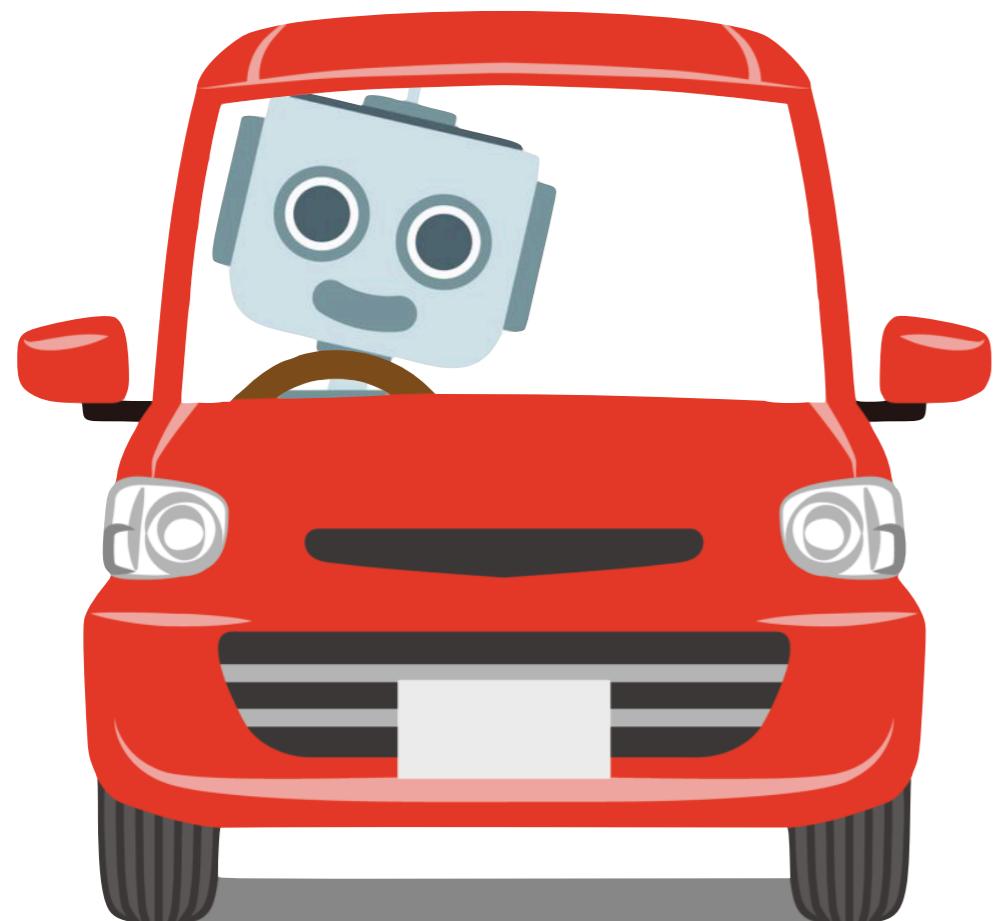


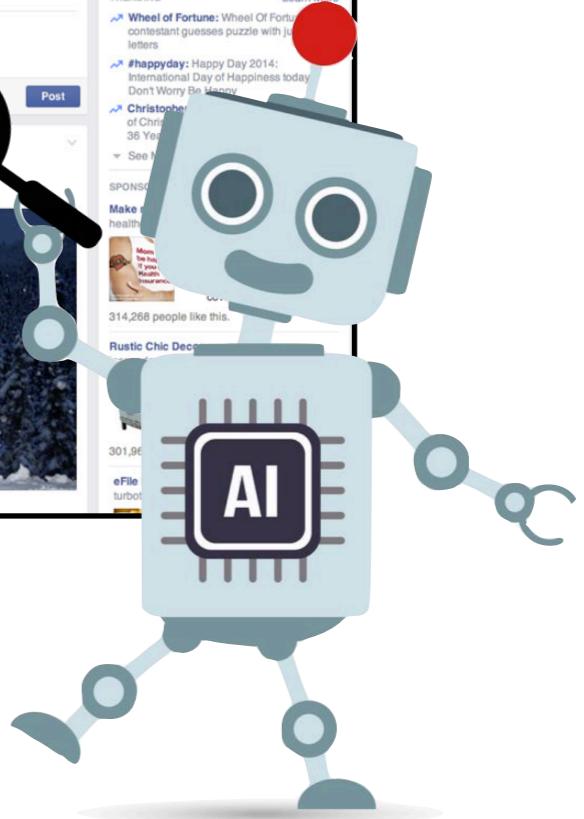
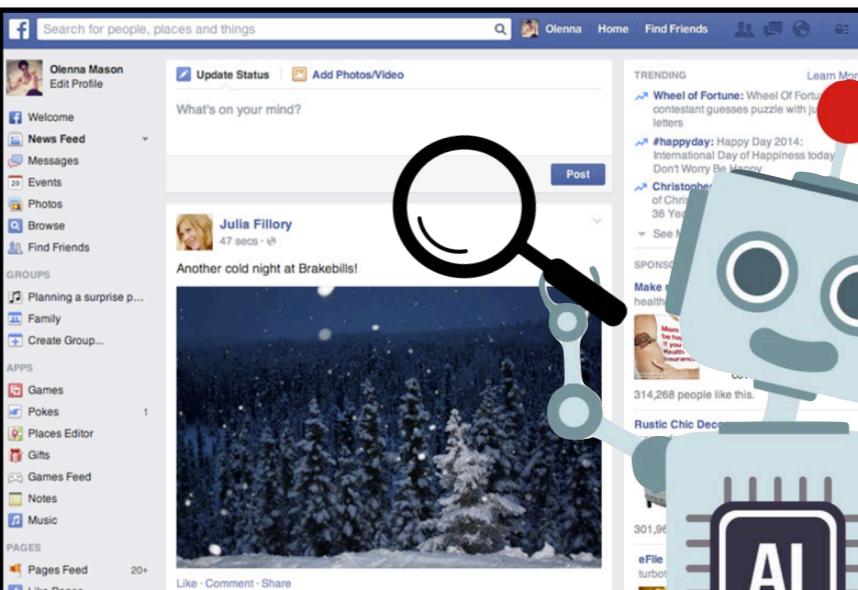
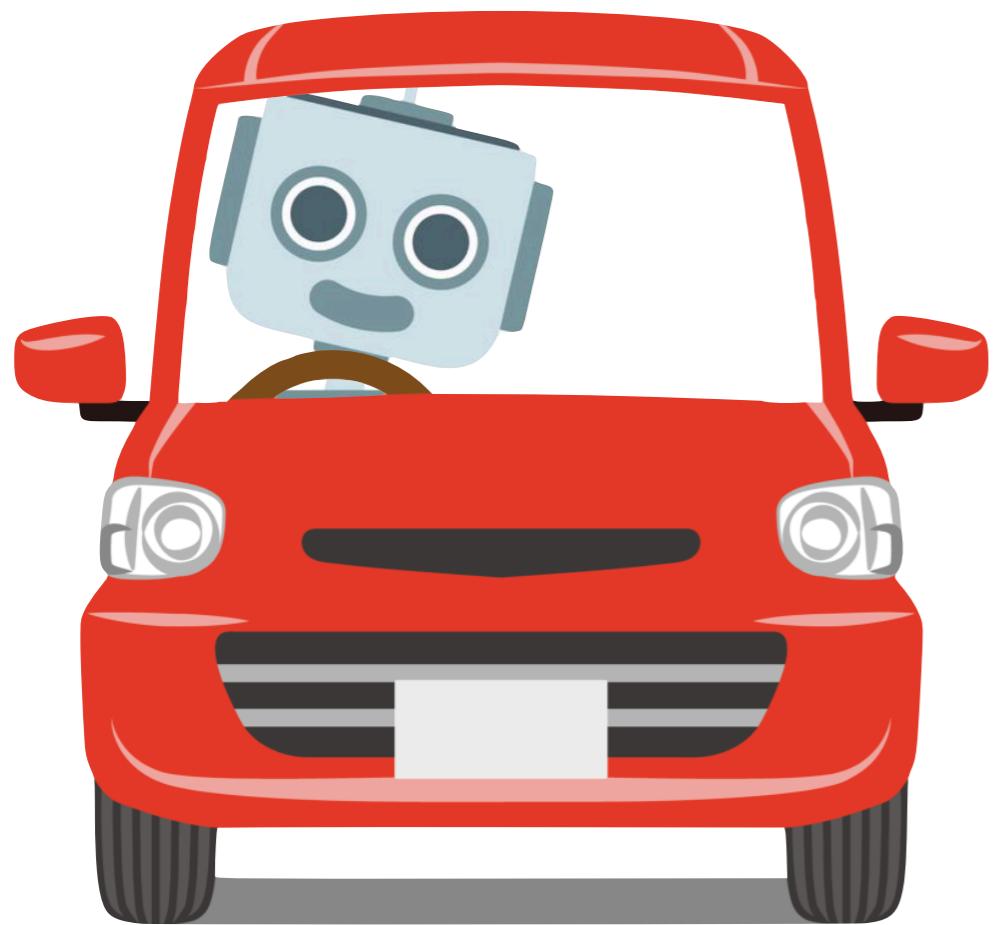
Learning to Defer to One, Multiple, or a Population of Expert(s)

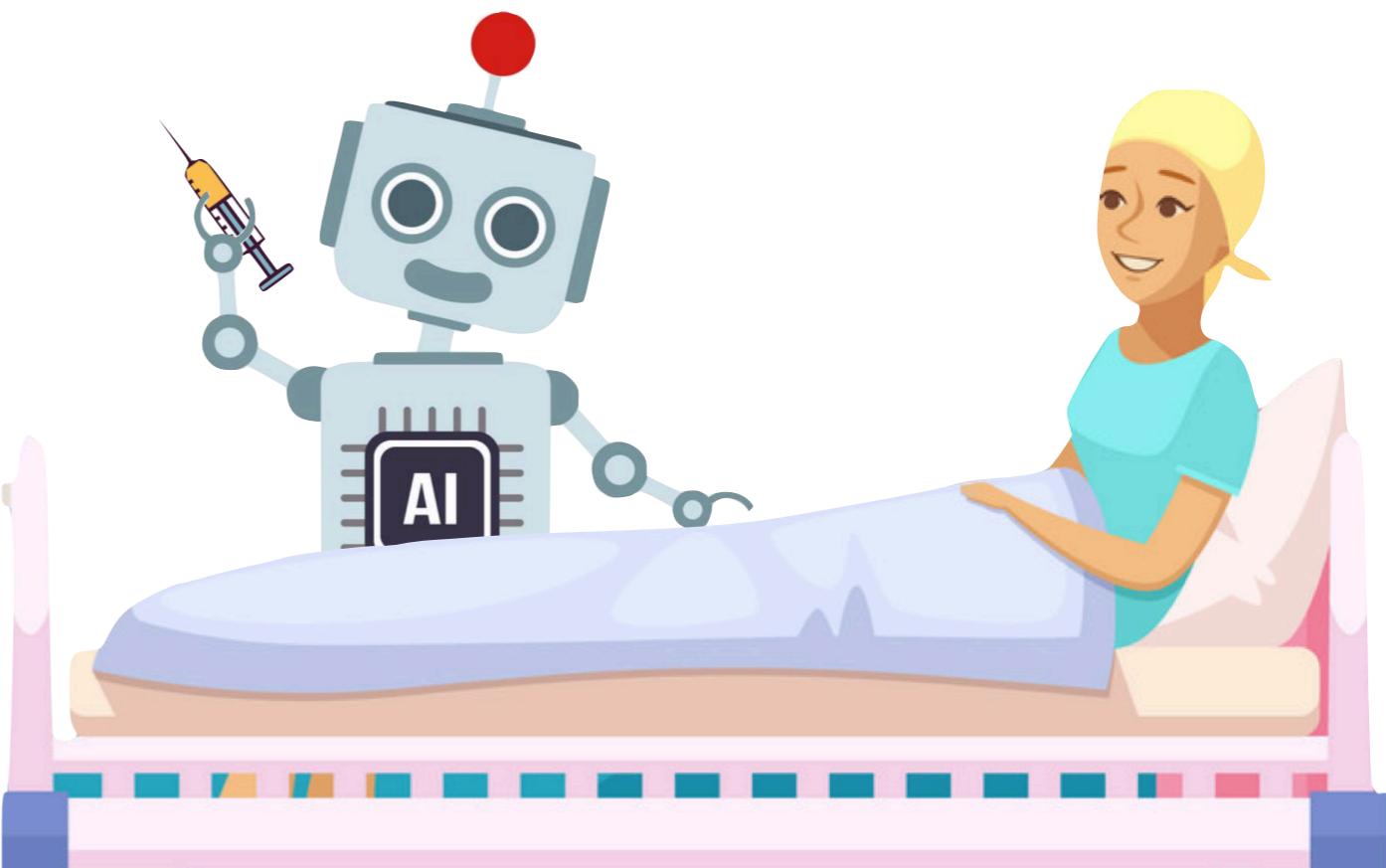
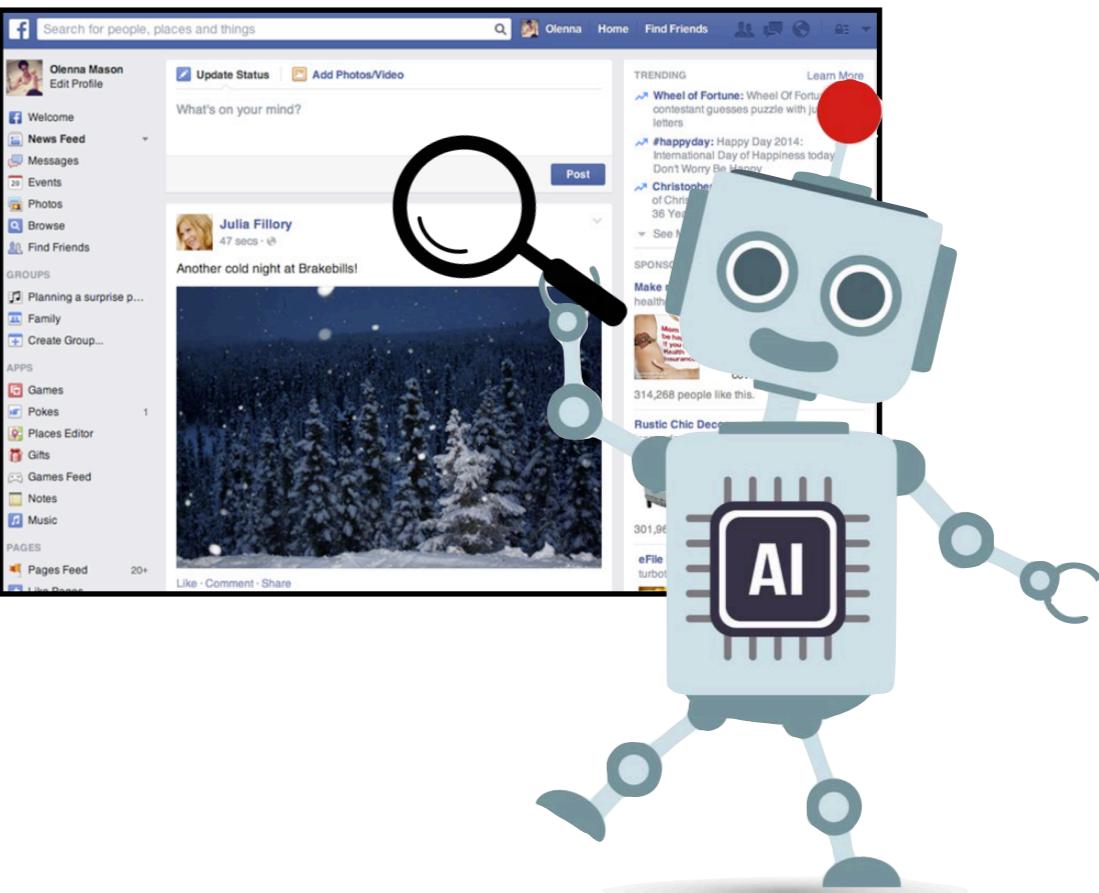
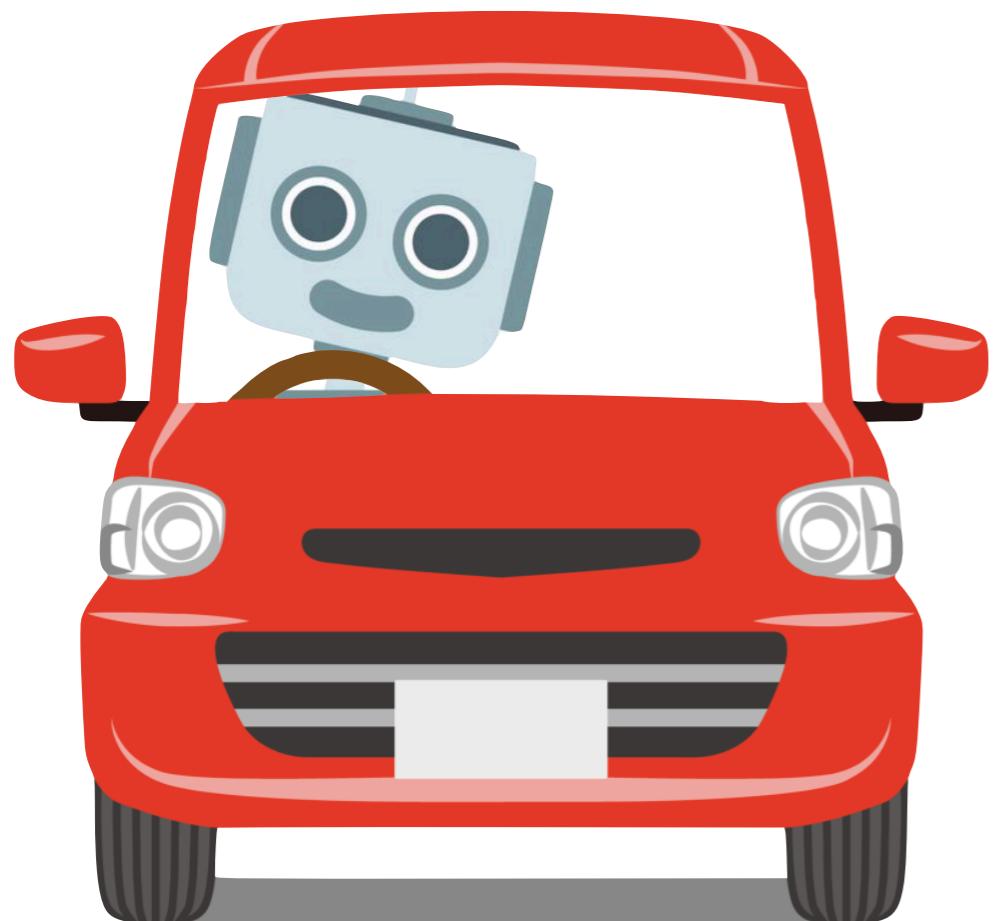
Eric Nalisnick

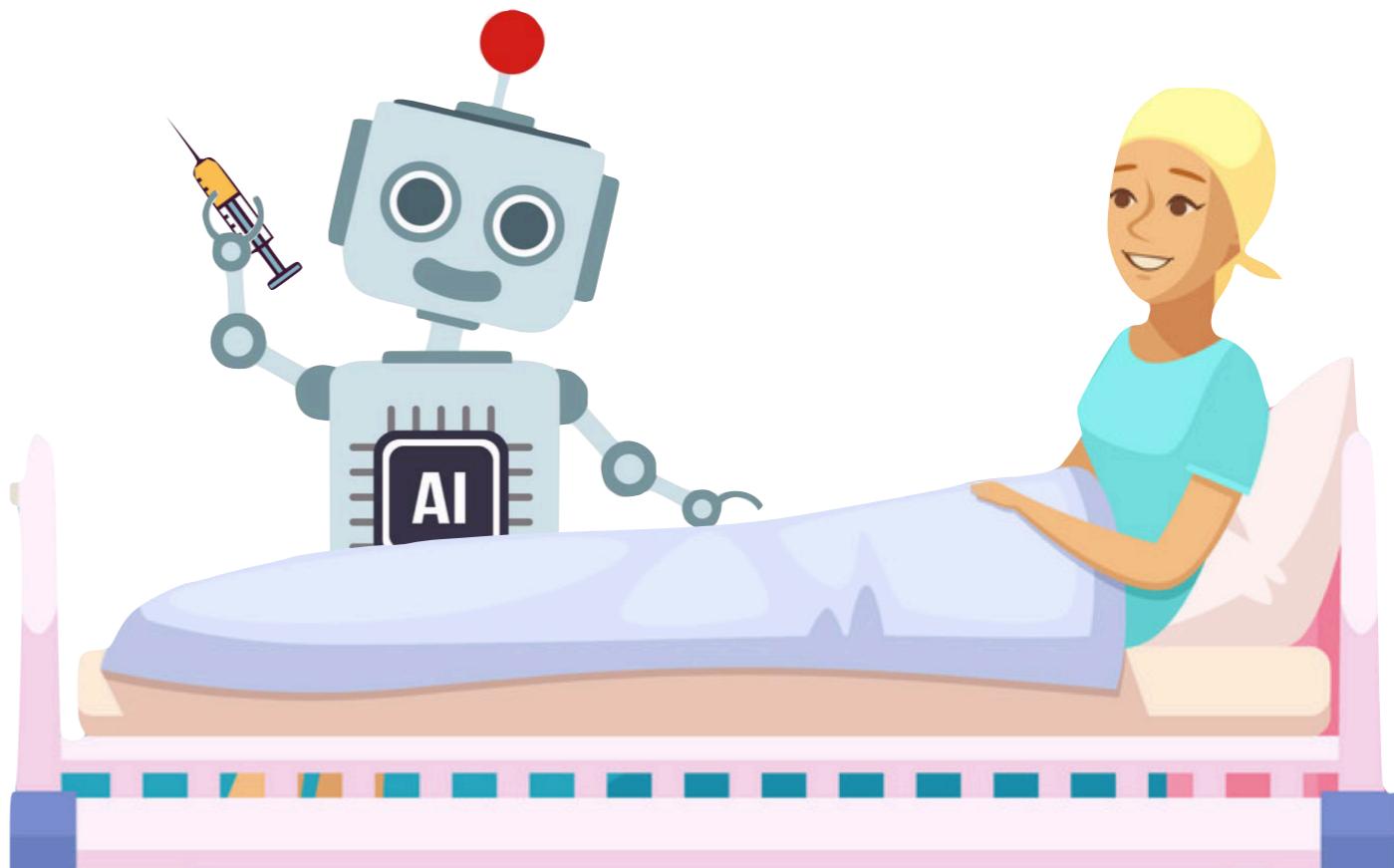
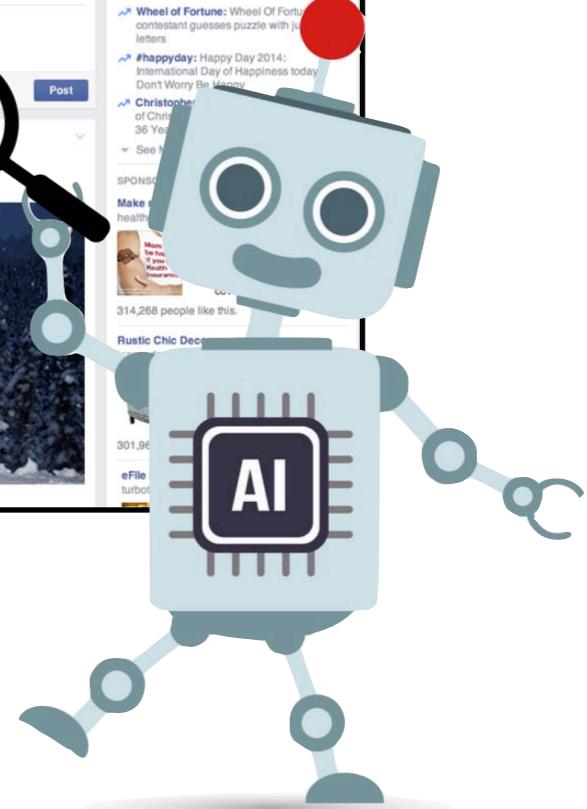
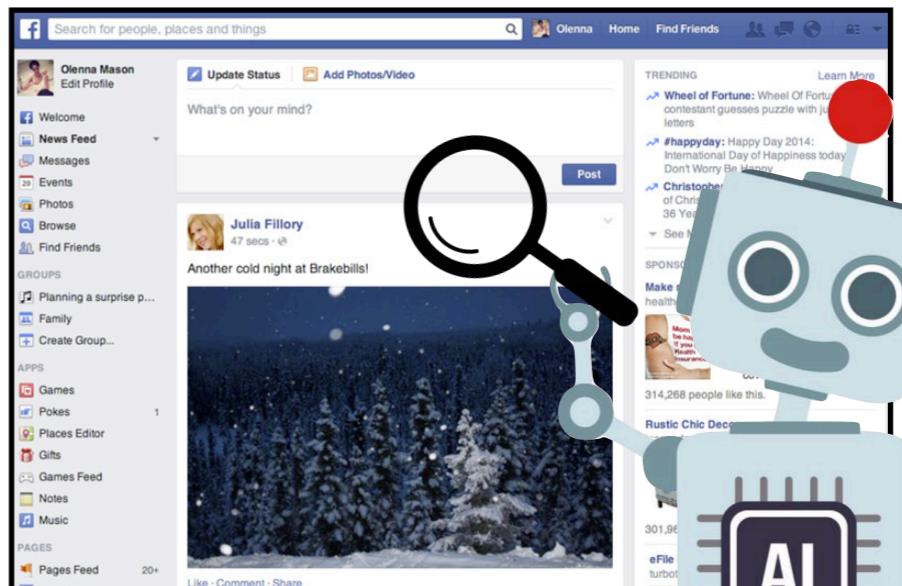
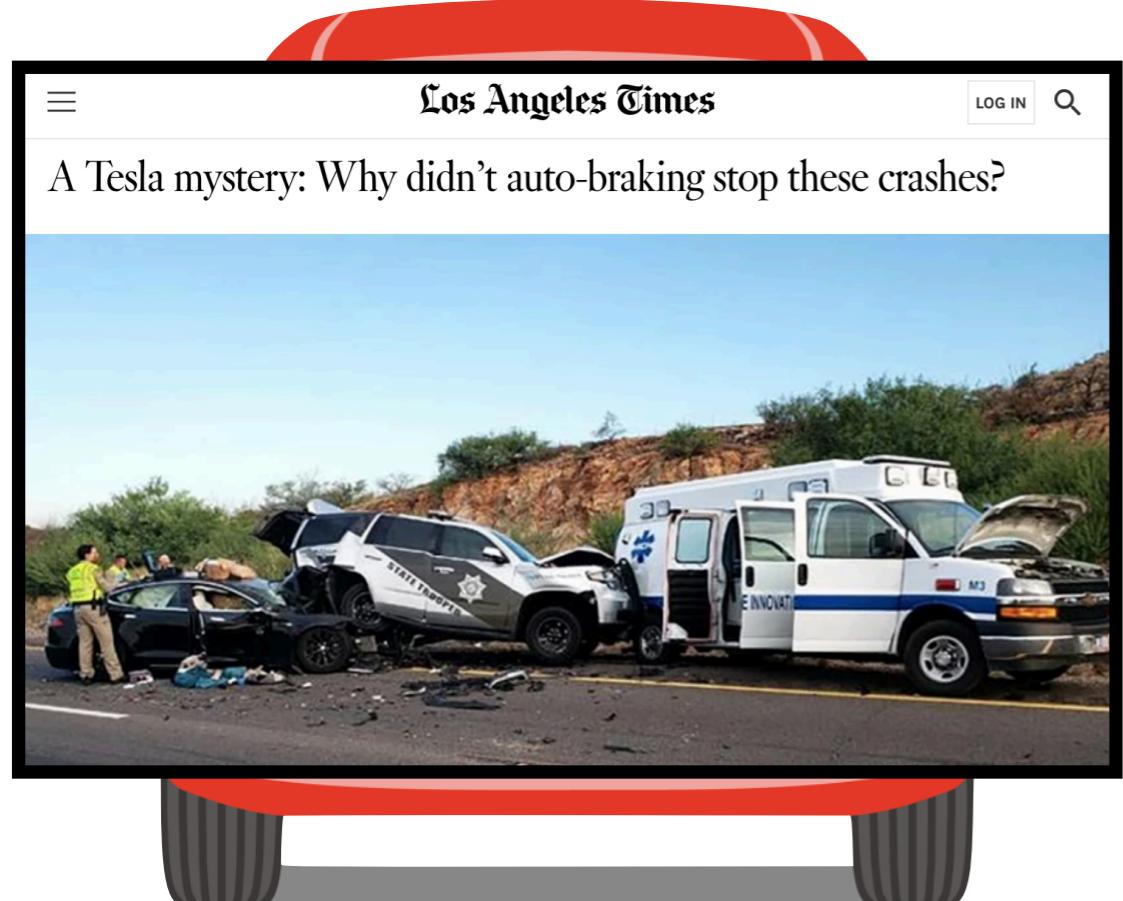
Johns Hopkins University

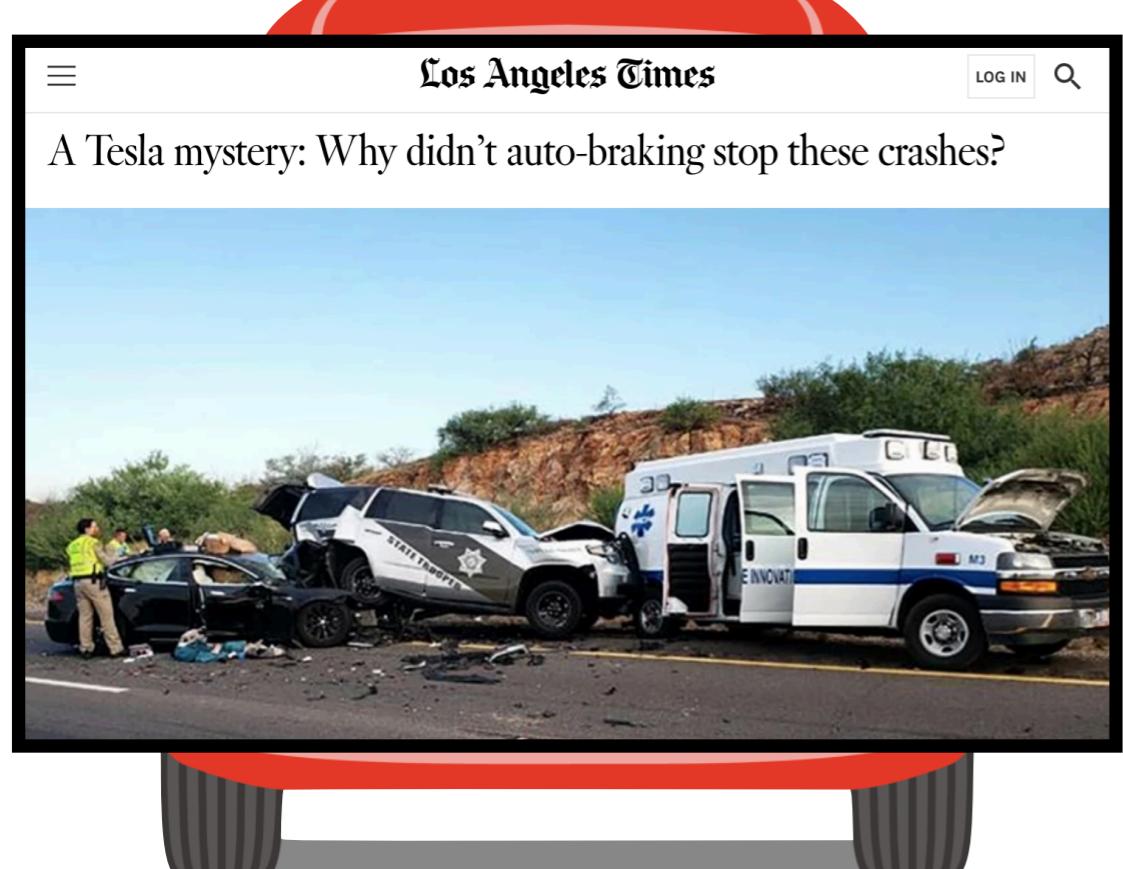












from Net Politics and Digital and Cyberspace Policy Program

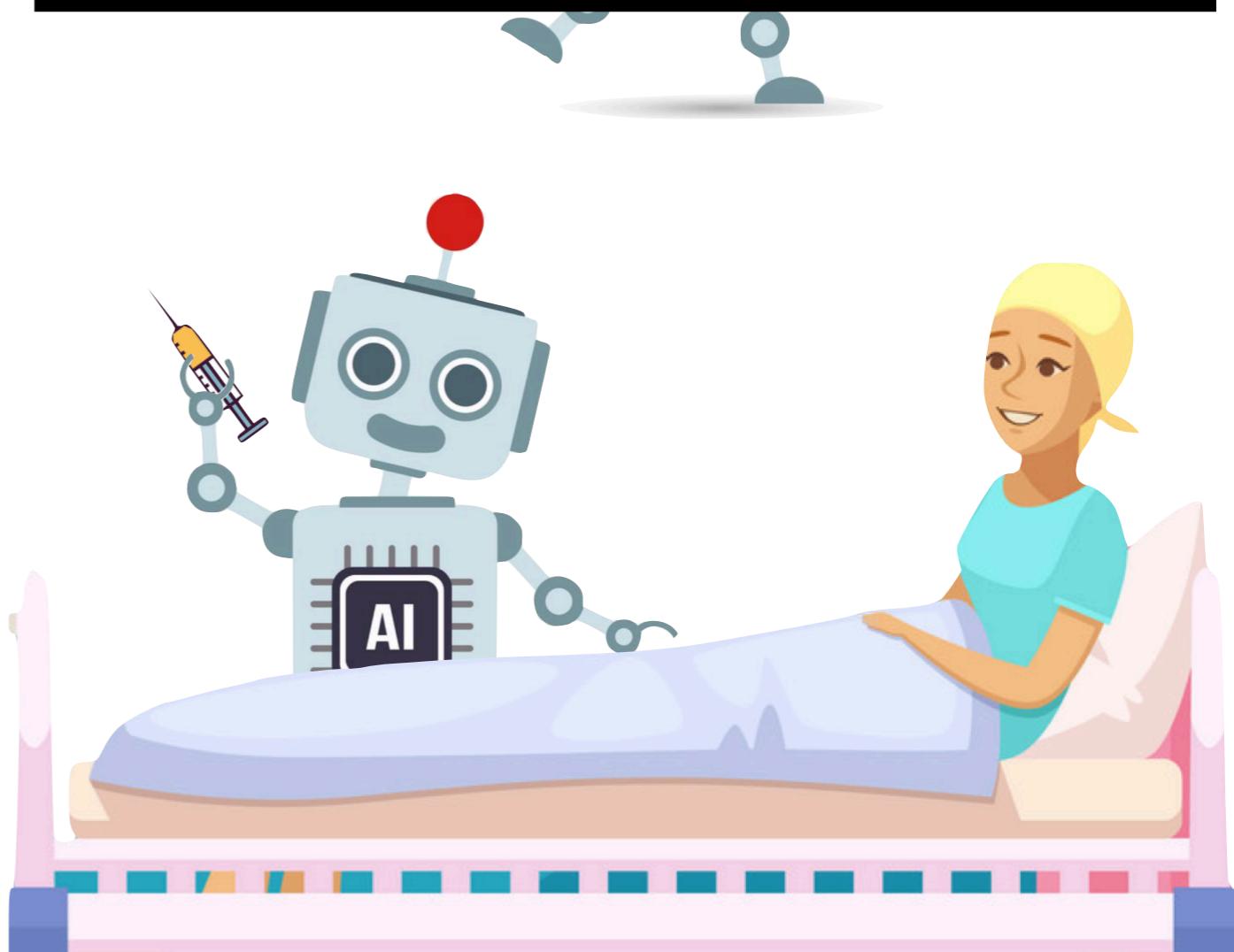
Facebook's Content Moderation Failures in Ethiopia

Facebook has failed to moderate content in underserved countries. Facebook and other social media companies must invest more in local content moderation, instead of relying on global AI systems.

Blog Post by Caroline Allen, Guest Contributor
April 19, 2022 2:36 pm (EST)

[Facebook](#) [Twitter](#) [LinkedIn](#) [Print](#) [Email](#)

Amhara militia members ride in the back of a truck towards a fight with the Tigray People's Liberation Front. Reuters/Tiksa Negeri



Los Angeles Times

A Tesla mystery: Why didn't auto-braking stop these crashes?

The image shows a scene of multiple vehicle collisions on a highway. In the foreground, a dark-colored Tesla sedan has crashed into the side of a white and blue emergency response vehicle, which appears to be a California State Trooper's car. Other vehicles are visible in the background, and several people are standing near the accident site.

from [Net Politics and Digital and Cyberspace Policy Program](#)

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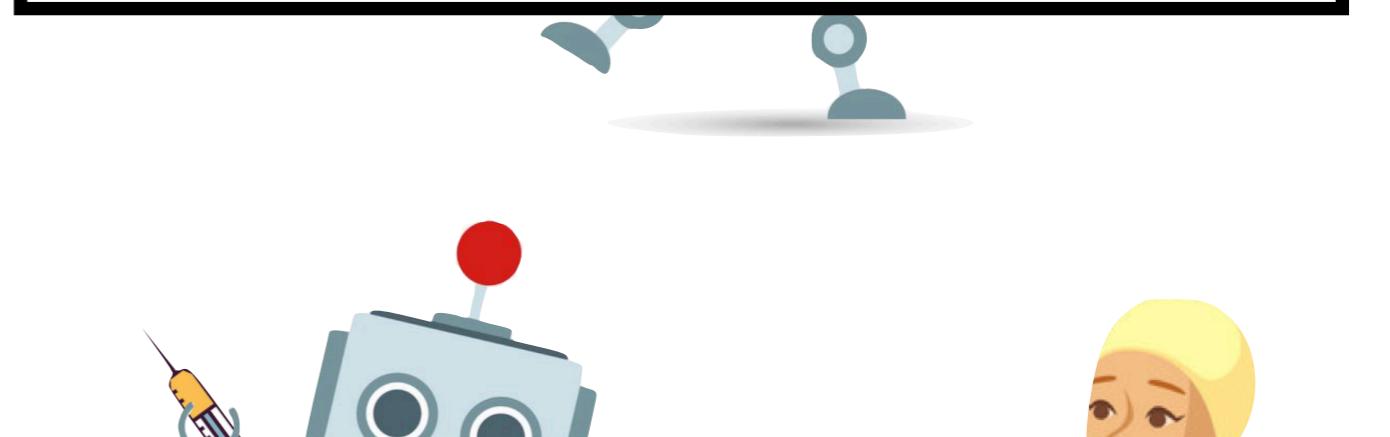
Amhara militia members ride in the back of a truck towards a fight with the Tigray People's Liberation Front. Reuters/Tiksa Negeri

ARTIFICIAL INTELLIGENCE

Google's medical AI was super accurate in a lab. Real life was a different story.

