```
import autograd.numpy as np # We need to use this numpy wrapper to
make automatic differentiation work later
from autograd import grad, elementwise grad
from sklearn import datasets
import matplotlib.pyplot as plt
from sklearn.metrics import accuracy score
# Defining some activation functions
def ReLU(z):
    return np.where(z > 0, z, 0)
# Derivative of the ReLU function
def ReLU der(z):
    return np.where(z > 0, 1, 0)
def sigmoid(z):
    return 1 / (1 + np.exp(-z))
def mse(predict, target):
    return np.mean((predict - target) ** 2)
```

Exercise 2a)

The shape of weights and biases will be determined based on the input and output sizes of the network. In this case, the input size will be 2, and the output size will be 3.

```
# Exercise 2b)
def feed_forward_one_layer(W, b, x):
    z = W @ x + b
    a = sigmoid(z)
    return a
def cost one layer(W, b, x, target):
    predict = feed forward one layer(W, b, x)
    return mse(predict, target)
x = np.random.rand(2)
target = np.random.rand(3)
W = np.random.randn(len(target), len(x))
b = np.random.randn(len(target))
# Exercise 2c)
autograd one layer = grad(cost one layer, [0, 1])
W g, b g = autograd one layer(W, b, x, target)
print(W g, b g)
```

```
[[-0.0806643 -0.04842969]
[-0.0281288 -0.01688813]
[-0.04492729 -0.0269737 ]] [-0.08157134 -0.0284451 -0.04543248]
```

Exercise 3a)

The reusable results are dC/da and da/dz.

```
# Exercise 3b)
z = W @ x + b
a = sigmoid(z)
predict = a
def mse der(predict, target):
    return 2/len(predict) * (predict - target)
print(mse der(predict, target))
cost autograd = grad(mse, 0)
print(cost autograd(predict, target))
[-0.3264923 -0.13291599 -0.49424357]
[-0.3264923 -0.13291599 -0.49424357]
# Exercise 3c)
def sigmoid der(z):
    return sigmoid(z) * (1 - sigmoid(z))
print(sigmoid der(z))
sigmoid autograd = elementwise grad(sigmoid, 0)
print(sigmoid_autograd(z))
[0.24984155 0.2140081 0.09192326]
[0.24984155 0.2140081 0.09192326]
# Exercise 3d)
dC_da = mse_der(a, target)
dC dz = dC da * sigmoid der(z)
print(dC da.shape, dC dz.shape)
print(sigmoid_der(z).shape)
(3,)(3,)
(3,)
# Exercise 3e)
dz_dW = np.tensordot(np.eye(len(target)), x, axes=0)
dz db = np.ones(len(b))
```

```
# Exercise 3f)
dC da = mse der(a, target)
dC_dz = dC_da * sigmoid_der(z)
dC dW = dC dz @ dz dW
dC db = dC dz * dz db
print(dC_dW, dC_db)
[[-0.0806643 -0.04842969]
 [-0.0281288 -0.01688813]
 [-0.04492729 -0.0269737 ]] [-0.08157134 -0.0284451 -0.04543248]
W_g, b_g = autograd_one_layer(W, b, x, target)
print(W g, b g)
[[-0.0806643 -0.04842969]
[-0.0281288 -0.01688813]
[-0.04492729 -0.0269737 ]] [-0.08157134 -0.0284451 -0.04543248]
x = np.random.rand(2)
target = np.random.rand(4)
W1 = np.random.rand(3, 2)
b1 = np.random.rand(3)
W2 = np.random.rand(4, 3)
b2 = np.random.rand(4)
layers = [(W1, b1), (W2, b2)]
z1 = W1 @ x + b1
a1 = sigmoid(z1)
z2 = W2 @ a1 + b2
a2 = sigmoid(z2)
# Exercise 4a)
dC da2 = mse der(a2, target) # OK
dC dz2 = dC da2 * sigmoid der(z2) # check vector as exponent
dC dW2 = dC dz2 @ np.tensordot(np.eye(len(z2)), a1, axes=0)
dC db2 = dC dz2 # deriv wrt b2 is 1
```

Exercise 4b)

