Exercise Sheet 2 Ex 1

1 (a) The decision boundary occus where $g_{ex}(x) = g_{s}(x)$. We will find the locus of such x.

Note: X~ N(M, E) =) p(X=x) = 1/(200P/2 15/11/2 expl-2(x-10) 2 1/(2-10))

=) $\log p(x=x) = \frac{1}{2} \log_2 \pi - \frac{1}{2} \log_1 |z| - \frac{1}{2} (x-y)^{\frac{1}{2}} |z|^{\frac{1}{2}} (x-y)$. $g_A(x) = g_B(x) (=) \log_1 p(x|y=A) + 4 \log_2 \pi_A = \log_2 p(x|y=B) + \log_2 \pi_B$

 $(\Rightarrow |\Delta y p(x|y=A) - |\Delta y p(x|y=B) + |\Delta y \frac{\pi A}{\pi B} = 0$

€ 2 hg/[28] - 2 hg/[5] + 2(x-48) [2-48)

- 2 (x-1/A) = 1 (2-1/A) + log TA =0 (

Simplify one part of (*):

(x-1/8) [x-1/8) - (x-1/4) [2-1/4)

= 2 (58 - 21) x - MB ZB 2 + MB ZB 48 - 2 ZI /18

+ Ma 5 2 x - pa 5 5 1 pa + 20 5 2 1 pa (*x)

Note that 2 T Zn MA is a scalar, and Zn is symmetric [Zn = Zn]

and ct = c for any scalar c. Thus

2 Ton MA = (DET TON MA) = MA TON X.

$$Here, linear is used to wear affire, is linear up$$

Here, linear is used to mean attine, ie linear up to a translating constant (in this case b). A linear function f solvines $f(2x) = \lambda f(x)$. If $f(x) = \omega^{\tau} x$, then $f(2x) = \omega^{\tau} (2x) = 2\omega^{\tau} x = 2f(x)$, ie linear ty fulfilled. However, for a component $c(2x) = x^{\tau} \Lambda x$ (ie a goodratic term). $c(2x) = (2x)^{\tau} \Lambda x$ (ie a goodratic term). $c(2x) = (2x)^{\tau} \Lambda x$ (is a goodratic term). $c(2x) = (2x)^{\tau} \Lambda x$ (in a goodratic term).

6) In this case, we have
$$\Lambda = \frac{1}{2} \left(\sum_{i=1}^{n-1} - \sum_{i=1}^{n-1} \right) = 0$$

$$\omega = \sum_{i=1}^{n-1} \mu_{A} - \sum_{i=1}^{n-1} \mu_{B} = \sum_{i=1}^{n-1} \left(\mu_{A} - \mu_{B} \right)$$

In particular, A=0, so we recover

 $\omega^{T}x + b = 0$

as desired.

SKUMEN I

Machine Learning Essentials SS25 - Exercise Sheet 2

Instructions

- T0D0 's indicate where you need to complete the implementations.
- You may use external resources, but write your own solutions.
- Provide concise, but comprehensible comments to explain what your code does.
- Code that's unnecessarily extensive and/or not well commented will not be scored.

```
In [1]: import numpy as np
   import matplotlib.pyplot as plt
   from sklearn.datasets import load_digits
   from sklearn.decomposition import PCA
   from sklearn.model_selection import train_test_split
   from sklearn.discriminant_analysis import LinearDiscriminantAnalysis
   from scipy.stats import multivariate_normal
   np.random.seed(42)
```

Exercise 1 - QDA

x = np.linspace(-4, 4, 100)

