

# Notebook

February 23, 2022

## 1 Support Vector Machines

```
[195]: import numpy as np
import pickle as pkl
from scipy import optimize
from scipy.linalg import cho_factor, cho_solve
import matplotlib.pyplot as plt
from utils import plotClassification, plotRegression, plot_multiple_images, \
    generateRings, scatter_label_points, loadMNIST
```

### 1.1 Loading the data

The file 'classification\_datasets' contains 3 small classification datasets:

- dataset\_1: mixture of two well separated gaussians
- dataset\_2: mixture of two gaussians that are not separated
- dataset\_3: XOR dataset that is non-linearly separable.

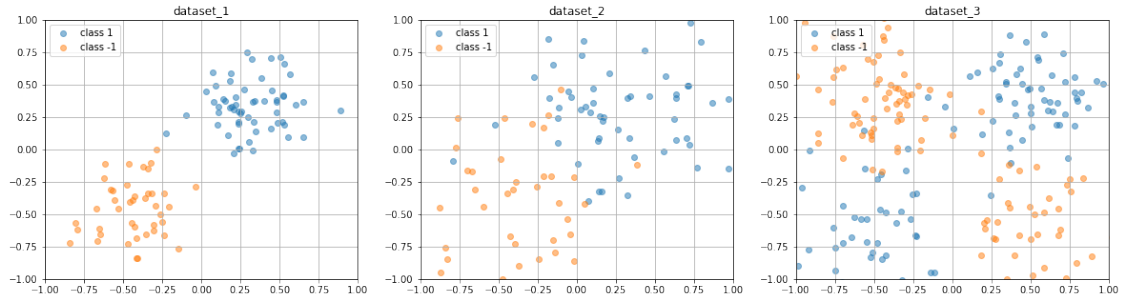
Each dataset is a hierarchical dictionary with the following structure:

```
dataset = {'train': {'x': data, 'y': label}
           'test': {'x': data, 'y': label}
          }
```

The data  $x$  is an  $N$  by 2 matrix, while the label  $y$  is a vector of size  $N$ .

```
[185]: file = open('datasets/classification_datasets', 'rb')
datasets = pkl.load(file)
file.close()
fig, ax = plt.subplots(1,3, figsize=(20, 5))
for i, (name, dataset) in enumerate(datasets.items()):

    plotClassification(dataset['train']['x'], dataset['train']['y'], ax=ax[i])
    ax[i].set_title(name)
```



## 1.2 III- Kernel SVC

### 1.2.1 1- Implementing the Gaussian Kernel

Implement the method 'kernel' of the class RBF below, which takes as input two data matrices  $X$  and  $Y$  of size  $N \times d$  and  $M \times d$  and returns a gram matrix  $G$  of shape  $N \times M$  whose components are  $k(x_i, y_j) = \exp(-\|x_i - y_j\|^2 / (2\sigma^2))$ . (The fastest solution does not use any for loop!)

```
[186]: class RBF:
    def __init__(self, sigma = 1.):
        self.sigma = sigma  ## the variance of the kernel

    def kernel(self, X, Y):
        d = X.shape[1]
        M = Y.shape[0]
        N = X.shape[0]

        self.X = X
        self.Y = Y
        G = np.zeros((X.shape[0], Y.shape[0]))

        G[:, :] = [[np.exp(-(1/2*self.sigma)*np.linalg.norm((X[i, :] - Y[j, :]) ,
↪2)) for j in range(M)]
                    for i in range(N)]

        return G

class Linear:

    def kernel(self, X, Y):
        #d = X.shape[1]
        M = Y.shape[0]
        N = X.shape[0]

        self.X = X
```

```

self.Y = Y
G = np.zeros((X.shape[0], Y.shape[0]))

G[:, :] = np.dot(X, Y.T)
return G

