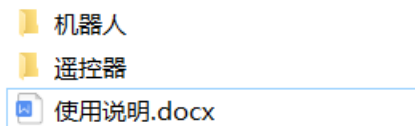1. Please download the Arduino editor yourself and configure it into ESP32 development mode, and set the board options.

2.

1. Download the "robot" and "remote control" programs to the robot and remote control respectively.

1.   Start the robot after starting the remote control. The robot will automatically connect to the hotspot opened by the remote control and then can be controlled.

2. Because the power on both sides is not large, the control distance is only about ten meters. If you want to have a longer distance, you can modify the program to connect to the router. This program is for learning reference only.