

# **MAT211: Calculus-II**

Lecture Notes

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# 1 Lecture-01

**Question:** what did we mean by the derivative  $f'(a)$ ?

**Answer:** Let  $U$  be an open subset of  $\mathbb{R}$  and  $f : U \rightarrow \mathbb{R}$  a function. Then  $f$  is differentiable at  $a$ , with derivative  $m$ , if and only if

$$\lim_{h \rightarrow 0} \frac{1}{h} \left( \underbrace{f(a+h) - f(a)}_{\Delta f} - \underbrace{mh}_{(*)} \right) = 0 \quad (1)$$

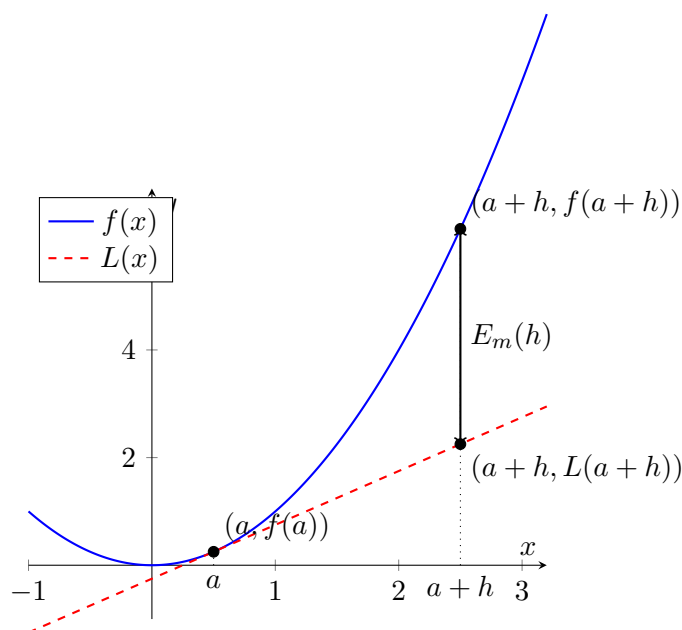
$(*)$  : linear function of  $\Delta x = h$ .

**Question:** Why impose the domain  $U$  that needs to be an open set?

**Answer:** Write the answer.

The function  $mh$  that multiplies  $h$  by the derivative  $m$  is thus a linear function of the change in  $x$ . This definition emphasizes the idea that a function  $f$  is differentiable at a point  $a$  if the increment  $\Delta f$  to the function is well approximated by a linear function of the increment  $h$  to the variable, this linear function is  $f'(a)h$ . Let's see how we can confirm that:

Suppose  $f(x)$  is our desired function and we want to approximate the function in the neighborhood at  $x = a$ . For this purpose, we will draw several straight lines through the point  $(a, f(a))$  and see which line approximates the function best. Here, the best means, the linear line should approximate the function well at  $x = a + h$ . Suppose the slope of that linear function is  $m$ .



Then,

$$\begin{aligned} \frac{L(a+h) - L(a)}{a+h-a} &= m \\ \frac{L(a+h) - f(a)}{h} &= m \\ L(a+h) &= f(a) + mh \end{aligned}$$

Now, we want to minimize the error,  $E_m(h) = f(a+h) - L(a+h)$ . Hence, we need to find the optimal value for  $m$ , for which:

$$\frac{E_m(h)}{h} \rightarrow 0$$

$$\boxed{\text{optimal } m \iff \lim_{h \rightarrow 0} \frac{E_m(h)}{h} = 0}$$

A simple computation show that,

$$\lim_{h \rightarrow 0} \frac{E_m(h)}{h} = \lim_{h \rightarrow 0} \frac{f(a+h) - f(a) - mh}{h} = 0$$

which is the desired condition 1, we showed in the definition.

## 2 Lecture-02

**Definition 2.1** (Euclidean Vector Space). A Euclidean vector space is a finite-dimensional inner product space over  $\mathbb{R}$ .

**Definition 2.2** (Inner product space). An inner product space is a vector space  $V$  over the field  $F$  together with an inner product, that is, a map

$$\langle \cdot, \cdot \rangle : V \times V \rightarrow F$$

that satisfies the following three properties for all vectors  $x, y, z \in V$  and all scalars  $a, b \in F$ .

1. (Symmetry)  $\langle x, y \rangle = \langle y, x \rangle$ .
2. (Linearity in the first argument)  $\langle ax + by, z \rangle = a\langle x, z \rangle + b\langle y, z \rangle$ .
3. (Positive-definiteness) If  $x \neq 0$  then,  $\langle x, x \rangle > 0$ .

**Example 2.3.** Verify that the dot product function  $\langle \cdot, \cdot \rangle : \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$  is an inner product.