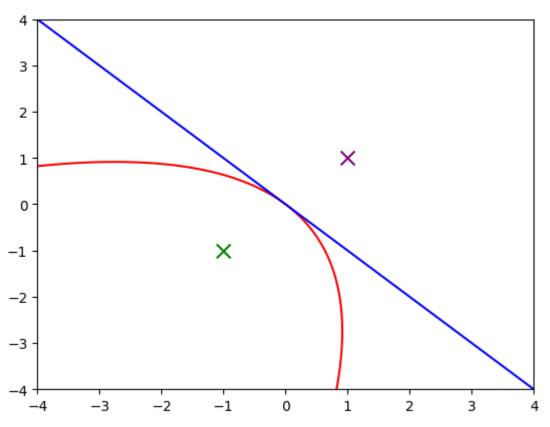
Task 2

```
In [2]: mu a = np.array([-1, -1])
        mu b = np.array([1, 1])
        sigma a = np.array([[1, 0.3], [0.3, 1]])
        sigma b = np.array([[1.5, -0.2], [-0.2, 1.5]])
        pooled_sigma = 1/2 * (sigma_a + sigma_b)
In [3]: # compute the qda boundary
        def qda_boundary(x, mu_a, mu_b, sigma_a, sigma_b):
            inv_sigma_a = np.linalg.inv(sigma_a)
            inv_sigma_b = np.linalg.inv(sigma_b)
            term1 = 0.5 * x.T @ (inv_sigma_b - inv_sigma_a) @ x
            w = (inv sigma a @ mu a - inv sigma b @ mu b).T @ x
            b = 0.5 * (mu_b.T @ inv_sigma_b @ mu_b - mu_a.T @ inv_sigma_a @ mu_a)
            return term1 + w + b
        # compute the lda boundary
        def lda_boundary(x, mu_a, mu_b, sigma):
            inv sigma = np.linalg.inv(sigma)
            w = (inv_sigma @ (mu_a - mu_b)).T @ x
            b = 0.5 * (mu_b.T @ inv_sigma @ mu_b - mu_a.T @ inv_sigma @ mu_a)
            return w + b
In [4]: # Plotting
```

```
y = np.linspace(-4, 4, 100)
X, Y = np.meshgrid(x, y)
grid = np.c_[X.ravel(), Y.ravel()]

Z_qda = np.array([qda_boundary(p, mu_a, mu_b, sigma_a, sigma_b) for p in
Z_lda = np.array([lda_boundary(p, mu_a, mu_b, pooled_sigma) for p in grid

plt.contour(X, Y, Z_qda, levels=[0], colors='r')
plt.contour(X, Y, Z_lda, levels=[0], colors='b')
plt.scatter(mu_a[0], mu_a[1], c='green', marker='x', s=100)
plt.scatter(mu_b[0], mu_b[1], c='purple', marker='x', s=100)
plt.show()
```



Exercise 2 - Implementing LDA

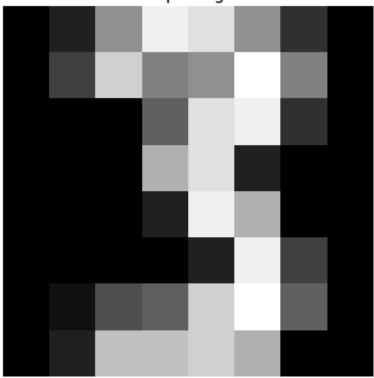
Task 1

```
In [21]: # TODO: Load digits dataset, visualize one example image of digit 3
    digits = load_digits()

index = np.where(digits.target == 3)[0][1]
    example_digit = digits.images[index]

plt.imshow(example_digit, cmap='gray', interpolation='none')
# Interpolation parameter doesn't make pixel values directly visible; we plt.title(f"Example Digit: {digits.target[0]}")
    plt.axis('off')
    plt.show()
```





```
In [22]: # TODO: Filter the dataset to keep only digits 3 and 9, split into traini
mask_3 = digits.target == 3
mask_9 = digits.target == 9

filtered_data = digits.data[mask_3 | mask_9]
filtered_target = digits.target[mask_3 | mask_9]

X_train, X_test, y_train, y_test = train_test_split(filtered_data, filter
```

Task 3

```
In [29]: def features_2d(data, labels):
    """
    This function takes the 64x1 feature vectors and returns a 2D represe
    """
    digit_3 = data[labels == 3]
    digit_9 = data[labels == 9]

    avg_3 = np.mean(digit_3, axis=0)
    avg_9 = np.mean(digit_9, axis=0)

    difference = avg_3 - avg_9

# take the two largest values of the difference
# and use these pixels to create a 2D representation
    largest_indices = np.argsort(np.abs(difference))[-2:]

    features_2d = (data[:, largest_indices], labels)
    return features_2d
```

