

# Indexing Vectors

Alfan F. Wicaksono

<https://www.pinecone.io/learn/series/faiss/hnsw/>

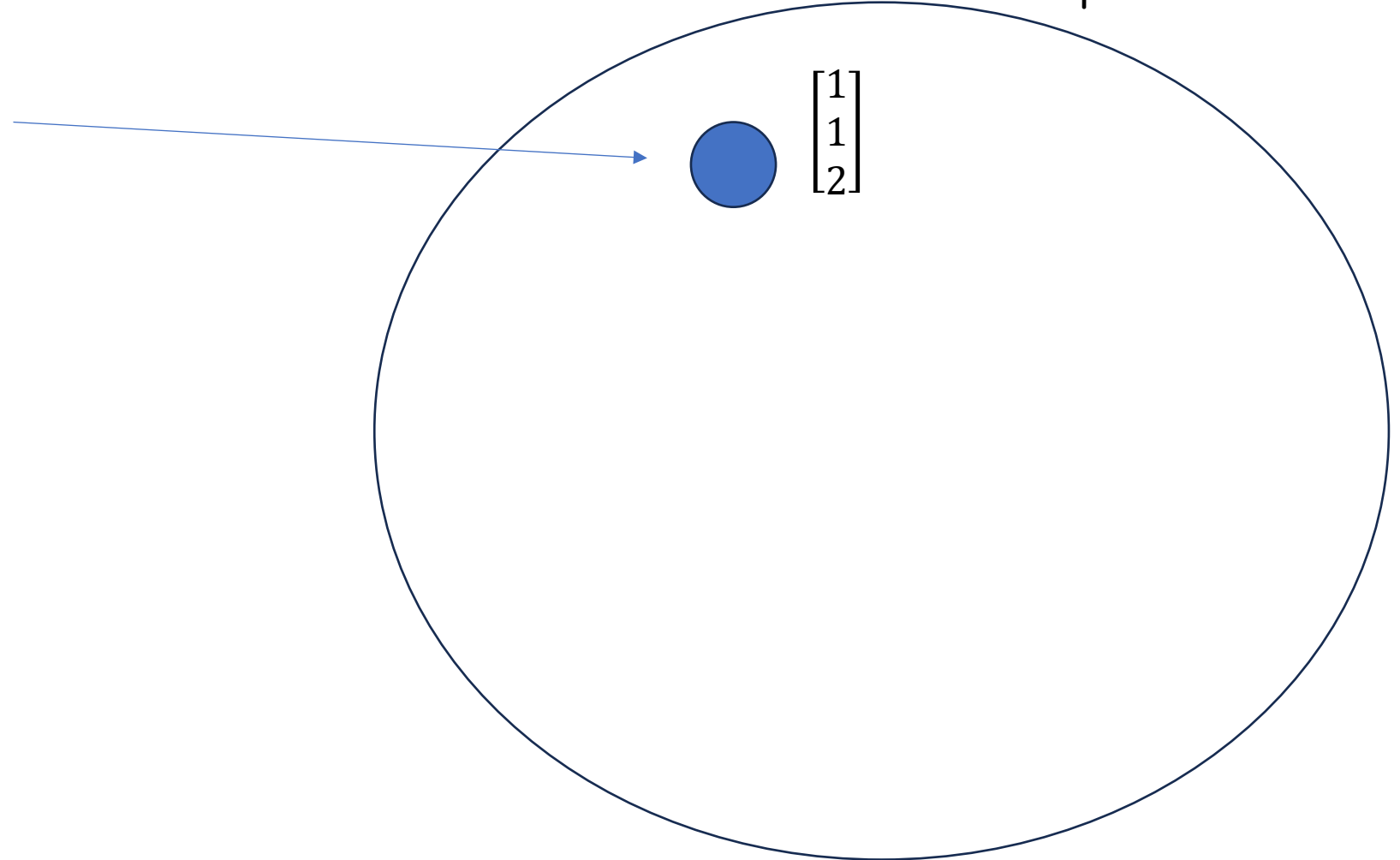
# Nowadays, everything can be encoded into vectors (or tensors)

inverted index (term document indexing), terlalu sparse, tidak bisa mengerti semantic meaning

## Vector Database

"A collection of vectors from the same vector space"

"Gedung Fasilkom UI"

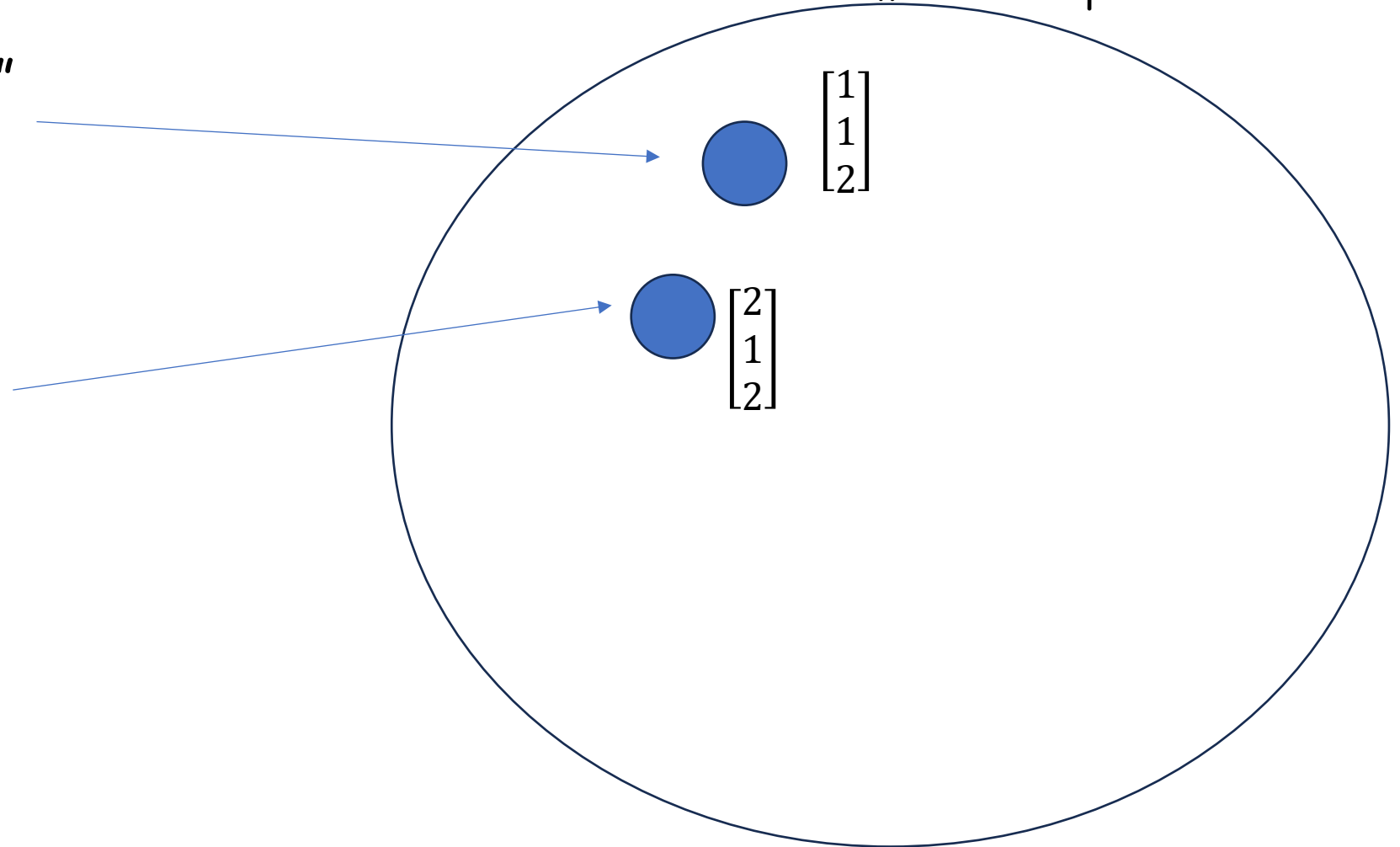


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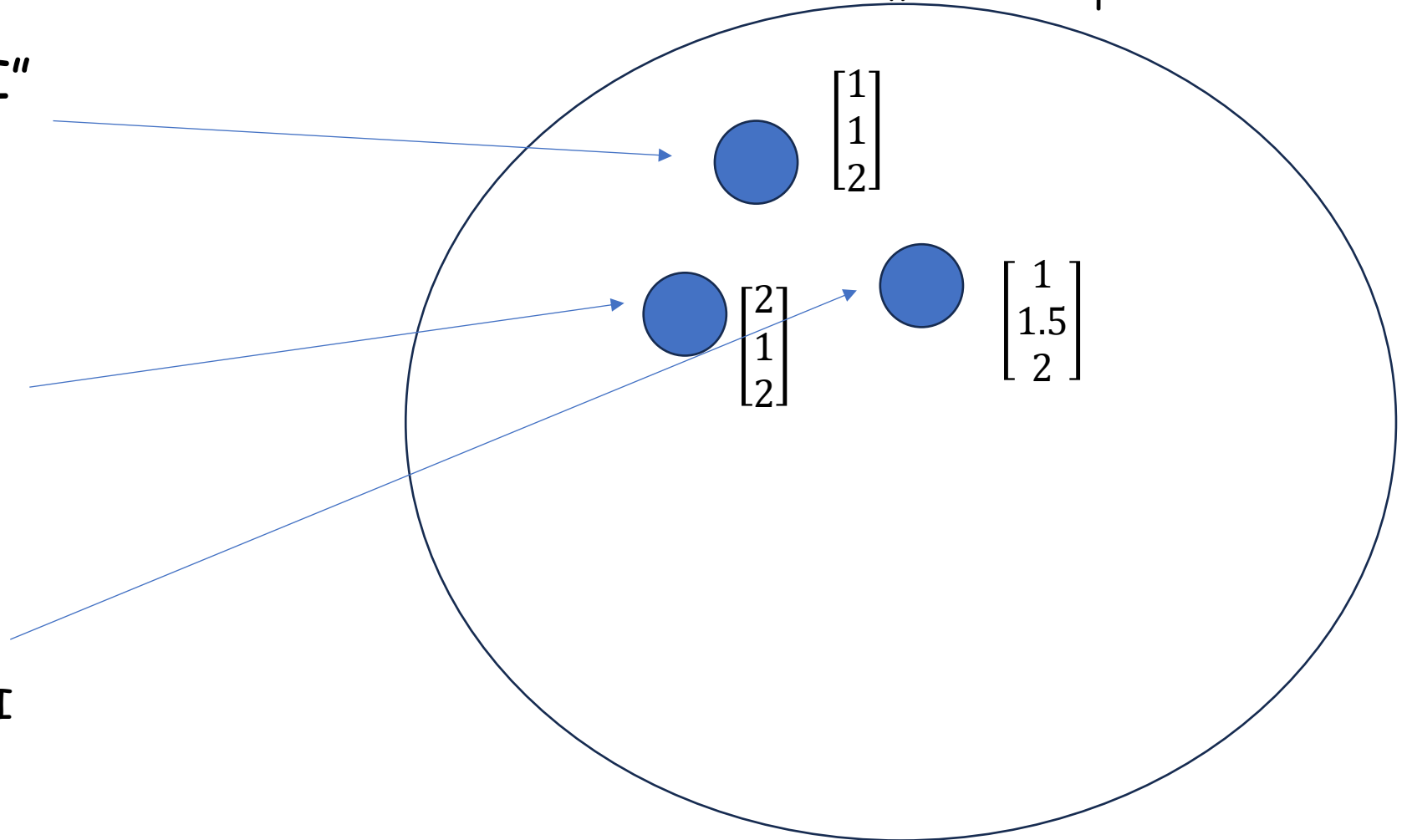
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Music: Mars Fasilkom UI



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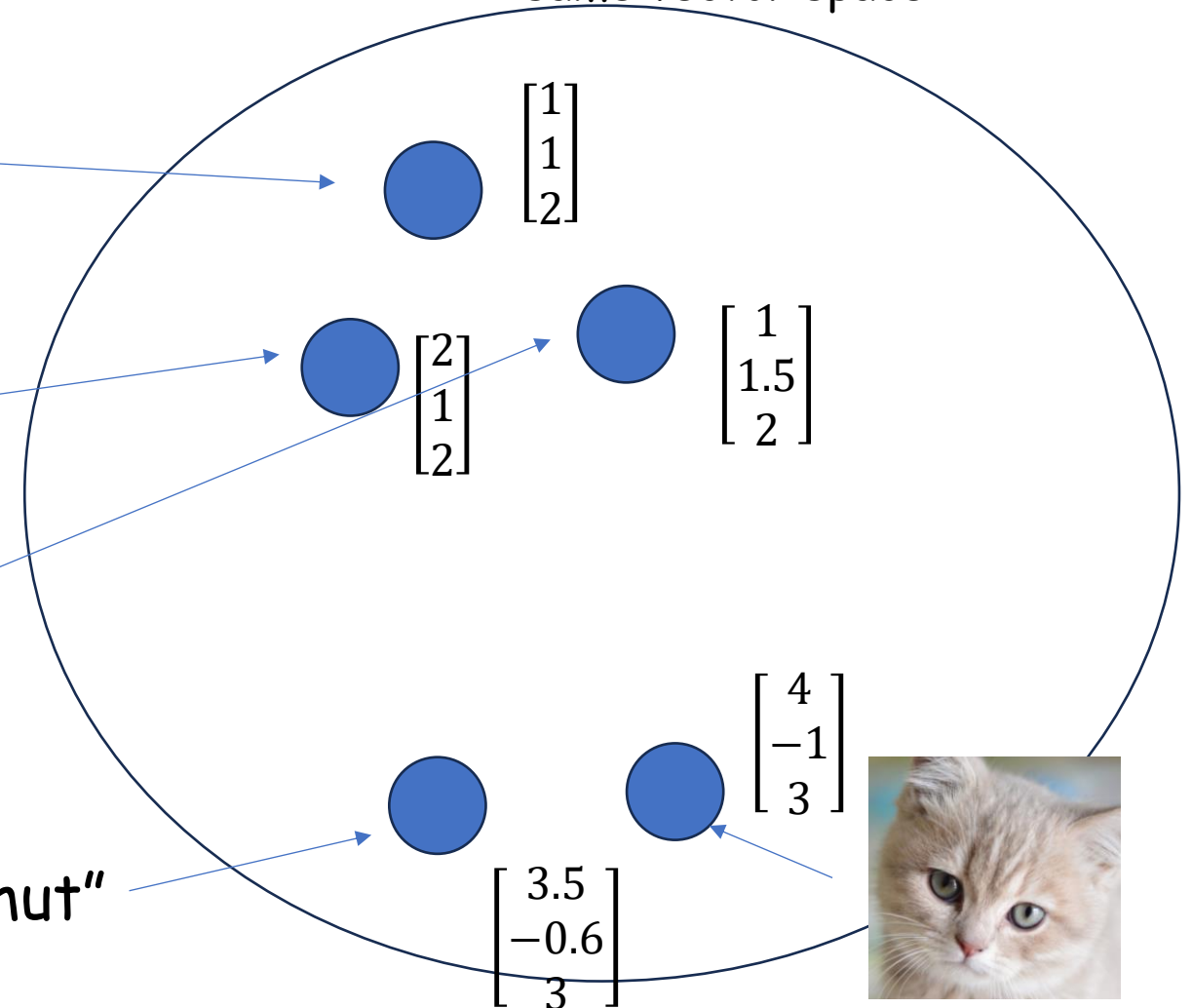
"A collection of vectors from the same vector space"

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Music: Mars Fasilkom UI

"kucing imut"



# K-Nearest neighbor search

- Given a query (which can be in any format, including text, image, or audio), find other items that are “similar” to the query.
  - Nowadays, everything can be represented as **vectors**!
- Given a set  **$S$**  of points in a space  **$M$**  and a query point  **$q \in M$** , find  **$k$**  closest points in  **$S$**  to  **$q$** .
- **$M$**  is a **metric space** and similarity is expressed as a distance metric, which is symmetric and satisfies triangle inequality.
  - Euclidean distance (**L2**), Inner Product, Manhattan distance, ...

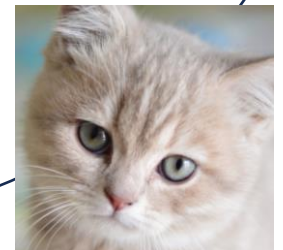
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"Gedung Fasilkom UI"



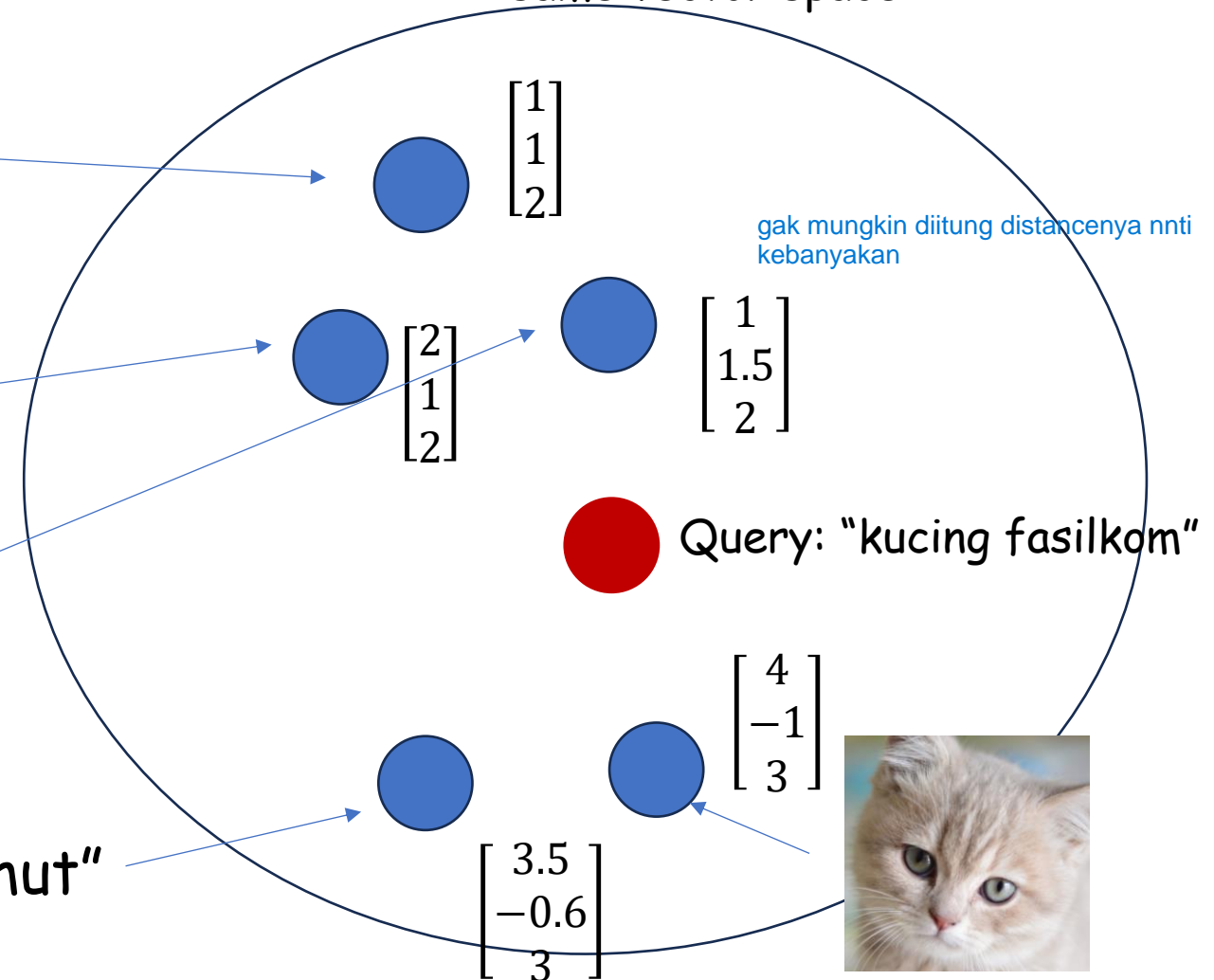
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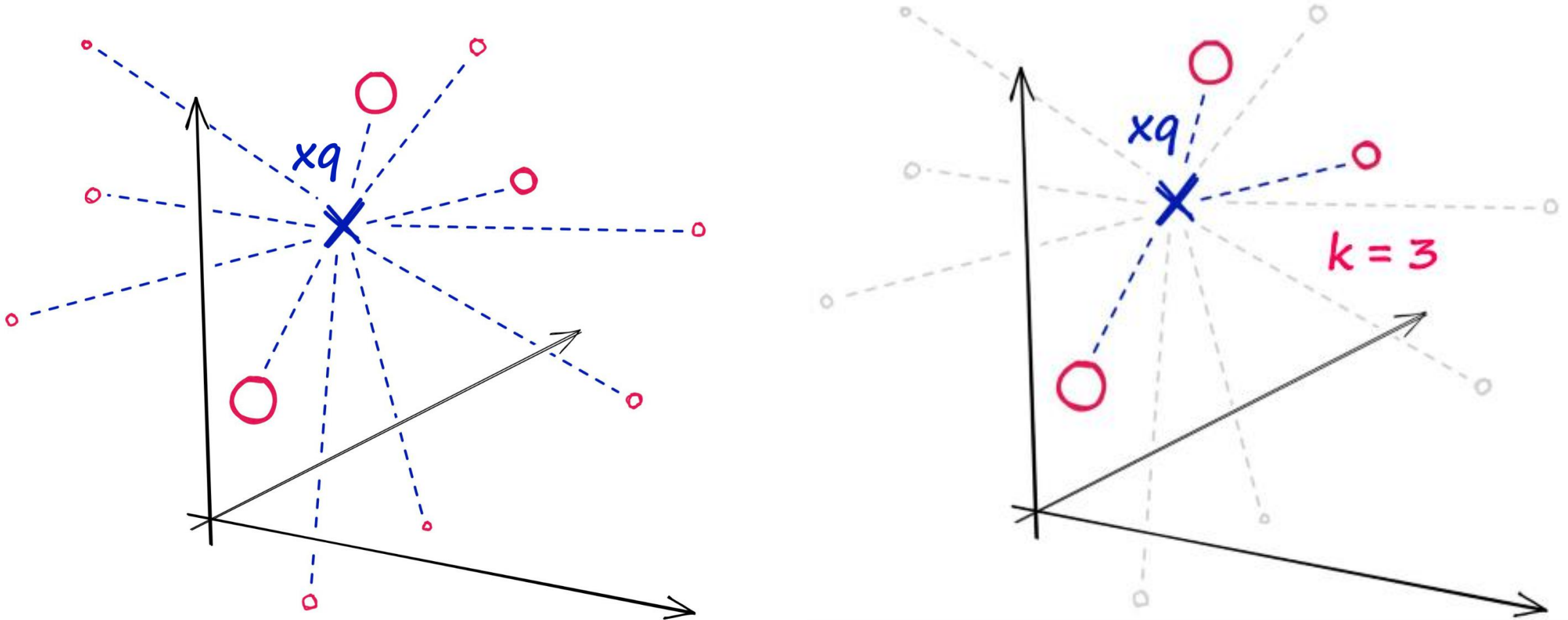


