

2025-02-13 Progress rate comparison Gaussian vs. Double Geometric

Comparing Mutation Distributions on a Simple Ellipsoid

In this experiment, we compare two integer mutation operators when optimizing a simple ellipsoid function

$$f(x) = \lambda_1 x_1^2 + \lambda_2 x_2^2,$$

with $\lambda_1 = 1.0$ and $\lambda_2 = 2.0$. The optimum is at $(0, 0)$.

We consider two mutation operators:

- **Double Geometric Mutation:**

Samples integer steps from a symmetric discrete Laplace (double geometric) distribution with

$$P(k) = \begin{cases} \frac{1-p}{1+p} & k = 0, \\ \frac{1-p}{1+p} p^{|k|} & k \neq 0, \end{cases}$$

where $p = \exp(-1/\sigma)$.

- **Gaussian Mutation:**

Samples from a bivariate Gaussian with independent coordinates (with standard deviations σ_1 and σ_2) and then rounds the results to the nearest integer.

For both operators, we assume the same domain and use integer truncation.

Tuning and Comparison

For a given parent point

$$x_{\text{parent}} = (d, d),$$

(with $d \geq 0$, so the distance to the optimum is $\sqrt{2}d$), we perform a grid search over σ_1 and σ_2 in $[0.1, 10]$ to determine the optimum expected progress rate

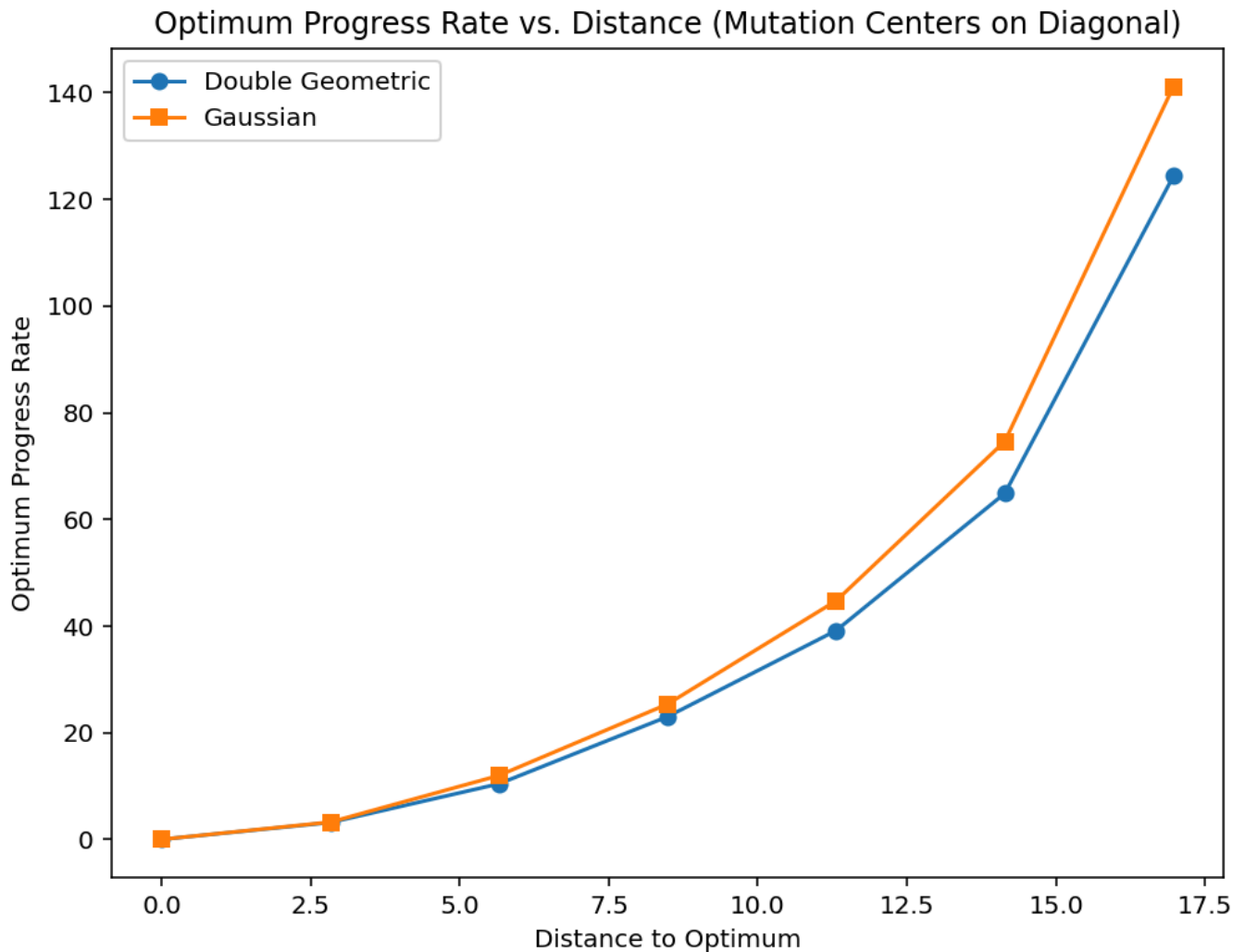
$$\Delta f = \max\{0, f(x_{\text{parent}}) - f(x_{\text{offspring}})\}.$$

The progress rate is averaged over many offspring generated by adding a mutation step

$$x_{\text{offspring}} = x_{\text{parent}} + (\delta_1, \delta_2),$$

with each coordinate mutated independently.

We then plot the optimum progress rates achieved by each distribution as a function of the distance from the optimum.



