

Most of the material presented here is taken from [1].

Given a finite dimensional vector space  $\mathcal{V}$  over a field  $\mathbb{F}$  with characteristic zero and with an inner product  $g : \mathcal{V} \times \mathcal{V} \rightarrow \mathbb{F}$  define a bilinear map  $E : \mathcal{V} \times \mathcal{V} \rightarrow \mathcal{V}$  with the following properties:

I Bilinear property:  $E(ax + by, z) = aE(x, z) + bE(y, z)$ ,  $E(x, ay + bz) = aE(x, y) + bE(x, z)$  where  $x, y, z \in \mathcal{V}$  and  $a, b \in \mathbb{F}$ .

II Antisymmetric property:  $g(E(x, y), E(x, y)) = \begin{vmatrix} g(x, x) & g(x, y) \\ g(y, x) & g(y, y) \end{vmatrix}$  for all  $x, y \in \mathcal{V}$ . This is an expression of the antisymmetric property since

$$\begin{aligned} g(E(x, y), E(y, x)) &= \begin{vmatrix} g(x, y) & g(x, x) \\ g(y, y) & g(y, x) \end{vmatrix} = -\begin{vmatrix} g(x, x) & g(x, y) \\ g(y, x) & g(y, y) \end{vmatrix} \\ &= -g(E(x, y), E(x, y)) = g(E(x, y), -E(x, y)) \end{aligned}$$

and so we must have  $E(x, y) = -E(y, x)$ .

III Orthogonal property:  $g(E(x, y), x) = g(E(x, y), y) = 0$ .

We can use the bilinear map  $E$  to induce a linear map  $L_x : \mathcal{V} \rightarrow \mathcal{V}$  as follows:

$$L_x(y) = E(x, y), \text{ for all } y \in \mathcal{V}.$$

This follows from (I). We note that

$$L_x^2(y) = L_x E(x, y) = E(x, E(x, y)).$$

From (II) we have

$$\begin{aligned} g(E(x, E(x, y)), E(x, E(x, y))) &= \begin{vmatrix} g(x, x) & g(x, E(x, y)) \\ g(E(x, y), x) & g(E(x, y), E(x, y)) \end{vmatrix} \\ &= \begin{vmatrix} g(x, x) & 0 \\ 0 & g(E(x, y), E(x, y)) \end{vmatrix} \\ &= g(x, x)g(E(x, y), E(x, y)) \\ &= g(x, x)(g(x, x)g(y, y) - g(x, y)^2) \\ &= g(x, x)^2g(y, y) - g(x, y)^2g(x, x) \\ &= g(x, x)^2g(y, y) + g(x, y)^2g(x, x) \\ &\quad - 2g(x, y)^2g(x, x) \\ &= g(g(x, y)x - g(x, x)y, g(x, y)x - g(x, x)y). \end{aligned}$$

Therefore

$$E(x, E(x, y)) = g(x, y)x - g(x, x)y$$

and

$$L_x^2(y) = g(x, y)x - g(x, x)y.$$

The tensor product  $x \otimes y$  induces a linear map  $L_{x \otimes y} : \mathcal{V} \rightarrow \mathcal{V}$  defined as

$$\begin{aligned} (x \otimes y)(z) &= (x^i e_i \otimes y^j e_j)(z) = x^i y^j (e_i \otimes e_j)(z) \\ &= x^i y^j z_j e_i = x^i y^j z^k g_{jk} e_i \\ &= g(y, z) x^i e_i = g(y, z)x, \text{ for all } z \in \mathcal{V}. \end{aligned}$$

From these definitions we can also generate the composite maps

$$L_{x \otimes y} L_z(u) = L_{x \otimes y}(E(z, u)) = g(y, E(z, u))x$$

and

$$L_x L_{y \otimes z}(u) = L_x(g(z, u)y) = g(z, u)E(x, y) = L_{E(x, y) \otimes z}u. \quad (1)$$

Note that since

$$g(x + y, E(x + y, z)) = 0$$

(using property (III)) we have

$$\begin{aligned} g(x + y, E(x + y, z)) &= g(x + y, E(x, z) + E(y, z)) \\ &= g(x, E(x, z)) + g(y, E(x, z)) + g(x, E(y, z)) + g(y, E(y, z)) \\ &= g(y, E(x, z)) + g(x, E(y, z)) = 0. \end{aligned}$$

So we obtain

$$g(y, E(z, x)) = g(x, E(y, z))$$

using the antisymmetric property of  $E$ . In the same way we can prove that this property is cyclic, i.e.