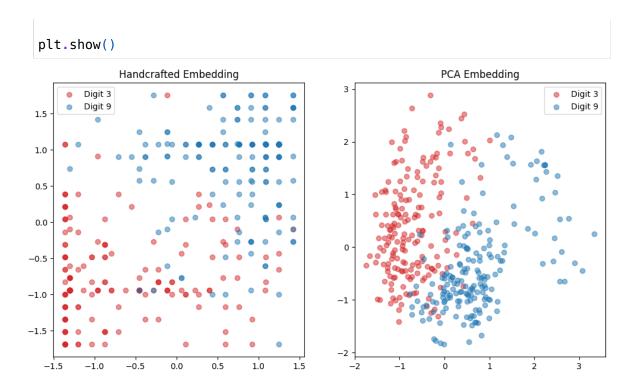
```
# TODO: Create an embedded dataset, provide a brief justification for you
data_2d, targets_2d = features_2d(X_train, y_train)
test_2d, test_targets_2d = features_2d(X_test, y_test)

# Standardise
data_2d = (data_2d - np.mean(data_2d, axis=0)) / np.std(data_2d, axis=0)
test_2d = (test_2d - np.mean(test_2d, axis=0)) / np.std(test_2d, axis=0)
```

Justification: We require a two dimensional embedding, so we take two of the 64 features: specifically the two in which the class averages differ most. Assuming low variance in these features relative to the differences in averages, then these features should separate the classes well. A more advanced method would be to take the two features which differ most relative to their variance, but we thought this was out of scope.

Task 4

```
In [43]: def pca_rep(x):
             This function takes the 64x1 feature vectors and returns a 2D represe
             # Standardize the data
             pca = PCA(n components=2)
             return pca.fit_transform(x)
         # TODO: Create a PCA-embedded dataset. Visualize & compare the embeddings
         pca_data = pca_rep(X_train)
         pca_test = pca_rep(X_test)
         # Standardise
         pca_data = (pca_data - np.mean(pca_data, axis=0)) / np.std(pca_data, axis
         pca test = (pca test - np.mean(pca test, axis=0)) / np.std(pca test, axis)
         # Plot
         data_all = np.vstack([data_2d, test_2d])
         targets_all = np.hstack([targets_2d, test_targets_2d])
         pca_all = np.vstack([pca_data, pca_test])
         # ...existing code above...
         plt.figure(figsize=(12, 6))
         # Hand-crafted embedding
         plt.subplot(1, 2, 1)
         mask3 = targets_all == 3
         mask9 = targets all == 9
         plt.scatter(data_all[mask3,0], data_all[mask3,1], c='tab:red',
                                                                           label='D
         plt.scatter(data_all[mask9,0], data_all[mask9,1], c='tab:blue', label='D
         plt.title('Handcrafted Embedding')
         plt.legend()
         # PCA embedding
         plt.subplot(1, 2, 2)
         plt.scatter(pca_all[mask3,0], pca_all[mask3,1], c='tab:red', label='Digi
         plt.scatter(pca_all[mask9,0], pca_all[mask9,1], c='tab:blue', label='Digi
         plt.title('PCA Embedding')
         plt.legend()
```



Both embeddings show a clear separation of the two classes. In fact, the PCA separation doesn't seem clearly much better. This could make sense if much of the variance is explained by those two features.

