

MAECS

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## Chapter 1

# MAECS: Model for Adaptive Ecosystems in Coastal Seas

### 1.1 General Overview

The goal of MAECS is...

maybe some script here

### 1.2 References

- K. W. Wirtz and M. Pahlow (2010): ...



## Chapter 2

## Todo List

Type `fabm_hzg_maecs::type_hzg_maecs`  
describe the `type_hzg_maecs`





## Chapter 3

# Data Type Index

### 3.1 Class Hierarchy

This inheritance list is sorted roughly, but not completely, alphabetically:

fabm_hzg_maecs . . . . .	11
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maecs_types::type_maecs_zoo . . . . .	19



## Chapter 4

# Data Type Index

### 4.1 Data Types List

Here are the data types with brief descriptions:

<a href="#">fabm_hzg_maecs</a>	
The MAECS module contains initialize do (=> maecs_do) get_light_extinction get_vertical_	
movement (=> <a href="#">maecs_get_vertical_movement</a> ) and maybe some humanly explanation here	11
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<a href="#">maecs_types::type_maecs_zoo</a>	19



## Chapter 5

# File Index

### 5.1 File List

Here is a list of all documented files with brief descriptions:

<a href="#">maecs.F90</a>	
Main MAECS module . . . . .	<a href="#">21</a>



## Chapter 6

# Data Type Documentation

### 6.1 fabm\_hzg\_maecs Module Reference

The MAECS module contains initialize do (=> maecs\_do) get\_light\_extinction get\_vertical\_movement (=> [maecs-get\\_vertical\\_movement](#)) and maybe some humanly explanation here.

#### Data Types

- interface [maecs\\_get\\_vertical\\_movement](#)  
*Brief description of routine.*
- type [type\\_hzg\\_maecs](#)  
*here we extend a model*

#### 6.1.1 Detailed Description

The MAECS module contains initialize do (=> maecs\_do) get\_light\_extinction get\_vertical\_movement (=> [maecs-get\\_vertical\\_movement](#)) and maybe some humanly explanation here.

The documentation for this module was generated from the following file:

- [maecs.F90](#)

### 6.2 maecs\_functions Module Reference

#### Public Member Functions

- pure real(rk) function, public **smooth\_small** (x, eps)
- pure real(rk) function, public **uptflex** (Aff0, Vmax0, Nut, fAv)
- pure real(rk) function, public **queuefunc0** (n, x)
- subroutine, public **queuefunc** (n, x, qfunc, qderiv)
- real(rk) function, public **queuederiv** (n, x)
- subroutine, public **sinking** (vS, phys\_status, sinkvel)
- subroutine, public **min\_mass** (maecs, phy, method)
- subroutine, public **calc\_rel\_chloropl** (maecs, phy, method)
- subroutine, public **calc\_sensitivities** (maecs, sens, phy, env, nut)
- subroutine, public **calc\_internal\_states** (maecs, phy, det, dom, zoo)

The documentation for this module was generated from the following file:

- [maecs\\_functions.F90](#)

## 6.3 fabm\_hzg\_maecs::maecs\_get\_vertical\_movement Interface Reference

Brief description of routine.

### 6.3.1 Detailed Description

Brief description of routine.

#### Author

Routine Author Name and Affiliation. Flow method (rate of change of position) used by integrator. Compute  $\frac{d\lambda}{dt}$ ,  $\frac{d\phi}{dt}$ ,  $\frac{dz}{dt}$

#### Parameters

in	<i>inParam</i>	
out	<i>outParam</i>	

#### Returns

returnValue

The documentation for this interface was generated from the following file:

- [maecs.F90](#)

## 6.4 maecs\_grazing Module Reference

### Public Member Functions

- subroutine, public **grazing** (lmax, HalfSat, preyconc, rate)
- subroutine, public **grazing\_losses** (zoo, resC, Q\_pre, lossZNut, lossZDet, mswitch)

The documentation for this module was generated from the following file:

- [maecs\\_grazing.F90](#)

