

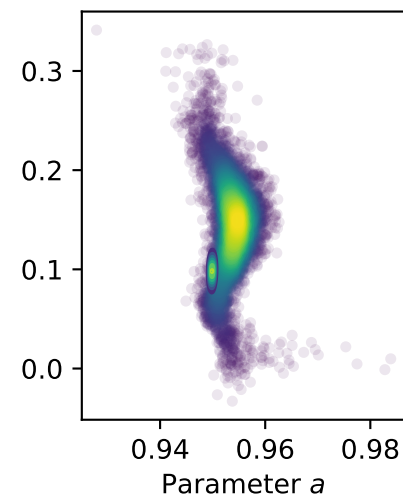
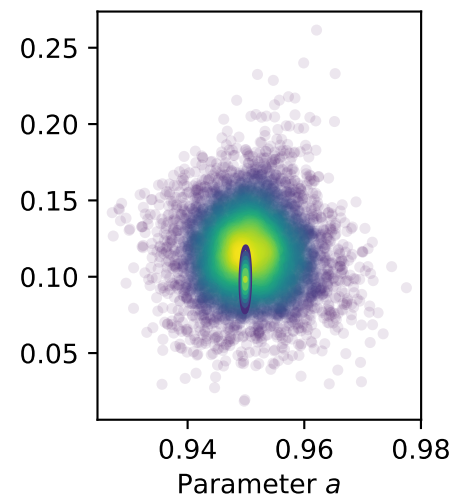
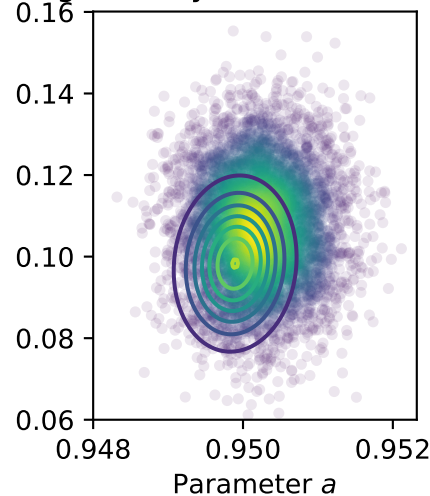
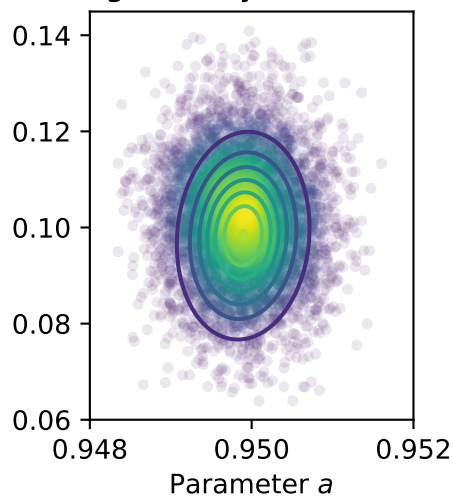
Posterior distribution

Augment by 0/1 (LSTM)

Augment by 0/1 (transformer)

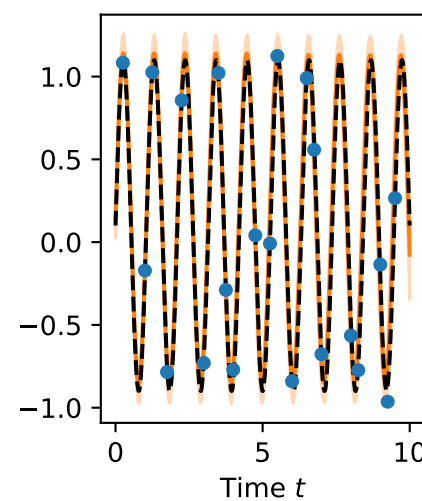
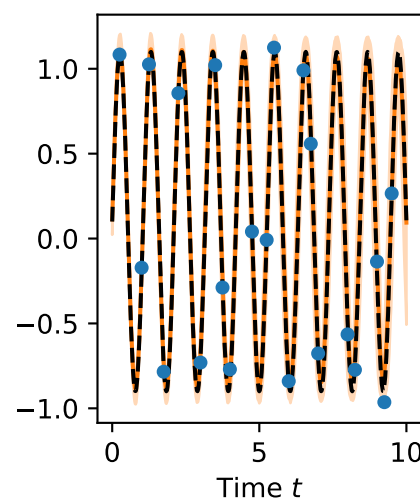
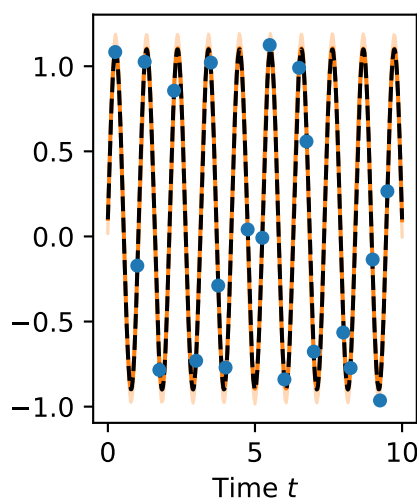
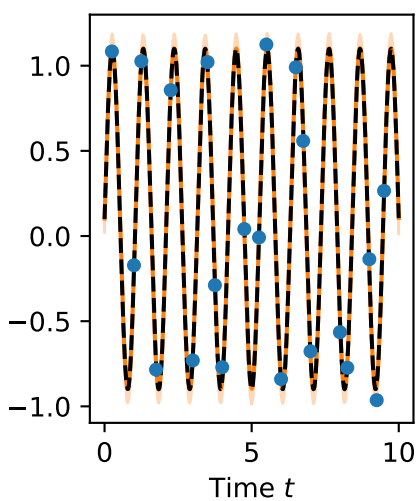
Time labels (LSTM)

Time labels (transformer)



— True posterior  
• BayesFlow

Posterior predictive check



--- True trajectory  
• Available data  
— Simulated mean  
90% CI