$$g(x, E(y, z)) = g(y, E(z, x)) = g(z, E(x, y)).$$

This means that we can write

$$g(y, E(z, u)) = g(z, E(u, y)) = g(u, E(y, z)) \quad (2)$$

and so

$$L_{x \otimes y} L_z(u) = g(u, E(y, z))x = L_{x \otimes E(y, z)}(u). \quad (3)$$

Using these properties we can write

$$L_x^2(y) = g(x, y)x - g(x, x)y = L_{x \otimes x}(y) - g(x, x)I(y)$$

where  $I : \mathcal{V} \rightarrow \mathcal{V}$  is the identity map. So

$$L_x^2 = L_{x \otimes x} - g(x, x)I.$$

We can obtain the linearization of  $L_x^2$  by writing

$$\begin{aligned} L_{x+h}^2(y) &= g(x+h, y)(x+h) - g(x+h, x+h)y \\ L_{x+h}^2 &= L_x L_{x+h} = L_x^2 + L_x L_h + L_h L_x + L_h^2 \end{aligned}$$

The r.h.s. of the first equation expands to

$$\begin{aligned} L_{x+h}^2(y) &= g(x, y)x - g(x, x)y + g(x, y)h - g(x, h)y \\ &\quad + g(h, y)x - g(h, x)y + g(h, y)h - g(h, h)y \\ &= L_x^2(y) + g(x, y)h - g(x, h)y + L_h^2(y). \end{aligned}$$

We obtain

$$L_x L_h(y) + L_h L_x(y) = g(x, y)h - g(x, h)y + g(h, y)x - g(h, x)y.$$

If

$$L_x L_h(y) = g(x, y)h - g(x, h)y \tag{4}$$

then

$$L_h L_x(y) = g(h, y)x - g(h, x)y.$$

Note that this linearization agrees with the property

$$\begin{aligned} L_x L_h(y) &= g(x, y)h - g(x, h)y \\ &= -(g(x, h)y - g(x, y)h) \\ &= -L_x L_y(h). \end{aligned}$$

We can use the linearization of  $L_x^2$  to perform the following derivation:

$$\begin{aligned} (L_{E(x,y)} + L_x L_y)(z) &= E(E(x, y), z) + L_x L_y(z) \\ &= -E(z, E(x, y)) + L_x L_y(z) \\ &= -L_z L_x(y) + L_x L_y(z) \\ &= -(g(z, y)x - g(z, x)y) + g(x, z)y - g(x, y)z \\ &= 2g(x, z)y - g(z, y)x - g(x, y)z. \end{aligned}$$

This result can be used to write

$$L_{E(x,y)} + L_x L_y = 2y \otimes x - x \otimes y - g(x, y)I. \tag{5}$$

From this equation we get

$$\begin{aligned} L_{E(x,y)} L_x + L_x L_y L_x &= 2y \otimes x L_x - x \otimes y L_x - g(x, y) L_x \\ L_x L_y L_x &= -L_{E(x,y)} L_x + 2y \otimes x L_x - x \otimes y L_x - g(x, y) L_x \\ L_x L_y L_x &= -L_{E(x,y)} L_x - x \otimes E(y, x) - g(x, y) L_x \end{aligned} \tag{6}$$

since

$$(y \otimes x)L_x(z) = (y \otimes x)(E(x, z)) = g(x, E(x, z))y = 0,$$

and

$$(x \otimes y)L_x(z) = (x \otimes y)E(x, z) = g(y, E(x, z))x = (x \otimes E(y, x))(z).$$

From the same equation

$$\begin{aligned} L_{E(x,y)}L_x &= -L_{E(E(x,y),x)} + 2x \otimes E(x, y) - E(x, y) \otimes x - g(E(x, y), y)I \\ &= -L_{E(E(x,y),x)} + 2x \otimes E(x, y) - E(x, y) \otimes x; \end{aligned}$$

this produces a second equation for  $L_xL_yL_x$ :

$$\begin{aligned} L_xL_yL_x &= -(-L_{E(E(x,y),x)} + 2x \otimes E(x, y) - E(x, y) \otimes x) - x \otimes E(y, x) - g(x, y)L_x \\ &= L_{E(E(x,y),x)} - 2x \otimes E(x, y) + E(x, y) \otimes x - x \otimes E(y, x) - g(x, y)L_x \\ &= L_{E(E(x,y),x)} - 2x \otimes E(x, y) + E(x, y) \otimes x + x \otimes E(x, y) - g(x, y)L_x \\ &= L_{E(E(x,y),x)} - x \otimes E(x, y) + E(x, y) \otimes x - g(x, y)L_x. \end{aligned} \quad (7)$$

