# Spatially explicit mapping of ecological similarity across a large region using matching techniques.

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#### Abstract

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7 ABSTRACT

## Plain Language Summary

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### 0.1 Introduction

A global biodiversity crisis is currently underway, driven by anthropogenic changes (Dirzo & Raven, 2003). Pressures such as climate change, land-use changes, and invasive species, are leading to species extinctions (Thomas et al., 2004; Urban, 2015) and the homogenization of biological communities (McGill et al., 2015). The Kunming-Montreal Global Biodiversity Framework (GBF) has been adopted as of December 2022, with the goal of restoring global biodiversity (Report of the conference of the parties to the convention on biological diversity on the second part of its fifteenth meeting, 2023). Targets within this framework include restoring 30% of all degraded ecosystems, and protecting 30% of of Earth's terrestrial, inland water, and marine areas (Report of the conference of the parties to the convention on biological diversity on the second part of its fifteenth meeting, 2023). In the terrestrial environment, forest biomes have been shown to harbour the largest amount of biodiversity (Cardinale et al., 2012; Myers, 1988; Pimm & Raven, 2000), and provide key ecosystem services (Thompson et al., 2009). To provide these services, it is integral that these forest ecosystems are in good ecological condition, as represented by natural or near-natural levels of forest structure, forest function, and forest composition (Marín et al., 2021).

While understanding forest condition is a key aspect of understanding biodiversity and the provision of ecosystem services due to their inherent linkages (Cardinale et al., 2012; Marín et al., 2021), it is difficult to acquire suitable field-derived data across wide expanses of land due to the extreme financial and temporal costs associated with field campaigns. Remote sensing data, however, can provide a timeefficient, cost-effective alternative to field data, providing access to new spatially explicit and exhaustive datasets that can be linked to ecological condition, with additional metrics being proposed at a rapid pace (Pereira et al., 2013; Volker C. Radeloff et al., 2024; Skidmore et al., 2021). Advances in lidar technologies and modelling methods are allowing wall-to-wall estimates of forest stand structure to be generated across entire countries (Becker et al., 2023; Matasci, Hermosilla, Wulder, White, Coops, Hobart, Bolton, et al., 2018; Matasci, Hermosilla, Wulder, White, Coops, Hobart, & Zald, 2018), serving as a finer scale indicator of ecosystem structure than the often previously used landscape fragmentation metrics (Andrew et al., 2012). Productivity metrics have been used as a proxy for ecosystem function for many years (Pettorelli et al., 2005, 2018), with new Landsat derived datasets providing integrative annual estimates of energy availability at a 30 m spatial resolution(V. C. Radeloff et al., 2019; Volker C. Radeloff et al., 2024; Razenkova et al., n.d.). Remote sensing is quickly providing access to a plethora of datasets suitable monitoring the various facets of biodiversity and ecological condition (Noss, 1990). Using these datasets in conjunction with information on the location of known or assumed natural forests can allow researchers to identify similar forest stands or ecosystems, thus locating high quality forests across entire jurisdictions, even when they are facing anthropogenic pressures.

However, identifying natural forests is not a simple task. There are many definitions of what constitutes 'naturalness' in forest environments (Winter, 2012), and these difficulties are compounded by shifting baseline syndrome (Pinnegar & Engelhard, 2008) and a lack of comprehensive historical data to generate reference states (Balaguer et al., 2014). Other proposed methods to delineate baseline conditions include protected areas (Arcese & Sinclair, 1997), and empirical estimates of the reference

state, generated by modelling outcomes (oftentimes species abundances and occurrence) in the absence of anthropogenic disturbance (Nielsen et al., 2007).

In this study, we seek to identify natural forests of good ecological condition at a 60 30 m spatial resolution across British Columbia, Canada. We first identify refer-61 ence states for ecosystems across the province as protected areas with little-to-no 62 anthropogenic disturbances. We then use an expanded coarsened exact matching 63 (CEM) approach to compare the entire forested landscape of British Columbia to 64 a reference state which accounts for forest type as well as topographic and climatic 65 information. We expand the CEM technique to allow for the the spatially explicit reconstruction of natural ecosystem similarity, even when a perfect match is not available. We further examine how the coverage of natural forest areas varies be-68 tween protected and unprotected areas in British Columbia. These methods will 69 allow managers to identify regions in need of restoration, or that could be suitable 70 for protection, and could be expanded to other regions. 71

