

Alice's Adventures in a differentiable wonderland

More on Neural Network Architectures

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This set of slides is prepared by **Alfan F. Wicaksono**Information Retrieval, CS UI

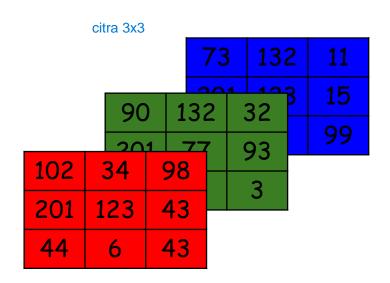
* Some slides were originally made by Alfan

"Convolutional" Neural Networks

- Fully-connected layers are important historically, but less so from a practical point of view: on unstructured data, FC layers are generally outperformed by other alternatives, such as random forests, gradient boosting trees, or well tuned support vector machines.
- This is not true, however, as soon as we consider other types of data, having some structure that can be exploited in the design of the layers and of the model.

channe

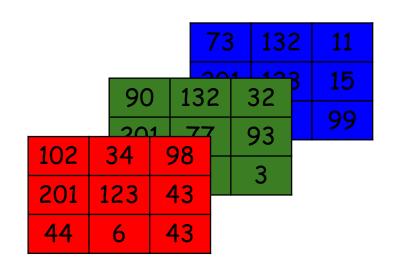
An image can be described by a tensor $X \sim (c, h, w)$, where h is the height of the image, w the width of the image, and c is the number of channels (which can be 1 for black and white images, or 3 for color images, RGB).

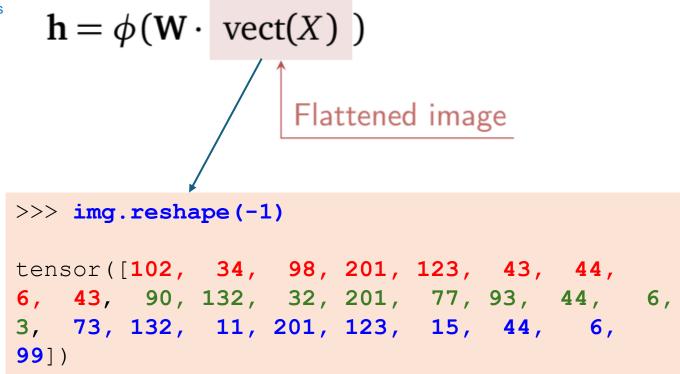


An image 3×3 pixels with 3 channels

In order to use a fully-connected layer, we would need to "flatten" (vectorize) the image:

kita perlu mendatarkan vektor kita kalau mau pakai fully connected layers





An image 3×3 pixels with 3 channels

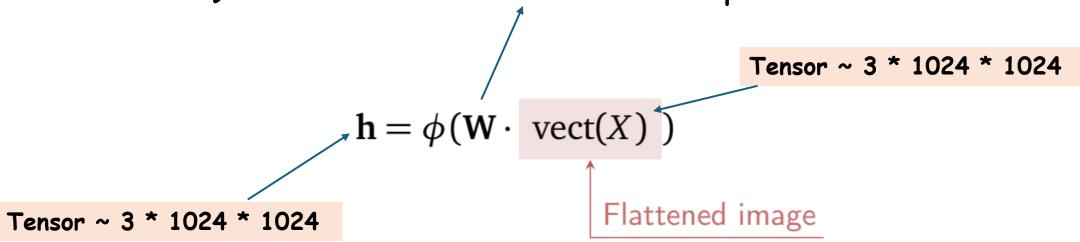
This leads directly to an issue, which is that the layer has a huge number of parameters.

parameternya gede akan sangat sulit

kalau kita flatten:

- paramternya itu ilang
- locality nya juga ilang

Considering, for example, a (1024, 1024) image in RGB, keeping the same dimensionality in output results in (1024 * $1024 * 3) ^2 = 9.895.604.649.984$ parameters!



Fully-connected layer on a 1D sequence

As a running example to visualize what follows, consider a 1D sequence (we will consider 1D sequences more in-depth later on; for now, you can think of this as "4 pixels with a single channel"):

$$\mathbf{x} = \left[x_1, x_2, x_3, x_4 \right]$$

In this case, we do not need any reshaping operations, and the previous layer (with c'=1) can be written as:

$$\begin{bmatrix} h_1 \\ h_2 \\ h_3 \\ h_4 \end{bmatrix} = \begin{bmatrix} W_{11} & W_{12} & W_{13} & W_{14} \\ W_{21} & W_{22} & W_{23} & W_{24} \\ W_{31} & W_{32} & W_{33} & W_{34} \\ W_{41} & W_{42} & W_{43} & W_{44} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix}$$

Figure F.7.1: Given a tensor (h, w, c) and a maximum distance k, the **patch** $P_k(i, j)$ (shown in red) is a (2k + 1, 2k + 1, c) tensor collecting all pixels at distance at most k from the pixel in position (i, j).

s = 2k + 1; we call s the filter size / kernel size.

s = 2k + 1Width

Definition D.7.1 (Image patch) Given an image X, we define the **patch** $P_k(i, j)$ as the sub-image centered at (i, j) and containing all pixels at distance equal or lower than k:

Height

$$P_k(i,j) = [X]_{i-k:i+k,j-k:j+k,:}$$

Locally-connected layers

Perbaikan dari Fully Connected Layer

fully connected layer, inputnya itu sebuah citra dimana:

h (tinggi) x w (panjang) x c (lebar) itu outputnya: tinggi (h), panjang (w), c' (lebar)

Definition D.7.2 (Local layer) Given an input image $X \sim (h, w, c)$, a layer $f(X) \sim (h, w, c')$ is **local** if there exists a k such that:

$$[f(X)]_{ij} = f(P_k(i,j))$$

kalau ada gambar 16x16, maka ada patch (1x1) sebanyak 16 kali

Nah tapi patch ini sizenya tergantung dengan s

This has to hold for all pixels of the image.

Total number of parameters = h * w * (s * s * c * c')

For comparison, in the fully-connected layers, we had $(h * w)^2 * (c * c')$

Locally-connected layer on a 1D sequence

untuk locally bedanya sama fully

1 patch 1 bobot

cuman kalau fully connected layer semua patch, 1 bobot

kalo locally connected layer gak perlu full.

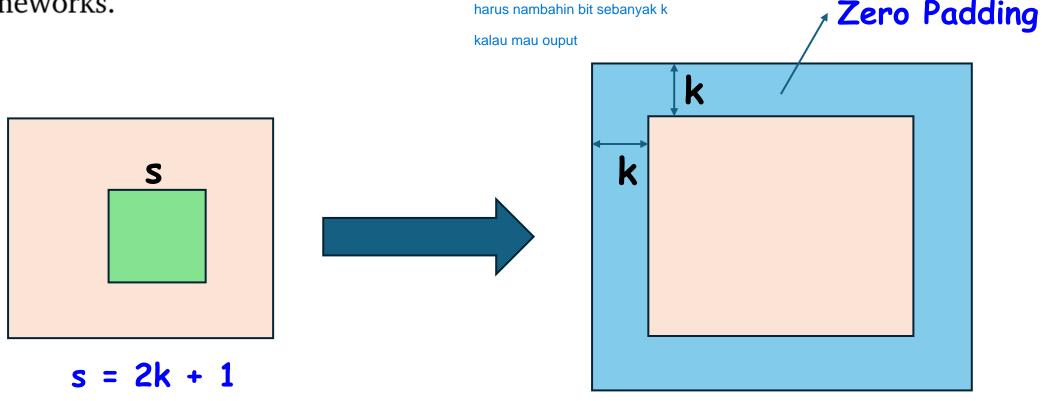
dibandingkan fully connected layer

Considering our toy example, assuming for example k = 1 (hence s = 3) we can write the resulting operation as:

$$\begin{bmatrix} h_1 \\ h_2 \\ h_3 \\ h_4 \end{bmatrix} = \begin{bmatrix} W_{11} & W_{12} & W_{13} & 0 & 0 & 0 \\ 0 & W_{21} & W_{22} & W_{23} & 0 & 0 \\ 0 & 0 & W_{31} & W_{32} & W_{33} & 0 \\ 0 & 0 & 0 & W_{41} & W_{42} & W_{43} \end{bmatrix} \begin{bmatrix} 0 \\ x_1 \\ x_2 \\ x_3 \\ x_4 \\ 0 \end{bmatrix}$$
 Zero Padding

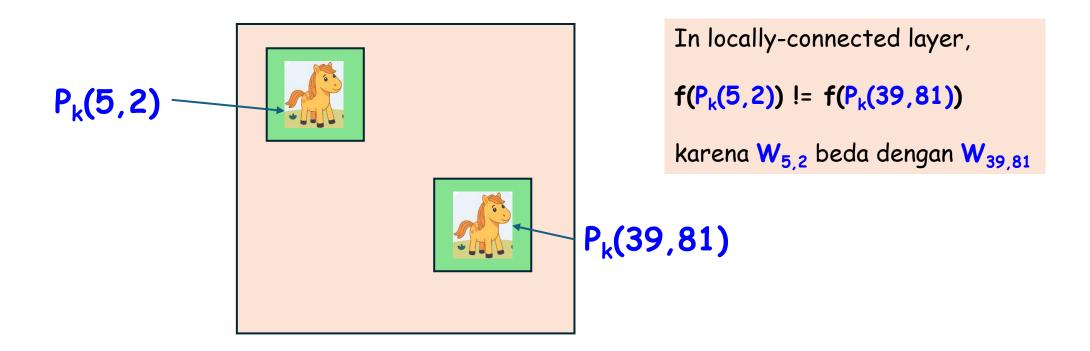
Zero-Padding

This technique is called **zero-padding**. In an image, for a kernel size 2k + 1 we need exactly k rows and columns of 0 on each side to ensure that the operation is valid for each pixel. Otherwise, the output cannot be computed close to the borders, and the output tensor will have shape (h - 2k, w - 2k, c'). Both are valid options in most frameworks.



Translation Equivariance

In a locally-connected layer, two identical patches can result in different outputs based on their location: some content on pixel (5,2), for example, will be processed differently than the same content on pixel (39,81) because the two matrices $W_{5,2}$ and $W_{39,81}$ are different. For the most part, however, we can assume that this information is irrelevant: informally, "a horse is a horse", irrespective of its positioning on the input image. We can formalize this with a property called **translation equivariance**.



Translation Equivariance

In a locally-connected layer, two identical patches can result in different outputs based on their location: some content on pixel (5,2), for example, will be processed differently than the same content on pixel (39,81) because the two matrices $\mathbf{W}_{5,2}$ and $\mathbf{W}_{39,81}$ are different. For the most part, however, we can assume that this information is irrelevant: informally, "a horse is a horse", irrespective of its positioning on the input image. We can formalize this with a property called **translation equivariance**.