## 6.5 maecs\_primprod Module Reference

### Public Member Functions

- subroutine, public **photosynthesis** (self, sens, phy, uptake, exud, acc)

The documentation for this module was generated from the following file:

- [maecs\\_primprod.F90](#)

## 6.6 maecs\_types Module Reference

### Data Types

- type [type\\_maecs\\_allocation\\_fractions](#)



- type [type\\_maecs\\_base\\_model](#)
- type [type\\_maecs\\_derivative](#)
- type [type\\_maecs\\_env](#)
- type [type\\_maecs\\_om](#)
- type [type\\_maecs\\_phy](#)
- type [type\\_maecs\\_rhs](#)
- type [type\\_maecs\\_sensitivities](#)
- type [type\\_maecs\\_switch](#)
- type [type\\_maecs\\_traitdyn](#)
- type [type\\_maecs\\_zoo](#)

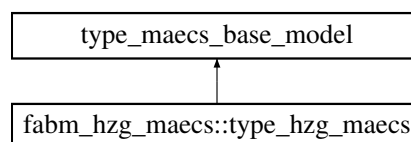
The documentation for this module was generated from the following file:

- [maecs\\_types.F90](#)

## 6.7 fabm\_hzg\_maecs::type\_hzg\_maecs Type Reference

here we extend a model

Inheritance diagram for fabm\_hzg\_maecs::type\_hzg\_maecs:



### Public Member Functions

- procedure **initialize**
- procedure **do** => [maecs\\_do](#)  
*initializes*
- procedure **get\_light\_extinction**
- procedure **get\_vertical\_movement** => [maecs\\_get\\_vertical\\_movement](#)

### 6.7.1 Detailed Description

here we extend a model

**Todo** describe the [type\\_hzg\\_maecs](#)

The documentation for this type was generated from the following file:

- [maecs.F90](#)

## 6.8 maecs\_types::type\_maecs\_allocation\_fractions Type Reference

### Public Attributes

- real(rk) **rub**
- real(rk) **theta**

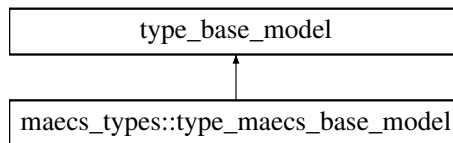
- real(rk) **nutupt**
- real(rk) **totfree**
- real(rk) **rel\_phys**

The documentation for this type was generated from the following file:

- maecs\_types.F90

## 6.9 maecs\_types::type\_maecs\_base\_model Type Reference

Inheritance diagram for maecs\_types::type\_maecs\_base\_model:



### Public Attributes

- type(type\_state\_variable\_id) **id\_nutn**
- type(type\_state\_variable\_id) **id\_nutp**
- type(type\_state\_variable\_id) **id\_nuts**
- type(type\_state\_variable\_id) **id\_phyc**
- type(type\_state\_variable\_id) **id\_phyn**
- type(type\_state\_variable\_id) **id\_phyp**
- type(type\_state\_variable\_id) **id\_phys**
- type(type\_state\_variable\_id) **id\_zooc**
- type(type\_state\_variable\_id) **id\_detc**
- type(type\_state\_variable\_id) **id\_detn**
- type(type\_state\_variable\_id) **id\_detp**
- type(type\_state\_variable\_id) **id\_dets**
- type(type\_state\_variable\_id) **id\_domc**
- type(type\_state\_variable\_id) **id\_domn**
- type(type\_state\_variable\_id) **id\_domp**
- type(type\_state\_variable\_id) **id\_rub**
- type(type\_state\_variable\_id) **id\_chl**
- type(type\_dependency\_id) **id\_temp**
- type(type\_dependency\_id) **id\_par**
- type(type\_diagnostic\_variable\_id) **id\_chl2**
- type(type\_diagnostic\_variable\_id) **id\_fracr**
- type(type\_diagnostic\_variable\_id) **id\_qn**
- type(type\_diagnostic\_variable\_id) **id\_qp**
- type(type\_diagnostic\_variable\_id) **id\_tmp**
- type(type\_conserved\_quantity\_id) **id\_totc**
- type(type\_conserved\_quantity\_id) **id\_totn**
- type(type\_conserved\_quantity\_id) **id\_totp**
- type(type\_conserved\_quantity\_id) **id\_tots**
- real(rk) **nutn\_initial**
- real(rk) **nutp\_initial**
- real(rk) **nuts\_initial**
- real(rk) **phyc\_initial**

