General Regulations.

- Please hand in your solutions in groups of two (preferably from the same tutorial group). Submissions by a single person alone will not be corrected.
- Your solutions to theoretical exercises can be either handwritten notes (scanned), or typeset using LATEX. For scanned handwritten notes please make sure that they are legible and not too blurry.
- For the practical exercises, the data and a skeleton for your jupyter notebook are available at https://github.com/sciai-lab/mlph_w24. Always provide the (commented) code as well as the output, and don't forget to explain/interpret the latter. Please hand in your notebook (.ipynb), as well as an exported pdf-version of it.
- Submit all your files in the Übungsgruppenverwaltung, only once for your group of two. Specify all names of your group in the submission.

1 The logistic sigmoid

- (a) Compute and simplify the derivative of the binary logistic sigmoid. (1 pt)
- (b) Show that the \tanh function $\tanh(x) = \frac{e^x e^{-x}}{e^x + e^{-x}}$, another function sometimes used as the activation function in neural networks, is simply a scaled and shifted version of the binary logistic sigmoid.
- (c) Consider binary classification: Given two points of class 1, one at (1,1) and one at (2,2) as well as two points of class 2, at (1,2) and (2,3), find a weight vector \mathbf{w} and bias b such that the activation

$$a = \sigma(\mathbf{w}^T \mathbf{x} + b) \tag{2 pts}$$

separates the two classes.

2 Logistic regression: an LLM lie detector

In this exercise, you will implement a lie detection system for Large Language Models (LLMs) using logistic regression (LR). Your lie detector is trained on a dataset of a few thousand hidden activation vectors from LLaMA-3-8B-Instruct.

The hidden activations (at layer 12 of the transformer model) have dimension 4096 and were generated by feeding true and false statements to the LLM, e.g., "The city of Berlin is in Germany" or "The city of Berlin is in France". For each statement, these 4096-dimensional vectors represent the model's internal state while processing the statement. Each activation vector is labeled as either true (1) or false (0).

Note: You will learn more about LLMs and LLM lie detection more towards the end of the lecture course. The experiments you consider in this exercise are directly based on the research of Lennart Bürger (MSc student in our group). If you are interested in the topic, please have a look at his NeurIPS 2024 paper (preprint at https://arxiv.org/abs/2407.12831).

- (a) Use the four provided datasets to train separate Logistic Regression classifiers. Train the Logistic Regression classifier (without regularization) on the training set. Evaluate the model's performance on the test set. Are the activation vectors of true and false statements linearly separable? You may use the Logistic Regression implementation from sklearn (https://scikit-learn.org/1.5/modules/generated/sklearn.linear_model.LogisticRegression.html).
 - Hint: The default implementation uses L2-regularization. You can also play with the tolerance used as stopping criterion. (3 pts)
- (b) Now we will investigate how well a LR classifier trained on one dataset generalizes to other datasets (out-of-distribution generalization). For this, train a LR classifier on the cities dataset (once with and once without regularization) and evaluate its performance on the other three datasets. The sp_en_trans dataset contains true and false Spanish to English translations, e.g., "The Spanish word 'uno' means 'one'." (True). The prefix "neg_" at the beginning of a dataset name indicates that the dataset contains only negated statements, which include the word "not", e.g., "The city of Bhopal is not in India." (False). What do you observe? Does the LR classifier generalize from one topic? Does it generalize from statements without negation to statements with negation? (3 pts)
- (c) Is it possible to train a lie detector that works well for both affirmative and negated statements? Train an LR classifier on the cities and the neg_cities dataset and evaluate its performance on the sp_en_trans and neg_sp_en_trans datasets. (2 pts)

3 Log-sum-exp and soft(arg)max

The log-sum-exp and soft(arg)max¹ functions are defined on vectors $\boldsymbol{\sigma} \in \mathbb{R}^k$ as

$$\operatorname{lse}(\boldsymbol{\sigma}; \lambda) = \frac{1}{\lambda} \log \left(\sum_{j=1}^{K} \exp(\lambda \sigma_j) \right) \quad \text{and} \quad \operatorname{soft}(\operatorname{arg}) \max(\boldsymbol{\sigma}; \lambda)_k = \frac{\exp(\lambda \sigma_k)}{\sum_{j=1}^{K} \exp(\lambda \sigma_j)},$$

with a scalar parameter $\lambda \in \mathbb{R}^+$ and k = 1, ..., K.