### Vector Database

"A collection of vectors from the same vector space"



# Exact Solution - Flat Index

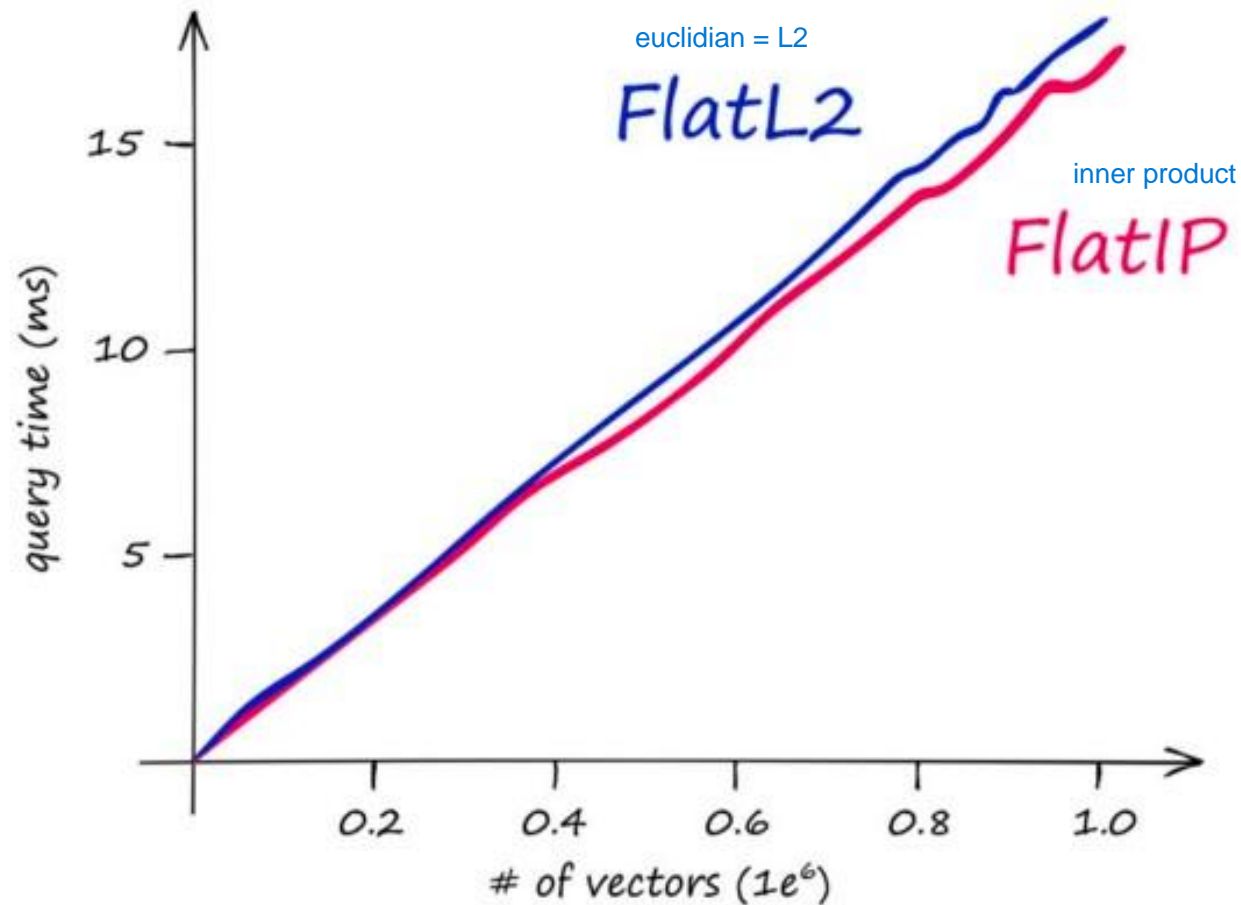


The query vector  $xq$  is against every other vectors in the index, calculating the distance to each and returning  $k$  nearest points.



<https://www.pinecone.io/learn/series/faiss/vector-indexes/>

# Exact Solution - Flat Index



**Tools FAISS:** Euclidean (L2) and Inner Product (IP) flat index search times using faiss-cpu on an M1 chip. Both using vector dimensionality of 100. IndexFlatIP is shown to be slightly faster than IndexFlatL2.

# Approximate nearest neighbors

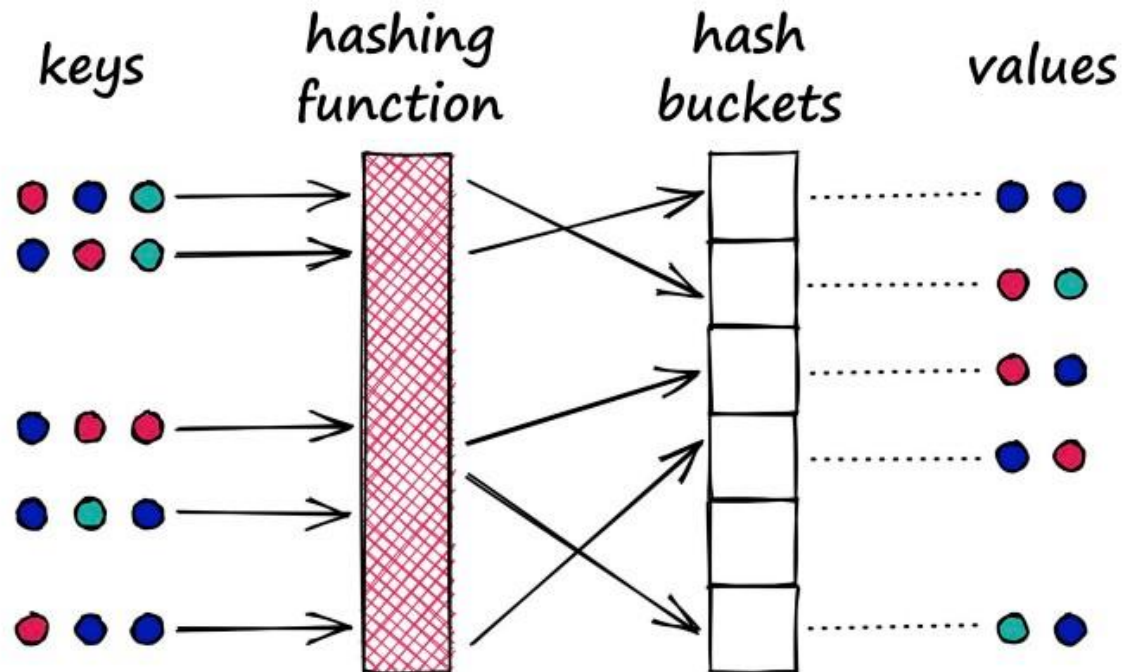
- Flat index is 100% accurate, but slow and not scalable as the number of vectors in the database increases.
- One solution is to **reduce the search scope**.
  - We can somehow cluster and organize vectors into tree structures based on certain attributes or similarities.
  - We are no longer performing an exhaustive nearest-neighbors search but an **approximate nearest-neighbors**.

# Three Types ANN Algorithms

- Using Trees (e.g. k-d trees)
- Using Locality Sensitive Hashing (e.g. Random Projection)
- Using Graphs (Hierarchical Navigable Small Worlds)

# Typical Hashing

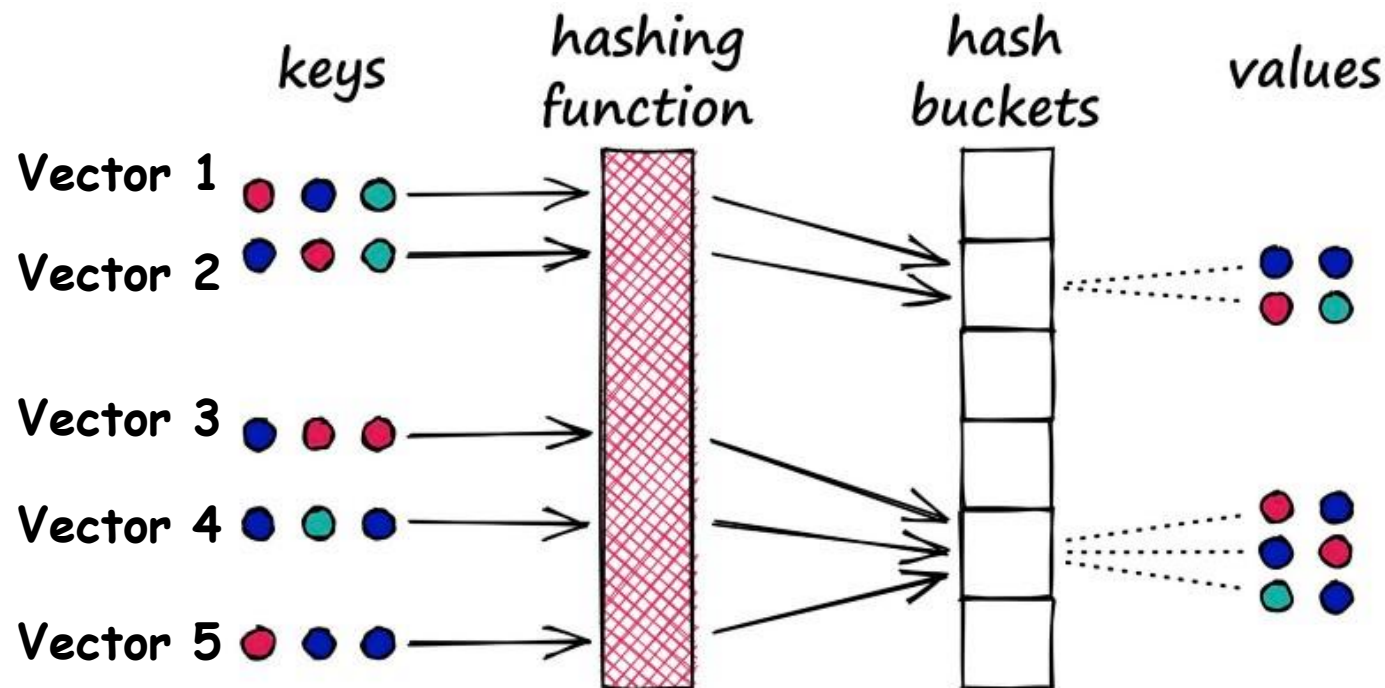
- Remember "Hash Table" on your last SDA course!
- We want a hash function that **minimizes collisions**; we really want to have multiple vectors mapped to a single key.



# Locality Sensitive Hashing (LSH)

local = yang similar mau di grup bareng

Instead of minimizing collisions, LSH aims at **maximizing** collisions in the sense that **similar vectors should be mapped into the same bucket!**



LSH: maksimalkan collision

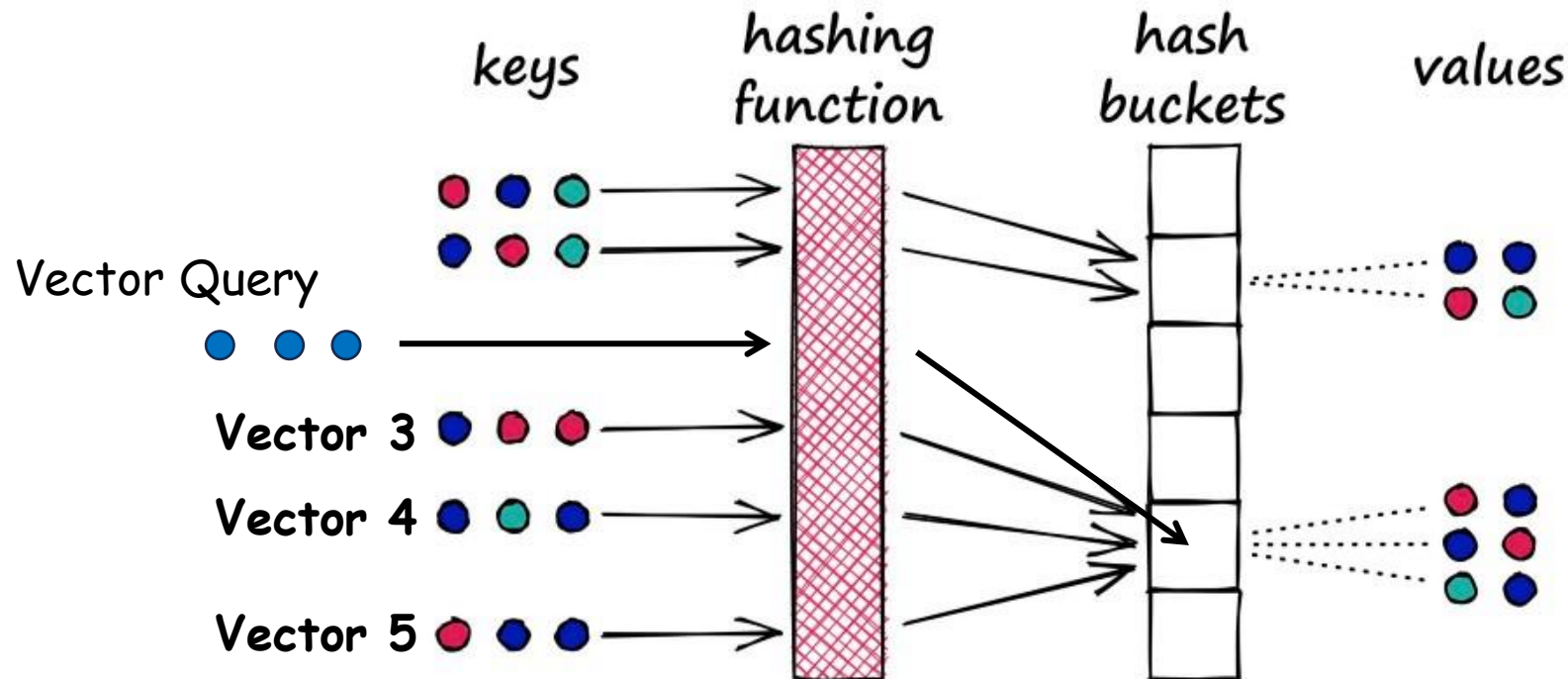
Similar vectors mau dimapped ke bucket yang sama

Kalau masuk ke hash function, dimasukkan ke buckets yang sama.

This produces groups of vectors.

# Locality Sensitive Hashing (LSH)

Ketika ada **vector query**, ia akan di-hash dan akan dipetakan ke sebuah bucket. Perhitungan nearest neighbor hanya mempertimbangkan vector-vector di bucket yang sama.



jadi kalau di vector database, dia itu udah di di gruping pas saat inserting ke database. Nah jadi proses search nya lebih bagus

Artinya, perhitungan similarity cukup dilakukan antara Query dengan vector 3, 4, dan 5.

<https://www.pinecone.io/learn/series/faiss/vector-indexes/>

# How to do LSH?

One way is to perform **Random Projection** or **Random Hyperplanes**.

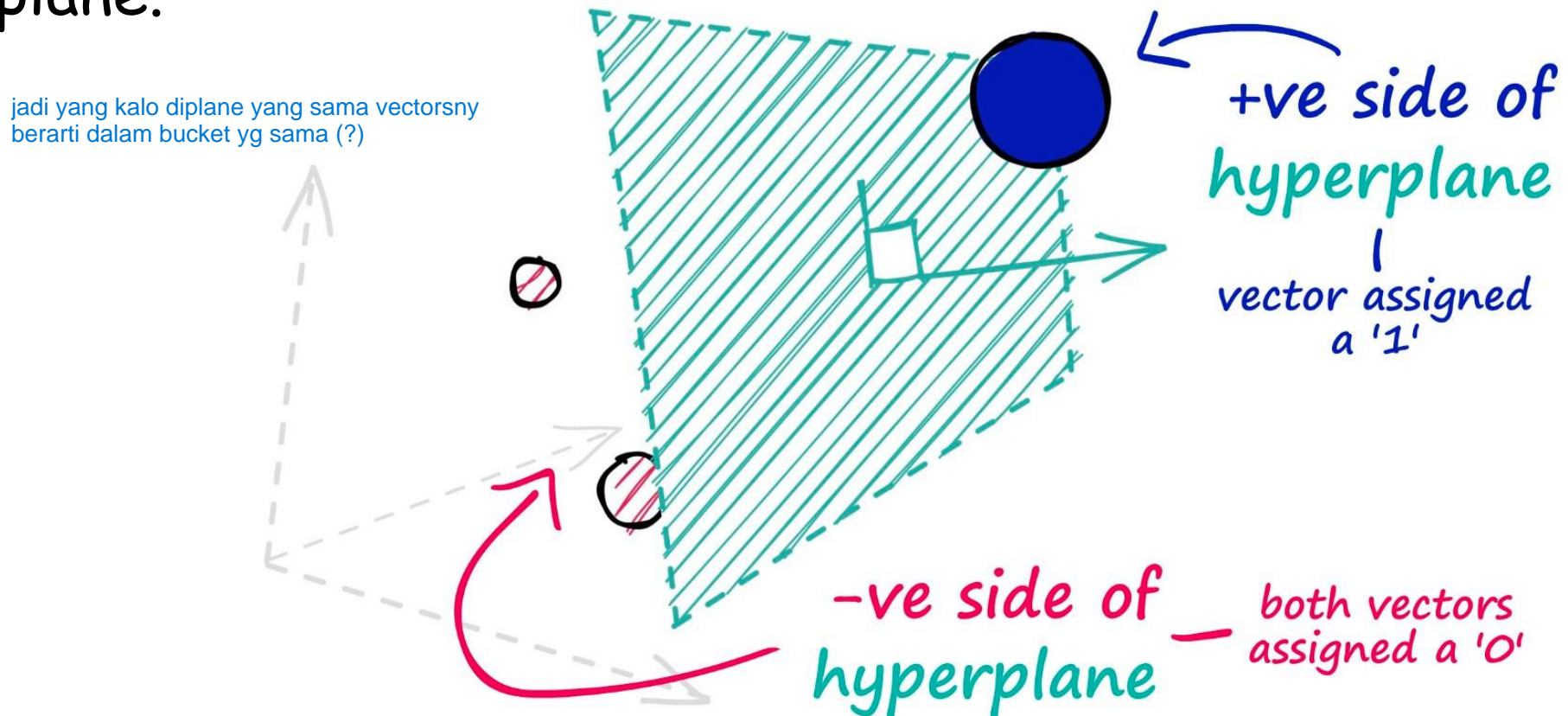
This is a mechanism to reduce our highly-dimensional vectors into **low-dimensionality binary vectors**.

**Two similar vectors should have the same low-dimensional binary vectors** --> this is our hash function that maximizes collisions!



# Random Projections or Hyperplanes

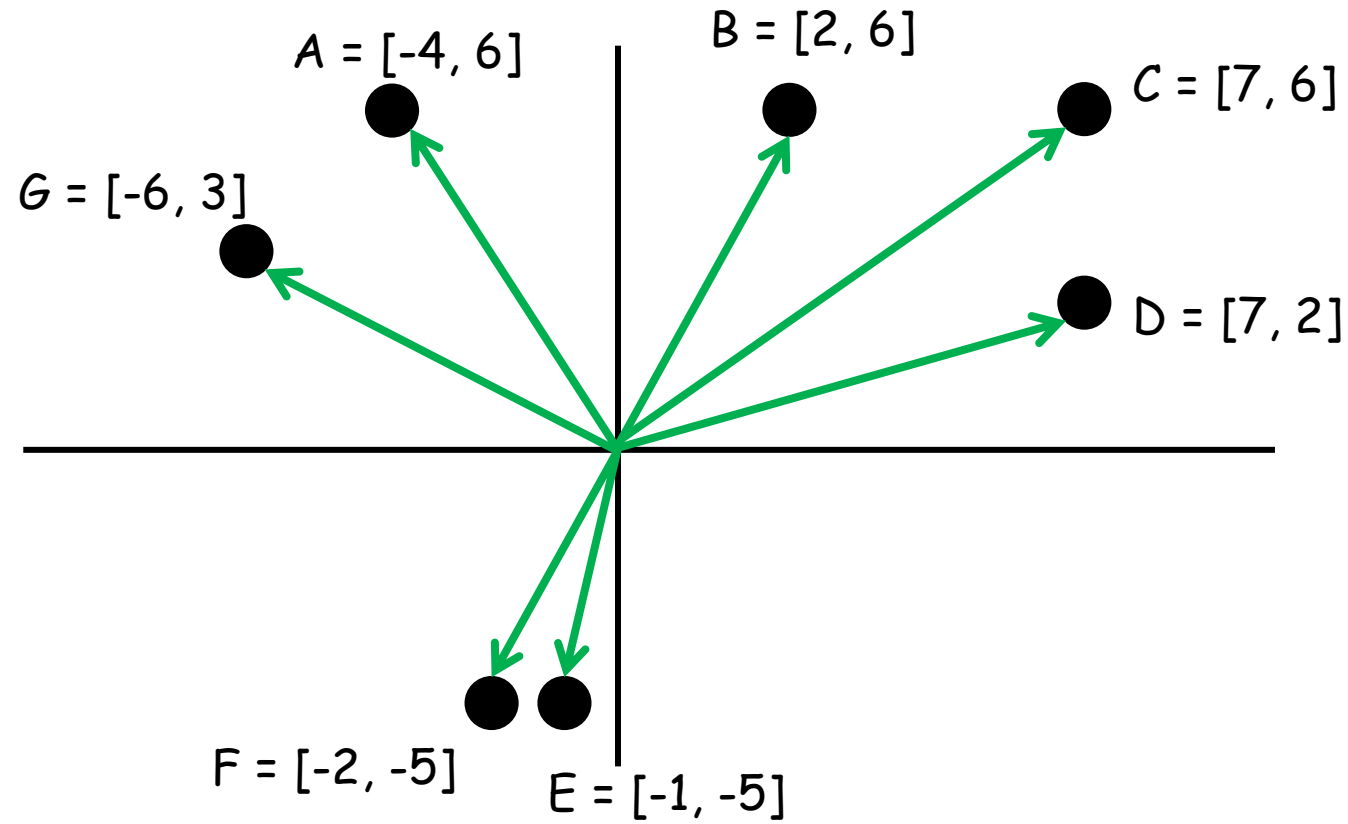
We assign **a value of 1** to vectors on the +ve side of our hyperplane and **a value of 0** to vectors on the -ve side of the hyperplane.