```

### 1.2.2 2- Implementing the classifier

Implement the methods 'fit' and 'separating\_function' of the class KernelSVC below to learn the Kernel Support Vector Classifier.

```

[192]: class KernelSVC:

    def __init__(self, C, kernel, epsilon = 1e-3):
        self.type = 'non-linear'
        self.C = C
        self.kernel = kernel
        self.alpha = None
        self.support = None
        self.epsilon = epsilon
        self.norm_f = None

    def fit(self, X, y):
        N = len(y)
        self.X = X
        self.y = y
        self.Y = np.diag(self.y)
        self.K = self.kernel(self.X, self.X)
        #K = self.kernel(X,X)

        # Lagrange dual problem
        def loss(alpha):
            return -np.sum(alpha) + 1/2*alpha.T.dot(np.diag(y)).dot(self.
↪kernel(X,X)).dot(np.diag(y)).dot(alpha)

        # Partial derivate of Ld on alpha
        def grad_loss(alpha):
            return -np.ones(N) + np.diag(y).dot(self.kernel(X,X)).dot(np.
↪diag(y)).dot(alpha)

        # Constraints on alpha of the shape :
        # - d - C*alpha = 0
        # - b - A*alpha >= 0

        A = np.vstack((-np.eye(N), np.eye(N)))

```

```

b = np.concatenate((np.zeros(N), self.C * np.ones(N)))

fun_eq = lambda alpha: np.dot(self.y,alpha)
jac_eq = lambda alpha: self.y
fun_ineq = lambda alpha: b - np.dot(A, alpha)
jac_ineq = lambda alpha: -A

constraints = ({'type': 'eq', 'fun': fun_eq, 'jac': jac_eq},
               {'type': 'ineq',
                'fun': fun_ineq,
                'jac': jac_ineq})

optRes = optimize.minimize(fun = lambda alpha: loss(alpha),
                           x0 = np.ones(N),
                           method = 'SLSQP',
                           jac = lambda alpha: grad_loss(alpha),
                           constraints = constraints)

self.alpha = optRes.x

## Assign the required attributes
sv = (self.alpha > self.epsilon)*(self.alpha < self.C)
supportIndices = np.arange(len(self.alpha))[sv]
self.support = X[supportIndices] ##### A matrix with
↪ each row corresponding to a support vector #####

alpha_sv = self.alpha[sv]
sv = np.argwhere(sv == True)
y_sv = y[sv]

# Bias value/intercept
self.b = 0*1.0;
for i in range(len(alpha_sv)):

    self.b += y_sv[i] - np.sum(alpha_sv * y_sv[:,0] * self.
↪ kernel(X,X)[sv,supportIndices[i]])

self.b /= len(alpha_sv)

# '#####RKHS norm of the function f
↪ #####

self.norm_f = self.alpha.T.dot(self.Y).dot(self.kernel(X,X)).dot(self.
↪ Y).dot(self.alpha)

### Implementation of the separating function $f$
def separating_function(self,x):

```

```

    # Input : matrix x of shape N data points times d dimension
    # Output: vector of size N
    N, d = x.shape
    sv = (self.alpha > self.epsilon)*(self.alpha < C)
    out = np.ones(N)
    for i in range(N):
        x_i = x[i]
        for j in range(np.sum(sv)):
            out[i]+=self.alpha[sv][j]*self.y[sv][j]*self.kernel(x_i,
↪reshape(-1,1).T,self.support[j].reshape(-1,1).T)
        return out

    def predict(self, X):
        """ Predict y values in {-1, 1} """
        d = self.separating_function(X)
        return 2 * (d+self.b> 0) - 1

```

```

[196]: fig, ax = plt.subplots(1,3, figsize=(20, 5))
C = 10000.
kernel = Linear().kernel
model = KernelSVC(C=C, kernel=kernel)
train_dataset = datasets['dataset_1']['train']
model.fit(train_dataset['x'], train_dataset['y'])
plotClassification(train_dataset['x'], train_dataset['y'], model,
↪label='Training', ax = ax[0])

C = 10.
model = KernelSVC(C=C, kernel=kernel)
train_dataset = datasets['dataset_2']['train']
model.fit(train_dataset['x'], train_dataset['y'])
plotClassification(train_dataset['x'], train_dataset['y'], model,
↪label='Training', ax = ax[1])

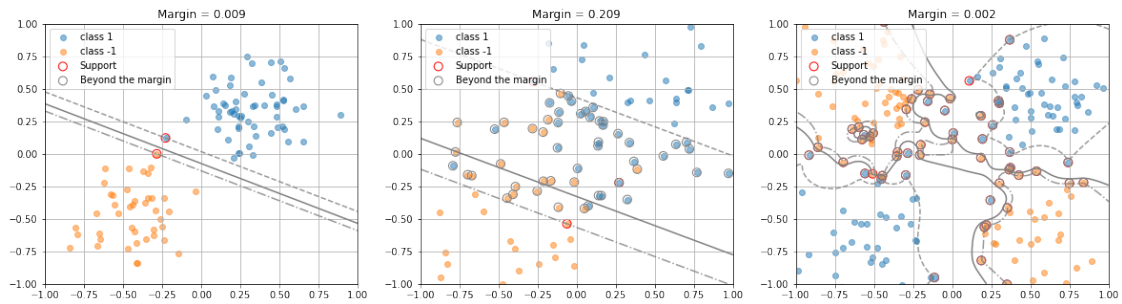
sigma = 1.5
C=100.
kernel = RBF(sigma).kernel
model = KernelSVC(C=C, kernel=kernel)
train_dataset = datasets['dataset_3']['train']
model.fit(train_dataset['x'], train_dataset['y'])
plotClassification(train_dataset['x'], train_dataset['y'], model,
↪label='Training', ax=ax[2])

plt.savefig('SVM Classification.pdf')

