```
1 Input: \epsilon_0, initial learning rate
 2 Input: \alpha, decay rate of learning rate
 з Input: \beta, momentum rate
 4 Input: m, minibatch size
 5 Input: k, epoch size
 6 Input: \theta, initial weights
 7 Input: v, initial velocity
 8 Input: X, training dataset inputs
 9 Input: y, training dataset targets
10 j \leftarrow 1
11 while j \leq k do
          update learning rate \epsilon_j \leftarrow \epsilon_0 + \alpha(\epsilon_{j-1} - \epsilon_0)
12
           \mathbf{while} \ \mathit{stopping} \ \mathit{criteria} \ \mathit{is} \ \mathit{not} \ \mathit{satisfied} \ \mathbf{do}
13
                 \{\mathbf{x}^1...\mathbf{x}^m\},\,\{\mathbf{y}^1...\mathbf{y}^m\}\leftarrow \mathrm{get}\ \mathrm{a}\ \mathrm{sample}\ \mathrm{from}\ \mathbf{X}\ \mathrm{and}\ \mathbf{y}\ \mathrm{randomly}
14
                calculate estimation of gradient \hat{g} \leftarrow \frac{1}{m} \sum_{i=1}^{m} L(f(\mathbf{x}^{i}; \theta), \mathbf{y}^{i})
15
                update velocity v \leftarrow \beta v - \epsilon_j \hat{g}
16
                update weights \theta \leftarrow \theta + v
17
         j \leftarrow j + 1 go to next epoch
18
```