Next

$$E(E(x, y), x) = -E(x, E(x, y)) = -(g(x, y)x - g(x, x)y) = g(x, x)y - g(x, y)x.$$

Therefore

$$\begin{aligned} L_{E(E(x,y),x)}(z) &= E(g(x, x)y - g(x, y)x, z) = g(x, x)E(y, z) - g(x, y)E(x, z) \\ &= g(x, x)L_y(z) - g(x, y)L_x(z). \end{aligned}$$

The third equation for  $L_xL_yL_x$  is:

$$\begin{aligned} L_xL_yL_x &= g(x, x)L_y - g(x, y)L_x - x \otimes E(x, y) + E(x, y) \otimes x - g(x, y)L_x \\ &= g(x, x)L_y - 2g(x, y)L_x - x \otimes E(x, y) + E(x, y) \otimes x. \end{aligned} \quad (8)$$

We choose an orthonormal basis  $\{e_i\}_{i=1}^d$  where  $\dim \mathcal{V} = d$ . Define the following linear map  $S : \text{end}(\mathcal{V}) \rightarrow \text{end}(\mathcal{V})$

$$f \mapsto \sum_{i=1}^d L_{e_i} \circ f \circ L_{e_i}.$$

If  $f = I$  then

$$S(I) = \sum_{i=1}^d L_{e_i}^2 = \sum_{i=1}^d L_{e_i \otimes e_i} - \sum_{i=1}^d I = \sum_{i=1}^d L_{e_i \otimes e_i} - dI.$$

Since

$$\sum_{i=1}^d L_{e_i \otimes e_i}(x) = \sum_{i=1}^d g(e_i, x)e_i = x,$$

$$S(I) = (1 - d)I. \quad (9)$$

If  $f = L_{x \otimes y}$  then using (1) and (3)

$$\begin{aligned} S(L_{x \otimes y}) &= \sum_{i=1}^d L_{e_i} \circ L_{x \otimes y} \circ L_{e_i} \\ &= \sum_{i=1}^d L_{e_i} \circ L_{x \otimes E(y, e_i)} \\ &= \sum_{i=1}^d L_{E(e_i, x) \otimes E(y, e_i)}. \end{aligned}$$

Using (2)

$$\begin{aligned} L_{E(e_i, x) \otimes E(y, e_i)}(z) &= g(E(y, e_i), z)E(e_i, x) \\ &= g(z, E(y, e_i))E(e_i, x) \\ &= g(e_i, E(z, y))E(e_i, x) \\ &= g(e_i, E(y, z))E(x, e_i) \\ &= E(x, g(e_i, E(y, z))e_i) \end{aligned}$$

which substituted back in the summation gives

$$\begin{aligned} S(L_{x \otimes y}) &= \sum_{i=1}^d E(x, g(e_i, E(y, z))e_i) \\ &= E\left(x, \sum_{i=1}^d g(e_i, E(y, z))e_i\right) \\ &= E(x, E(y, z)) = L_x L_y(z) \end{aligned}$$

and so

$$S(L_{x \otimes y}) = L_x L_y. \quad (10)$$

If  $f = L_y$  then using (8)

$$S(L_y) = \sum_{i=1}^d L_{e_i} \circ L_y \circ L(e_i) \quad (11)$$

$$= \sum_{i=1}^d (g(e_i, e_i)L_y - 2g(e_i, y)L_{e_i} - e_i \otimes E(e_i, y) + E(e_i, y) \otimes e_i). \quad (12)$$

Since  $g(e_i, e_i) = 1$  the first term is simply  $dL_y$ ; for the second term write

$$\begin{aligned} \sum_{i=1}^d g(e_i, y)L_{e_i}(z) &= \sum_{i=1}^d g(e_i, y)E(e_i, z) = \sum_{i=1}^d E(g(e_i, y)e_i, z) \\ &= E\left(\sum_{i=1}^d g(e_i, y)e_i, z\right) = E(y, z) = L_y(z). \end{aligned}$$

For the third term

$$\begin{aligned}\sum_{i=1}^d e_i \otimes E(e_i, y)(z) &= \sum_{i=1}^d g(z, E(e_i, y))e_i = \sum_{i=1}^d g(e_i, E(y, z))e_i \\ &= E(y, z) = L_y(z).\end{aligned}$$

In a similar way the fourth term is

$$\begin{aligned}\sum_{i=1}^d E(e_i, y) \otimes e_i(z) &= \sum_{i=1}^d E(e_i, y)g(z, e_i) \\ &= E\left(\sum_{i=1}^d g(z, e_i)e_i, y\right) = E(z, y) = -E(y, z) = -L_y(z).\end{aligned}$$

