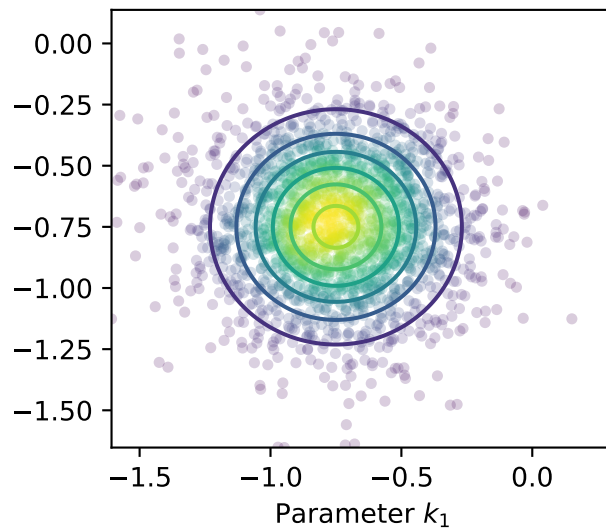
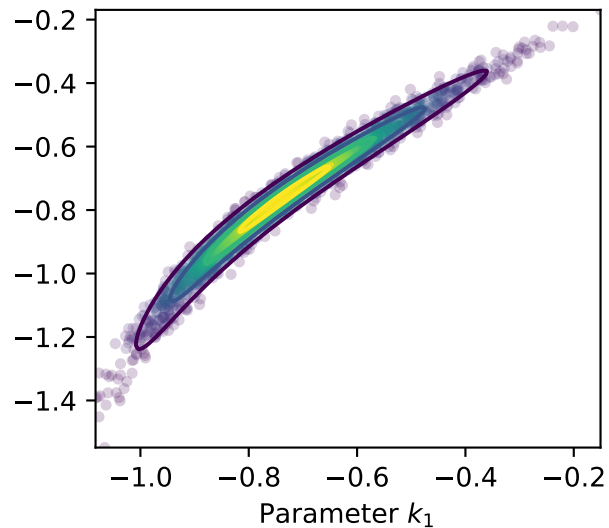
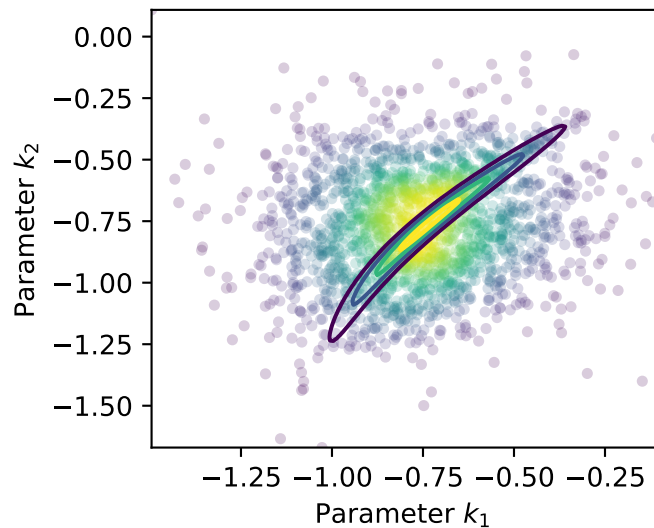


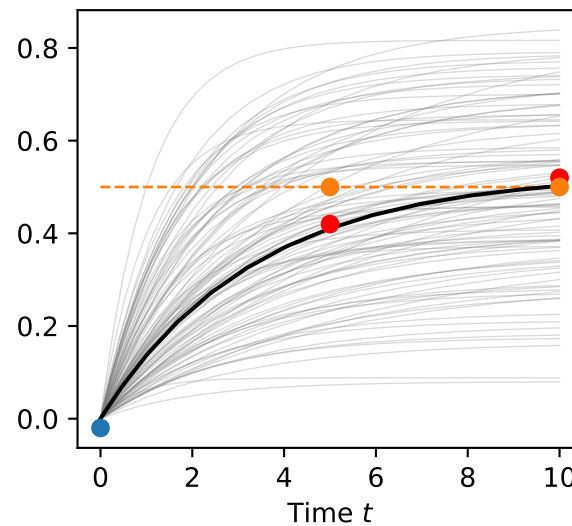
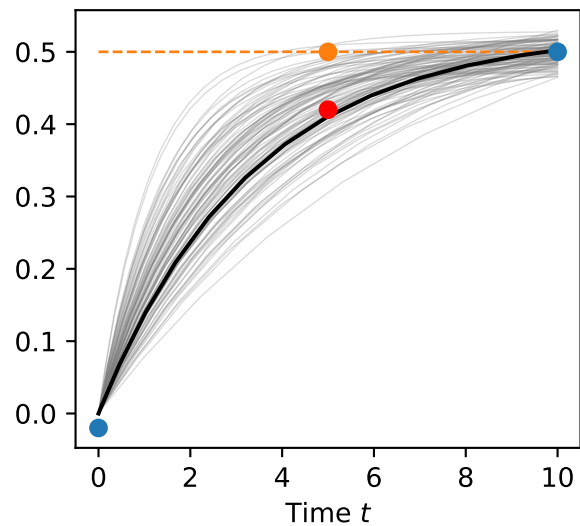
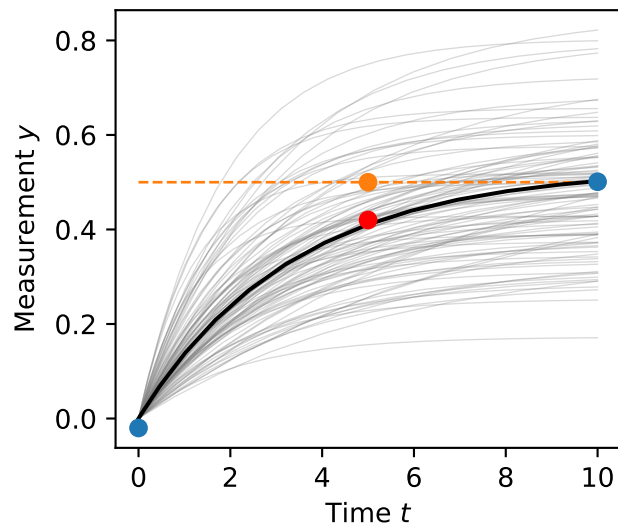
Posterior distribution

Insert 0.5 ✗

Augment by 0/1 ( $c = 0.5$ ) ✓Augment by 0/1 ( $c = 0.5$ ) ✓

— True posterior  
● BayesFlow

Posterior predictive check



— True trajectory  
● Available data  
● Missing data  
● Dummy value  
— Simulation