Emmanuel Senft

Curriculum Vitae - May 2021

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RESEARCH MISSION

To develop human-centered robotic tools for end-users to design effective robot behaviors in situ, to explore challenging environments with high cost of failure, large variability of tasks, and real-world application, and to enable robots to be used by anyone to impact positively our society.

EMPLOYMENT

- 2019–Current Research Associate, People and Robots Lab, University of Wisconsin–Madison, USA, PI: Prof. Bilge Mutlu and Prof. Michael Gleicher (since Oct. 2019).
 - 2019 **Cooperate Researcher**, *JSPS Summer program*, *IRC ATR*, Japan, PI: Prof. Takayuki Kanda (June to August 2019).

Research Fellow, *Plymouth University*,, UK, PI: Prof. Tony Belpaeme. part-time (January to March 2019)

2018 **Research Assistant**, *Plymouth University*, UK, PI: Prof. Tony Belpaeme.

EDUCATION

- 2014–2018 **PhD**, Plymouth University, Plymouth, UK, Teaching Robots Social Autonomy From In Situ Human Supervision.
 - Supervisory team: Prof. Tony Belpaeme, Dr. Paul Baxter, and Dr Séverin Lemaignan
- 2011–2013 Master of Science in Robotic and Autonomous Systems, EPFL (École Polytechnique Fédérale de Lausanne), Switzerland, with Minor in Area and Cultural Studies.

 Master thesis with Prof. Auke J. Ijspeert
- 2011–2013 **Bachelor of Science in Microengineering**, *EPFL (École Polytechnique Fédérale de Lausanne)*, Switzerland.

AWARD & FUNDING

- 2021 **National Robotics Initiative 3.0**: Collaboration on writing two research grants (under review).
 - Enabling Robotic Assistance in Construction Work

 Designing Social Companion Robots for Long-term Interaction
- 2019 **JSPS Summer Program**: 2 months research program with Prof. Takayuki Kanda at ATR, Japan.
- 2019 Queen Mary UK Best PhD in Robotics Award: Second position.

INVITED TALKS and PRESENTATIONS

- 2021 NASA Transformative Aeronautics Concepts Program (TACP) Showcase (online)
- 2020 HRI Lab University of Chicago (online)
- 2019 CHILI Lab EPFL (Lausanne, Switzerland)

Robot Learning and Interaction Lab - IDIAP (Martigny, Switzerland)

SELECTED PUBLICATIONS

Journals

2021 Corrective Shared Autonomy for Addressing Task Variability.
M. Hagenow, E. Senft, R. Radwin, M. Gleicher, B. Mutlu, and M. Zinn IEEE Robotics and Automation Letters 6 (2), 3720-3727.

A Socially Assistive Robot for Long-Term Cardiac Rehabilitation in the Real World.

N. Céspedes, B. Irfan, **E. Senft**, C. A. Cifuentes, L. F. Gutierrez, M. Rincon-Roncancio, T. Belpaeme, and M. Múnera,

Frontiers in Neurorobotics 15, 21.

2020 Social Assistive Robots: Assessing the Impact of a Training Assistant Robot in Cardiac Rehabilitation.

J. Casas, **E. Senft**, L. F. Gutiérrez, M. Rincón-Rocancio, M. Múnera, T. Belpaeme, and C. A. Cifuentes

International Journal of Social Robotics.

The DREAM Dataset: Supporting a Data-Driven Study of Autism Spectrum Disorder and Robot Enhanced Therapy.

E. Billing, ... , E. Senft, ... , and T. Ziemke

PloS one 15 (8), e0236939.

2019 Teaching Robots Social Autonomy From in Situ Human Guidance.

E. Senft, S. Lemaignan, PE. Baxter, and T. Belpaeme

Science Robotics 4 (35).

Generating Spatial Referring Expressions in a Social Robot: Dynamic vs Non-Ambiguous.

CD Wallbridge, S. Lemaignan, E. Senft, and T. Belpaeme

Frontiers in Robotics and Al 6 (2019): 67.

Robot-Enhanced Therapy: Developing and Validating a Supervised Autonomous Robotic System for Autism Spectrum Disorders Therapy.

HL. Cao, ..., E. Senft, ..., and T. Ziemke

EEE Robotics & Automation Magazine, vol. 26, no. 2.

2018 The PInSoRo dataset: Supporting the Data-Driven Study of Child-Child and Child-Robot Social Dynamics.

S. Lemaignan, C. Edmunds, E. Senft, and T. Belpaeme

PloS one 13 (10), e0205999.

A Personalized and Platform-Independent Behavior Control System for Social Robots in Therapy: Development and Applications.

H. L. Cao, G. Van de Perre, J. Kennedy, E. Senft, P. Gómez Esteban, A. De Beir, R. Simut,

T. Belpaeme, D. Lefeber, and B. Vanderborght

IEEE Transactions on Cognitive and Developmental Systems 11 (3).

