

Linear Algebra Done Right: answers to selected exercises

Chapter 3

Problem 1 (3.B.20): Suppose W is finite dimensional and $T \in \mathcal{L}(V, W)$. Prove that T is injective if and only if there exists $S \in \mathcal{L}(W, V)$ such that ST is the identity map on V .

Solution: If $ST : \mathcal{L}(V, V)$ is the identity map then for any $v \in V$, $STv = v$. This can be rewritten as $S(Tv)$; now assume that T is not injective in which case for $v_1 \neq v_2$, $Tv_1 = Tv_2 = w$. Since $STv_1 \neq STv_2$ we must have $Sw \neq Sw$ which is not possible. Therefore T must be injective.

Next assume that T is injective and define a linear map $S = \mathcal{L}(W, V)$ with the property $Sw = v$ if $Tv = w$. This map is defined since T is injective and there is a unique v for which $Tv = w$. Therefore $STv = v$ and ST is the identity map on V .

Problem 2 (3.B.21): Suppose V is finite dimensional and $T \in \mathcal{L}(V, W)$. Prove that T is surjective if and only if there exists $S \in \mathcal{L}(W, V)$ such that TS is the identity map on W .

Solution: If $TS \in \mathcal{L}(W, W)$ is the identity map then for all $w \in W$, $TSw = w$. For the identity map to exist S must map all $w \in W$ to some $\text{range } S \subseteq V$ and then T must map $\text{range } S$ to the whole of W . But if T is not surjective, $\text{range } T \subset W$ and therefore for any $\text{range } S$ it is not possible for $\text{range } TS = W$. Therefore T must be surjective.

If T is surjective then $\text{range } T = W$; therefore for any $w \in W$ there is one or more $v \in V$ such that $Tv = w$. Define a map $S : \mathcal{L}(W, V)$ which maps $w \in W$ to $v \in V$ such that $Tv = w$ (if more than one v have this property select one and keep this choice fixed). So if we start with $w \in W$ then we can map it to $v = Sw$. From the definition of S then it follows that $Tv = w$ or $TSw = w$ and therefore TS is the identity map.

Problem 3 (3.B.24): Suppose W is finite-dimensional and $T_1, T_2 \in \mathcal{L}(V, W)$. Prove that $\text{null } T_1 \subset \text{null } T_2$ if and only if there exists $S \in \mathcal{L}(W, W)$ such that $T_2 = ST_1$.

Solution: Start with $\text{null } T_1 \subset \text{null } T_2$; this means that for some $v \in \text{null } T_2$, $T_1 v \neq 0$. We can define a linear map $S \in \mathcal{L}(W, W)$ with the following properties: if $T_1 v = T_2 v = 0$ then $ST_1 v = S0 = 0 = T_2 v$ which is a property of all linear maps; if $T_2 v = 0$ and $T_1 v \neq 0$ then $T_1 v \in \text{null } S$ and $S(T_1 v) = 0 = T_2 v$; in all other cases S maps $T_1 v$ to $T_2 v$, i.e. $ST_1 v = T_2 v$. Therefore we can define a linear map with the property $ST_1 = T_2$.

Next assume the existence of a linear map $S \in \mathcal{L}(W, W)$ such that $T_2 = ST_1$. For $v \in \text{null } T_1$ we have $ST_1 v = 0 = T_2 v$ and therefore $v \in \text{null } T_2$. For $v \in \text{null } T_2$ there is no linear map $S' \in \mathcal{L}(W, W)$ such that $T_1 = S'T_2$. Therefore if $T_2 v = 0$ it is not always the case that $T_1 v = 0$. Therefore $\text{null } T_1 \subset \text{null } T_2$.

Problem 4 (3.B.25): Suppose V is finite dimensional and $T_1, T_2 \in \mathcal{L}(V, W)$. Prove that $\text{range } T_1 \subset \text{range } T_2$ if and only if there exists $S \in \mathcal{L}(V, V)$ such that $T_1 = T_2 S$.

Solution: If $\text{range } T_1 \subset \text{range } T_2$ then if $w = T_1 v$ there exists $v' \in V$ for which $w = T_2 v'$. We can define $S \in \mathcal{L}(V, V)$ such that given $v \in \text{range } T_1$ we find $v' \in \text{range } T_2$ such that $T_1 v = T_2 v'$. Therefore if $v' = Sv$ then $T_2 v' = T_2 Sv$ and since $T_1 v = T_2 v'$ we have $T_1 v = T_2 Sv$ i.e. $T_1 = T_2 S$.