The derivative of the second layer intermediate z2 wrt. the first layer activation a1 is a row vector where each entry is the sum of the corresponding row in the matrix.

```
# Exercise 4c)
dC_dal = dC_dz2 @ W2 # OK
dC_dz1 = dC_dal * sigmoid_der(z1) # check vector as exponent
dC_dW1 = dC_dz1 @ np.tensordot(np.eye(len(z1)), x, axes=0) # OK
dC_dbl = dC_dzl # deriv wrt bl is 1
```

```
print(dC dW1, dC db1)
print(dC dW2, dC db2)
[[0.00412035 0.00806305]
 [0.00421007 0.00823863]
 [0.00358914 0.00702353]] [0.00812245 0.00829932 0.00707527]
[[-0.01723865 -0.02157461 -0.02236588]
 [ 0.03704805  0.04636658  0.04806713]
 [ 0.02956084  0.03699614  0.038353021
 [0.00109094 \ 0.00136534 \ 0.00141542]] [-0.02825852 \ 0.06073115]
0.04845771 0.00178833]
# Exercise 4d)
def feed forward two layers(layers, x):
    W1, b1 = layers [0]
    z1 = W1 @ x + b1
    a1 = sigmoid(z1)
    W2, b2 = layers[1]
    z2 = W2 @ a1 + b2
    a2 = sigmoid(z2)
    return a2
def cost two layers(layers, x, target):
    predict = feed_forward_two_layers(layers, x)
    return mse(predict, target)
grad two layers = grad(cost two layers, 0)
grad two layers(layers, x, target)
[(array([[0.00412035, 0.00806305],
         [0.00421007, 0.00823863],
         [0.00358914, 0.00702353]]),
  array([0.00812245, 0.00829932, 0.00707527])),
 (array([[-0.01723865, -0.02157461, -0.02236588],
         [ 0.03704805, 0.04636658, 0.04806713],
         [ 0.02956084, 0.03699614, 0.03835302],
         [ 0.00109094, 0.00136534, 0.00141542]]),
  array([-0.02825852, 0.06073115, 0.04845771, 0.00178833]))]
```

Exercise 4e)

