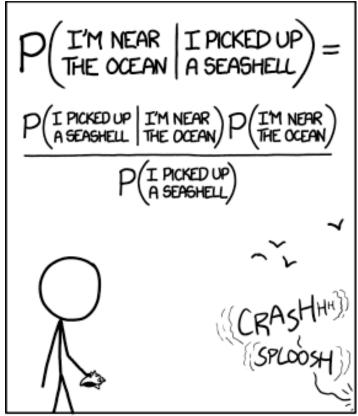
Review: Probability

- Random variables, events
- Axioms of probability
- Atomic events
- Joint and marginal probability distributions
- Conditional probability distributions
- Product rule
- Independence and conditional independence

Bayesian inference, Naïve Bayes model



STATISTICALLY SPEAKING, IF YOU PICK UP A SEASHELL AND DON'T HOLD IT TO YOUR EAR, YOU CAN PROBABLY HEAR THE OCEAN.

http://xkcd.com/1236/



Bayes Rule



Rev. Thomas Bayes (1702-1761)

 The product rule gives us two ways to factor a joint probability:

$$P(A,B) =$$

• Therefore,
$$P(A \mid B) = \frac{P(B \mid A)P(A)}{P(B)}$$

- Why is this useful?
 - Key tool for probabilistic inference: can get diagnostic probability
 from causal probability
 - E.g., P(Cavity | Toothache) from P(Toothache | Cavity)
 - Can update our beliefs based on evidence

Bayes Rule example

• Marie is getting married tomorrow, at an outdoor ceremony in the desert. In recent years, it has rained only 5 days each year (5/365 = 0.014). Unfortunately, the weatherman has predicted rain for tomorrow. When it actually rains, the weatherman correctly forecasts rain 90% of the time. When it doesn't rain, he incorrectly forecasts rain 10% of the time. What is the probability that it will rain on Marie's wedding?

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$$P(\text{Rain} | \text{Predict}) = \frac{P(\text{Predict} | \text{Rain})P(\text{Rain})}{P(\text{Predict} | \text{Rain})P(\text{Rain})}$$

$$= \frac{P(\text{Predict} | \text{Rain})P(\text{Rain})}{P(\text{Predict} | \text{Rain})P(\text{Rain}) + P(\text{Predict} | \neg \text{Rain})P(\neg \text{Rain})}$$

$$= \frac{0.9 \times 0.014}{0.9 \times 0.014 + 0.1 \times 0.986} = \frac{0.0126}{0.0126 + 0.0986} = 0.111$$

Bayes rule: Another example

1% of women at age forty who participate in routine screening have breast cancer. 80% of women with breast cancer will get positive mammographies.
 9.6% of women without breast cancer will also get positive mammographies. A woman in this age group had a positive mammography in a routine screening. What is the probability that she actually has breast cancer?

$$P(\text{Cancer} | \text{Positive}) = \frac{P(\text{Positive} | \text{Cancer})P(\text{Cancer})}{P(\text{Positive})}$$

$$= \frac{P(\text{Positive} | \text{Cancer})P(\text{Cancer})}{P(\text{Positive} | \text{Cancer})P(\text{Cancer}) + P(\text{Positive} | \neg \text{Cancer})P(\neg \text{Cancer})}$$

$$= \frac{0.8 \times 0.01}{0.8 \times 0.01 + 0.096 \times 0.99} = \frac{0.008}{0.008 + 0.095} = 0.0776$$



Probabilistic inference

- Suppose the agent has to make a decision about the value of an unobserved query variable X given some observed evidence variable(s) E = e
 - Partially observable, stochastic, episodic environment
 - Examples: X = {spam, not spam}, e = email message
 X = {zebra, giraffe, hippo}, e = image features



Dear Sir.

First, I must solicit your confidence in this transaction, this is by virture of its nature as being utterly confidencial and top secret. ...

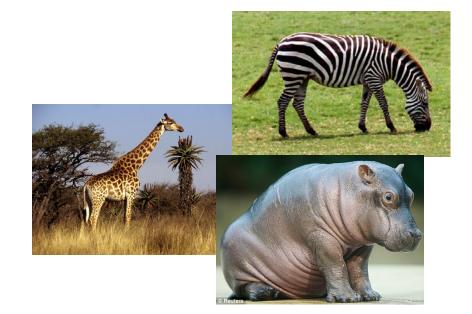


TO BE REMOVED FROM FUTURE MAILINGS, SIMPLY REPLY TO THIS MESSAGE AND PUT "REMOVE" IN THE SUBJECT.

99 MILLION EMAIL ADDRESSES FOR ONLY \$99



Ok, Iknow this is blatantly OT but I'm beginning to go insane. Had an old Dell Dimension XPS sitting in the corner and decided to put it to use, I know it was working pre being stuck in the corner, but when I plugged it in, hit the power nothing happened.