```

Number of support vectors = 2  
Number of support vectors = 3

Number of support vectors = 57



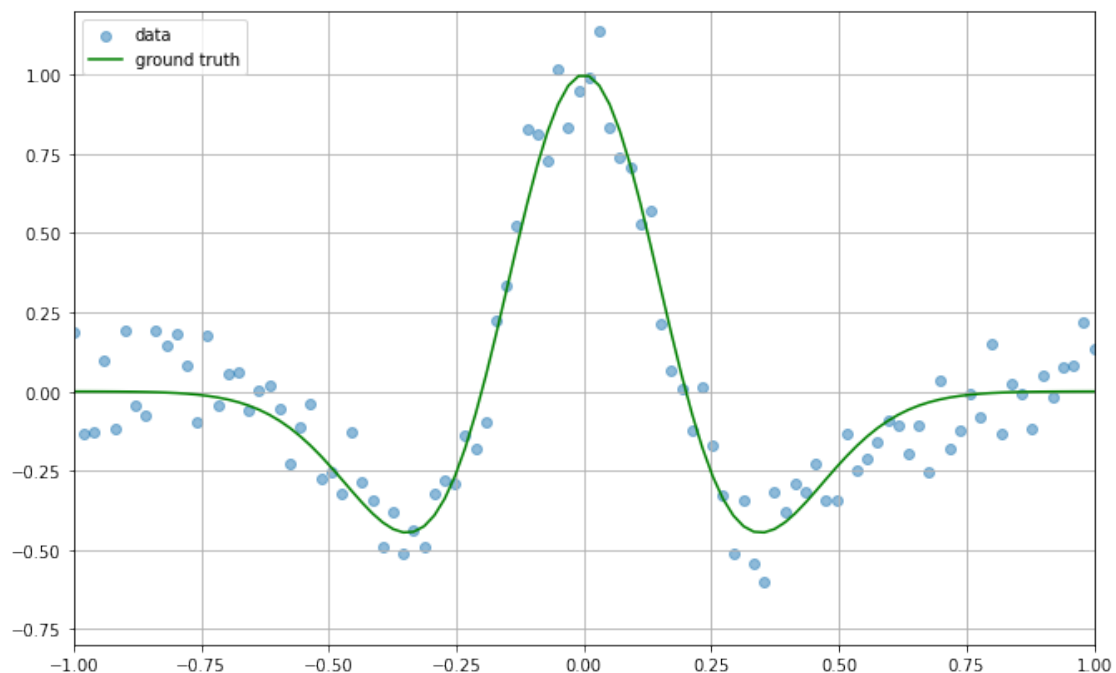
### 1.2.3 2- Fitting the classifier

Run the code block below to fit the classifier and report its output.