Next assume that there exists $S \in \mathcal{L}(V, V)$ such that $T_1 = T_2 S$. If $w \in \text{range } T_1$ we have $w = T_1 v = T_2 Sv$ and since $Sv \in V$, $T_2 v \in \text{range } T_2$, $w \in \text{range } T_2$. If $w \in \text{range } T_2$ we have $w = T_2 v$; however there is no linear map $S' \in \mathcal{L}(V, V)$ for which $T_2 = T_1 S'$ and therefore $w \in \text{range } T_1$. Therefore it is not always true that if $w \in \text{range } T_2$ it is also the case that $w \in \text{range } T_1$ and therefore $\text{range } T_1 \subset \text{range } T_2$.

Problem 5 (3.B.29): Suppose $\phi \in \mathcal{L}(V, \mathbb{F})$. Suppose $u \in V$ is not in $\text{null } \phi$. Prove that,

$$V = \text{null } \phi \oplus \{au : a \in \mathbb{F}\}$$

Solution: To simplify the expressions denote $\{au : a \in \mathbb{F}\}$ as U . First we must prove that,

$$\text{null } \phi \cap U = \{0\}$$

Since $u \notin \text{null } \phi$ it is also the case that for $a \in \mathbb{F}$, $au \notin \text{null } \phi$ except from the trivial case $u = 0$ for which $U = \{0\}$ or $a = 0, u \neq 0$ for which $au = 0$. Therefore,

$$\text{null } \phi \cap U = \{0\}$$

Next we must prove that any $v \in V$ can be written as the sum of two vectors, $w \in \text{null } \phi$ and $u \in U$. Since $\dim \text{range } \phi \leq \dim \mathbb{F}$ we have,

$$\dim V - \dim \text{null } \phi \leq 1 \Rightarrow \dim V - 1 \leq \dim \text{null } \phi$$

For the case $\dim \text{null } \phi = \dim V = n$ then all $v \in V$ are also $v \in \text{null } \phi$. In this case $u = 0$ and since,

$$v = v + 0$$

any $v \in V$ can be written as the sum of $v \in \text{null } \phi$ and $u \in U$. If $\dim \text{null } \phi = \dim V - 1 = n - 1$, then any $w \in \text{null } \phi$ can be written as,

$$w = w^1 e_1 + \dots + w^{n-1} e_{n-1}$$

i.e. a linear combination of $n - 1$ basis vectors. Since $u \notin \text{null } \phi$,

$$au = au^n e_n$$

For $v \in V$,

$$v = v^1 e_1 + \dots + v^{n-1} e_{n-1} + v^n e_n$$

Set $w^1 = v^1, \dots, w^{n-1} = v^{n-1}$ and $au^n = v^n$ by setting $a = v^n / u^n$ (note that if $\dim \text{null } \phi = n - 1$, $u^n \neq 0$ and $au = 0$ only for $a = 0$). Then any $v \in V$ can be expressed as the sum of $w \in \text{null } \phi$ and au where $u \in U$ and $a \in \mathbb{F}$.

Problem 6 (3.B.30): Suppose ϕ_1 and ϕ_2 are linear maps from V to \mathbb{F} that have the same null space. Show that there exists a constant $c \in \mathbb{F}$ such that $\phi_1 = c\phi_2$.

Solution: Denote $\text{null } \phi_1 = \text{null } \phi_2$ as N . For any linear map $\dim V = \dim \text{null} + \dim \text{range}$ so $\dim V - \dim N = \dim \text{range } \phi_1 \leq \dim \mathbb{F} = 1$ (same is true for ϕ_2). If $\dim V = n$ then $\dim V - \dim N \leq 1$ or $n - 1 \leq \dim N$.

If $\dim N = n$ then $\dim \text{range } \phi_1 = 0$ (same is true for ϕ_2) and therefore $\text{range } \phi_1 = \text{range } \phi_2 = \{0\}$. This is only possible if $\phi_1 v = \phi_2 v = 0v = 0$ for all $v \in V$. So if $\dim \text{null } \phi_1 = \dim \text{null } \phi_2 = n$ for any $c \in \mathbb{F}$, $\phi_1 = c\phi_2$.

