdots \\ \frac{\partial f_m}{\partial x_1} & \dots & \frac{\partial f_m}{\partial x_n} \end{pmatrix}$$

$$dy := Df(x)dx$$

Chain rule

$$g: \mathbb{R}^m \rightarrow \mathbb{R}^k$$

$$D(g \circ f)(x) = Dg(f(x)) Df(x)$$