Definition D.7.3 (Translation equivariance) We say that a layer H = f(X) is **translation equivariant** if:

kalau misal 2 2nya pixelnya sama, pasti bobotnya sama juga. Nah ini yang disebut convulotional layer.

$$P_k(i,j) = P_k(i',j') \quad \text{implies} \quad f(P_k(i,j)) = f(P_k(i',j'))$$

$$| \text{Identical patches}$$

Translation Equivariance & Convolutional layers

We do weight sharing, ting every position share the same set of weights:

$$H_{ij} = \phi(\mathbf{W} \cdot \text{vect}(P_k(i, j)))$$

Weight matrix does not depend on (i, j)

Definition D.7.4 (Convolutional layer) Given an image $X \sim (h, w, c)$ and a kernel size s = 2k + 1, a **convolutional layer** H = Conv2D(X) is defined element-wise by:

$$H_{ij} = \mathbf{W} \cdot \text{vect}(P_k(i,j)) + \mathbf{b}$$
 (E.7.4)

The trainable parameters are $\mathbf{W} \sim (c',ssc)$ and $\mathbf{b} \sim (c')$. The hyper-parameters are k, c', and (eventually) whether to apply zero-padding or not. In the former case the output has shape (h,w,c'), in the latter case it has shape (h-2k,w-2k,c').

Translation Equivariance & Convolutional layers

We do weight sharing, ting every position share the same set of weights:

$$H_{ij} = \mathbf{W} \cdot \text{vect}(P_k(i,j)) + \mathbf{b}$$

$$\uparrow \text{Weight matrix does not depend on } (i,j) \text{ Shape = } (\mathbf{c'}, \mathbf{s*s*c})$$

Fully-connected layer -> Total number of parameters = $(h * w)^2 * (c * c')$

Locally-connected layer -> Total number of parameters = h * w * (s * s * c * c')

Convolutional layer -> Total number of parameters = (s * s * c * c') + c'

karena bobotnya sama, makanya kayak h * w dihapus aja disini.

Convolutional layer on a 1D sequence

Considering our toy example, assuming for example k = 1 (hence s = 3) we can write the resulting operation as:

kalau fully connected layer, weightny ada semua (gak ada yang di 0 in)

$$\begin{bmatrix} h_1 \\ h_2 \\ h_3 \\ h_4 \end{bmatrix} = \begin{bmatrix} W_{11} & W_{12} & W_{13} & 0 & 0 & 0 \\ 0 & W_{21} & W_{22} & W_{23} & 0 & 0 \\ 0 & 0 & W_{31} & W_{32} & W_{33} & 0 \\ 0 & 0 & 0 & W_{41} & W_{42} & W_{43} \end{bmatrix} \begin{bmatrix} 0 \\ x_1 \\ x_2 \\ x_3 \\ x_4 \\ 0 \end{bmatrix} \quad \text{Locally-connected Layer}$$

$$\begin{bmatrix} h_1 \\ h_2 \\ h_3 \\ h_4 \end{bmatrix} = \begin{bmatrix} W_1 & W_2 & W_3 & 0 & 0 & 0 \\ 0 & W_1 & W_2 & W_3 & 0 & 0 \\ 0 & 0 & W_1 & W_2 & W_3 & 0 \\ 0 & 0 & 0 & W_1 & W_2 & W_3 \end{bmatrix} \begin{bmatrix} 0 \\ x_1 \\ x_2 \\ x_3 \\ x_4 \\ 0 \end{bmatrix}$$
 weight nya sama, karena juga kayak parameter x1 and the same of the sa

weight nya sama, karena juga kayak parameter x1 nya sama

2D Convolutional layer on PyTorch

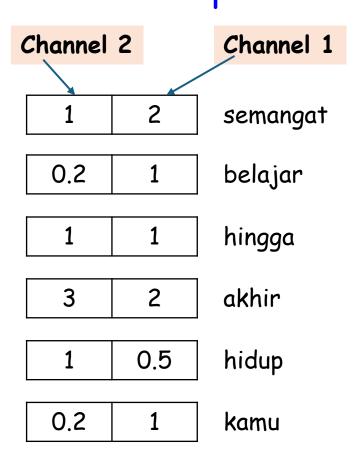
```
import torch
# random 20 images, each with 3 channels and
\# h = 50 pixels & w = 100 pixels
random images = torch.randn(20, 3, 50, 100)
                                     20 image, 3 channel, untuk setiap channgel adalah matrix 50 x 100
\# c = in channel = 3
                                     ada 20 citra urutannya (50 x 100)
\# c' = out channel = 6
                                kita set output nya 6
                                                        jadi ini paddingnya karena in channelnya 3, padding itu:
                                                         s = 2*k + 1 -> 2 = 2*k
\# kernel size = (3 \times 3)
# padding = 'same' meaning that the output must have
#the same shape as the input, 'valid' meaning no padding
conv layer = torch.nn.Conv2d(3, 6, (3, 3), padding = "same")
hidden = conv layer(random images)
                                                          The weight W is inside this
print(hidden.shape) #[20, 6, 50, 100]
```

function, and is initialized

randomly.

ada 20 citra, output citra sekarang 6 channel

1D Convolutional Layers for Sequences



word embeeding

- high level term: ada sebuah kata ("depok"), perlu diubah menjadi sebuah vector, contohnya [0.2, 0.7, 0.4). Nah untuk ubah depok menjadi vector itu ada fungsi f_w(str)

dimana fungsi itu disebut embeeding layer

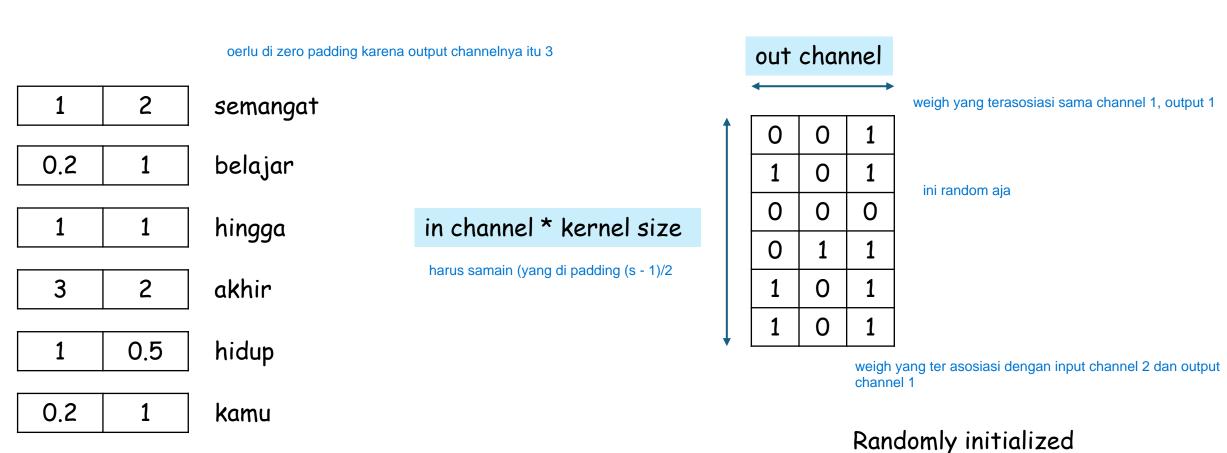
dimana basically embeeding layer itu akan menentukan "jauh" atau "dekatnya" sebuah term

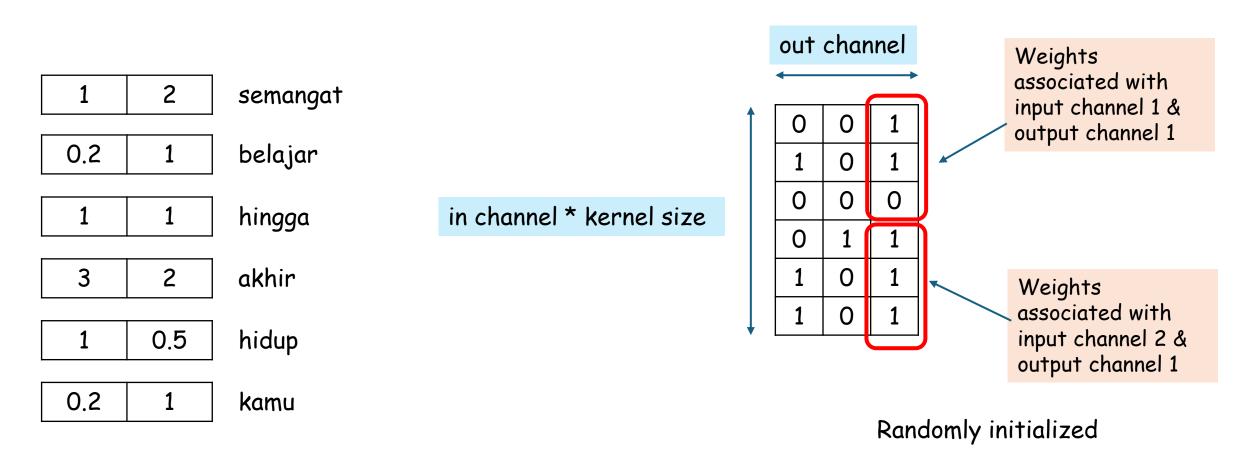
What is the size of our weight matrix W?

saya pergi ke depok ke jayapura



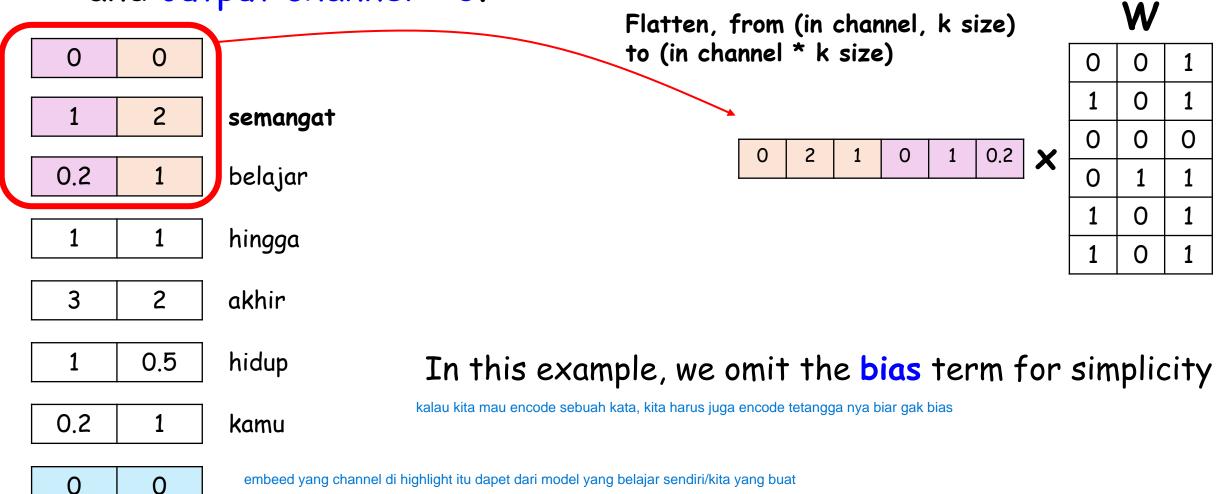
nah panjang dari word embeeding = channel