If $\dim N = n - 1$ then $\dim \text{range } \phi_1 = \dim \text{range } \phi_2 = 1$ so for $v \notin N$,

$$v = v^1 e_1 + \dots + v^n e_n$$

$$\phi_1 v = v^n \phi_1 e_n$$

$$\phi_2 v = v^n \phi_2 e_n$$

Define $c = \phi_1 e_n / \phi_2 e_n$ (note that $\phi_2 e_n \neq 0$ since if this is not the case $\phi_2 v = 0$ for all v); then

$$\phi_1 v = v^n (c \phi_2 e_n) = c \phi_2 v$$

and therefore $\phi_1 = c\phi_2$.

Problem 7 (3.B.31): Give an example of two linear maps T_1 and T_2 from \mathbb{R}^5 to \mathbb{R}^2 that have the same null space but are such that T_1 is not a scalar multiple of T_2 .

Solution: Consider,

$$A = [A_1 \ A_2 \ A_3 \ A_4 \ A_5]$$

where A_i are 2×1 independent vectors. For $i = 3, 4, 5$,

$$A_i = a_{i1}A_1 + a_{i2}A_2$$

and the null space of A is composed of vectors x with the property,

$$x_1A_1 + x_2A_2 + x_3A_3 + x_4A_4 + x_5A_5 = 0$$

or,

$$(x_1 + a_{31}x_3 + a_{41}x_4 + a_{51}x_5)A_1 + (x_2 + a_{32}x_3 + a_{42}x_4 + a_{52}x_5)A_2 = 0$$

Since A_1, A_2 are independent vectors the last condition holds only if,

$$x_1 = -a_{31}x_3 - a_{41}x_4 - a_{51}x_5$$

$$x_2 = -a_{32}x_3 - a_{42}x_4 - a_{52}x_5$$

therefore any $x \in \text{null } A$,

$$x = \begin{pmatrix} -a_{31}x_3 - a_{41}x_4 - a_{51}x_5 \\ -a_{32}x_3 - a_{42}x_4 - a_{52}x_5 \\ x_3 \\ x_4 \\ x_5 \end{pmatrix} = x_3 \begin{pmatrix} -a_{31} \\ -a_{32} \\ 1 \\ 0 \\ 0 \end{pmatrix} + x_4 \begin{pmatrix} -a_{41} \\ -a_{42} \\ 0 \\ 1 \\ 0 \end{pmatrix} + x_5 \begin{pmatrix} -a_{51} \\ -a_{52} \\ 0 \\ 0 \\ 1 \end{pmatrix}$$

Since the three vectors in the last equation are independent they form the basis of $\text{null } A$.

Now define another 5×2 matrix,

$$B = [B_1 \ B_2 \ B_3 \ B_4 \ B_5]$$

where B_i are 2×1 independent vectors. For $i = 3, 4, 5$,

$$B_i = a_{i1}B_1 + a_{i2}B_2$$

and using the same procedure as above the same three vectors form the basis of $\text{null } B$. Therefore $\text{null } A = \text{null } B$; since B_1, B_2 are different from A_1, A_2 , A is not a scalar multiple of B . As an example,

$$A = \begin{bmatrix} 2 & -1 & 1 & 3 & 5 \\ 1 & 2 & 3 & -1 & 0 \end{bmatrix}$$

and,

$$B = \begin{bmatrix} 1 & 0 & 1 & 1 & 2 \\ 0 & 1 & 1 & -1 & -1 \end{bmatrix}$$

have null space,

$$\text{null } A = \text{null } B = \text{Span} \left\{ \begin{pmatrix} -1 \\ -1 \\ 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} -1 \\ 1 \\ 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} -2 \\ 1 \\ 0 \\ 0 \\ 1 \end{pmatrix} \right\}$$

Problem 8 (3.C.2): Suppose $D \in \mathcal{L}(\mathcal{P}_3(\mathbb{R}), \mathcal{P}_2(\mathbb{R}))$ is the differentiation map defined by $Dp = p'$. Find a basis of $\mathcal{P}_3(\mathbb{R})$ and a basis of $\mathcal{P}_2(\mathbb{R})$ such that the matrix of D with respect to these bases is,

