

MAT211: Calculus-II

Lecture Notes

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Contents

1 Lecture-01	2
2 Lecture-02	4

1 Lecture-01

Question: what did we mean by the derivative $f'(a)$?

Answer: Let U be an open subset of \mathbb{R} and $f : U \rightarrow \mathbb{R}$ a function. Then f is differentiable at a , with derivative m , if and only if

$$\lim_{h \rightarrow 0} \frac{1}{h} \left(\underbrace{f(a+h) - f(a)}_{\Delta f} - \underbrace{mh}_{(*)} \right) = 0 \quad (1)$$

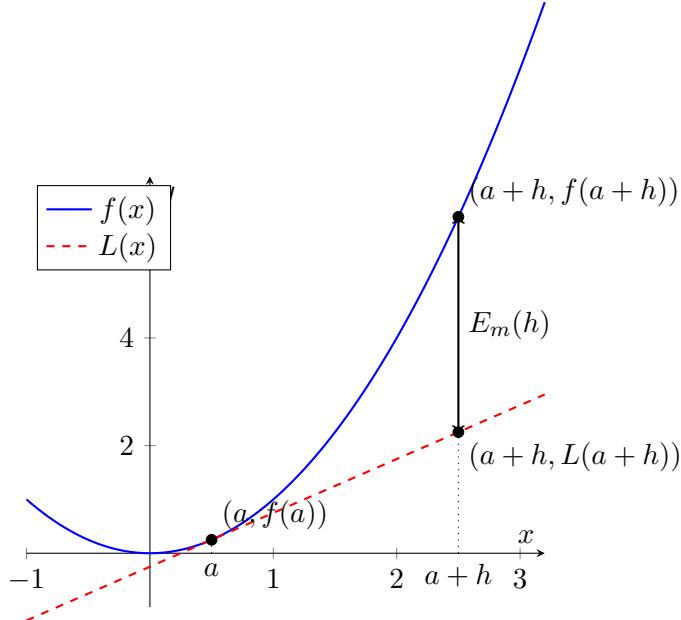
(*) : linear function of $\Delta x = h$.

Question: Why impose the domain U that needs to be an open set?

Answer: Write the answer.

The function mh that multiplies h by the derivative m is thus a linear function of the change in x . This definition emphasizes the idea that a function f is differentiable at a point a if the increment Δf to the function is well approximated by a linear function of the increment h to the variable, this linear function is $f'(a)h$. Let's see how we can confirm that:

Suppose $f(x)$ is our desired function and we want to approximate the function in the neighborhood at $x = a$. For this purpose, we will draw several straight lines through the point $(a, f(a))$ and see which line approximates the function best. Here, the best means, the linear line should approximate the function well at $x = a + h$. Suppose the slope of that linear function is m .



Then,

$$\begin{aligned} \frac{L(a+h) - L(a)}{a+h-a} &= m \\ \frac{L(a+h) - f(a)}{h} &= m \\ L(a+h) &= f(a) + mh \end{aligned}$$

Now, we want to minimize the error, $E_m(h) = f(a + h) - L(a + h)$. Hence, we need to find the optimal value for m , for which:

$$\frac{E_m(h)}{h} \rightarrow 0$$

$\text{optimal } m \iff \lim_{h \rightarrow 0} \frac{E_m(h)}{h} = 0$

A simple computation show that,

$$\lim_{h \rightarrow 0} \frac{E_m(h)}{h} = \lim_{h \rightarrow 0} \frac{f(a + h) - f(a) - mh}{h} = 0$$

which is the desired condition 1, we showed in the definition.

2 Lecture-02

Definition 2.1 (Euclidean Vector Space). A Euclidean vector space is a finite-dimensional inner product space over \mathbb{R} .

Definition 2.2 (Inner product space). An inner product space is a vector space V over the field F together with an inner product, that is, a map

$$\langle \cdot, \cdot \rangle : V \times V \rightarrow F$$

that satisfies the following three properties for all vectors $x, y, z \in V$ and all scalars $a, b \in F$.

1. (Symmetry) $\langle x, y \rangle = \langle y, x \rangle$.
2. (Linearity in the first argument) $\langle ax + by, z \rangle = a\langle x, z \rangle + b\langle y, z \rangle$.
3. (Positive-definiteness) If $x \neq 0$ then, $\langle x, x \rangle > 0$.

Example 2.3. Verify that the dot product function $\langle \cdot, \cdot \rangle : \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$ is an inner product.