Bayesian decision theory

- Let x be the value predicted by the agent and x* be the true value of X.
- The agent has a **loss function**, which is 0 if $x = x^*$ and 1 otherwise
- Expected loss:

$$\sum_{x} L(x^*, x) P(x \mid e) :$$

- What is the estimate of X that minimizes the expected loss?
 - The one that has the greatest posterior probability P(x|e)
 - This is called the Maximum a Posteriori (MAP) decision

MAP decision

 Value x of X that has the highest posterior probability given the evidence E = e:

$$x^* = \operatorname{arg\,max}_x P(X = x \mid E = e) = \frac{P(E = e \mid X = x)P(X = x)}{P(E = e)}$$

$$\propto \operatorname{arg\,max}_x P(E = e \mid X = x)P(X = x)$$

$$P(x | e) \propto P(e | x)P(x)$$
posterior likelihood prior

Maximum likelihood (ML) decision:

$$x^* = \arg\max_{x} P(e \mid x)$$

Naïve Bayes model

- Suppose we have many different types of observations (symptoms, features) E_1, \ldots, E_n that we want to use to obtain evidence about an underlying hypothesis X
- MAP decision involves estimating

$$P(X | E_1, ..., E_n) \propto P(E_1, ..., E_n | X) P(X)$$

- If each feature E_i can take on k values, how many entries are in the (conditional) joint probability table $P(E_1, ..., E_n | X = x)$?

Naïve Bayes model

- Suppose we have many different types of observations (symptoms, features) E_1, \ldots, E_n that we want to use to obtain evidence about an underlying hypothesis X
- MAP decision involves estimating

$$P(X | E_1, ..., E_n) \propto P(E_1, ..., E_n | X) P(X)$$

 We can make the simplifying assumption that the different features are conditionally independent given the hypothesis:

$$P(E_1,...,E_n \mid X) = \prod_{i=1}^n P(E_i \mid X)$$

– If each feature can take on k values, what is the complexity of storing the resulting distributions?

Naïve Bayes model

Posterior:

$$P(X = x | E_1 = e_1, ..., E_n = e_n)$$

MAP decision:

$$x^* = \operatorname{arg\,max}_x P(x \mid e) \propto P(x) \prod_{i=1}^n P(e_i \mid x)$$
posterior prior likelihood

Case study: Spam filter

 MAP decision: to minimize the probability of error, we should classify a message as spam if

P(spam | message) > P(¬spam | message)





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Case study: Spam filter

 MAP decision: to minimize the probability of error, we should classify a message as spam if

```
P(spam | message) > P(¬spam | message)
```

- To enable classification, we need to be able to estimate the likelihoods P(message | spam) and P(message | ¬spam) and priors P(spam) and P(¬spam)

Naïve Bayes Representation

- Goal: estimate likelihoods P(message | spam) and P(message | ¬spam) and priors P(spam) and P(¬spam)
- Likelihood: bag of words representation
 - The message is a sequence of words $(w_1, ..., w_n)$
 - The order of the words in the message is not important
 - Each word is conditionally independent of the others given message class (spam or not spam)

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Bag of words illustration

2007-01-23: State of the Union Address

George W. Bush (2001-)

abandon accountable affordable afghanistan africa aided ally anbar armed army baghdad bless challenges chamber chaos choices civilians coalition commanders commitment confident confront congressman constitution corps debates deduction deficit deliver democratic deploy dikembe diplomacy disruptions earmarks economy einstein elections eliminates expand extremists failing faithful families freedom fuel funding god haven ideology immigration impose

insurgents iran iraq islam julie lebanon love madam marine math medicare moderation neighborhoods nuclear offensive palestinian payroll province pursuing qaeda radical regimes resolve retreat rieman sacrifices science sectarian senate

september shia stays strength students succeed sunni tax territories terrorists threats uphold victory violence violent War washington weapons wesley

Bag of words illustration



Bag of words illustration



Naïve Bayes Representation

- Goal: estimate likelihoods P(message | spam) and
 P(message | ¬spam) and priors P(spam) and P(¬spam)
- Likelihood: bag of words representation
 - The message is a sequence of words $(w_1, ..., w_n)$
 - The order of the words in the message is not important
 - Each word is conditionally independent of the others given message class (spam or not spam)

$$P(message \mid spam) = P(w_1, ..., w_n \mid spam) = \prod_{i=1}^n P(w_i \mid spam)$$

 Thus, the problem is reduced to estimating marginal likelihoods of individual words P(w_i | spam) and P(w_i | ¬spam)

Summary: Decision rule

General MAP rule for Naïve Bayes:

$$x^* = \arg\max_{x} P(x \mid e) \propto P(x) \prod_{i=1}^{n} P(e_i \mid x)$$

posterior prior likelihood

$$P(spam \mid w_1, ..., w_n) \propto P(spam) \prod_{i=1}^{n} P(w_i \mid spam)$$

Thus, the filter should classify the message as spam if

$$P(spam)\prod_{i=1}^{n}P(w_{i}|spam) > P(\neg spam)\prod_{i=1}^{n}P(w_{i}|\neg spam)$$