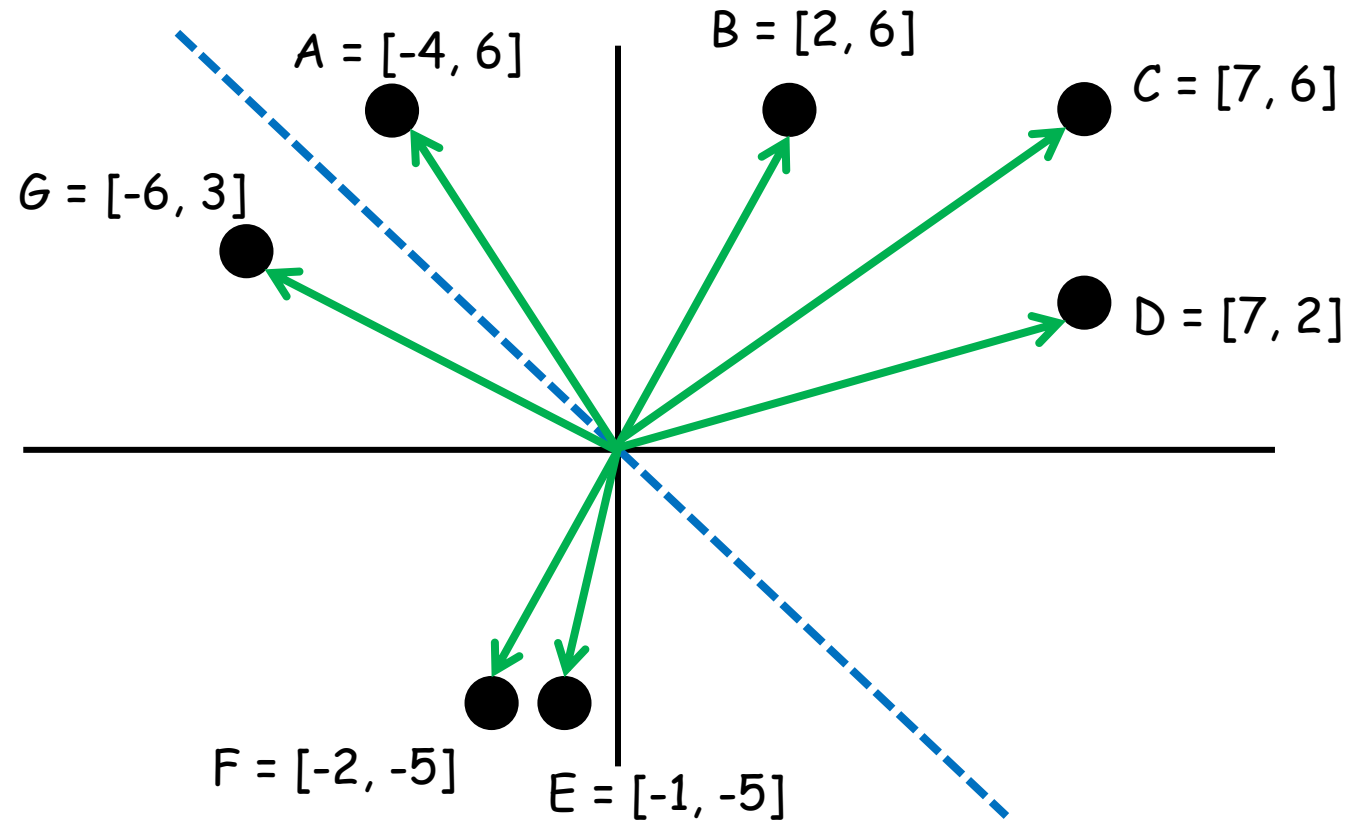
# Random Projections or Hyperplanes

Misal, ada beberapa vektor 2D



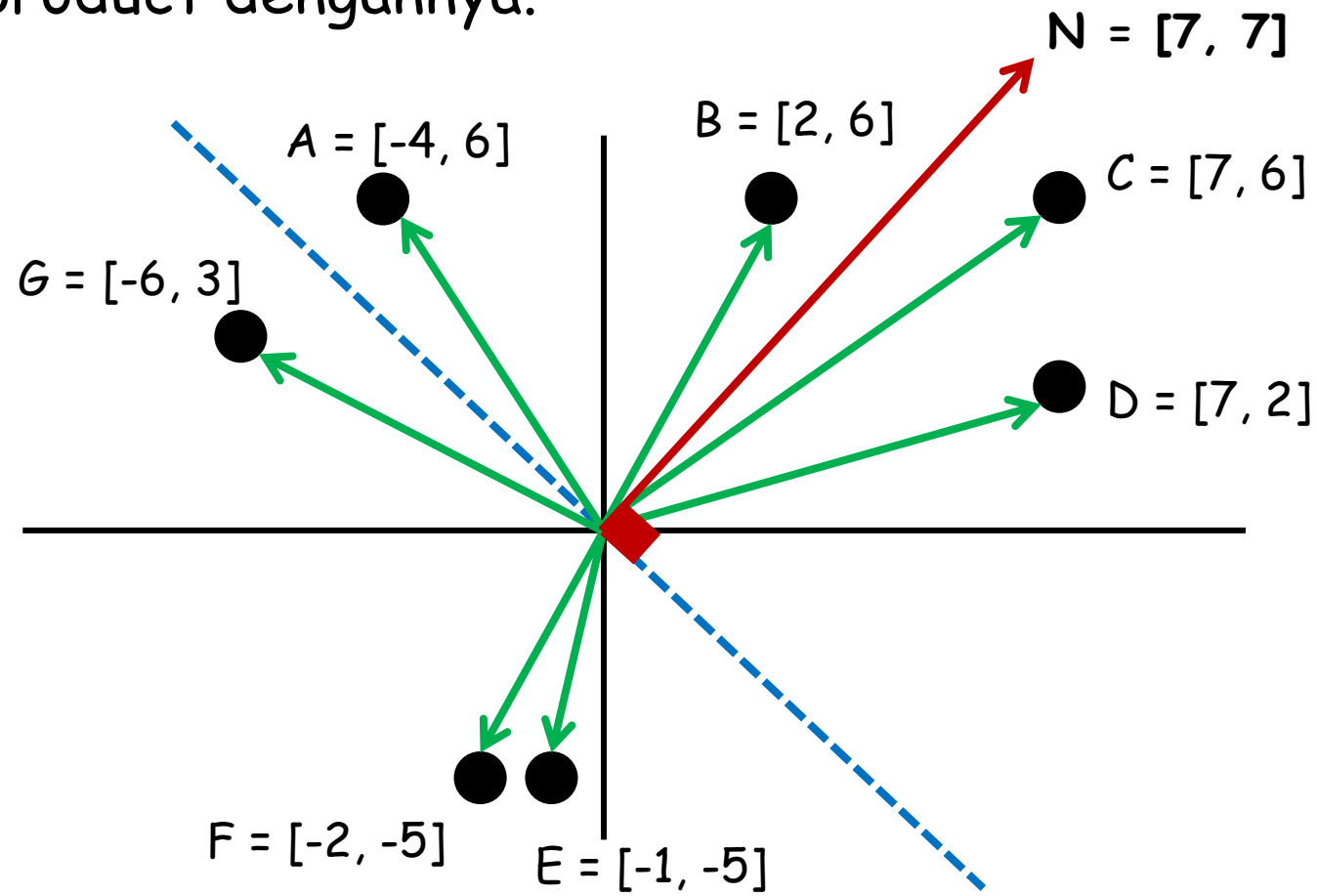
# Random Projections or Hyperplanes

Misal, kita hasilkan sebuah hyperplane **secara random**!



# Random Projections or Hyperplanes

Untuk identifikasi pada sisi hyperplane mana vektor-vektor berada, kita dapat menggunakan **normal vector (tegak lurus hyperplane)**, dan melakukan dot product dengannya.



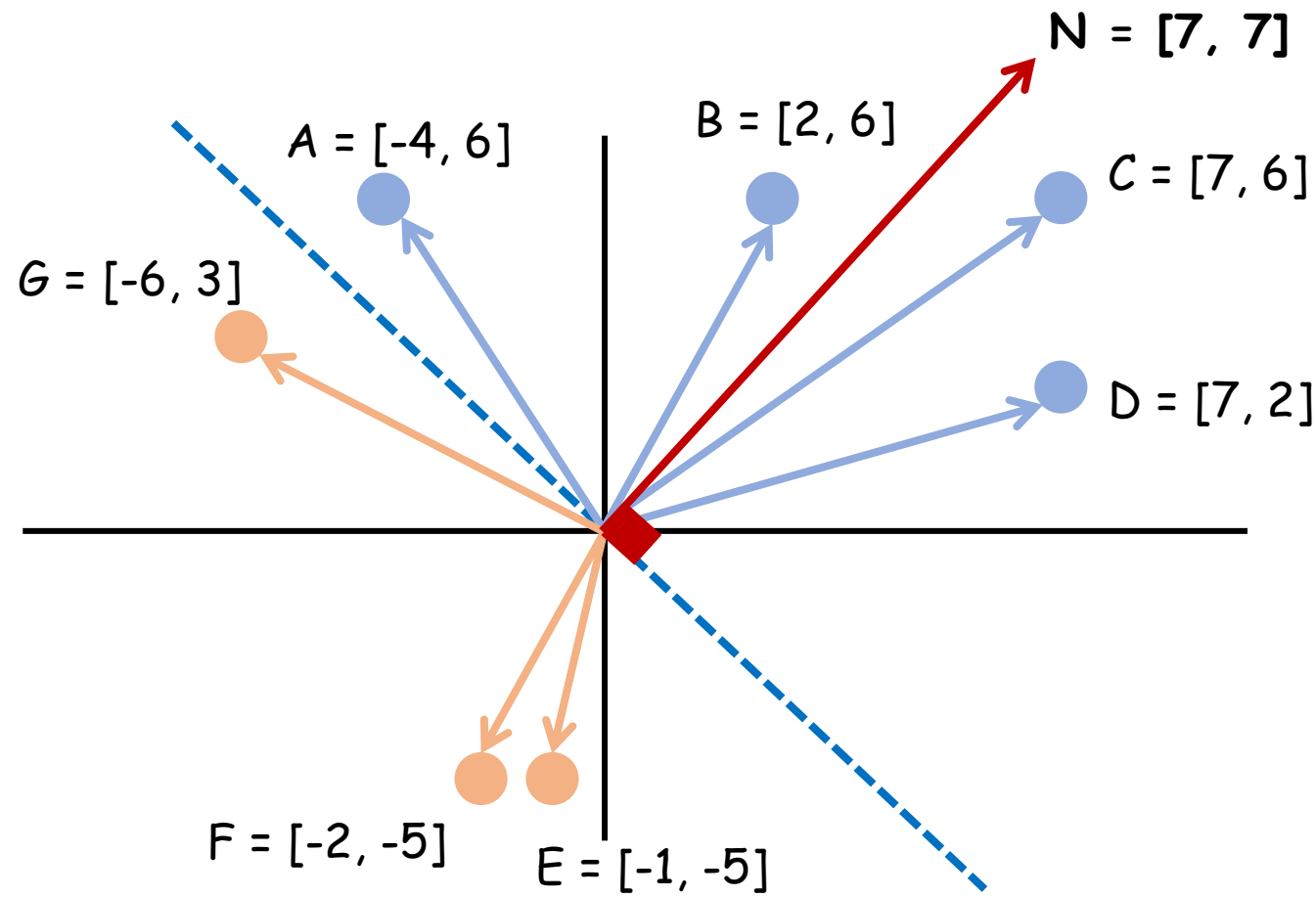
# Random Projections or Hyperplanes

Jika dua vector berada pada **arah yang sama**, dot product akan menghasilkan nilai positif; dan jika tidak, dot product akan negatif.

untuk tau positif/negative, di dot product dengan tegak lurus (yang garis merah)

Kita encode vektor E, F, dan G dengan [0]

$\text{dot}(G, N) < 0$   
 $\text{dot}(F, N) < 0$   
 $\text{dot}(E, N) < 0$



$\text{dot}(A, N) > 0$   
 $\text{dot}(B, N) > 0$   
 $\text{dot}(C, N) > 0$   
 $\text{dot}(D, N) > 0$

titik warna biru itu diatas,

yang warna orange itu dibawah

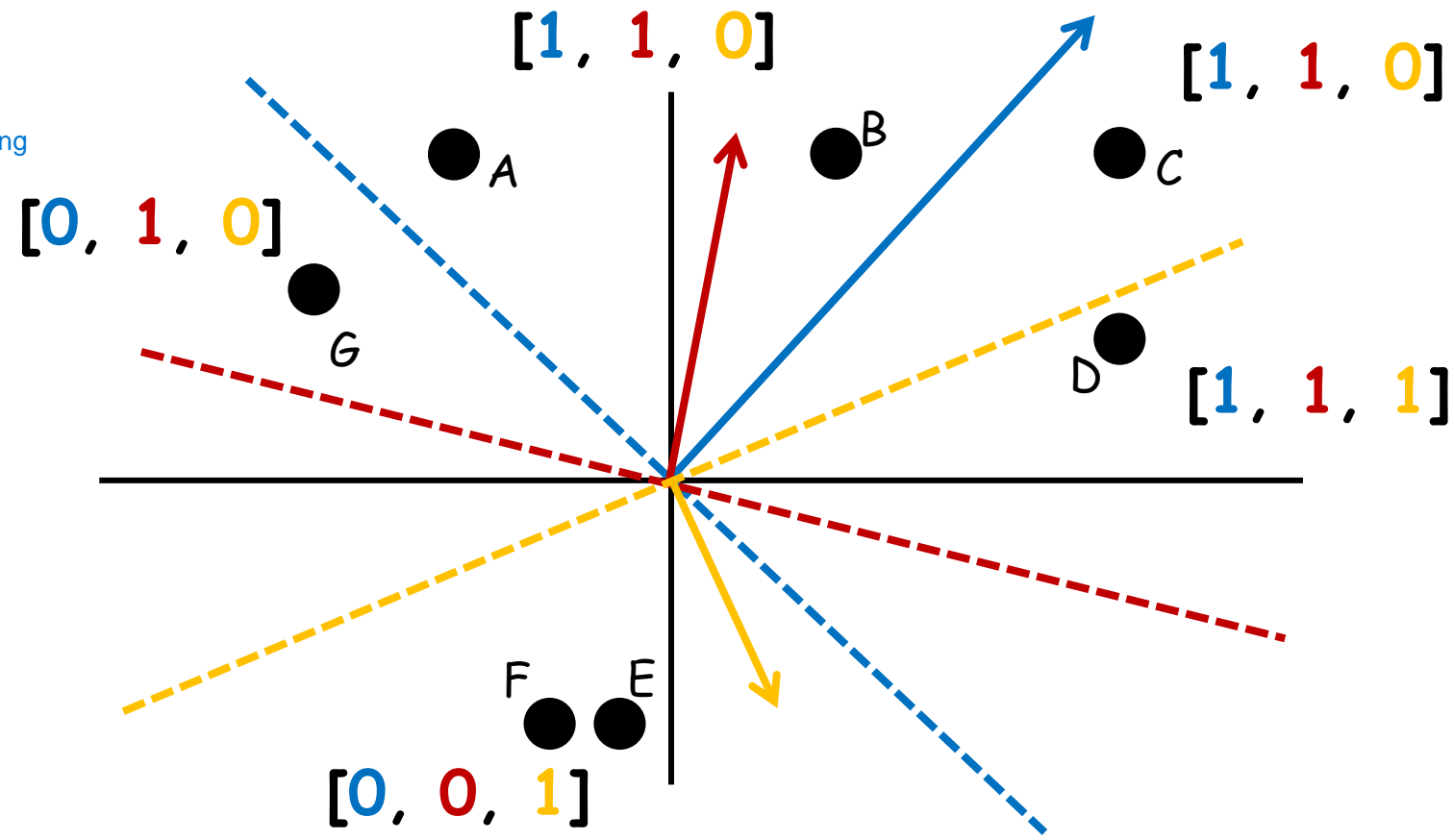
Kita encode vektor A, B, C, dan D dengan [1]

# Random Projections or Hyperplanes

Kita perlu tambah **random hyperplane** agar bisa menambah informasi.  
Contoh di bawah adalah dengan **nbits = 3**.

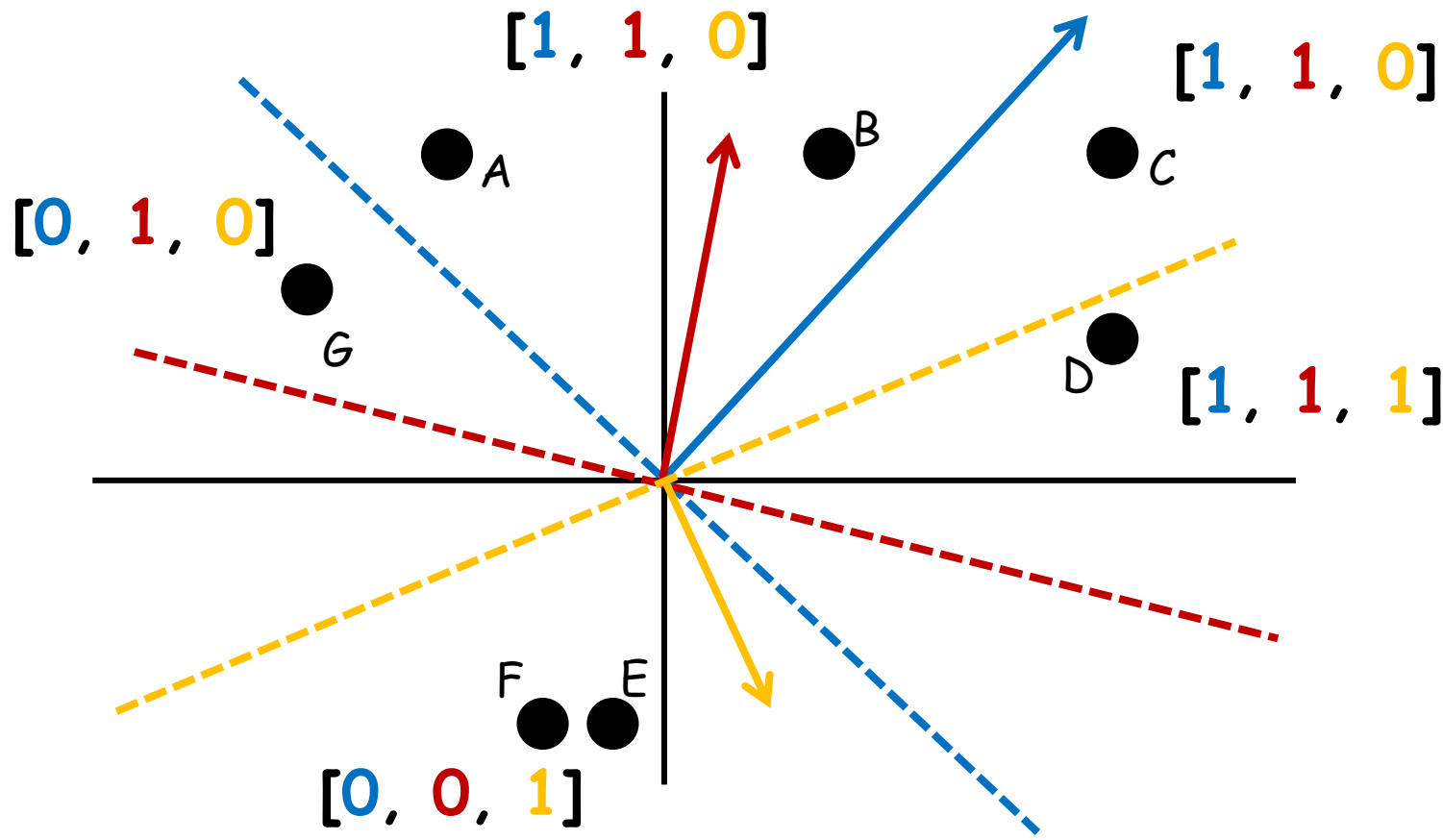
ada 3 random hyperplane

warna biru, merah, sama kuning



# Random Projections or Hyperplanes

Now, we have bucketed **eight** vectors!



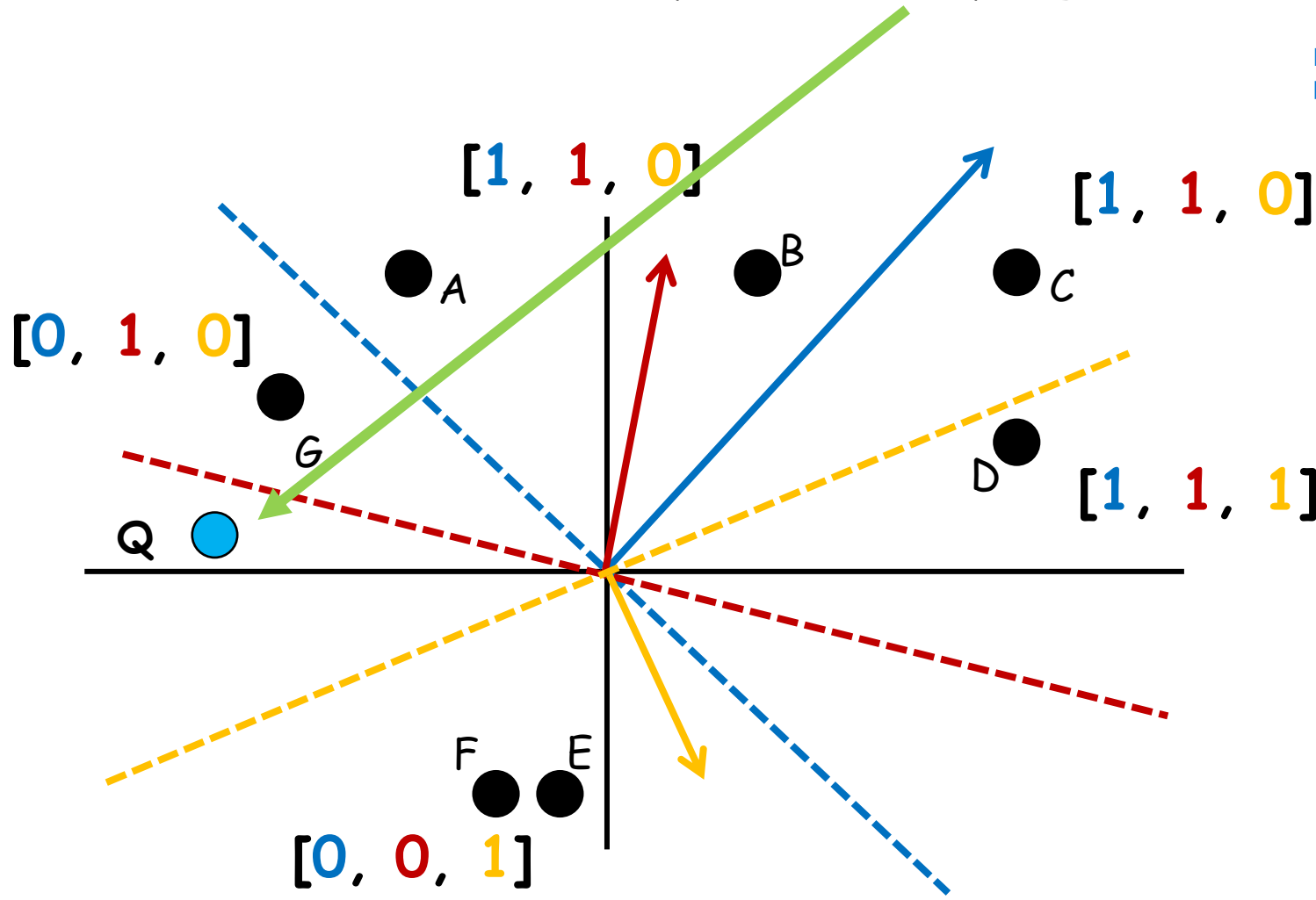
$\{ '110' : [A, B, C],$   
 $'111' : [D],$   
 $'001' : [E, F],$   
 $'010' : [G] \}$

This is our LSH index!