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

Solution: If we express,

$$\mathcal{P}_3(x) = \sum_{i=1}^4 b_i f_i(x)$$

where f_i is the i^{th} basis of \mathcal{P}_3 and,

$$\mathcal{P}_2(x) = \sum_{i=1}^3 b_i g_i(x)$$

where g_i is the i^{th} basis of \mathcal{P}_2 then from the structure of the matrix of D we have,

$$\sum_{i=1}^3 b_i g_i(x) = \sum_{i=1}^4 b_i f'_i(x)$$

Since $f'_4(x) = 0$, $f_4(x) = \text{constant}$ and we can set $f_4(x) = 1$. For $i = 3$, $f'_3(x) = g_3(x)$ so one choice is $f_3(x) = x$ and $g_3(x) = 1$; similarly $f_2(x) = x^2$, $g_2(x) = 2x$ and $f_1(x) = x^3$, $g_1(x) = 3x^2$. So starting from the polynomial,

$$\mathcal{P}(x) = a_0 + a_1x + a_2x^2 + a_3x^3$$

we can write it as,

$$\mathcal{P}_3(x) = a_3f_1(x) + a_2f_2(x) + a_1f_3(x) + a_0f_4(x)$$

which when differentiated gives,

$$D\mathcal{P}_3(x) = \mathcal{P}_2(x) = a_3g_1(x) + a_2g_2(x) + a_1g_3(x)$$

We can rewrite the last equation in matrix form as,

$$\begin{pmatrix} a_3 \\ a_2 \\ a_1 \end{pmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix} \begin{pmatrix} a_3 \\ a_2 \\ a_1 \\ a_0 \end{pmatrix}$$

Problem 9 (3.C.3): Suppose V and W are finite-dimensional and $T \in \mathcal{L}(V, W)$. Prove that there exist a basis of V and W such that with respect to these bases, all entries of $\mathcal{M}(T)$ are 0 except that the entries in row j , column j , equal 1 for $1 \leq j \leq \dim \text{range } T$.

Solution: Denote $\dim V$ as n and $\dim \text{null } T$ as r ; from the Fundamental Theorem of Linear Maps we have, $\dim \text{range } T = n - r$, $\text{range } T = \text{Span}\{e_1, \dots, e_{n-r}\}$ and $\text{null } T = \text{Span}\{e_{n-r+1}, \dots, e_n\}$. Any $v \in V$ can be written as,

$$v = v^1 e_1 + \dots + v^{n-r} e_{n-r} + v^{n-r+1} e_{n-r+1} + \dots + v^n e_n$$

where $\{e_1, \dots, e_n\}$ is a basis of V . If $v \in \text{null } T$,

$$v = 0e_1 + \dots + 0e_{n-r} + v^{n-r+1} e_{n-r+1} + \dots + v^n e_n$$

and since $Te_{n-r+1} = \dots = Te_n = 0$ we have,

$$Tv = 0Te_1 + \dots + 0Te_{n-r} + v^{n-r+1} 0 + \dots + v^n 0 = 0$$

For $w \in \text{range } T$ with $w \neq 0$,

$$w = Tv = v^1 Te_1 + \dots + v^{n-r} Te_{n-r} + v^{n-r+1} Te_{n-r+1} + \dots + v^n Te_n$$

or,

$$w = Tv = v^1 Te_1 + \dots + v^{n-r} Te_{n-r} + v^{n-r+1} 0 + \dots + v^n 0$$

Note that vectors Te_1, \dots, Te_{n-r} are independent since $w = 0$ only if $v = 0$ if $v \notin \text{null } T$. Therefore vectors Te_1, \dots, Te_{n-r} can be the basis vectors for $\text{range } T$. From the definition of $\mathcal{M}(T)$ the entries of the matrix satisfy the condition,

$$Te_k = A_{1,k} w_1 + \dots + A_{n-r,k} w_{n-r}$$

where w_1, \dots, w_{n-r} are the basis vectors of $\text{range } T$. If $w_k = Te_k$ for $j = 1, \dots, n - r$ then $A_{k,k} = 1$ and $A_{k,k'} = 0$ for $k \neq k'$. Therefore A is,

$$\begin{pmatrix} w^1 \\ \vdots \\ w^{n-r} \end{pmatrix} = \begin{bmatrix} 1 & 0 & \dots & 0 & 0 & 0 & \dots & 0 \\ 0 & 1 & \dots & 0 & 0 & 0 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 1 & 0 & 0 & \dots & 0 \end{bmatrix} \begin{pmatrix} v^1 \\ \vdots \\ v^n \end{pmatrix}$$

or,

$$A = \begin{bmatrix} I & O \end{bmatrix}$$

where I is the $n - r \times n - r$ identity matrix and O is the $n - r \times r$ zero matrix.