If AI is really going to make a difference, it needs to work when real humans are involved.

By Will Douglas Heaven



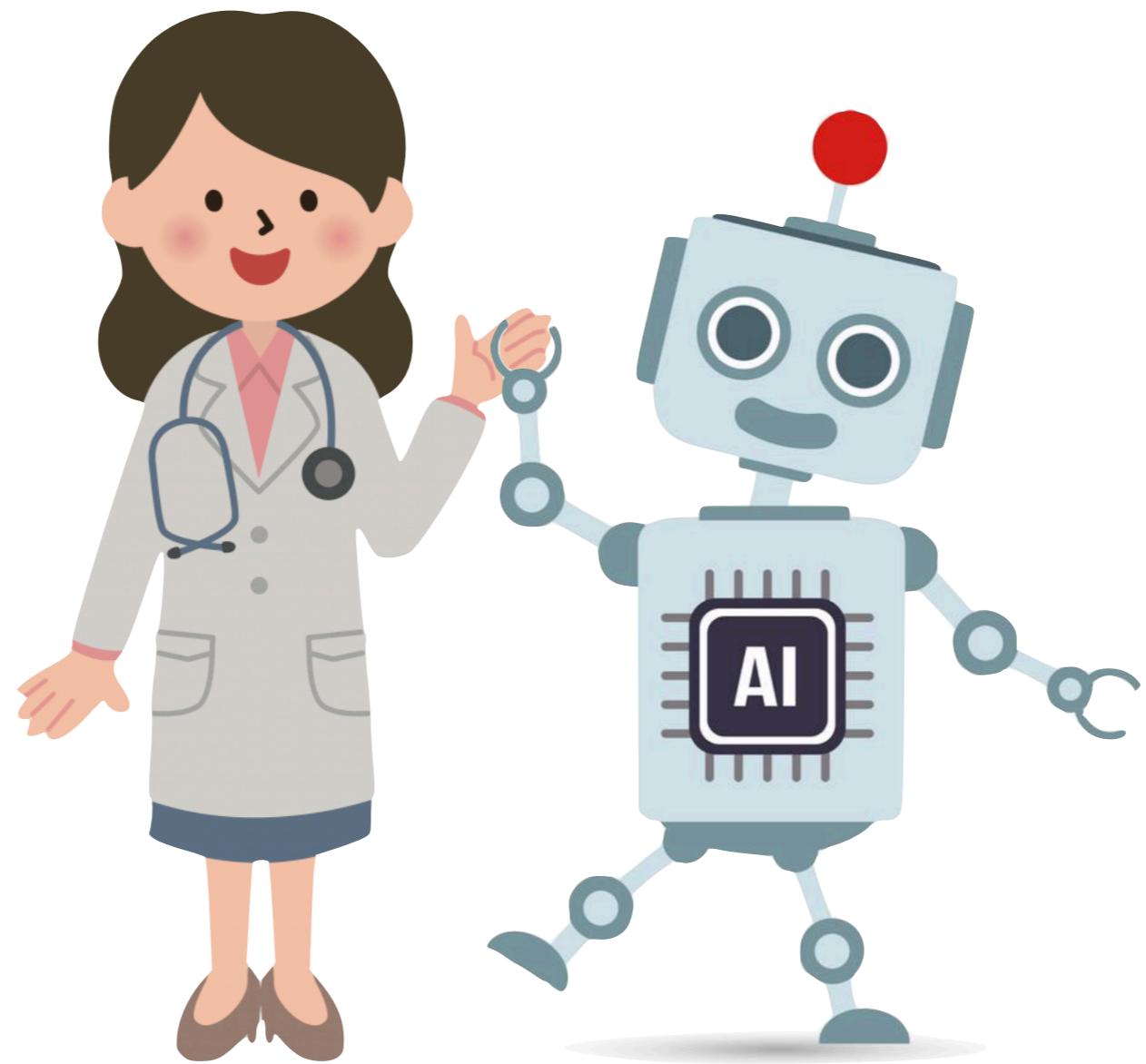
Medscape Tuesday, December 13, 2022

NEWS & PERSPECTIVE DRUGS & DISEASES CME & EDUCATION ACADEMY VIDEO DECISION POINT

News > Medscape Medical News > Conference News > CHEST 2022

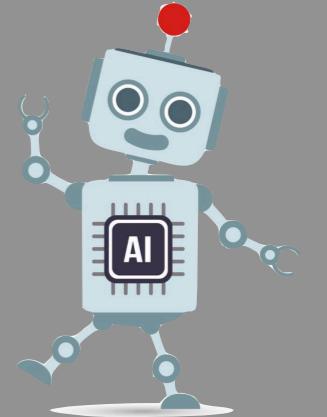
Sepsis Predictor Tool Falls Short in Emergency Setting

Heidi Splete
October 17, 2022



human-AI collaboration

input
features



classifier



expert

learning to defer (to an expert)

input
features



allocation
mechanism

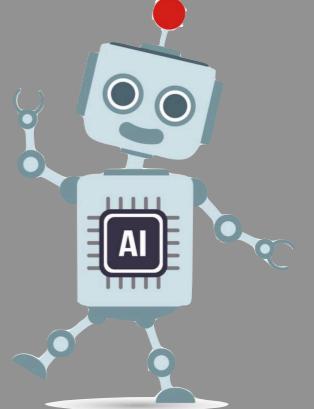
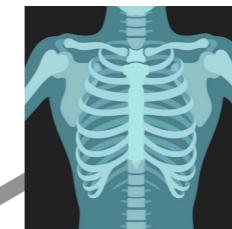


learning to defer (to an expert)

input
features



allocation
mechanism



classifier



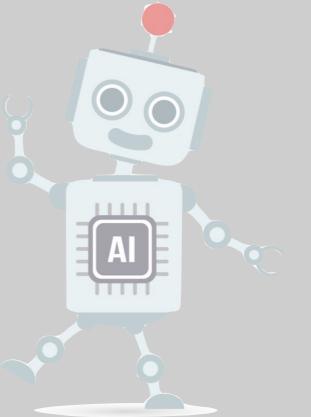
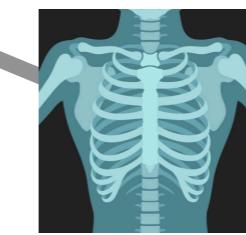
expert

learning to defer (to an expert)

input
features



allocation
mechanism



classifier



expert

learning to defer (to an expert)

input
features

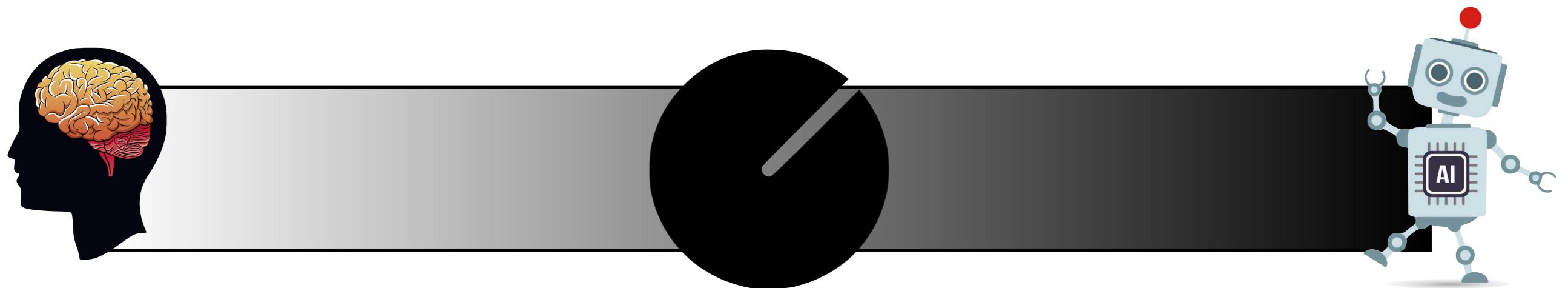


allocation
mechanism



safe and robust semi-automation
via expert handling the hardest cases

safe, gradual automation



- ⊗ single expert
 - ⊗ softmax surrogate loss
 - ⊗ improving calibration via one-vs-all
- ⊗ multiple experts
 - ⊗ surrogate losses
 - ⊗ conformal sets of experts
- ⊗ population of experts
 - ⊗ surrogate losses
 - ⊗ meta-learning a rejector

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input
features



allocation
mechanism

classifier



expert

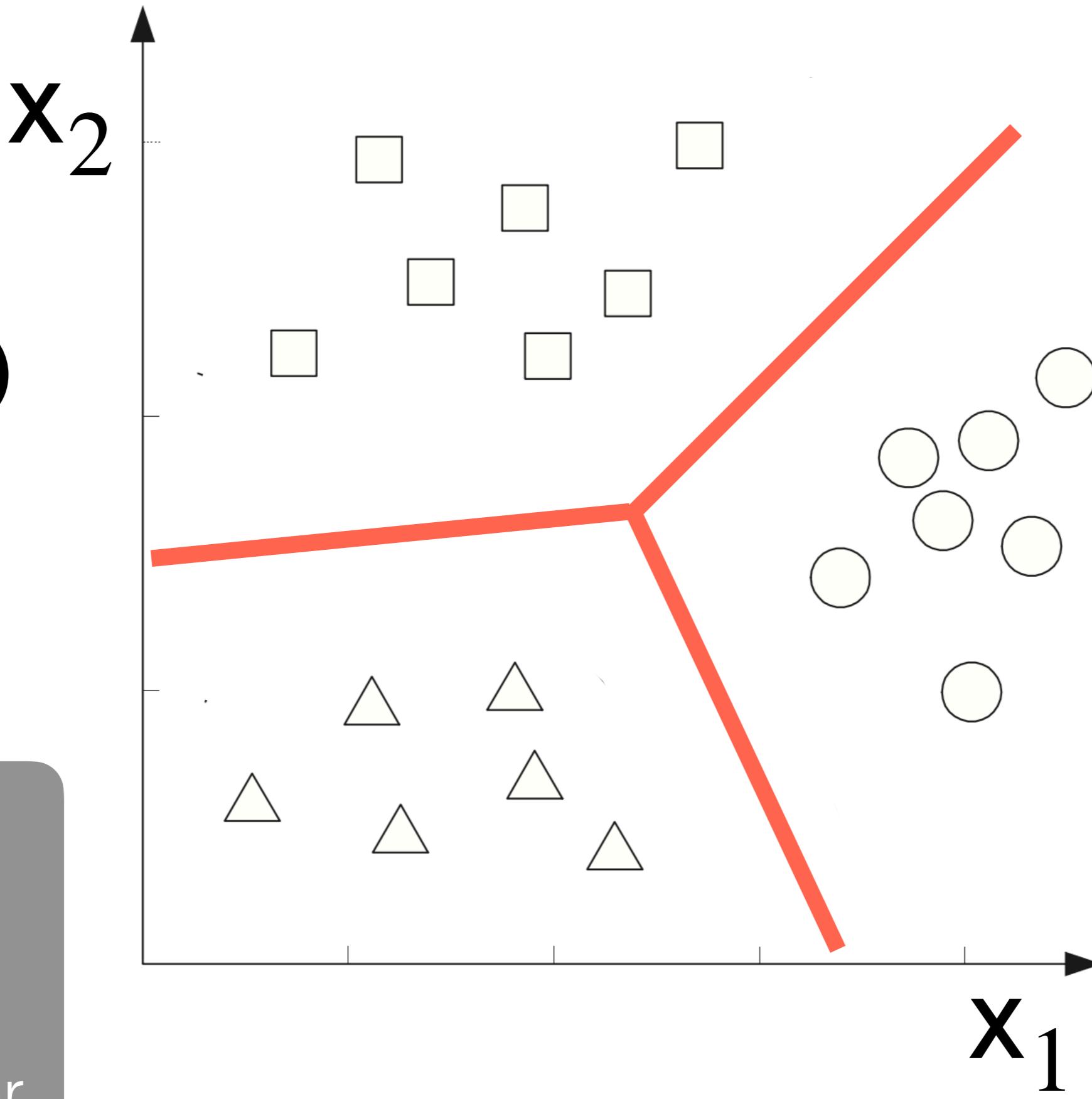
input
features



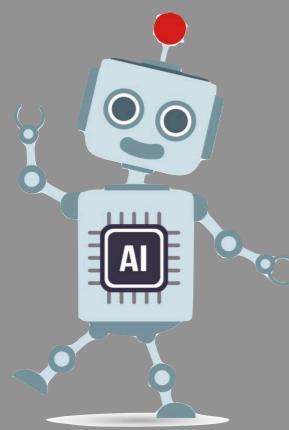
allocation
mechanism

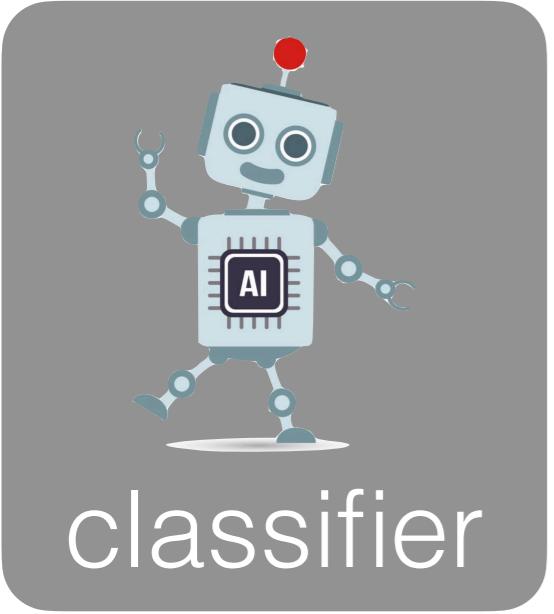


$p(y | x)$

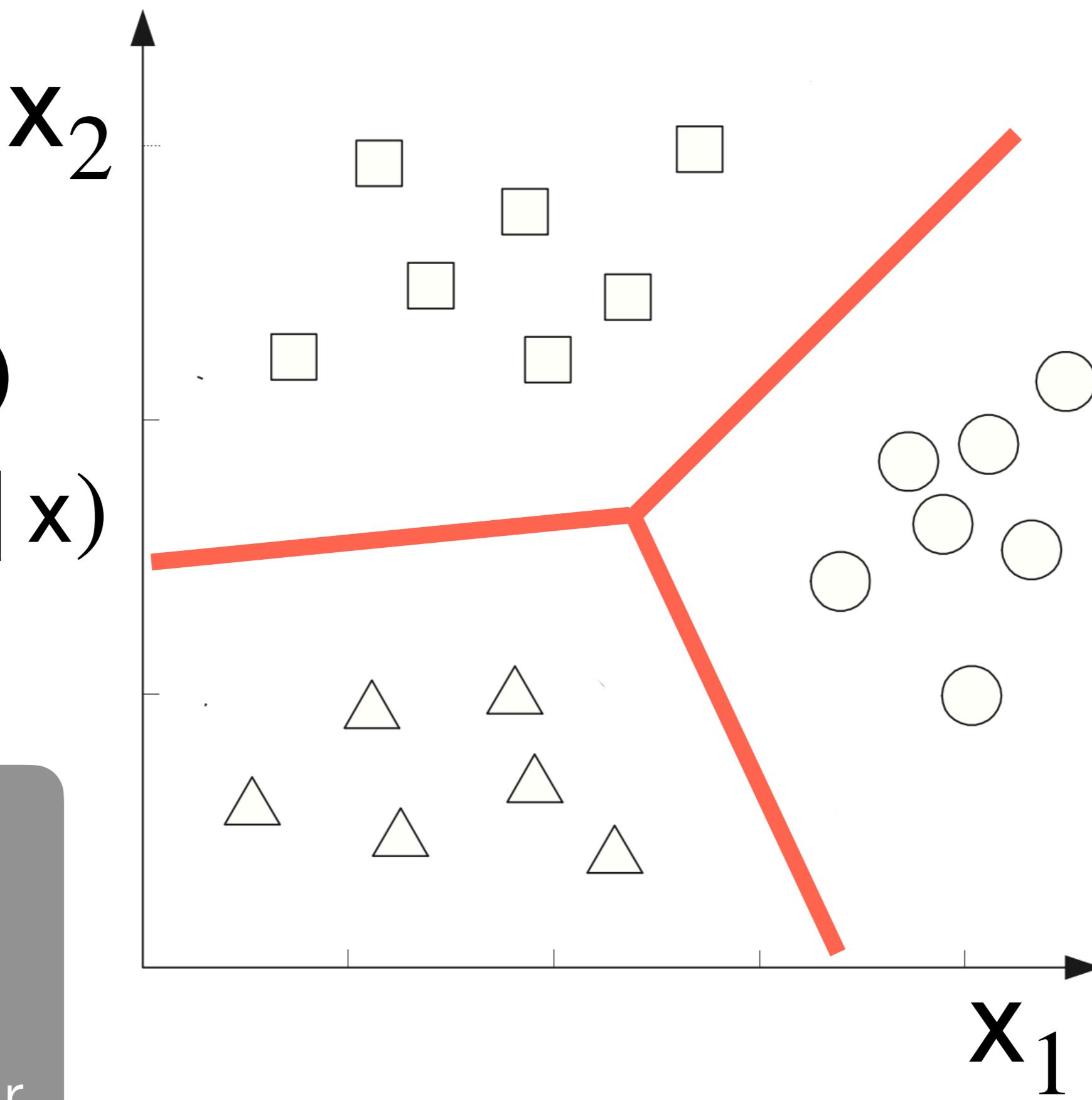


classifier





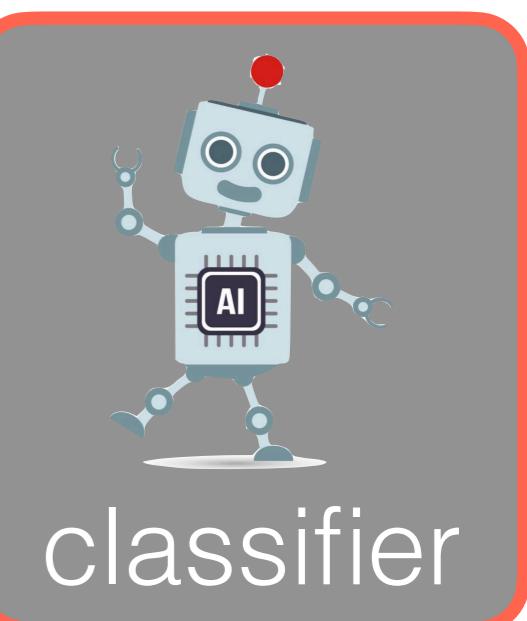
$p(y | x)$
 $\approx \mathbb{P}(y | x)$



input
features



allocation
mechanism



input
features



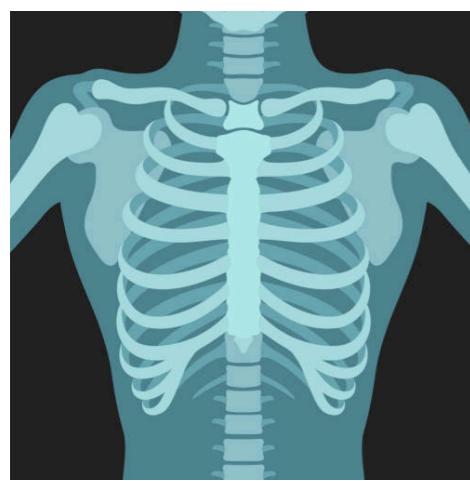
allocation
mechanism

classifier



expert

input
features

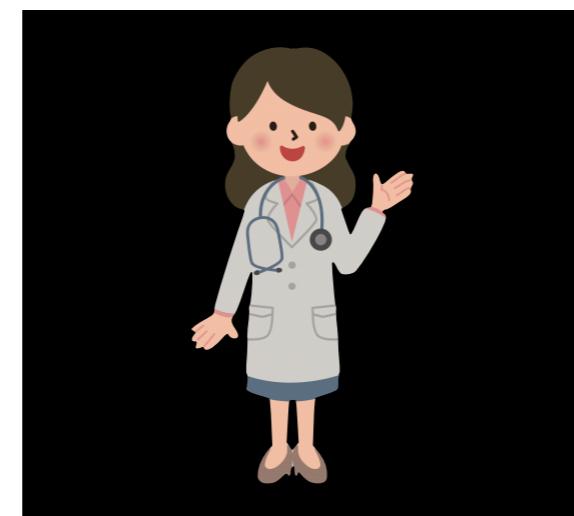


allocation
mechanism



input
features

X



m
prediction

(black box)



input
features



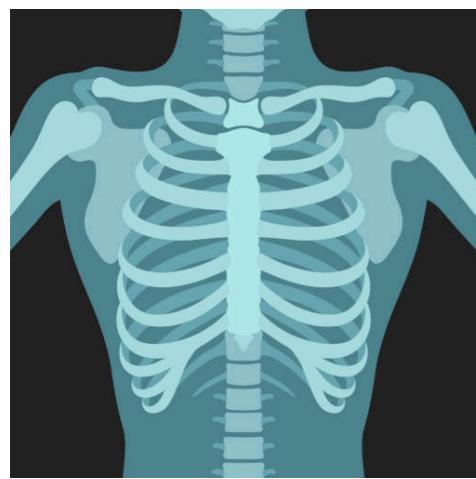
allocation
mechanism

classifier



expert

input
features



allocation
mechanism

???



input
features



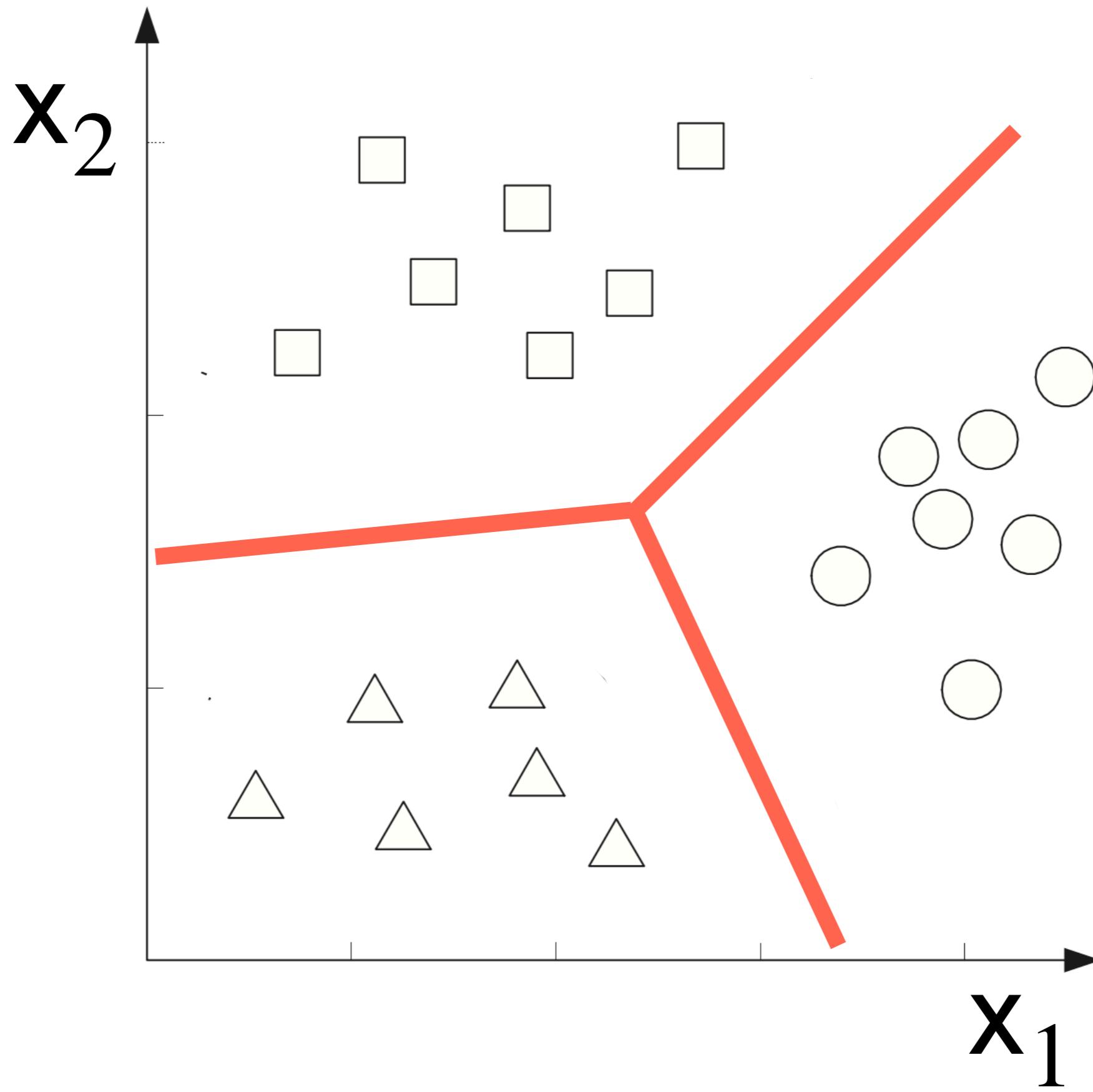
allocation
mechanism

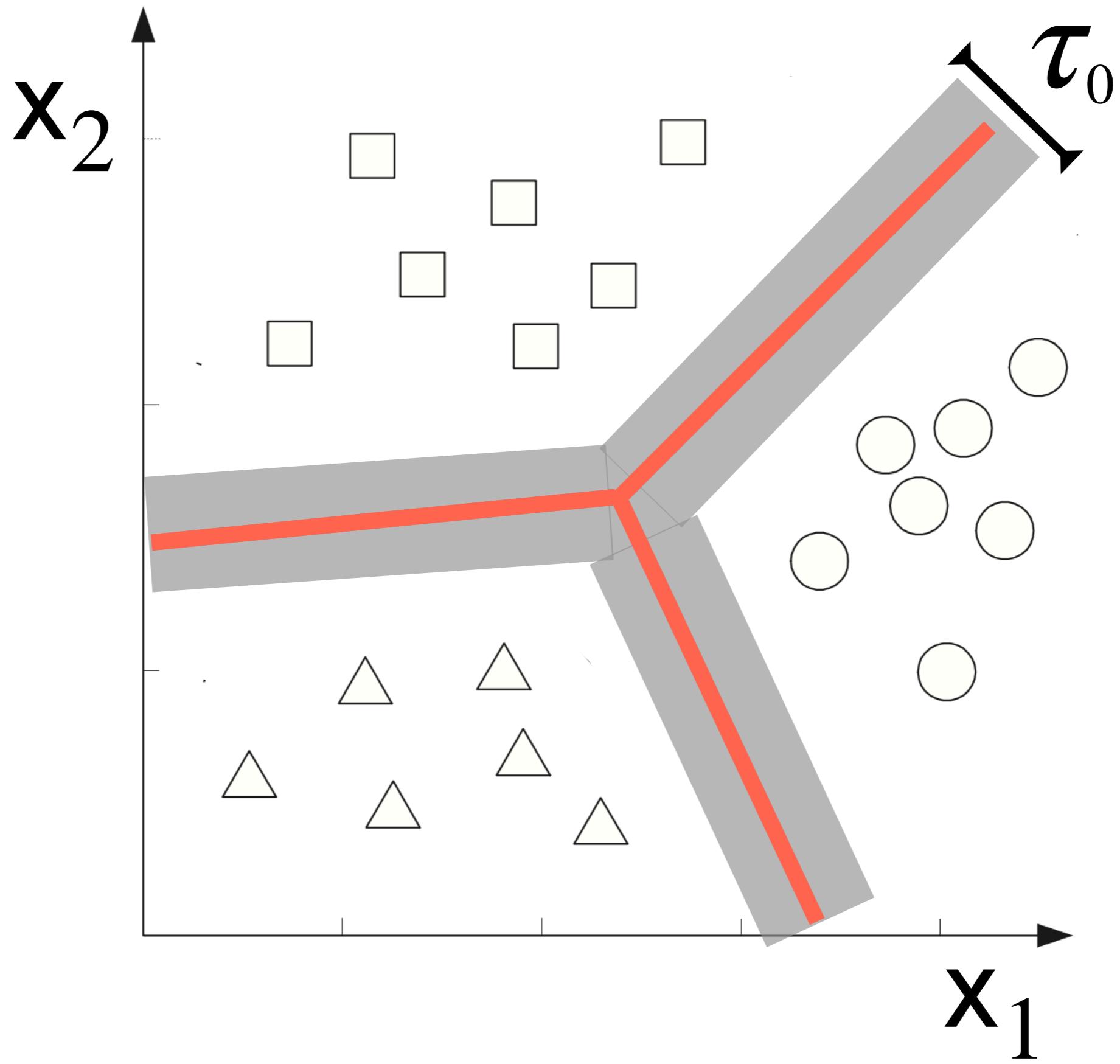


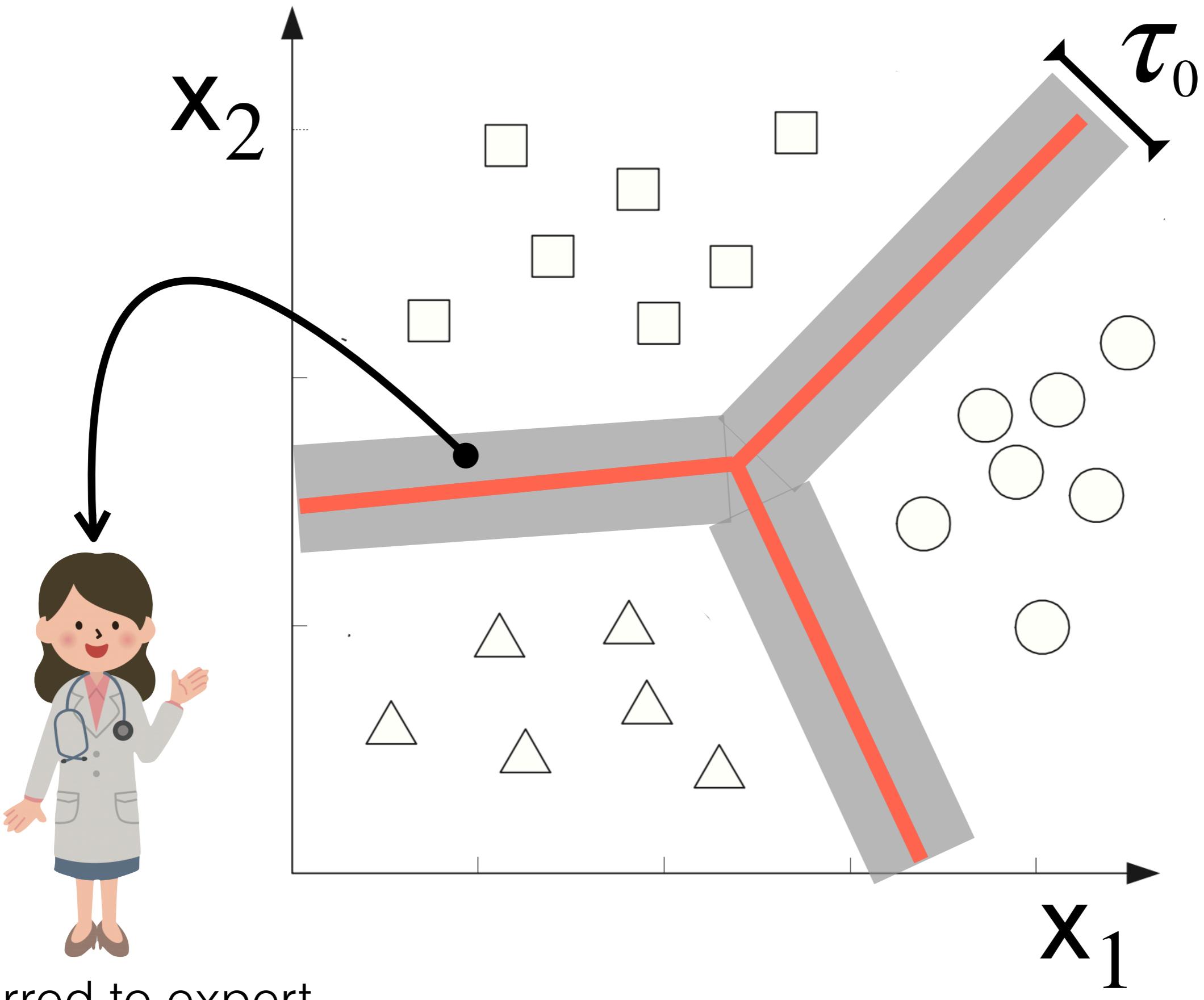
defer to expert if...

$$\max_y p(y|x) \leq \tau_0$$

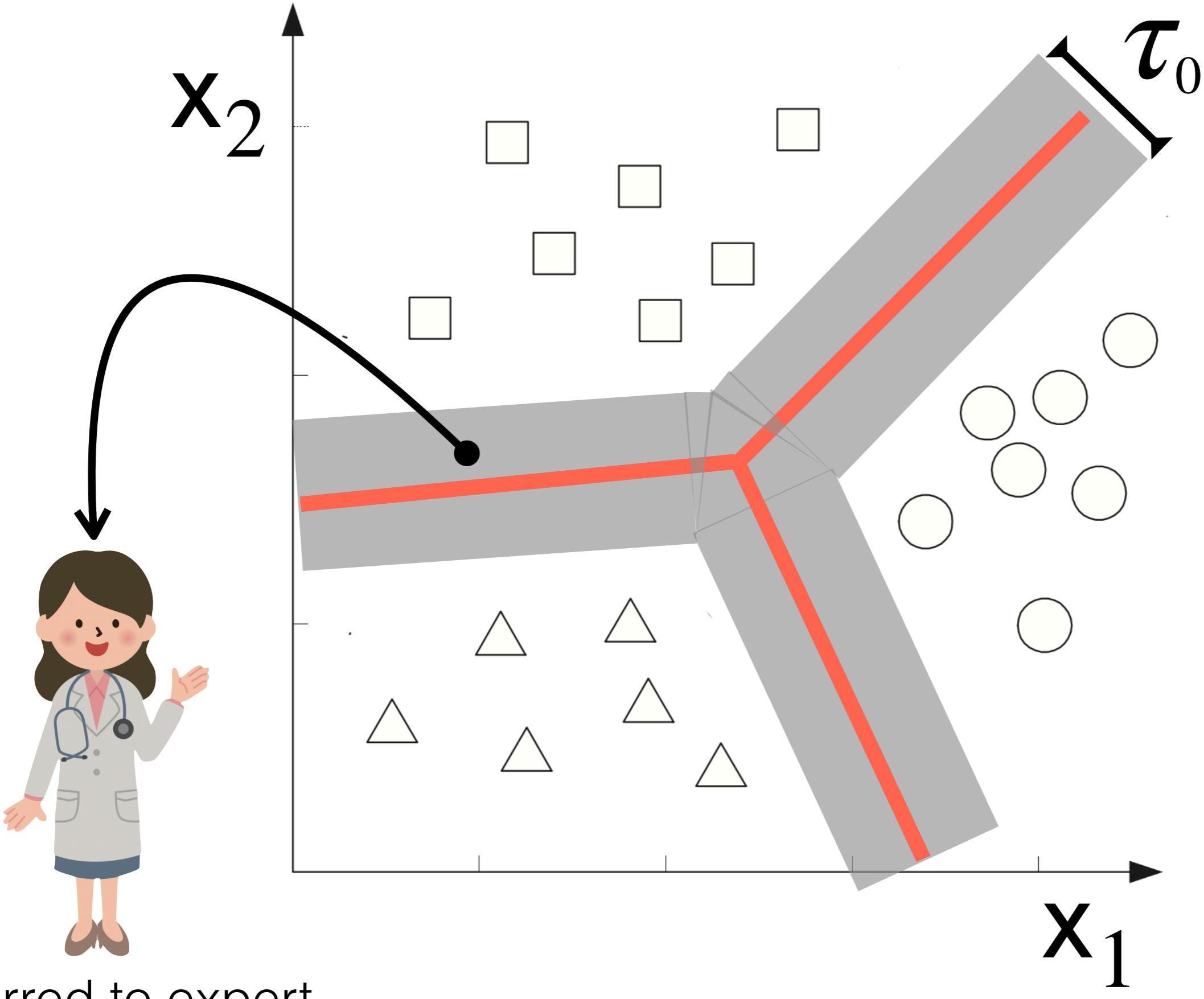
(constant)







deferred to expert

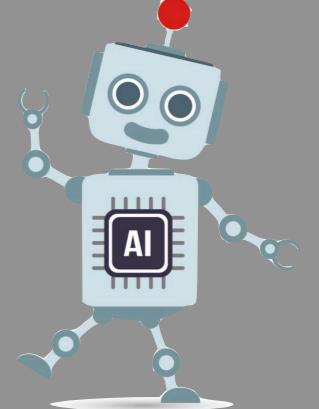


deferred to expert

input
features



allocation
mechanism



classifier



expert

defer to expert if...

$$\max_y p(y|x) \leq \tau_0$$

(constant)

input
features



allocation
mechanism



defer to expert if...

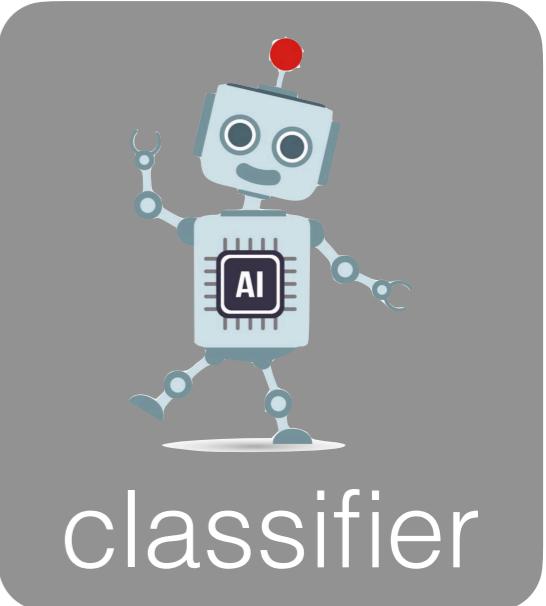
$$\max_y p(y|x) \leq \tau_0 \quad (\text{constant})$$

problem?

input
features



allocation
mechanism



defer to expert if...

$$\max_y p(y|x) \leq \tau_0 \quad (\text{constant})$$

the expert's
knowledge is
not considered!

input
features



allocation
mechanism

classifier



expert

defer to expert if...