The first derivative (the cost function) will be used one time on the outer layer. On the layer in question, we differentiate wrt W or b, but for intermediate layers we differentiate the activation functions and application of weight and bias over and over, until we reach the layer we are interested in.

```
def create layers(network input size, layer output sizes):
    layers = []
    i size = network input size
    for layer output size in layer output sizes:
        W = np.random.randn(layer output size, i size)
        b = np.random.randn(layer_output_size)
        layers.append((W, b))
        i size = layer output size
    return layers
def feed forward(input, layers, activation funcs):
    a = input
    for (W, b), activation func in zip(layers, activation funcs):
        z = W @ a + b
        a = activation func(z)
    return a
def cost(layers, input, activation funcs, target):
    predict = feed forward(input, layers, activation funcs)
    return mse(predict, target)
def feed forward saver(input, layers, activation funcs):
    layer inputs = []
    zs = []
    a = input
    for (W, b), activation func in zip(layers, activation funcs):
        layer_inputs.append(a)
        z = W @ a + b
        a = activation func(z)
        zs.append(z)
    return layer_inputs, zs, a
# Exercise 5a)
def backpropagation(
    input, layers, activation funcs, target, activation ders,
cost der=mse der
):
    layer inputs, zs, predict = feed forward saver(input, layers,
activation funcs)
    layer grads = [() for layer in layers]
    # We loop over the layers, from the last to the first
    for i in reversed(range(len(layers))):
        layer input, z, activation der = layer inputs[i], zs[i],
```

```
activation ders[i]
        if i == len(layers) - 1:
            # For last layer we use cost derivative as dC da(L) can be
computed directly
            dC da = cost der(predict, target)
        else:
            # For other layers we build on previous z derivative, as
dC da(i) = dC dz(i+1) * dz(i+1)_da(i)
            (W, b) = layers[i + 1]
            dC da = dC dz @ W
        dC dz = dC da * activation der(z)
        dC dW = dC dz @ np.tensordot(np.eye(len(z)), layer input,
axes=0)
        dC db = dC dz # deriv wrt b is 1
        layer grads[i] = (dC dW, dC db)
    return layer grads
network input size = 2
layer output sizes = [3, 4]
activation funcs = [sigmoid, ReLU]
activation ders = [sigmoid der, ReLU der]
layers = create layers(network input size, layer output sizes)
x = np.random.rand(network input size)
target = np.random.rand(4)
layer grads = backpropagation(x, layers, activation funcs, target,
activation ders)
print(layer grads)
cost grad = grad(cost, 0)
cost grad(layers, x, [sigmoid, ReLU], target)
[(array([[ 0.0040953 , 0.04639799],
       [ 0.05674624, 0.64290998],
       [-0.00898892, -0.10184046]]), array([ 0.05622079,  0.77901893,
-0.12340087])), (array([[0.00175181, 0.00429662, 0.00061569],
       [0.20018365, 0.49098549, 0.07035625],
       [0.06733028, 0.16513931, 0.0236638],
       [0.1903718 , 0.46692022, 0.06690779]]), array([0.00660111,
0.75432519, 0.25371165, 0.71735252]))]
[(array([[ 0.0040953 , 0.04639799],
         [ 0.05674624, 0.64290998],
         [-0.00898892, -0.10184046]]),
  array([ 0.05622079, 0.77901893, -0.12340087])),
```

```
(array([[0.00175181, 0.00429662, 0.00061569],
         [0.20018365, 0.49098549, 0.07035625],
         [0.06733028, 0.16513931, 0.0236638],
         [0.1903718 , 0.46692022, 0.06690779]]),
 array([0.00660111, 0.75432519, 0.25371165, 0.71735252]))]
# Exercise 6
def create layers batch(network input size, layer output sizes):
    lavers = []
    i size = network input size
    for layer output size in layer output sizes:
        W = np.random.randn(layer output size, i size).T
        b = np.random.randn(layer output size)
        layers.append((W, b))
        i size = layer output size
    return layers
def feed forward batch(inputs, layers, activation funcs):
    a = inputs
    for (W, b), activation_func in zip(layers, activation_funcs):
        z = a @ W + b
        a = activation func(z)
    return a
def cost batch(layers, inputs, activation funcs, target):
    predict = feed_forward_batch(inputs, layers, activation_funcs)
    return mse(predict, target)
def feed_forward_saver_batch(inputs, layers, activation funcs):
    layer inputs = []
    zs = []
    a = inputs
    for (W, b), activation func in zip(layers, activation funcs):
        layer inputs.append(a)
        z = a @ W + b
        a = activation func(z)
        zs.append(z)
    return layer inputs, zs, a
def backpropagation batch(inputs, layers, activation funcs, target,
activation ders, cost der=mse der):
    layer inputs, zs, predict = feed forward saver batch(inputs,
layers, activation funcs)
    layer grads = [None] * len(layers)
    for i in reversed(range(len(layers))):
```

```
layer input, z, activation der = layer inputs[i], zs[i],
activation ders[i]
        if i == len(layers) - 1:
            # For last layer we use cost derivative as dC da(L) can be
computed directly
            dC da = cost der(predict, target)
        else:
            # For other layers we build on previous z derivative, as
dC \ da(i) = dC \ dz(i+1) * dz(i+1) \ da(i)
            (W, b) = layers[i + 1]
            dC da = dC dz @ W.T
        dC dz = dC da * activation_der(z)
        dC dW = layer input.T @ dC dz / len(layers[-1][1])
        dC_db = np.mean(dC_dz, axis=0) / len(layers[-1][1]) *
len(layer input) # deriv wrt b is 1
        layer grads[i] = (dC dW, dC db)
    return layer grads
number of datapoints = np.random.randint(2, 20)
network input size = np.random.randint(2, 20)
final output size = np.random.randint(2, 20)
inputs = np.random.rand(number of datapoints, network input size)
layer output sizes = [5, 2, final output size]
activation funcs = [sigmoid, ReLU, sigmoid]
activation ders = [sigmoid der, ReLU der, sigmoid der]
layers = create layers batch(network input size, layer output sizes)
target = np.random.rand(number of datapoints, final output size)
layer grads = backpropagation batch(inputs, layers, activation funcs,
target, activation ders)
print("Number of datapoints:", number of datapoints)
print("Network input size:", network_input_size)
print("Final output size:", final_output_size)
print("Our gradients:")
for i in range(len(layer grads)):
    print(i, layer grads[i][1])
print("Autograd:")
cost grad = grad(cost batch, 0)
w autograd = cost grad(layers, inputs, activation funcs, target)
for i in range(len(w autograd)):
    print(i, w autograd[i][1])
```

```
Number of datapoints: 17
Network input size: 19
Final output size: 7
Our gradients:
0 [ 1.68184154e-03 -2.09762290e-03 6.76325518e-03 4.85893527e-05
-1.92748982e-03]
              0.04003649]
1 [0.
2 [-0.00455653  0.00685776  0.01933652  0.00962605  0.01221039 -
0.00951721
 -0.00247036]
Autograd:
0 [ 1.68184154e-03 -2.09762290e-03 6.76325518e-03 4.85893527e-05
 -1.92748982e-031
              0.040036491
2 [-0.00455653  0.00685776  0.01933652  0.00962605  0.01221039 -
0.00951721
 -0.002470361
# Exercise 7a)
. . .
# Exercise 7b)
. . .
```

We were not able to complete exercise 7 in time, but will hopefully have time to update the submission during the weekend. If not, you will see the training implementation in the final project.