## 2 Kernel Regression

### 2.1 Loading the data

```
[22]: file = open('datasets/regression_datasets', 'rb')
datasets = pickle.load(file)
file.close()
train_set = datasets['dataset_1']['train']
train_set = datasets['dataset_1']['test']
plotRegression(train_set['x'], train_set['y'], Y_clean= train_set['y_clean'])
```



## 2.2 Kernel Support Vector Regression

### 2.2.1 1- Implementing the regressor

Implement the method 'fit' of the classes KernelSVR below to perform Kernel Support Vector Regression.

```
[189]: class KernelSVR:

    def __init__(self, C, kernel, eta= 1e-2, epsilon = 1e-3):
        self.C = C
        self.kernel = kernel
        self.alpha = None # Vector of size 2*N
        self.support = None
        self.support1 = None
        self.support2 = None
        self.eta = eta
        self.epsilon = epsilon
        self.eps = 0.
        self.type='svr'
        self.sv = None

    def fit(self, X, y):
        #### You might define here any variable needed for the rest of the code
        N = len(y)

        self.X = X
        self.y = y
        # Lagrange dual problem
        def loss(alpha):
            alpha_plus = alpha[0:N]
            alpha_moins = alpha[N:2*N]
            return 1/2*(alpha_plus + alpha_moins).T.dot(self.kernel(X,X)).
↪dot(alpha_plus + alpha_moins) -(alpha_plus - alpha_moins).T.dot(y - self.
↪eta*np.ones(N))
            #####dual loss #####

        # Partial derivate of Ld on alpha
        def grad_loss(alpha):
            alpha_plus = alpha[0:N]
            alpha_moins = alpha[N:2*N]
            grad_plus = -(y - self.eta*np.ones(N)) +self.kernel(X,X).
↪dot(alpha_plus + alpha_moins)
            grad_moins = (y - self.eta*np.ones(N)) +self.kernel(X,X).
↪dot(alpha_plus + alpha_moins)
            return np.concatenate((grad_plus,grad_moins))
```

```

# Constraints on alpha of the shape :
# -  $d - C * \alpha = 0$ 
# -  $b - A * \alpha \geq 0$ 

A = np.vstack((-np.eye(2*N), np.eye(2*N)))
b = np.concatenate((np.zeros(2*N), C * np.ones(2*N)))

Cmat = np.concatenate((np.ones(N), -np.ones(N)))
fun_eq = lambda alpha: np.dot(alpha, Cmat)
# '''-----function defining the equality
↳constraint-----'''
jac_eq = lambda alpha: Cmat #'''-----jacobian wrt alpha
↳of the equality constraint-----'''
fun_ineq = lambda alpha: b - np.dot(A, alpha) #
↳'''-----function defining the inequality
↳constraint-----'''
jac_ineq = lambda alpha: -A # '''-----jacobian wrt alpha of
↳the inequality constraint-----'''

constraints = ({'type': 'eq', 'fun': fun_eq, 'jac': jac_eq},
               {'type': 'ineq', 'fun': fun_ineq, 'jac': jac_ineq})

optRes = optimize.minimize(fun=lambda alpha: loss(alpha),
                           x0= self.C*np.ones(2*N),
                           method='SLSQP',
                           jac=lambda alpha: grad_loss(alpha),
                           constraints=constraints,
                           tol=1e-7)

self.alpha = optRes.x
## Assign the required attributes
sv = (self.alpha > self.epsilon)*(self.alpha < self.C)
self.sv = sv
sv1 = sv[0:N]
sv2 = sv[N:2*N]
sv = sv1|sv2
supportIndices = np.arange(N)[sv]
self.support = X[supportIndices] #'''----- A matrix with
↳each row corresponding to a support vector -----'''
y_sv = y[supportIndices]
self.support = [item for sublist in self.support for item in sublist]
self.support = np.column_stack((self.support, y_sv))

self.support1 = X[np.arange(N)[sv1]]
self.support2 = X[np.arange(N)[sv2]]