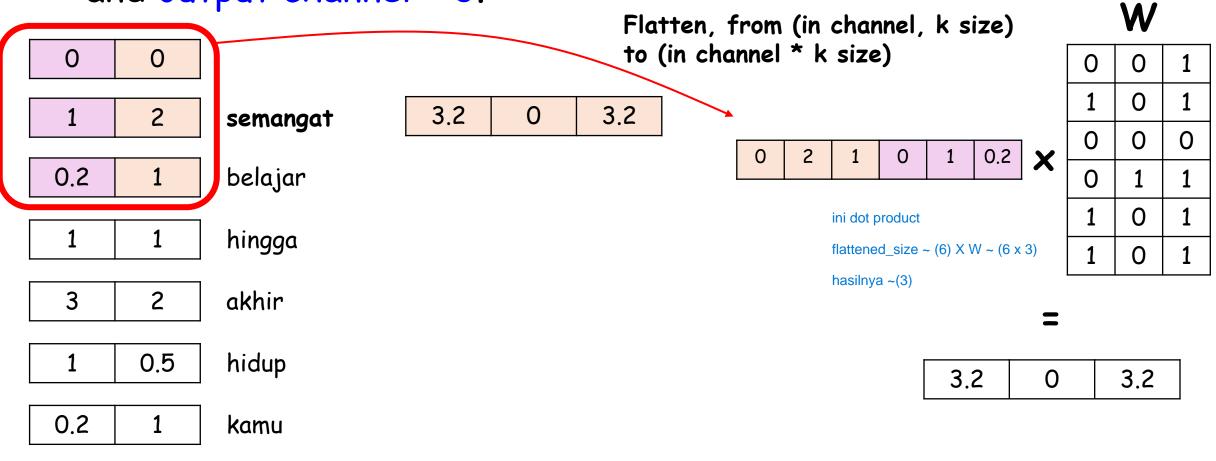


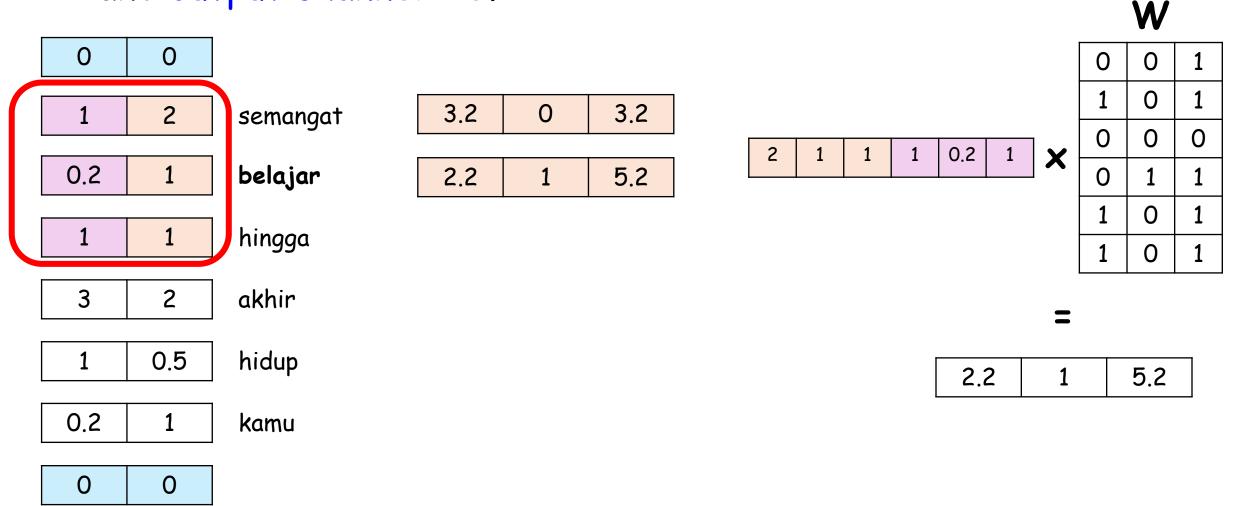


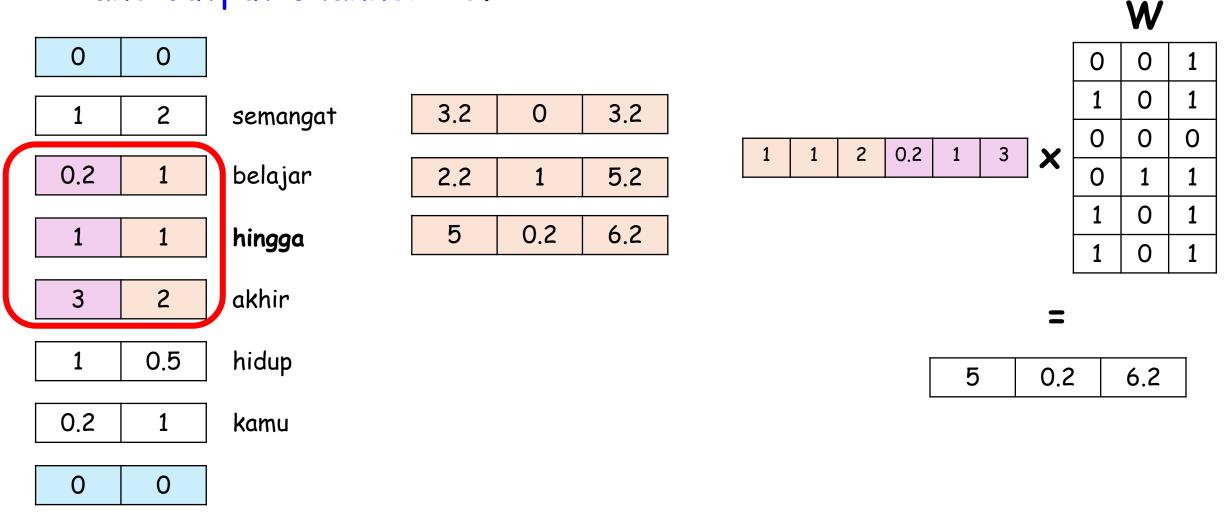
0	0	
1	2	semangat
0.2	1	belajar
1	1	hingga
3	2	akhir
1	0.5	hidup
	0.5	таар
0.2	1	kamu
0	0	

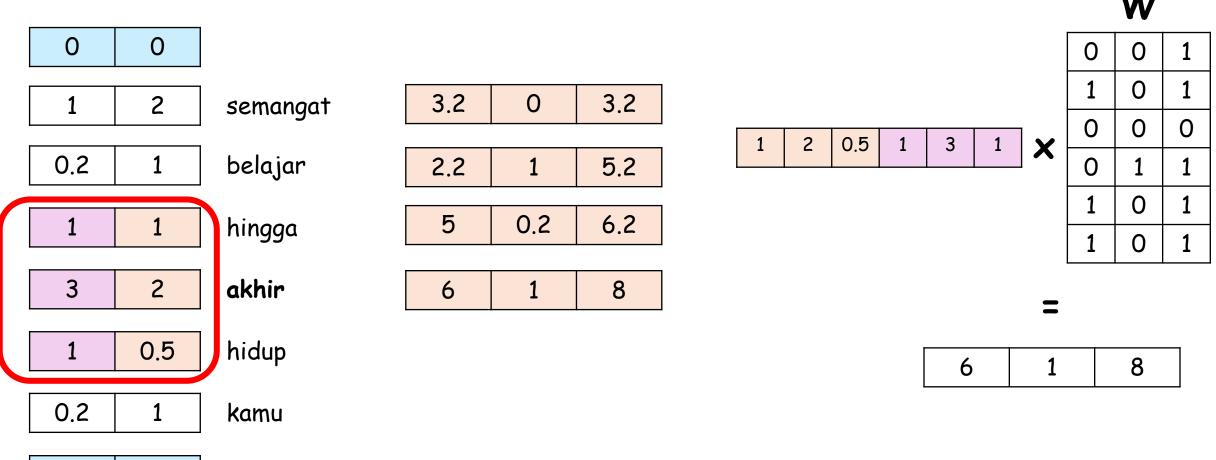
Suppose we use zero padding so that the length of output sequence is the same as that of input sequence.