Parameter estimation

- Model parameters: feature likelihoods P(word | spam) and P(word | ¬spam) and priors P(spam) and P(¬spam)
 - How do we obtain the values of these parameters?

prior

spam: 0.33 ¬spam: 0.67

P(word | spam)

the: 0.0156
to: 0.0153
and: 0.0115
of: 0.0095
you: 0.0093
a: 0.0086
with: 0.0080
from: 0.0075

P(word | ¬spam)

the: 0.0210
to: 0.0133
of: 0.0119
2002: 0.0110
with: 0.0108
from: 0.0107
and: 0.0105
a: 0.0100

Parameter estimation

- Model parameters: feature likelihoods P(word | spam) and P(word | ¬spam) and priors P(spam) and P(¬spam)
 - How do we obtain the values of these parameters?
 - Need training set of labeled samples from both classes

 This is the maximum likelihood (ML) estimate, or estimate that maximizes the likelihood of the training data:

$$\prod_{d=1}^{D} \prod_{i=1}^{n_d} P(w_{d,i} \mid class_{d,i})$$

d: index of training document, i: index of a word

Parameter estimation

Parameter estimate:

```
P(word | spam) = # of word occurrences in spam messages total # of words in spam messages
```

- Parameter smoothing: dealing with words that were never seen or seen too few times
 - Laplacian smoothing: pretend you have seen every vocabulary word one more time than you actually did

(V: total number of unique words)

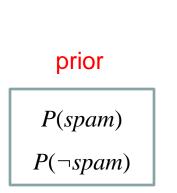
Summary of model and parameters

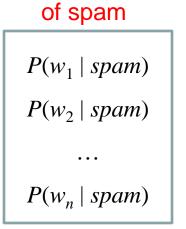
Naïve Bayes model:

$$P(spam \mid message) \propto P(spam) \prod_{i=1}^{n} P(w_i \mid spam)$$

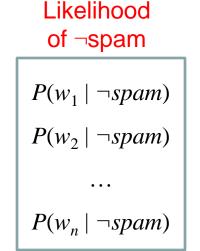
 $P(\neg spam \mid message) \propto P(\neg spam) \prod_{i=1}^{n} P(w_i \mid \neg spam)$

Model parameters:





Likelihood





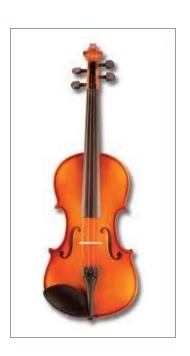




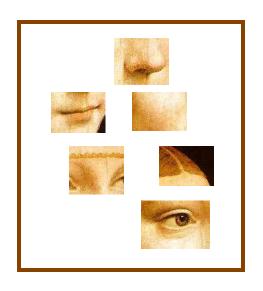
1. Extract image features







1. Extract image features



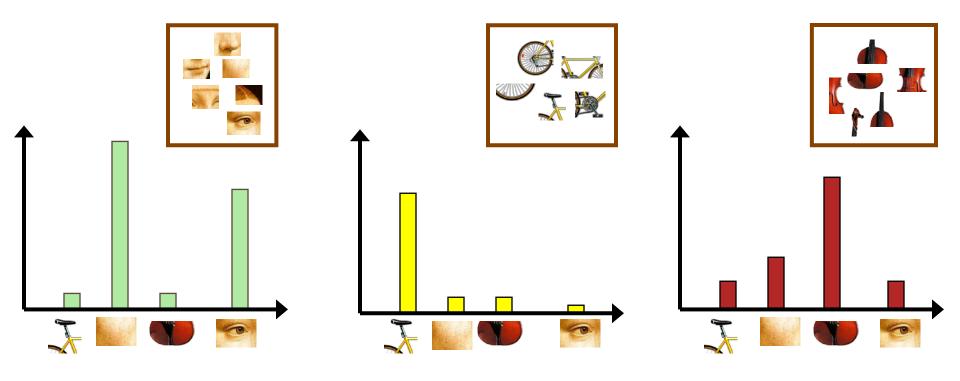




- 1. Extract image features
- 2. Learn "visual vocabulary"



- 1. Extract image features
- 2. Learn "visual vocabulary"
- 3. Map image features to visual words



Bayesian decision making: Summary

- Suppose the agent has to make decisions about the value of an unobserved query variable X based on the values of an observed evidence variable E
- Inference problem: given some evidence E = e, what is P(X | e)?
- Learning problem: estimate the parameters of the probabilistic model $P(X \mid E)$ given a *training* sample $\{(x_1,e_1), ..., (x_n,e_n)\}$