Task 5

```
In [9]:
        def fit_lda(training_features, training_labels):
            Compute LDA parameters.
            # filter features with low variance
            #mask = np.var(training_features, axis=0) > 0.001
            #training_features = training_features[:, mask]
            mu = []
            covmat = []
            p = []
            for i in np.unique(training_labels):
                features_pc = training_features[training_labels==i]
                # mu calculation
                mu_pc = np.mean(features_pc, axis=0)
                # cov calculation
                features_pcc = (features_pc - mu_pc)
                covmat_prod = features_pcc.T @ features_pcc
                mu.append(mu_pc)
                covmat.append(covmat_prod)
                # prior calculation
                p.append(features_pc.shape[0] / training_features.shape[0])
            mu = np.array(mu)
            covmat = np.sum(covmat, axis=0) / training_features.shape[0]
            p = np.array(p)
            return mu, covmat, p
```

```
# TODO: Fit seperate LDA models using your hand-crafted embedding, the PC
lda_2d = fit_lda(data_2d, targets_2d)

lda_pca = fit_lda(pca_data, y_train)

# filter data dimensions with less than 0.001 variance
X_train = X_train[:, np.var(X_train, axis=0) > 0.001]
X_test = X_test[:, np.var(X_test, axis=0) > 0.001]
lda_org = fit_lda(X_train, y_train)
```

```
In [10]: |lda_2d_mu, lda_2d_covmat, lda_2d_p = lda_2d
                    lda pca mu, lda pca covmat, lda pca p = lda pca
                    lda org mu, lda org covmat, lda org p = lda org
In [11]: | print(lda_2d_mu.shape)
                  (2, 2)
In [12]: def predict_lda(mu, covmat, p, test_features):
                            Predict labels using the LDA decision rule.
                            # TODO: Implement the LDA decision rule
                            covmat_inv = np.linalg.inv(covmat)
                            w = covmat_inv @ (mu[1, :] - mu[0, :])
                            b = -.5 * (mu[1, :] @ covmat_inv @ mu[1, :] - mu[0, :] @ covmat_inv @ mu[1, :]
                            predicted labels = np.zeros(test features.shape[0])
                            for i in range(test_features.shape[0]):
                                     predicted_labels[i] = 1 if (w.T @ test_features[i, :] + b) > 0 el
                            return predicted_labels
                    # TODO: Perform LDA on the filtered train sets of all 3 embeddings, evalu
                    lda 2d pred = predict lda(lda 2d mu, lda 2d covmat, lda 2d p, data 2d)
                    lda_pca_pred = predict_lda(lda_pca_mu, lda_pca_covmat, lda_pca_p, pca_dat
                    lda_org_pred = predict_lda(lda_org_mu, lda_org_covmat, lda_org_p, X_train
                    # report the error rates
                    def error_rate(predicted_labels, true_labels):
                            # replace the values of 0 with 3 and 1 with 9
                            predicted_labels[predicted_labels == 0] = 3
                            predicted_labels[predicted_labels == 1] = 9
                            return np.mean(predicted labels != true labels)
                    error 2d = error rate(lda 2d pred, targets 2d)
                    error_pca = error_rate(lda_pca_pred, y_train)
                    error_org = error_rate(lda_org_pred, y_train)
                    print(f"Error rate for original data: {error_org:.2f}")
                    print(f"Error rate for PCA embedding: {error pca:.2f}")
                    print(f"Error rate for 2D embedding: {error 2d:.2f}")
                    lda_2d_test = predict_lda(lda_2d_mu, lda_2d_covmat, lda_2d_p, test_2d)
                    lda_pca_test = predict_lda(lda_pca_mu, lda_pca_covmat, lda_pca_p, pca_tes
                    lda_org_test = predict_lda(lda_org_mu, lda_org_covmat, lda_org_p, X_test)
                    error 2d test = error rate(lda 2d test, test targets 2d)
```

```
error_pca_test = error_rate(lda_pca_test, test_targets_2d)
error_org_test = error_rate(lda_org_test, test_targets_2d)
print(f"Test Error rate for original data: {error_org_test:.2f}")
print(f"Test Error rate for PCA embedding: {error_pca_test:.2f}")
print(f"Test Error rate for 2D embedding: {error_2d_test:.2f}")

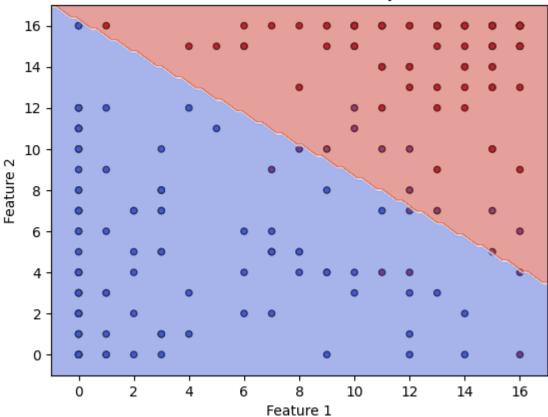
Error rate for original data: 0.00
Error rate for PCA embedding: 0.04
```

