

Phase	Implementation					Interaction in the real world	Post-interaction development			Refining (if necessary)			Final robot behaviour
WoZ	Analysis of the application domain	Implementation of robot's actions		Creation of interface		WoZ							
LfD			Implementation of sensory inputs			WoZ Data collection	Analysis of dataset	Implementation of algorithm	Offline learning	Testing	Additional data collection	Refining	Robot Autonomous
WoZ++					Implementation of algorithm	WoZ + IML Teaching + Testing				Additional Teaching			

Domain experts and technical experts

Only technical experts

Only domain experts

Only robot