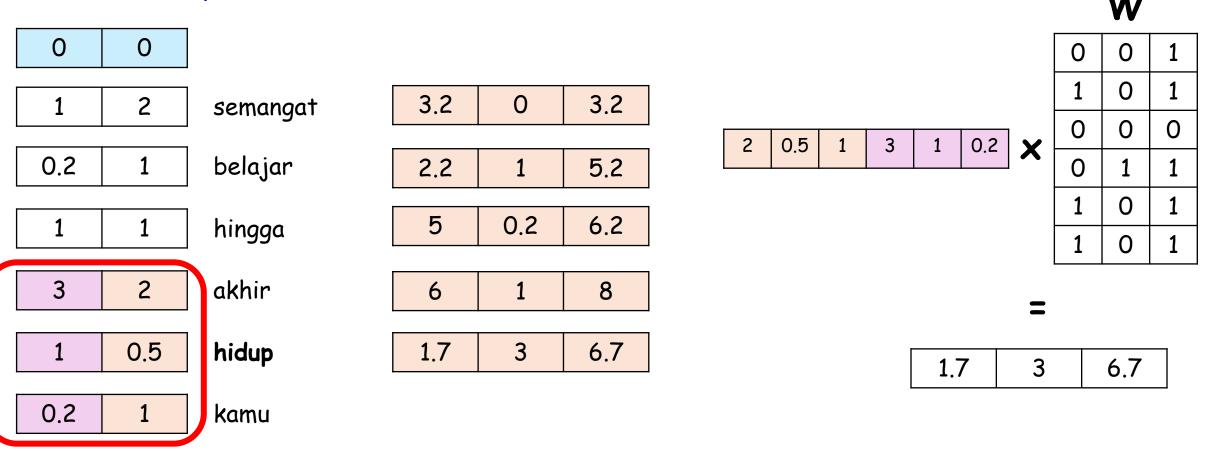




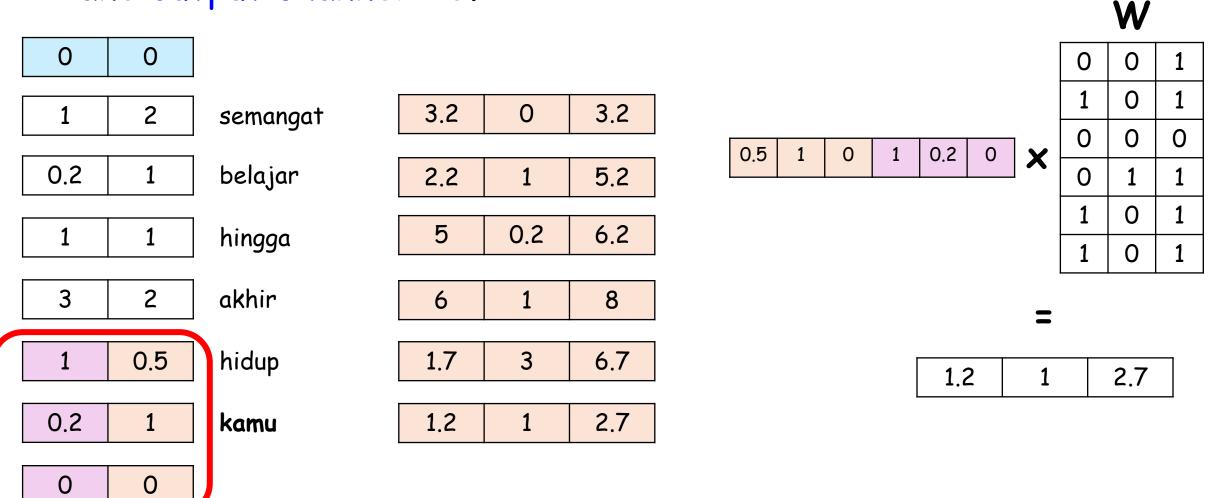


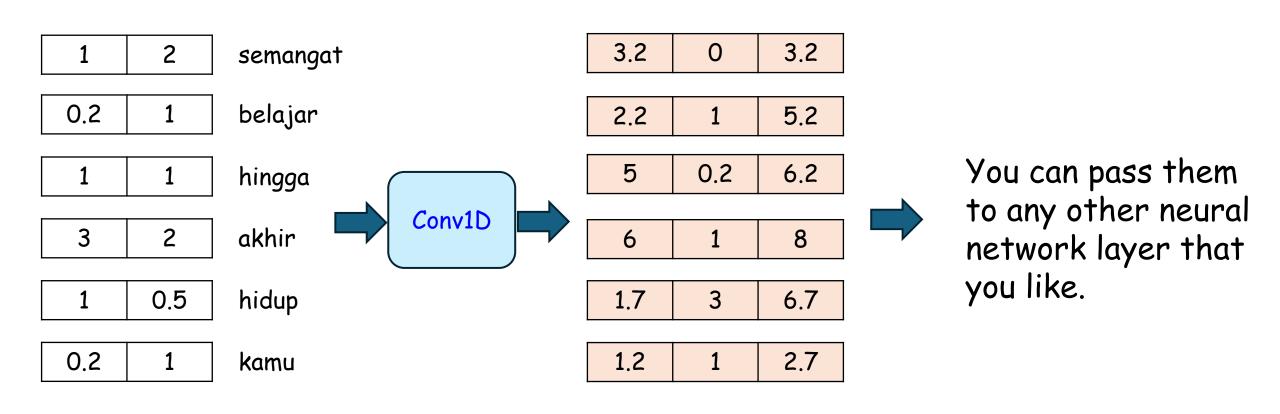


0



0





Here is the precise procedure ...

The output value of the layer with input size (batch size, in channel, sequence len) and output (batch size, out channel, sequence len) can be described as

The number of in channels

$$out(x_i, c_j^{out}) = bias(c_j^{out}) + \sum_{k=0}^{|c^{in}|-1} weight(c_j^{out}, k) \bigstar in(x_i, k)$$

 j^{th} value in the out channel of x_i

Cross-correlation operator

In signal processing, "Convolution" is different from "Cross-Correlation".

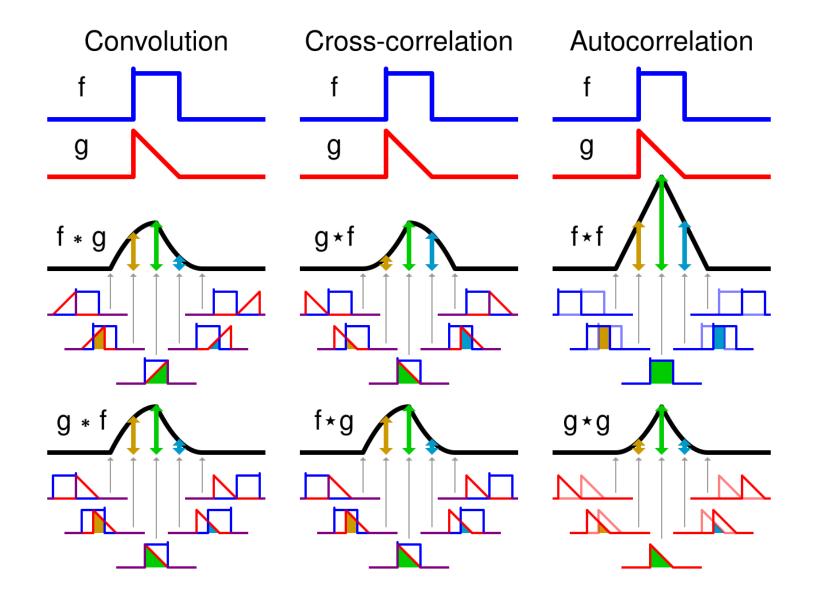
Yes, You're right!

"Convolutional NNs" are actually not really "Convolutional"! They are just doing "Cross-Correlation".

300 point!

Find the difference between "Convolution" and "Cross-Correlation" ->

https://www.kaggle.com/discussions/general/225375



https://en.wikipedia.org/wiki/Convolution

The codes, from the scratch (well, not really ...)

```
import torch
import torch.nn as nn
class Linear(nn.Module):
    def init (self, n inputs, n outputs):
        super(). init ()
        self.n inputs = n inputs
        self.n outputs = n outputs
        self.W = nn.Parameter(torch.Tensor(self.n inputs, self.n outputs))
        self.init weights()
    def init weights(self):
        for param in self.parameters():
            nn.init.uniform (param, -0.1, 0.1)
    def forward(self, x):
       return x @ self.W
```

For simplicity, we assume no bias

The codes, from the scratch (well, not really ...)

```
class Conv1D (nn.Module):
    def init (self, in channels, out channels, kernel width):
        """ kernel width harus ganjil """
        super(Conv1D, self). init ()
        self.in channels = in channels
        self.out channels = out channels
        self.kernel width = kernel width
        self.pad_size = (self.kernel_width - 1) // 2 _{k=(s-1)/2}^{pad size \rightarrow s = 2*k+1}
        self.kernel = Linear(kernel_width * in_channels, out_channels)
    def forward(self, x):
        # padding
        x = nn.functional.pad(x, (self.pad_size, self.pad_size), "constant", 0)
        1 = []
        for i in range(self.pad size, x.shape[2] - self.pad size):
            patch = x[:, :, i - self.pad_size: i + self.pad size + 1]
            patch = patch.reshape(x.shape[0], self.in_channels * self.kernel_width)
            1.append(self.kernel(patch))
        return torch.stack(1, dim=2)
```

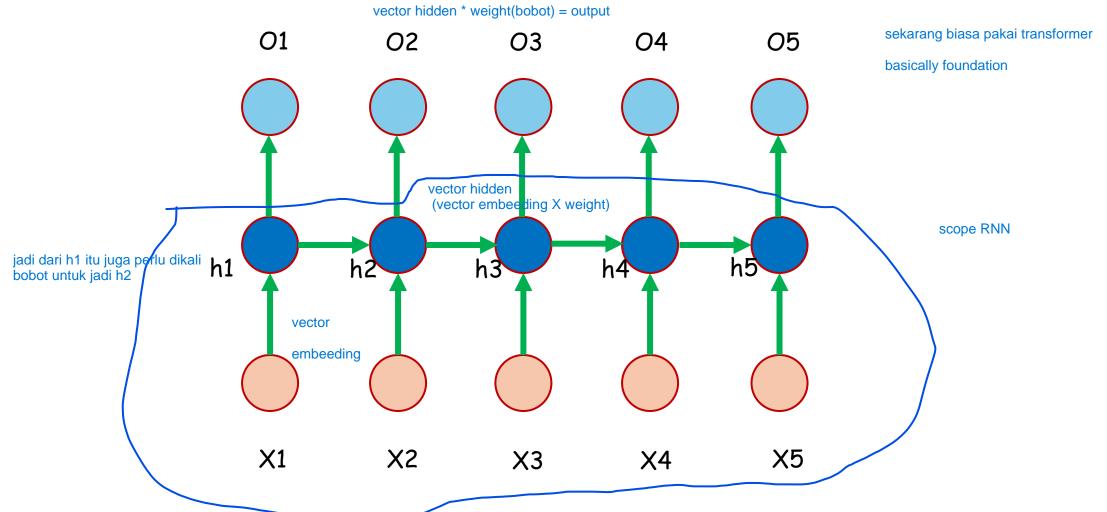
Wait, ... what is "torch.stack()"?

```
>>> x = torch.tensor([[1,2,3], [4,5,6]])
>>> torch.stack([x, x], dim=1)
tensor([[[1, 2, 3],
         [1, 2, 3]],
        [[4, 5, 6],
         [4, 5, 6]]])
>>> torch.stack([x, x], dim=2)
tensor([[[1, 1],
         [2, 2],
         [3, 3]],
        [[4, 4],
         [5, 5],
         [6, 6]]])
```

The codes, from the scratch (well, not really ...)

Recurrent Neural Networks

Recurrent Neural Networks



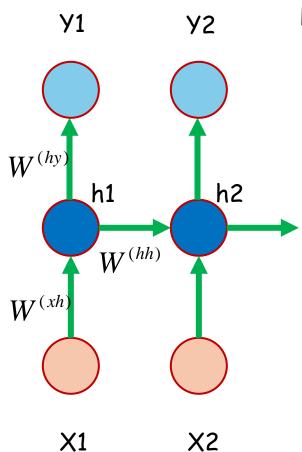
One of the famous Deep Learning Architectures in the NLP community

10/23/2024 IR Lab., CS - UI 39

dibidang NLP informasi masa lampu itu penting untuk konsiderasi sekarang

Makanya bobotnya hidden layer perlu diganti

Misal, ada I input unit, K output unit, dan H hidden unit (state).