Error rate for original data: 0.00
Error rate for PCA embedding: 0.04
Error rate for 2D embedding: 0.08
Test Error rate for original data: 0.40
Test Error rate for PCA embedding: 0.17
Test Error rate for 2D embedding: 0.19

Task 7

```
In [13]: # TODO: For your hand-crafted embedding, visualize the decision boundary
         def plot decision boundary(mu, covmat, p, data, labels):
             # scatter plot
             plt.scatter(data[:, 0], data[:, 1], c=labels, cmap='coolwarm', edgeco
             # min and max vals for the grid
             x_{min}, x_{max} = data[:, 0].min() - 1, <math>data[:, 0].max() + 1
             y_{min}, y_{max} = data[:, 1].min() - 1, <math>data[:, 1].max() + 1
             # grid for the predictions and boundary
             xx, yy = np.meshgrid(np.linspace(x_min, x_max, 100), np.linspace(y_min, x_max, 100))
             grid points = np.c [xx.ravel(), yy.ravel()]
             # throw grid into the LDA function to get predictions
             grid predictions = predict lda(mu, covmat, p, grid points)
             grid predictions = grid predictions.reshape(xx.shape)
             # plot the decision boundary
             plt.contourf(xx, yy, grid predictions, alpha=0.5, cmap='coolwarm')
             plt.xlim(x_min, x_max)
             plt.ylim(y min, y max)
             plt.title('LDA Decision Boundary')
             plt.xlabel('Feature 1')
             plt.ylabel('Feature 2')
             plt.show()
         plot decision boundary(lda 2d mu, lda 2d covmat, lda 2d p, data 2d, targe
```





```
In [44]:
        def cross_val_lda(X, y, n_splits):
             Perform n-fold cross-validation for LDA using the earlier defined fun
             # TODO: Implement cross-validation for LDA.
             fold size = len(X) // n splits
             indices = np.arange(len(X))
             np.random.shuffle(indices)
             folds = np.array_split(indices, n_splits)
             avg_error = []
             for i in range(n_splits):
                 test_indices = folds[i]
                 train_indices = np.concatenate([folds[j] for j in range(n_splits)
                 # filter data dimensions with less than 0.001 variance
                 X_train, X_test = X[train_indices, :], X[test_indices, :]
                 y train, y test = y[train indices], y[test indices]
                 # filter data dimensions with less than 0.001 variance
                 var indices = np.var(X train, axis=0) > 0.001
                 X_train = X_train[:, var_indices]
                 X_test = X_test[:, var_indices]
                 mu, covmat, p = fit_lda(X_train, y_train)
                 predictions = predict_lda(mu, covmat, p, X_test)
                 error = error_rate(predictions, y_test)
                 avg_error.append(error)
```

```
avg = np.mean(avg_error)
    return avg, np.std(avg_error)/np.sqrt(n_splits)

# TODO: Perform 10-fold CV on the original data. Report average test erro
n_splits = 10
average, standard_error = cross_val_lda(filtered_data, filtered_target, n_error)
print(f"Average error: {average:.2f}")
print(f"Standard error of error estimates: {standard_error:.2f}")
```

```
Average error: 0.06
Standard error of error estimates: 0.05
```

Compared to the error from task 2.6 trained on the entire data set the average test error rate is much lower with 10 fold cross validation.

