sudo sh -c '. /etc/lsb-release && echo "deb

http://mirrors.tuna.tsinghua.edu.cn/ros/ubuntu/ `lsb\_release -cs`main" > /etc/apt/sources.list.d/ros-latest.list'

sudo apt-key adv --keyserver 'hkp://keyserver.ubuntu.com

:80' --recv-key C1CF6E31E6BADE8868B172B4F42ED6FBAB17C654

sudo apt-get update

sudo apt-get install ros-melodic-desktop-full

echo "source /opt/ros/melodic/setup.bash" >> ~/.bashrc

source ~/.bashrc

roscore

rosrun turtlesim turtle\_teleop\_key