Hence we conclude that

$$S(L_y) = (d-4)L_y. \quad (13)$$

If  $f = L_x L_y$  then

$$\begin{aligned}S(L_x L_y) &= -S(L_{E(x,y)}) + 2S(L_{y \otimes x}) - S(L_{x \otimes y}) - g(x, y)S(I) && \text{using (5)} \\ &= -(d-4)L_{E(x,y)} + 2S(L_{y \otimes x}) - S(L_{x \otimes y}) - g(x, y)S(I) && \text{using (13)} \\ &= -(d-4)L_{E(x,y)} + 2L_y L_x - L_x L_y - g(x, y)S(I) && \text{using (10)} \\ &= -(d-4)L_{E(x,y)} + 2L_y L_x - L_x L_y - (1-d)g(x, y)I && \text{using (9).} \quad (14)\end{aligned}$$

Using this derivation we can compute the following transformation:

$$g = \sum_{i=1}^d \sum_{j=1}^d L_{e_i} \circ L_x \circ L_{e_j} \circ L_{e_i} \circ L_{e_j}.$$

First using  $S(L_{e_i}) = \sum_{j=1}^d L_{e_j} \circ L_{e_i} \circ L_{e_j}$  and (13) we have

$$g = \sum_{i=1}^d L_{e_i} \circ L_x \circ (d-4)L_{e_i} = (d-4)S(L_x) = (d-4)^2 L_x.$$

Another way of computing the same transformation is to write

$$\begin{aligned}g &= \sum_{j=1}^d S(L_x L_{e_j}) \circ L_{e_j} \\ &= \sum_{j=1}^d \left( -(d-4)L_{E(x,e_j)} + 2L_{e_j} L_x - L_x L_{e_j} - (1-d)g(x, e_j)I \right) \circ L_{e_j}.\end{aligned}$$

Starting from the last term we have

$$g(x, e_j)I \circ L_{e_j}(z) = g(x, e_j)L_{e_j}(z) = g(x, e_j)E(e_j, z)$$

which after applying the summation w.r.t.  $j$  becomes

$$\sum_{j=1}^d g(x, e_j)I \circ L_{e_j}(z) = E\left(\sum_{j=1}^d g(x, e_j)e_j, z\right) = E(x, z) = L_x(z).$$

For  $L_{e_j}L_x$  we have

$$2 \sum_{j=1}^d L_{e_j}L_x \circ L_{e_j} = 2S(L_x) = 2(d-4)L_x$$

while for  $L_xL_{e_j}$  we have

$$L_x \sum_{j=1}^d L_{e_j} \circ L_{e_j} = L_x S(I) = (1-d)L_x.$$

For  $L_{E(x, e_j)}$  write using (6)

$$L_{E(x, e_j)}L_{e_j} = -L_{E(e_j, x)}L_{e_j} = -\left(-L_{e_j}L_xL_{e_j} - L_{e_j \otimes E(x, e_j)} - g(e_j, x)L_{e_j}\right)$$

For the second term

$$L_{e_j \otimes E(x, e_j)}(z) = g(z, E(x, e_j))e_j = g(e_j, E(z, x))e_j$$

which after summation w.r.t.  $j$  is equal to  $E(z, x)$ . For the third term

$$g(e_j, x)L_{e_j}(z) = g(e_j, x)E(e_j, z) = E(g(e_j, x)e_j, z)$$

which after summation w.r.t.  $j$  is equal to  $E(x, z)$ . Therefore

$$\sum_{j=1}^d L_{E(x, e_j)}L_{e_j} = \sum_{j=1}^d L_{e_j}L_xL_{e_j} + E(z, x) + E(x, z) = S(L_x) = (d-4)L_x$$

and so computing the transformation using this method we have

$$\begin{aligned} g &= \left(-(d-4)^2 + 2(d-4) - (1-d) - (1-d)\right)L_x \\ &= \left(-(d-4)^2 + 2(d-4) - 2(1-d)\right)L_x \end{aligned}$$

Since both methods compute the same transformation we must have

$$-(d-4)^2 + 2(d-4) - 2(1-d) = (d-4)^2$$

or

$$(d-4)^2 - (d-4) - (d-1) = d^2 - 10d + 21 = (d-3)(d-7) = 0.$$

## References

- [1] Alberto Elduque. Vector cross products. *Electronic copy found at: <http://www.unizar.es/matematicas/algebra/elduque/Talks/crossproducts.pdf>*, 2004.