Komputasi RNNs untuk satu sample:

$$h_t \in R^{1 \times H}$$
 $x_t \in R^{1 \times I}$ $y_t \in R^{1 \times K}$

$$W^{xh} \in R^{I \times H}$$

hidden layer itu contextual word embeeding karena word embeeding itu sudah mengakomodasi konteks. Karena saya bisa dan ular mempunyai bisa.

Meaningnya beda

$$W^{hh} \in R^{H \times H}$$
$$W^{hy} \in R^{H \times K}$$

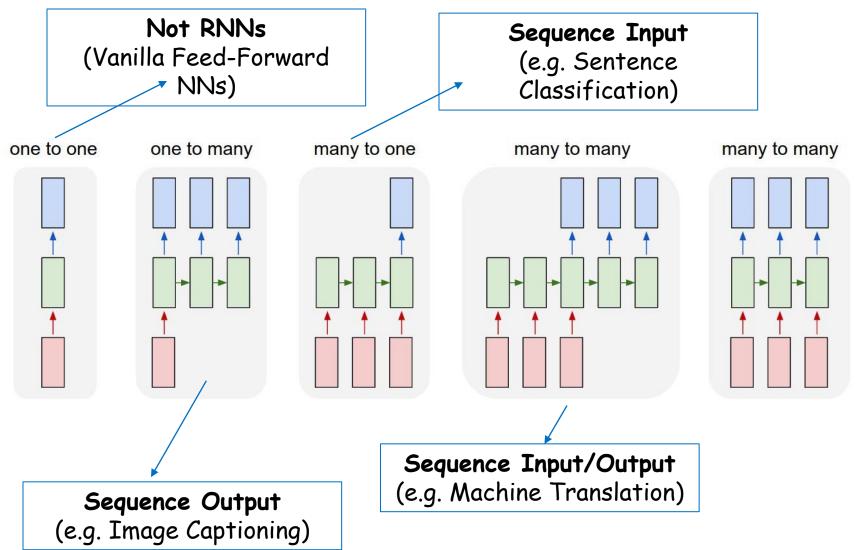
h_t adalah contextual word embedding dari kata X_t yang mengandung informasi kata-kata sebelumnya.

tanh biar gak linear nilainya (karena neural network gak mau linear

$$h_t = \tanh(x_t W^{xh} + h_{t-1} W^{hh})$$

$$h_0 = 0$$

$$y_t = activation(h_t W^{hy})$$



sequnce labeling

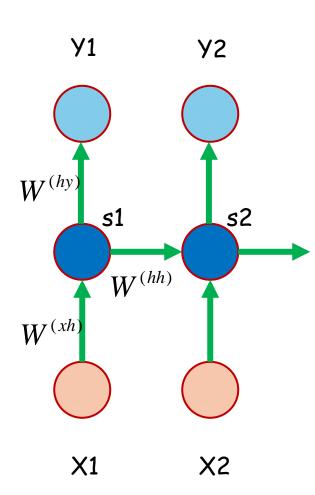
(nentuin kelas kata dari kalimat)

RNNs as Causal Language Models

ini GPT sekarang causal language model

LLM adalah model yang memberikan nilai probabilitas ke sebuah bahasa (kalimat yang dimasukkan

Vektor representasi hidden pada timestep t, yang berukuran d x 1 (vektor kolom)



$$P(x_1,\ldots,x_T) = \prod_{t=1}^{T} P(x_t|x_{t-1},\ldots,x_1)$$

$$\text{Artinya P(W+1) * P(W2 \mid W1) * P(W3 \mid W1W2) * P(W4 \mid W1W2W3) \ldots + 1}$$

$$P(\boldsymbol{x}_t | \boldsymbol{x}_{t-1}, \dots, \boldsymbol{x}_1) = \begin{bmatrix} P(\boldsymbol{x}_t = \boldsymbol{w}_1) \\ P(\boldsymbol{x}_t = \boldsymbol{w}_2) \\ \dots \\ P(\boldsymbol{x}_t = \boldsymbol{w}_{|V|}) \end{bmatrix} = Softmax\{W^{(hy)}, \boldsymbol{s}_t\}$$
 aya pergi ke depok orgi saya ke depok orgi saya ke depok

S1: Saya pergi ke depok S2: pergi saya ke depok

P (s1 | M -> model) = 0.7P(s2 | M) = 0.01

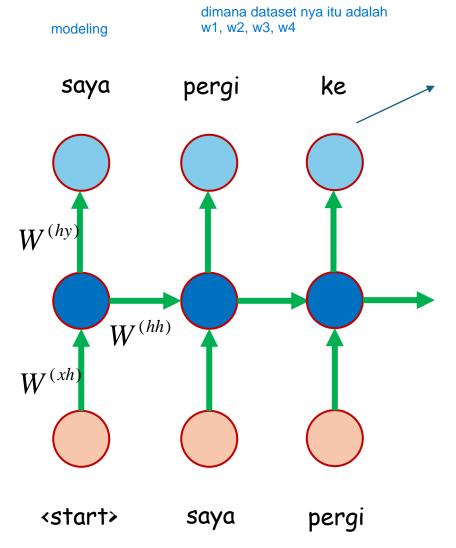
$$= softmax\{W_{s}^{(hy)}, s_{t}\}$$

Matriks berukuran |V| x d

$$V = \{w_1, w_2, \dots w_{|V|}\}$$

Vektor berukuran $|V| \times 1$, dimana setiap baris merupakan nilai probabilitas sebuah kata w. muncul pada posisi t.

RNNs as Causal Language Models





Vektor pada output adalah vektor kolom yang berukuran sebesar ukuran vocabulary.

artinya kalau <Start> dia harus bisa prediksi saya, terus kalau <saya> dia bisa prediksi pergi, dst.

Matriks parameter pada RNNs dapat dilatih secara unsupervised, dengan membuat output RNNs berupa kalimat yang digeser 1 ke kiri dari kalimat input.

Categorical Cross Entropy dapat digunakan sebagai loss function pada output di setiap timestep.

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```
import torch
import pandas as pd
import numpy as np

from collections import Counter
from torch import nn, optim
from torch.utils.data import DataLoader
```

```
class RNN (nn.Module):
    def init (self, n inputs, n hiddens, cell):
         super(). init ()
         self.n inputs = n inputs
         self.n hiddens = n hiddens
         self.cell = cell(n inputs, n hiddens)
                                                                           kelemahan RNN: dia harus nunggu hasil
                                                                           sebelumnya
                                                                          Kalau transformers bisa paralel
    def forward(self, inputs, prev hidden state):
         """ inputs: [batch size, sequence length, embedding size] """
         outputs = []
                                                                embeeding_size = channel Size (kalau di CNN)
         hidden state = prev hidden state
                                                                nah biasa dia input dibalik kalau CNN
         n steps = inputs.shape[1]
                                                                [batch_size, embeeding_size, sequence_length\
         for i in range(n_steps):
              hidden state = self.cell(inputs[:, i], hidden state)
              outputs.append(hidden state)
         return torch.stack(outputs, dim=1), hidden state
```

```
class Dataset(torch.utils.data.Dataset):
    def init (
         self,
         sequence length,
         documents, # list of strings
    ):
                                                                  nah kan awal-awal ada kayak
         self.sequence length = sequence length
                                                                  self.words = w1 w2 w3 w3 w4 w5 w6 .... w100
                                                                  self.word indexes itu intinya index dari itu
         self.words = self.load words()
                                                                  contoh: {
         self.uniq words = self.get uniq words()
                                                                    "w1": 1,
         self.index to word = {index: word for index, word in enumerate(self.uniq words)}
         self.word to index = {word: index for index, word in enumerate(self.uniq words)}
         self.words indexes = [self.word to index[w] for w in self.words]
    def load words(self):
                                           semua kata-katanya di concat dulu.
         text = ""
         for doc in documents:
           text += doc + " "
         return text.split(' ')
```

```
def get uniq words(self):
    word counts = Counter(self.words)
    return sorted(word counts, key=word counts.get, reverse=True)
def len (self):
    return len(self.words indexes) - self.sequence length
def getitem (self, index):
    return (
         torch.tensor(self.words indexes[index:index+self.sequence length]),
         torch.tensor(self.words indexes[index+1:index+self.sequence length+1]),
                             nah dia itu kan harus berdasarkan sequence_length gitu (panjang dari STEP RNN untuk mendapatkan hasil). Beda ya btw
                             sequence length sama
```

```
1 data point itu ([w1, w2, w3, w4], [w2 w3 w4 w5])
dimana yang torch.tensor(.... [ index:index+ self.sequence_length ]) -> itu dia input
kalau [index + 1 : index + self.sequence_length + 1] itu output
```

```
class Model(nn.Module):
   def init (self, dataset):
        super(Model, self). init ()
        self.rnn size = 16
        self.embedding dim = 16
        self.n vocab = len(dataset.uniq words)
        self.embedding = nn.Embedding(
            num embeddings=self.n vocab,
            embedding dim=self.embedding dim
        self.rnn = RNN(
            n inputs=self.embedding dim,
            n hiddens=self.rnn size,
            cell=RNNCell
        self.fc = Linear(self.rnn size, self.n vocab)
```

```
V = {saya, pergi, ke}
karena RNN mau itu vector
tapi karena encodingnya embeeding kita adalah
saya = 1
pergi = 2
                                                  jadi di
                                                  embeeding layer,
makanya
                                                  setiap kata-kata
                                                  tersebut
                                                  diembeed
                                                  menjadi sebuah
                                                  matrix. Disini
                                                  contohnya
                                                  embeeding
    RNN
                                                  sizenya itu 16
                                                  (lihat deh di
                                                  kode) terus
                                                  untuk parameter
                                                  ada
                                                  16 x 4
                         vektor
                                                  4 = ada 4 kata di
                                                  vocab.
                             isinya adalah hasil encoding dari term
    embeeding layer
```

embeeding layer yang dimensinya

ID (1, 2) jadiin one hot eoncoding, terus dikali oleh matriks dengan:

w = vector dimensi embeeding h = panjangnya Vector input

hasilnya [h, w]

[1,2]

Tutorial Link:

```
def train(dataset, model, batch size, max epochs=400):
   model.train()
    dataloader = DataLoader(dataset, batch size=batch size)
    criterion = nn.CrossEntropyLoss()
    optimizer = optim.Adam(model.parameters(), lr=0.001)
    for epoch in range(max epochs):
        h state = model.init state(batch size) #hidden state awal, NOL
        for batch, (x, y) in enumerate(dataloader):
            y pred, h state = model(x, h state)
            loss = criterion(y_pred.transpose(1, 2), y)
            loss.backward()
            optimizer.step()
            #h state detached from current graph; tapi isi tetap sama agar berlanjut (sta
            #graph batch sekarang jangan nyambung dengan batch berikutnya; tetapi nilai
            #h state harus berlanjut dari satu batch ke batch berikutnya. Caranya adalah
            #dengan detach() ini.
            h state = h state.detach()
            optimizer.zero grad()
```