Exercise 3 - Statistical Darts

Task 1

```
In [15]: def simulate_data(mu_true, Sigma_true, n_samples):
    # TODO: Simulate data from a bivariate Gaussian distribution given th

# Sample
data = np.random.multivariate_normal(mu_true, Sigma_true, n_samples)

return data
```

Task 2

```
In [16]: def compute_mle(data):
    # TODO: Compute the MLE for the mean of a Gaussian distribution.
    mu_mle = np.mean(data, axis=0)
    return mu_mle
```

Task 3

```
In [17]: def compute_posterior(data, prior, Sigma_true):
    # TODO: Compute the parameters of the posterior distribution for the
    sigma_inv = np.linalg.inv(Sigma_true)

    sigma_prior_inv = np.linalg.inv(prior['Sigma0'])
    mu_prior = prior['mu0']

    mu_mle = compute_mle(data)

    n = data.shape[0]

    Sigma_post = np.linalg.inv(sigma_prior_inv + n * sigma_inv)
    mu_post = Sigma_post @ (sigma_prior_inv @ mu_prior + n * sigma_inv)

    return mu_post, Sigma_post
```

```
def compute_map(data, prior, Sigma_true):
    # TODO: Assign mean of the posterior to mu_map.
    mu_map, _ = compute_posterior(data, prior, Sigma_true)
    return mu_map
```

```
In [45]: def visualize_inference(mu_true, mu_mle, mu_map, mu_post, Sigma_post, dat
                                 grid limits=[-1, 1, -1, 1], n points=100):
             Visualizes the full posterior distribution as Gaussian isocontours ov
             alongside the true mean, MLE estimate, MAP estimate and the simulated
             Additional parameters:
                 grid limits: [xmin, xmax, ymin, ymax] limits for the 2D grid.
                 n points: Number of grid points per axis.
             # Define the grid
             xmin, xmax, ymin, ymax = grid_limits
             x = np.linspace(xmin, xmax, n points)
             y = np.linspace(ymin, ymax, n_points)
             X, Y = np.meshgrid(x, y)
             pos = np.dstack((X, Y))
             # Get the posterior distribution
             rv = multivariate normal(mu post, Sigma post)
             # Evaluate the pdf of the posterior @ the grid points
             Z = rv.pdf(pos)
             # Compute some contour levels
             levels = np.linspace(Z.max()*0.05, Z.max()*0.95, 7)
             plt.figure(figsize=(8, 6), facecolor='white')
             # Plot a dartboard-like background (concentric circles)
             center = [0,0]
             radius = 0.8
             for r in [radius, radius*0.8, radius*0.6, radius*0.4, radius*0.2]:
                 circle = plt.Circle(center, r, fill=False, color='black')
                 plt.gca().add artist(circle)
             plt.axis('equal')
             # Add bullseye
             plt.plot(center[0], center[1], 'o', markersize=10, c='red')
             # Plot isocontours of posterior
             contour = plt.contour(X, Y, Z, levels=levels, cmap='viridis',linewidt
             # Add labels to the isocontours (off by default for visibility)
             # plt.clabel(contour, inline=True, fontsize=8, fmt="%.1f")
             # Plot observed data points
             plt.scatter(data[:, 0], data[:, 1], c='gray', edgecolor='k', alpha=0.
             # Plot true mean (ground truth)
             plt.scatter(mu true[0], mu true[1], c='black', marker='*', s=200, lab
             # Plot MLE estimate
```

