nonlinear_regression

August 2, 2025

1 Nonlinear Regression Predictor – Ice Cream Sales

1.0.1 Project Description:

This project explores nonlinear regression techniques to model the relationship between temperature and ice cream sales using a simple dataset from Kaggle. It begins with polynomial regression to capture the quadratic relationship and progresses to more advanced techniques, including learning both weights and exponents (learnable feature transformations). The project also implements k-fold cross-validation to evaluate model generalization and prevent overfitting.

1.0.2 Objectives:

- Load and explore a real-world ice cream selling dataset from Kaggle
- Visualize the relationship between temperature and sales to motivate the use of polynomial regression
- Implement polynomial regression from scratch, including design matrix construction and gradient descent optimization
- Extend the approach to support learnable exponents for flexible feature transformation
- Evaluate model performance using mean squared error (MSE) and visualize the fitted regression curve

1.0.3 Public dataset source:

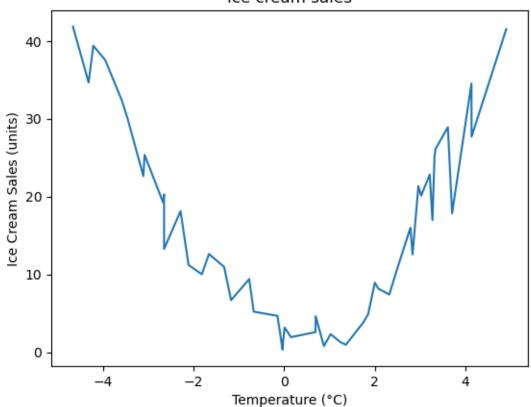
Kaggle Ice Cream Selling Data Set The data contains information on the temperature and the corresponding number of units of ice cream sold

```
[2]: # Import libraries
import pandas as pd
import numpy as np
import matplotlib.pyplot as plt
import seaborn as sns
from matplotlib.ticker import FuncFormatter
from sklearn.metrics import r2_score
```

```
[3]: # Establish file path and import data
path = 'ice_cream_sales.csv'
df = pd.read_csv(path)
df.head()
```

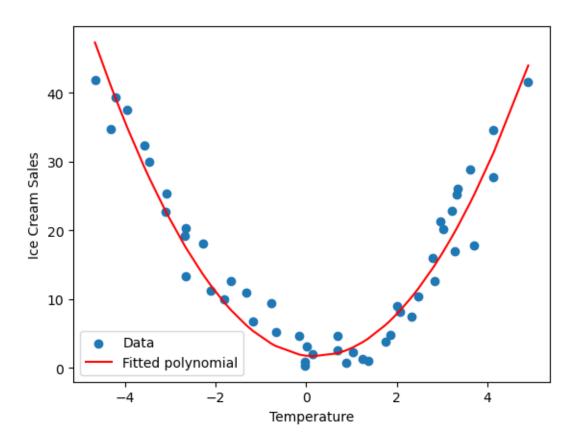
```
[3]:
        Temperature (°C)
                          Ice Cream Sales (units)
     0
               -4.662263
                                         41.842986
     1
               -4.316559
                                         34.661120
     2
               -4.213985
                                         39.383001
               -3.949661
     3
                                         37.539845
     4
               -3.578554
                                         32.284531
[4]: df.describe()
[4]:
            Temperature (°C)
                              Ice Cream Sales (units)
                   49.000000
     count
                                             49.000000
                    0.271755
                                             15.905308
    mean
     std
                    2.697672
                                             12.264682
    min
                   -4.662263
                                              0.328626
     25%
                   -2.111870
                                              4.857988
     50%
                    0.688781
                                             12.615181
     75%
                    2.784836
                                             25.142082
    max
                    4.899032
                                             41.842986
[]: plt.plot(df['Temperature (°C)'],df['Ice Cream Sales (units)'])
     plt.title('Ice Cream Sales')
     plt.xlabel('Temperature (°C)')
     plt.ylabel('Ice Cream Sold (units)')
[]: Text(0, 0.5, 'Ice Cream Sales (units)')
```