# Random Projections or Hyperplanes

Misal, ada sebuah query vector  $Q$  yang di-hash ke  $[0, 0, 0]$

karena ada 3 hyperplane setiap vektor mengandung array of positive/negative (terhadap garis tegak lurus)



```
{ '110': [A, B, C],  
  '111': [D],  
  '001': [E, F],  
  '010': [G] }
```

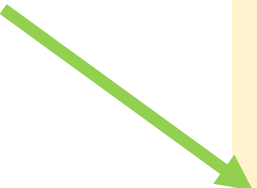
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# Random Projections or Hyperplanes

Misal, ada sebuah query vector  $Q$  yang di-hash ke  $[0, 0, 0]$

Kita kemudian bandingkan query vector  $Q$  dengan semua **bucket** pada LSH index kita; dan ambil **Top-K vectors**.

Kita bisa gunakan **Hamming Distance**, yang menghitung "mismatch" antara dua binary vectors.



'110'	: [A, B, C],
'111'	: [D],
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This is our LSH index!



# Random Projections or Hyperplanes

Misal, ada sebuah query vector  $Q$  yang di-hash ke  $[0, 0, 0]$

pokokny yang gak sama

kayak

## Hamming Distance

000 vs 110 -> ada yang gak sama sebanyak 2 bit (2 MSB pertama)

```
def hamming_distance(string1, string2) :  
  
    if len(string1) != len(string2):  
        raise ValueError("Panjang string harus sama.")  
  
    num_mismatch = 0  
    for n in range(len(string1)):  
        if string1[n] != string2[n]:  
            num_mismatch += 1  
    return num_mismatch
```

```
{ '110' : [A, B, C],  
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  '010' : [G]}
```

This is our LSH index!

# Random Projections or Hyperplanes

Misal, ada sebuah query vector  $Q$  yang di-hash ke  $[0, 0, 0]$

Hamming Distance (HD), misal  $K = 3$

$$\text{HD}('000', '110') = 2$$

$$\text{HD}('000', '111') = 3$$

$$\text{HD}('000', '001') = 1$$

$$\text{HD}('000', '010') = 1$$

```
{ '110' : [A, B, C],  
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```

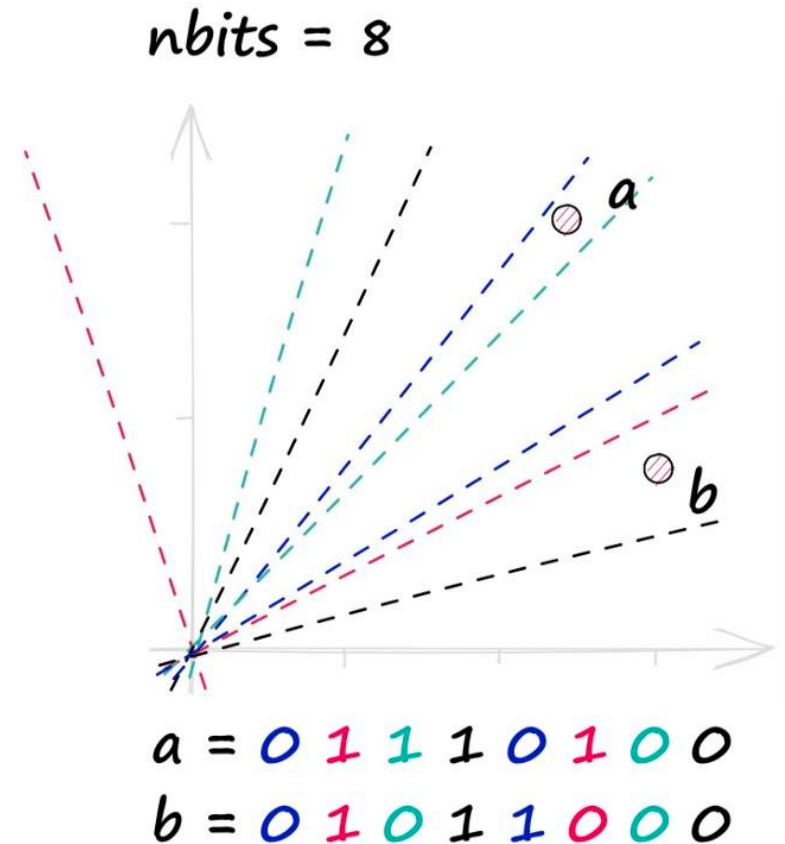
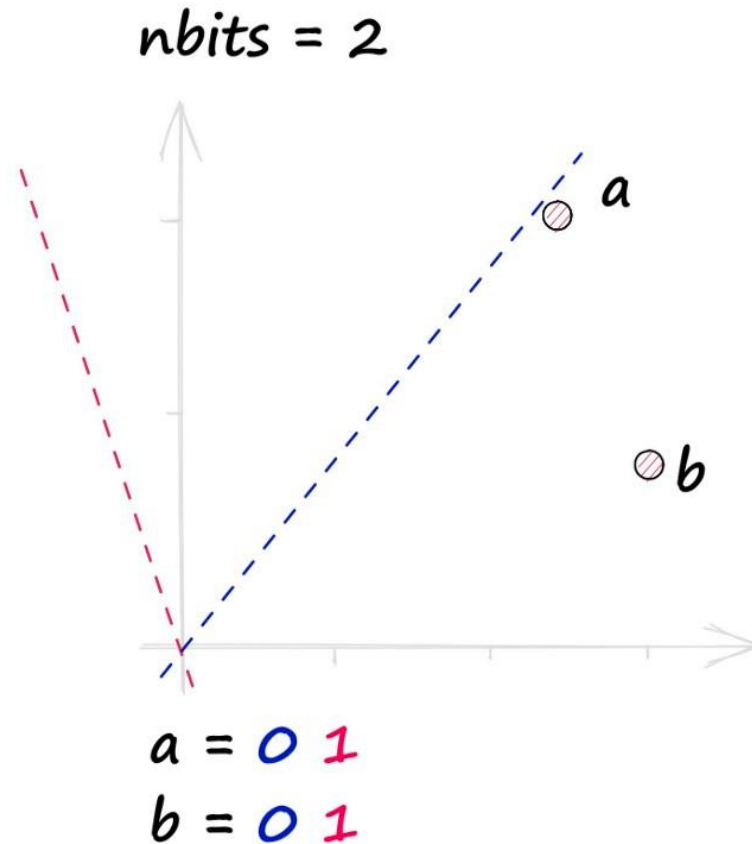
This is our LSH index!

**Top-3 = [E, F, G]**

\* Kita juga bisa re-ranking 3 top vectors ini berdasarkan nilai Cosine Similarity dengan  $Q$

In reality, we use many more hyperplanes — more hyperplanes mean **higher resolution binary vectors** — producing much more precise representations of our vectors.

A higher **nbits** value improves search quality by increasing the resolution of hashed vectors.



## Contoh Implementasi (Toy Implementation)

[https://github.com/pinecone-io/examples/blob/master/learn/search/faiss-ebook/locality-sensitive-hashing-random-projection/random\\_projection.ipynb](https://github.com/pinecone-io/examples/blob/master/learn/search/faiss-ebook/locality-sensitive-hashing-random-projection/random_projection.ipynb)

```
def all_binary(n):  
    total = 1 << n  
    print(f"{total} possible combinations")  
    combinations = []  
    for i in range(total):  
        # get binary representation of integer  
        b = bin(i)[2:]  
        # pad zeros to start of binary representtion  
        b = '0' * (n - len(b)) + b  
        b = [int(i) for i in b]  
        combinations.append(b)  
    return combinations
```

[https://github.com/pinecone-io/examples/blob/master/learn/search/fais-ebook/locality-sensitive-hashing-random-projection/random\\_projection.ipynb](https://github.com/pinecone-io/examples/blob/master/learn/search/fais-ebook/locality-sensitive-hashing-random-projection/random_projection.ipynb)

```
class RandomProjection:
    # initialize what will be the buckets
    buckets = {}
    # initialize counter
    counter = 0
```

```
def __init__(self, nbits, d):
    self.nbits = nbits
    self.d = d
    # create our hyperplane normal vecs for splitting data
    self.plane_norms = np.random.rand(d, nbits) - .5
    print(f"Initialized {self.plane_norms.shape[1]} hyperplane normal vectors.")
    # add every possible combination to hashes attribute as numpy array
    self.hashes = all_binary(nbits)
    # and add each as a key to the buckets dictionary
    for hash_code in self.hashes:
        # convert to string
        hash_code = ''.join([str(i) for i in hash_code])
        self.buckets[hash_code] = []
    # convert self.hashes to numpy array
    self.hashes = np.stack(self.hashes)
```

[https://github.com/pinecone-io/examples/blob/master/learn/search/fais-ebook/locality-sensitive-hashing-random-projection/random\\_projection.ipynb](https://github.com/pinecone-io/examples/blob/master/learn/search/fais-ebook/locality-sensitive-hashing-random-projection/random_projection.ipynb)

```
def get_binary(self, vec):  
    # calculate nbits dot product values  
    direction = np.dot(vec, projection.plane_norms)  
    # find positive direction (>0) and negative direction (<=0)  
    direction = direction > 0  
    # convert boolean array to integer strings  
    binary_hash = direction.astype(int)  
    return binary_hash
```

```
def hash_vec(self, vec, show=False):  
    # generate hash  
    binary_hash = self.get_binary(vec)  
    # convert to string format for dictionary  
    binary_hash = ''.join(binary_hash.astype(str))  
    # add ID to buckets dictionary  
    self.buckets[binary_hash].append(self.counter)  
    if show:  
        print(f"{self.counter}: {''.join(binary_hash)}")  
    # increment counter  
    self.counter += 1
```

[https://github.com/pinecone-io/examples/blob/master/learn/search/fai-s-ebook/locality-sensitive-hashing-random-projection/random\\_projection.ipynb](https://github.com/pinecone-io/examples/blob/master/learn/search/fai-s-ebook/locality-sensitive-hashing-random-projection/random_projection.ipynb)

```
def hamming(self, hashed_vec):  
    # get hamming distance between query vec and all buckets in self.hashes  
    hamming_dist = \  
        np.count_nonzero(hashed_vec != projection.hashes, axis=1).reshape(-1, 1)  
    # add hash values to each row  
    hamming_dist = np.concatenate((projection.hashes, hamming_dist), axis=1)  
    # sort based on distance  
    hamming_dist = hamming_dist[hamming_dist[:, -1].argsort()]  
    return hamming_dist
```

[https://github.com/pinecone-  
io/examples/blob/master/learn/search/fais-  
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```
def top_k(self, vec, k=5):  
    # generate hash  
    binary_hash = self.get_binary(vec)  
    # calculate hamming distance between all vectors  
    hamming_dist = self.hamming(binary_hash)  
    # loop through each bucket until we have k or more vector IDs  
    vec_ids = []  
    for row in hamming_dist:  
        str_hash = ''.join(row[:-1].astype(str))  
        bucket_ids = self.buckets[str_hash]  
        vec_ids.extend(bucket_ids)  
        if len(vec_ids) >= k:  
            vec_ids = vec_ids[:k]  
            break  
    # return top k IDs  
    return vec_ids
```

[https://github.com/pinecone-io/examples/blob/master/learn/search/fais-ebook/locality-sensitive-hashing-random-projection/random\\_projection.ipynb](https://github.com/pinecone-io/examples/blob/master/learn/search/fais-ebook/locality-sensitive-hashing-random-projection/random_projection.ipynb)

# Hierarchical Navigable Small Worlds

Semua materi diambil tanpa malu dari:

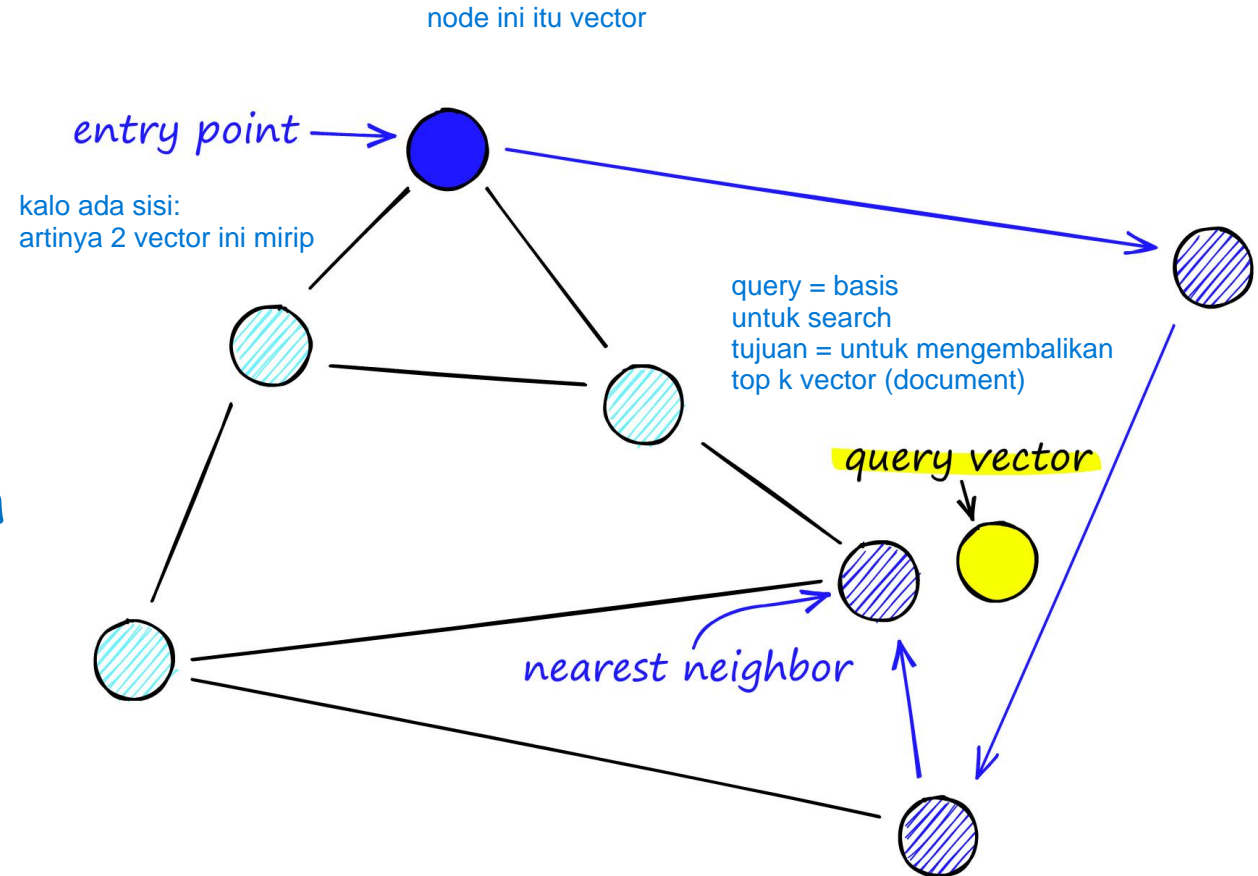
<https://www.pinecone.io/learn/series/faiss/hnsw/>

<https://towardsdatascience.com/similarity-search-part-4-hierarchical-navigable-small-world-hnsw-2aad4fe87d37>

# Navigable Small World Graphs

When searching an NSW graph, we begin at a pre-defined **entry-point**. This entry point connects to several nearby vertices. We identify which of these vertices is the closest to our query vector and move there.

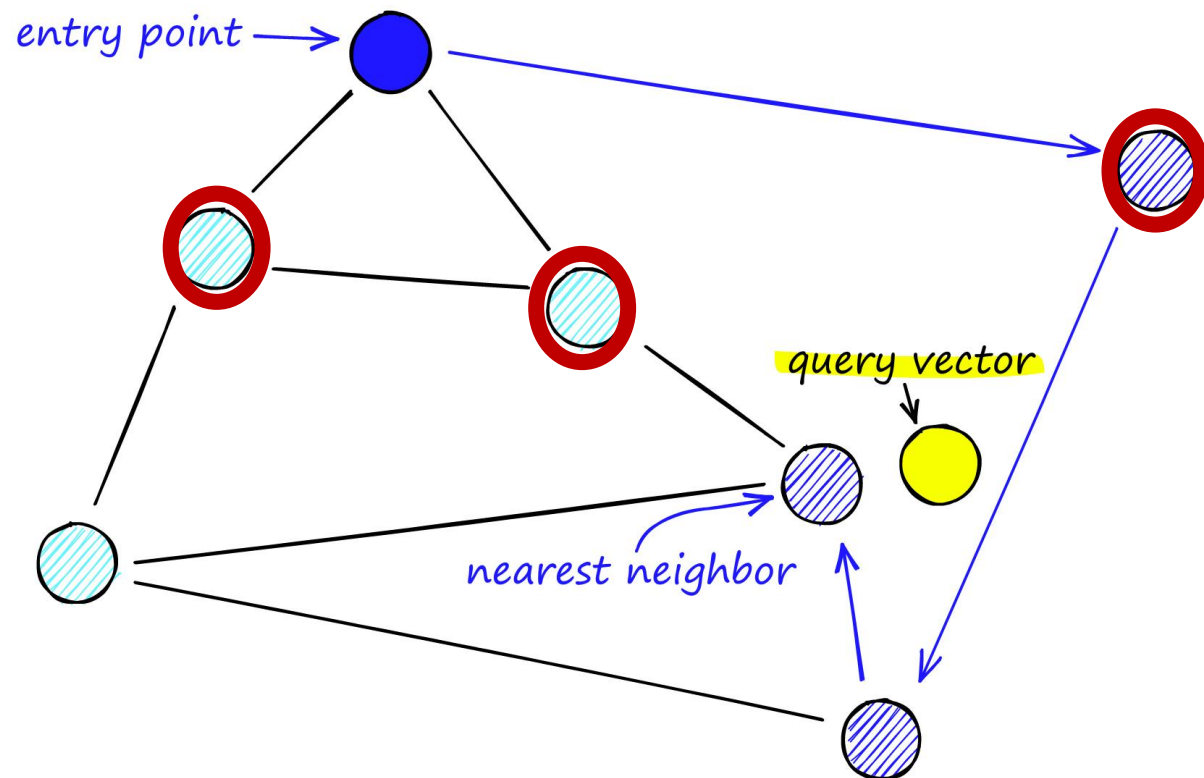
We repeat the **greedy-routing search** process of moving from vertex to vertex by identifying the nearest neighboring vertices in each friend list. **Eventually, we will find no nearer vertices than our current vertex** — this is a local minimum and acts as our **stopping condition**.