```



```

alpha1_sv = self.alpha[0:N][sv1]
sv1 = np.argwhere(sv1==True)
sv1_y = y[sv1]

margin_pos = 0*1.0;
for i in range(len(alpha1_sv)):
    margin_pos += sv1_y[i] - np.sum(alpha1_sv * sv1_y[:,0] * self.
↪kernel(X,X)[sv1,np.arange(N)[sv1][i]]) - self.eta
    margin_pos /= len(alpha1_sv)

alpha2_sv = self.alpha[N:2*N][sv2]
sv2 = np.argwhere(sv2==True)
sv2_y = y[sv2]

margin_neg = 0*1.0;
for i in range(len(alpha2_sv)):
    margin_neg += self.eta + sv2_y[i] - np.sum(alpha2_sv * sv2_y[:,0] *
↪self.kernel(X,X)[sv2,np.arange(N)[sv2][i]])
    margin_neg /= len(alpha2_sv)

self.b = 0.5*(margin_pos + margin_neg)    #''' -----offset
↪of the regressor ----- '''

### Implementation of the separating function $f$
def regression_function(self,x):
    # Input : matrix x of shape N data points times d dimension
    # Output: vector of size N
    N, d = x.shape
    out = np.ones(N)
    sv1 = self.sv[0:N]
    sv2 = self.sv[N:2*N]
    alpha1 = self.alpha[0:N]
    alpha2 = self.alpha[N:2*N]
    for i in range(N):
        x_i = x[i]
        for j in range(np.sum(sv1)):
            out[i]+=alpha1[sv1][j]*self.y[sv1][j]*(self.kernel(x_i.
↪reshape(-1,1),self.support1[j].reshape(-1,1)))
        for j in range(np.sum(sv2)):
            out[i]+=alpha2[sv2][j]*self.y[sv2][j]*(self.kernel(x_i.
↪reshape(-1,1).T,self.support2[j].reshape(-1,1)))
    return out

def predict(self, X):
    """ Predict y values in {-1, 1} """
    return self.regression_function(X)+self.b

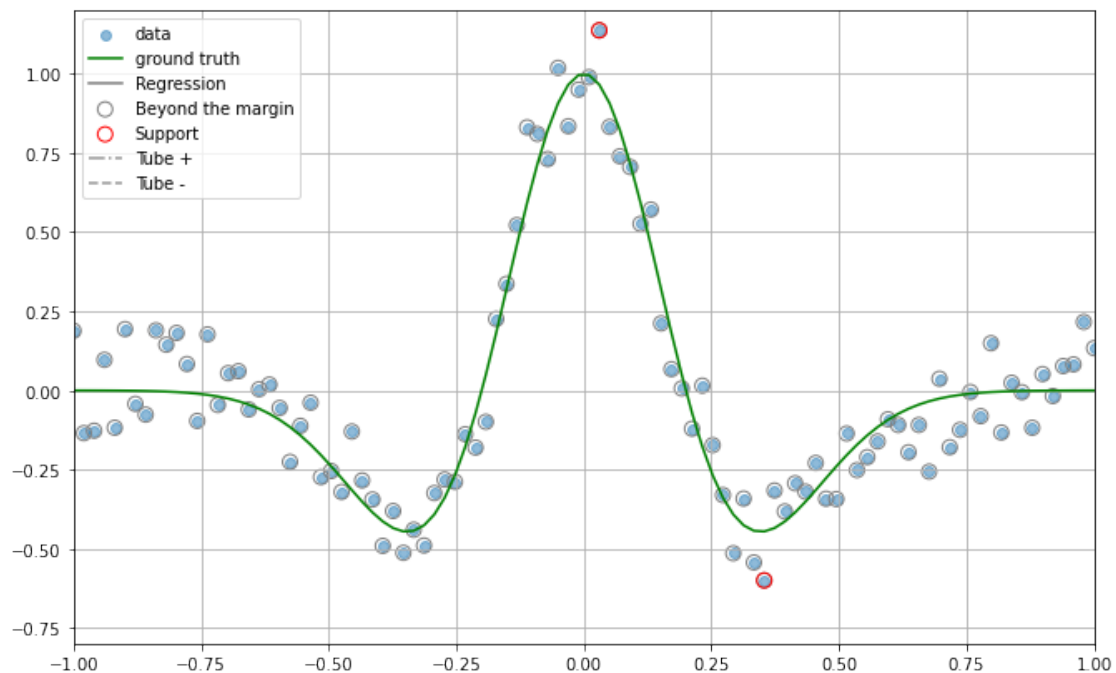
```

### 2.2.2 2- Fitting the regressor

Run the code block below to fit the regressor and report its output.

```
[197]: sigma = 0.2
C = 10.
kernel = RBF(sigma).kernel
model = KernelSVR(C,kernel, eta= .1, epsilon = 1e-6)
model.fit(train_set['x'].reshape(-1,1),train_set['y'])
plotRegression(train_set['x'], train_set['y'], Y_clean= train_set['y_clean'],
               ↪model=model, label='Train')
plt.savefig('Kernel Regression.pdf')
```

Number of support vectors = 2



```
[ ]:
```