To verify this we must prove the three conditions shown above. Let  $u = (a, b)$  and  $v = (c, d)$ . Then,

1.  $\langle u, v \rangle = ac + bd = ca + db = \langle v, u \rangle$ .
2. Let  $a, b \in \mathbb{R}$  and  $u, v, w \in \mathbb{R}^2$  with  $u = (u_1, u_2), v = (v_1, v_2), w = (w_1, w_2)$ . Then

$$\begin{aligned} \langle au + bv, w \rangle &= (au_1 + bv_1)w_1 + (au_2 + bv_2)w_2 \\ &= au_1w_1 + bv_1w_1 + au_2w_2 + bv_2w_2 \\ &= a(u_1w_1 + u_2w_2) + b(v_1w_1 + v_2w_2) \\ &= a\langle u, w \rangle + b\langle v, w \rangle. \end{aligned}$$

3. For any  $u = (u_1, u_2)$ ,

$$\langle u, u \rangle = u_1^2 + u_2^2.$$

Since squares of non-zero numbers are positive, we have  $u_1^2 > 0, u_2^2 > 0$  and therefore,  $\langle u, u \rangle > 0$ .

**Definition 2.4** (Informal). Define **norm** of a vector  $x \in V$  as

$$\|x\| = \sqrt{\langle x, x \rangle}.$$

**Definition 2.5** (Metric Space). A metric space is an ordered pair  $(M, d)$  where  $M$  is a set and  $d$  is a **metric** (distance) on  $M$ , i.e., a function

$$d : M \times M \rightarrow \mathbb{R}$$

satisfying the following axioms for all points  $x, y, z \in M$  :

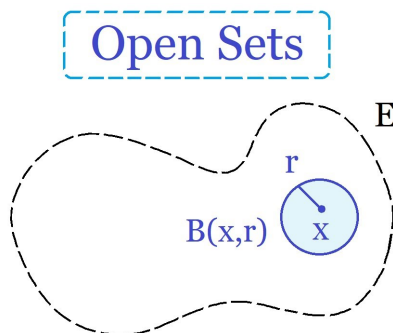
1.  $d(x, y) \geq 0$ ;
2.  $d(x, y) = 0 \iff x = y$  ;

3.  $d(x, y) = d(y, x)$ .
4.  $d(x, z) \leq d(x, y) + d(y, z)$ .

**Example 2.6** (Tax-cab Metric). In  $\mathbb{R}^2$ , the taxi-cab distance between  $p = (p_1, p_2)$  and  $q = (q_1, q_2)$  is  $|q_1 - p_1| + |q_2 - p_2|$ . It is easy to verify that this is a metric.

**Definition 2.7** (Open ball). For any  $x \in \mathbb{R}^n$  and any  $r > 0$ , the **open ball** of radius  $r$  around  $x$  is the subset

$$B_r(x) = \{y \in \mathbb{R}^n \mid |x - y| < r\}.$$



**Definition 2.8** (Open sets of  $\mathbb{R}^n$ ). A subset  $U \in \mathbb{R}^n$  is open if for every point  $x \in U$ , there exists  $r > 0$  such that the open ball  $B_r(x)$  is contained in  $U$ .

**Example 2.9.** We prove that the Cartesian product  $(a_1, b_1) \times (a_2, b_2)$  of two open intervals in  $\mathbb{R}$  is an open set in  $\mathbb{R}^2$  with the standard Euclidean topology.

*Proof.* Let  $d$  denote the Euclidean metric on  $\mathbb{R}^2$ :

$$d((x_1, y_1), (x_2, y_2)) = \sqrt{(x_1 - x_2)^2 + (y_1 - y_2)^2}.$$

Take an arbitrary point  $p = (x, y) \in (a_1, b_1) \times (a_2, b_2)$ . Then

$$a_1 < x < b_1, \quad a_2 < y < b_2.$$

Define the four positive distances to the endpoints:

$$d_1 = x - a_1, \quad d_2 = b_1 - x, \quad d_3 = y - a_2, \quad d_4 = b_2 - y.$$

Let

$$r = \min\{d_1, d_2, d_3, d_4\} > 0.$$

We claim that the open ball  $B(p, r) = \{q \in \mathbb{R}^2 : d(p, q) < r\}$  is contained in  $(a_1, b_1) \times (a_2, b_2)$ .

Indeed, take any point  $q = (u, v) \in B(p, r)$ . Then

$$|u - x| \leq d(p, q) < r, \quad |v - y| \leq d(p, q) < r.$$

Hence

$$x - r < u < x + r, \quad y - r < v < y + r.$$

Because  $r \leq x - a_1$  and  $r \leq b_1 - x$ , we have

$$a_1 \leq x - r < u < x + r \leq b_1,$$

so  $u \in (a_1, b_1)$ . Similarly,  $r \leq y - a_2$  and  $r \leq b_2 - y$  imply

$$a_2 \leq y - r < v < y + r \leq b_2,$$

so  $v \in (a_2, b_2)$ . Consequently  $q = (u, v) \in (a_1, b_1) \times (a_2, b_2)$ .

Thus every point of the product has an open neighbourhood (an open ball) contained in the product. By definition,  $(a_1, b_1) \times (a_2, b_2)$  is open in  $\mathbb{R}^2$ .  $\square$

**Definition 2.10** (Closed set). A closed set  $A$  is defined by its ability to contain all of its limit points, meaning if a sequence of points  $\{x_n\}$  within  $A$  converges to a limit  $x$ , then that limit  $x$  must also be in  $A$ .

**Definition 2.11** (Sequence). A sequence is a function whose domain is  $\mathbb{N}$ .