```
def predict(dataset, model, text, next words=20):
                                                                         misal dari {saya, pergi}
     model.eval()
                                                                         jadi
     words = text.split(' ')
                                                                         nanti dapet "ke" sebagai kata selanjutnya
     h state = model.init state(len(words))
                                                                         terus yang berikutnya dia bakal ambil input RNN
                                                                         {pergi, ke}
     for i in range(0, next words):
                                                                         terus dapet depok
          x = torch.tensor([[dataset.word to index[w] for w in words[i:]]])
          y pred, h state = model(x, h state)
   tapi init_hidden_statenya untuk kata yang pertama 0, cuman lalu selalu di update
                                                       sebelum masuk ke softmax itu namanya logits (hasil dari CCE). Nah jadi yang digunakan untuk
                                                       memprediksi itu, pakai yang terakhir aja (logits terakhir). Terus logits itu masuk ke softmax.
          last word logits = y pred[0][-1]
          p = torch.nn.functional.softmax(last_word_logits, dim=0).detach().numpy()
          # random choice
          #word index = np.random.choice(len(last word logits), p=p)
          # the best one
          word index = np.argmax(p)
          words.append(dataset.index to word[word index])
     return words
```

```
documents = ["saya pergi ke depok",
             "di depok makan sayuran",
             "dan buah nangka yang segar",
             "angin bertiup kencang",
             "tanda hujan akan turun di jalan margonda"]
# make a dataset
dataset = Dataset(2, documents)
# the model
model = Model(dataset)
# train
train(dataset, model, 2)
# try prompt the model with "saya pergi"
print(predict(dataset, model, "saya pergi", next words=20))
```

Back Propagation Through Time (BPTT)

Misal, untuk parameter antar state:

$$\frac{\partial L_t}{\partial W^{(hh)}} = \sum_{k=1}^t \frac{\partial L_t}{\partial h_t} \cdot \frac{\partial h_t}{\partial h_k} \cdot \frac{\partial^+ h_k}{\partial W^{(hh)}}$$

Term-term ini disebut

temporal contribution:
bagaimana W^(hh) pada step k
mempengaruhi cost pada stepstep setelahnya († > k)

Diputus sampai k step ke belakang. Di sini artinya "immediate derivative", yaitu h_{k-1} dianggap konstan terhadap $W^{(hh)}$.

$$\frac{\partial h_{t}}{\partial h_{k}} = \frac{\partial h_{t}}{\partial h_{t-1}} \cdot \frac{\partial h_{t-1}}{\partial h_{t-2}} \cdots \frac{\partial h_{k+2}}{\partial h_{k+1}} \cdot \frac{\partial h_{k+1}}{\partial h_{k}}$$

$$\frac{\partial^{+} h_{k}}{\partial W^{(hh)}} = \frac{\partial^{+} \left(W^{(xh)} \cdot x_{t} + W^{(hh)} \cdot s_{t-1} \right)}{\partial W^{(hh)}} = s_{t-1}$$

Vanishing & Exploding Gradient Problems

kalau vanish, informasi dari gradient yang pertama, akan hilang (jadi tidak ada efek pada timestamp selanjutnya)

Bengio et al., (1994) said that "the **exploding gradients problem** refers to the large increase in the norm of the gradient during training. Such events are caused by the explosion of the long term components, which can grow exponentially more then short term ones."