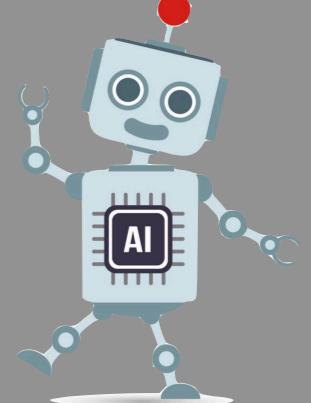
$$\max_y p(y|x) \leq \tau \left(\text{[skeleton icon]}, \text{[doctor icon]} \right)$$

input
features



allocation
mechanism

L_{0-1}



classifier



expert

defer to expert if...

$$\max_y p(y|x) \leq \tau \left(\text{[skeleton icon]}, \text{[doctor icon]} \right),$$

input
features



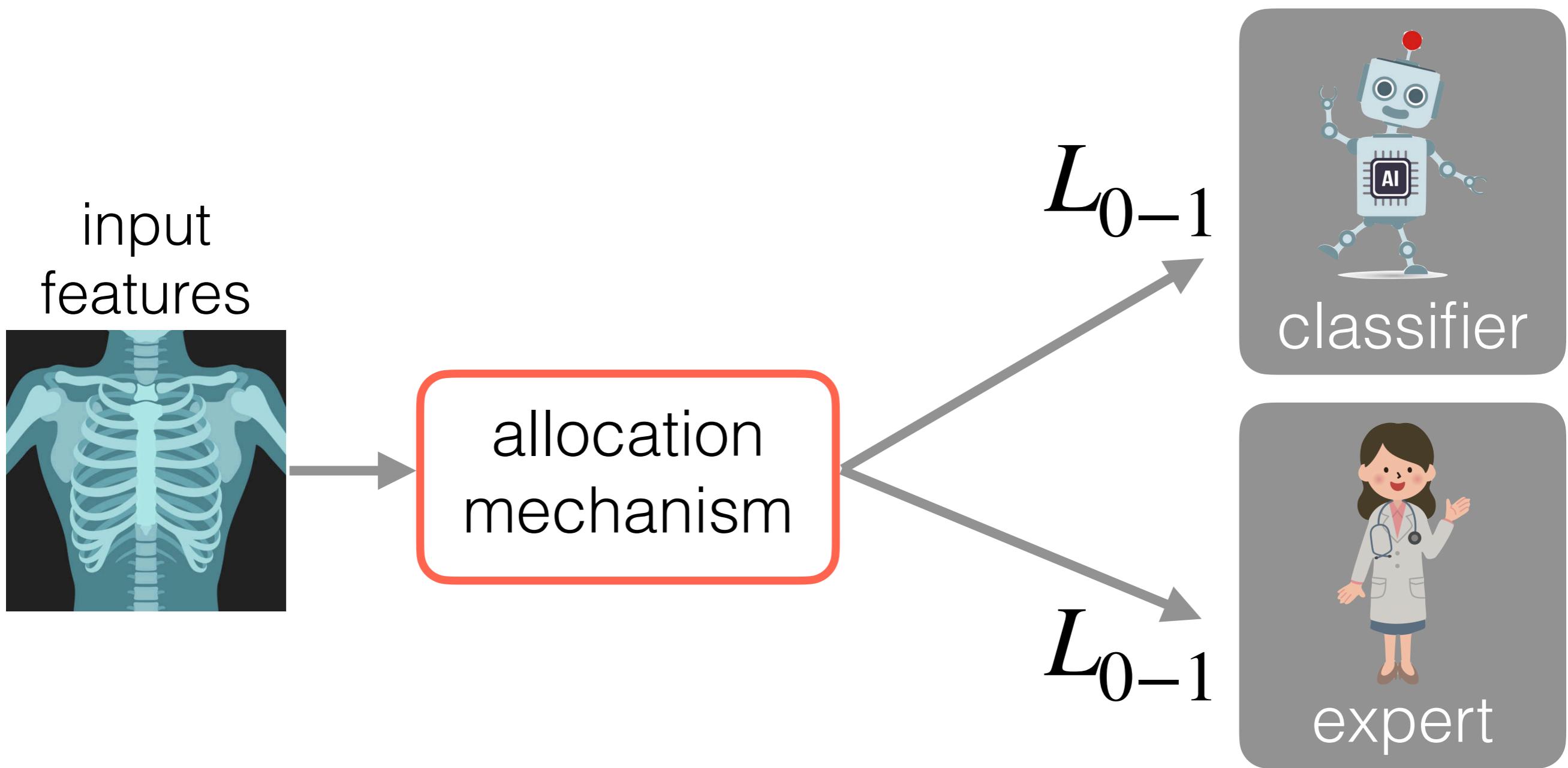
allocation
mechanism

L_{0-1}



defer to expert if...

$$\max_y p(y|x) \leq \tau \left(\text{[skeleton icon]}, \text{[doctor icon]} \right)$$



Bayes optimal deferral rule:

$$\max_y \mathbb{P}(y | x) \leq \mathbb{P}(m = y | x)$$

y

probability that the expert is correct

softmax implementation

[Mozannar & Sontag, 2020]

softmax implementation

[Mozannar & Sontag, 2020]

training data

$$\mathcal{D} = \left\{ \mathbf{x}_n, \mathbf{y}_n, \mathbf{m}_n \right\}_{n=1}^N$$

softmax implementation

[Mozannar & Sontag, 2020]

training data

$$\mathcal{D} = \left\{ \mathbf{x}_n, \mathbf{y}_n, \mathbf{m}_n \right\}_{n=1}^N$$

model

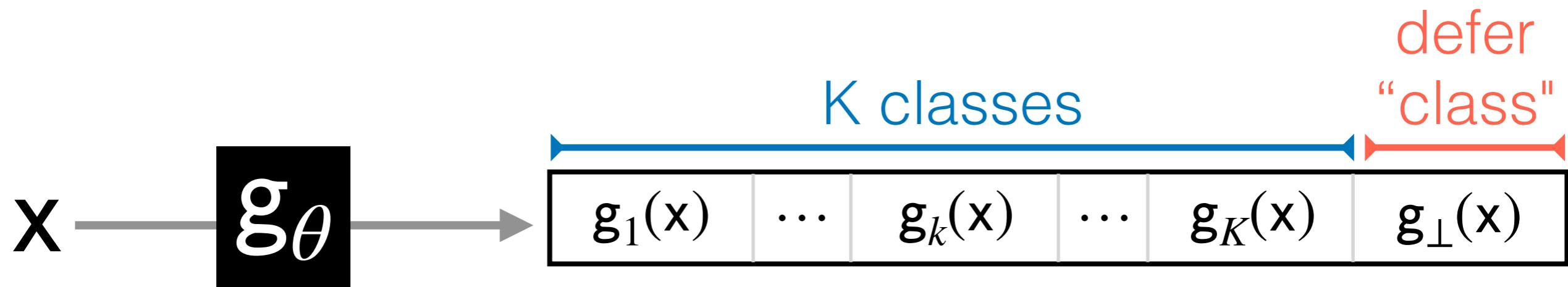
softmax implementation

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softmax implementation

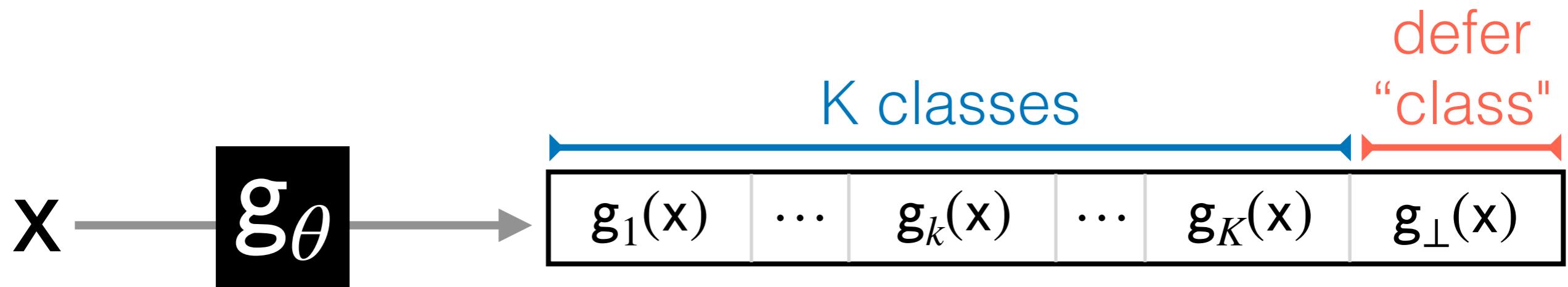
[Mozannar & Sontag, 2020]

training data

$$\mathcal{D} = \left\{ \mathbf{x}_n, \mathbf{y}_n, \mathbf{m}_n \right\}_{n=1}^N$$

model

$$g_k(\mathbf{x}) \in \mathbb{R}$$



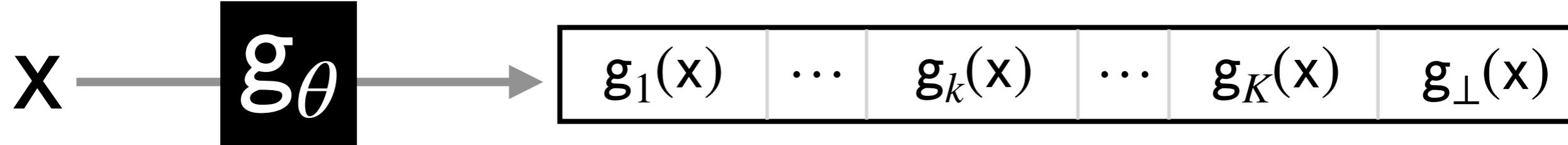
softmax implementation

[Mozannar & Sontag, 2020]

training data

$$\mathcal{D} = \left\{ \mathbf{x}_n, \mathbf{y}_n, \mathbf{m}_n \right\}_{n=1}^N$$

model



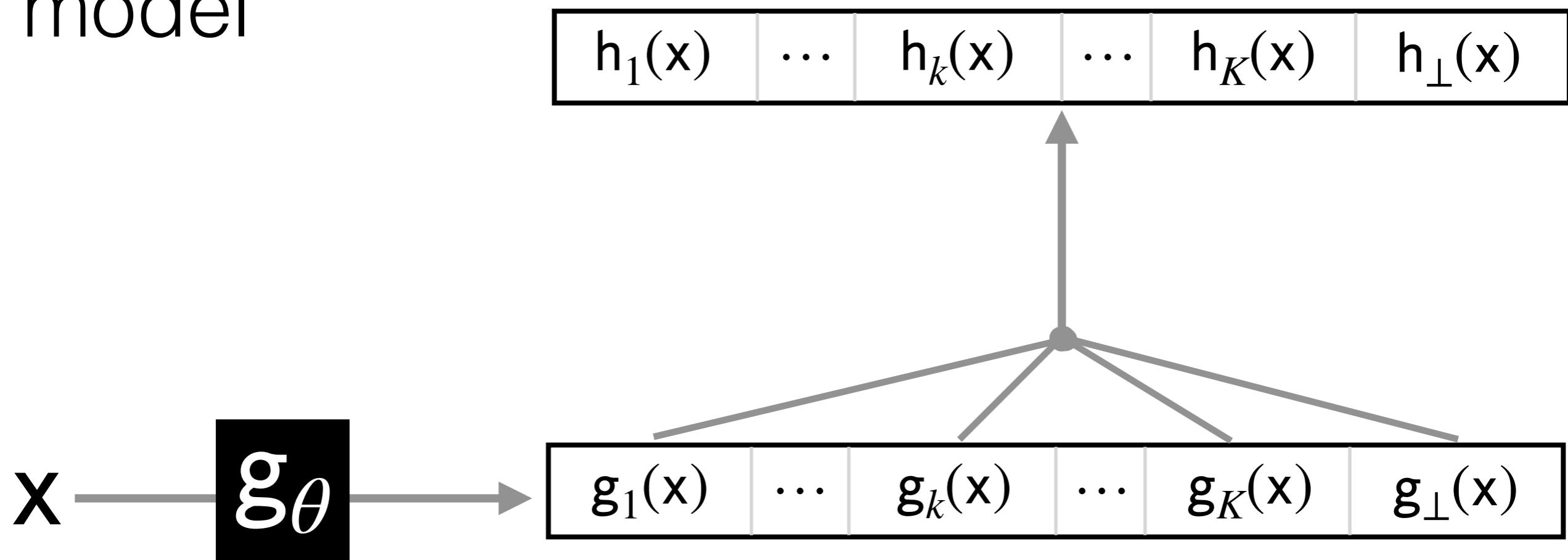
softmax implementation

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softmax implementation

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$$\mathcal{D} = \left\{ \mathbf{x}_n, \mathbf{y}_n, \mathbf{m}_n \right\}_{n=1}^N$$

model

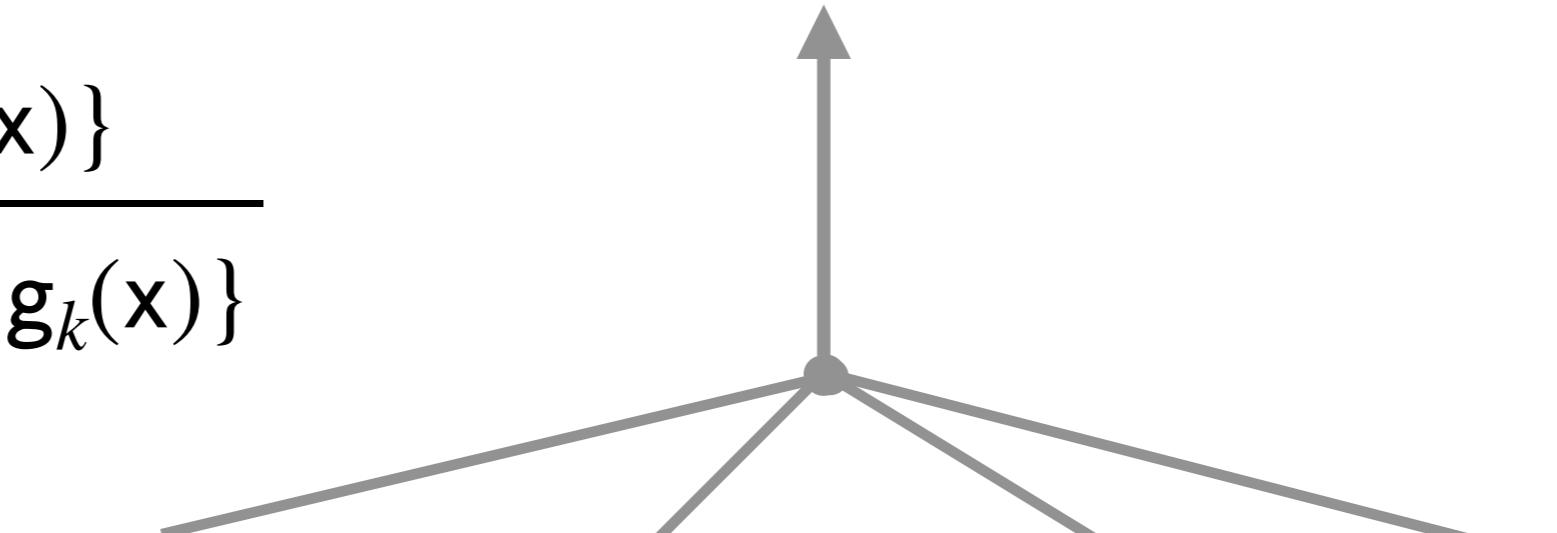
$$h_i(\mathbf{x}) = \frac{\exp\{g_i(\mathbf{x})\}}{\sum_{k=1}^{K+1} \exp\{g_k(\mathbf{x})\}}$$

$$\begin{array}{c} h_1(\mathbf{x}) \quad \cdots \quad h_k(\mathbf{x}) \quad \cdots \quad h_K(\mathbf{x}) \quad h_\perp(\mathbf{x}) \\ \hline \end{array}$$

\mathbf{x}

\mathbf{g}_θ

$$\begin{array}{c} g_1(\mathbf{x}) \quad \cdots \quad g_k(\mathbf{x}) \quad \cdots \quad g_K(\mathbf{x}) \quad g_\perp(\mathbf{x}) \\ \hline \end{array}$$



softmax implementation

[Mozannar & Sontag, 2020]

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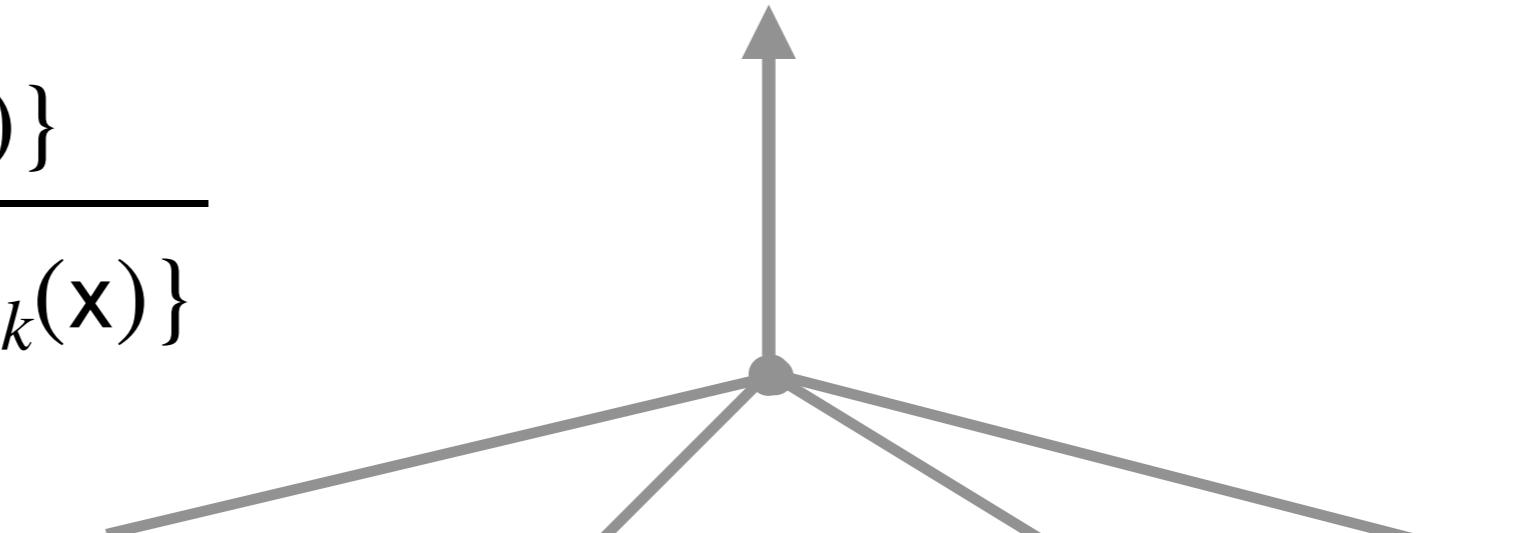
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\mathbf{x}

\mathbf{g}_θ

$$\begin{array}{c} g_1(\mathbf{x}) \quad \cdots \quad g_k(\mathbf{x}) \quad \cdots \quad g_K(\mathbf{x}) \quad g_\perp(\mathbf{x}) \\ \hline \end{array}$$



softmax implementation

[Mozannar & Sontag, 2020]

training data

$$\mathcal{D} = \left\{ \mathbf{x}_n, \mathbf{y}_n, \mathbf{m}_n \right\}_{n=1}^N$$

model

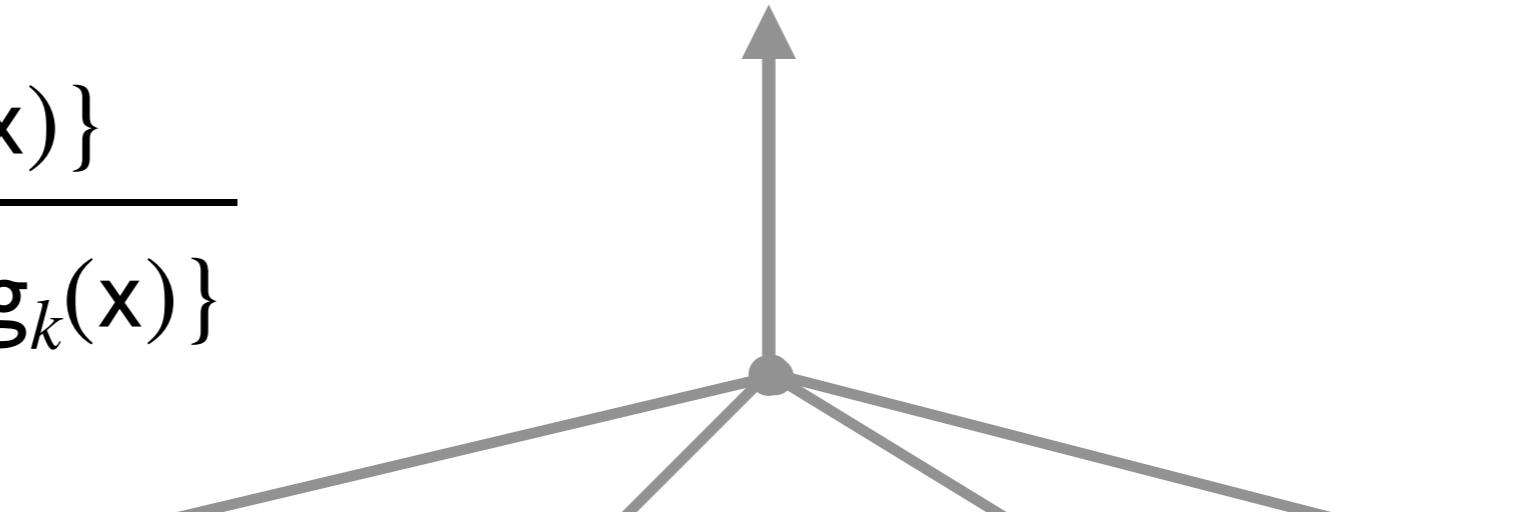
$$h_{\perp}(x) = \frac{\exp\{g_{\perp}(x)\}}{\sum_{k=1}^{K+1} \exp\{g_k(x)\}}$$

$h_1(x)$	\dots	$h_k(x)$	\dots	$h_K(x)$	$h_{\perp}(x)$
----------	---------	----------	---------	----------	----------------

x

g_{θ}

$g_1(x)$	\dots	$g_k(x)$	\dots	$g_K(x)$	$g_{\perp}(x)$
----------	---------	----------	---------	----------	----------------



softmax implementation

[Mozannar & Sontag, 2020]

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softmax implementation

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model

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loss function

$$\ell(\theta; \mathbf{x}, \mathbf{y}, \mathbf{m}) = -\log h_y(\mathbf{x}) - \mathbb{I}[y = m] \cdot \log h_m(\mathbf{x})$$

softmax implementation

[Mozannar & Sontag, 2020]

training data

$$\mathcal{D} = \left\{ \mathbf{x}_n, \mathbf{y}_n, \mathbf{m}_n \right\}_{n=1}^N$$

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softmax implementation

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loss function

$$\ell(\theta; \mathbf{x}, \mathbf{y}, \mathbf{m}) = -\log h_y(\mathbf{x}) - \mathbb{I}[y = m] \cdot \log h_\perp(\mathbf{x})$$

input
features



allocation
mechanism



defer to expert if...

$$\max_{y \in [1, K]} h_y(x) \leq h_\perp(x)$$

- ⊗ single expert

- ⊗ softmax surrogate loss
 - ⊗ improving calibration via one-vs-all

- ⊗ multiple experts

- ⊗ surrogate losses
 - ⊗ conformal sets of experts

- ⊗ population of experts

- ⊗ surrogate losses
 - ⊗ meta-learning a rejector

- ⊗ single expert
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- ⊗ multiple experts
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How well can the softmax-based system estimate expert correctness?

$$\hat{p}(m = y | x) \underset{?}{\approx} P(m = y | x)$$

How well can the softmax-based system estimate expert correctness?

$$\hat{p}(m = y | x) \underset{?}{\approx} P(m = y | x)$$

- ⊗ optimal allocation
- ⊗ transparency
- ⊗ detecting distribution shift
(in the expert)

How well can the softmax-based system estimate expert correctness?

$$\hat{p}(m = y | x) \cancel{\approx} P(m = y | x)$$

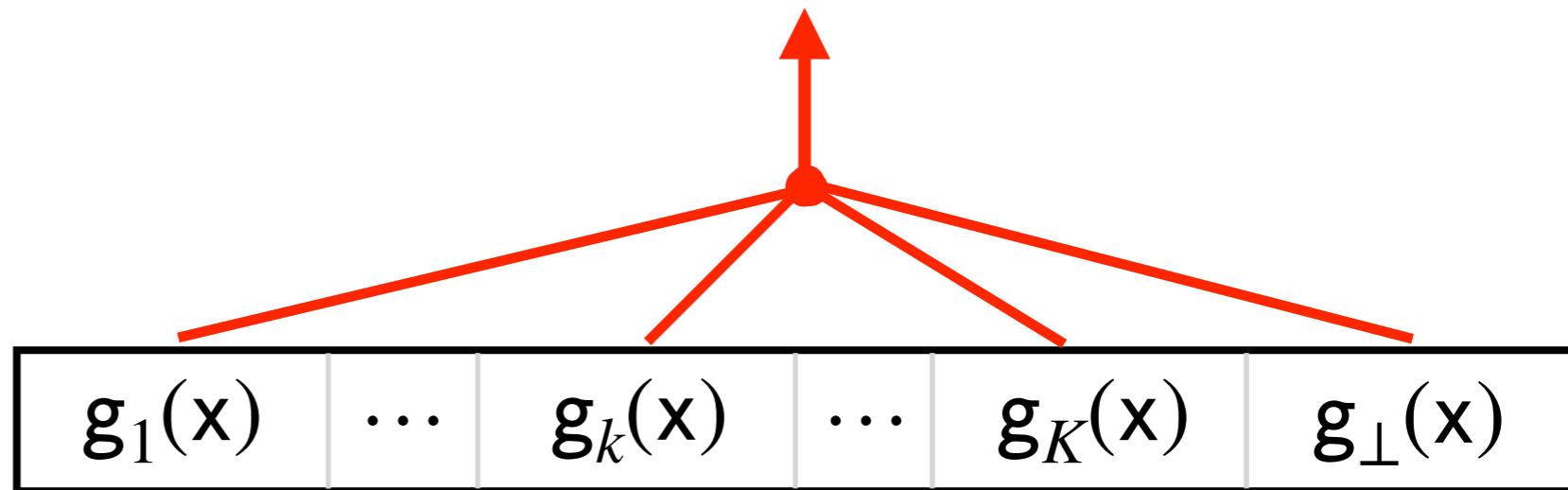
How well can the softmax-based system estimate expert correctness?

$$\hat{p}(m = y | x) \cancel{\approx} P(m = y | x)$$

degenerate
parameterization

[Proposition 3.1]

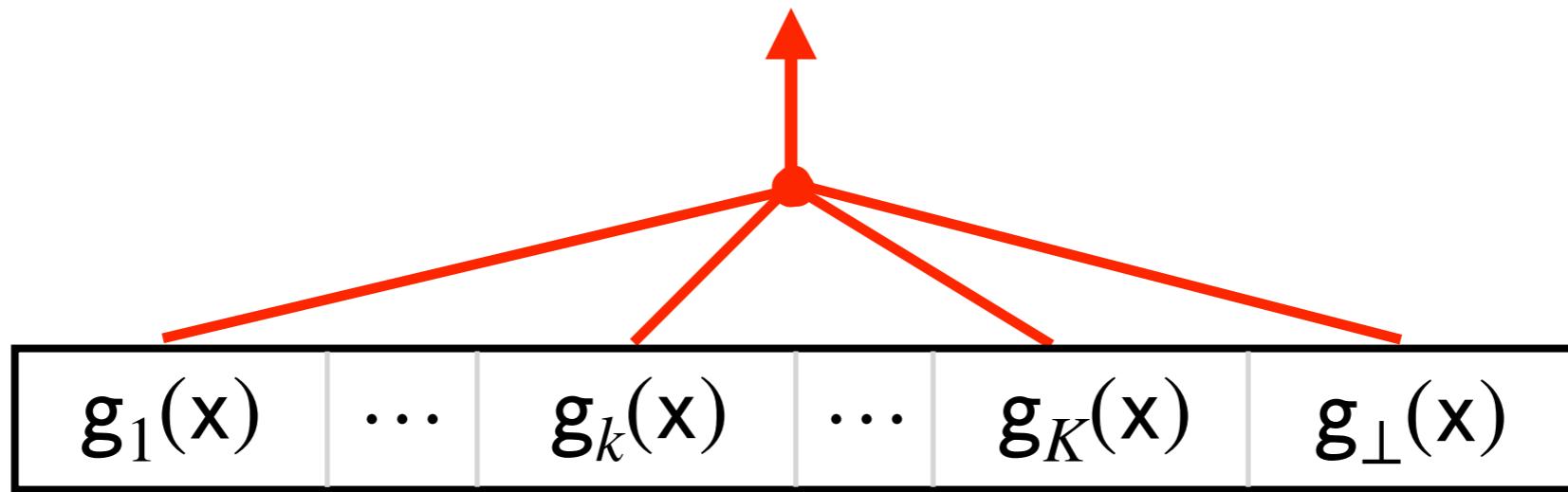
$$h_{\perp}(x) = \frac{\exp\{g_{\perp}(x)\}}{\sum_{k=1}^{K+1} \exp\{g_k(x)\}}$$



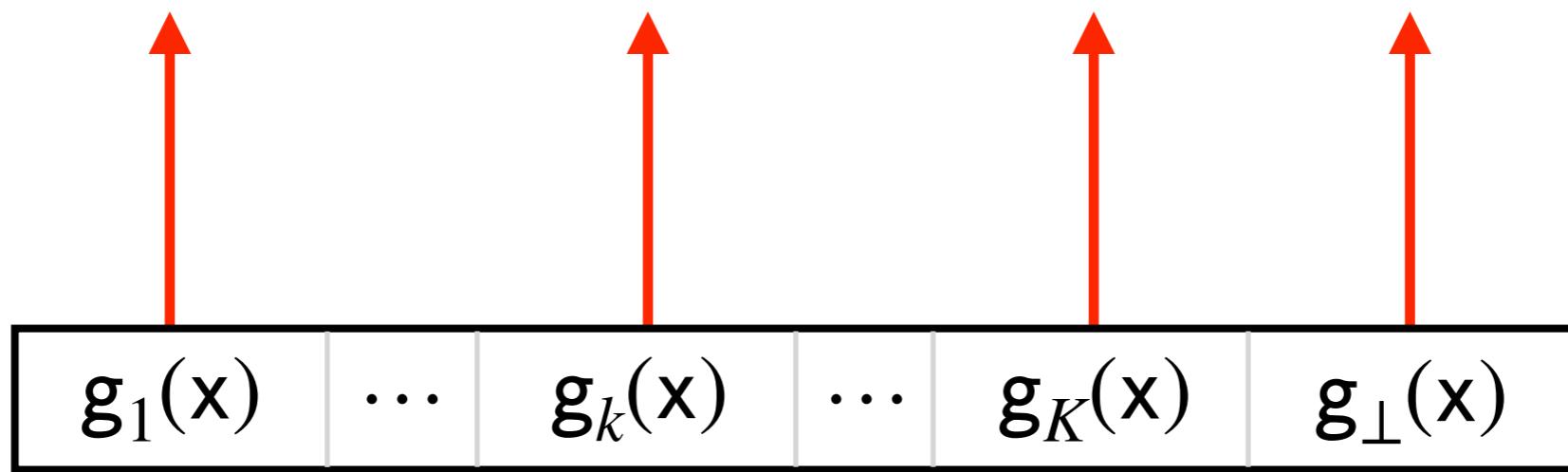
our solution: switch to a
one-vs-all parameterization

our solution: switch to a one-vs-all parameterization

$$h_{\perp}(x) = \frac{\exp\{g_{\perp}(x)\}}{\sum_{k=1}^{K+1} \exp\{g_k(x)\}}$$

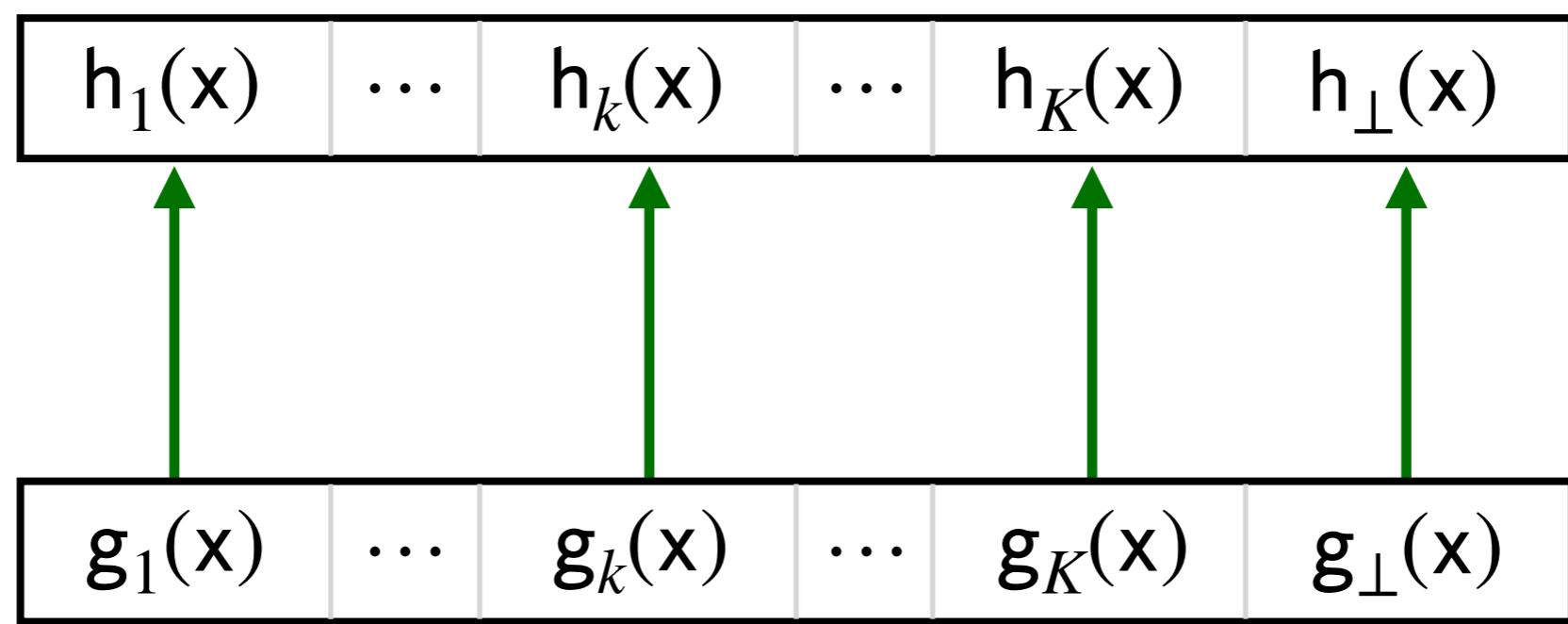


our solution: switch to a
one-vs-all parameterization



our solution: switch to a one-vs-all parameterization

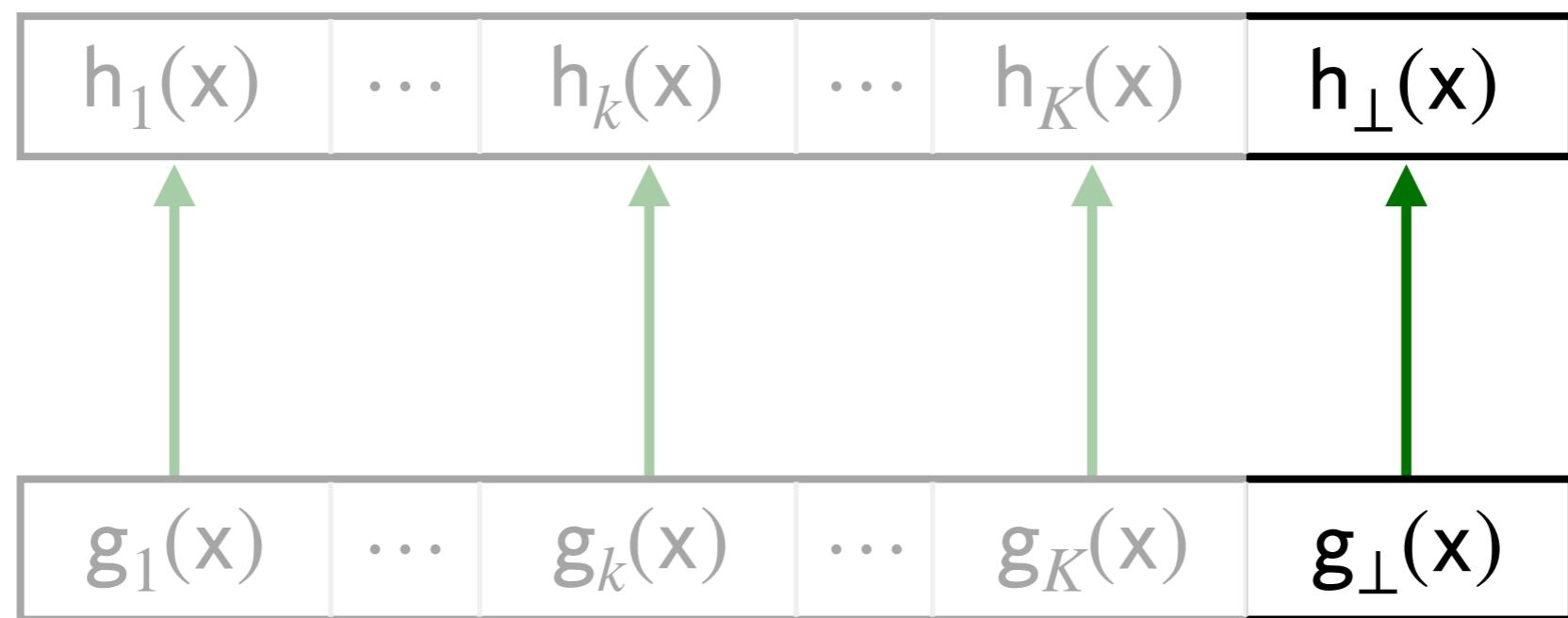
$$h_i(x) = \frac{1}{1 + \exp \{-g_i(x)\}}$$