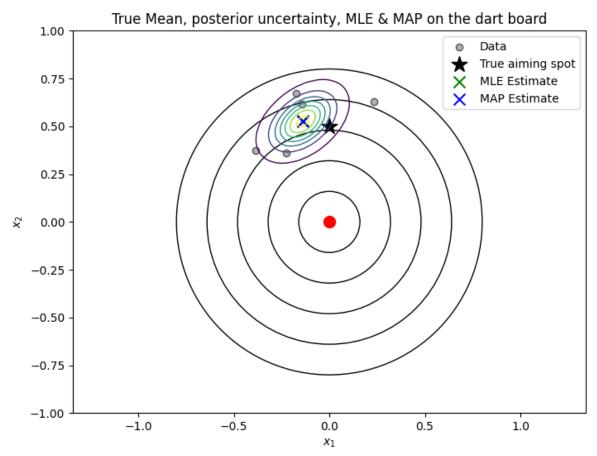
```
plt.scatter(mu_mle[0], mu_mle[1], c='green', marker='x', s=100, label

# Plot MAP estimate
plt.scatter(mu_map[0], mu_map[1], c='blue', marker='x', s=100, label=

plt.title("True Mean, posterior uncertainty, MLE & MAP on the dart bo
plt.xlabel("$x_1$")
plt.ylabel("$x_2$")
plt.legend()
plt.grid(False)

plt.show()
```

```
In [46]: # Ground truth parameters for the dart throws:
         mu\_true = np.array([0, 0.50])
         Sigma true = np.array([[0.05, 0.02],
                                 [0.02, 0.04]
         # Prior for mu - standard normal around the bullseye
         prior = {
             "mu0": np.array([0, 0]),
             "Sigma0": np.eye(2)
         # TODO: Simulate data, compute MLE, MAP and posterior
         n \text{ samples} = 5
         data = simulate_data(mu_true, Sigma_true, n_samples=n_samples)
         mu mle = compute mle(data)
         mu_map = compute_map(data, prior, Sigma_true)
         mu_post, Sigma_post = compute_posterior(data, prior, Sigma_true)
         # Visualize the inference
         visualize_inference(mu_true, mu_mle, mu_map, mu_post, Sigma_post, data)
         print(f"MLE estimate for N={n_samples}:", mu_mle)
         print(f"MAP estimate for N={n_samples}:", mu_map)
         print(f"Posterior covariance for N={n_samples}:\n", Sigma_post)
         # TODO: Assess results (see exercise sheet)
```



MLE estimate for N=5: [-0.13875311 0.52952618]
MAP estimate for N=5: [-0.139462 0.52587701]
Posterior covariance for N=5:
[[0.00988543 0.00392903]
[0.00392903 0.00792092]]

Task 5

The posterior reflects a weighted combination of the prior and the likelihood. The posterior variance is quite easy to interpret in 1D, in particular:

$$\sigma_{post}^2 = rac{1}{rac{1}{\sigma_o^2} + rac{N}{\sigma_{true}^2}}$$

which is a weighted harmonic mean, weighted by the number of samples. The harmonic mean works with inverse $(\frac{1}{\sigma_0^2})$ Thus with a more informative prior (smaller σ_0^2 -> larger $1/\sigma_0^2$) the influence on the posterior increases, while for less informative prior (larger σ^2 -> smaller $1/\sigma_0^2$) the influence is smaller.

On the other hand, we can interpret μ_{post} by plugging in σ_{post}^2 :

$$\mu_{post} = rac{P_0}{P_0 + NP_{true}} \mu_0 + rac{NP_{true}}{P_0 + NP_{true}} \mu_{MLE}$$

which is a weighted average (the usual average) depending on the prior precision P_0 and the posterior precision P_{true} , with precisions being inverse variances.

Two conditions under which the MLE and the MAP estimates match:

1. Prior with infinite variance: then the prior is 'uninformative' and thus has no influence on the posterior estimate, and the estimate is generated entirely from the data term. Then $P_0=0$ and plugging into

$$\mu_{post} = rac{P_0}{P_0 + NP_{true}} \mu_0 + rac{NP_{true}}{P_0 + NP_{true}} \mu_{MLE}$$

one obtains

$$\mu_{post} = rac{NP_{true}}{NP_{true}} \mu_{MLE} = \mu_{MLE}$$

w. The prior mean matches the MLE estimate (which could not be organised prior to an experiment). Then the same expression simplifies to

$$\mu_{post} = rac{P_0 + NP_{true}}{P_0 + NP_{true}} \mu_{MLE} = \mu_{MLE}$$

Task 7

- 1. Suppose you want to estimate the efficacy of a medical treatment (eg in change in probability of survival). Then a positive estimate would sound good, but if there's a high variance, it would indicate that the treatment is ineffective, or even harmful for some patients. This would be very important to know when communicating to patients to allow for an informed decision, depending on the acceptability of risks.
- 2. When estimating the number of people attending an event, one may wish to estimate a likely maximum and minimum (eg end-points of a 95% confidence interval) to allow planning for facilities.

