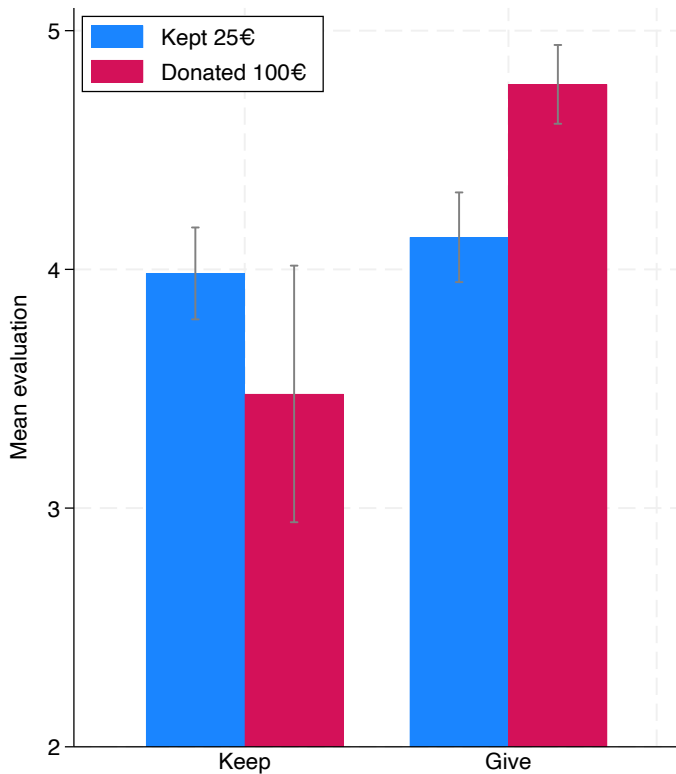


Active observers: real share



Passive observers: Gaussian NB pred share