our solution: switch to a
one-vs-all parameterization

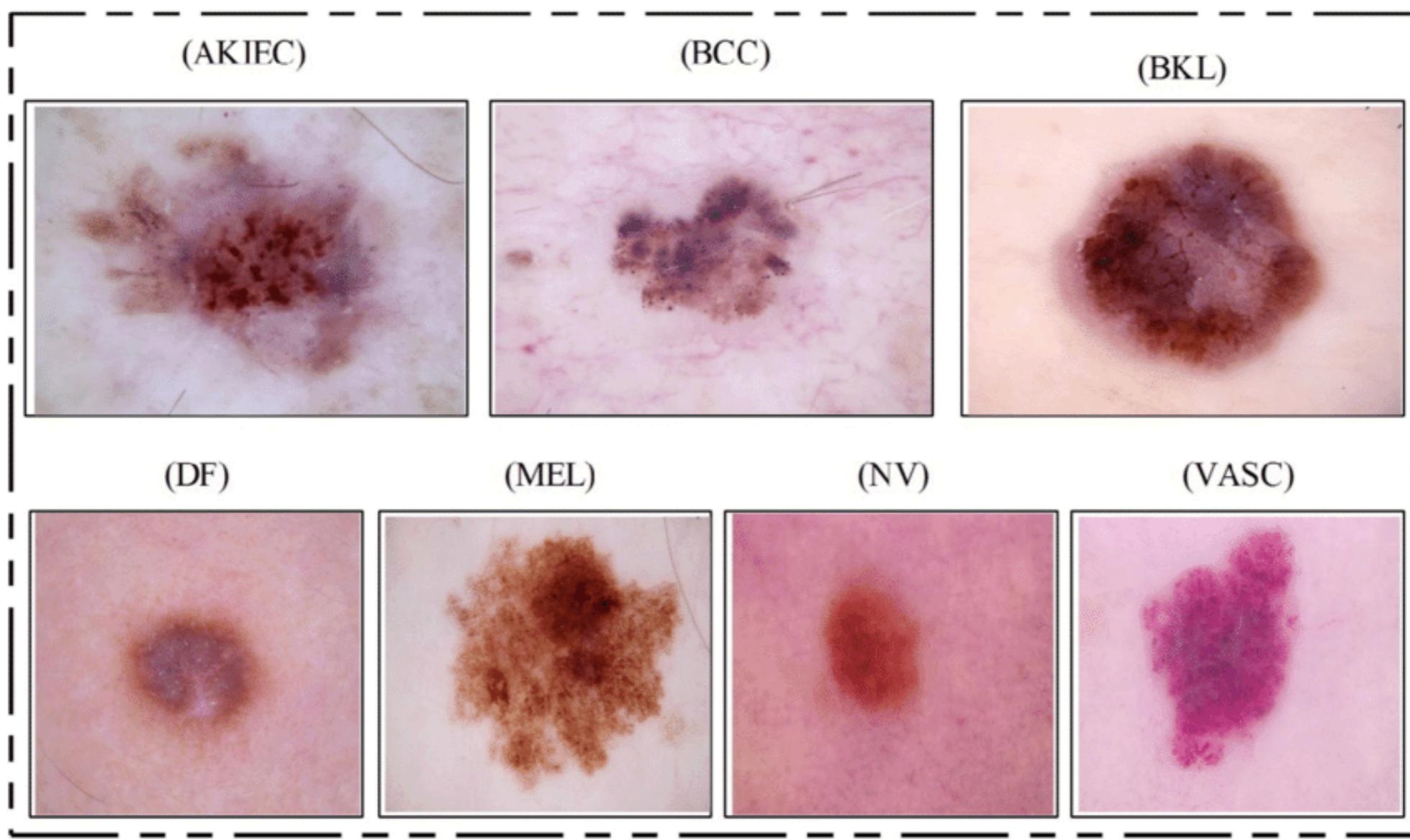
[Theorem 4.1]

$$h_{\perp}^*(x) = P(m = y | x)$$



estimating expert correctness

skin lesion diagnosis



estimating expert correctness

\hat{p}

distance: \hat{p} vs P

softmax

one-vs-all
(ours)

estimating expert correctness

\hat{p}

distance: \hat{p} vs P

softmax

26.7 ± 1.8

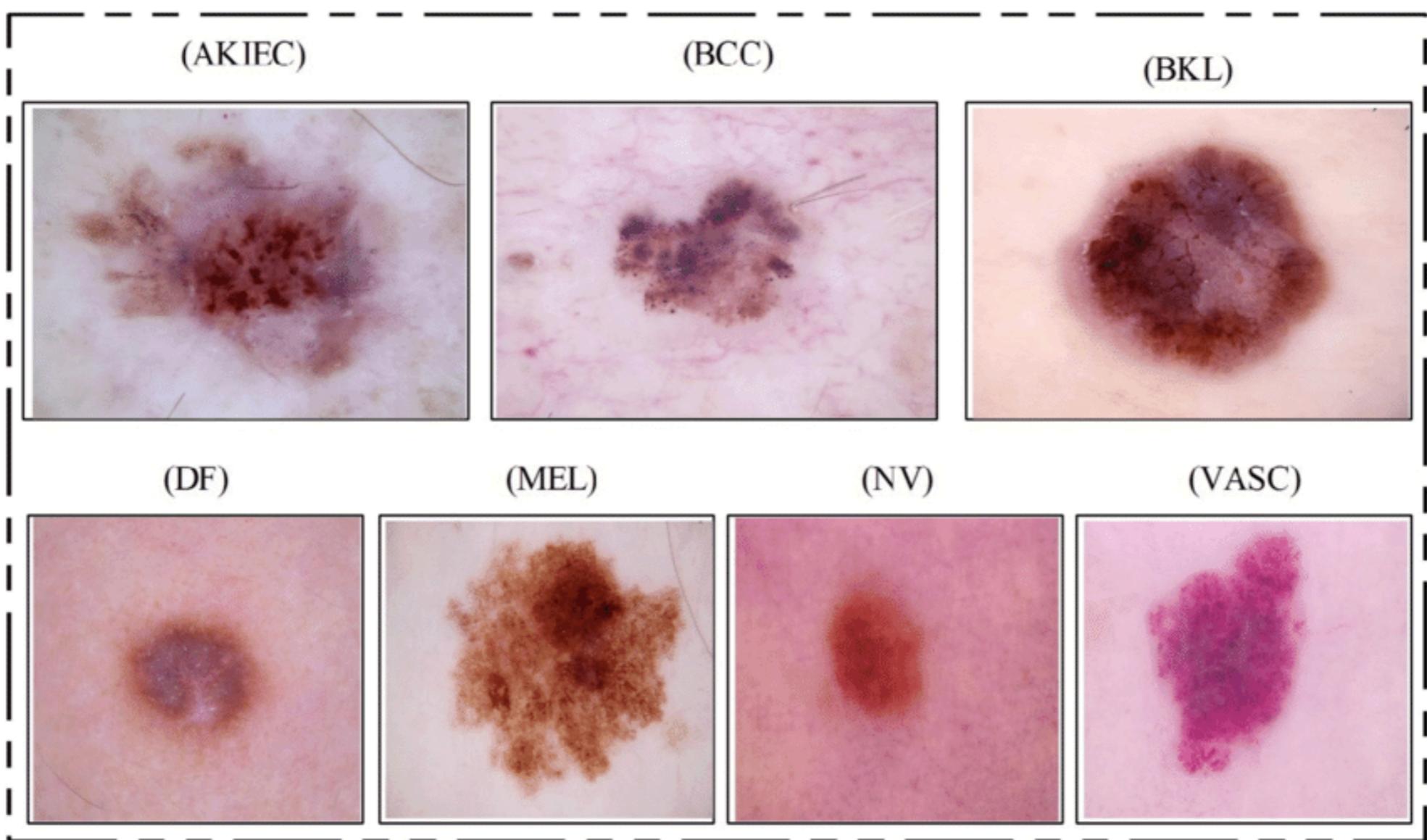
one-vs-all
(ours)

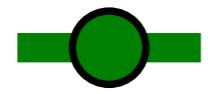
8.0 ± 1.0



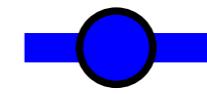
But does one-vs-all
result in more accurate models?

skin lesion diagnosis



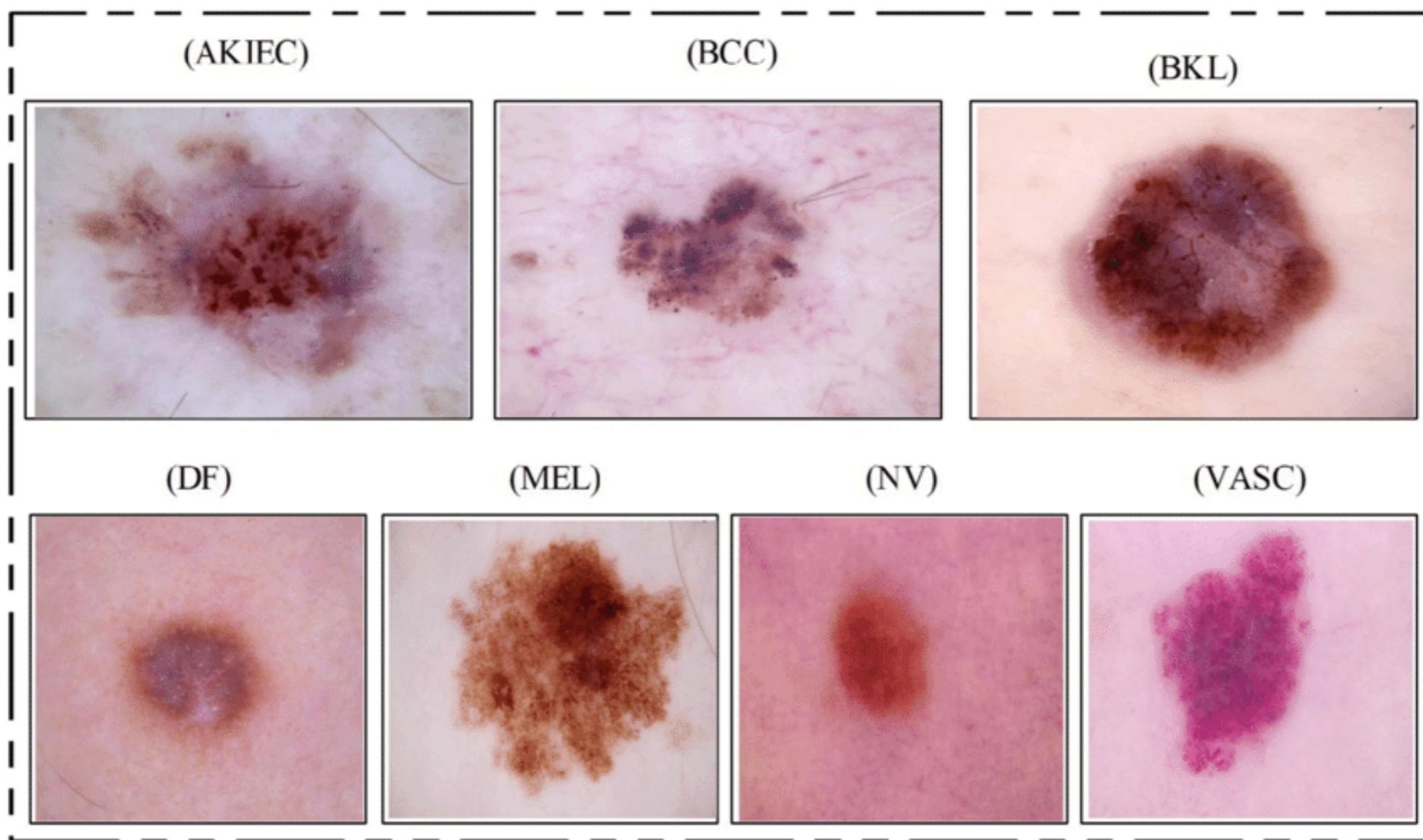


one-vs-all (ours)



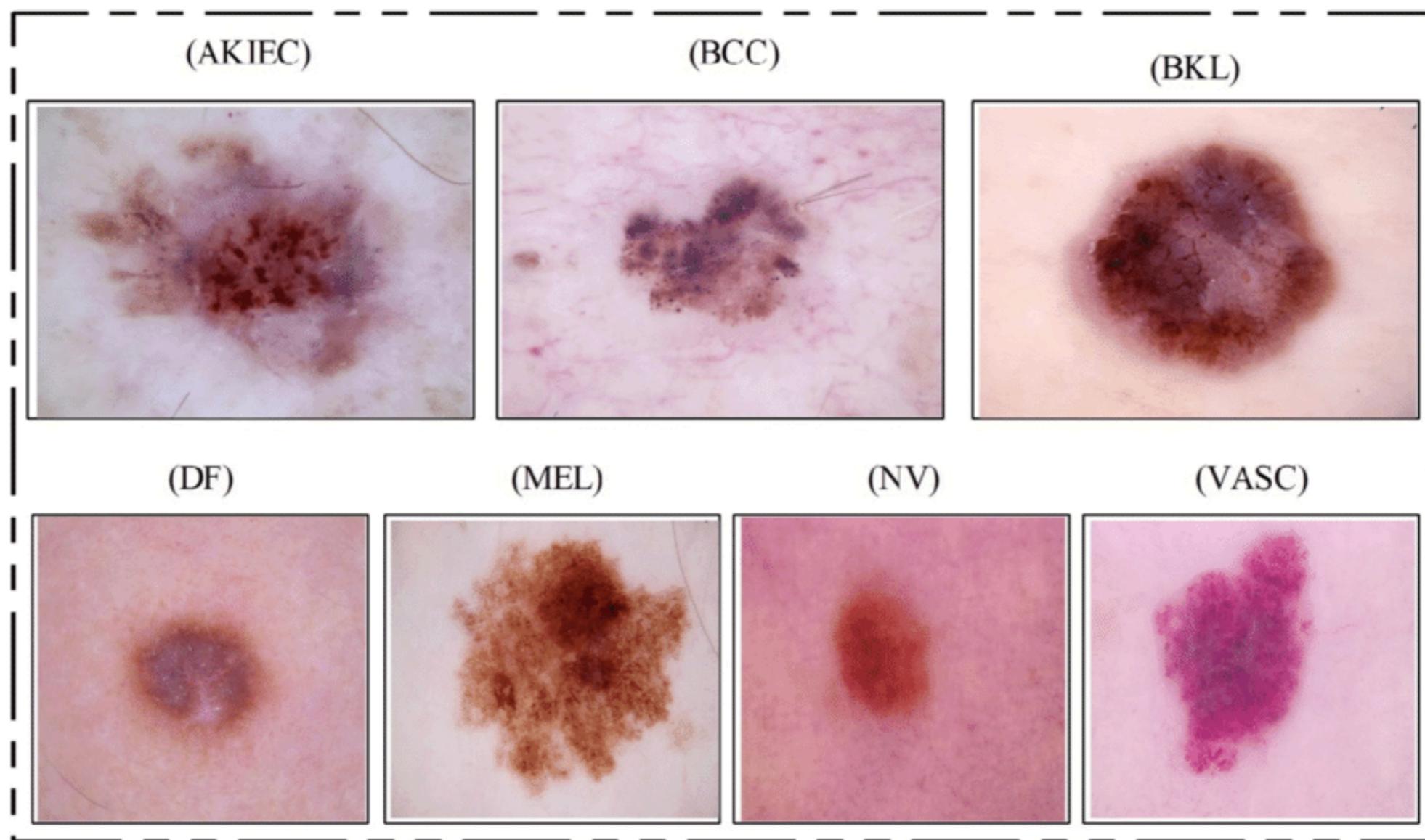
softmax

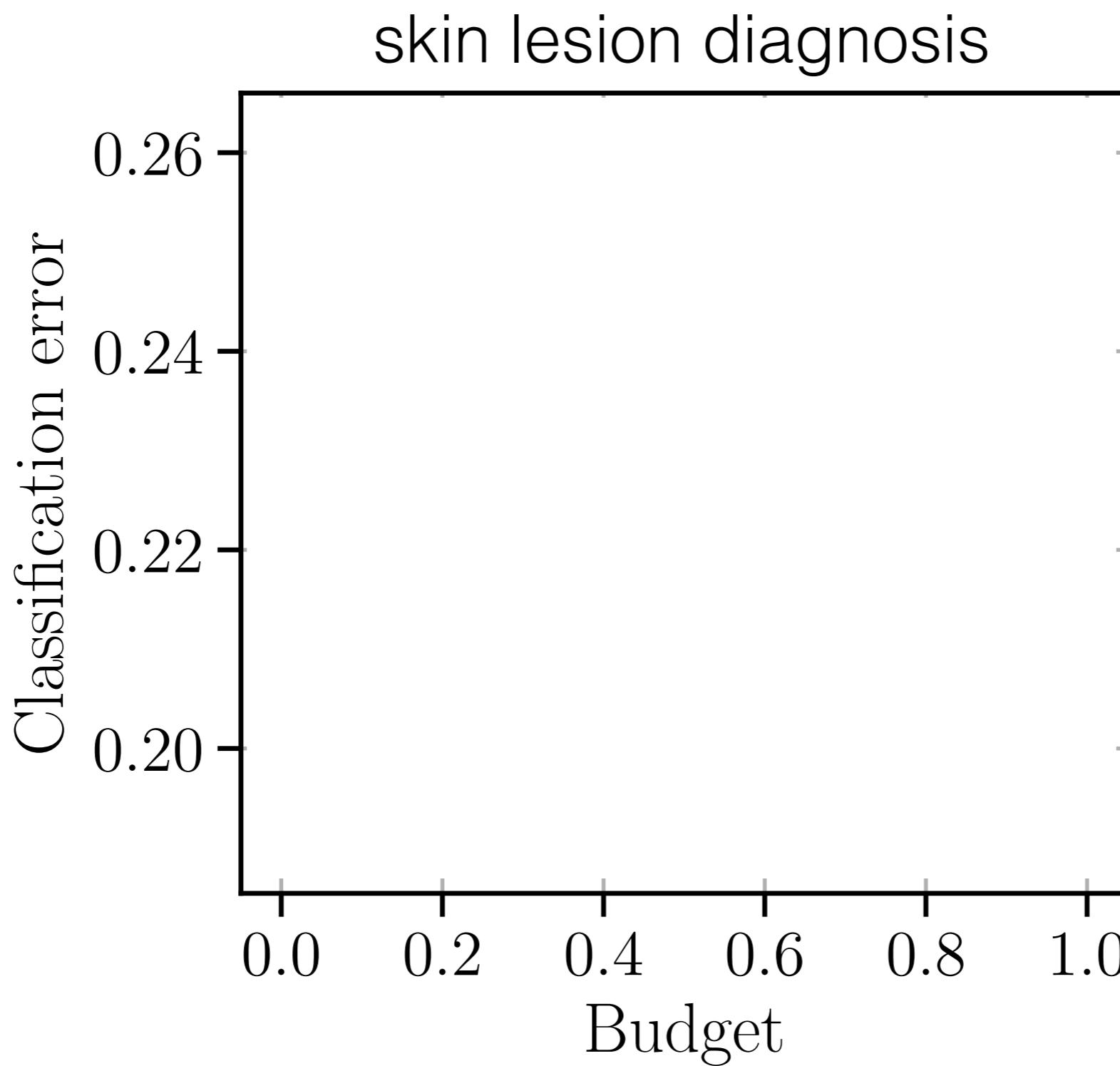
skin lesion diagnosis

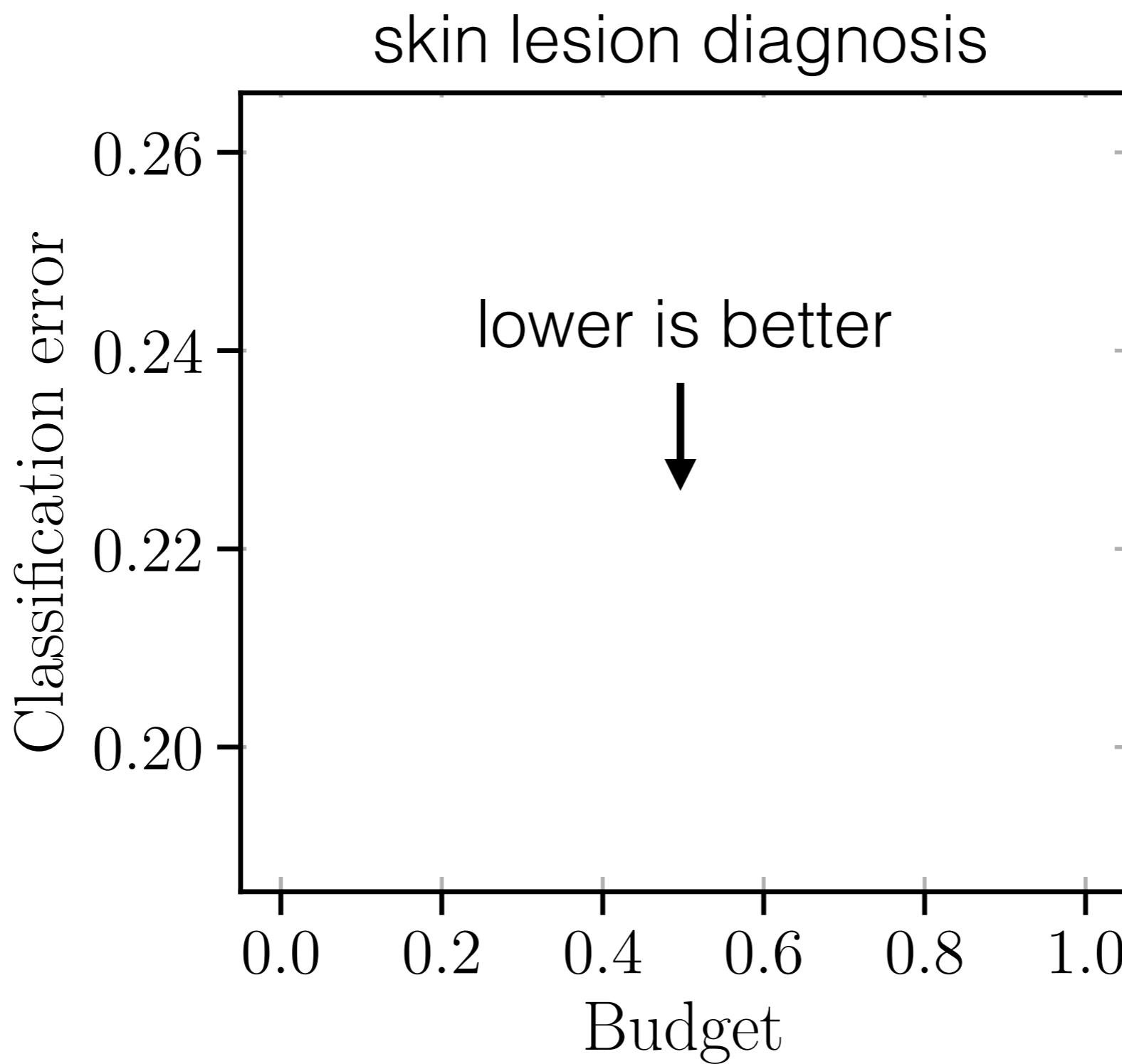
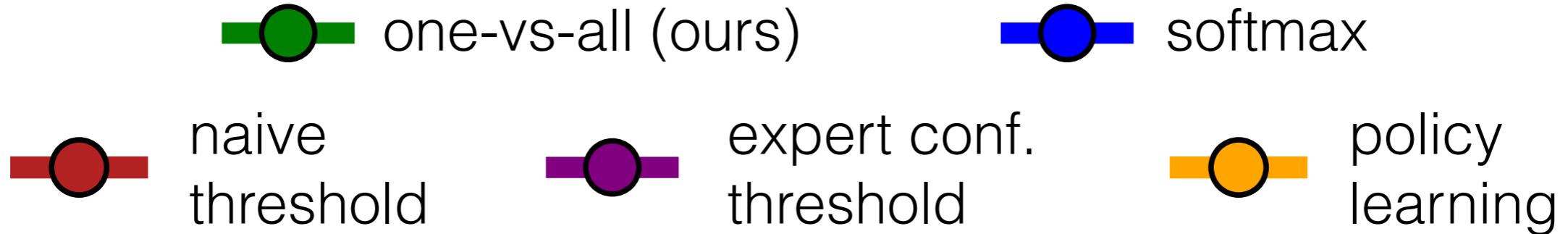




skin lesion diagnosis

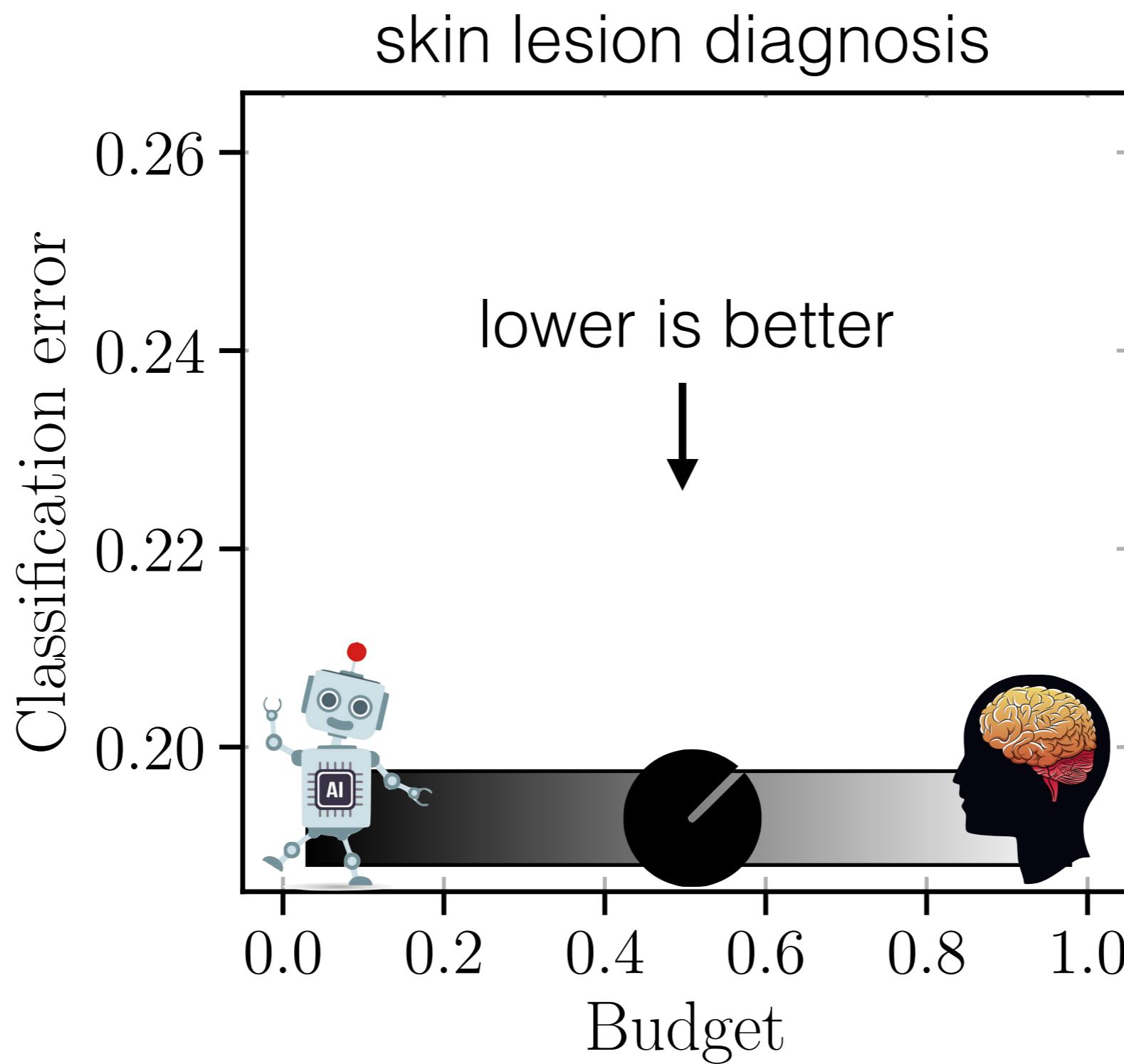


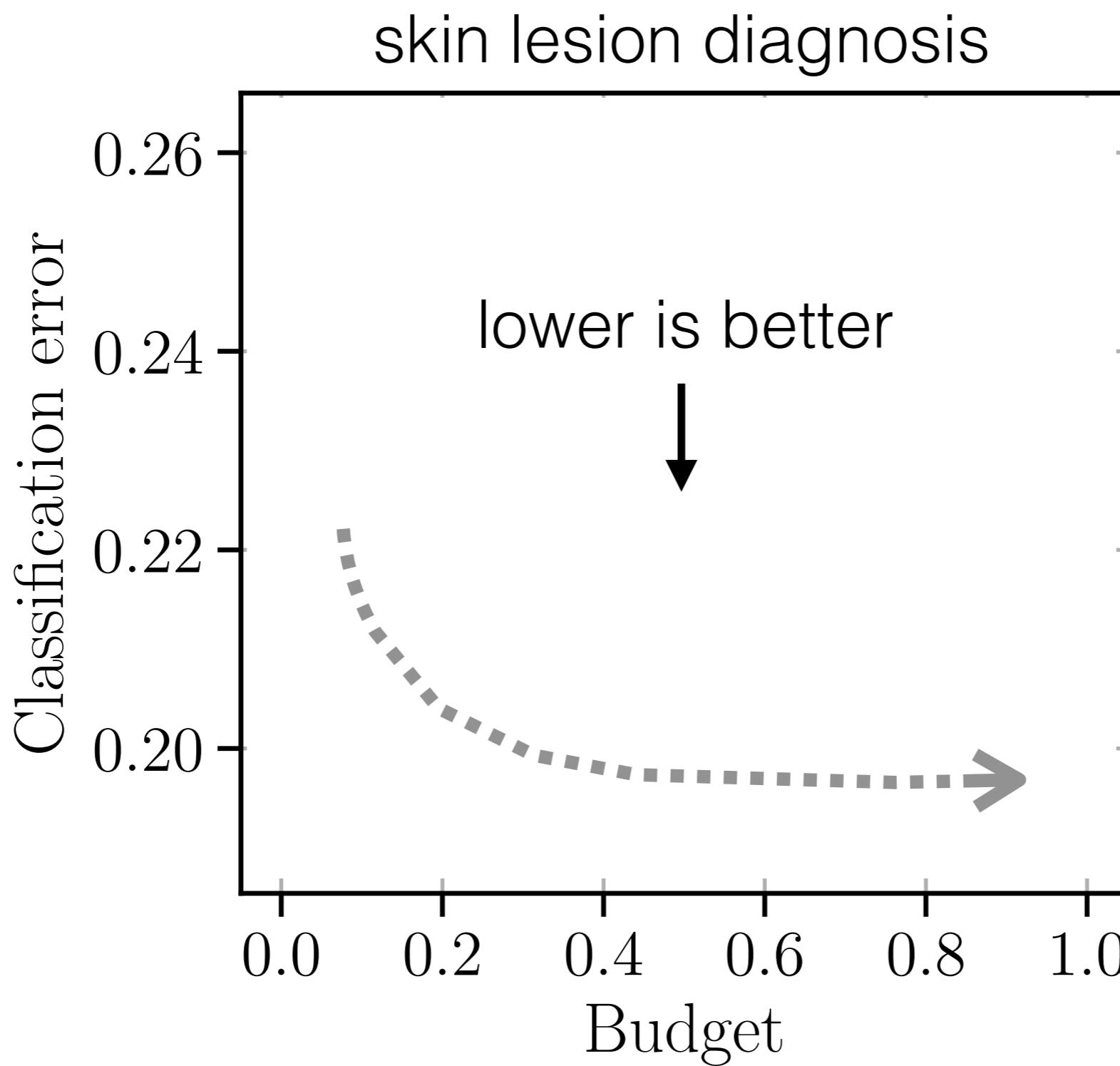




Legend:

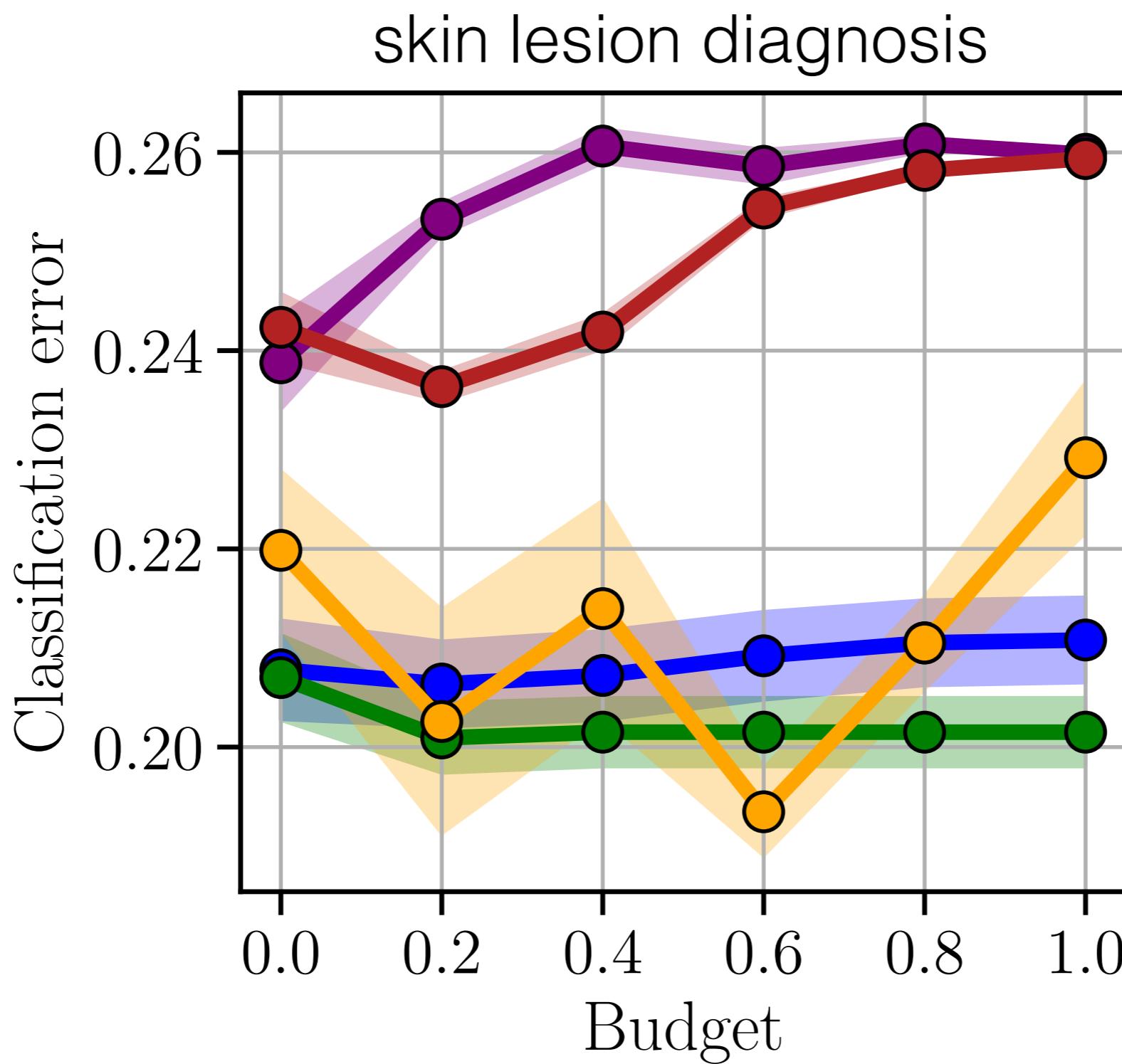
- one-vs-all (ours) (Green)
- softmax (Blue)
- naive threshold (Red)
- expert conf. threshold (Purple)
- policy learning (Yellow)





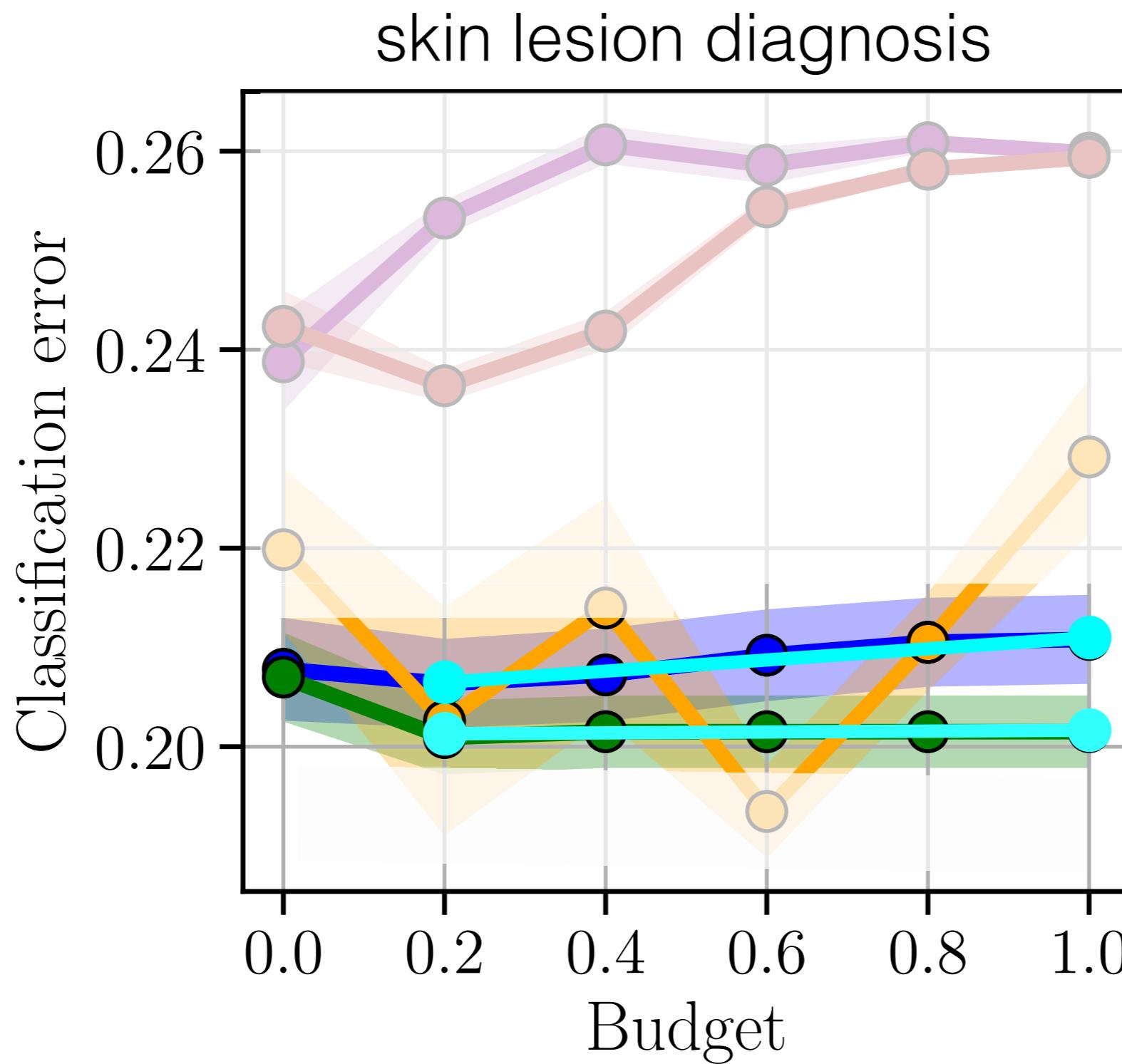
one-vs-all (ours) softmax

naive threshold expert conf. threshold policy learning



one-vs-all (ours) softmax

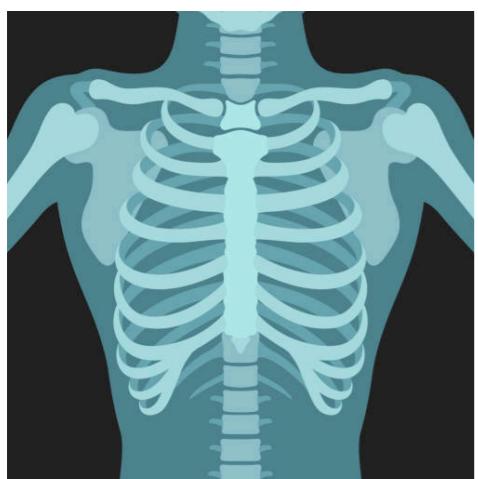
naive threshold expert conf. threshold policy learning