Exercise 4: Logistic Regression 1) $y \in \{0,1\}$, $\rho = \rho(y=1|x) = \sigma(\omega^T x) = \mu_A$ y~ Bes(ρ) = N+2-2-N 1+2-2 $=> \rho(y=k|x) = \mu_k^k (1-\mu_k)^{1-k} = \sigma(\omega T_X)^k \sigma(-\omega T_X)^{1-k}$ $=\frac{1}{1+e^2}=o(-2)$ Log likelihood: $\mathcal{L}(\omega) = \sum_{i=1}^{N} \log \left(\rho(y_i | x_i) \right) = \sum_{i=1}^{N} \log \left(\sigma(\omega^T x_i) \right)^{y_i} \sigma(-\omega^T x_i)^{1-y_i} \right)$ $= \sum_{i=1}^{n} y_i \log(\sigma(\omega^T x_i)) + (1-y_i) \log(\sigma(-\omega^T x_i))$ Convexity of function ensures that following the direction indicated by gradient descent you will find its global minimum, since any local minimum is the global minimum of a convex function. To proof: $-l(\omega) = \sum_{i=1}^{\infty} k \log(\sigma(\omega^{T} \times_{i})) + (1-k) \log(\sigma(\omega^{T} \times_{i}))$ is convex Convexity: $f: D \in \mathbb{R} \longrightarrow \mathbb{R}$ convex iff $f(tx_1 + (1-t)x_2) \subseteq t f(x_1) + (1-t) f(x_2)$ $\forall x_1, x_2 \in D$, $o \subseteq t \subseteq A$ Equivalently: f convex $<=> f">0 <math>\forall x \in D$ i) First consider - log(o(x)): $\partial_{x} - (\log (\sigma(x))) = \partial_{x} \log (1 + e^{-x}) = \frac{-e^{-x}}{1 + e^{-x}} = -\sigma(x)$ $=>-\log(\sigma(x))$ is convex $\partial_{x}^{2} - \log(\sigma(x)) = \partial_{x} \sigma(x) = \sigma(x) \sigma(-x) > 0 \quad \forall x$ ii) Secondly consider: - log(o-(-x)): $-\mathcal{O}_{\times}(\log(\sigma(-x)) = \mathcal{O}_{\times}(\log(1+e^{x})) = \frac{1}{1+e^{x}}e^{x} = \sigma(x)$ $\partial_x^2 - log(\sigma(-x)) = \partial_x \sigma(x) = \sigma(x)\sigma(-x) > 0 \forall x$ $= \rightarrow -(og(\sigma(-x)))$ is convex Since - L(w) is a sum of convex functions of the form i) and ii) it is convex itself. LBCE(W) = -N L(W) => maximizing log-likelihood => uninimizing awage binary <10ss-entropy

3) a) Suppose we have found ω s.t. $\omega T \times = 0$ defines the electron boundary between two linearly separable classes. That would lead to a loss: $\mathcal{L}(\omega) = -\mathcal{L}(\omega) = -\sum_{i=1}^{N} y_i \log(\sigma(\omega^{T} x_i)) + (1 - y_i) \log(\sigma(-\omega^{T} x_i))$ where the arguments of all o - furctions contributing to it will be positive, ie. $\sigma \in (0,5,1]$, because the model performs "correct" classifications The only way for the model to optimize, i.e. minimize the loss, is now to have not only correct classifications, but also "confident" classifications, meaning σ (±ωτχ;) ~ 1 and this log (σ (±ωτχ;)) ~ O. For this we need: IlwTx: 11 -> 00, which the model will try to ensure by taking |w| to

This can be unitigated implementing a so-called L2-regularization in the Loss: in the Loss: $\widehat{\mathcal{L}}(\omega) = \mathcal{L}(\omega) + 2 \|\omega\|^2$

which penalizes high w-wagnitudes and prevents the divergence.