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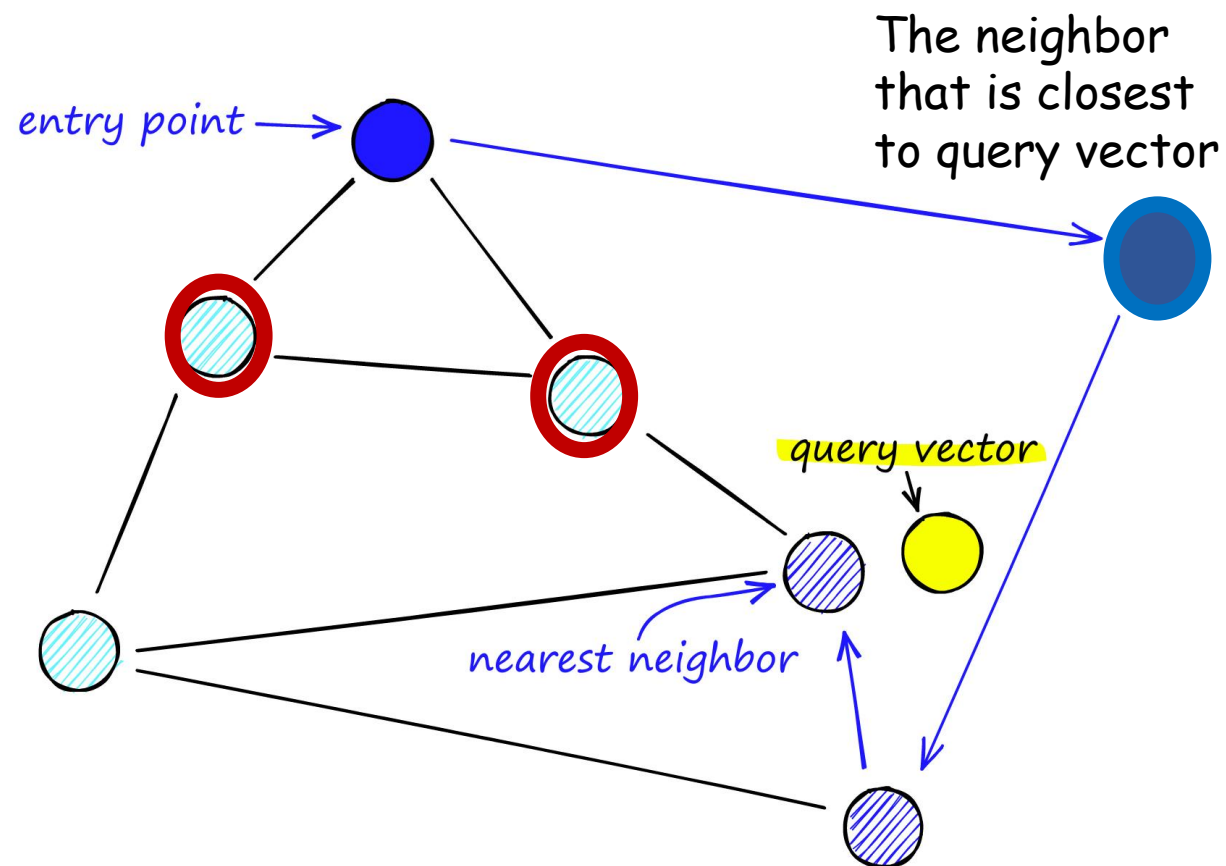
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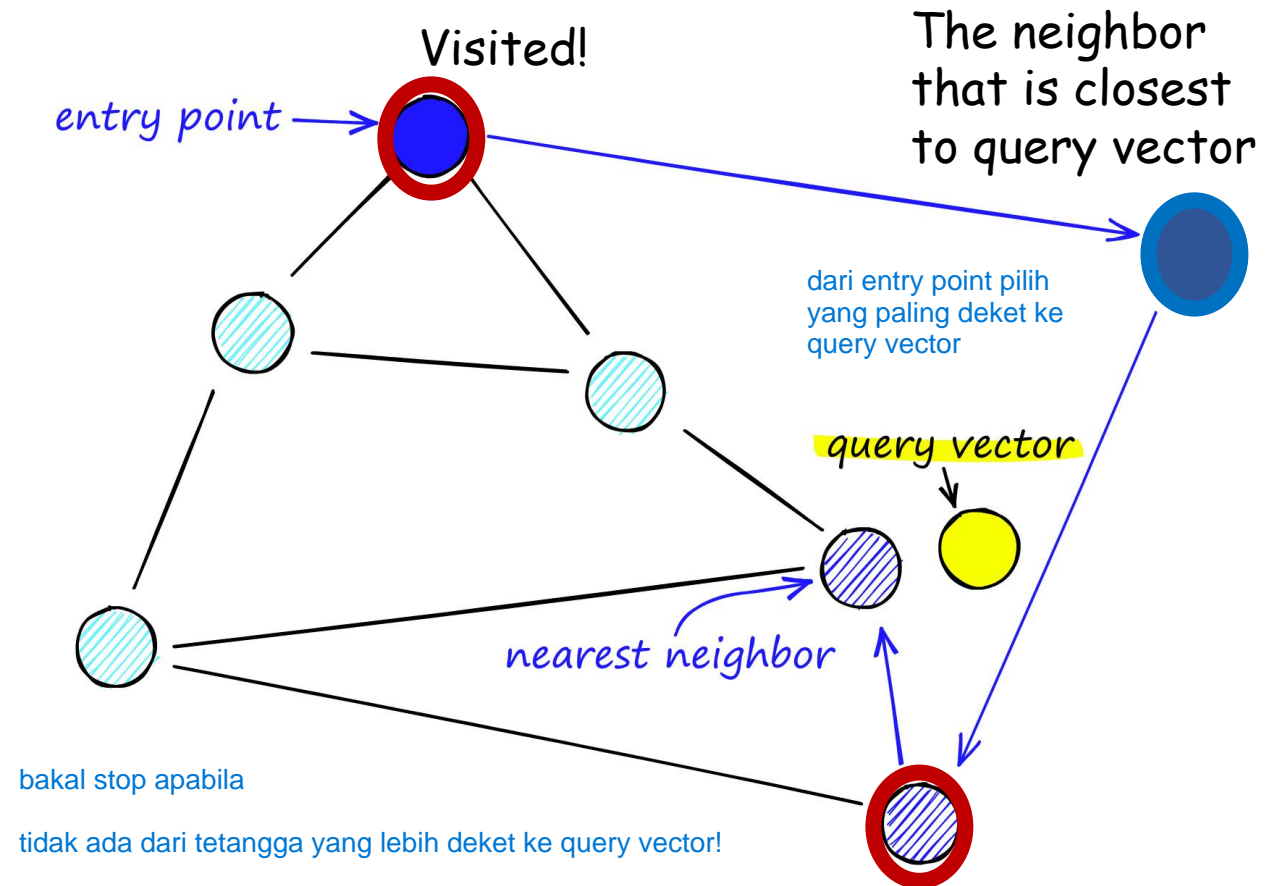
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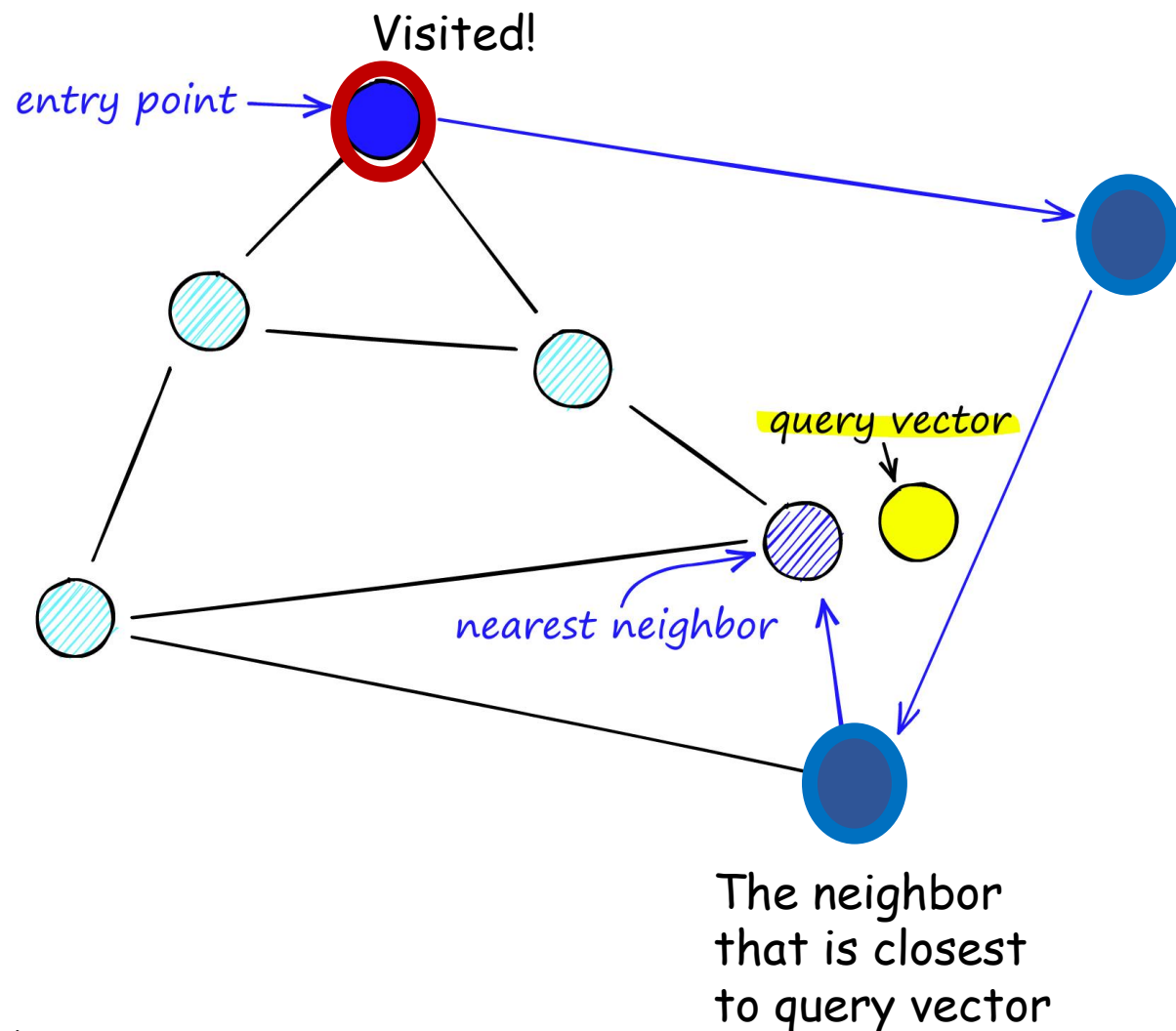
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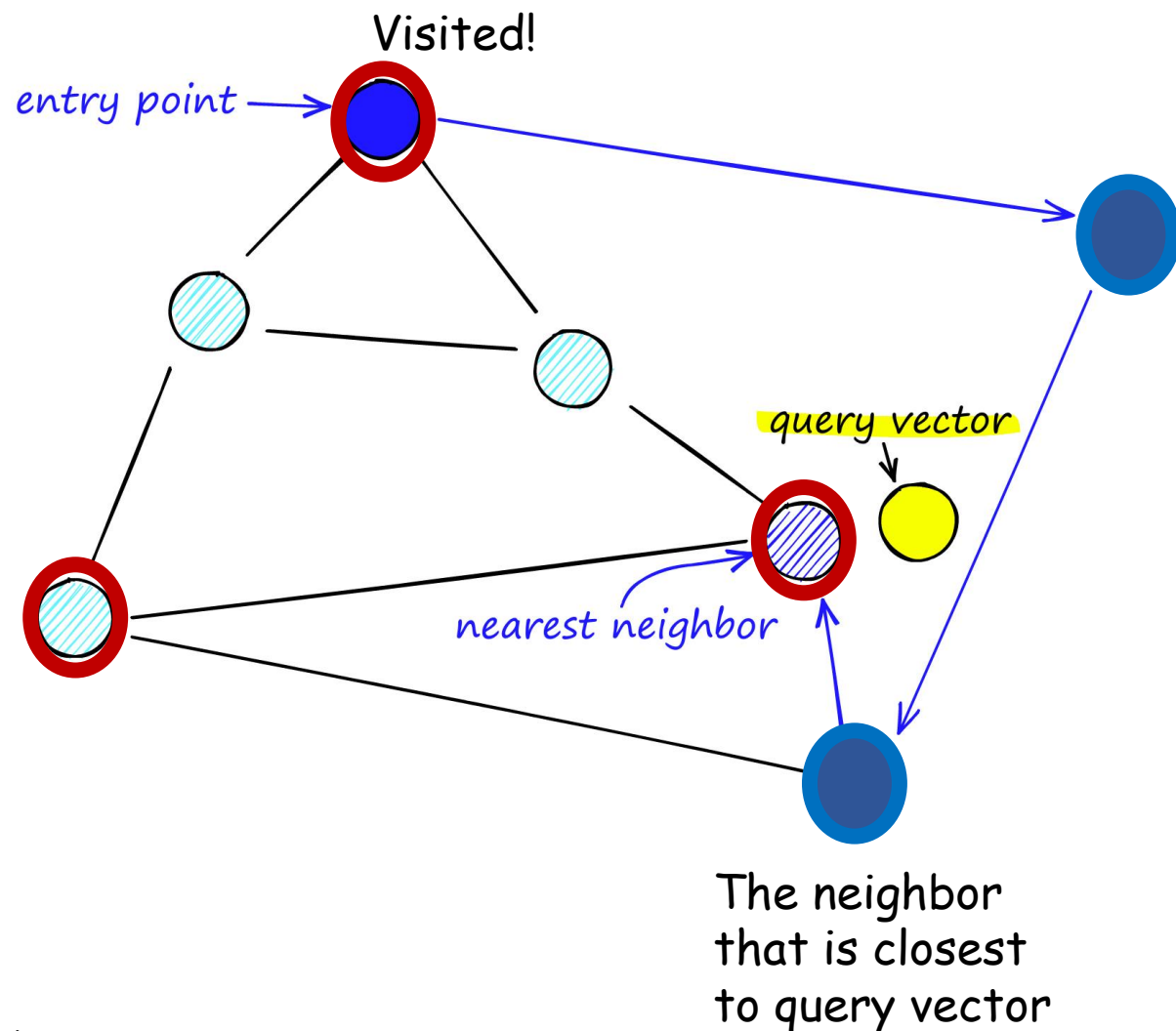




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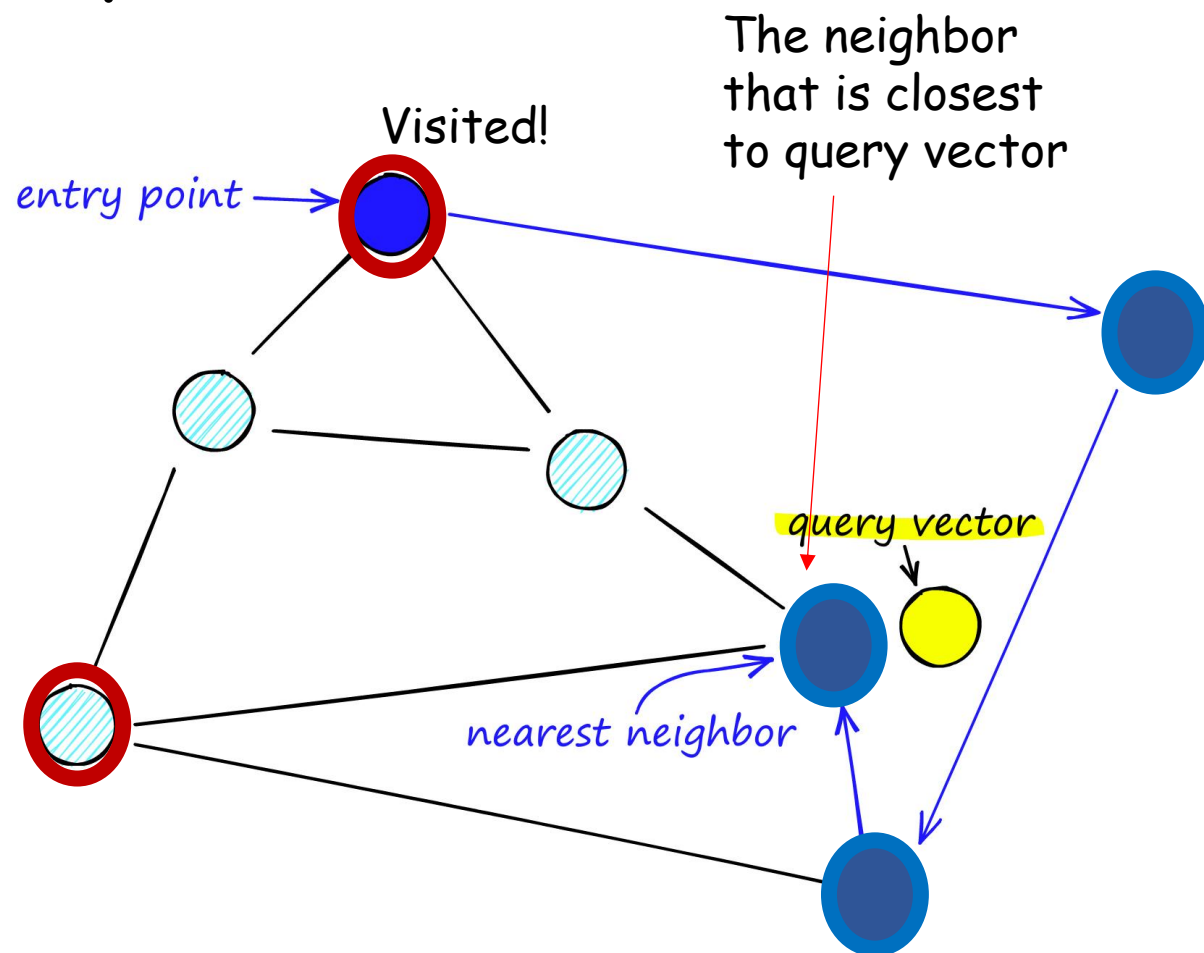




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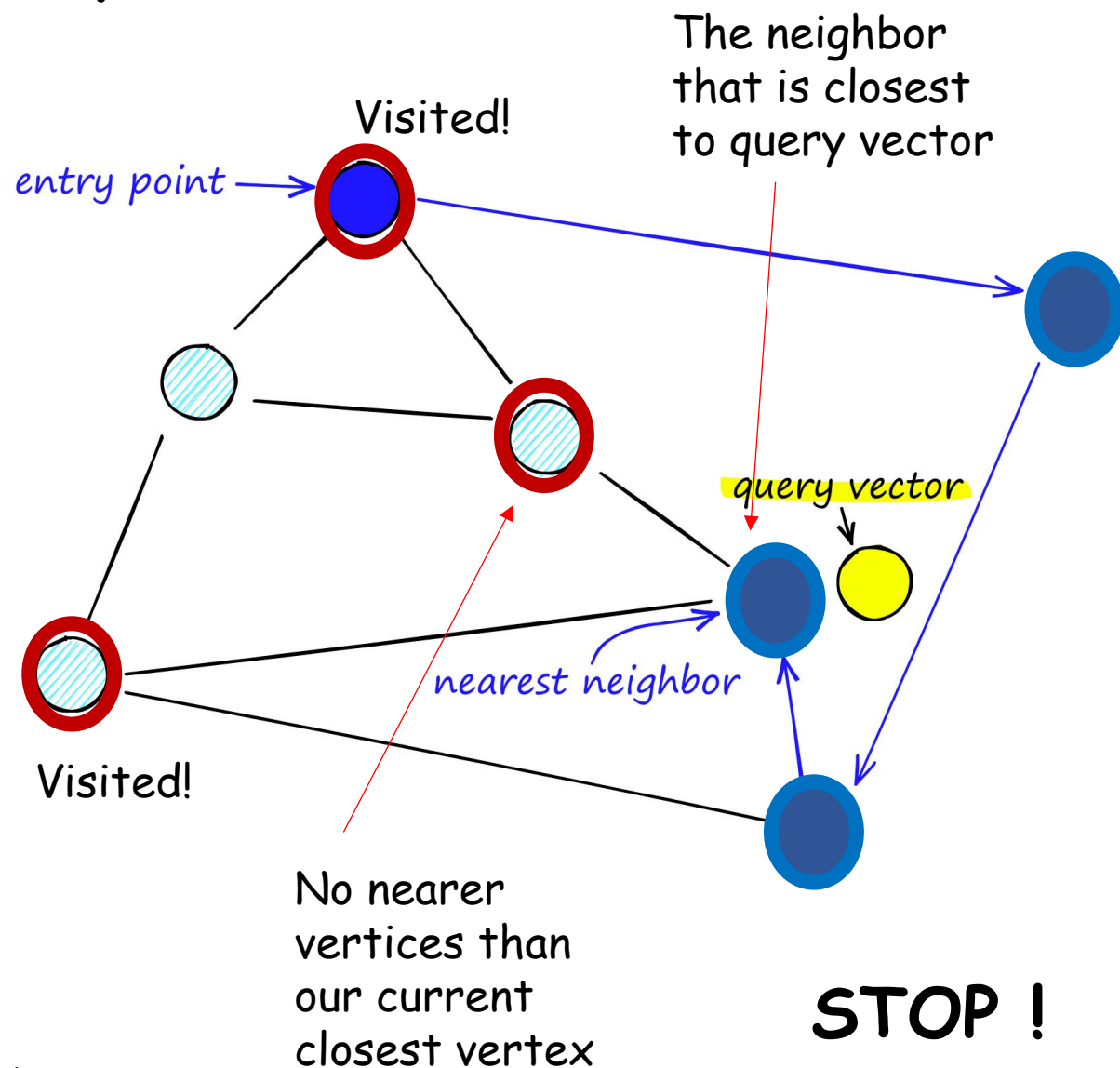
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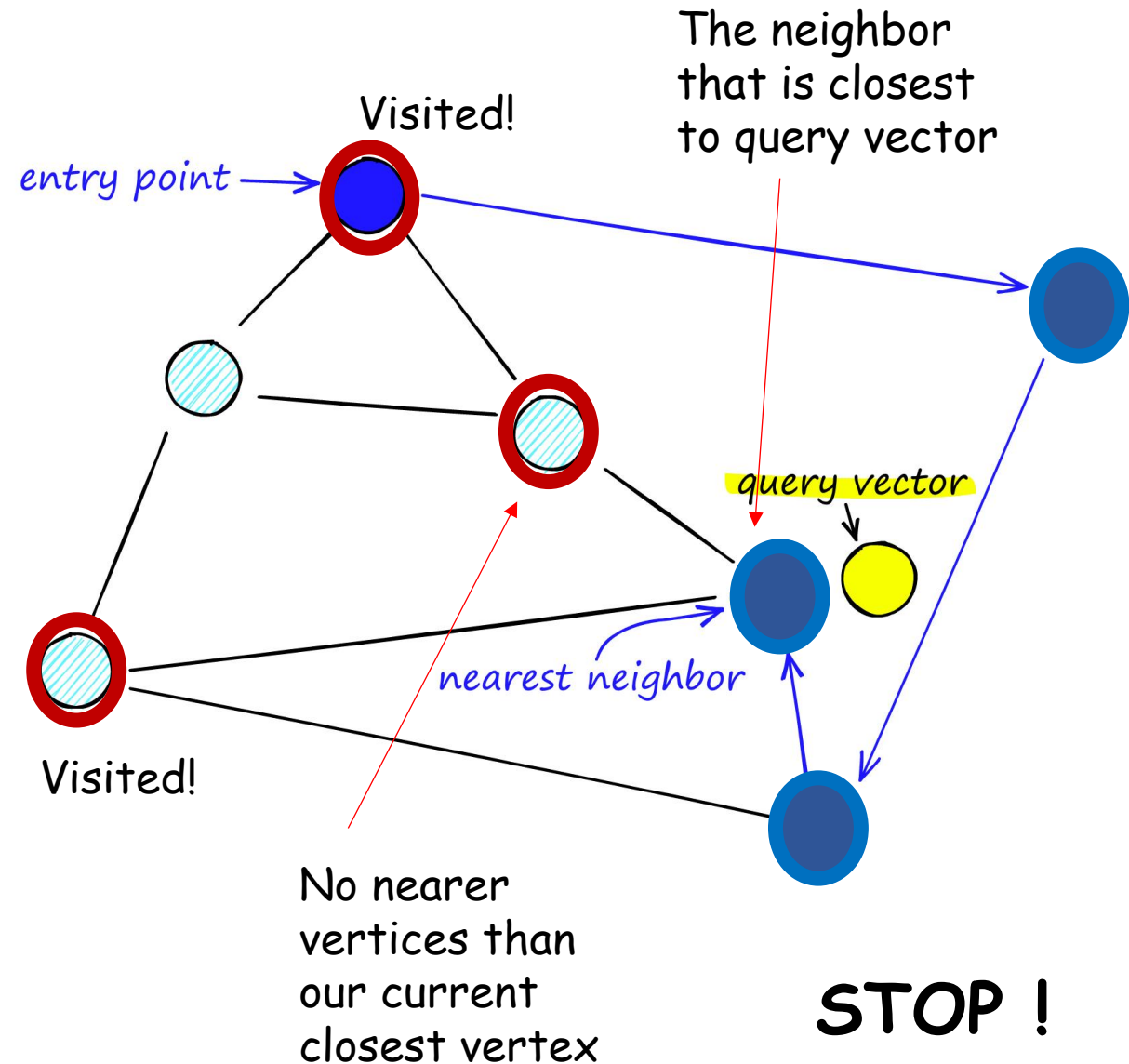
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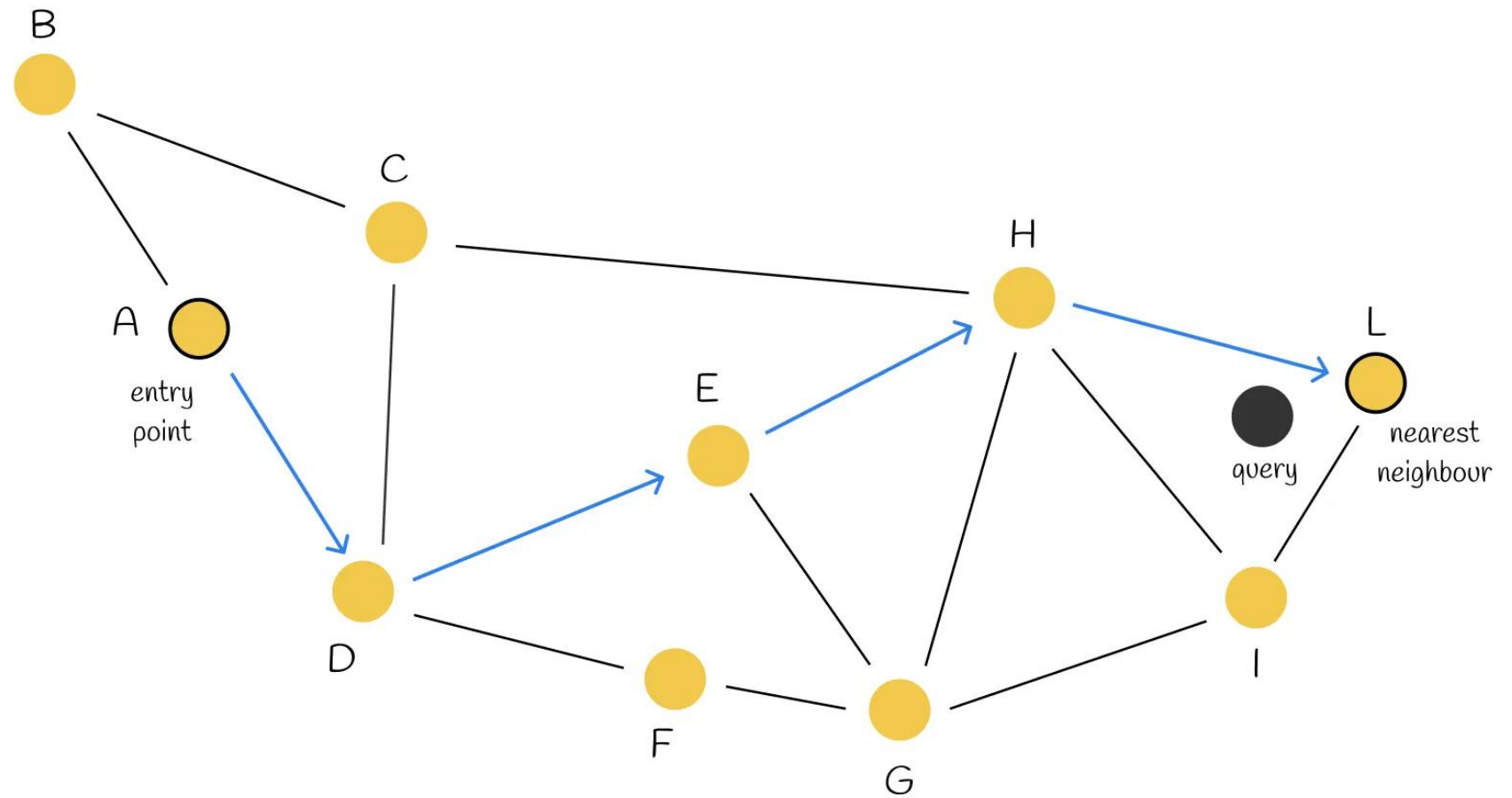
Secara praktis, proses seperti ini dilakukan secara berulang-ulang untuk mendapatkan **K buah nearest vectors**.