- ⊗ single expert
 - ⊗ softmax surrogate loss
 - ⊗ improving calibration via one-vs-all
- ⊗ multiple experts
 - ⊗ surrogate losses
 - ⊗ conformal sets of experts
- ⊗ population of experts
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 - ⊗ meta-learning a rejector

input
features



allocation
mechanism

classifier

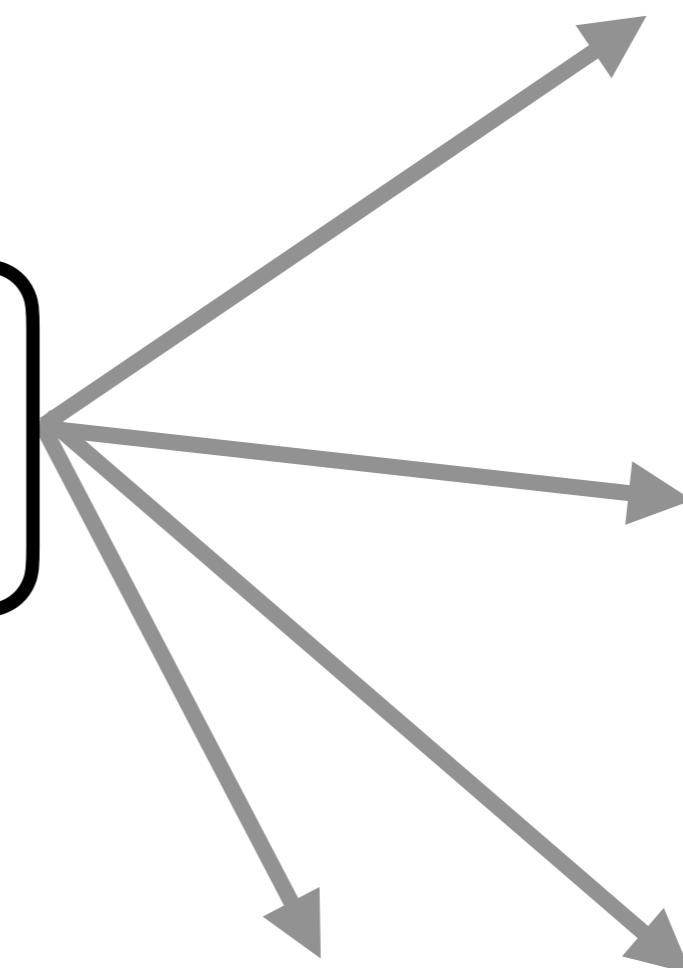


expert

input
features



allocation
mechanism



classifier



expert #1



expert #3

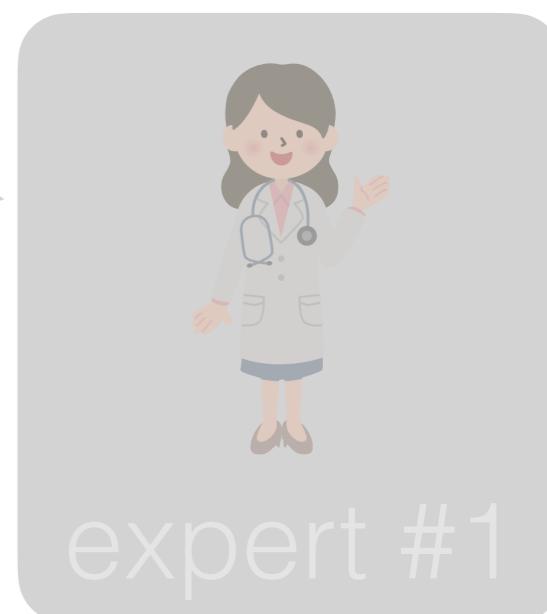
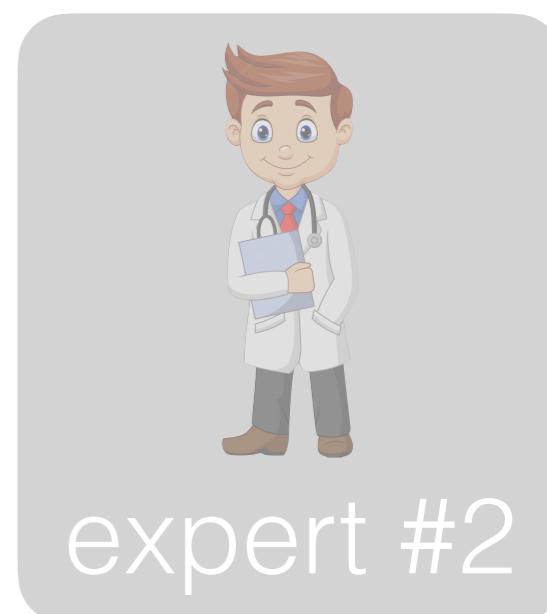


expert #2

input
features



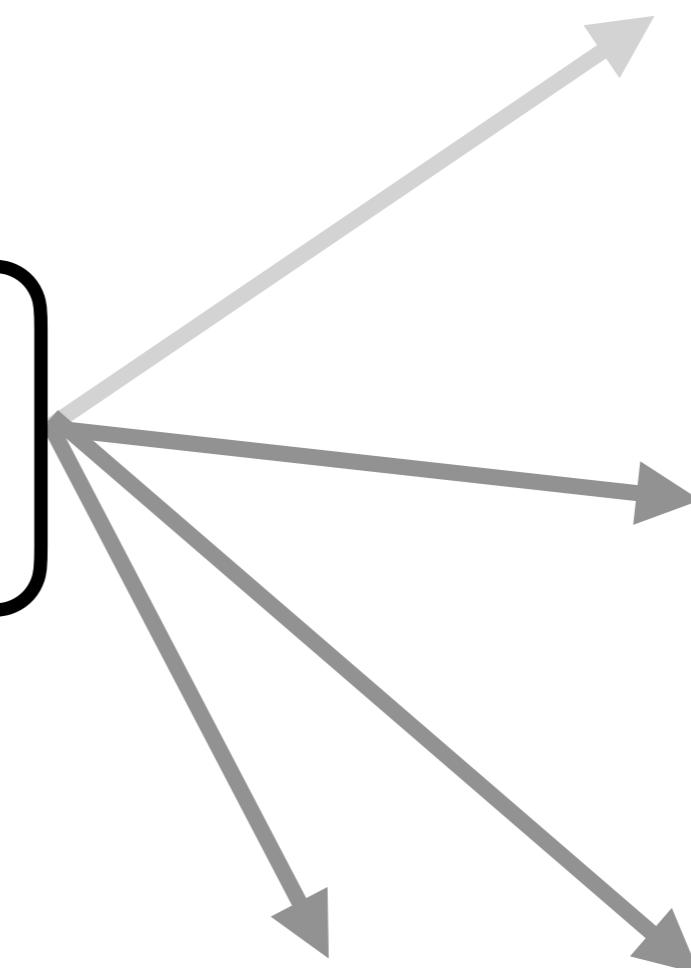
allocation
mechanism



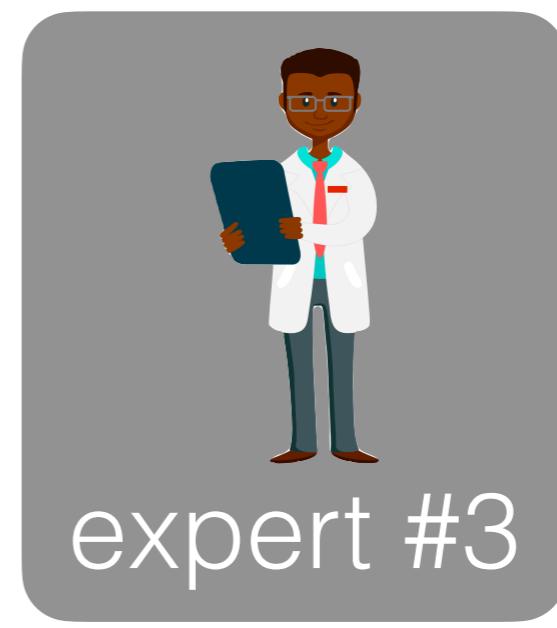
input
features



allocation
mechanism



expert #3



expert #2



expert #1

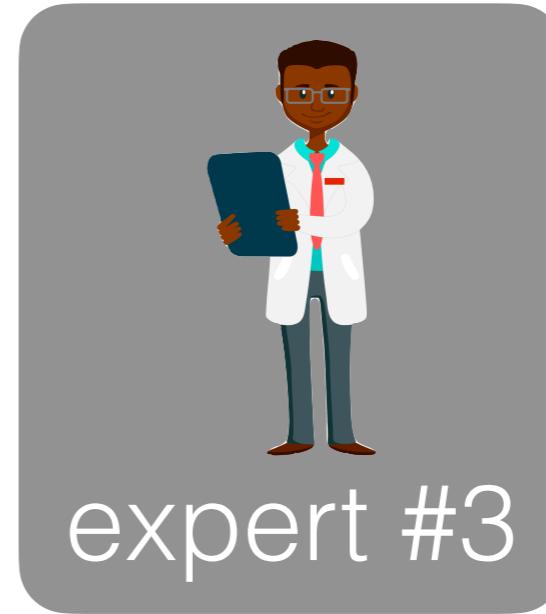


input
features



allocation
mechanism

expert #3



expert #2

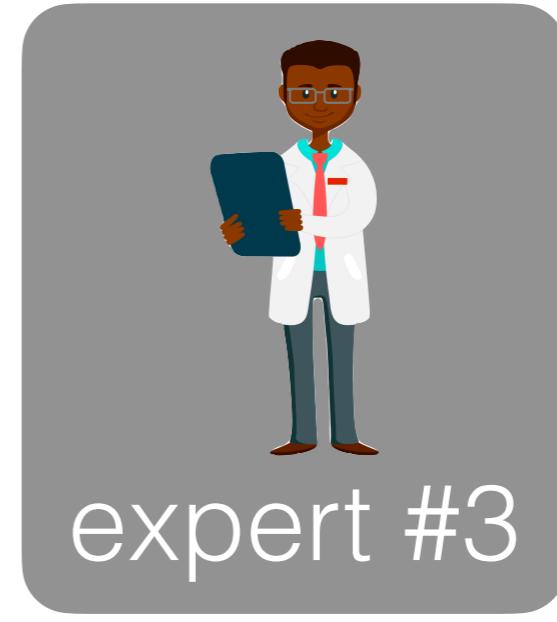


input
features

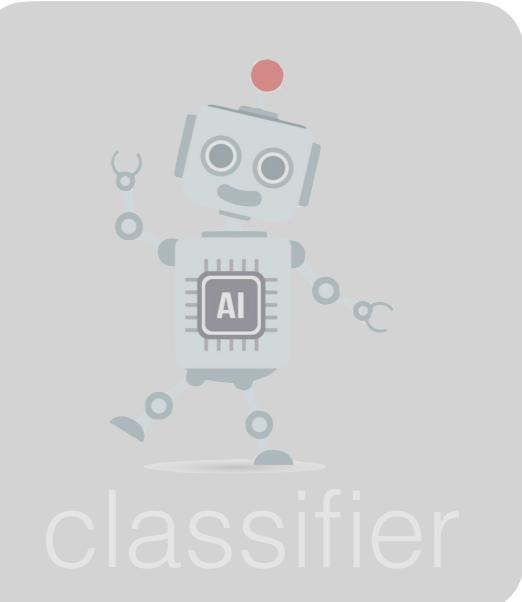


allocation
mechanism

expert #3



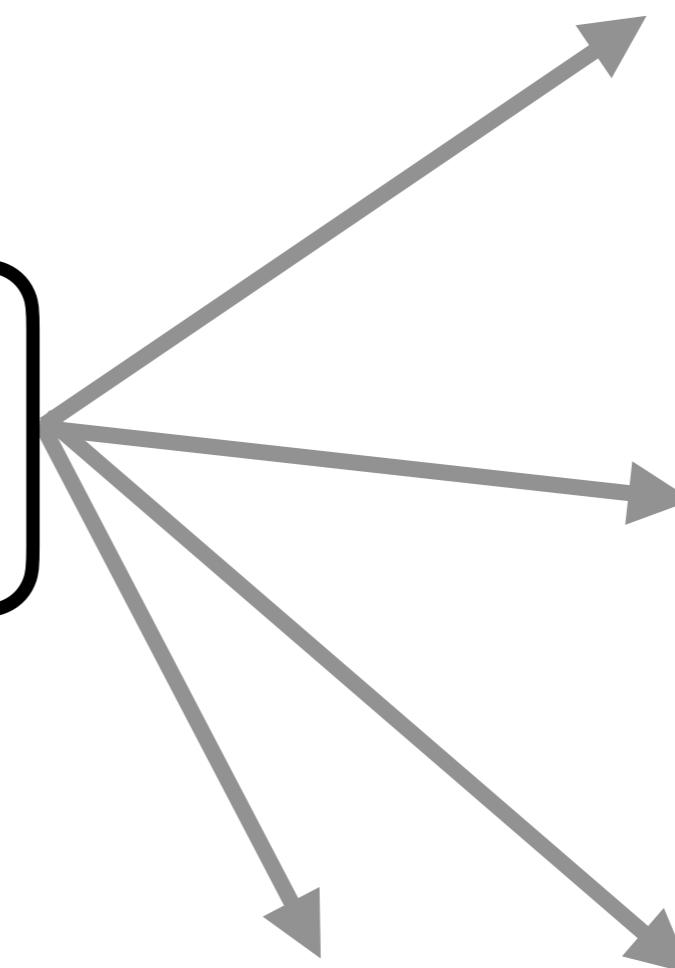
expert #2



input
features



allocation
mechanism

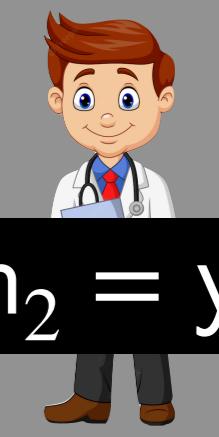


classifier



$$P(m_1 = y | x)$$

expert #1



$$P(m_3 = y | x)$$

expert #3

$$P(m_2 = y | x)$$

expert #2



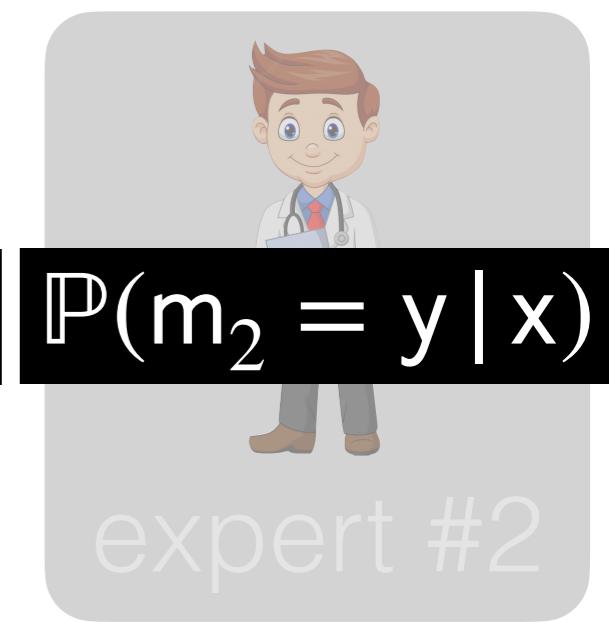
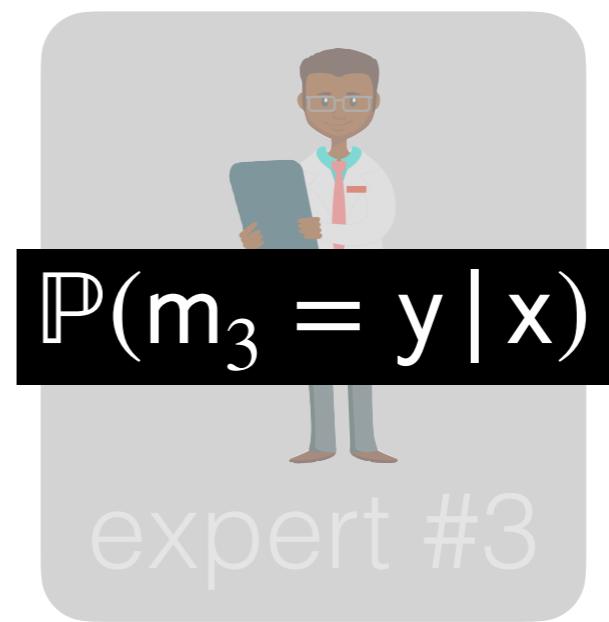
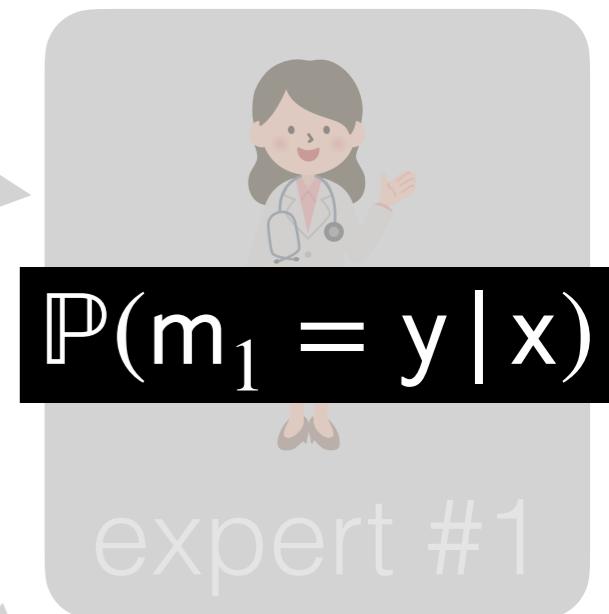
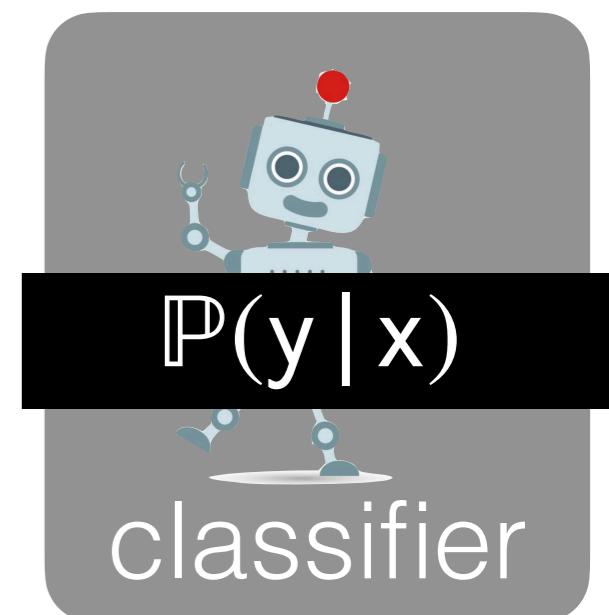
input
features



allocation
mechanism

use classifier if...

$$\max_y \mathbb{P}(y | x) > \mathbb{P}(m_j = y | x), \forall j$$



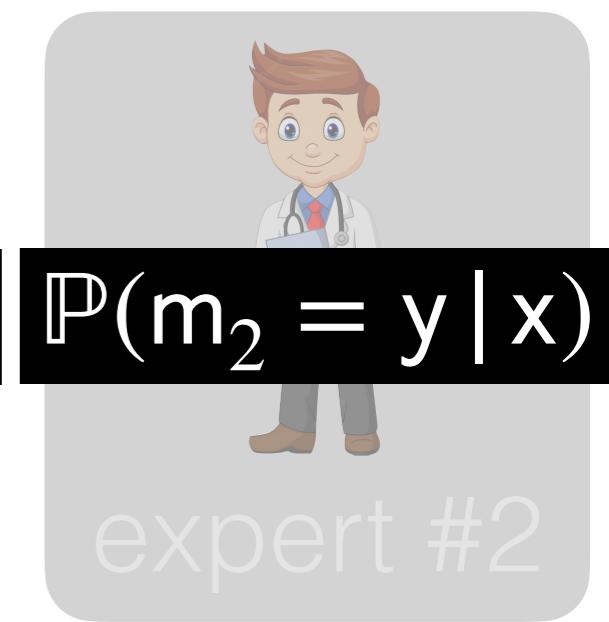
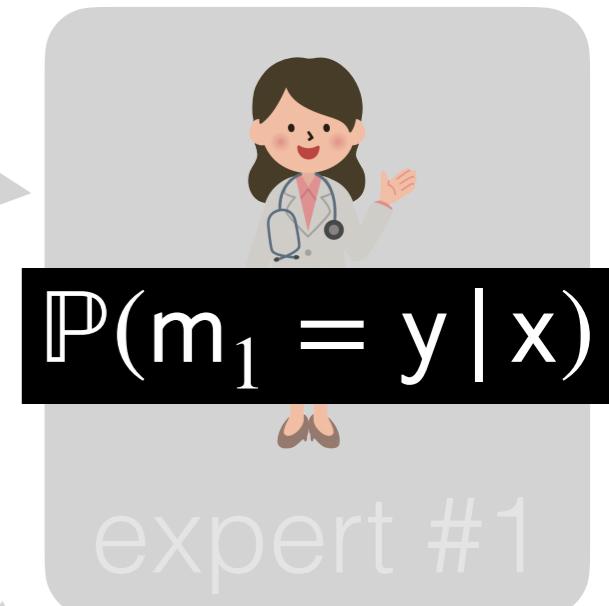
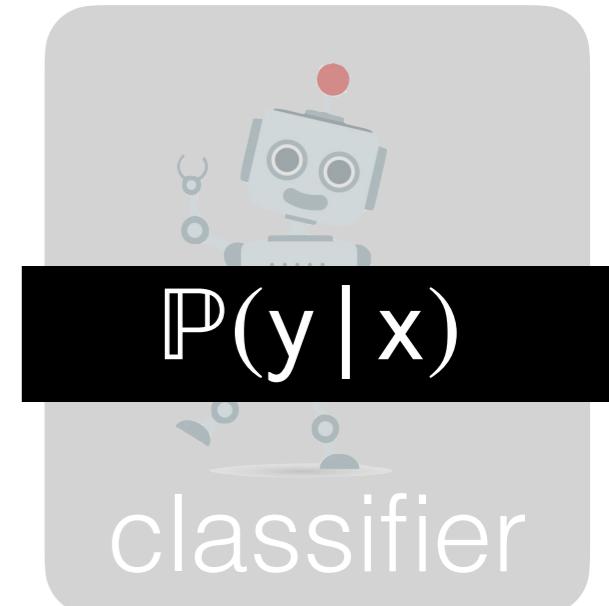
input
features



allocation
mechanism

else, pick best expert:

$$\arg \max_j \mathbb{P}(m_j = y | x)$$



multi-expert implementation

training data

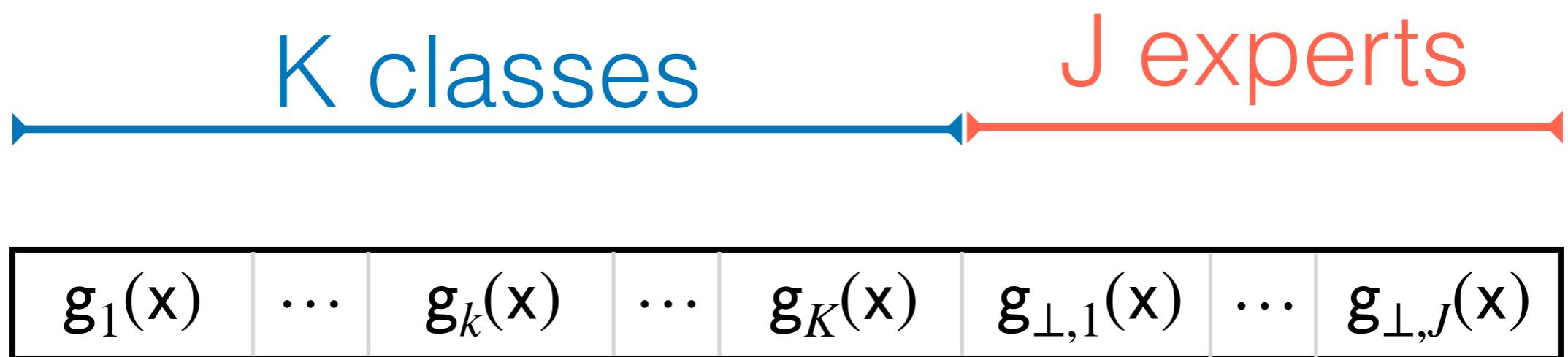
$$\mathcal{D} = \left\{ \mathbf{x}_n, \mathbf{y}_n, \mathbf{m}_{n,1}, \dots, \mathbf{m}_{n,J} \right\}_{n=1}^N$$

multi-expert implementation

training data

$$\mathcal{D} = \left\{ \mathbf{x}_n, \mathbf{y}_n, \mathbf{m}_{n,1}, \dots, \mathbf{m}_{n,J} \right\}_{n=1}^N$$

model



multi-expert implementation

training data

$$\mathcal{D} = \left\{ \mathbf{x}_n, \mathbf{y}_n, \mathbf{m}_{n,1}, \dots, \mathbf{m}_{n,J} \right\}_{n=1}^N$$

model

$h_1(\mathbf{x})$	\dots	$h_k(\mathbf{x})$	\dots	$h_K(\mathbf{x})$	$h_{\perp,1}(\mathbf{x})$	\dots	$h_{\perp,J}(\mathbf{x})$
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K classes

J experts

$g_1(\mathbf{x})$	\dots	$g_k(\mathbf{x})$	\dots	$g_K(\mathbf{x})$	$g_{\perp,1}(\mathbf{x})$	\dots	$g_{\perp,J}(\mathbf{x})$
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multi-expert implementation

training data

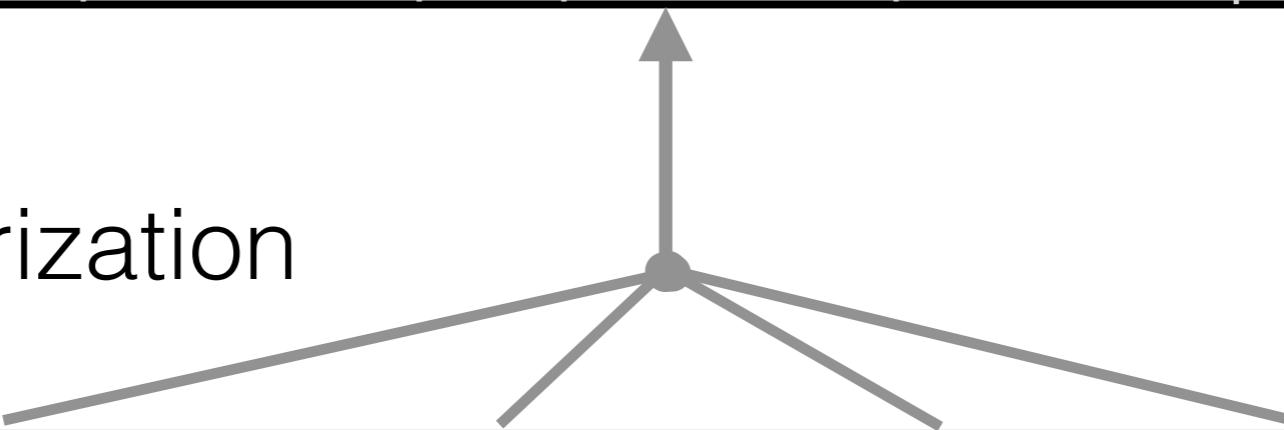
$$\mathcal{D} = \left\{ \mathbf{x}_n, \mathbf{y}_n, \mathbf{m}_{n,1}, \dots, \mathbf{m}_{n,J} \right\}_{n=1}^N$$

model

$$\boxed{h_1(\mathbf{x}) \mid \dots \mid h_k(\mathbf{x}) \mid \dots \mid h_K(\mathbf{x}) \mid h_{\perp,1}(\mathbf{x}) \mid \dots \mid h_{\perp,J}(\mathbf{x})}$$

softmax
parametrization

$$\boxed{g_1(\mathbf{x}) \mid \dots \mid g_k(\mathbf{x}) \mid \dots \mid g_K(\mathbf{x}) \mid g_{\perp,1}(\mathbf{x}) \mid \dots \mid g_{\perp,J}(\mathbf{x})}$$



multi-expert implementation

training data

$$\mathcal{D} = \left\{ \mathbf{x}_n, \mathbf{y}_n, \mathbf{m}_{n,1}, \dots, \mathbf{m}_{n,J} \right\}_{n=1}^N$$

model

$$\boxed{h_1(\mathbf{x}) \mid \dots \mid h_k(\mathbf{x}) \mid \dots \mid h_K(\mathbf{x}) \mid h_{\perp,1}(\mathbf{x}) \mid \dots \mid h_{\perp,J}(\mathbf{x})}$$

one-vs-all
parameterization

$$\boxed{g_1(\mathbf{x}) \mid \dots \mid g_k(\mathbf{x}) \mid \dots \mid g_K(\mathbf{x}) \mid g_{\perp,1}(\mathbf{x}) \mid \dots \mid g_{\perp,J}(\mathbf{x})}$$

multi-expert implementation

training data

$$\mathcal{D} = \left\{ \mathbf{x}_n, \mathbf{y}_n, \mathbf{m}_{n,1}, \dots, \mathbf{m}_{n,J} \right\}_{n=1}^N$$

model

- ⊗ softmax and one-vs-all variants
- ⊗ both consistent w.r.t. 0-1 loss

multi-expert implementation

training data

$$\mathcal{D} = \left\{ \mathbf{x}_n, y_n, m_{n,1}, \dots, m_{n,J} \right\}_{n=1}^N$$

model

- ⊗ softmax and one-vs-all variants
- ⊗ both consistent w.r.t. 0-1 loss

softmax loss function

$$\ell(\theta; \mathbf{x}, \mathbf{y}, \mathbf{m}) = -\log h_y(\mathbf{x}) - \sum_j \mathbb{I}[y = m_j] \cdot \log h_{\perp,j}(\mathbf{x})$$

multi-expert implementation

training data

$$\mathcal{D} = \left\{ \mathbf{x}_n, y_n, m_{n,1}, \dots, m_{n,J} \right\}_{n=1}^N$$

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multi-expert implementation

training data

$$\mathcal{D} = \left\{ \mathbf{x}_n, \mathbf{y}_n, \mathbf{m}_{n,1}, \dots, \mathbf{m}_{n,J} \right\}_{n=1}^N$$

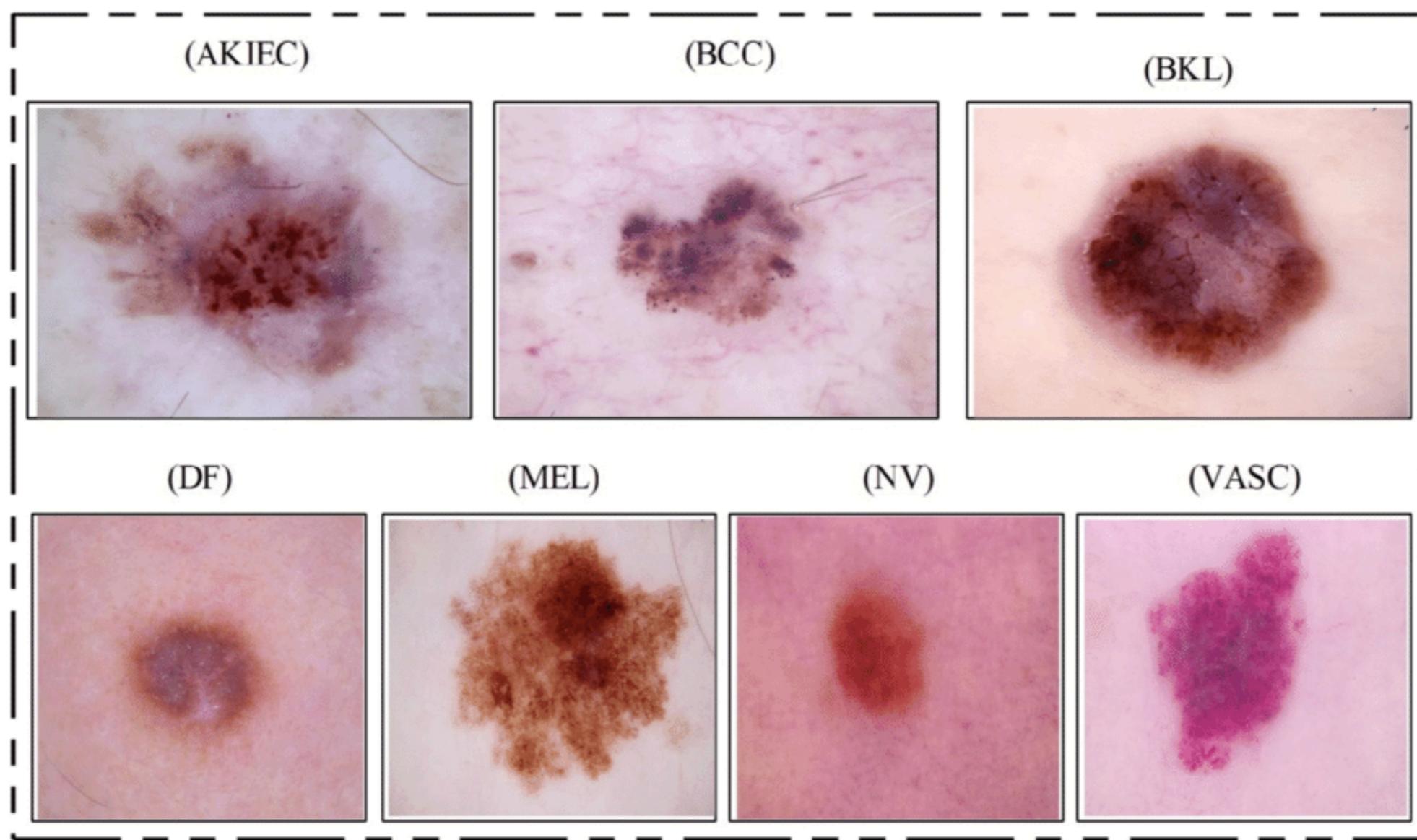
model

- ⊗ softmax and one-vs-all variants
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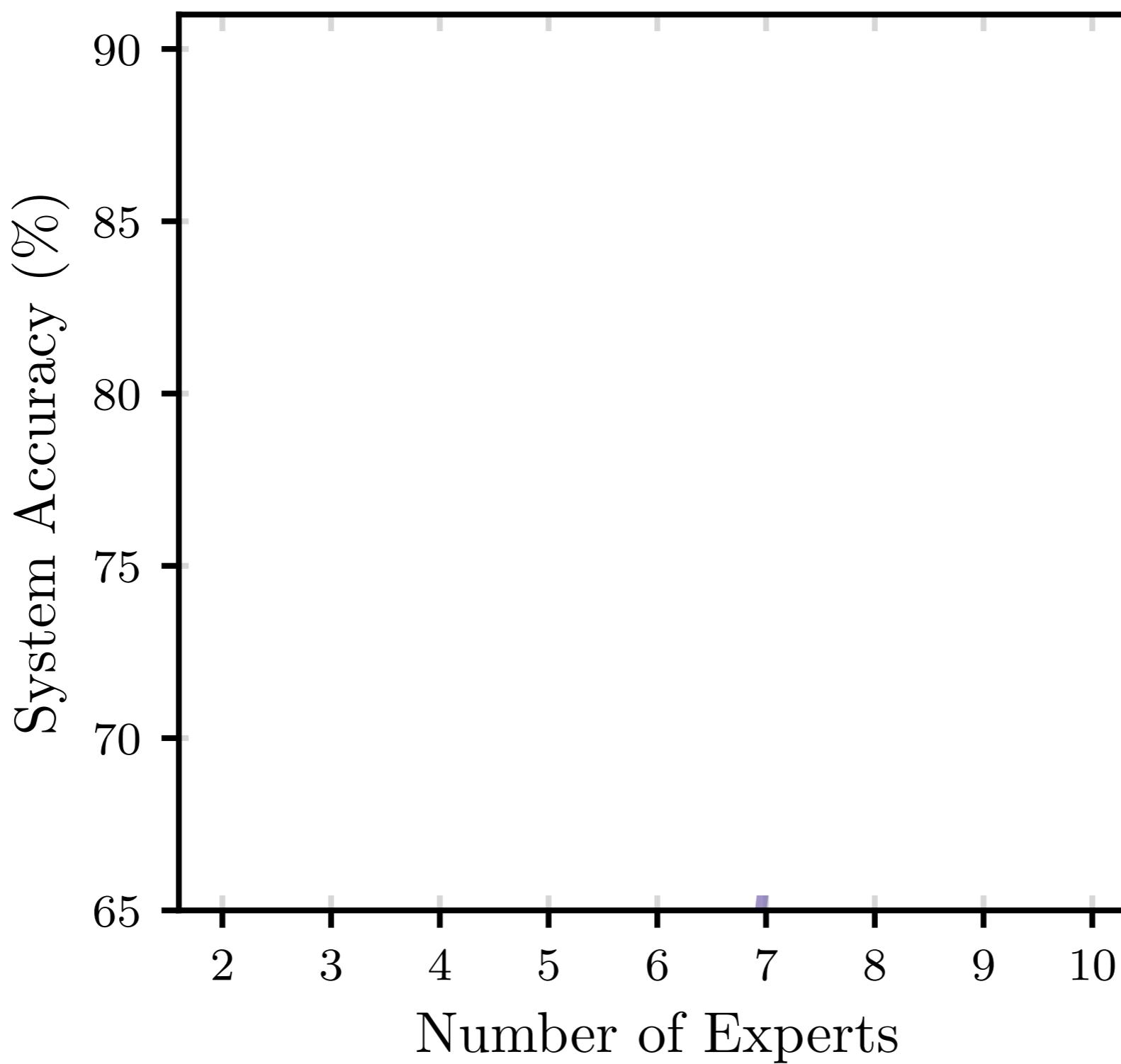
softmax loss function