Problem 10 (3.C.4): Suppose v_1, \dots, v_m is a basis of V and W is finite-dimensional. Suppose $T \in \mathcal{L}(V, W)$. Prove there exists a basis w_1, \dots, w_n of W such that all the entries in the first column of $\mathcal{M}(T)$ (with respect to the bases v_1, \dots, v_m and w_1, \dots, w_n) are 0 except from possibly a 1 in the first row, first column.

Solution: The format of $\mathcal{M}(T)$ is as follows,

$$\begin{array}{c} \\ \\ \\ \\ \\ \end{array} \begin{array}{ccccc} v_1 & \cdots & v_j & \cdots & v_m \\ w_1 & \left[\begin{array}{ccccc} A_{1,1} & \cdots & A_{1,j} & \cdots & A_{1,m} \\ \vdots & \ddots & \vdots & \ddots & \vdots \\ A_{i,1} & \cdots & A_{i,j} & \cdots & A_{i,m} \\ \vdots & \ddots & \vdots & \ddots & \vdots \\ A_{n,1} & \cdots & A_{n,j} & \cdots & A_{n,m} \end{array} \right] \end{array}$$

and the matrix coefficients are defined by,

$$Tv_j = \sum_{i=1}^n A_{i,j} w_i$$

We want a basis $\hat{w}_1, \dots, \hat{w}_n$ for which the linear map $T' : V \rightarrow \hat{W}$,

$$\begin{array}{c} \\ \\ \\ \\ \\ \end{array} \begin{array}{ccccc} v_1 & \cdots & v_j & \cdots & v_m \\ \hat{w}_1 & \left[\begin{array}{ccccc} 1 \text{ or } 0 & \cdots & B_{1,j} & \cdots & B_{1,m} \\ \vdots & \ddots & \vdots & \ddots & \vdots \\ 0 & \cdots & B_{i,j} & \cdots & B_{i,m} \\ \vdots & \ddots & \vdots & \ddots & \vdots \\ 0 & \cdots & B_{n,j} & \cdots & B_{n,m} \end{array} \right] \end{array}$$

If we start with the linear map $T : V \rightarrow W$ and then add a linear map $S : W \rightarrow \hat{W}$ then since $T' : V \rightarrow \hat{W}$, $\mathcal{M}(T') = \mathcal{M}(S)\mathcal{M}(T)$ or $B = CA$.

If $B_{1,1} = \dots = B_{n,1} = 0$ then the equation,

$$T'v_1 = 0\hat{w}_1 + \dots + 0\hat{w}_n$$

holds for any basis $\{\hat{w}_1, \dots, \hat{w}_n\}$. If $B_{1,1} = 1$ and $B_{i,1} = 0$ for $i > 1$ then we must have,

$$Tv_1 = 1\hat{w}_1 + \dots + 0\hat{w}_n$$

and therefore $\hat{w}_1 = Tv_1$.

Define a $n \times n$ matrix with the following properties,

$$\begin{aligned} C_{i,i} &= A_{i,1}^{-1} \\ C_{i,1} &= A_{1,1}^{-1} \\ C_{i,j} &= 0 \text{ for } i \neq j, j > 1 \end{aligned}$$