Ice cream sales



```
[5]: # Relationship looks quadratic, so a polynomial degree of 2
      X = df['Temperature (°C)'] # Input
      y = df['Ice Cream Sales (units)'] # Target
[40]: # Define function to construct b matrix from transforming X in higher dimensions
      def b(X, p):
          n = len(X)
          \# b = np.zeros((n, p + 1)) \# Initialize b matrix
          for j in range(n): # Index over rows (samples)
              for i in range(p): # Index over columns (degree)
                  b[j,i] = X[j] **i # Generate a row of features for each sample
          return b
[21]: def nonlinear_model(X,y,W,b, alpha = 0.001, n_iterations=1000):
          N = len(X)
          loss_history = [] # Initialize loss history
          for i in range(n_iterations):
              # y_hat = np.dot(b.T, W)
              y_hat = b @ W # Prediction equation
              resid = y_hat - y # Error
```

```
grad = (2/N) * (b.T @ resid) # Gradient descent
              W -= alpha * grad # Update weights
              mse = np.mean(resid ** 2) # Calculate loss
              loss_history.append(mse)
              if i % 100 == 0:
                  print(f"Iteration {i}: Loss = {mse:.4f}")
          return W, loss_history
 []: # Choose zeroes as W
      degree = 3
      W = np.zeros(degree + 1)
      B = b(X, degree)
      W, loss_history = nonlinear_model(X,y,W,B)
     Iteration 0: Loss = 400.3314
     Iteration 100: Loss = 13.1364
     Iteration 200: Loss = 12.4252
     Iteration 300: Loss = 12.0310
     Iteration 400: Loss = 11.7105
     Iteration 500: Loss = 11.4411
     Iteration 600: Loss = 11.2143
     Iteration 700: Loss = 11.0233
     Iteration 800: Loss = 10.8624
     Iteration 900: Loss = 10.7268
[28]: # Graph prediction
      X_sorted = np.sort(X) # Put the x values in order
      B sorted = b(X_sorted, degree) # Build polynomial features for sorted points
      y_pred = B_sorted @ W # Compute predictions for the line, based on model's_{\sqcup}
       \hookrightarrow parameters
      plt.scatter(X, y, label="Data") # Original scatterplot
      plt.plot(X_sorted, y_pred, color="red", label="Fitted polynomial") # Fitted_
       \hookrightarrow curve
      plt.xlabel("Temperature")
      plt.ylabel("Ice Cream Sales")
      plt.legend()
      plt.show()
```



```
[]: # Try with random W initialization
W = np.random.randn(degree + 1) * 0.01 # Small normally distributed random
→ numbers
W, loss_history = nonlinear_model(X,y,W,B)
# Similar loss as initializing with zeroes
```

```
Iteration 0: Loss = 399.5587
Iteration 100: Loss = 13.1402
Iteration 200: Loss = 12.4310
Iteration 300: Loss = 12.0360
Iteration 400: Loss = 11.7147
Iteration 500: Loss = 11.4447
Iteration 600: Loss = 11.2173
Iteration 700: Loss = 11.0258
Iteration 800: Loss = 10.8645
Iteration 900: Loss = 10.7286
```

1.1 Learnable Feature Transformations

In the case of classic polynomial regression, the degree is fixed and exponents are known. Only w parameters are learned.

For a learnable-exponent model, on the other hand, while the degree (or number of terms) is still fixed, the exponents (v1, v2, v3, etc.) are learned. This means that v can be fractional, non-integer, negative, etc.

```
[]: def b(X, v):
         n = len(X) # Number of samples
         p = len(v) # Degree of polynomial
         b = np.zeros((n, p + 1)) # Initialize b matrix
         b[:, 0] = 1 # Constant term (bias w0)
         for i in range(p):
             b[:, i+1] = X ** v[i]
         return b
     def model_features(X,y,theta,b, alpha = 0.001, n_iterations=1000):
         N = len(X)
         p = (len(theta) - 1) // 2
         loss_history = [] # Initialize loss history
         for i in range(n_iterations):
             \# Separate w and v from theta vector
             w = theta[:p+1] # First p+1 params are w_i
             v = theta[p+1:] # Remaining p params are v_i
             # Build b matrix dynamically based on current v
             b = np.zeros((N, p+1))
             b[:, 0] = 1
             for j in range(p):
                 b[:, j+1] = X ** v[j]
             y_hat = b @ W # Prediction equation
             resid = y_hat - y # Error
             # Gradient descent
             grad_w = (2/N) * (b.T @ resid)
             grad_v = np.zeros(p) # Gradient w.r.t v
             for j in range(p):
                 term = (X ** v[j]) * np.log(X)
                 grad_v[j] = (2/N) * np.sum(resid * w[j+1] * term)
             # Combine gradients into one theta gradient
             grad = np.concatenate([grad_w, grad_v])
             mse = np.mean(resid ** 2) # Calculate loss
             loss_history.append(mse)
             if i % 100 == 0:
                 print(f"Iteration {i}: Loss = {mse:.4f}")
         return theta, loss_history
```

```
[]: p = 3  # Allow up to cubic powers
w_init = np.zeros(p+1)  # Start weights at 0 or small random values
v_init = np.arange(1, p+1)  # Initialize exponents to 1, 2, 3

theta_init = np.concatenate([w_init, v_init])
B = b(X,v_init)
theta_trained, loss_history = model_features(X, y, theta_init, B)

# This approach resulted in a slightly better performance according to the loss_u
function
```

```
Iteration 0: Loss = 10.6127

Iteration 100: Loss = 10.6127

Iteration 200: Loss = 10.6127

Iteration 300: Loss = 10.6127

Iteration 400: Loss = 10.6127

Iteration 500: Loss = 10.6127

Iteration 600: Loss = 10.6127

Iteration 700: Loss = 10.6127

Iteration 800: Loss = 10.6127

Iteration 900: Loss = 10.6127
```