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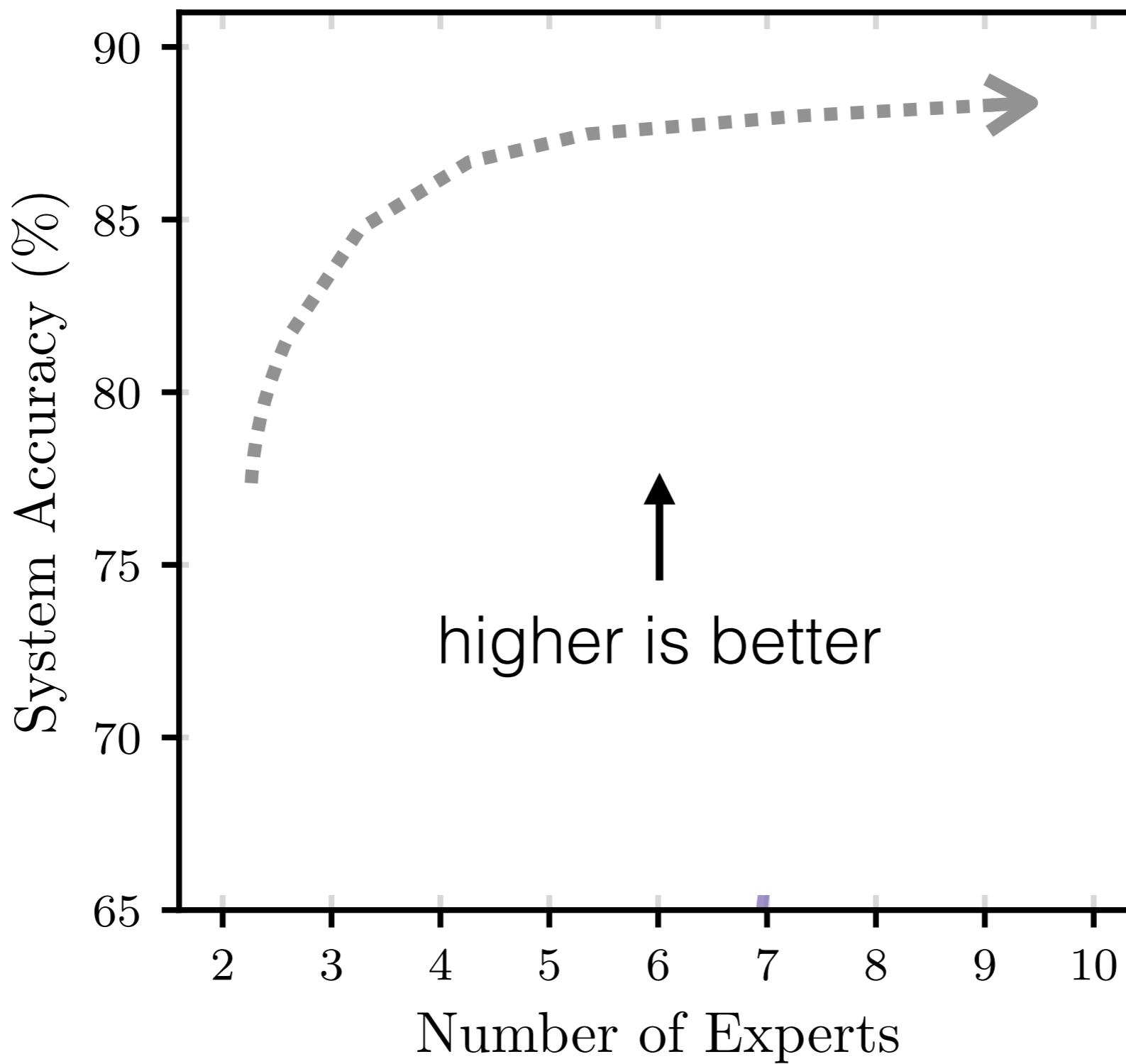
skin lesion diagnosis



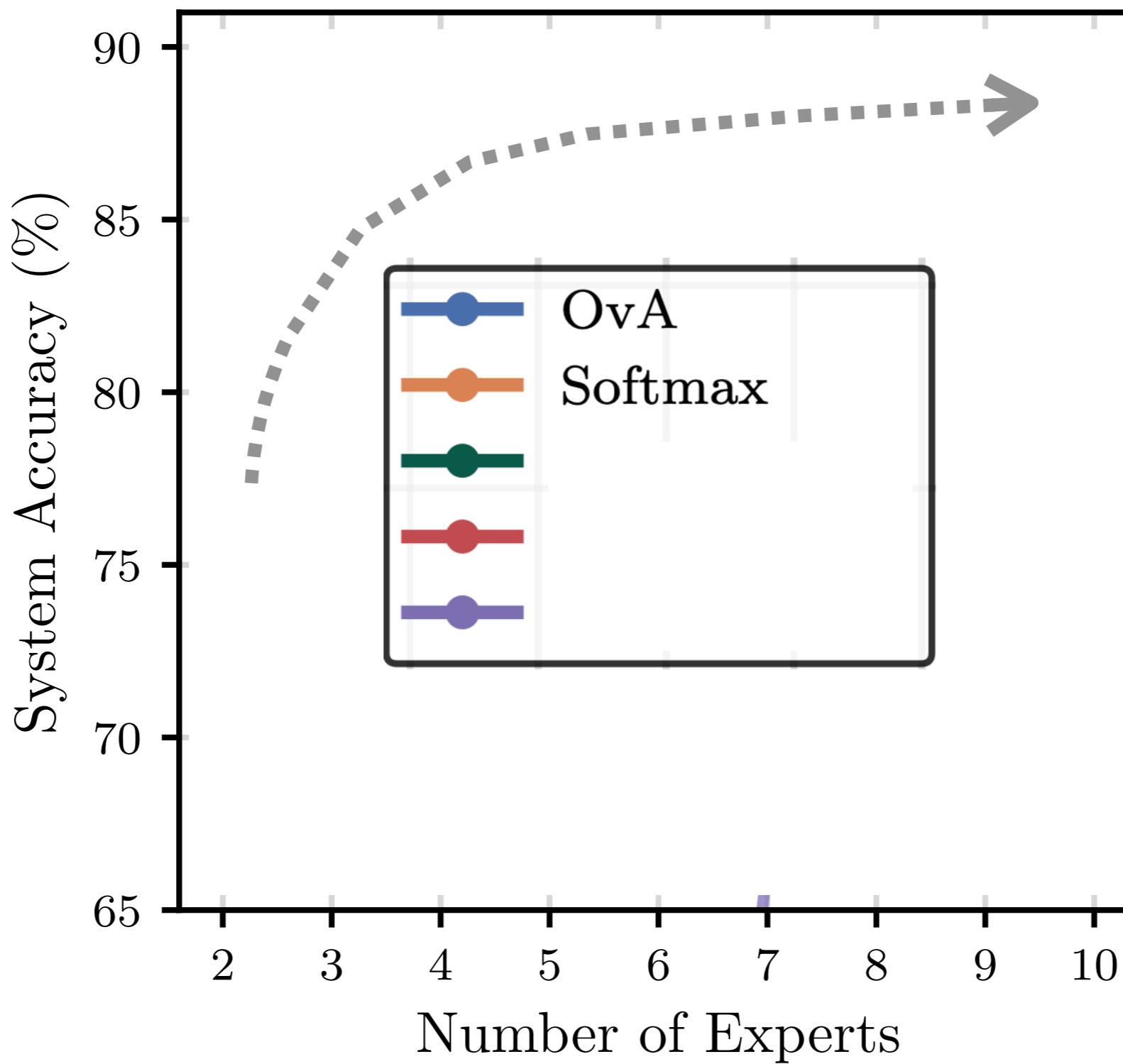
skin lesion diagnosis



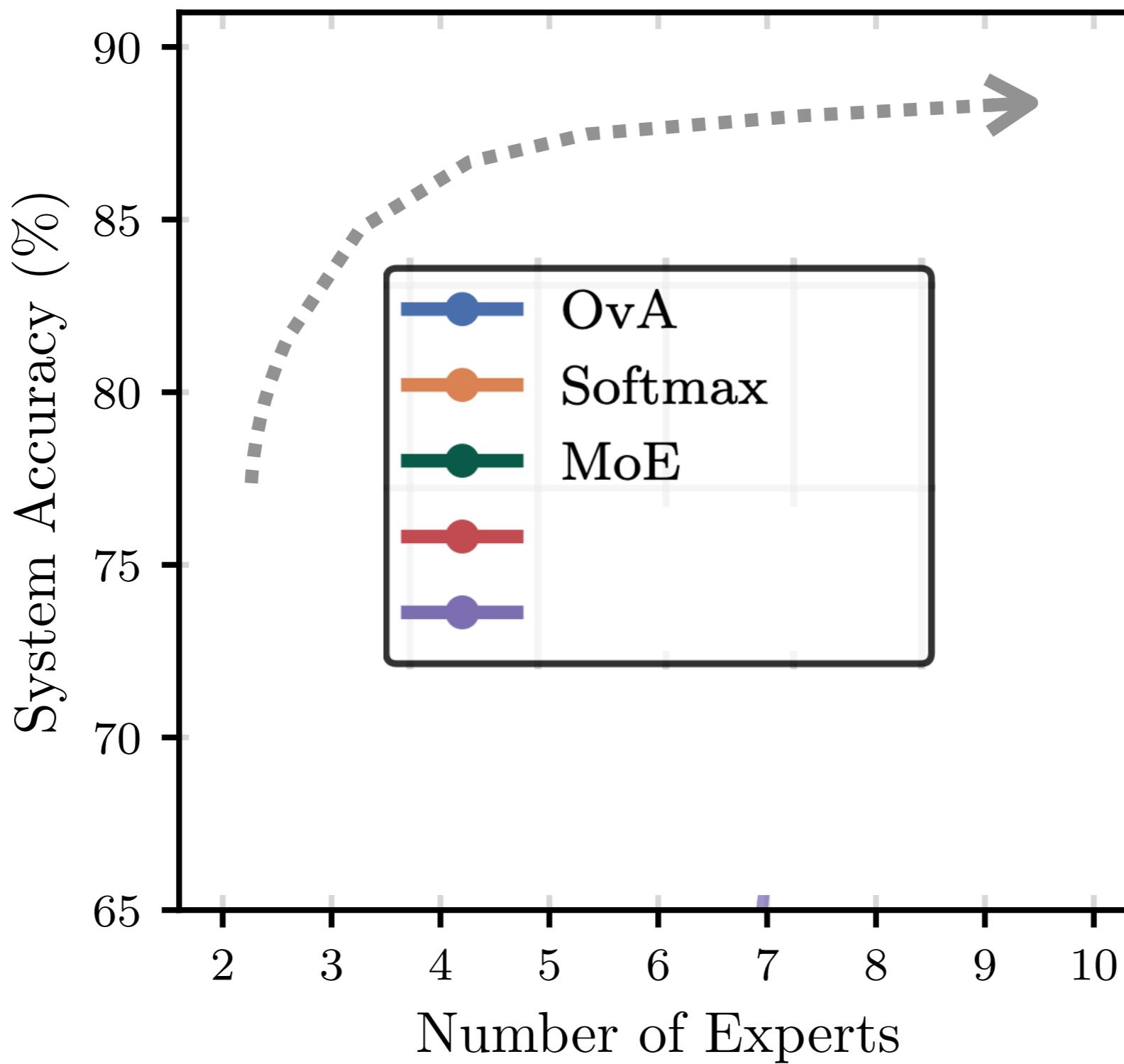
skin lesion diagnosis



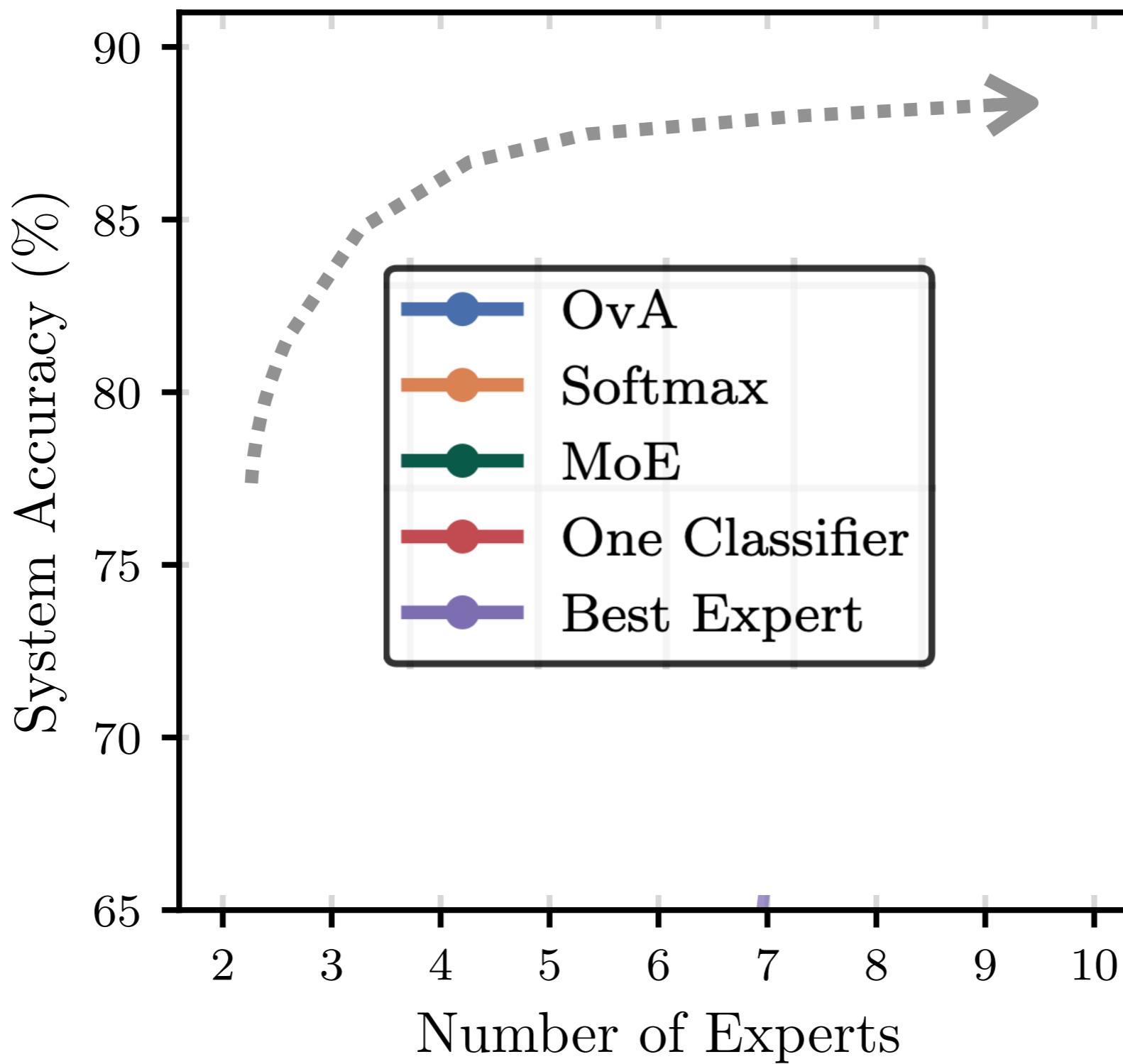
skin lesion diagnosis



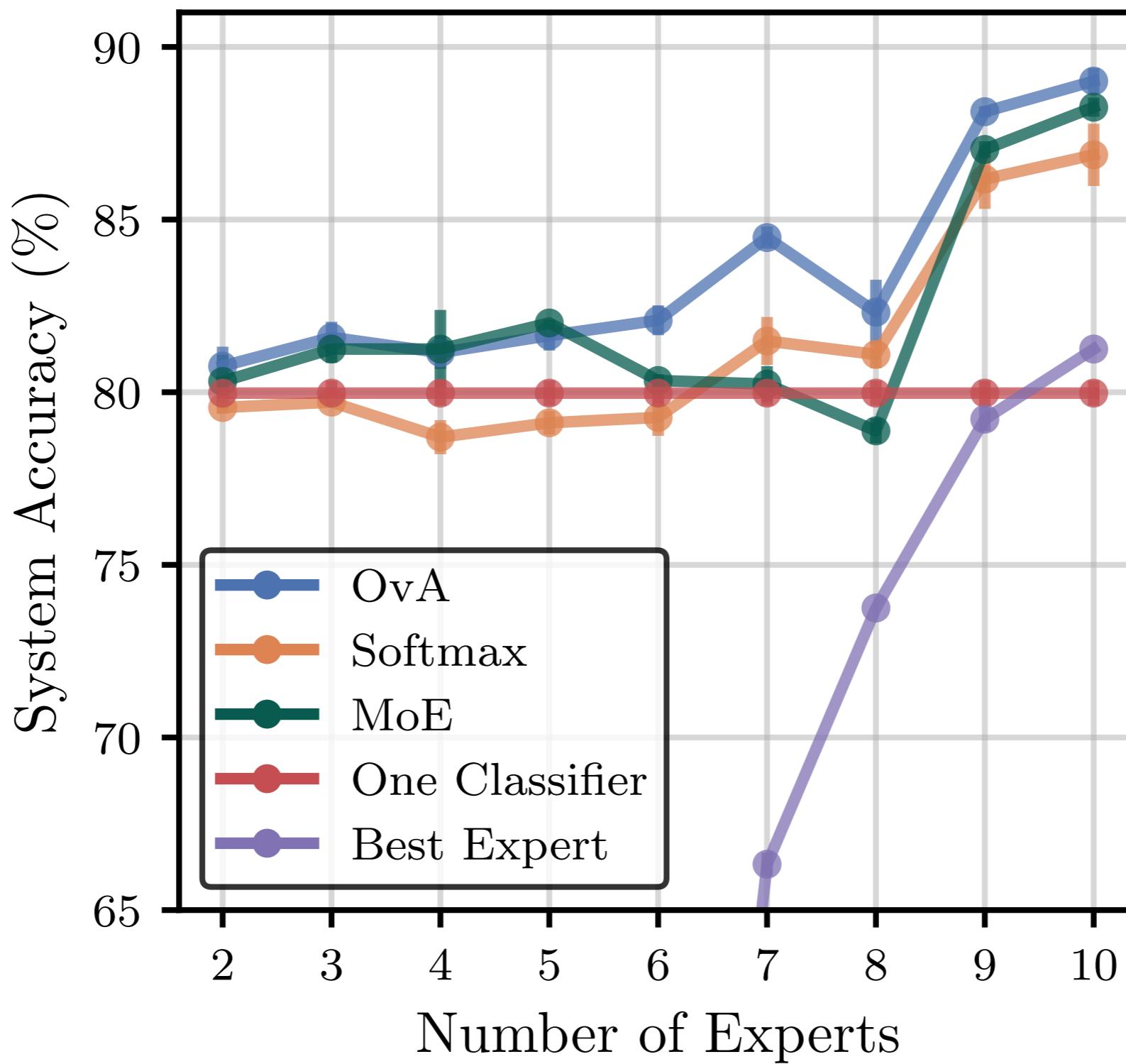
skin lesion diagnosis



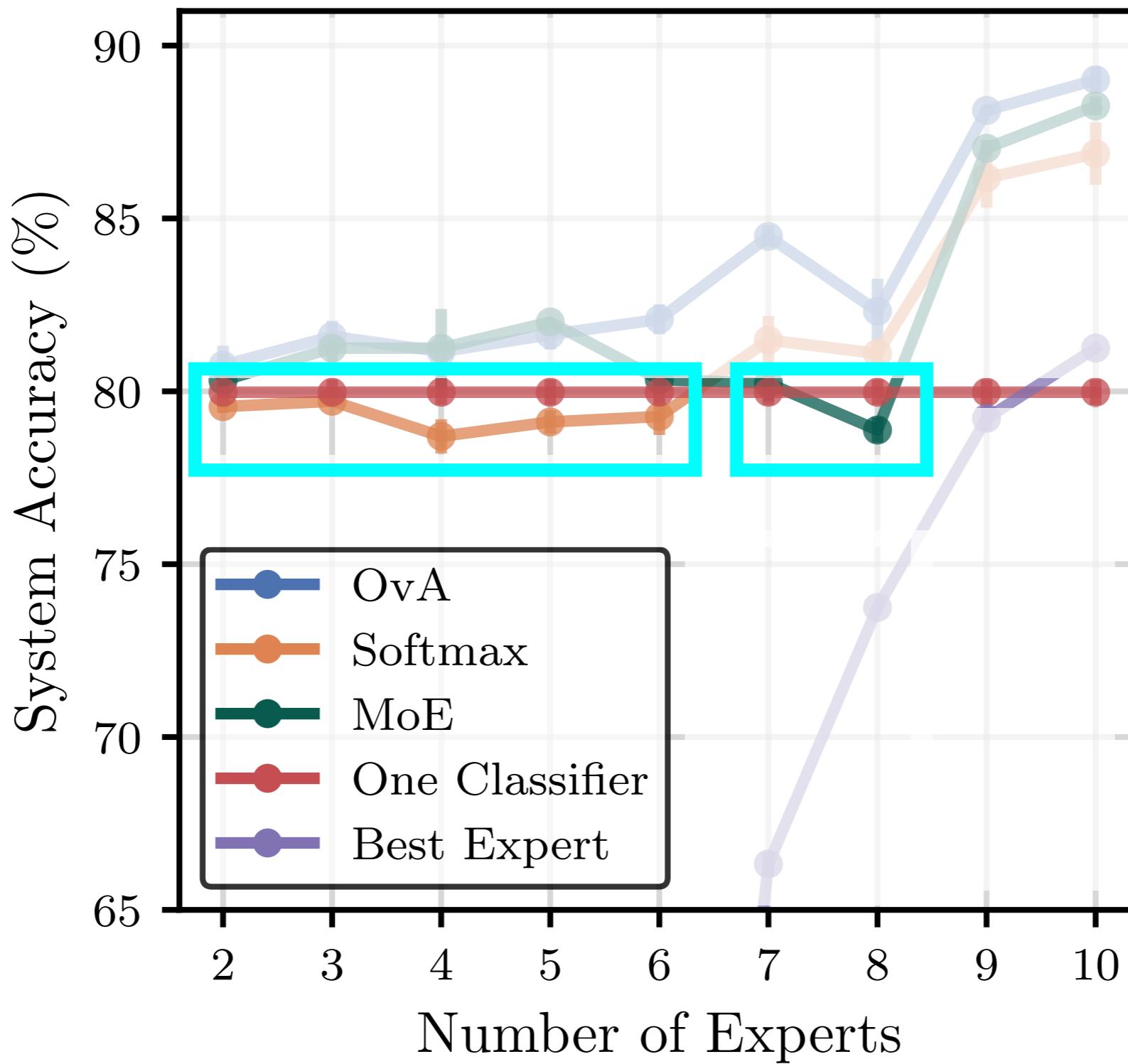
skin lesion diagnosis



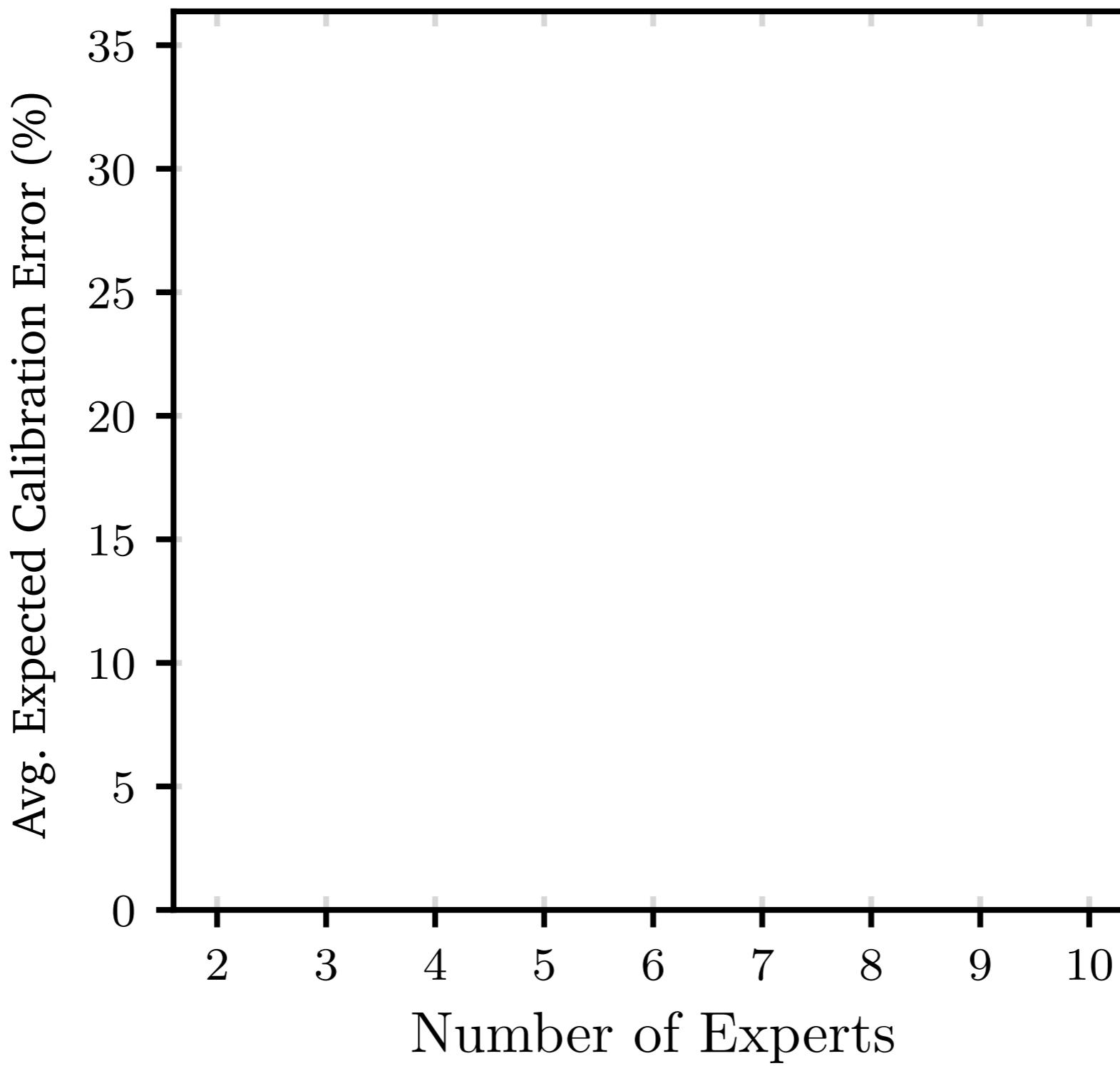
skin lesion diagnosis



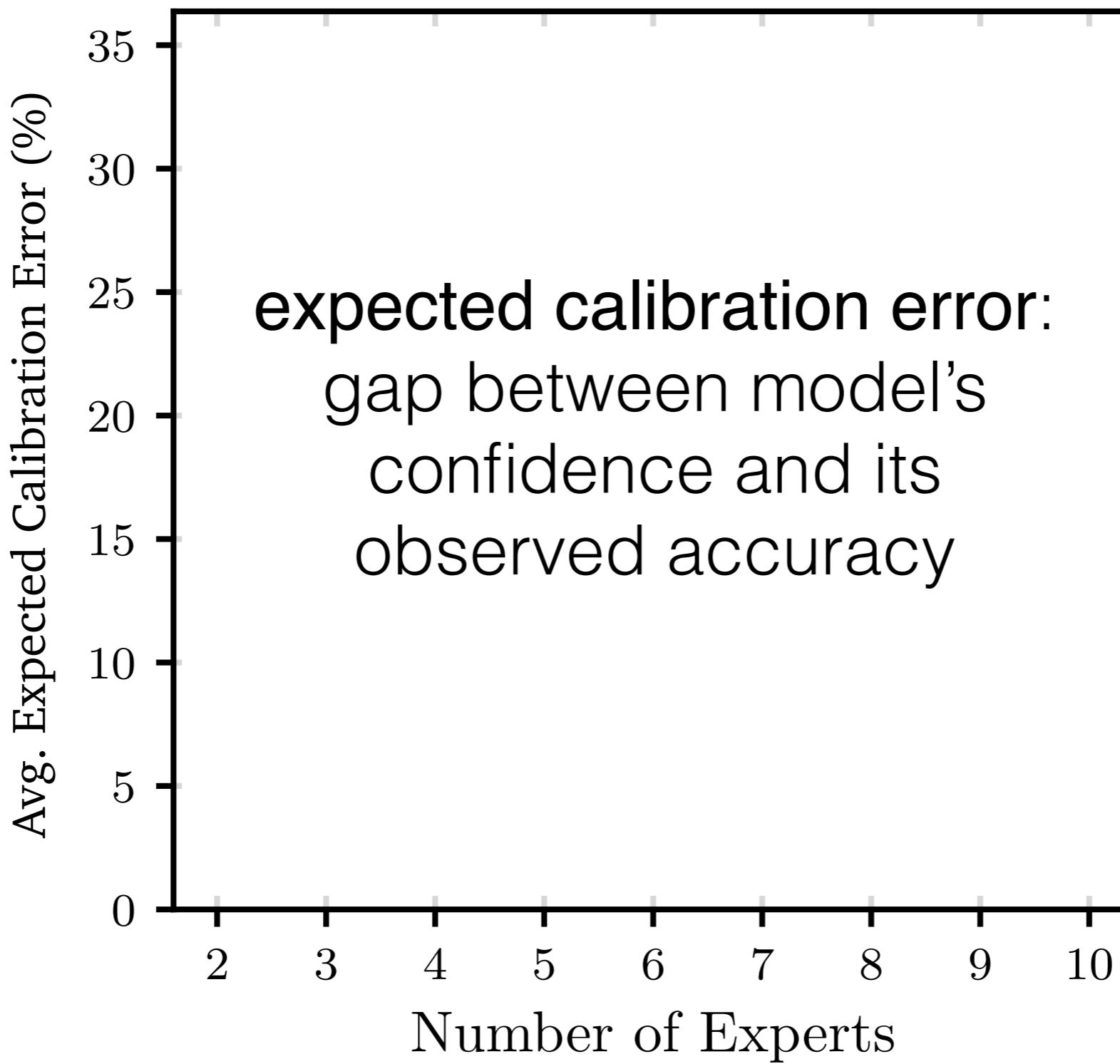
skin lesion diagnosis



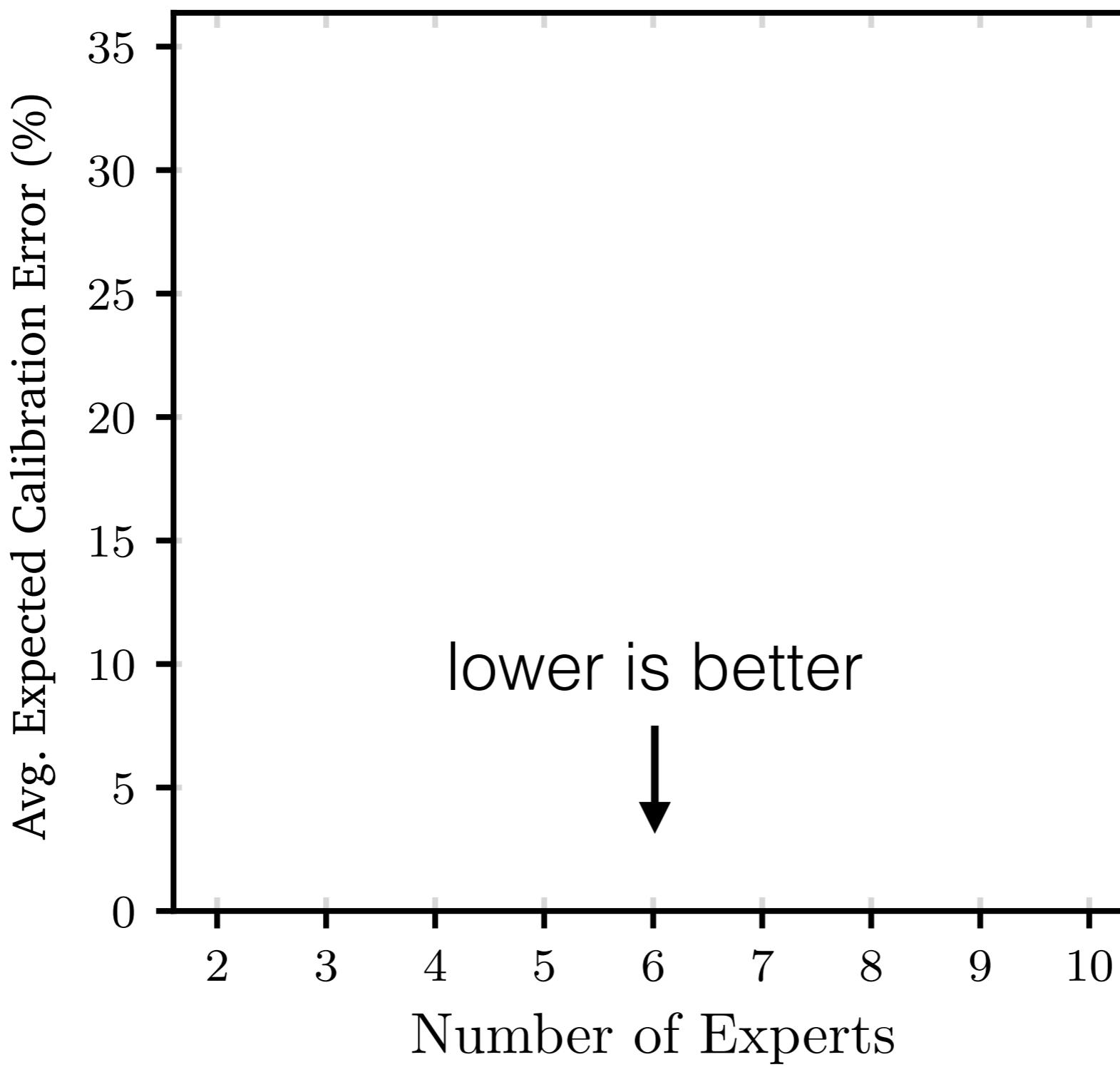
skin lesion diagnosis



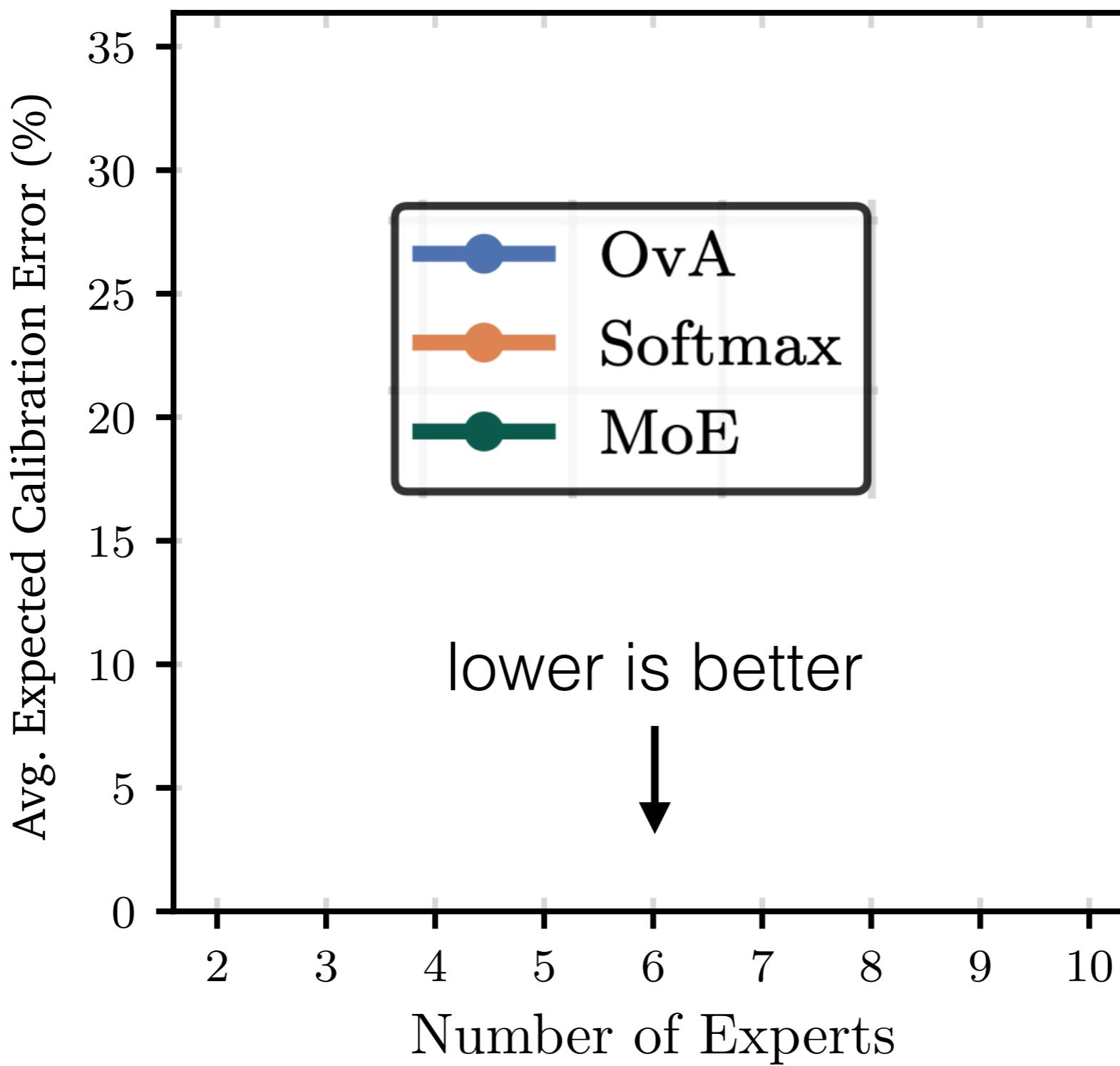
skin lesion diagnosis



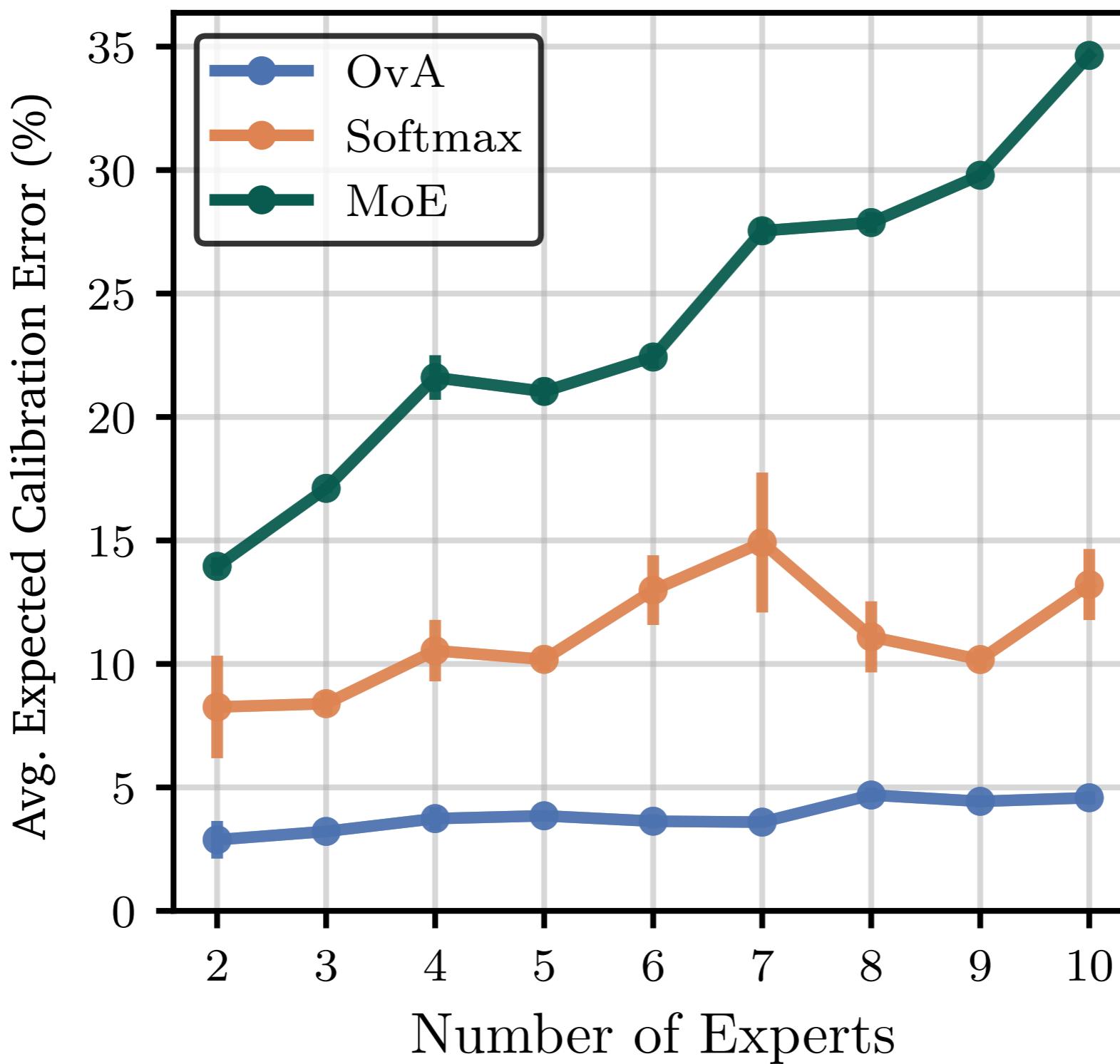
skin lesion diagnosis



skin lesion diagnosis



skin lesion diagnosis



- ⊗ single expert
 - ⊗ softmax surrogate loss
 - ⊗ improving calibration via one-vs-all
- ⊗ multiple experts
 - ⊗ surrogate losses
 - ⊗ conformal sets of experts
- ⊗ population of experts
 - ⊗ surrogate losses
 - ⊗ meta-learning a rejector