- (a) On which subset of the vectors $\sigma^1 = (1,2,3)^T$, $\sigma^2 = (11,12,13)^T$, $\sigma^3 = (10,20,30)^T$ does the soft(arg)max yield identical results? Show in general whether the soft(arg)max is invariant under (i) constant offset and (ii) rescaling of its input. (2 pts)
- (b) Make a 2D contour plot of $lse((\sigma_1, \sigma_2)^T; \lambda)$ for $\lambda \in \{1, 10, 100\}$ and both σ_1 and σ_2 in the range [-1, 1]. Compare this to a contour plot of $max(\sigma_1, \sigma_2)$ over the same range. (2 pts)
- (c) Plot the two components of the soft(arg)max, over the same range and the same choices for λ as in (c), but as images instead of contour plots. Compare this to corresponding plots of the two components of the arg max over the 2D vectors, represented as a 2D one-hot vectors instead of indices:

onehot(arg max
$$\sigma_i$$
) =
$$\begin{cases} (1,0)^T & \text{if } \sigma_1 > \sigma_2, \\ (0,1)^T & \text{else.} \end{cases}$$

(2 pts)

(1 pt)

- (d) Prove that the derivative of the lse is the soft(arg)max.
- (e) Bonus Prove that

$$\lim_{\lambda \to \infty} \operatorname{lse}(\boldsymbol{\sigma}; \lambda) = \max(\boldsymbol{\sigma}),$$

for all
$$\sigma \in \mathbb{R}^n$$
. (2 pts)

¹In the literature known as just "softmax".

4 Linear regions of MLPs

In this exercise, you will build and investigate two regression Multi Layer Perceptrons (MLPs) using the pytorch (https://pytorch.org/) deep learning library. The input is two dimensional and each hidden layer consists of a linear transformation (torch.nn.Linear) followed by a ReLU activation function (ReLU(x) = max(x,0), torch.nn.ReLU)). The final layer is a linear transformation without activation function and should produce one scalar output. Formally, for H hidden layers, we have

$$\mathbf{a}_0 = \mathbf{x}, \quad \mathbf{a}_{i+1} = \text{ReLU}(\mathbf{W}_i \mathbf{a}_i + \mathbf{b}_i) \quad \text{for} \quad i \in \{0, ..., H-1\}, \quad \mathbf{y} = \mathbf{W}_H \mathbf{a}_H + \mathbf{b}_H.$$
 (1)

Here, $\mathbf{x} \in \mathbb{R}^2$ is the input, $\mathbf{y} \in \mathbb{R}^1$ the output, \mathbf{a}_i are the activations and \mathbf{W}_i , \mathbf{b}_i the weight matrices and bias vectors of the linear layers (the parameters of the model).

- (a) Implement a shallow model with a single hidden layer with 20 neurons. For a tutorial on how to do this with pytorch, see for example https://pytorch.org/tutorials/recipes/recipes/defining_a_neural_network.html. How many parameters does the model have? (2 pts)
- (b) Pytorch automatically takes care of the random initialization of the model. Compute the output for a dense grid of at least 500 by 500 points in the range $\mathbf{x} \in [-10, 10] \times [-10, 10]$ and visualize it as an image. Repeat for a larger range; How far do you have to zoom out to capture all the structure?

(2 pts)

(c) Use numpy.gradient to (approximately) compute the spatial gradient of the network output (as an image, from part (b)) and visualize both of its components as images using 'prism' as the colormap. What do you observe?

(2 pts)

(d) Implement a deeper model with four hidden layers with 5 neurons each, and repeat part (b) and (c). Interpret your results and compare to the shallow model. (2 pts)

5 Bonus: Number of linear regions

What is the maximum number of linear regions of an MLP with a two dimensional input and one hidden layer with n neurons and ReLU activations? Hint: Consider the construction in the lecture, representing each hidden neuron as a line in the input space. (5 pts)