so that,

$$\begin{aligned} CA &= \begin{bmatrix} A_{1,1}^{-1} & 0 & 0 & 0 & \cdots & 0 \\ A_{1,1}^{-1} & -A_{2,1}^{-1} & 0 & 0 & \cdots & 0 \\ A_{1,1}^{-1} & 0 & -A_{3,1}^{-1} & 0 & \cdots & 0 \\ A_{1,1}^{-1} & 0 & 0 & -A_{4,1}^{-1} & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ A_{1,1}^{-1} & 0 & 0 & 0 & \cdots & -A_{n,1}^{-1} \end{bmatrix} \begin{bmatrix} A_{1,1} & A_{1,2} & A_{1,3} & A_{1,4} & \cdots & A_{1,m} \\ A_{2,1} & A_{2,2} & A_{2,3} & A_{2,4} & \cdots & A_{2,m} \\ A_{3,1} & A_{3,2} & A_{3,3} & A_{3,4} & \cdots & A_{3,m} \\ A_{4,1} & A_{4,2} & A_{4,3} & A_{4,4} & \cdots & A_{4,m} \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ A_{n,1} & A_{n,2} & A_{n,3} & A_{n,4} & \cdots & A_{n,m} \end{bmatrix} \\ &= \begin{bmatrix} 1 & \frac{A_{1,2}}{A_{1,1}} & \frac{A_{1,3}}{A_{1,1}} & \frac{A_{1,4}}{A_{1,1}} & \cdots & \frac{A_{1,m}}{A_{1,1}} \\ 0 & \frac{A_{1,2}}{A_{1,1}} - \frac{A_{2,2}}{A_{2,1}} & \frac{A_{1,3}}{A_{1,1}} - \frac{A_{2,3}}{A_{2,1}} & \frac{A_{1,4}}{A_{1,1}} - \frac{A_{2,4}}{A_{2,1}} & \cdots & \frac{A_{1,m}}{A_{1,1}} - \frac{A_{2,m}}{A_{2,1}} \\ 0 & \frac{A_{1,2}}{A_{1,1}} - \frac{A_{3,2}}{A_{3,1}} & \frac{A_{1,3}}{A_{1,1}} - \frac{A_{3,3}}{A_{3,1}} & \frac{A_{1,4}}{A_{1,1}} - \frac{A_{3,4}}{A_{3,1}} & \cdots & \frac{A_{1,m}}{A_{1,1}} - \frac{A_{3,m}}{A_{3,1}} \\ 0 & \frac{A_{1,2}}{A_{1,1}} - \frac{A_{4,2}}{A_{4,1}} & \frac{A_{1,3}}{A_{1,1}} - \frac{A_{4,3}}{A_{4,1}} & \frac{A_{1,4}}{A_{1,1}} - \frac{A_{4,4}}{A_{4,1}} & \cdots & \frac{A_{1,m}}{A_{1,1}} - \frac{A_{4,m}}{A_{4,1}} \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & \frac{A_{1,2}}{A_{1,1}} - \frac{A_{n,2}}{A_{n,1}} & \frac{A_{1,3}}{A_{1,1}} - \frac{A_{n,3}}{A_{n,1}} & \frac{A_{1,4}}{A_{1,1}} - \frac{A_{n,4}}{A_{n,1}} & \cdots & \frac{A_{1,m}}{A_{1,1}} - \frac{A_{n,m}}{A_{n,1}} \end{bmatrix} \end{aligned}$$

C is admissible as a basis transformation matrix only if $A_{i,1} \neq 0$ for all i . Since,

$$w_r = \sum_{j=1}^n C_{j,r} \hat{w}_j$$

and both w_r and \hat{w}_j are $n \times 1$ vectors, if W is the matrix whose columns are the w basis vectors and \hat{W} is the matrix whose columns are the \hat{w} basis vectors then,

$$W_{i,r} = \sum_{j=1}^n C_{j,r} \hat{W}_{i,j}$$

and therefore,

$$W = \hat{W}C$$

To express the new basis vectors in terms of the original basis we can right multiply both sides with C^{-1} to get,

$$\hat{W} = WC^{-1}$$

It is easy to show that,

$$C^{-1} = \begin{array}{c} \begin{matrix} & \hat{w}_1 & \hat{w}_2 & \hat{w}_3 & \hat{w}_4 & \cdots & \hat{w}_n \end{matrix} \\ \begin{matrix} w_1 \\ w_2 \\ w_3 \\ w_4 \\ \vdots \\ w_n \end{matrix} \end{array} \begin{bmatrix} A_{1,1} & 0 & 0 & 0 & \cdots & 0 \\ A_{2,1} & -A_{2,1} & 0 & 0 & \cdots & 0 \\ A_{3,1} & 0 & -A_{3,1} & 0 & \cdots & 0 \\ A_{4,1} & 0 & 0 & -A_{4,1} & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ A_{n,1} & 0 & 0 & 0 & \cdots & -A_{n,1} \end{bmatrix}$$

and therefore,

$$\begin{aligned} \hat{w}_1 &= \sum_{i=1}^n A_{i,1} w_i = T v_1 \\ \hat{w}_i &= -A_{i,1} w_i \quad \text{for } i > 1 \end{aligned}$$

Why can't we go further and derive a basis of W such that the first two entries in the first column of $\mathcal{M}(T)$ are equal to 1? Let's assume that a matrix C exists with the property,

$$\begin{aligned} \sum_{r=1}^n C_{1,r} A_{r,1} &= 1 \\ \sum_{r=1}^n C_{2,r} A_{r,1} &= 1 \end{aligned}$$

