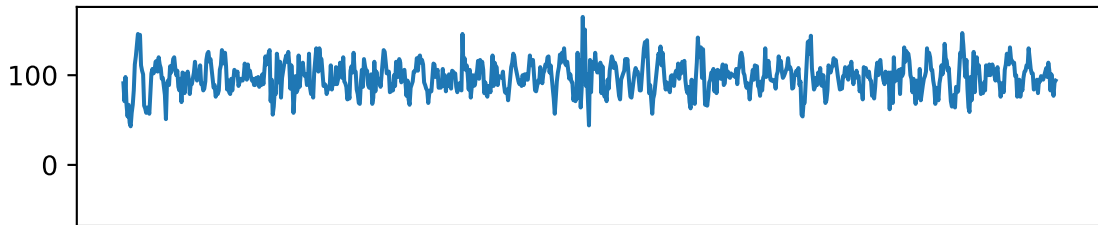


Comparison of filtered and unfiltered accelerometer data for the stationary robot

Unfiltered data



Filtered data