And "The vanishing gradients problem refers to the opposite behaviour, when long term components go exponentially fast to norm 0, making it impossible for the model to learn correlation between temporally distant events."

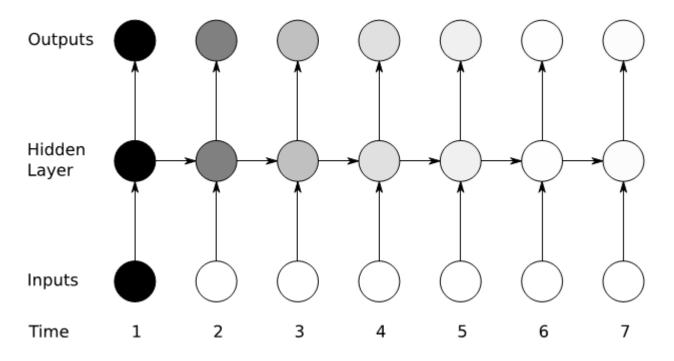
karena nanti dia akan shrink to 0

Kok bisa terjadi? Coba lihat salah satu temporal component dari sebelumnya:

$$\frac{\partial h_{t}}{\partial h_{k}} = \frac{\partial h_{t}}{\partial h_{t-1}} \cdot \frac{\partial h_{t-1}}{\partial h_{t-2}} \cdots \frac{\partial h_{k+2}}{\partial h_{k+1}} \cdot \frac{\partial h_{k+1}}{\partial h_{k}}$$

In the same way a product of $\mathbf{t} - \mathbf{k}$ real numbers can shrink to zero or explode to infinity, so does this product of Matrices. (Pascanu et al.,)

Vanishing & Exploding Gradient Problems



Sequential Jacobian biasa digunakan untuk analisis penggunaan konteks pada RNNs.

> gambar disini, melihatkan bahwa Sensistivitas sendiri decay kalau semakin banyak melewati hidden layer.

Figure 4.1: The vanishing gradient problem for RNNs. The shading of the nodes in the unfolded network indicates their sensitivity to the inputs at time one (the darker the shade, the greater the sensitivity). The sensitivity decays over time as new inputs overwrite the activations of the hidden layer, and the network 'forgets' the first inputs.

Solusi untuk Vanishing Gradient Problem

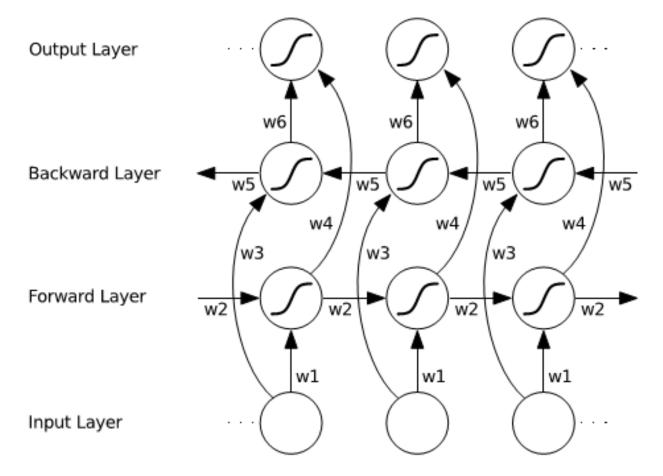
- 1) Penggunaan non-gradient based training algorithms (Simulated Annealing, Discrete Error Propagation, etc.) (Bengio et al., 1994)
- engga pakai gradien

- 2) Definisikan arsitektur baru di dalam RNN Cell!, seperti Long-Short Term Memory (LSTM) (Hochreiter & Schmidhuber, 1997).
 - 3) Untuk metode yang lain, silakan merujuk (Pascanu et al., 2013).

Pascanu et al., On the difficulty of training Recurrent Neural Networks, 2013

S. Hochreiter and J. Schmidhuber. Long Short-Term Memory. Neural Computation, 9(8):1735 1780, 1997

Variant: Bi-Directional RNNs

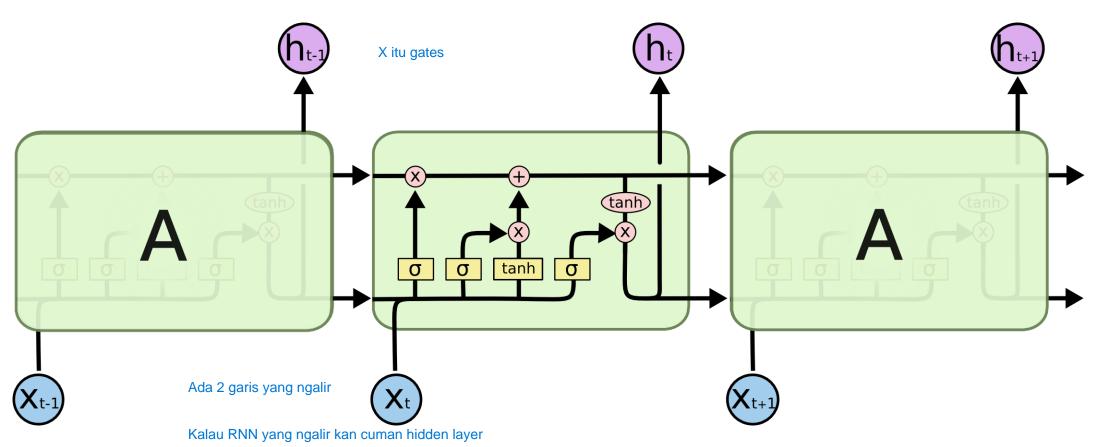


Long Short Term Memory Networks

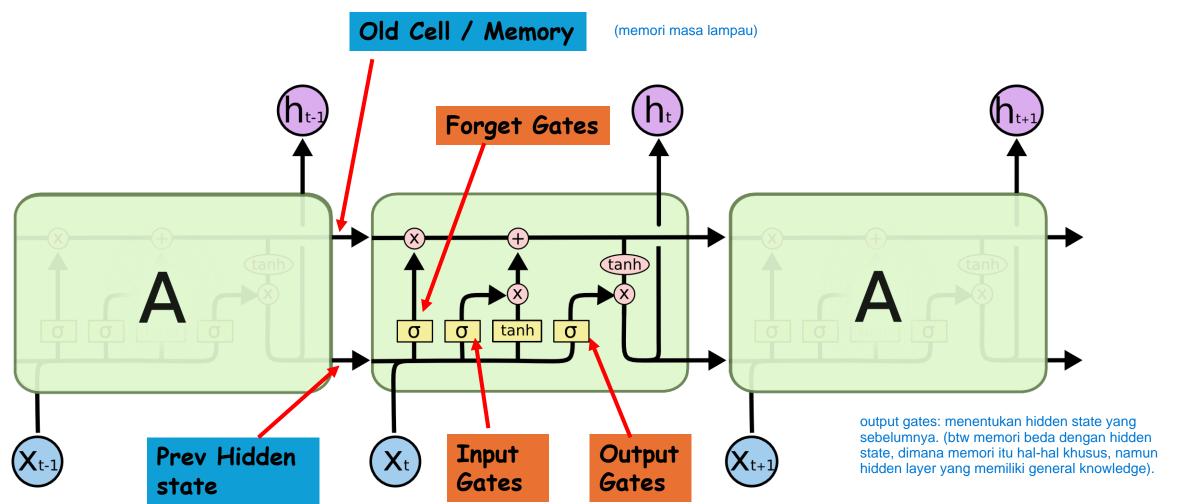
prinsipjnya kayak gates, dimana kalau ini itu 0 - 1. Nah ini itu artinya kalau 1, semuah memori lama diinget, selain itu kalau 0, memori yang lampau dilupakan

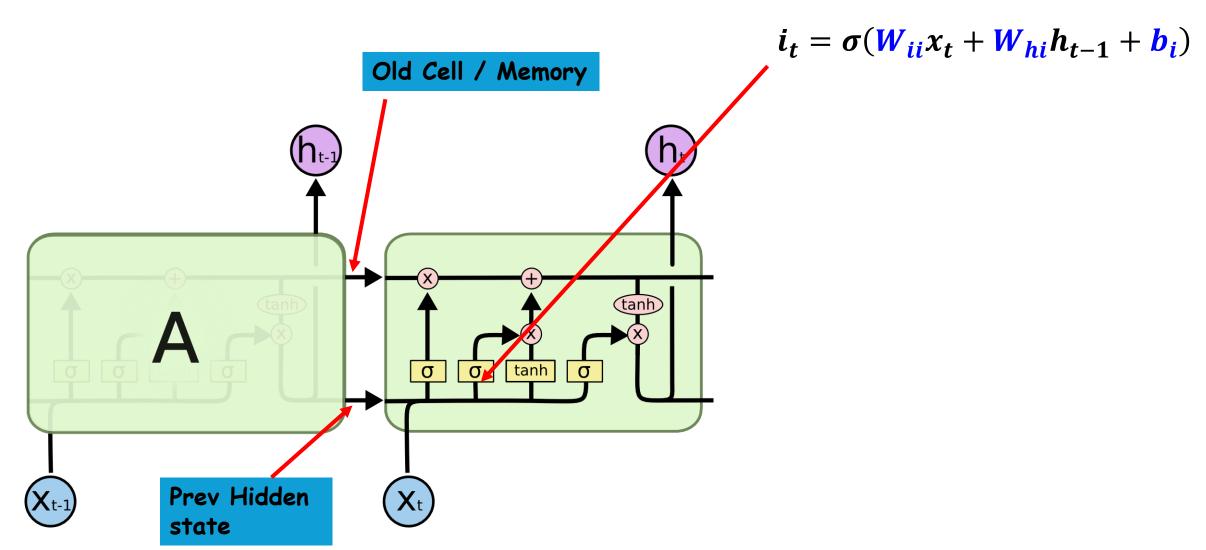
- 1. The LSTM architecture consists of a set of recurrently connected subnets, known as memory blocks.
- 2. These blocks can be thought of as a differentiable version of the memory chips in a digital computer.
- 3. Each block contains:
 - 1. Self-connected memory cells
 - 2. Three multiplicative units (gates)
 - 1. Input gates (analogue of write operation)
 - 2. Output gates (analogue of read operation)
 - 3. Forget gates ((analogue of reset operation))

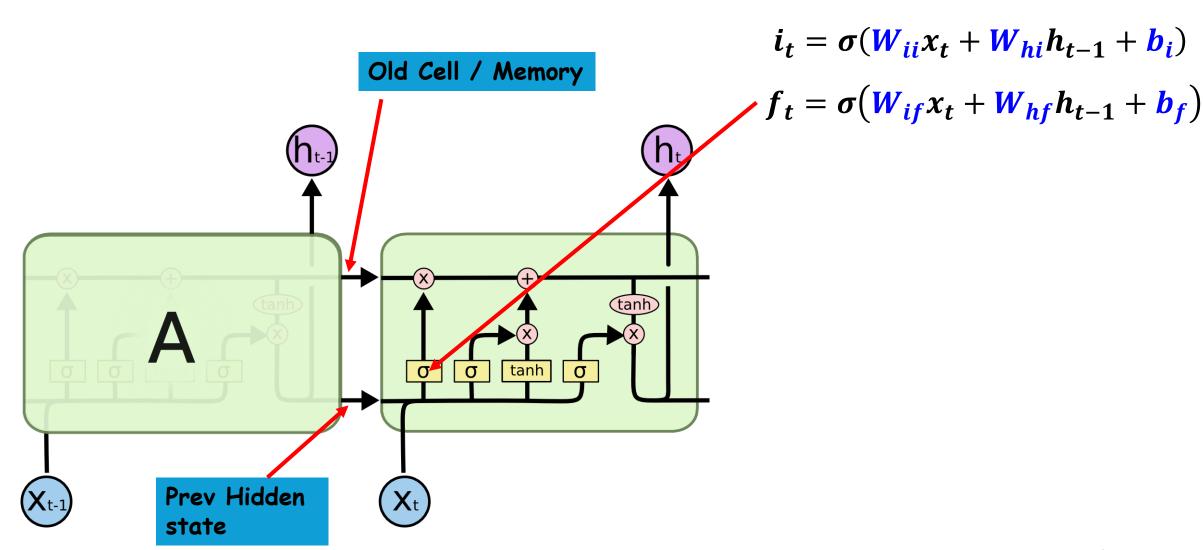
Pelajari: https://colah.github.io/posts/2015-08-Understanding-LSTMs/

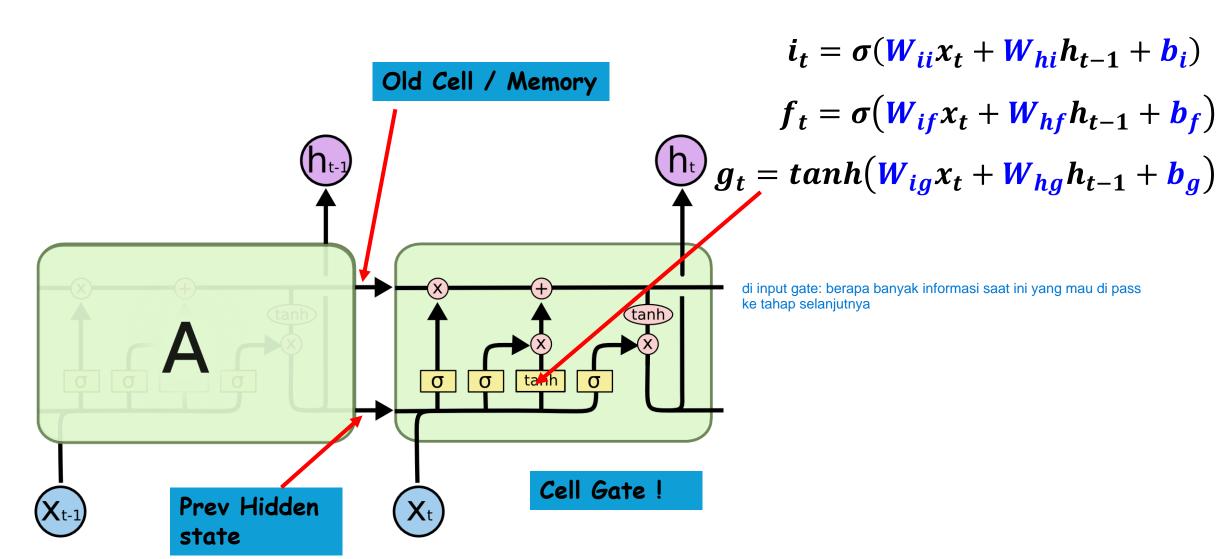


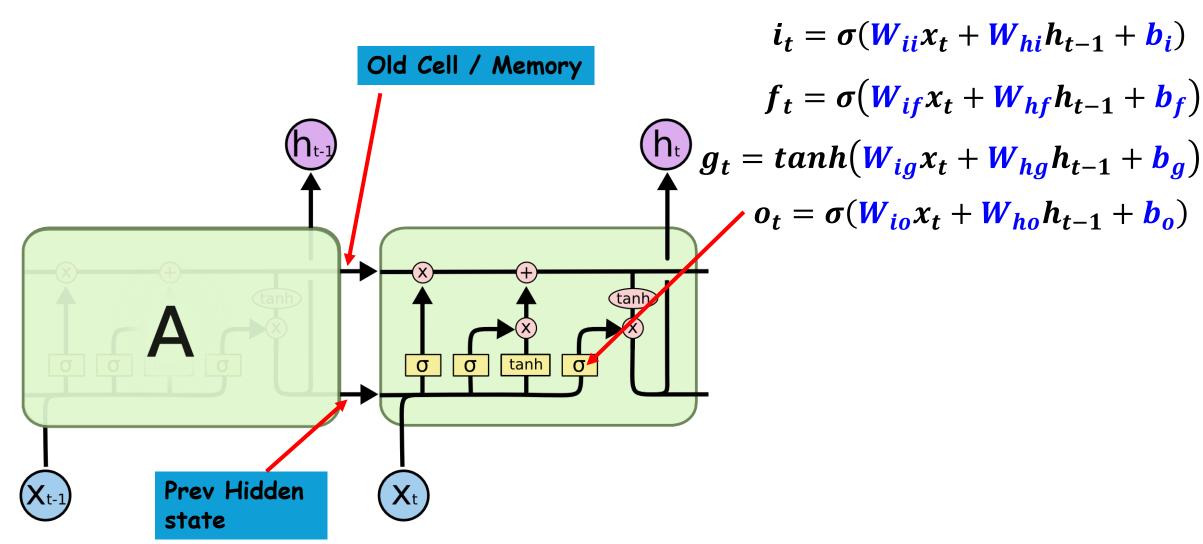
Kalau mau nginget memori masa lampau, akan bergantung dengan kondisi kita saat ini.

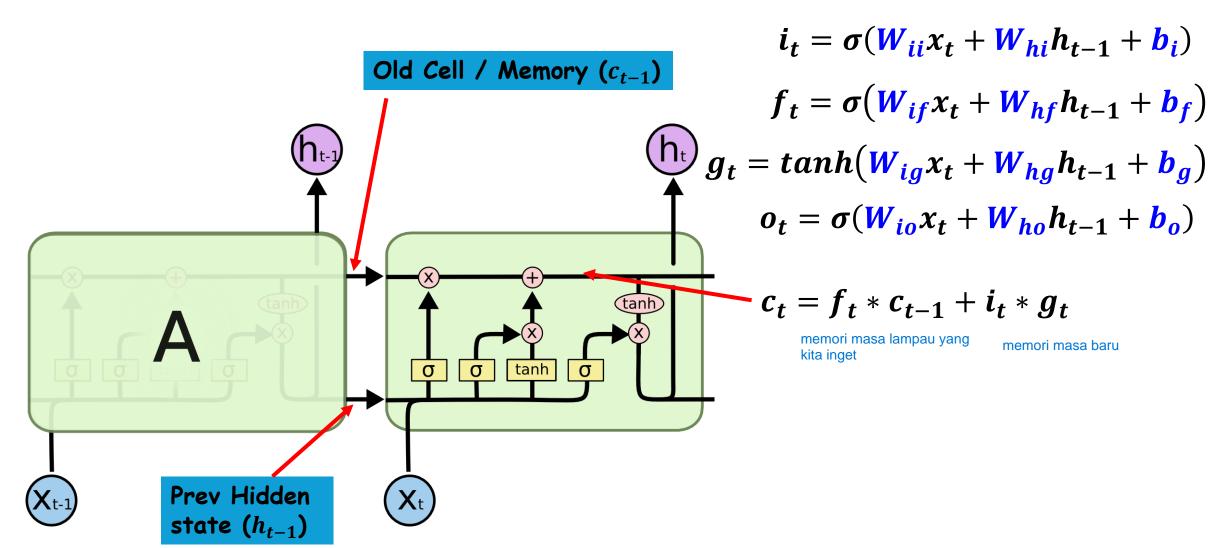


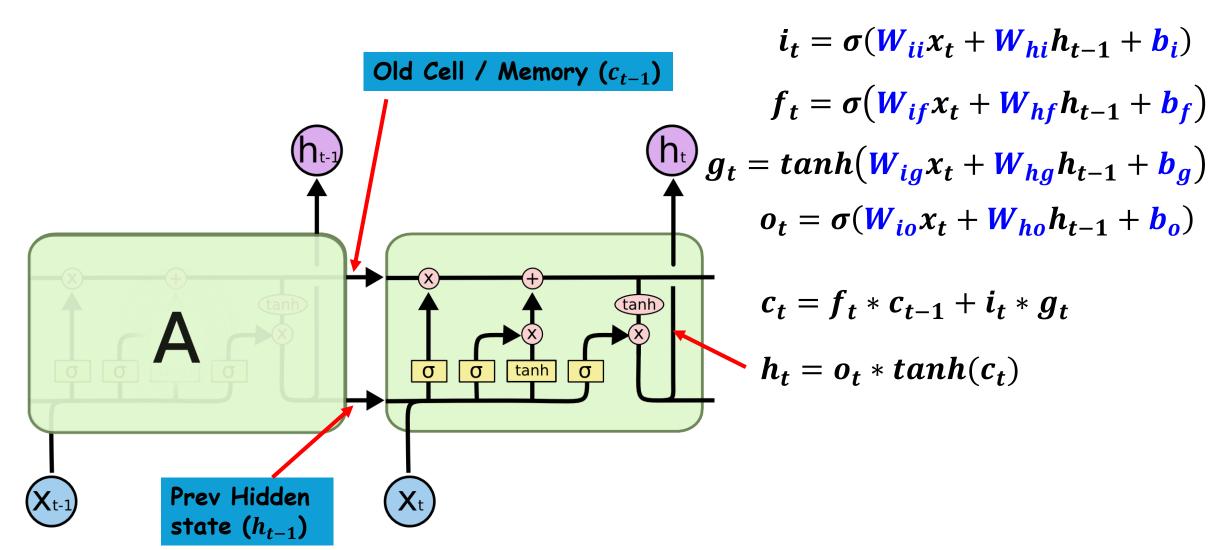