This is only possible if $C_{1,r} = C_{2,r}$ i.e. if the first two rows of C are identical. A matrix with two identical rows is not admissible as a basis transformation matrix. In order to prove this lets assume that a matrix C exists such that,

$$\begin{array}{c}
 \\
 \\
 \hat{w}_1 \\
 \hat{w}_2 \\
 \hat{w}_3 \\
 \hat{w}_4 \\
 \vdots \\
 \hat{w}_n
 \end{array}
 \begin{bmatrix}
 w_1 & w_2 & w_3 & w_4 & \cdots & w_n \\
 C_{1,1} & C_{1,2} & C_{1,3} & C_{1,4} & \cdots & C_{1,n} \\
 C_{1,1} & C_{1,2} & C_{1,3} & C_{1,4} & \cdots & C_{1,n} \\
 C_{2,1} & C_{2,2} & C_{2,3} & C_{2,4} & \cdots & C_{2,n} \\
 C_{3,1} & C_{3,2} & C_{3,3} & C_{3,4} & \cdots & C_{3,n} \\
 \vdots & \vdots & \vdots & \vdots & \cdots & \vdots \\
 C_{n-1,1} & C_{n-1,2} & C_{n-1,3} & C_{n-1,4} & \cdots & C_{n-1,n}
 \end{bmatrix}$$

Given that vectors \hat{w}_i are independent we want to show that we can choose a set of constants a_1, \dots, a_n that are not all zero but for which,

$$\sum_{i=1}^n a_i w_i = 0$$

Since,

$$w_i = C_{1,i}(\hat{w}_1 + \hat{w}_2) + \sum_{j=2}^n C_{j,i} \hat{w}_j$$

we must have,

$$\sum_{i=1}^n a_i \left(C_{1,i}(\hat{w}_1 + \hat{w}_2) + \sum_{j=2}^n C_{j,i} \hat{w}_j \right) = 0$$

The last equation holds only if the coefficients of the \hat{w}_j vectors are all zero, i.e.,

$$\sum_{i=1}^n C_{j,i} a_i = 0$$

for all j . Since C is the matrix of a linear map from a vector space with dimension n to vector space with dimension $n - 1$ this linear map cannot be injective; therefore the null set of this transformation contains non-zero vectors. It follows that w_1, w_2, \dots, w_n are not independent and a basis transformation matrix with two identical rows is not admissible.

Problem 11 (3.D.2): Suppose V is finite-dimensional and $\dim V > 1$. Prove that the set of noninvertible operators on V is not a subspace of $\mathcal{L}(V)$.

Solution: If an operator T is noninvertible it is also noninjective and nonsurjective since V is finite-dimensional. If an operator is nonsurjective then $\dim \text{range } T < \dim V$ (this explains the condition $\dim V > 1$; if $\dim V = 1$ then $\dim \text{range } T = 0$, T is an operator which maps all $v \in V$ to 0 and the set of operators with this property is a subspace).

We can choose two operators T_1 and T_2 with the following property: $\text{range } T_1 = \text{Span}\{v_1, \dots, v_r\}$ and $\text{range } T_2 = \text{Span}\{v_{r+1}, \dots, v_n\}$ where $n = \dim V$. Then $T_1 + T_2$ has the property $\text{range } T_1 + T_2 = \text{Span}\{v_1, \dots, v_n\} = V$. Since $T_1 + T_2$ is surjective it is also the case that it is invertible. Therefore the set of noninvertible operators is not closed under addition and is not a subspace of $\mathcal{L}(V)$.

Problem 12 (3.D.3): Suppose V is finite-dimensional, U is a subspace of V , and $S \in \mathcal{L}(U, V)$. Prove there exists an invertible operator $T \in \mathcal{L}(V)$ such that $Tu = Su$ for every $u \in U$ if and only if S is injective.

Solution: Since U is a subspace of V we can construct an operator $T \in \mathcal{L}(V)$ with the property $Tu = Su$ for every $u \in U$. It is clear that since S is injective in U , T has the same property. For $v \in V \setminus U$, we can use the identity operator so that $Tv = Iv = v$ which is also injective. Therefore, T is injective for all $v \in V$; since an injective operator in finite dimensional space is also invertible it follows that T is invertible.

Now start with the condition that T is an invertible operator in $\mathcal{L}(V)$; this implies it is also injective. Since $Tu = Su$ for every $u \in U$, S must also be injective.