To verify this we must prove the three conditions shown above. Let $u = (a, b)$ and $v = (c, d)$. Then,

1. $\langle u, v \rangle = ac + bd = ca + db = \langle v, u \rangle$.
2. Let $a, b \in \mathbb{R}$ and $u, v, w \in \mathbb{R}^2$ with $u = (u_1, u_2), v = (v_1, v_2), w = (w_1, w_2)$. Then

$$\begin{aligned} \langle au + bv, w \rangle &= (au_1 + bv_1)w_1 + (au_2 + bv_2)w_2 \\ &= au_1w_1 + bv_1w_1 + au_2w_2 + bv_2w_2 \\ &= a(u_1w_1 + u_2w_2) + b(v_1w_1 + v_2w_2) \\ &= a\langle u, w \rangle + b\langle v, w \rangle. \end{aligned}$$

3. For any $u = (u_1, u_2)$,

$$\langle u, u \rangle = u_1^2 + u_2^2.$$

Since squares of non-zero numbers are positive, we have $u_1^2 > 0, u_2^2 > 0$ and therefore, $\langle u, u \rangle > 0$.

Definition 2.4 (Informal). Define **norm** of a vector $x \in V$ as

$$\|x\| = \sqrt{\langle x, x \rangle}.$$

Definition 2.5 (Metric Space). A metric space is an ordered pair (M, d) where M is a set and d is a **metric** (distance) on M , i.e., a function

$$d : M \times M \rightarrow \mathbb{R}$$

satisfying the following axioms for all points $x, y, z \in M$:

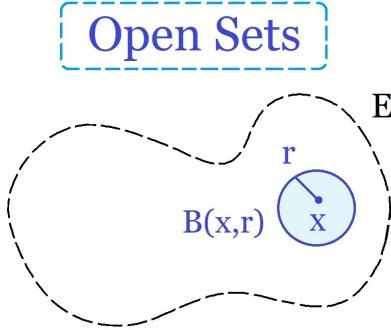
1. $d(x, y) \geq 0$;
2. $d(x, y) = 0 \iff x = y$;

3. $d(x, y) = d(y, x)$.
4. $d(x, z) \leq d(x, y) + d(y, z)$.

Example 2.6 (Tax-cab Metric). In \mathbb{R}^2 , the taxi-cab distance between $p = (p_1, p_2)$ and $q = (q_1, q_2)$ is $|q_1 - p_1| + |q_2 - p_2|$. It is easy to verify that this is a metric.

Definition 2.7 (Open ball). For any $x \in \mathbb{R}^n$ and any $r > 0$, the **open ball** of radius r around x is the subset

$$B_r(x) = \{y \in \mathbb{R}^n \mid |x - y| < r\}.$$



Definition 2.8 (Open sets of \mathbb{R}^n). A subset $U \subseteq \mathbb{R}^n$ is open if for every point $x \in U$, there exists $r > 0$ such that the open ball $B_r(x)$ is contained in U .

Example 2.9. We prove that the Cartesian product $(a_1, b_1) \times (a_2, b_2)$ of two open intervals in \mathbb{R} is an open set in \mathbb{R}^2 with the standard Euclidean topology.

Proof. Let d denote the Euclidean metric on \mathbb{R}^2 :

$$d((x_1, y_1), (x_2, y_2)) = \sqrt{(x_1 - x_2)^2 + (y_1 - y_2)^2}.$$

Take an arbitrary point $p = (x, y) \in (a_1, b_1) \times (a_2, b_2)$. Then

$$a_1 < x < b_1, \quad a_2 < y < b_2.$$

Define the four positive distances to the endpoints:

$$d_1 = x - a_1, \quad d_2 = b_1 - x, \quad d_3 = y - a_2, \quad d_4 = b_2 - y.$$

Let

$$r = \min\{d_1, d_2, d_3, d_4\} > 0.$$

We claim that the open ball $B(p, r) = \{q \in \mathbb{R}^2 : d(p, q) < r\}$ is contained in $(a_1, b_1) \times (a_2, b_2)$.

Indeed, take any point $q = (u, v) \in B(p, r)$. Then

$$|u - x| \leq d(p, q) < r, \quad |v - y| \leq d(p, q) < r.$$

Hence

$$x - r < u < x + r, \quad y - r < v < y + r.$$

Because $r \leq x - a_1$ and $r \leq b_1 - x$, we have

$$a_1 \leq x - r < u < x + r \leq b_1,$$

so $u \in (a_1, b_1)$. Similarly, $r \leq y - a_2$ and $r \leq b_2 - y$ imply

$$a_2 \leq y - r < v < y + r \leq b_2,$$

so $v \in (a_2, b_2)$. Consequently $q = (u, v) \in (a_1, b_1) \times (a_2, b_2)$.

Thus every point of the product has an open neighbourhood (an open ball) contained in the product. By definition, $(a_1, b_1) \times (a_2, b_2)$ is open in \mathbb{R}^2 . \square

Definition 2.10 (Closed set). A closed set A is defined by its ability to contain all of its limit points, meaning if a sequence of points $\{x_n\}$ within A converges to a limit x , then that limit x must also be in A .

Definition 2.11 (Sequence). A sequence is a function whose domain is \mathbb{N} .