Setiap run, kita "entry point" bisa diacak.



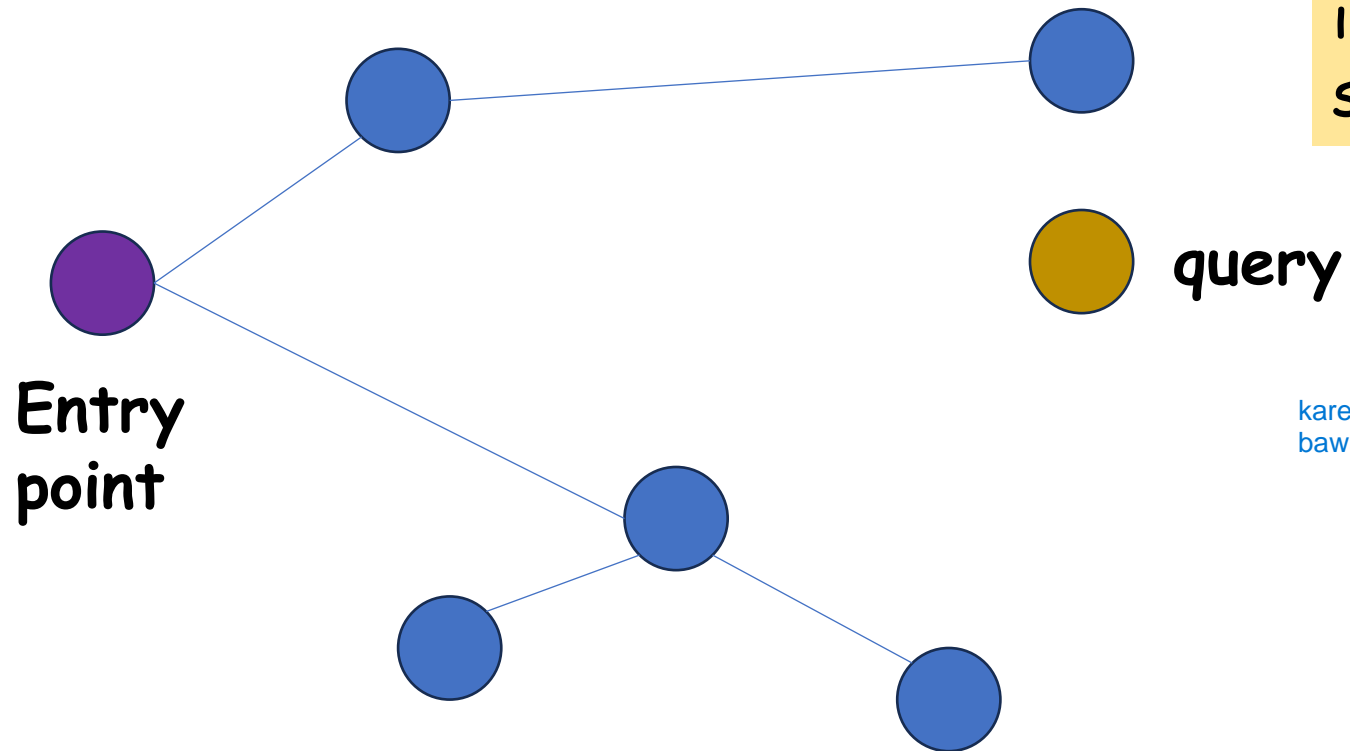
# Navigable Small World Graphs

Contoh lain:



# Navigable Small World Graphs

This greedy strategy **does not guarantee** that it will find the exact nearest neighbor as the method uses only local information at the current step to take decisions.



karena greedy, yang terdekat itu dari query vector itu yang entry point ke arah bawah

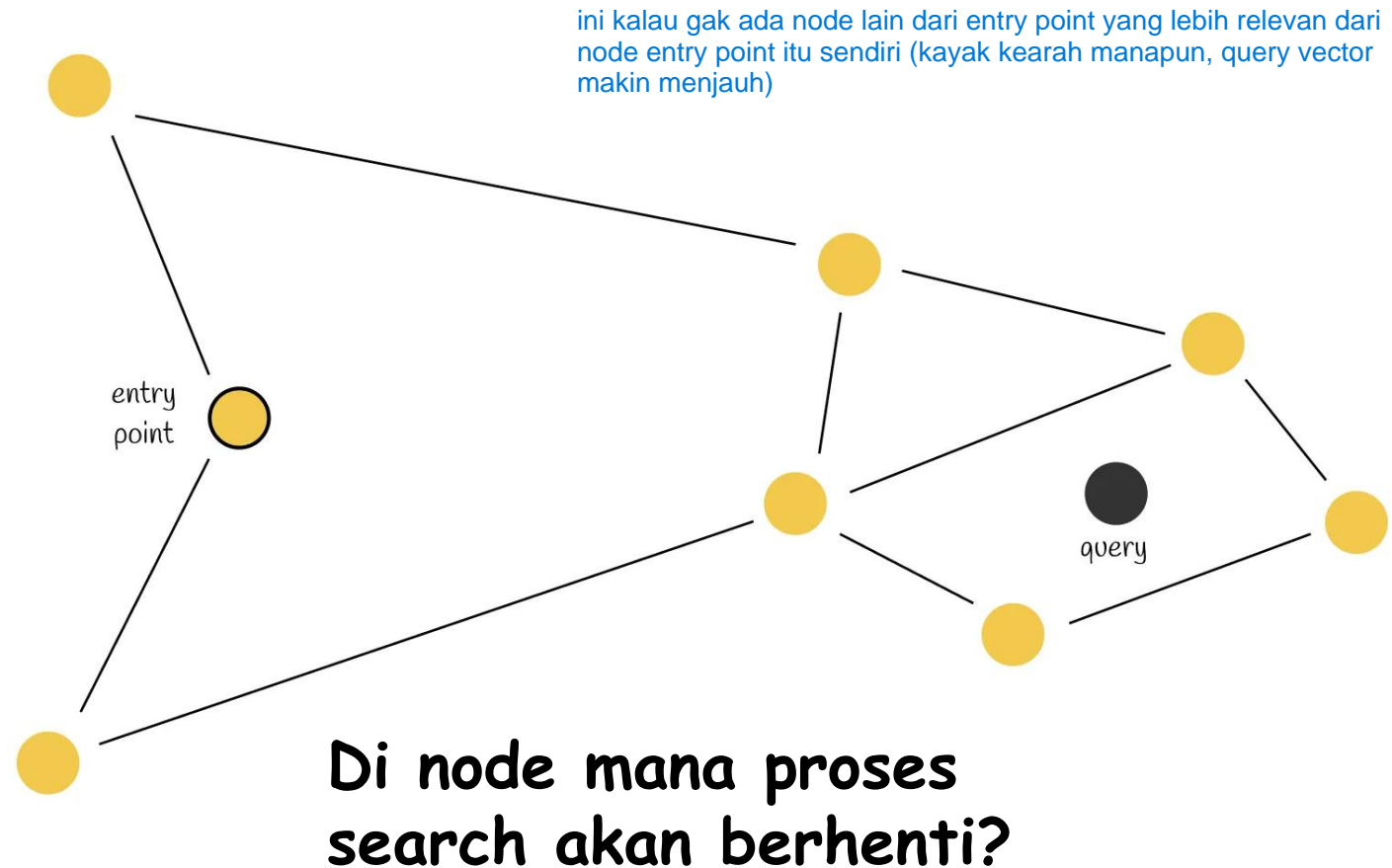
# Navigable Small World Graphs

(Search)

Problem:

**Early stopping** is one of the problems of the algorithm.

For the most part, this might happen when the starting region has too many **low-degree vertices**.



# Indexing

## (Constructing Navigable Small World Graphs)

# How to construct NSW? (indexing)

sebelumnya itu search, sekarang itu indexing

- Sebuah node = sebuah vektor
- Node A **dekat** dengan Node B = vektor A dan vektor B **"similar"** (cosine sim., Euclidean dist., dsb.)

M itu tetangga terdekat

- Misal, **M** adalah banyaknya tetangga terdekat untuk node yang baru "masuk".
- Pada setiap iterasi, sebuah node baru ditambahkan ke dalam index dan dihubungkan dengan **M** buah tetangga terdekat.



# Constructing Navigable Small World Graphs

$M = 2$

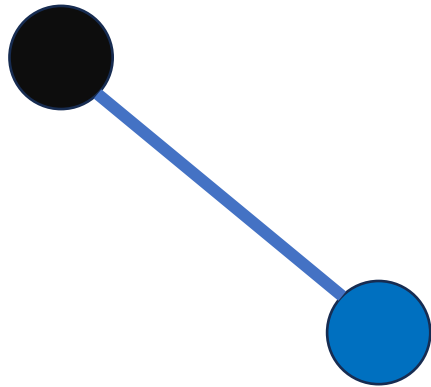


**Node biru:** vektor yang baru dimasukkan ke index

**Sisi biru:** sisi yang baru terbentuk

# Constructing Navigable Small World Graphs

$M = 2$

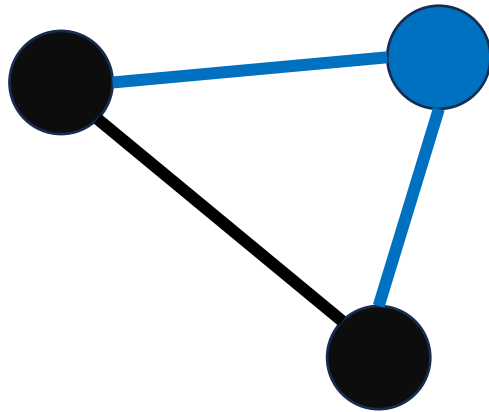


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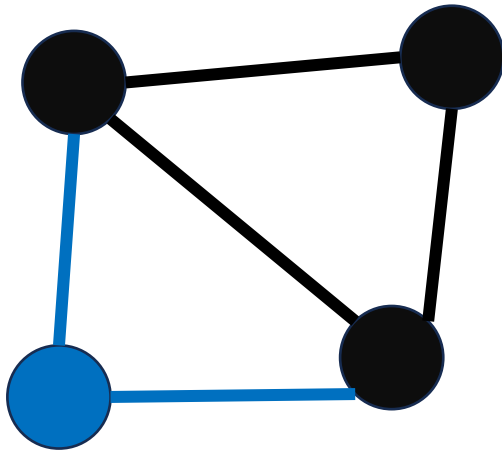


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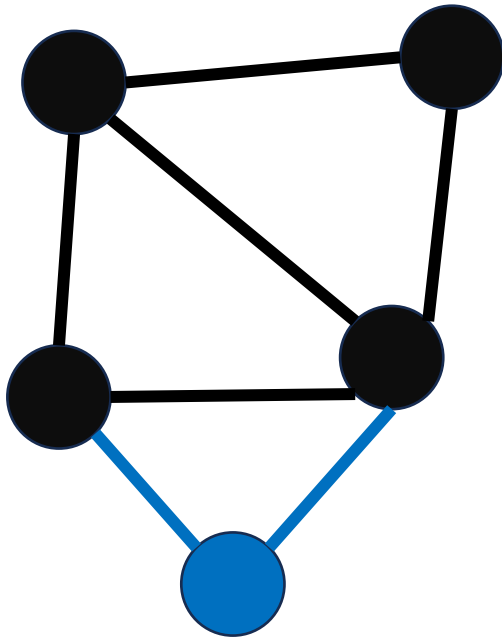


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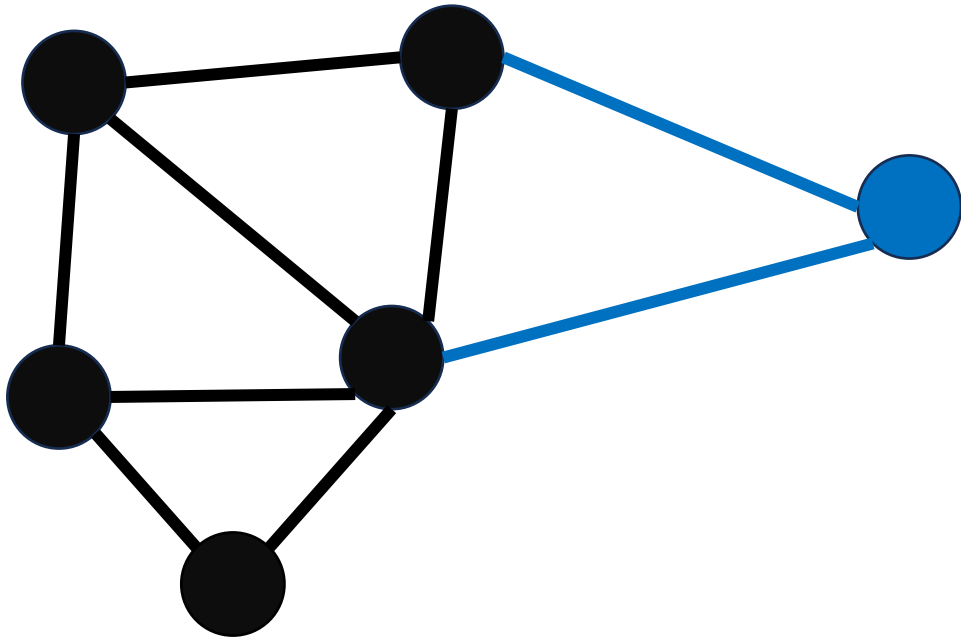


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# Constructing Navigable Small World Graphs

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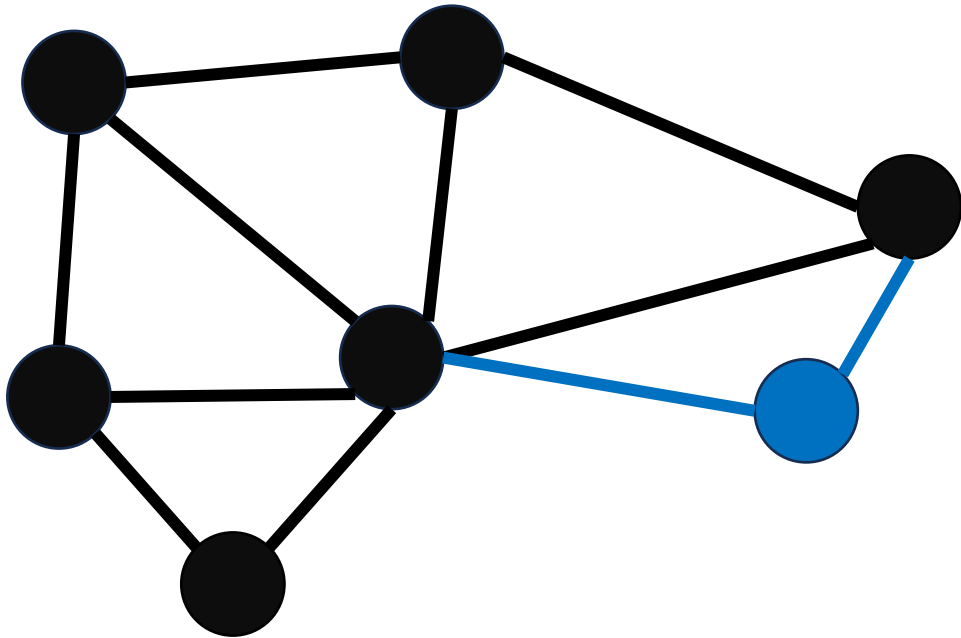


**Node biru:** vektor yang baru dimasukkan ke index

**Sisi biru:** sisi yang baru terbentuk

# Constructing Navigable Small World Graphs

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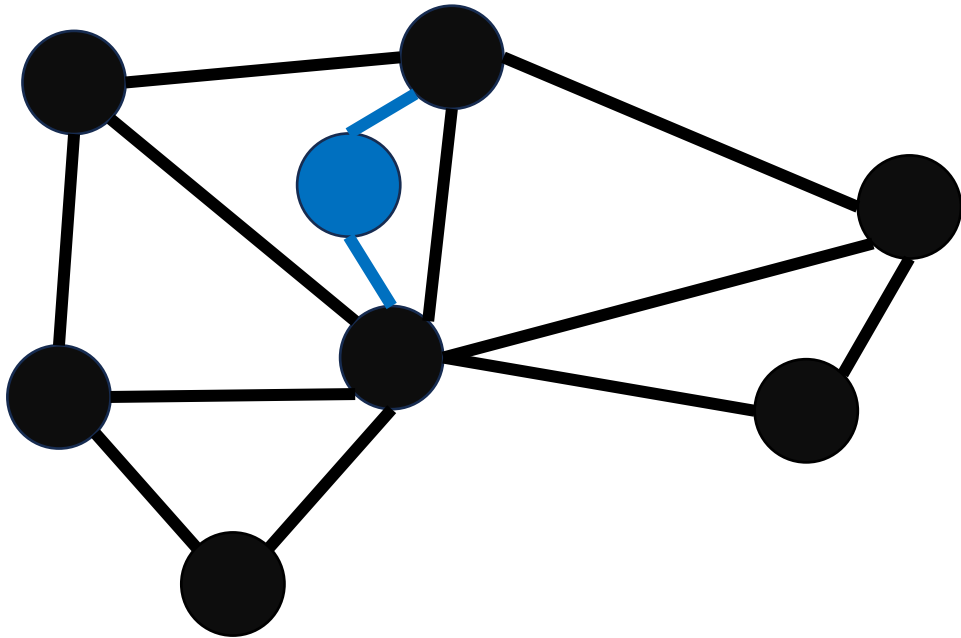


**Node biru:** vektor yang baru dimasukkan ke index

**Sisi biru:** sisi yang baru terbentuk

# Constructing Navigable Small World Graphs

$M = 2$



**Node biru:** vektor yang baru dimasukkan ke index

**Sisi biru:** sisi yang baru terbentuk



# Make them "Hierarchical"

## Hierarchical NSW = HNSW

IEEE TRANSACTIONS ON JOURNAL NAME, MANUSCRIPT ID

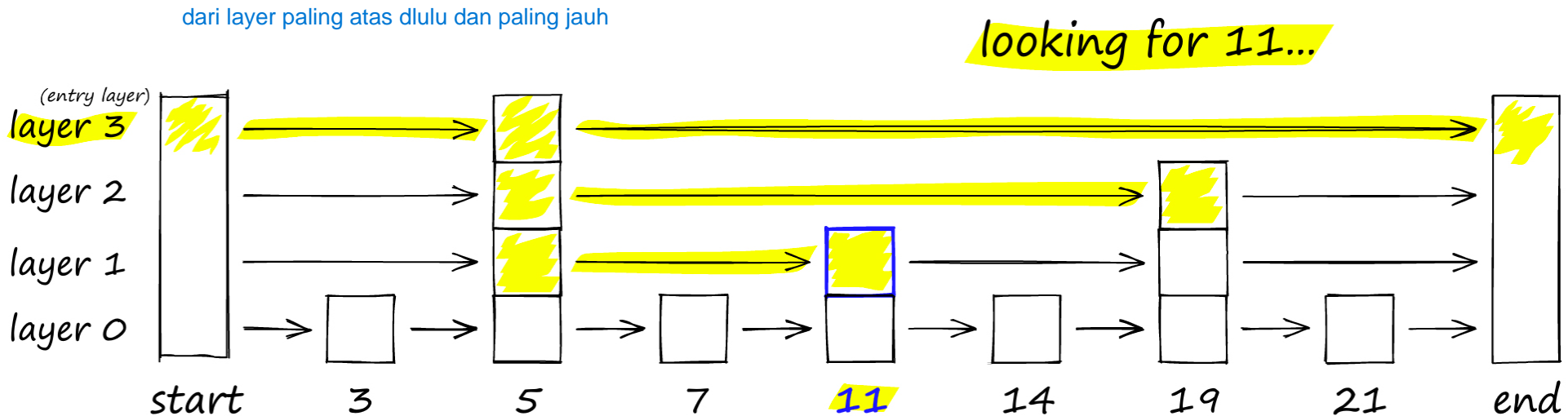
1

### Efficient and robust approximate nearest neighbor search using Hierarchical Navigable Small World graphs

Yu. A. Malkov, D. A. Yashunin

**Abstract** — We present a new approach for the approximate K-nearest neighbor search based on navigable small world graphs with controllable hierarchy (Hierarchical NSW, HNSW). The proposed solution is fully graph-based, without any need for additional search structures, which are typically used at the coarse search stage of the most proximity graph techniques. Hierarchical NSW incrementally builds a multi-layer structure consisting from hierarchical set of proximity graphs (layers) for nested subsets of the stored elements. The maximum layer in which an element is present is selected randomly with an

# Probability Skip List - Fast Search



To search a skip list, we start at the highest layer with the longest 'skips' and move along the edges towards the right (below). If we find that the current node 'key' is *greater than* the key we are searching for — we know we have overshoot our target, so we move down to previous node in the *next* level.