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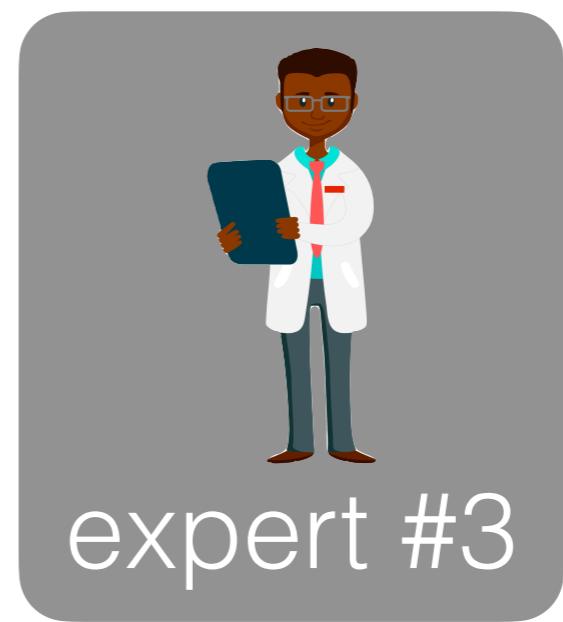
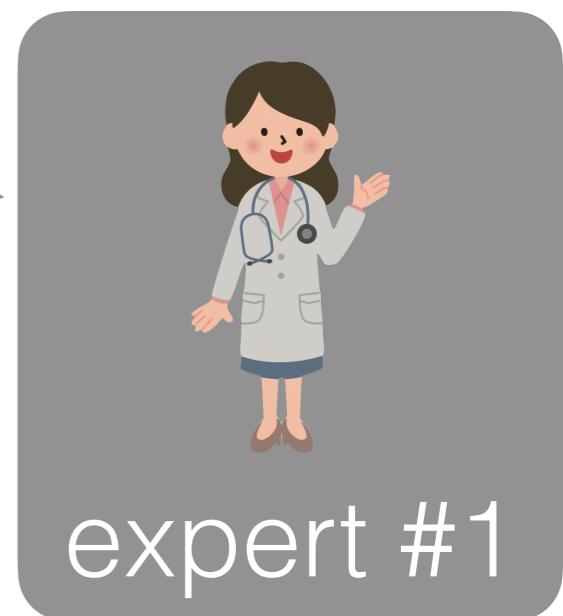
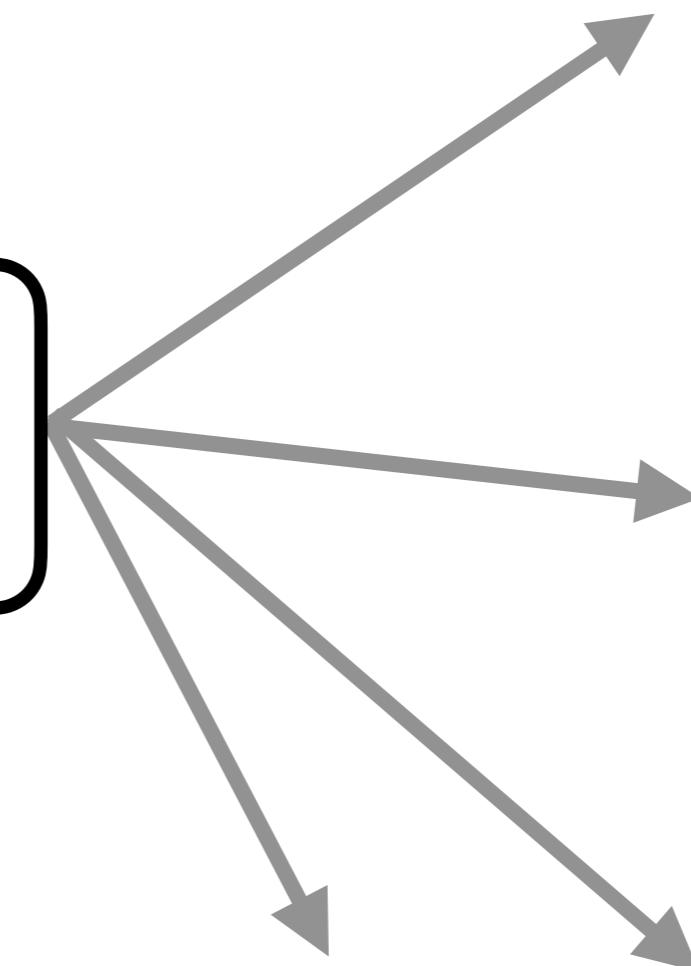
- ⊗ multiple experts
 - ⊗ surrogate losses
 - ⊗ conformal sets of experts

- ⊗ population of experts
 - ⊗ surrogate losses
 - ⊗ meta-learning a rejector

input
features



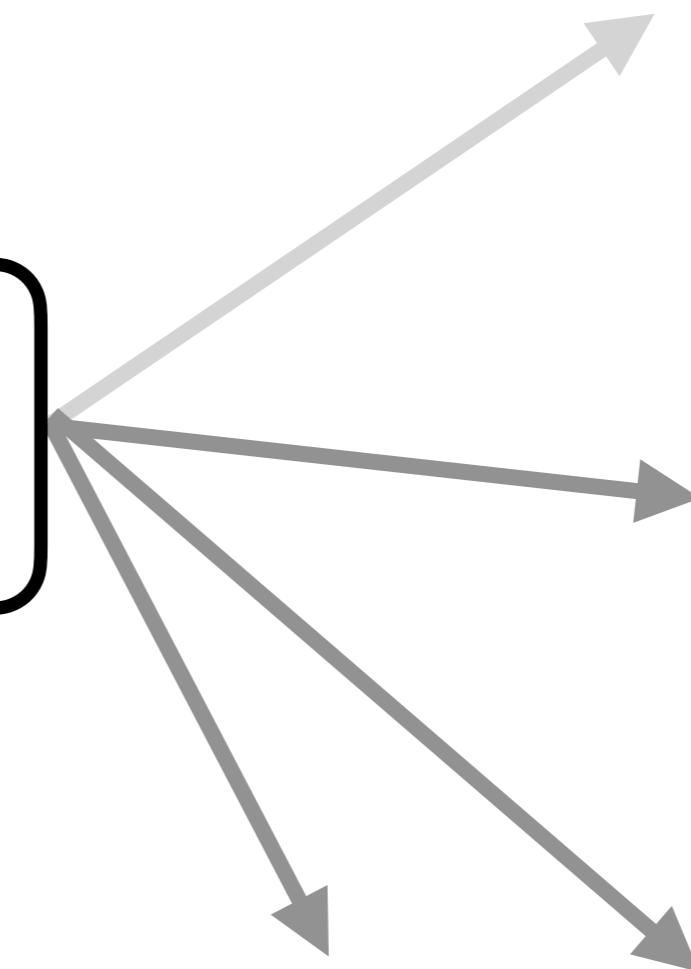
allocation
mechanism



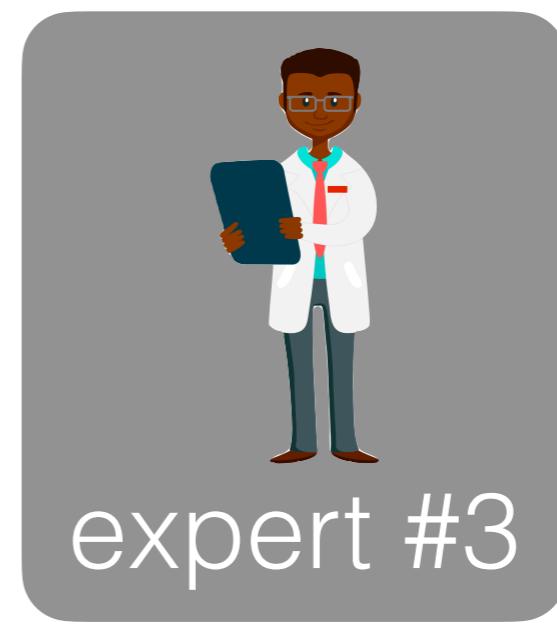
input
features



allocation
mechanism



expert #3



expert #2



expert #1



input
features



allocation
mechanism



input
features



allocation
mechanism

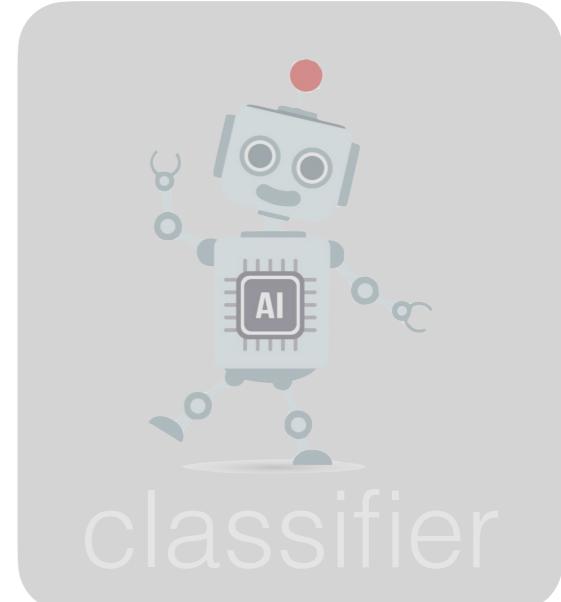
expert #3



expert #2



expert #1



conformal inference

conformal inference

assume there's a best expert, j^* :

$$\mathbb{P}(m_{j^*} = y | x) > \mathbb{P}(m_e = y | x), \quad \forall e \neq j^*$$

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construct a confidence set of experts:

$$\mathbb{P}(j^* \in C(x)) \geq 1 - \alpha$$

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construct a confidence set of experts:

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team of experts: adaptive in size and membership

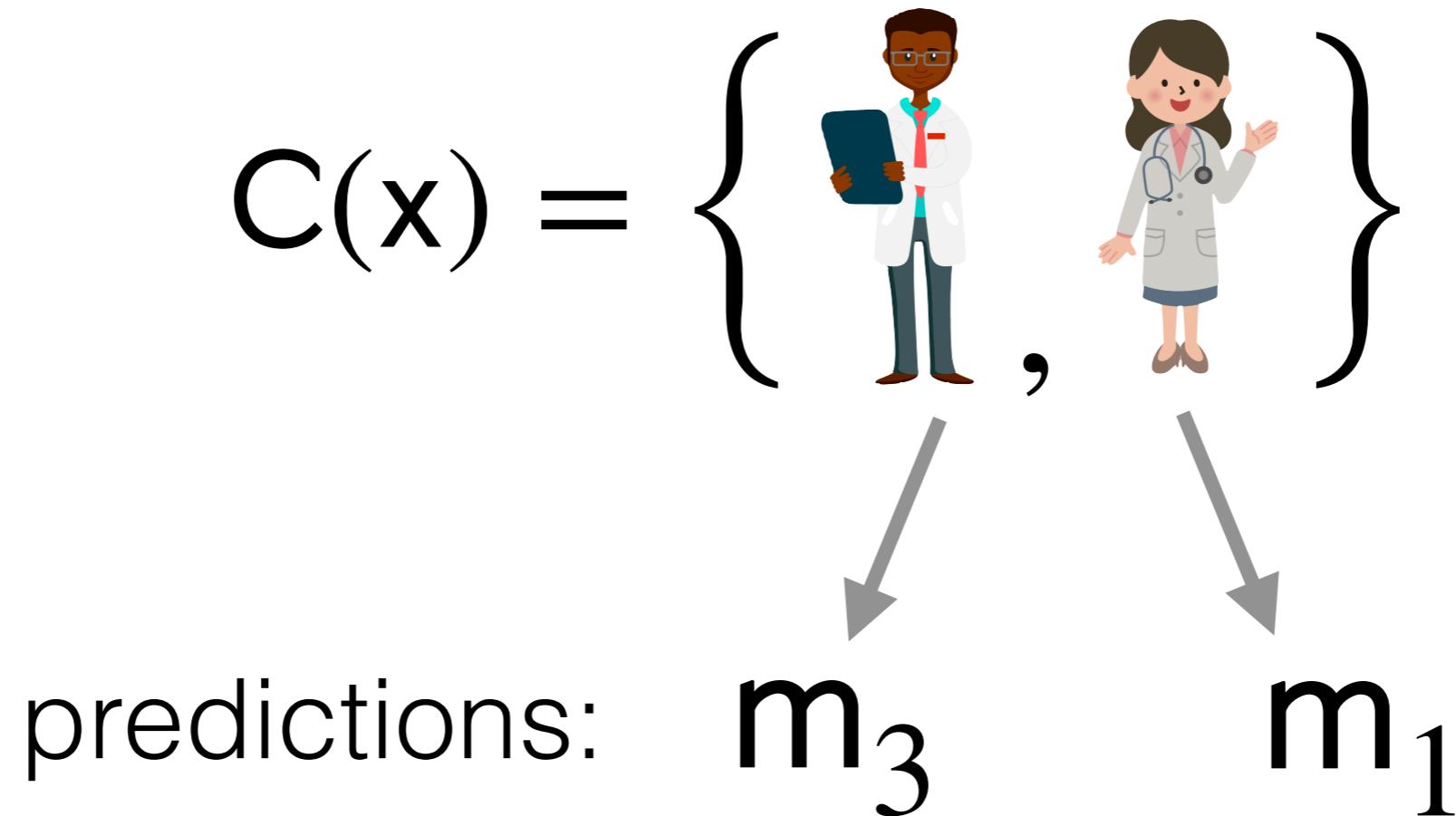
conformal inference: ensembling

$$C(x) = \left\{ \begin{array}{c} \text{Illustration of a Black male doctor holding a clipboard, and a white female doctor with a stethoscope.} \\ , \end{array} \right\}$$

conformal inference: ensembling

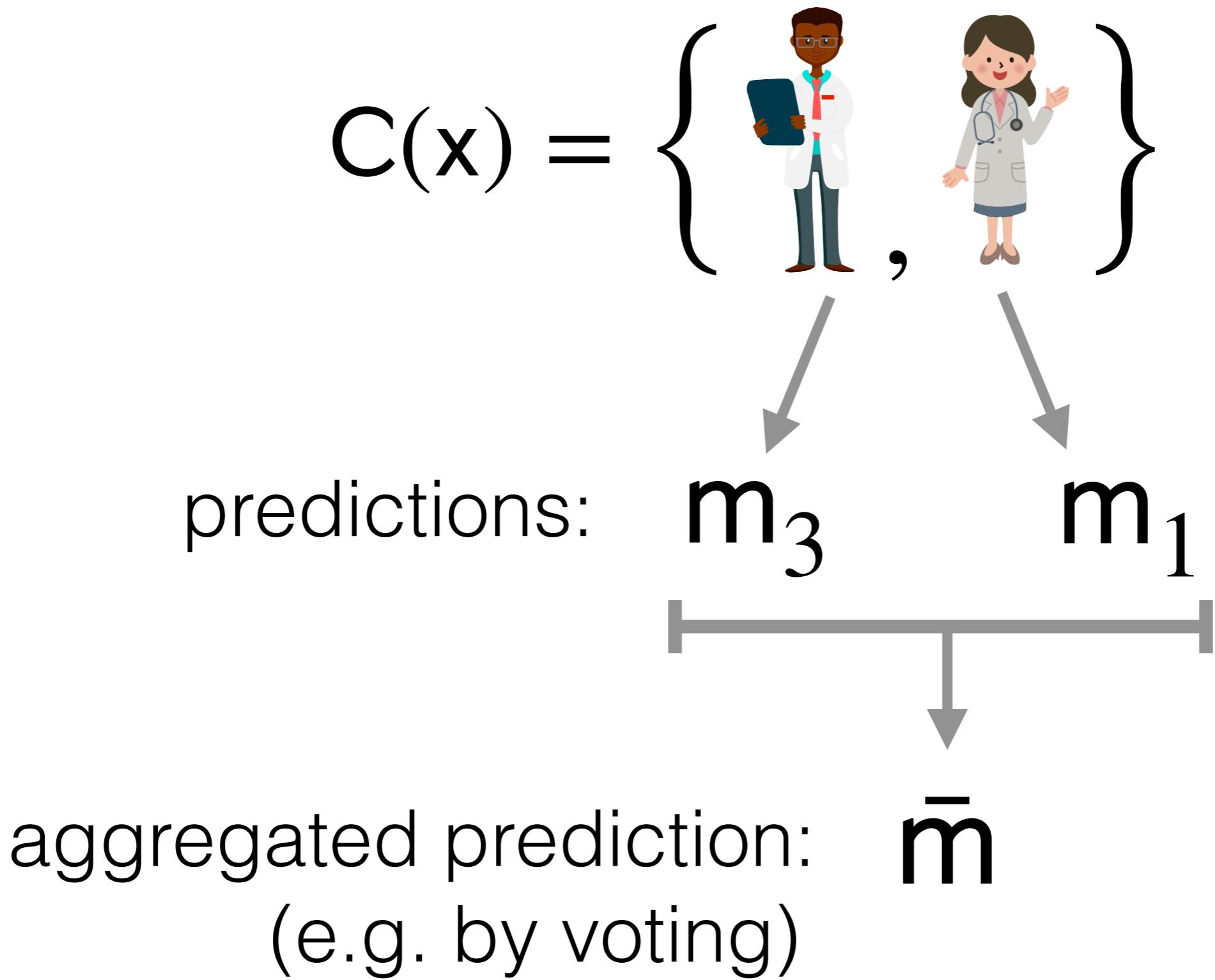
$$C(x) = \left\{ \begin{array}{c} \text{doctor 1} \\ , \\ \text{doctor 2} \end{array} \right\}$$

predictions: m_3 m_1



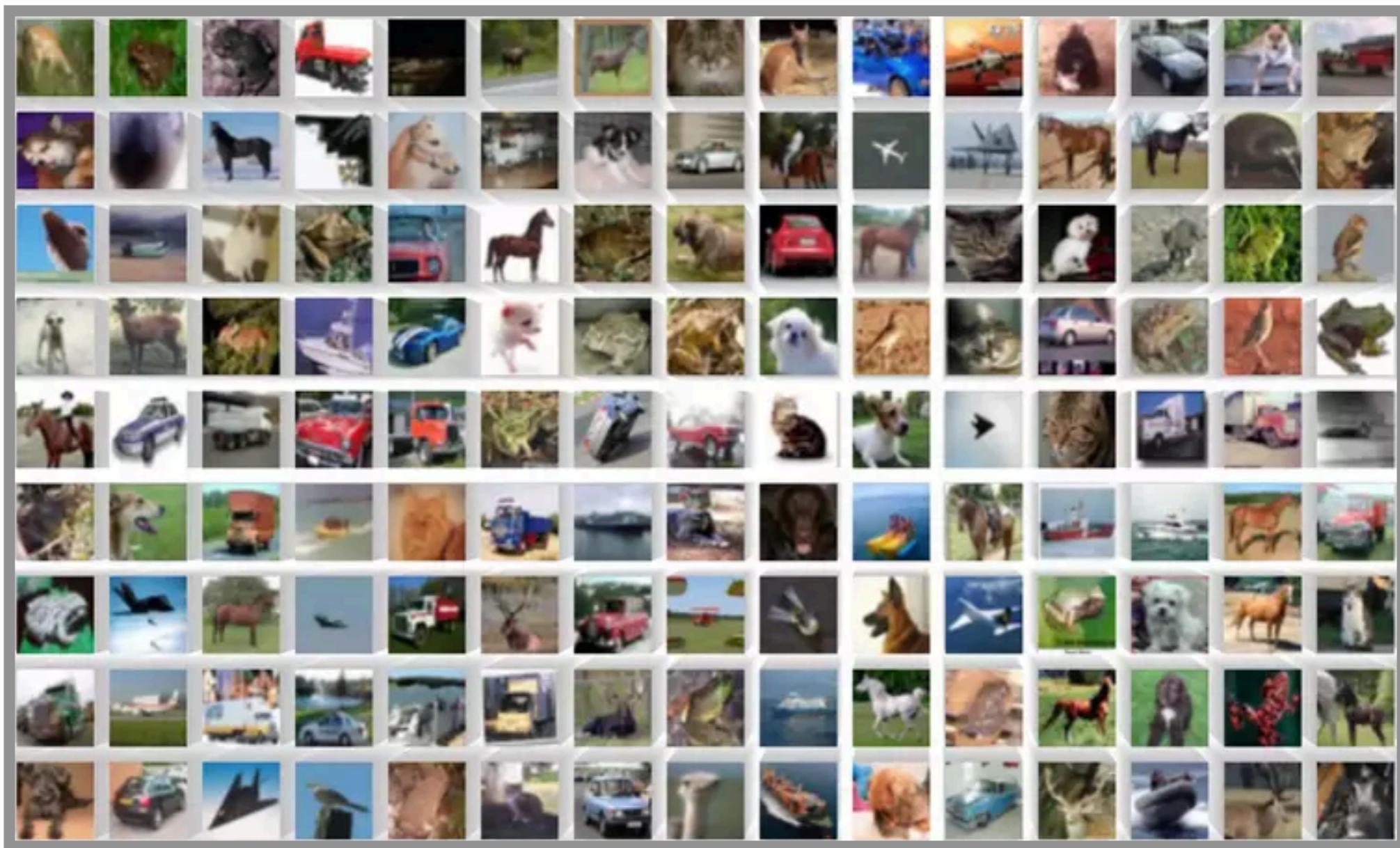
The diagram illustrates the concept of conformal inference ensembling. It shows a set $C(x)$ containing two doctors. Arrows point from each doctor to their respective predictions m_3 and m_1 .

conformal inference: ensembling

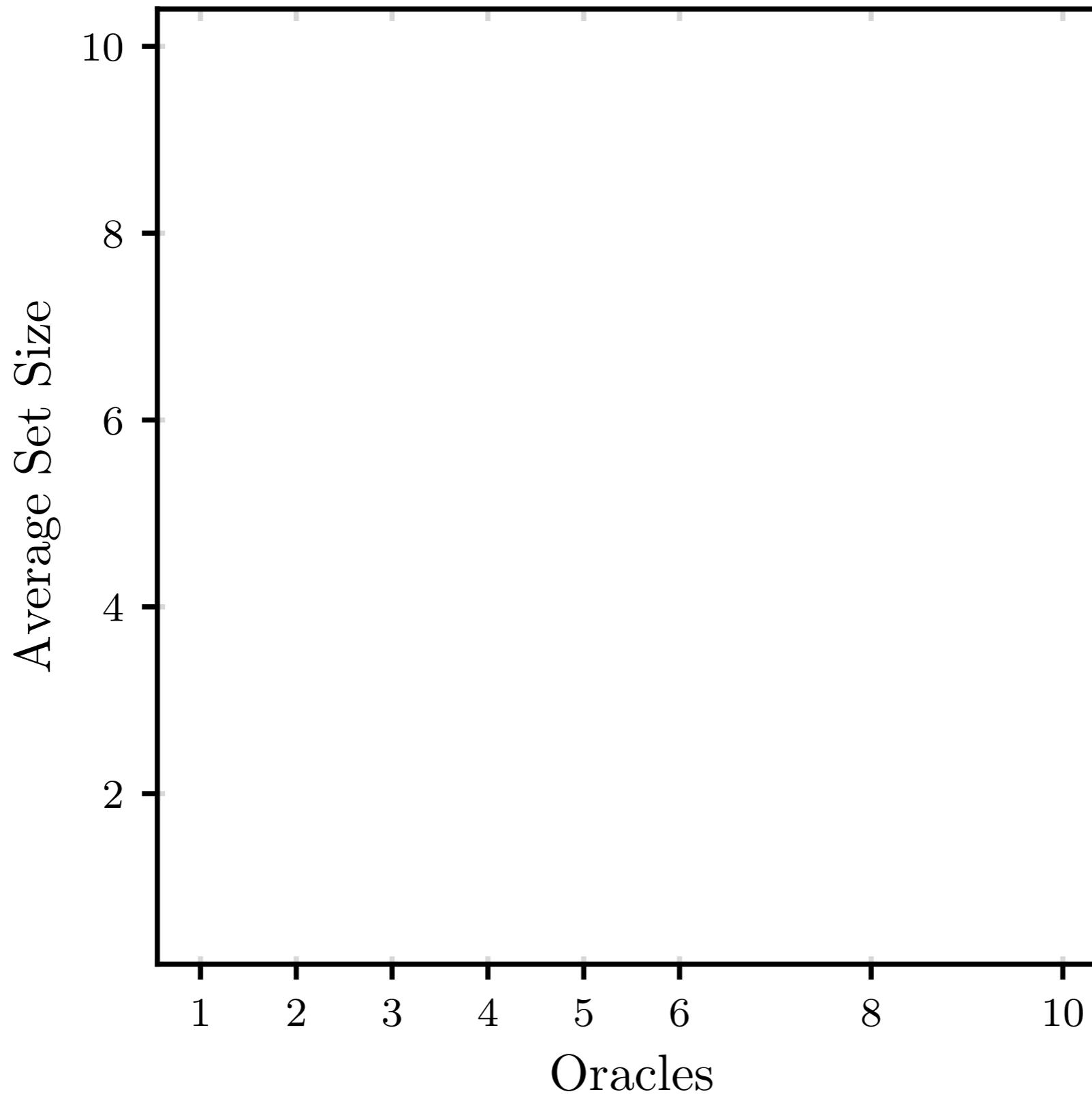


expert selection

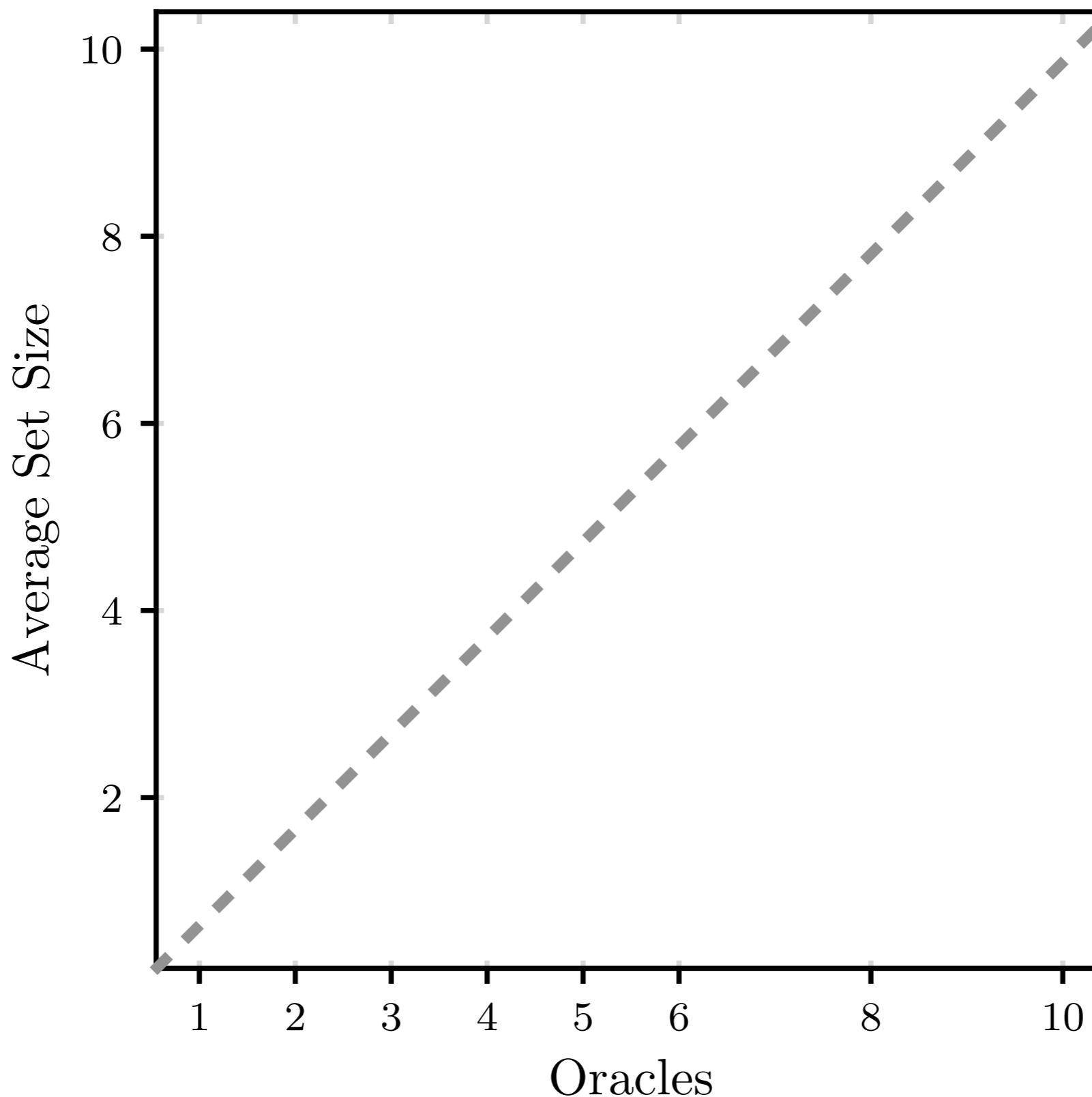
CIFAR-10



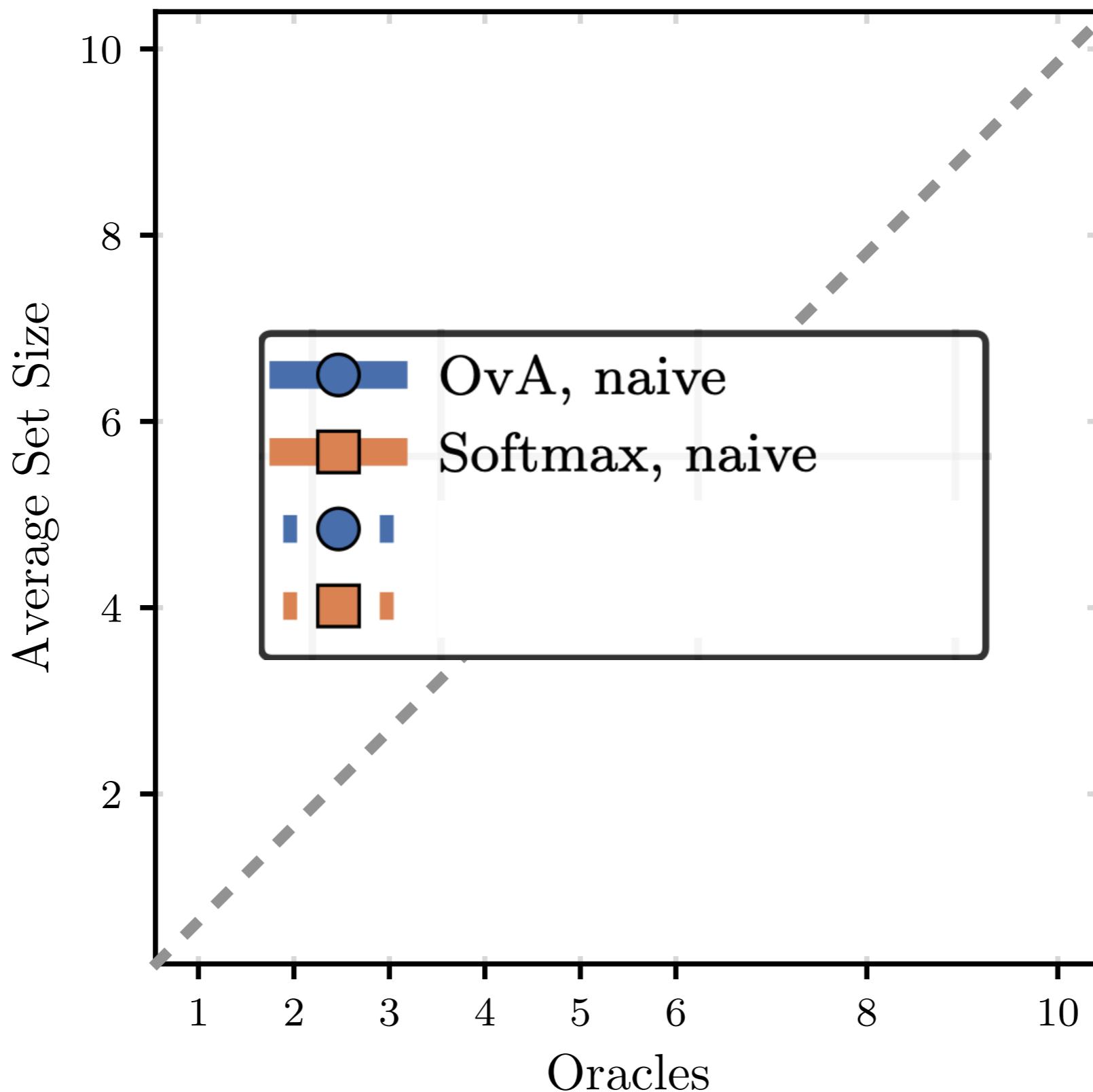
expert selection



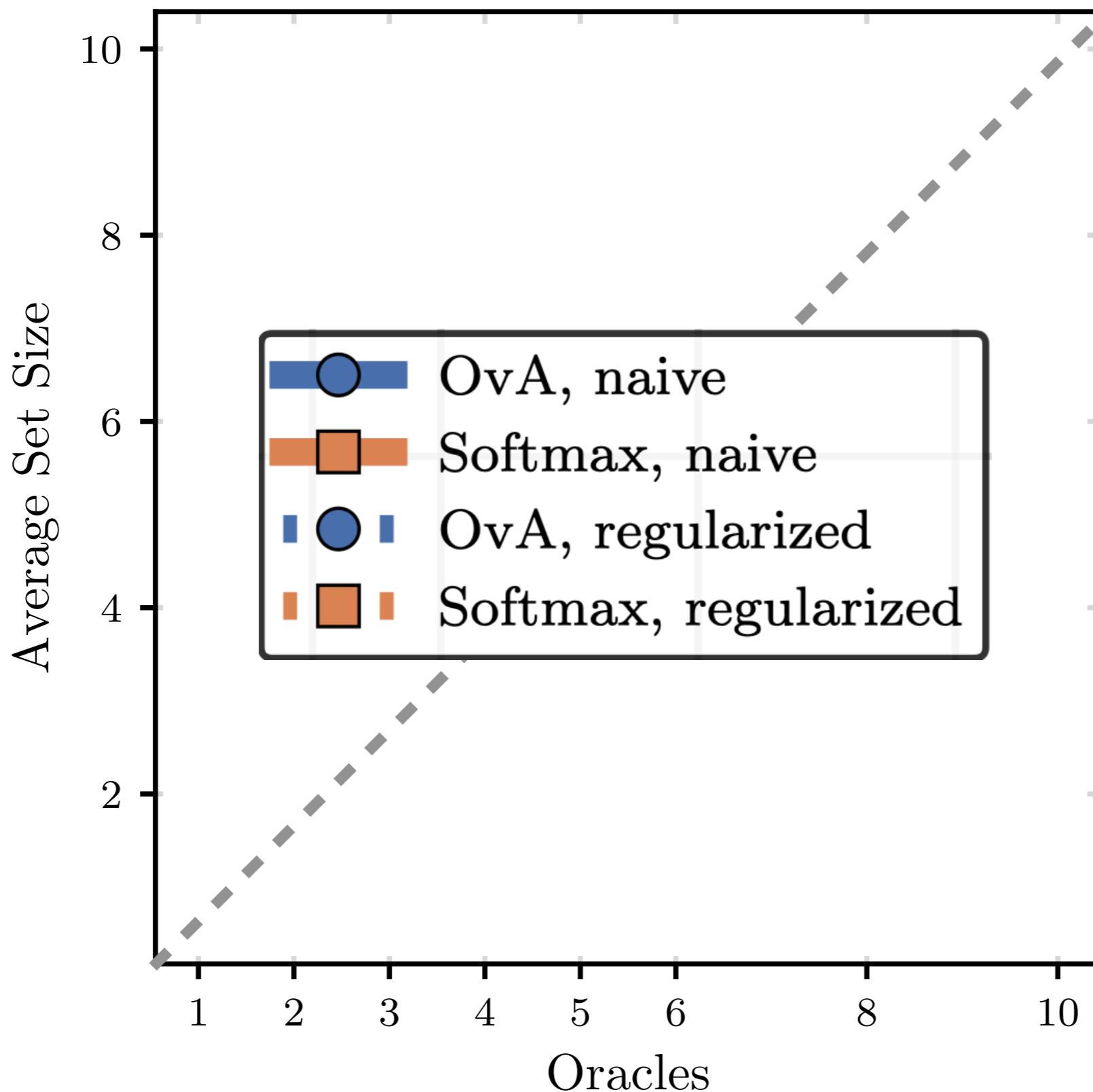
expert selection



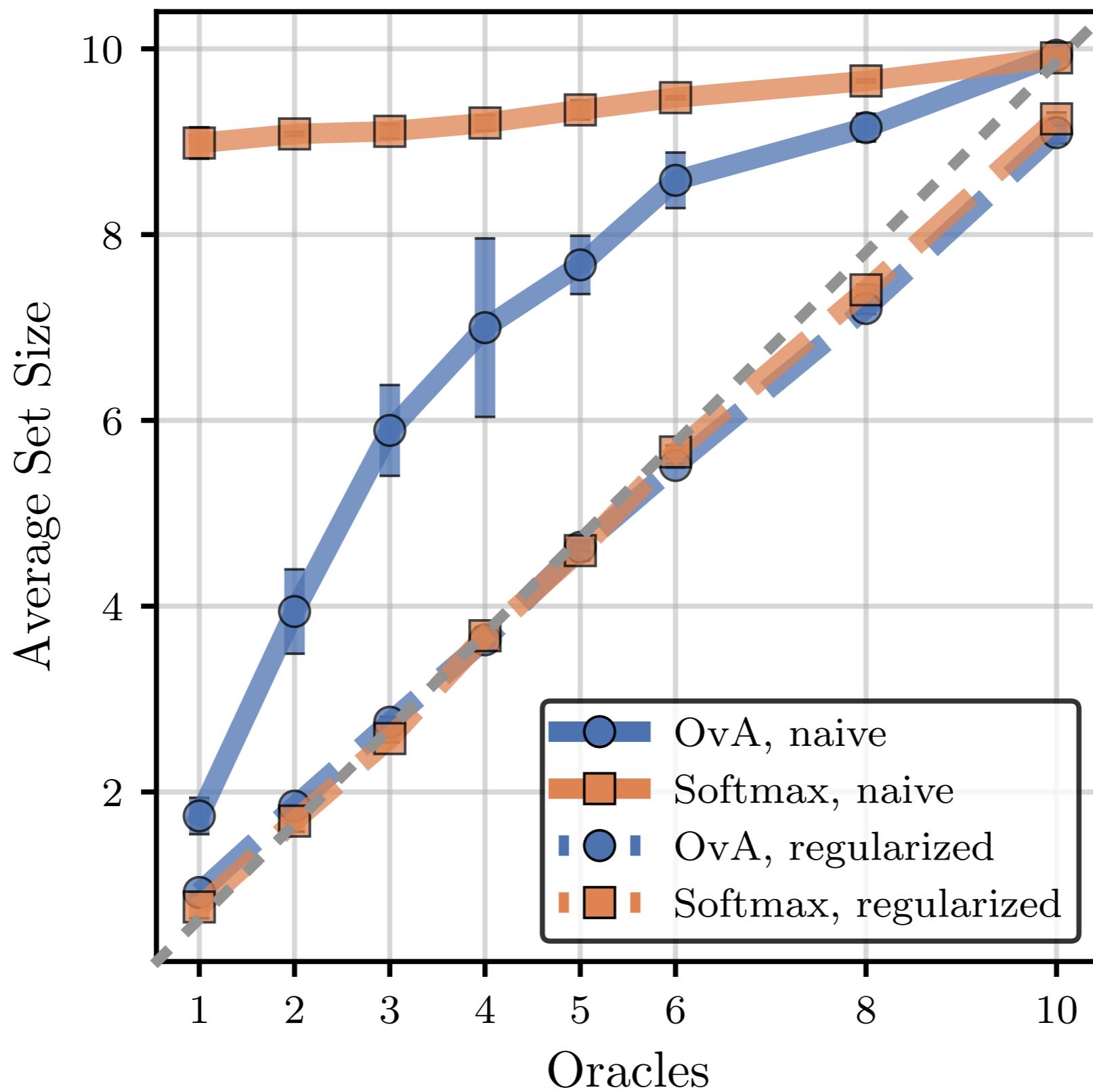
expert selection



expert selection



expert selection



- ⊗ single expert
 - ⊗ softmax surrogate loss
 - ⊗ improving calibration via one-vs-all

