

# Stability Analysis of a Minimal Within-Host TB Model

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## 1 Introduction

We consider a minimal model for within-host tuberculosis (TB) dynamics consisting of two interacting compartments: the TB burden  $b(t)$ , and the immune response  $i(t)$ . The system exhibits rich dynamics including bistability and tipping points between clearance and dominance. This document presents steady-state analysis, feasibility conditions, and local and global stability results.

## 2 Model Definition and Rescaling

We begin with the rescaled ODE system:

$$\frac{db}{dt} = \beta_b b [\eta_b(1 - b) - i] \quad \text{and} \quad \frac{di}{dt} = \beta_i i [\eta_i(1 - i) - b]$$

where  $b(t)$  and  $i(t)$  are non-dimensional variables representing TB and immune response (scaled 0–1), and the parameters are defined as:

- $\beta_b = \alpha_B K_I$ ,  $\beta_i = \alpha_I K_B$  (feedback strength)
- $\eta_b = \frac{r_B}{\alpha_B K_I}$ ,  $\eta_i = \frac{r_I}{\alpha_I K_B}$  (self-limiting growth factors)

## 3 Steady States

Setting the time derivatives to zero yields four equilibria:

- Trivial:  $(b^*, i^*) = (0, 0)$
- TB-only:  $(b^*, i^*) = (1, 0)$
- Immune-only:  $(b^*, i^*) = (0, 1)$
- Coexistence equilibrium:

$$b^* = \frac{\eta_i(\eta_b - 1)}{\eta_i\eta_b - 1}, \quad i^* = \frac{\eta_b(\eta_i - 1)}{\eta_i\eta_b - 1}$$

## 4 Existence and Feasibility Conditions

The coexistence equilibrium is biologically feasible (i.e.,  $b^* > 0$ ,  $i^* > 0$ ) if either:

- $\eta_b > 1$  and  $\eta_i > 1$
- $\eta_b < 1$  and  $\eta_i < 1$

If one is above and one is below 1, then either  $b^*$  or  $i^*$  becomes negative, rendering the equilibrium nonphysical.

## 5 Local Stability Analysis

The Jacobian matrix evaluated at the coexistence point is:

$$J = \begin{bmatrix} -r_b b^* & -\beta_b b^* \\ -\beta_i i^* & -r_i i^* \end{bmatrix}$$

Stability requires:

- $\text{tr}(J) < 0$
- $\det(J) > 0 \Rightarrow b^* i^* (r_b r_i - \beta_b \beta_i) > 0$

Thus, coexistence is locally stable if  $r_b r_i > \beta_b \beta_i$  and  $b^*, i^* > 0$ .

## 6 Global Stability

Using the Bendixson–Dulac criterion with  $B(b, i) = \frac{1}{bi}$  yields:

$$\frac{\partial(Bf)}{\partial b} + \frac{\partial(Bg)}{\partial i} = -\frac{r_b}{i} - \frac{r_i}{b} < 0$$

Hence, no periodic orbits exist and all bounded solutions tend to equilibria. This suggests global convergence to one of the steady states.

## 7 Lyapunov Stability

We construct a Lyapunov function for the coexistence equilibrium:

$$V(b, i) = b - b^* - b^* \log \left( \frac{b}{b^*} \right) + c \left( i - i^* - i^* \log \left( \frac{i}{i^*} \right) \right)$$

With  $c = \beta_b / \beta_i$ , the derivative along trajectories satisfies:

$$\dot{V} \leq -\beta_b (b - b^* + i - i^*)^2$$

indicating global asymptotic stability when  $r_b \geq \beta_b$  and  $r_i \geq \beta_i$ .