```
class LSTMCell(nn.Module):
    def init (self, input size, hidden size):
        super(LSTMCell, self).__init__()
        self.hidden size = hidden size
        self.input size = input size
        # Input gate components
        self.W ii = nn.Parameter(torch.Tensor(hidden size, input size))
        self.W hi = nn.Parameter(torch.Tensor(hidden size, hidden size))
        self.b i = nn.Parameter(torch.Tensor(hidden size))
        # Forget gate components
        self.W if = nn.Parameter(torch.Tensor(hidden size, input size))
        self.W hf = nn.Parameter(torch.Tensor(hidden size, hidden size))
        self.b f = nn.Parameter(torch.Tensor(hidden size))
        # Cell gate components
        self.W ig = nn.Parameter(torch.Tensor(hidden size, input size))
        self.W hg = nn.Parameter(torch.Tensor(hidden size, hidden size))
        self.b g = nn.Parameter(torch.Tensor(hidden size))
```

```
... Continued
       # Output gate components
       self.W io = nn.Parameter(torch.Tensor(hidden size, input size))
       self.W ho = nn.Parameter(torch.Tensor(hidden size, hidden size))
       self.b o = nn.Parameter(torch.Tensor(hidden size))
       self.init weights()
   def init weights(self):
       for param in self.parameters():
           nn.init.uniform (param, -0.1, 0.1)
   def forward(self, x, hidden):
       h prev, c prev = hidden
       i t = torch.sigmoid(x @ self.W ii.T + h prev @ self.W hi.T + self.b i)
       f_t = torch.sigmoid(x @ self.W_if.T + h_prev @ self.W_hf.T + self.b_f)
       g_t = torch.tanh(x @ self.W_ig.T + h_prev @ self.W_hg.T + self.b_g)
       o t = torch.sigmoid(x @ self.W io.T + h prev @ self.W ho.T + self.b o)
       ct = ft * cprev + it * gt
       h t = o t * torch.tanh(c t)
       return (h t, c t)
```

```
class LSTM(nn.Module):
    def init (self, input size, hidden size):
        super(LSTM, self).__init__()
        self.hidden size = hidden size
        self.cell = LSTMCell(input size, hidden size)
   def forward(self, x, prev state):
        batch_size, seq_len, _ = x.size()
        h, c = prev state
        outputs = []
        for t in range(seq len):
            x t = x[:, t, :]
            (h, c) = self.cell(x t, (h, c))
            outputs.append(h)
        return torch.stack(outputs, dim=1), (h, c)
```

Tutorial Link (LSTMs for causal language modeling):

https://colab.research.google.com/drive/1aY4R_zq-Bw0HcW9L1q6WN0JYIxwsA-bN?usp=sharing

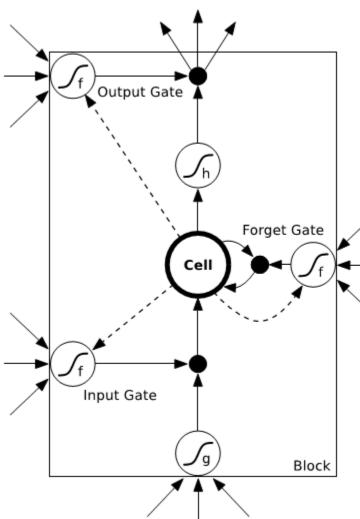
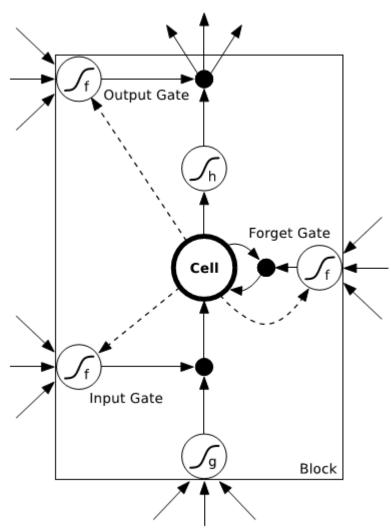


Figure 4.2: **LSTM memory block with one cell.** The three gates are nonlinear summation units that collect activations from inside and outside the block, and control the activation of the cell via multiplications (small black circles). The input and output gates multiply the input and output of the cell while the forget gate multiplies the cell's previous state. No activation function is applied within the cell. The gate activation function 'f' is usually the logistic sigmoid, so that the gate activations are between 0 (gate closed) and 1 (gate open). The cell input and output activation functions ('g' and 'h') are usually tanh or logistic sigmoid, though in some cases 'h' is the identity function. The weighted 'peephole' connections from the cell to the gates are shown with dashed lines. All other connections within the block are unweighted (or equivalently, have a fixed weight of 1.0). The only outputs from the block to the rest of the network emanate from the output gate multiplication.

Alex Graves, Supervised Sequence Labelling with Recurrent Neural Networks S. Hochreiter and J. Schmidhuber. Long Short-Term Memory. Neural Computation, 9(8):1735 1780, 1997



The multiplicative gates allow LSTM memory cells to store and access information over long periods of time, thereby mitigating the vanishing gradient problem.

For example, as long as the input gate remains closed (i.e. has an activation near 0), the activation of the cell will not be overwritten by the new inputs arriving in the network, and can therefore be made available to the net much later in the sequence, by opening the output gate.

Alex Graves, Supervised Sequence Labelling with Recurrent Neural Networks
23 October 2024 Hochreiter and J. Schmidhuber. Long Short-Term Memory. Neural
Computation, 9(8):1735 1780, 1997

Preservation of Gradient Information pada LSTM

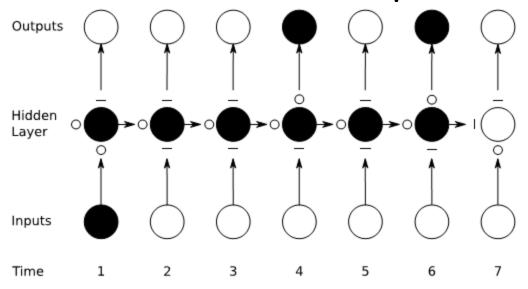
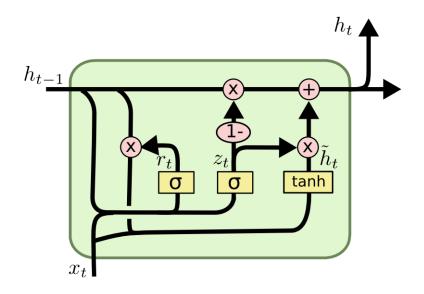


Figure 4.4: **Preservation of gradient information by LSTM.** As in Figure 4.1 the shading of the nodes indicates their sensitivity to the inputs at time one; in this case the black nodes are maximally sensitive and the white nodes are entirely insensitive. The state of the input, forget, and output gates are displayed below, to the left and above the hidden layer respectively. For simplicity, all gates are either entirely open ('O') or closed ('—'). The memory cell 'remembers' the first input as long as the forget gate is open and the input gate is closed. The sensitivity of the output layer can be switched on and off by the output gate without affecting the cell.

Alex Graves, Supervised Sequence Labelling with Recurrent Neural Networks
23 October 2024 Hochreiter and J. Schmidhuber. Long Short-Term Memory. Neural
Computation, 9(8):1735 1780, 1997

Another Variant: Gated Recurrent Units (GRUs)



https://colah.github.io/posts/2015-08-Understanding-LSTMs/

500 Point for those who implement GRUs from the scratch, like we did for LSTMs

23 October 2024 75