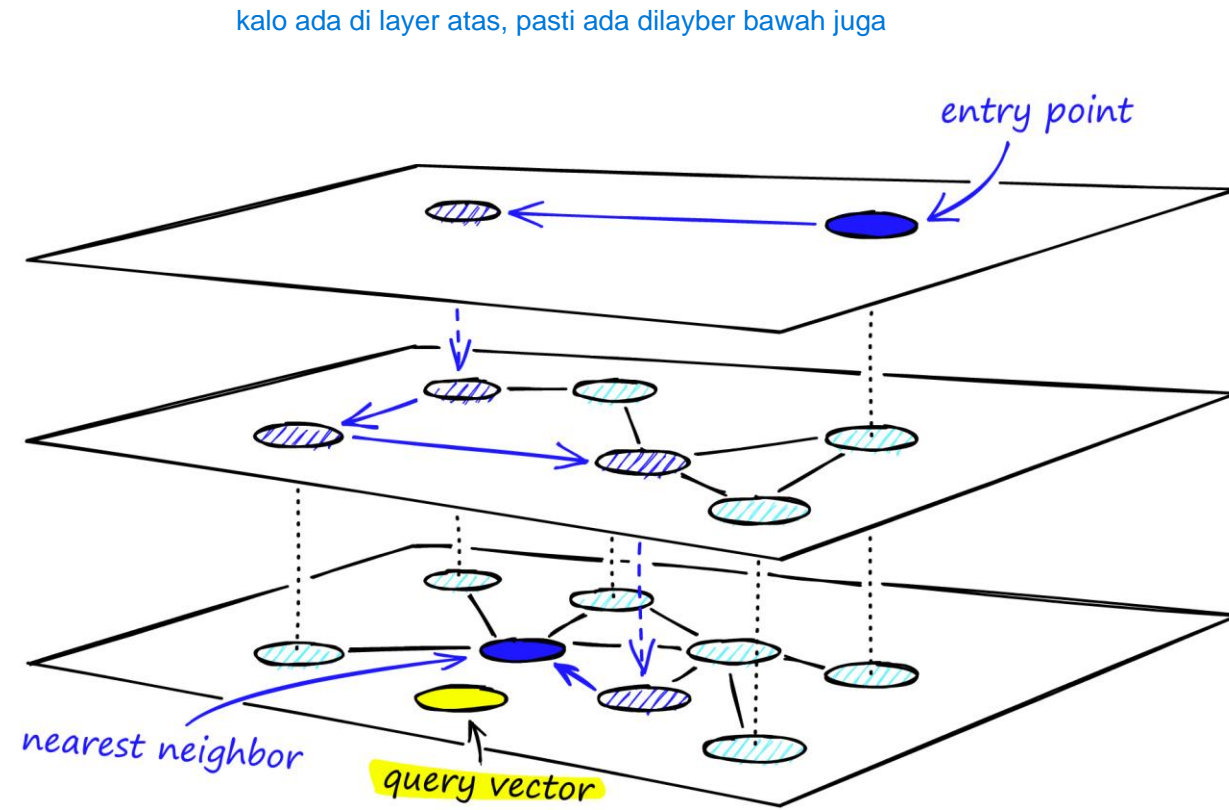
A skip list has the main parameter  $p$  which defines **the probability of an element appearing in several lists**. If an element appears in **layer  $i$** , then the probability that it will appear in **layer  $i + 1$**  is equal to  $p$ .

Insert & search: **On average  $O(\log N)$**

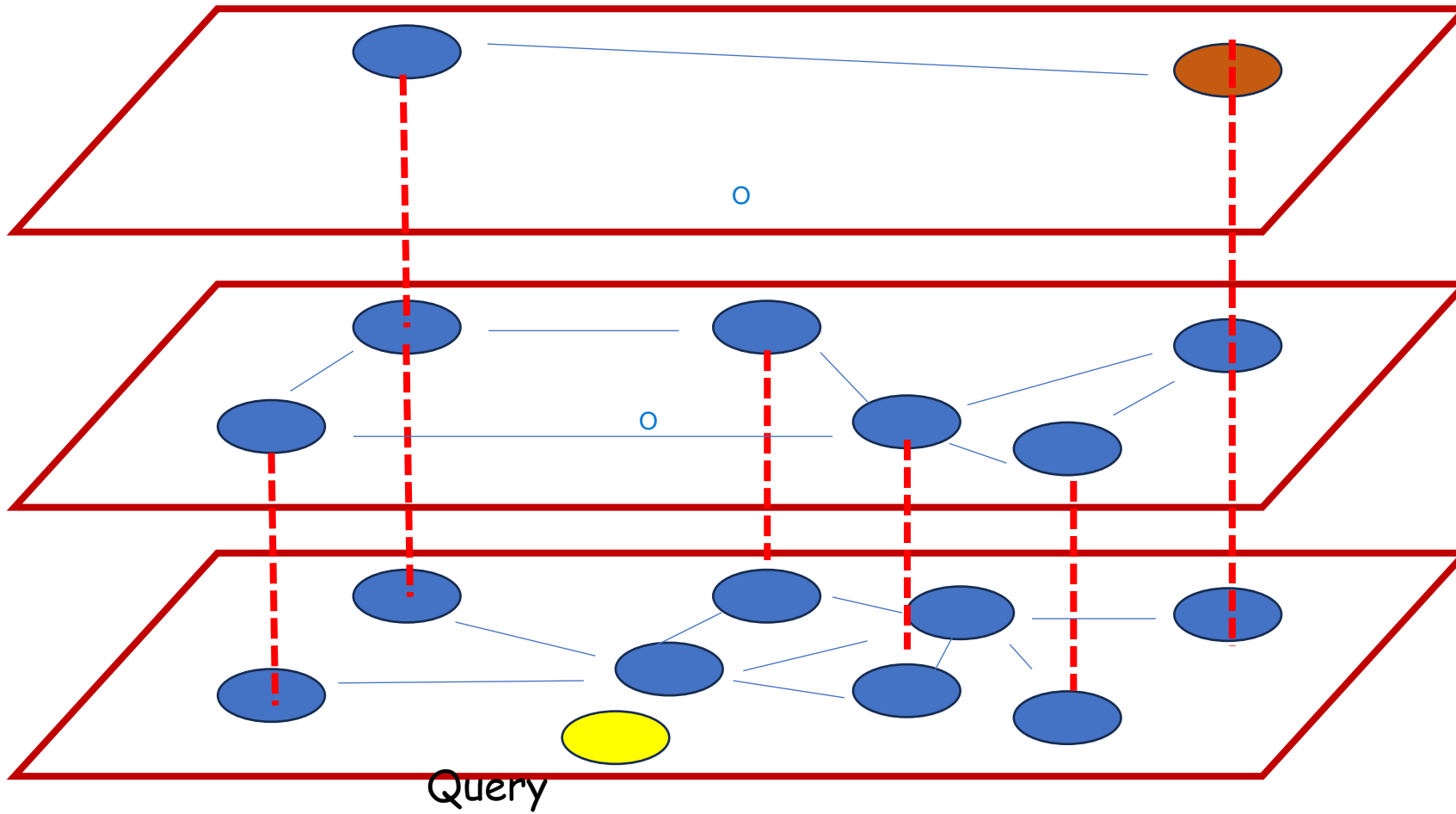
# Hierarchical Navigable Small World Graphs

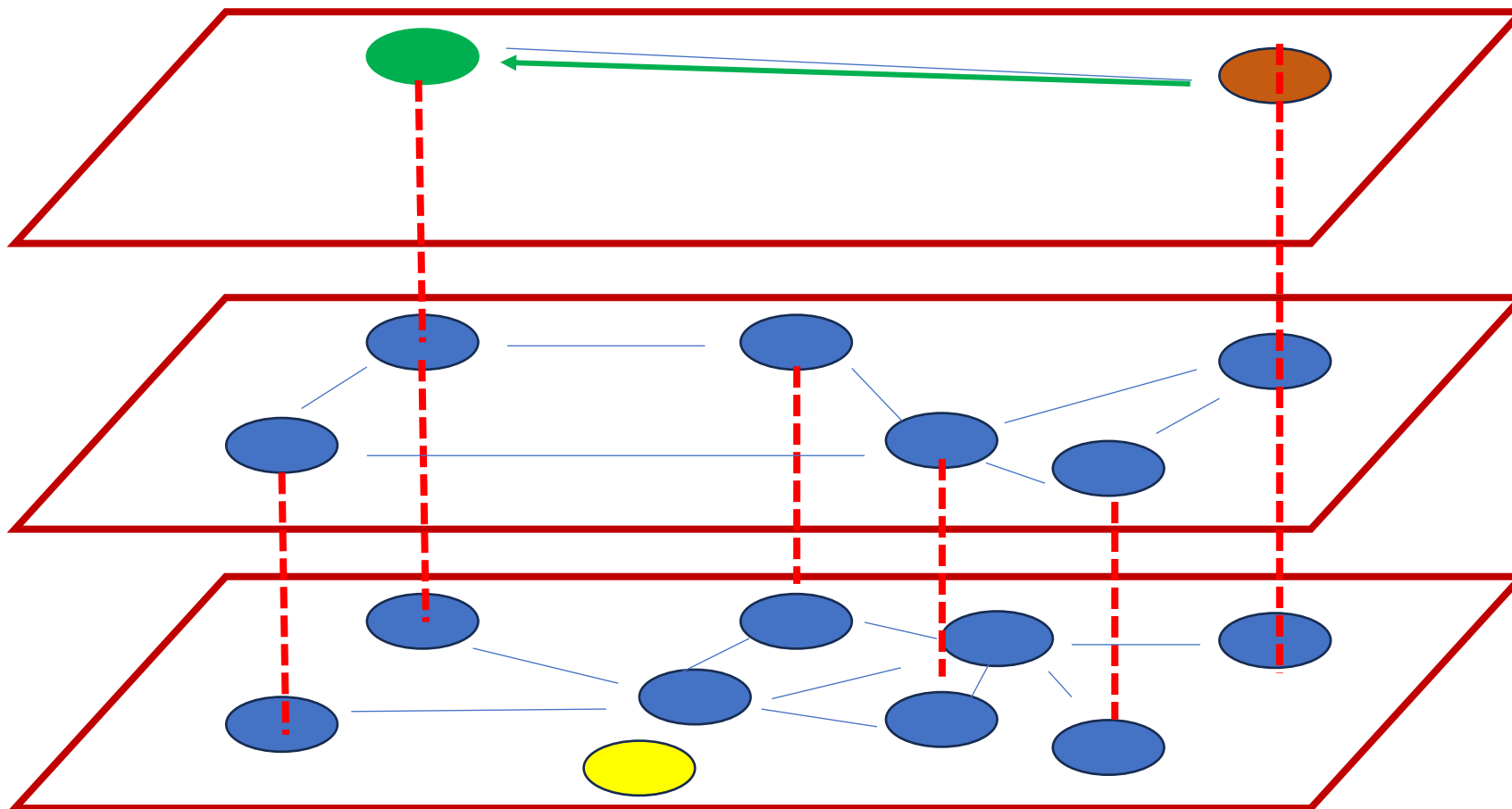
During the search, we enter the top layer. These vertices will tend to be **higher-degree vertices** (with links separated across multiple layers), meaning that we, by default, start in the **zoom-in phase**.

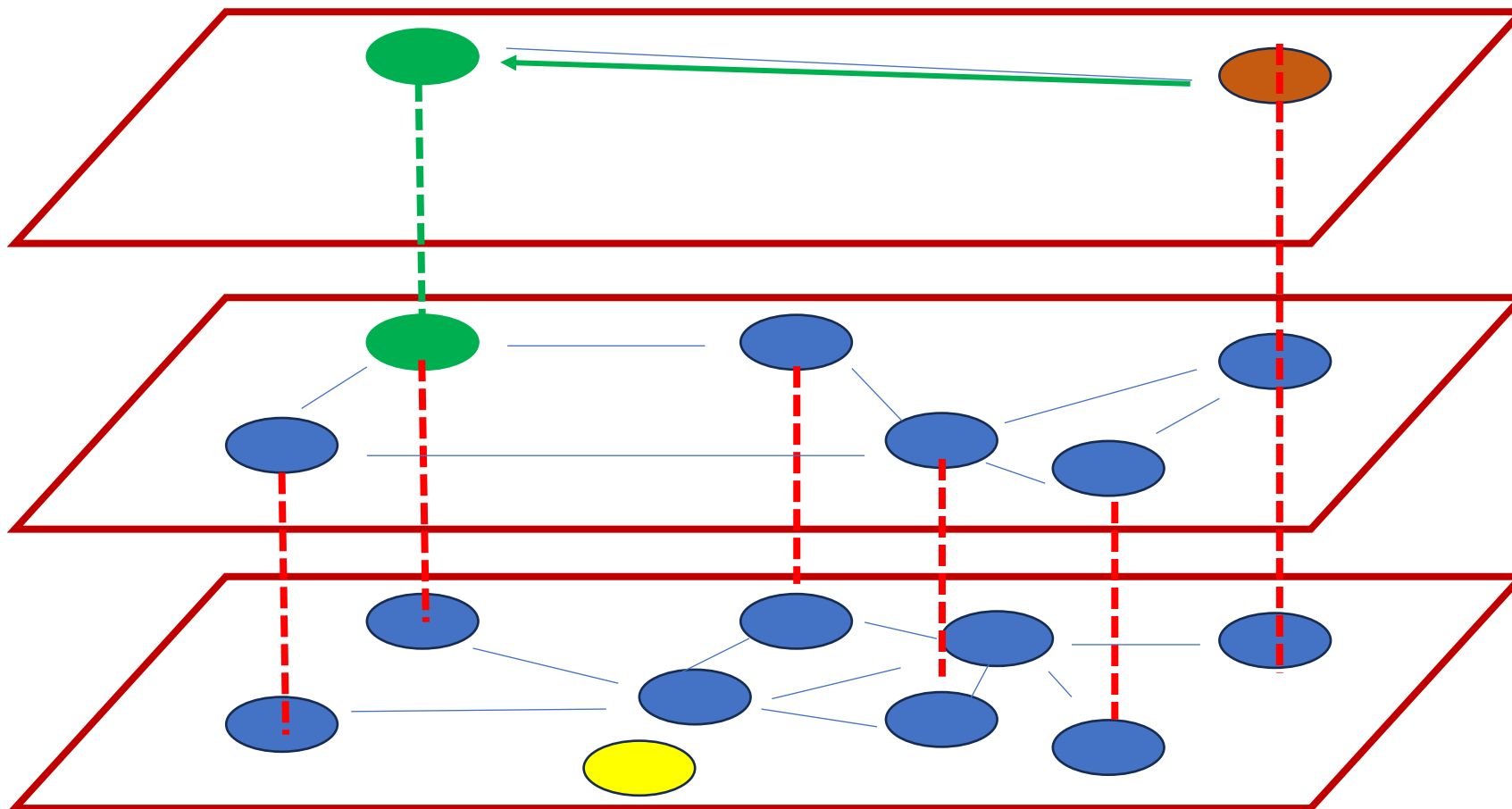
We move to the nearest vertex until we find a local minimum. Unlike NSW, **at this point, we shift to the current vertex in a lower layer and begin searching again**. We repeat this process until finding the local minimum of our bottom layer — layer 0.

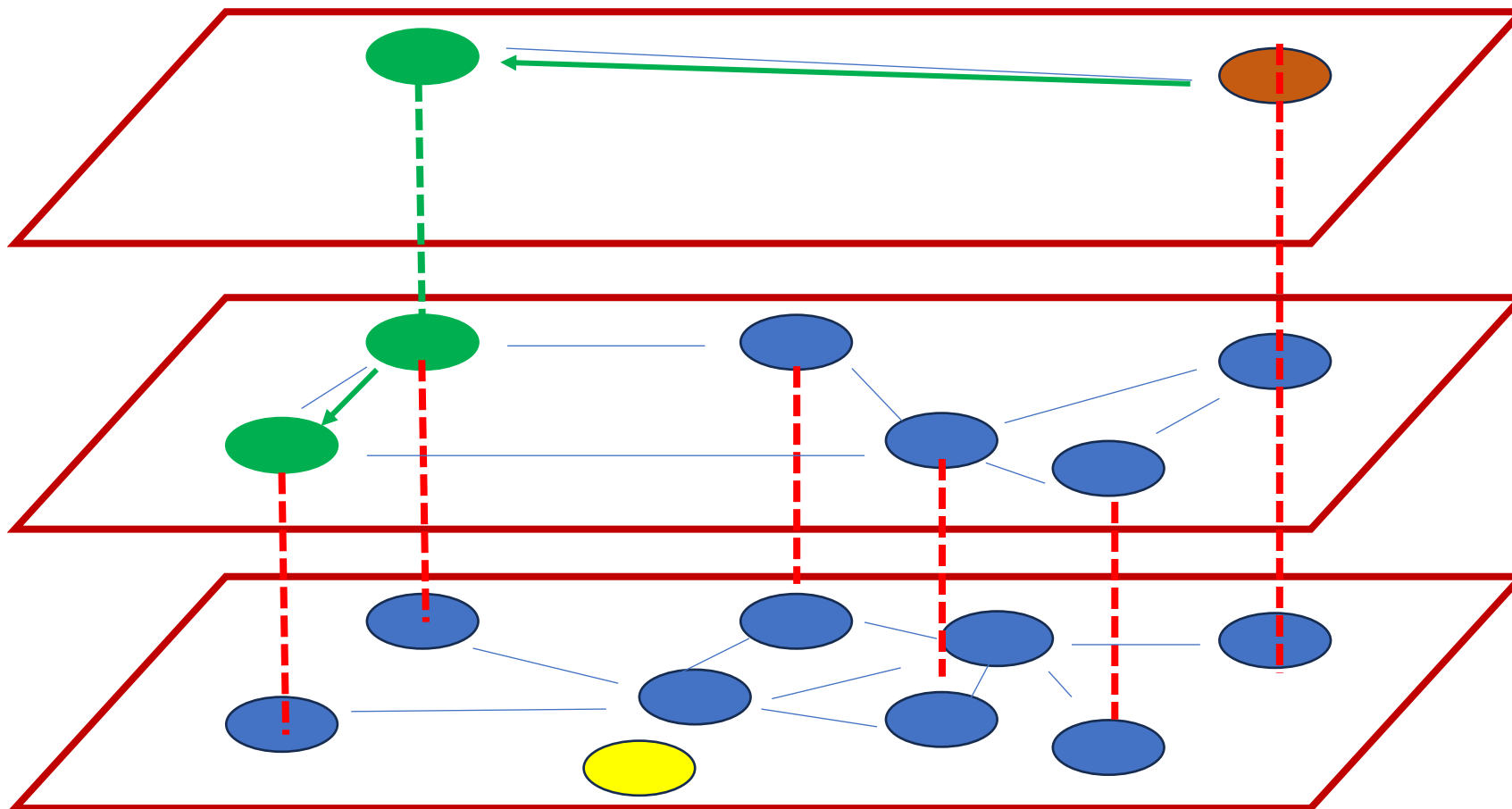


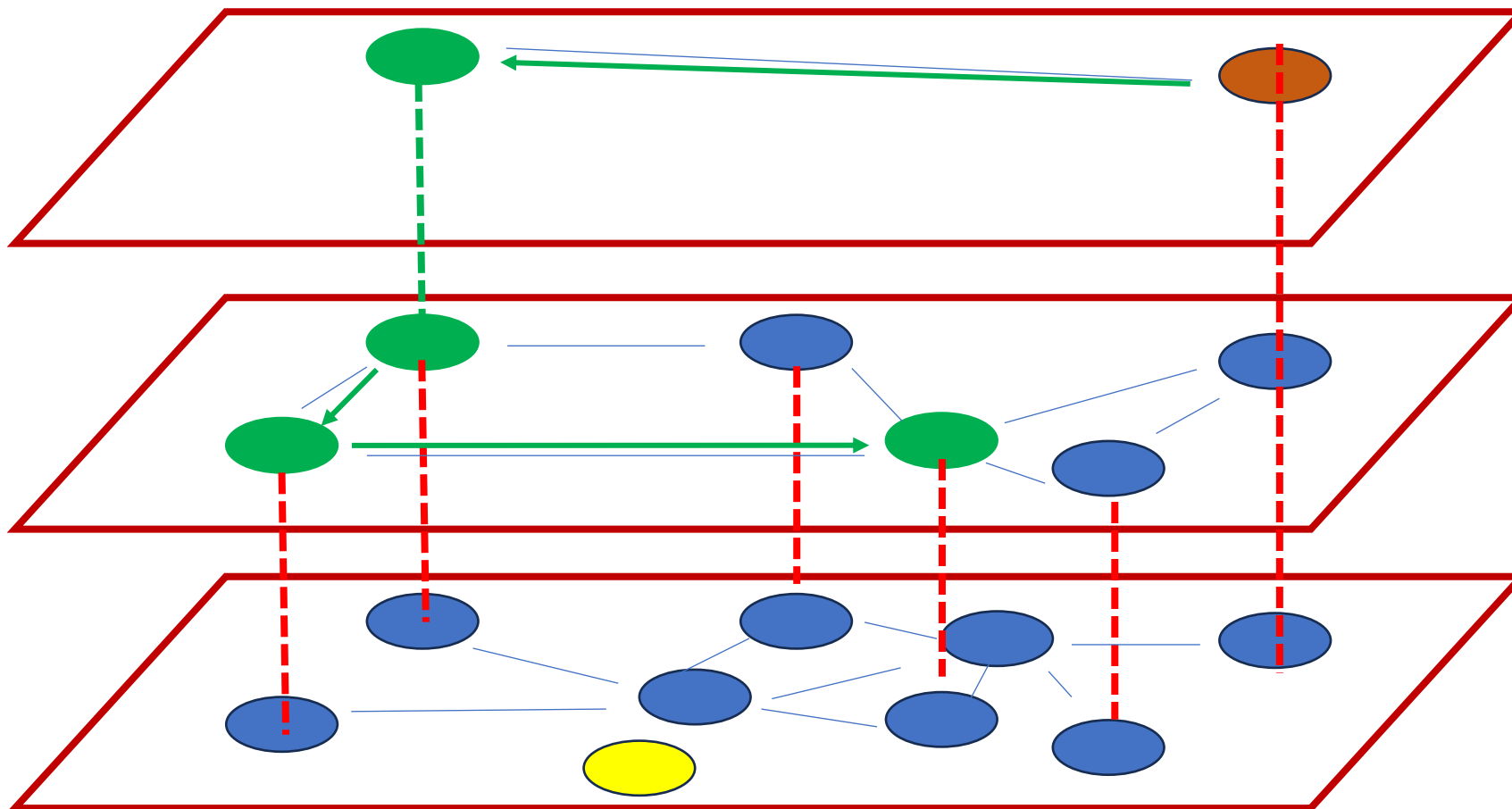
ngitung jaraknya itu query vector di copy per layer