- real(rk) **phyn\_initial**
- real(rk) **phyp\_initial**
- real(rk) **phys\_initial**
- real(rk) **zooc\_initial**
- real(rk) **detc\_initial**
- real(rk) **detn\_initial**
- real(rk) **detp\_initial**
- real(rk) **dets\_initial**
- real(rk) **domc\_initial**
- real(rk) **domn\_initial**
- real(rk) **domp\_initial**
- real(rk) **frac\_rub\_ini**
- real(rk) **frac\_chl\_ini**
- real(rk) **p\_max**
- real(rk) **alpha**
- real(rk) **sigma**
- real(rk) **theta\_lhc**
- real(rk) **rel\_chloropl\_min**
- real(rk) **qn\_phy\_0**
- real(rk) **qn\_phy\_max**
- real(rk) **v\_nc\_max**
- real(rk) **affn**
- real(rk) **zeta\_cn**
- real(rk) **exud\_phy**
- real(rk) **qp\_phy\_0**
- real(rk) **qp\_phy\_max**
- real(rk) **v\_pc\_max**
- real(rk) **affp**
- real(rk) **qsi\_phy\_0**
- real(rk) **qsi\_phy\_max**
- real(rk) **v\_sic\_max**
- real(rk) **affsi**
- real(rk) **syn\_nut**
- real(rk) **adap\_rub**
- real(rk) **adap\_theta**
- real(rk) **tau\_regv**
- real(rk) **phi\_agg**
- real(rk) **vs\_phy**
- real(rk) **vs\_det**
- real(rk) **hydrol**
- real(rk) **remin**
- real(rk) **ae\_all**
- real(rk) **t\_ref**
- real(rk) **const\_nc\_zoo**
- real(rk) **const\_pc\_zoo**
- real(rk) **g\_max**
- real(rk) **k\_grazc**
- real(rk) **yield\_zoo**
- real(rk) **basal\_resp\_zoo**
- real(rk) **mort\_zoo**
- real(rk) **a\_water**
- real(rk) **a\_spm**
- real(rk) **a\_chl**
- real(rk) **frac\_par**
- real(rk) **small**

- `real(rk) dil`
- `real(rk) k_qn_phy`
- `real(rk) ik_qn`
- `real(rk) ik_qp`
- `real(rk) itheta_max`
- `real(rk) aver_qn_phy`
- `real(rk) aver_qp_phy`
- `real(rk) small_finite`
- `logical rubiscoon`
- `logical photoacclimon`
- `logical phosphoruson`
- `logical siliconon`
- `logical grazingon`
- `logical biocarbochemon`
- `logical biooxyon`
- `logical debugdiagon`
- `logical chemostaton`
- `logical uptakelock`
- `logical detritus_no_river_dilution`
- `logical plankton_no_river_dilution`

The documentation for this type was generated from the following file:

- `maecs_types.F90`

## 6.10 `maecs_types::type_maecs_derivative` Type Reference

### Public Attributes

- `real(rk) dregv`
- `real(rk) dtheta`
- `real(rk) dfracr`
- `real(rk) dfracp`
- `real(rk) dqn`

The documentation for this type was generated from the following file:

- `maecs_types.F90`

## 6.11 `maecs_types::type_maecs_env` Type Reference

### Public Attributes

- `real(rk) temp`
- `real(rk) par`

The documentation for this type was generated from the following file:

- `maecs_types.F90`

## 6.12 maecs\_types::type\_maecs\_om Type Reference

### Public Attributes

- real(rk) **c**
- real(rk) **n**
- real(rk) **p**
- real(rk) **s**

The documentation for this type was generated from the following file:

- maecs\_types.F90

## 6.13 maecs\_types::type\_maecs\_phy Type Reference

### Public Attributes

- real(rk) **c**
- real(rk) **n**
- real(rk) **p**
- real(rk) **s**
- real(rk) **c\_reg**
- real(rk) **n\_reg**
- real(rk) **p\_reg**
- real(rk) **chl**
- real(rk) **rub**
- real(rk) **rel\_chloropl**
- real(rk) **rel\_qn**
- real(rk) **rel\_qp**
- real(rk) **rel\_qsi**
- real(rk) **qn**
- real(rk) **qp**
- real(rk) **qsi**
- real(rk) **qpqn**
- real(rk) **theta**
- type([type\\_maecs\\_allocation\\_fractions](#)) **frac**

The documentation for this type was generated from the following file:

- maecs\_types.F90

## 6.14 maecs\_types::type\_maecs\_rhs Type Reference

### Public Attributes

- real(rk) **nutn**
- real(rk) **nutp**
- real(rk) **nuts**
- real(rk) **phyc**
- real(rk) **phyn**
- real(rk) **phyp**
- real(rk) **phys**

- real(rk) **zooc**
- real(rk) **detc**
- real(rk) **detn**
- real(rk) **detp**
- real(rk) **dets**
- real(rk) **domc**
- real(rk) **domn**
- real(rk) **domp**
- real(rk) **rub**
- real(rk) **chl**

The documentation for this type was generated from the following file:

- maecs\_types.F90

## 6.15 maecs\_types::type\_maecs\_sensitivities Type Reference

### Public Attributes

- real(rk) **func\_t**
- real(rk) **p\_max\_t**
- real(rk) **a\_light**
- real(rk) **s\_phot**
- real(rk) **up\_nc**
- real(rk) **up\_pc**
- real(rk) **up\_sic**

The documentation for this type was generated from the following file:

- maecs\_types.F90

## 6.16 maecs\_types::type\_maecs\_switch Type Reference

### Public Attributes

- logical **isp**
- logical **issi**
- logical **istoting**

The documentation for this type was generated from the following file:

- maecs\_types.F90

## 6.17 maecs\_types::type\_maecs\_traitdyn Type Reference

### Public Attributes

- real(rk) **dtheta\_dt**
- real(rk) **dfracr\_dt**
- real(rk) **drchl\_dtheta**
- real(rk) **drchl\_dfracr**

- real(rk) **drchl\_dqn**
- real(rk) **tmp**
- real(rk) **fac1**
- real(rk) **fac2**

The documentation for this type was generated from the following file:

- maecs\_types.F90

## 6.18 maecs\_types::type\_maecs\_zoo Type Reference

### Public Attributes

- real(rk) **c**
- real(rk) **n**
- real(rk) **p**
- real(rk) **yield**
- real(rk) **flopp**
- real(rk) **qn**
- real(rk) **qp**
- real(rk) **feeding**

The documentation for this type was generated from the following file:

- maecs\_types.F90





# Chapter 7

## File Documentation

### 7.1 maecs.F90 File Reference

main MAECS module

```
#include "fabm_driver.h"
```

#### Data Types

- module [fabm\\_hzg\\_maecs](#)  
*The MAECS module contains initialize do (=> maecs\_do) get\_light\_extinction get\_vertical\_movement (=> [maecs\\_get\\_vertical\\_movement](#)) and maybe some humanly explanation here.*
- type [fabm\\_hzg\\_maecs::type\\_hzg\\_maecs](#)  
*here we extend a model*
- interface [fabm\\_hzg\\_maecs::maecs\\_get\\_vertical\\_movement](#)  
*Brief description of routine.*

#### 7.1.1 Detailed Description

main MAECS module

##### Author

Richard Hofmeister, Markus Schartau, Kai Wirtz, Onur Kerimoglu

##### Copyright

HZG

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