2017 Supervised Autonomy for Online Learning in Human-Robot Interaction.

E. Senft, P. Baxter, J. Kennedy, S. Lemaignan, and T. Belpaeme

Pattern Recognition Letters.

How to Build a Supervised Autonomous System for Robot-Enhanced Therapy for Children with Autism Spectrum Disorder.

P. G. Esteban, ..., E. Senft, ..., T.Ziemke

Paladyn, Journal of Behavioral Robotics. De Gruyter Open.

Conferences

2020 Would You Mind Me if I Pass by You? Socially-Appropriate Behaviour for an Omnibased Social Robot in Narrow Environment.

E. Senft, S. Satake, and T. Kanda HRI, 2020.

2017 Child Speech Recognition in Human-Robot Interaction: Evaluations and Recom-

J. Kennedy, S. Lemaignan, C. Montassier, P. Lavalade, B. Irfan, F. Papadopoulos, **E. Senft**, and T. Belpaeme

HRI, 2017.

2016 Social Robot Tutoring for Child Second Language Learning.

J. Kennedy, P. Baxter, **E. Senft**, and T. Belpaeme HRI, 2016.

2015 SPARC: Supervised Progressively Autonomous Robot Competencies.

E. Senft, P. Baxter, J. Kennedy, and T. Belpaeme. ICSR, 2015.

Link to complete list with pdf

PRESS COVERAGE

2020 Financial Times. Opinion sought for "How AI eases teachers' heavy workloads"

Teacher Magazine. Interview for and research covered in "Using robots to assist teachers and improve student learning"

2019 **Financial Times.** Interview for and research covered in "Robot trained to be useful teaching assistant in three hours"

The Telegraph. Research covered in "British schools test 'robot teachers' to tackle staff shortage"

ACADEMIC SERVICES

EDITORIAL WORK

Frontiers in Robotics & AI, Guest Editor

REFEREE SERVICE

Journals

Scientific Reports

Frontiers in Robotics and Al

Robotics and Automation Letters

Journal of Human-Robot Interaction

IEEE Transactions in Human-Robot Interaction

International Journal of Social Robotics

Mechatronics

Intelligent Service Robotics

Interaction Studies Journal

Behaviour and Interaction Technology

Conferences

ACM/IEEE Human-Robot Interaction Conference (HRI)

Robotics: Science and Systems Conference (RSS)

IEEE International Conference on Robotics and Automation (ICRA)

IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)

IEEE-RAS Conference on Humanoid Robots

International Conference on Social Robotics (ICSR)

IEEE International Conference on Development and Learning and Epigenetic Robotics (ICDL-EpiRob)

International Conference on Human-Agent Interaction (HAI)

Towards Autonomous Robotic Systems Conference (TAROS)

IEEE International Symposium on Robot-Human Interactive Communication (Ro-Man)

EVENT ORGANIZATION

Wisonsin Robotics Seminar Series, Organizer

AAMAS 2019, PC Member

AAAI Symposium - Al-HRI (2017-), Program Chair / Committee member

HRI Workhop - Robots in Therapy and Care (2019), Committee member

TEACHING

Practical ROCO 318 - Mobile and Humanoid Robots at the University of Plymouth, *Demonstrator* (2015–2017)

MENTORING

Graduate Students: Michael Hagenow, Kevin Welsh, Anna Konstant, and Prajna Bhat

Undergraduate Students: Titus Smith, Yash Hindka

COLLABORATIONS

EDUCATION

Local schools (Plymouth, UK). Developing and evaluating robot tutoring solutions.

HEALTHCARE

Therapists (Babes-Bolyai University, Roumania), industry (Softbank Robotics EU) and academics in EU FP7 project. Developing therapy-driven robot applications for children with ASD.

Clinicians and hospital staff (Fundacion Cardioinfantil, Bogota, Colombia) and academics. Robot behaviours for cardiac rehabilitation.

MANUFACTURING

The Boeing Company, NASA, and academics in a NASA ULI project. Designing robot platform for collaborative aircraft manufacturing.

TELEVISION

Channel 4 (UK). Designing a teleoperation interface for the Pepper robot for the show: The Secret Life of 4 and 5 Year Olds.

TECHNICAL SKILLS

Research Academic writing, Study Design, Machine Learning (ANN, RL, Interactive Machine Learning)

Programming Python, QML, C++, ROS, YARP, Matlab

Robot Nao, Pepper, Robovie, Panda, Roombots

Software Solidworks, ProEngineer, Onshape, Blender, Cura (3D printing)

LANGUAGES

French Mother tongue

English Advanced Conversationally fluent and technical

Mandarin Basic Level A2

German Basic Level A2

INTERESTS

Martial Arts Judo, Kick-Boxing, Kung-fu, Vo-vietnam, Karate (Brown Belt)

Climbing Indoor and outdoor, from bouldering to leading

Skiing Ski and Snowboard

Scouts Team Leader from 2007 to 2013, member from 1998 to 2013