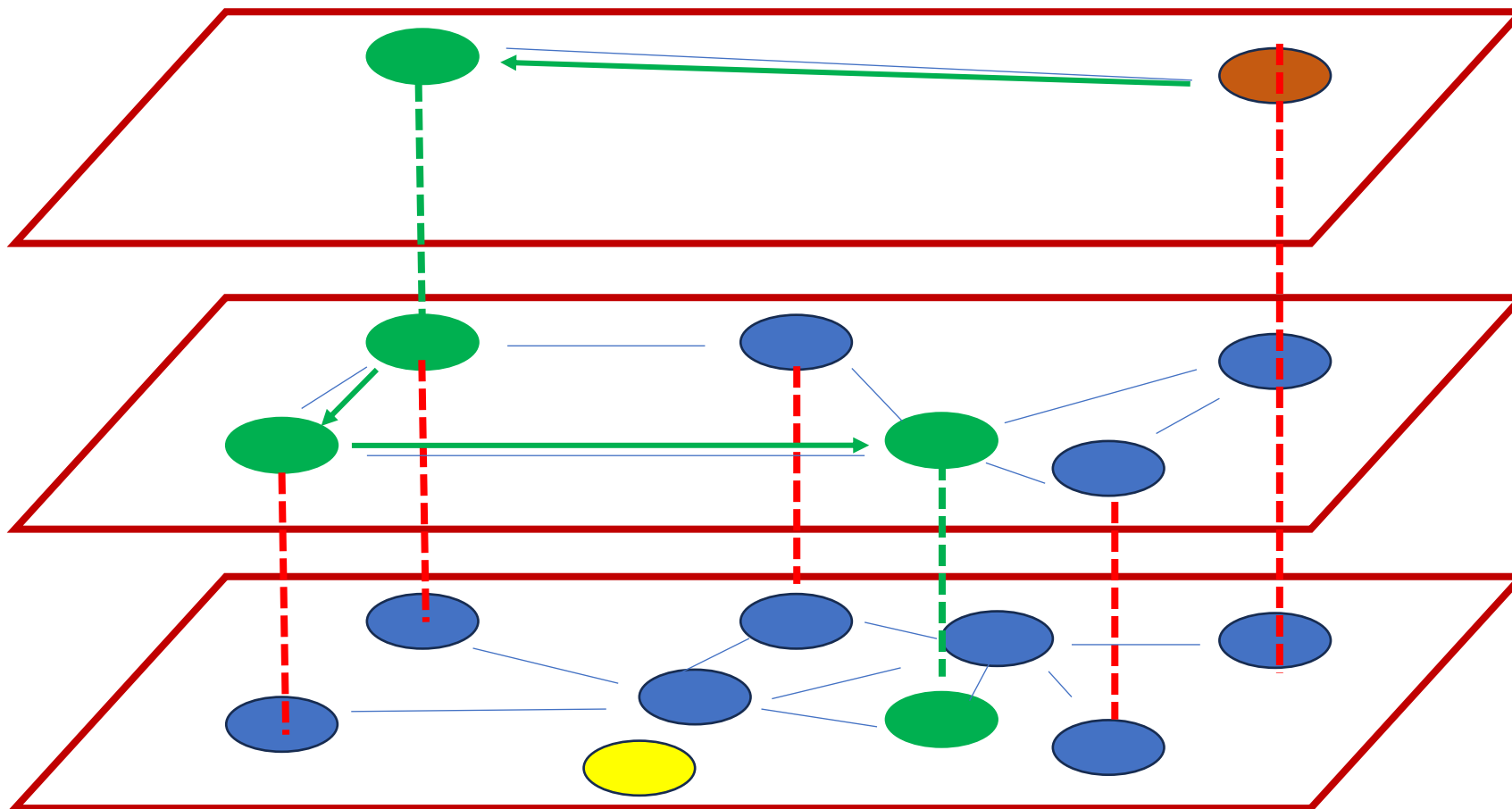


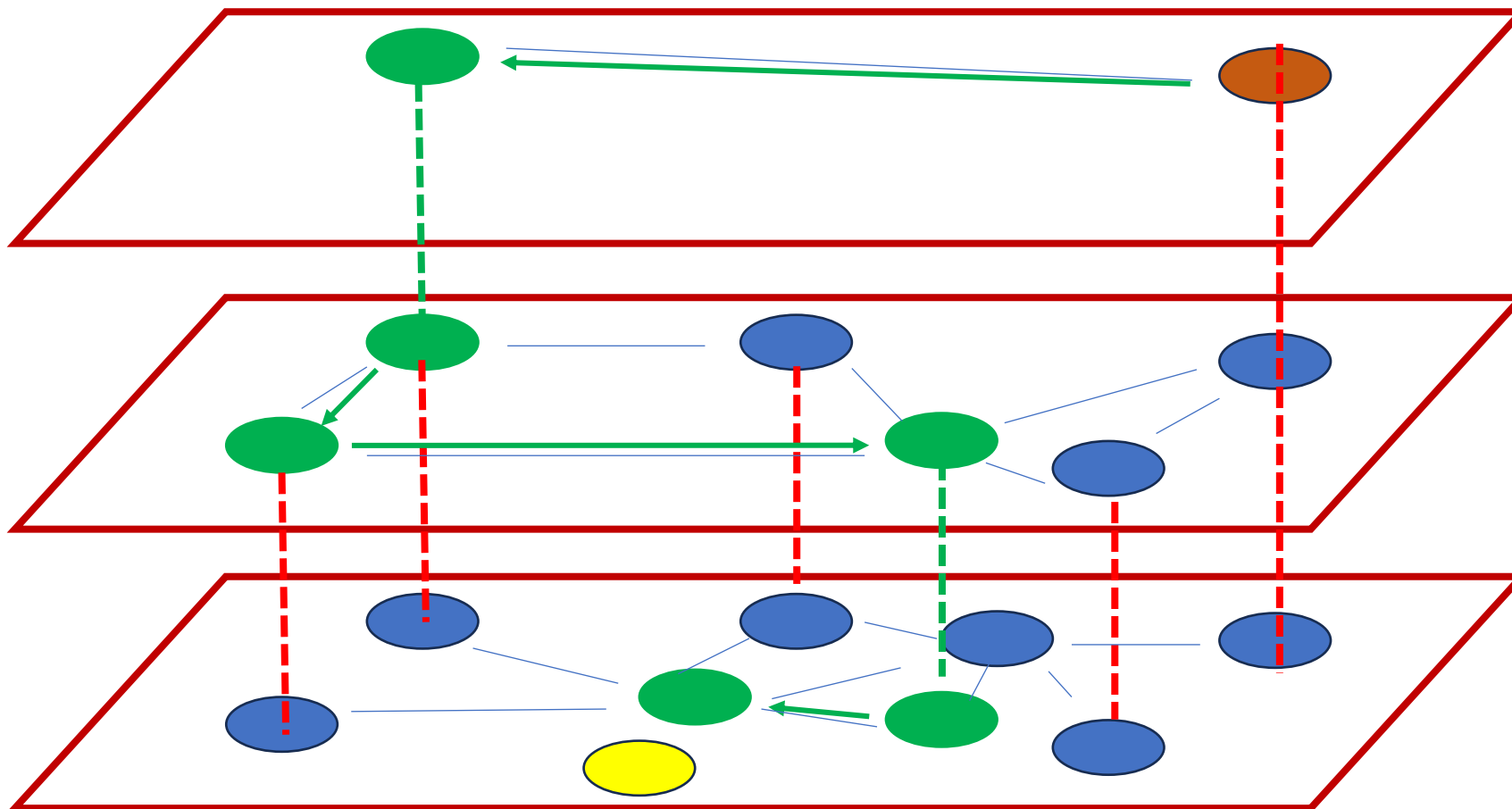










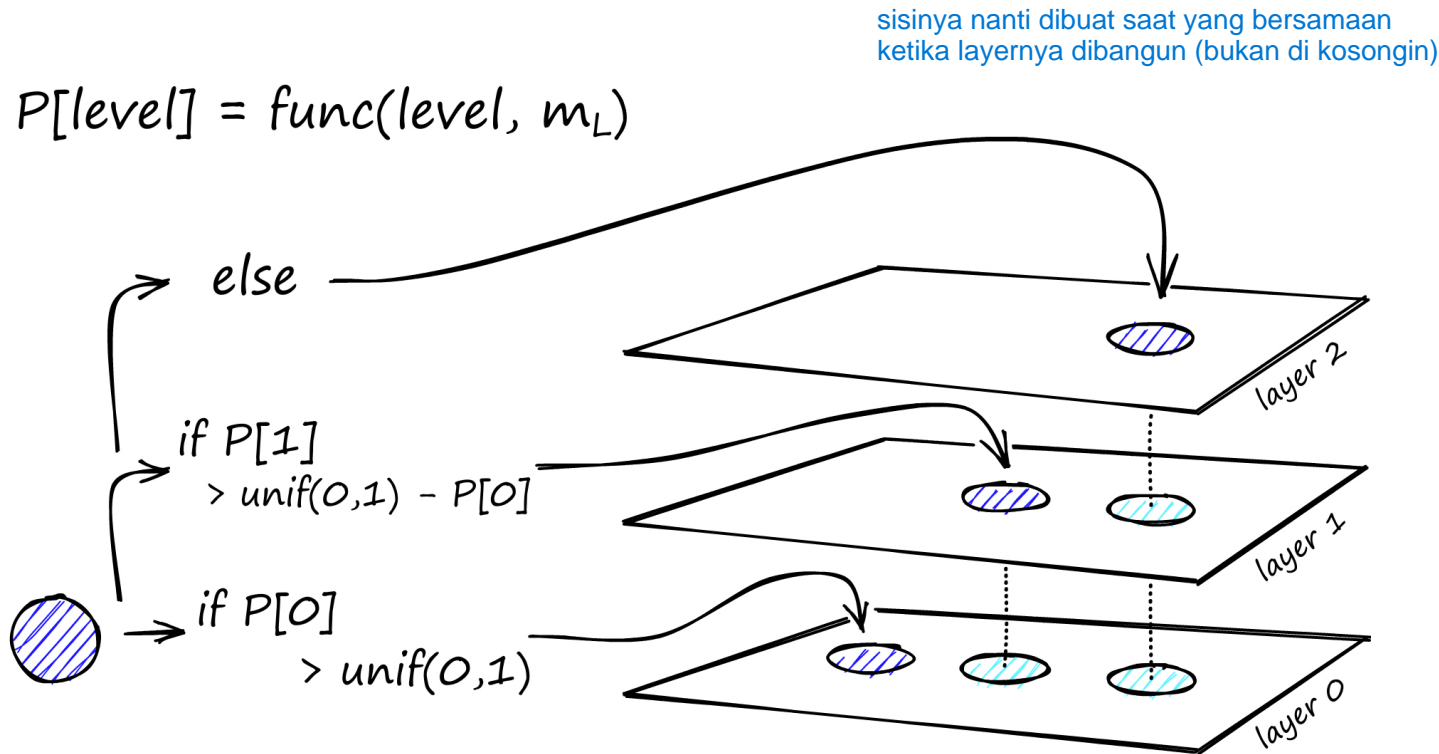


# How to construct HNSW graph?

lebih cepat karena bisa di skip per layer nya

During graph construction, vectors are iteratively inserted one-by-one. The number of layers is represented by **parameter  $L$** .

The probability of a vector insertion at a given layer is given by an **exponentially decaying probability** function normalized by the '**level multiplier**'  $m_L$



The probability function is repeated for each layer (other than layer 0).

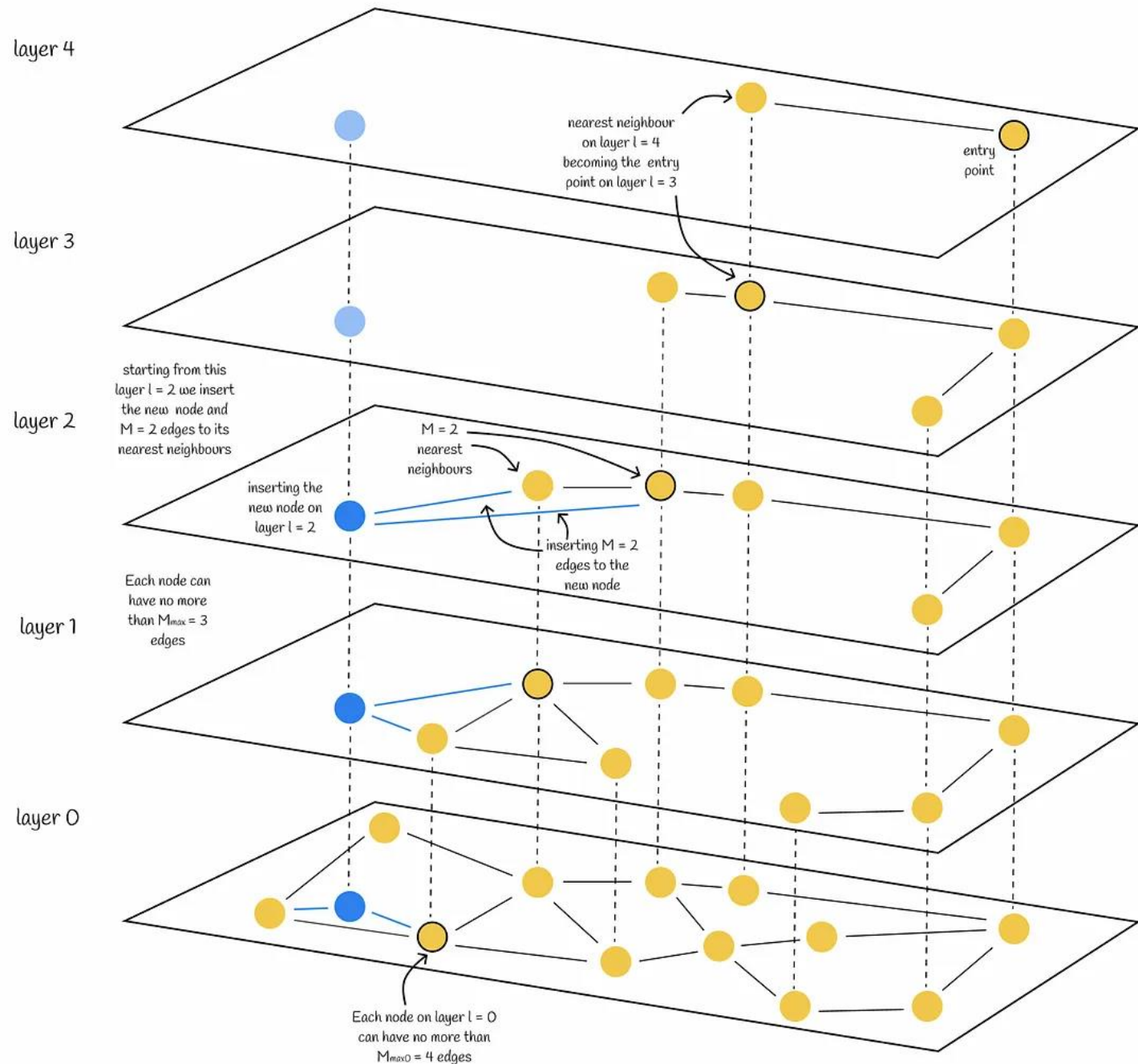
The vector is added to its insertion layer and every layer below it.

# Constructing HNSW

After a node is assigned the level number (**value 1**), the algorithm starts from the upper layer and greedily finds the nearest node.

The found node is then used as an entry point to the next layer and the search process continues.

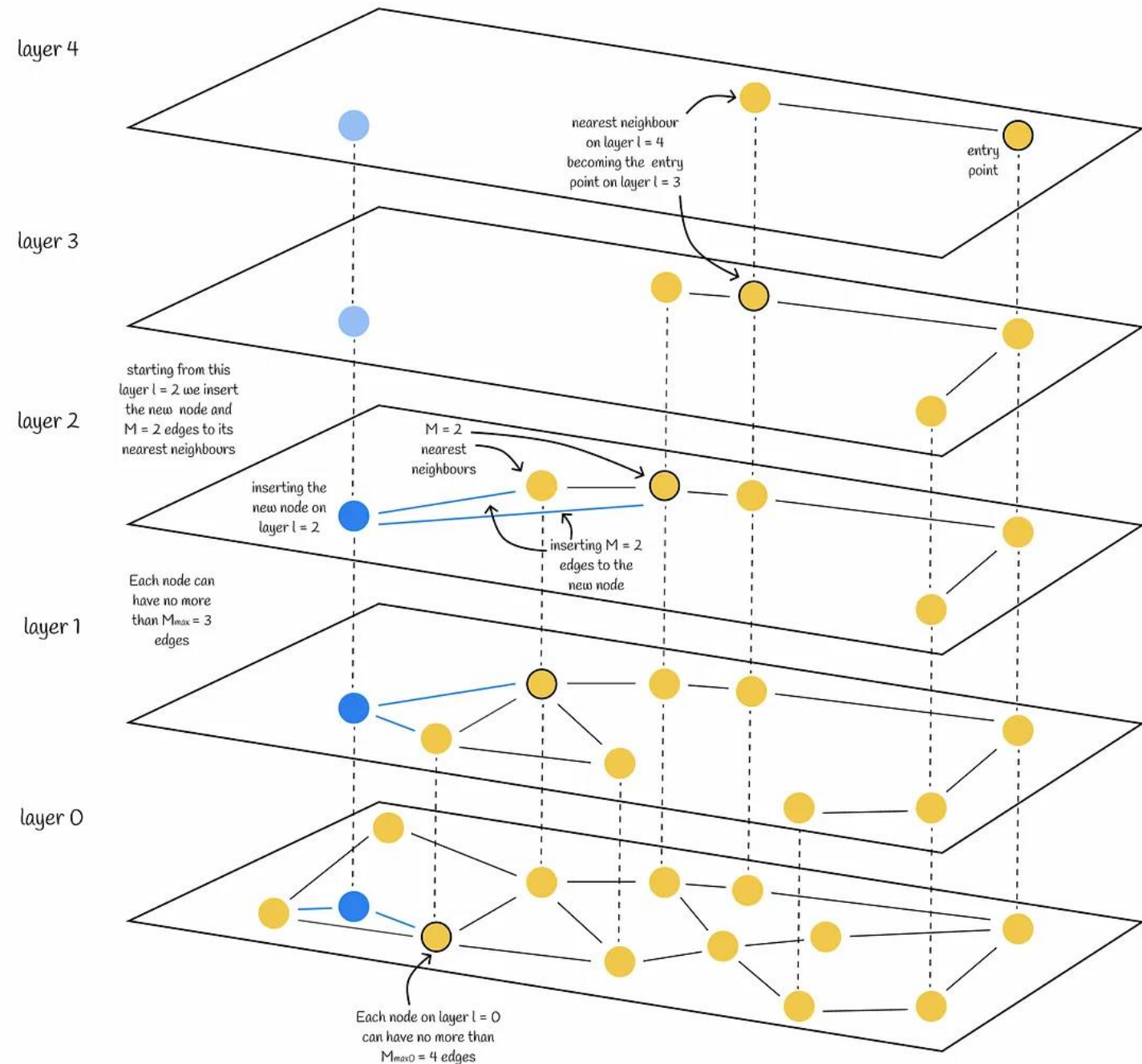
**Once the layer 1 is reached,** the insertion proceeds to the second step.



# Constructing HNSW

Starting from **layer 1** the algorithm inserts the new node at the current layer.

Then it acts the same as before at step 1 but instead of finding only one nearest neighbour, it greedily searches for **efConstruction** (hyperparameter) nearest neighbours.





# Constructing HNSW

Then  $M$  out of **efConstruction** neighbours are chosen and edges from the inserted node to them are built.

After that, the algorithm descends to the next layer and each of found **efConstruction** nodes acts as an entry point. The algorithm terminates after the new node and its edges are inserted on the lowest layer 0.