Below is the complete source code.

```
import numpy as np
import matplotlib.pyplot as plt

def ellipsoid(x, lambdas=(1.0, 2.0)):
    """
    Computes  $f(x) = x_1^2 + 2 x_2^2$  for an integer vector  $x$ .
    """
    x = np.array(x, dtype=int)
    return lambdas[0] * x[0]**2 + lambdas[1] * x[1]**2

def sample_double_geometric(sigma, size=None):
```

```

"""
Samples integer offsets from a symmetric double geometric (discrete
Laplace)
distribution.

PMF:

$$P(k) = \begin{cases} (1-p)/(1+p) & \text{if } k = 0, \\ (1-p)/(1+p)*p^{|k|} & \text{if } k \neq 0, \end{cases}$$

with  $p = \exp(-1/\sigma)$ .
"""
p = np.exp(-1.0 / sigma)
if size is None:
    u = np.random.rand()
    threshold = (1 - p) / (1 + p)
    if u < threshold:
        return 0
    else:
        n = np.random.geometric(p=1 - p)
        return np.random.choice([-1, 1]) * n
else:
    u = np.random.rand(*np.atleast_1d(size))
    threshold = (1 - p) / (1 + p)
    samples = np.zeros(u.shape, dtype=int)
    idx = (u >= threshold)
    if np.any(idx):
        n = np.random.geometric(p=1 - p, size=np.sum(idx))
        samples[idx] = np.random.choice([-1, 1], size=np.sum(idx)) * n
    return samples

def sample_gaussian(sigma, size=None):
    """
    Samples from a Gaussian with mean 0 and standard deviation sigma,
    then rounds to the nearest integer.
    """
    if size is None:
        return int(np rint(np.random.normal(0, sigma)))
    else:
        return np rint(np.random.normal(0, sigma, size)).astype(int)

def compute_progress_rate(x, sigma1, sigma2, sample_func, num_samples=5000,
                           lambdas=(1.0, 2.0), lower_bound=-12,
                           upper_bound=12):
    """
    For a given parent x, estimates the expected progress rate using mutations
    sampled by sample_func with parameters sigma1 and sigma2.

```

Progress is defined as:

$$\Delta f = \max\{0, f(x_{\text{parent}}) - f(x_{\text{offspring}})\}.$$

Mutations resulting in (0,0) are discarded and re-sampled.

Resampling is attempted in batches and limited to at most 40 iterations.

"""

```
x = np.array(x, dtype=int)
f_parent = ellipsoid(x, lambdas)
valid_offspring = []
batch_size = num_samples # generate this many mutations per iteration
iterations = 0
max_iterations = 40 # limit resampling iterations
while len(valid_offspring) < num_samples and iterations < max_iterations:
    iterations += 1
    delta1 = sample_func(sigma1, size=batch_size)
    delta2 = sample_func(sigma2, size=batch_size)
    # Exclude mutations where both coordinates are zero.
    valid = ~((delta1 == 0) & (delta2 == 0))
    if np.sum(valid) > 0:
        valid_d1 = delta1[valid]
        valid_d2 = delta2[valid]
        new_offspring = np.vstack((x[0] + valid_d1, x[1] + valid_d2)).T
        new_offspring = np.clip(new_offspring, lower_bound, upper_bound)
        valid_offspring.extend(new_offspring.tolist())
    if len(valid_offspring) == 0:
        return 0
valid_offspring = np.array(valid_offspring[:num_samples])
f_offspring = np.array([ellipsoid(o, lambdas) for o in valid_offspring])
improvements = f_parent - f_offspring
improvements[improvements < 0] = 0
return np.mean(improvements)
```

Tuning Procedure with Mutation Centers on the Diagonal

Parent centers are placed on the diagonal: x = (d, d)

d_values = np.arange(0, 13, 2) # d = 0, 2, 4, ..., 12

sigma_range = np.linspace(0.1, 10.0, 20) # grid for sigma1 and sigma2

opt_progress_double = [] # optimum progress for double geometric mutation

opt_progress_gaussian = [] # optimum progress for Gaussian mutation

distances = [] # Euclidean distance from the optimum

for d in d_values:

parent = np.array([d, d], dtype=int)

distance = np.linalg.norm(parent)

```

distances.append(distance)

progress_matrix_double = np.zeros((len(sigma_range), len(sigma_range)))
progress_matrix_gaussian = np.zeros((len(sigma_range), len(sigma_range)))

for i, s1 in enumerate(sigma_range):
    for j, s2 in enumerate(sigma_range):
        progress_matrix_double[i, j] = compute_progress_rate(parent, s1,
s2, sample_double_geometric, num_samples=5000)
        progress_matrix_gaussian[i, j] = compute_progress_rate(parent, s1,
s2, sample_gaussian, num_samples=5000)

    opt_progress_double.append(np.max(progress_matrix_double))
    opt_progress_gaussian.append(np.max(progress_matrix_gaussian))
    print(f"d = {d}, distance = {distance:.2f} | Double Geometric:
{np.max(progress_matrix_double):.3f}, Gaussian:
{np.max(progress_matrix_gaussian):.3f}")

plt.figure(figsize=(8, 6))
plt.plot(distances, opt_progress_double, marker='o', label='Double Geometric')
plt.plot(distances, opt_progress_gaussian, marker='s', label='Gaussian')
plt.xlabel("Distance to Optimum")
plt.ylabel("Optimum Progress Rate")
plt.title("Optimum Progress Rate vs. Distance (Mutation Centers on Diagonal)")
plt.legend()
plt.show()

```