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SYSCALL functions available in MARS

Introduction

A number of system services, mainly for input and output, are available for use by your MIPS program. They are described in the table below.

MIPS register contents are not affected by a system call, except for result registers as specified in the table below.

How to use SYSCALL system services

- Step 1. Load the service number in register \$v0.
- Step 2. Load argument values, if any, in \$a0, \$a1, \$a2, or \$f12 as specified.
- Step 3. Issue the SYSCALL instruction.
- Step 4. Retrieve return values, if any, from result registers as specified.

Example: display the value stored in \$t0 on the console

Table of Available Services

Service	Code in \$v0	Arguments	Result
print integer	1	\$a0 = integer to print	
print float	2	f12 = float to print	
print double	3	\$f12 = double to print	
print string	4	\$a0 = address of null-terminated string to print	
read integer	5		\$v0 contains integer read
read float	6		\$f0 contains float read
read double	7		\$f0 contains double read
read string		\$a0 = address of input buffer \$a1 = maximum	See note below table

		number of characters to read	
sbrk (allocate heap memory)	9	\$a0 = number of bytes to allocate	\$v0 contains address of allocated memory
exit (terminate execution)	10		
print character	11	\$a0 = character to print	See note below table
read character	12		\$v0 contains character read
open file	13	\$a0 = address of null-terminated string containing filename \$a1 = flags \$a2 = mode	\$v0 contains file descriptor (negative if error). See note below table
read from file	14	\$a0 = file descriptor \$a1 = address of input buffer \$a2 = maximum number of characters to read	\$v0 contains number of characters read (0 if end-of-file, negative if error). See note below table
write to file	15	\$a0 = file descriptor \$a1 = address of output buffer \$a2 = number of characters to write	\$v0 contains number of characters written (negative if error). <i>See note below table</i>
close file	16	\$a0 = file descriptor	
exit2 (terminate with value)	17	\$a0 = termination result	See note below table
			PIM simulator, other than Open File (13) as es 30 and higher are exclusive to MARS.
time (system time)	30		\$a0 = low order 32 bits of system time \$a1 = high order 32 bits of system time. See note below table
MIDI out	31	\$a0 = pitch (0-127) \$a1 = duration in milliseconds \$a2 = instrument (0-127) \$a3 = volume (0- 127)	Generate tone and return immediately. See note below table
sleep	32	\$a0 = the length of time to sleep in milliseconds.	Causes the MARS Java thread to sleep for (at least) the specified number of milliseconds. This timing will not be precise, as the Java implementation will add some overhead.