#### 0.2 Methods

#### 0.2.1 Data

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0.2.1.1 Natural forests

We defined natural forests as forests under formal protection with little-to-no anthropogenic pressure. We obtained boundaries for the protected areas of British Columbia using the wdpar R package (Hanson, 2022 version 1.3.7), and filtered these protected areas larger than 100 ha and in the IUCN categories Ia, Ib, II, and IV Muise et al. (2022). We use the Canadian Human Footprint generated by Hirsh-Pearson et al. (2022), a 300 m estimating of anthropogenic pressures across the entirety of Canada, which accounts for pressures included in the global human footprint (Venter et al., 2016), as well as pressures specific to the Canadian environment. The Canadian Human Footprint considers built environments, crop land, pasture land, human population density, nighttime lights, railways, roads, navigable waterways, dams and associated reservoirs, mining activity, oil and gas, and forestry pressures (Hirsh-Pearson et al., 2022). We consider any pixel within our protected area criteria with a Canadian Human Footprint score below four as representative of natural ecosystems, which balances the tradeoff between having a suitable number of high-quality pixels, and low anthropogenic pressures being represented in the natural areas.

## 0.2.1.2 Forest Ecosystem Structure

Wall-to-wall, 30 m forest structure metrics (canopy height, canopy cover, structural complexity, and aboveground biomass) were generated by Matasci, Hermosilla, Wulder, White, Coops, Hobart, Bolton, et al. (2018) for 2015 across the forested landscape of British Columbia. This data was generated by using a random forestkNN approach, imputing airborne laser scanning derived forest structural attributes across the entirety of Canada using Landsat-derived best-available-pixel (BAP) composites (Hermosilla et al., 2016; White et al., 2014) and topographic information (Matasci, Hermosilla, Wulder, White, Coops, Hobart, Bolton, et al., 2018; Matasci, Hermosilla, Wulder, White, Coops, Hobart, & Zald, 2018). The BAP composites were derived by selecting optical observations from the Landsat archive (including Landsat-5 Thematic Mapper, Landsat-7 Enhanced Thematic Mapper Plus, and Landsat-8 Operational Land Imager imagery) over the course of the growing season, considering atmospheric effects (haze, clouds, cloud shadows) and distance from the desired composite date (in this case, August 31st). Details on the pixel scoring method can be found in White et al. (2014). The BAP composites were further refined by using a spectral trend analysis on the normalized burn ratio to remove noise, and missing pixels are infilled using temporally-interpolated values. This procedure results in gap-free, surface-reflectance image composites (Hermosilla et al., 2015).

#### 0.2.1.3 Forest Ecosystem Function

Landsat DHIs

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0.2.1.4 Auxiliary Datasets

In our matching procedure (see Section ) we use two core datasets as our covariates. Firstly, we use a 30 m digital elevation model and derived slope dataset from the Advanced Spaceborne Thermal Emission and Reflection Radiometer (ASTER) Version 2 GDEM product (Tachikawa et al., 2011). We also match on four climate variables; mean annual precipitation (MAP), mean annual temperature (MAT), mean warmest month temperature (MWMT), and mean coldest month temperature (MCMT) calculated from 1990-2020 climate normals using the ClimateNA software package at a 1 km spatial resolution, and downsampled to 30 m using cubic spline resampling in the **terra** R package (Hijmans, 2024 version 1.7-71) in R (R Core Team, 2024 version 4.4.0).

#### 0.2.2 Matching

To identify natural forests across the province, we implement an expanded coarsened exact matching (CEM) technique (Iacus et al., 2012). This allows us to assess the similarity of all forested pixels in the province to known natural forests, while controlling for covariates such as climate and topography. CEM creates comparable groups of observation among covariates by first coarsening the covariates into meaningful bins. In our case, we coarsen all six of our covariates into 10 quantilebased bins. As an example, elevation observations in the 0-10th percentile would be grouped into elevation bin one, the 10th-20th percentile of observations into bin two, and so on. Following the binning procedure, CEM performs exact matching on the coarsened covariates, and discards any unmatched samples. We diverge from this method by not dropping unmatched samples. Instead, we group our unmatched strata with their nearest neighbour in quartile space, up to a minimum of 30 samples, while minimizing the overall nearest neighbour distance. This method combines the advantages of CEM [no bias checking, simple computation; Iacus et al. (2012)], with the ability to generate wall-to-wall comparisons of our treated cells to all other cells in the province.

0.2.3 Analysis
0.3 Results

0.4 Discussion

0.5 Conclusion

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