- ⊗ multiple experts
 - ⊗ surrogate losses
 - ⊗ conformal sets of experts

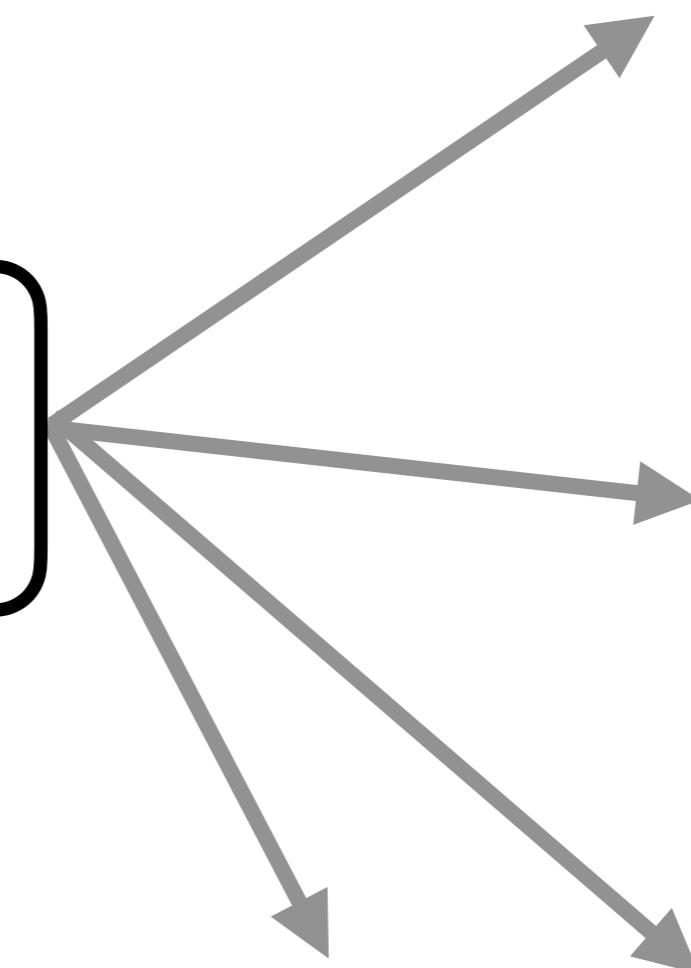
- ⊗ population of experts
 - ⊗ surrogate losses
 - ⊗ meta-learning a rejector

- ⊗ single expert
 - ⊗ softmax surrogate loss
 - ⊗ improving calibration via one-vs-all
- ⊗ multiple experts
 - ⊗ surrogate losses
 - ⊗ conformal sets of experts
- ⊗ population of experts
 - ⊗ surrogate losses
 - ⊗ meta-learning a rejector

input
features



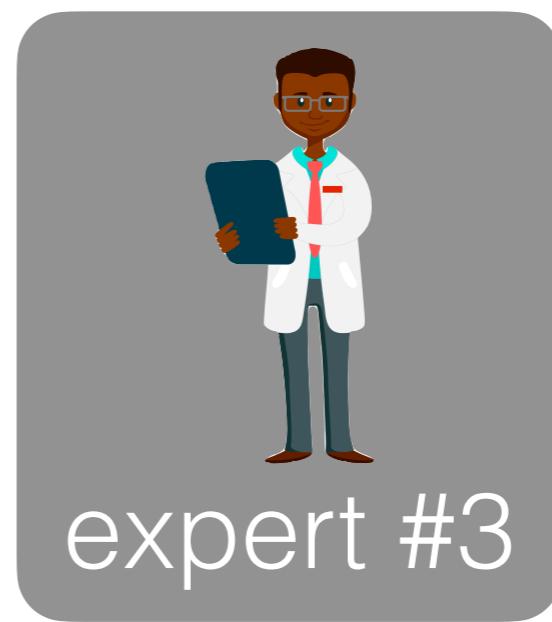
allocation
mechanism



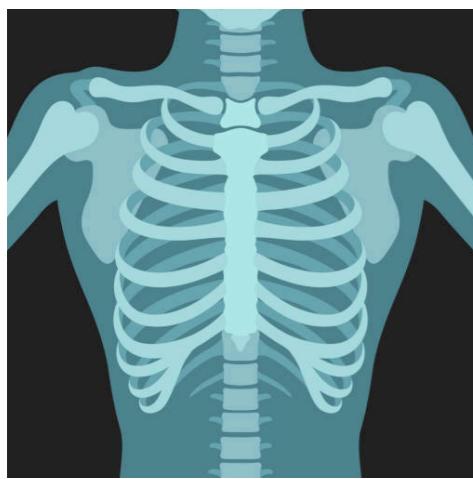
classifier



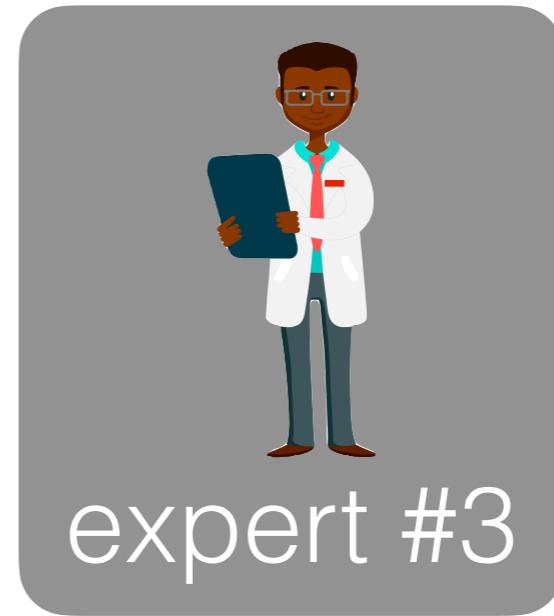
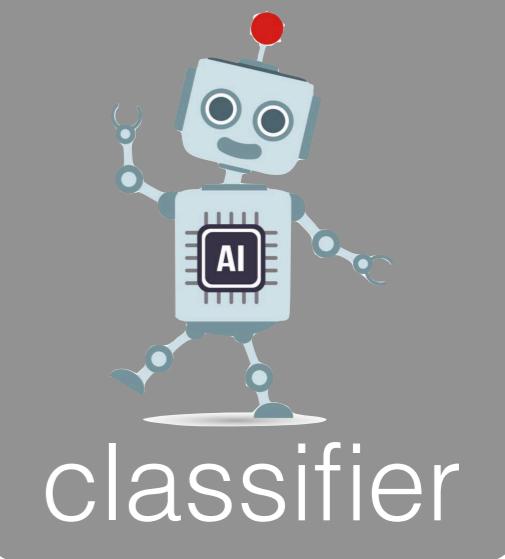
expert #1



input
features



allocation
mechanism

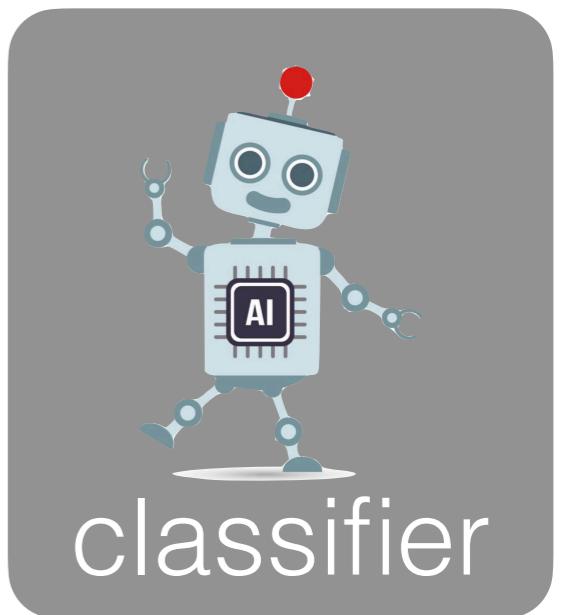


limitations?

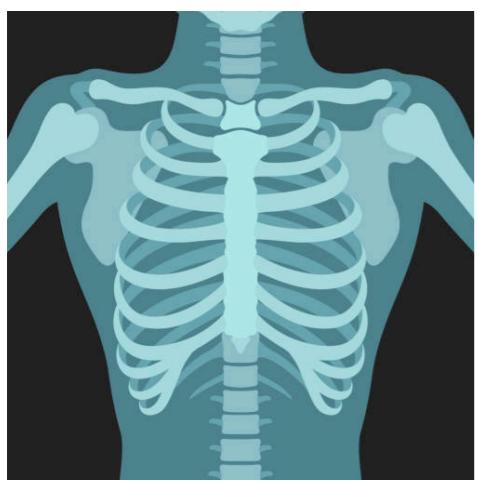
input
features



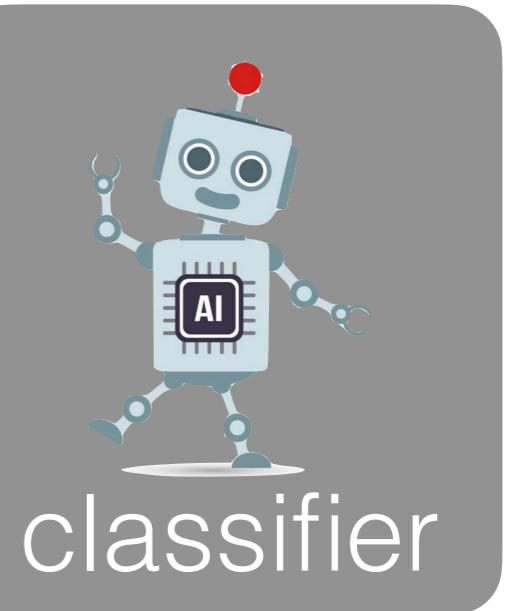
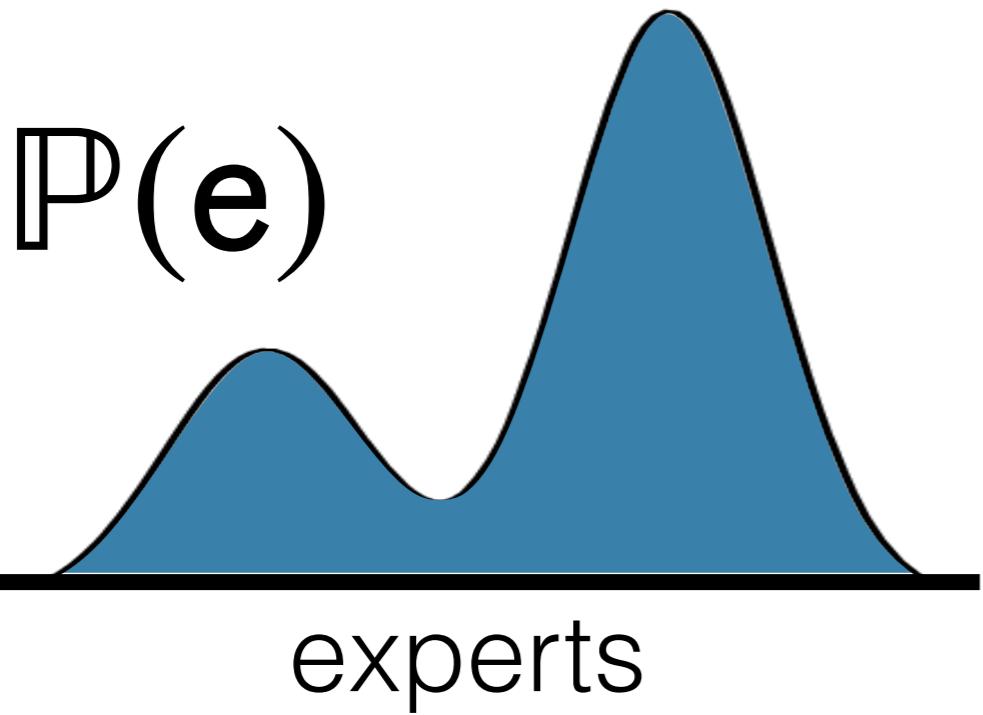
allocation
mechanism



input
features



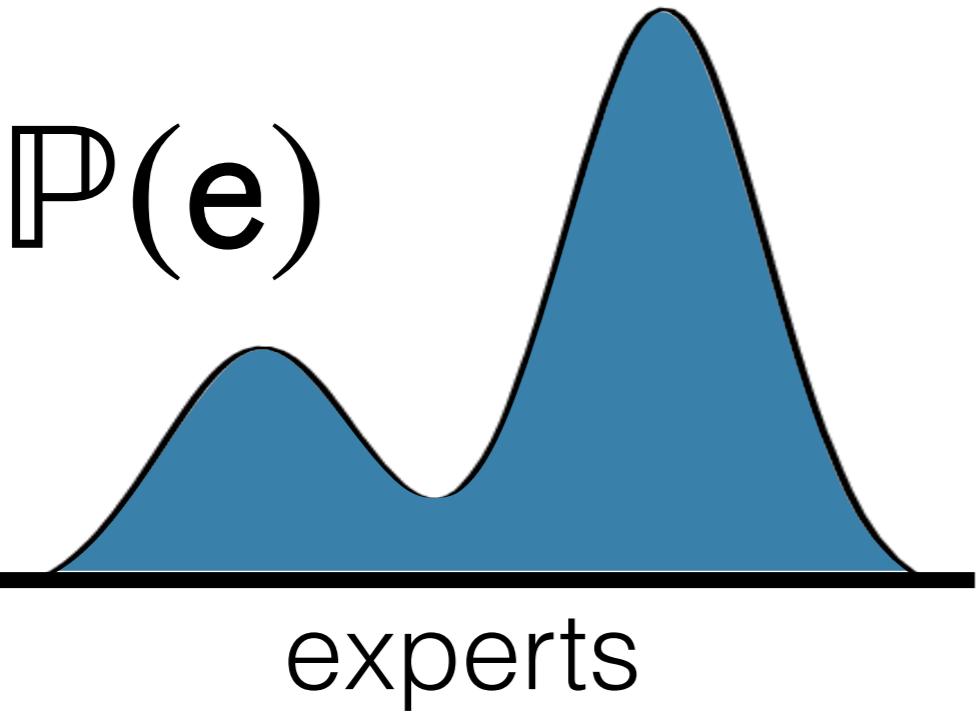
allocation
mechanism



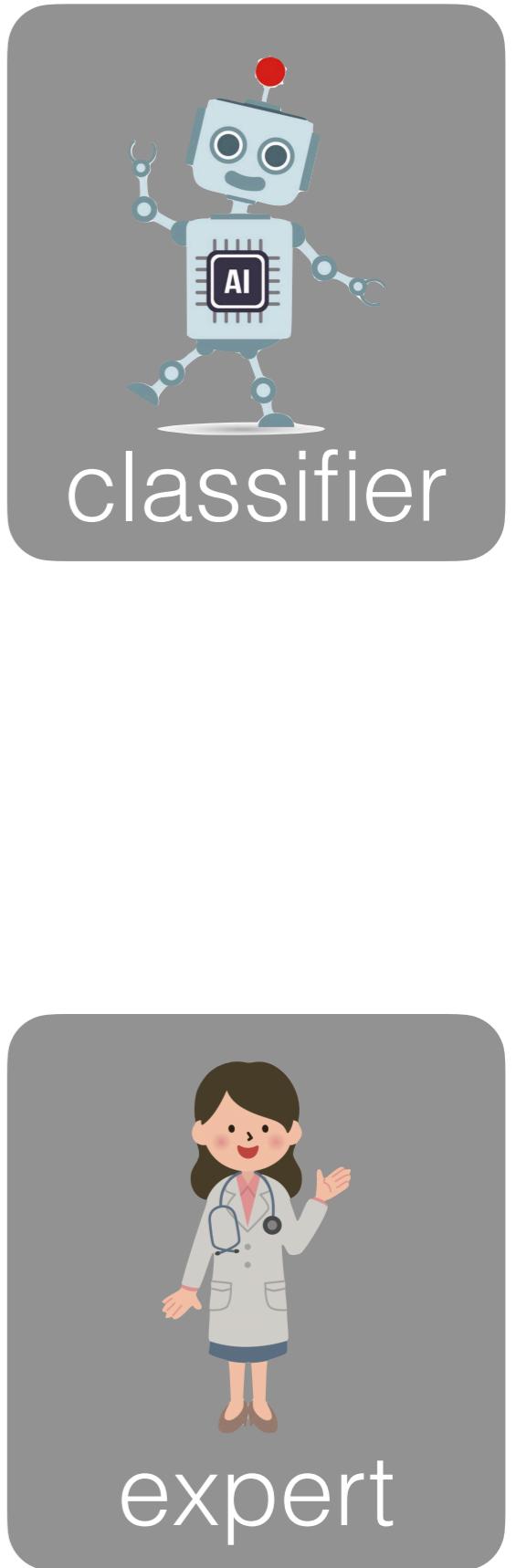
input
features



allocation
mechanism



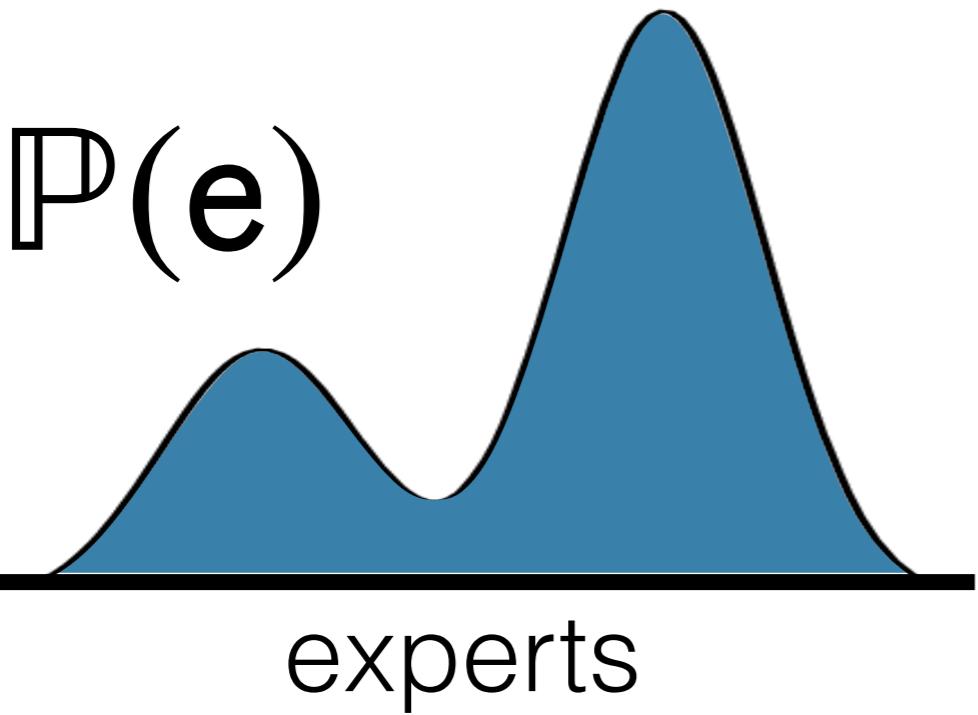
$e \sim P(e)$



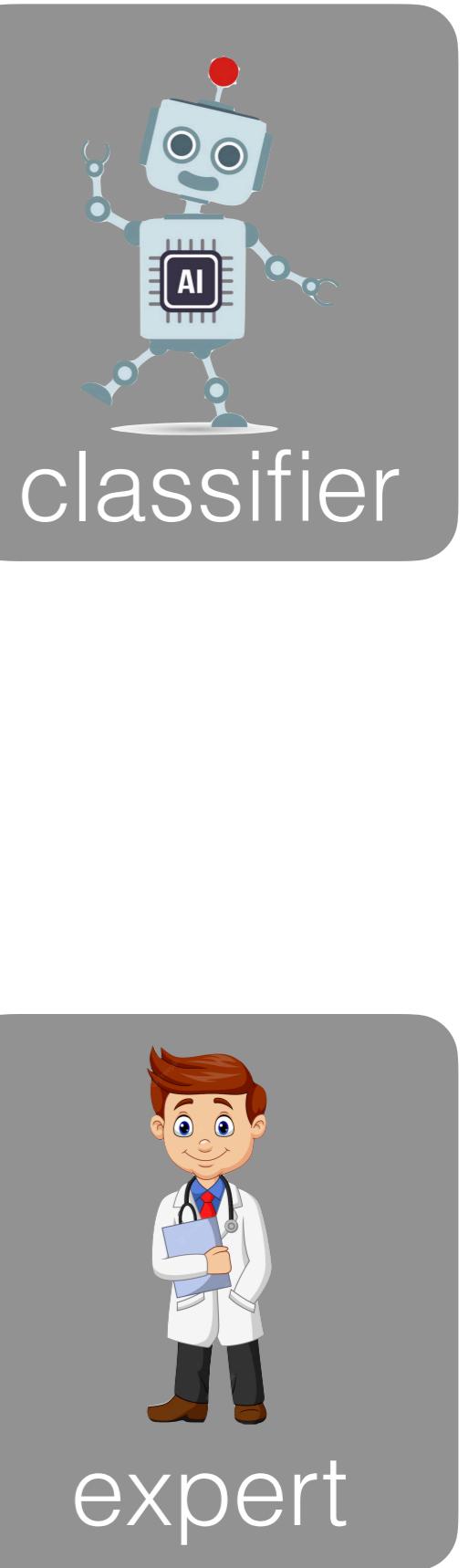
input
features



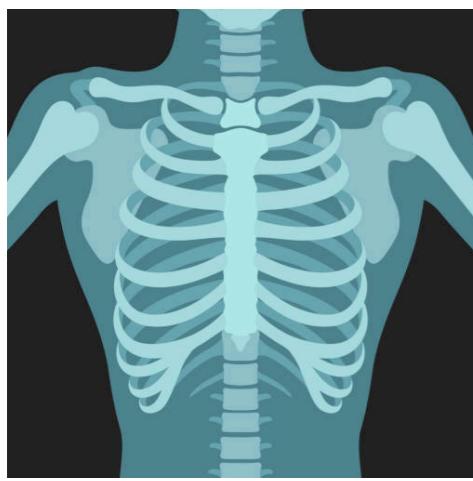
allocation
mechanism



$$e \sim P(e)$$



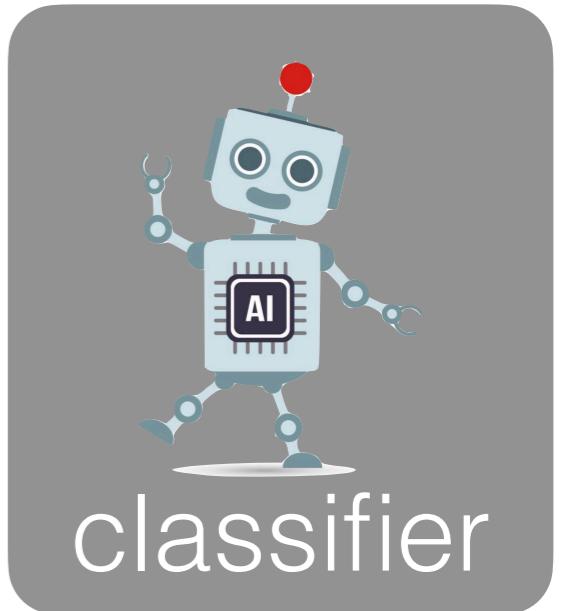
input
features



allocation
mechanism

$$e \sim P(e)$$

$$m \sim P(m | e)$$



input
features



allocation
mechanism

L_{0-1}

classifier

L_{0-1}

?

expert

Bayes optimal deferral rule:

$$\max_y \mathbb{P}(y | x) \leq \mathbb{P}(m = y | x, e)$$

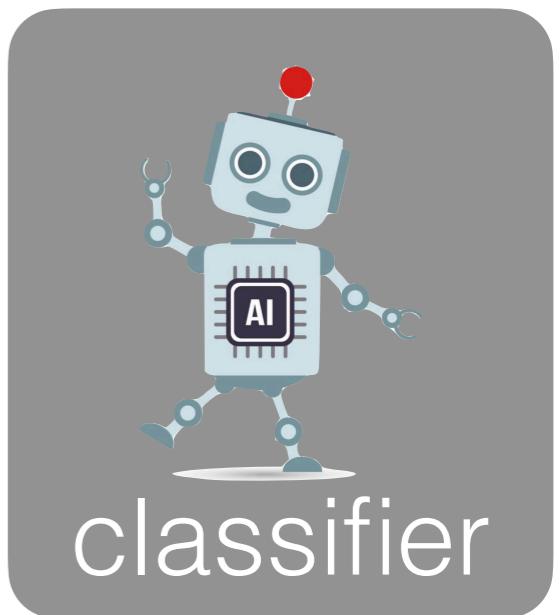
input
features



allocation
mechanism

defer to expert if...

$$\max_{y \in [1, K]} h_y(x) \leq h_\perp(x, e)$$



input
features

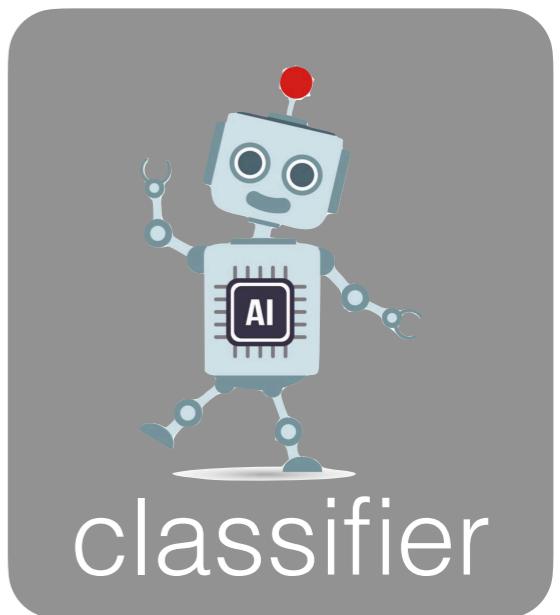


allocation
mechanism

defer to expert if...

$$\max_{y \in [1, K]} h_y(x) \leq h_\perp(x, e)$$

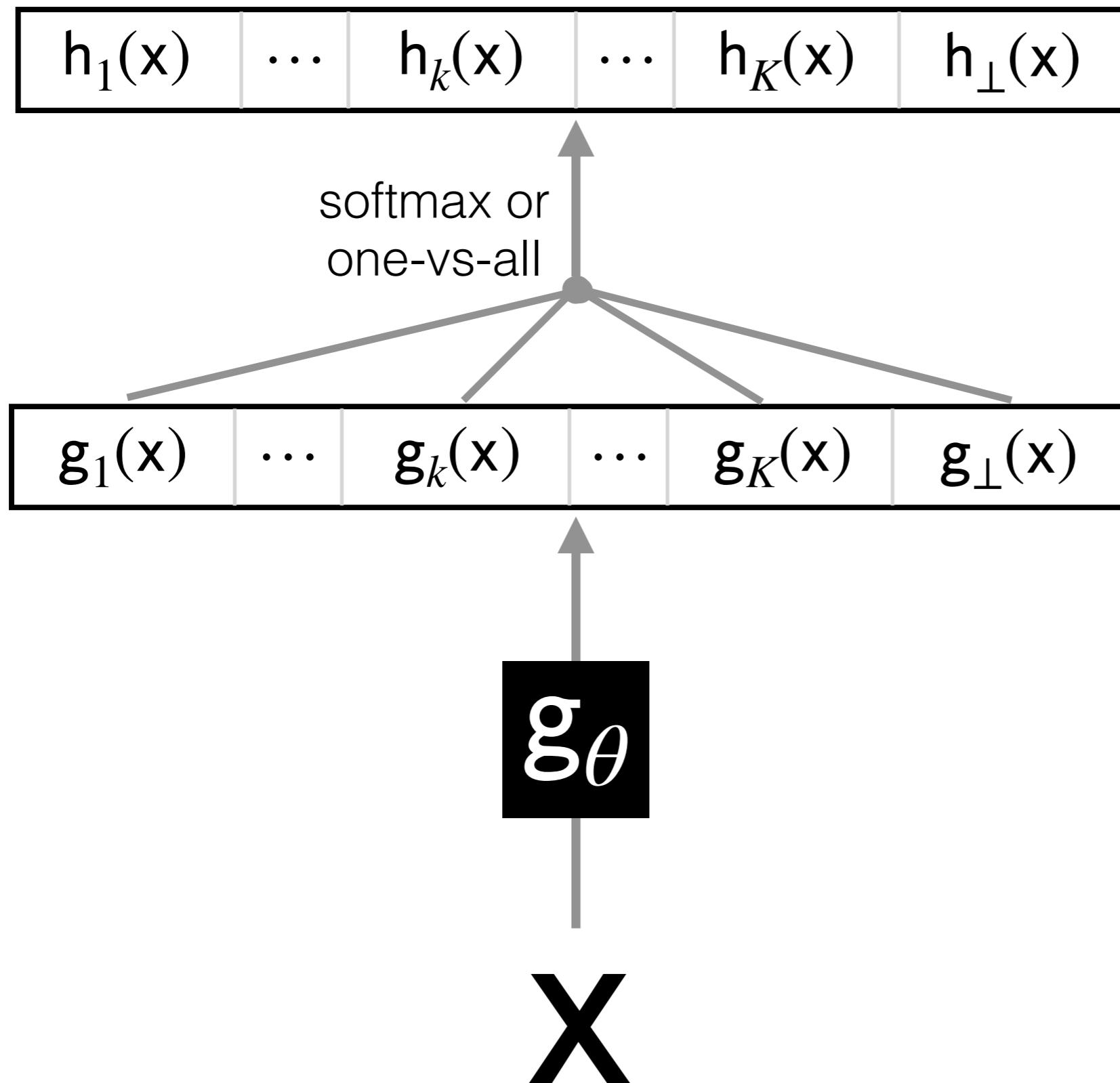
?



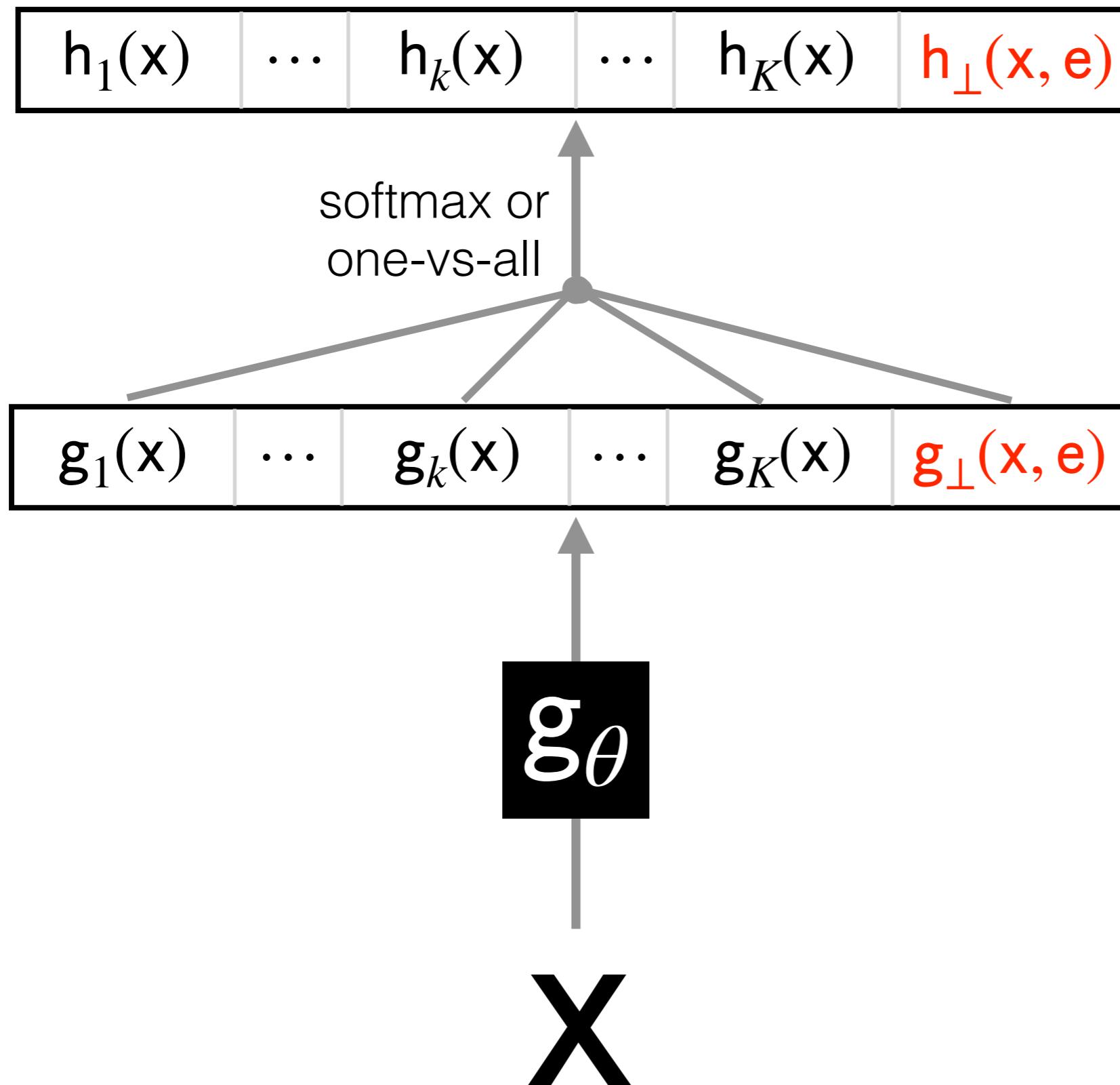
- ⊗ single expert
 - ⊗ softmax surrogate loss
 - ⊗ improving calibration via one-vs-all
- ⊗ multiple experts
 - ⊗ surrogate losses
 - ⊗ conformal sets of experts
- ⊗ population of experts
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 - ⊗ meta-learning a rejector

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 - ⊗ surrogate losses
 - ⊗ meta-learning a rejector

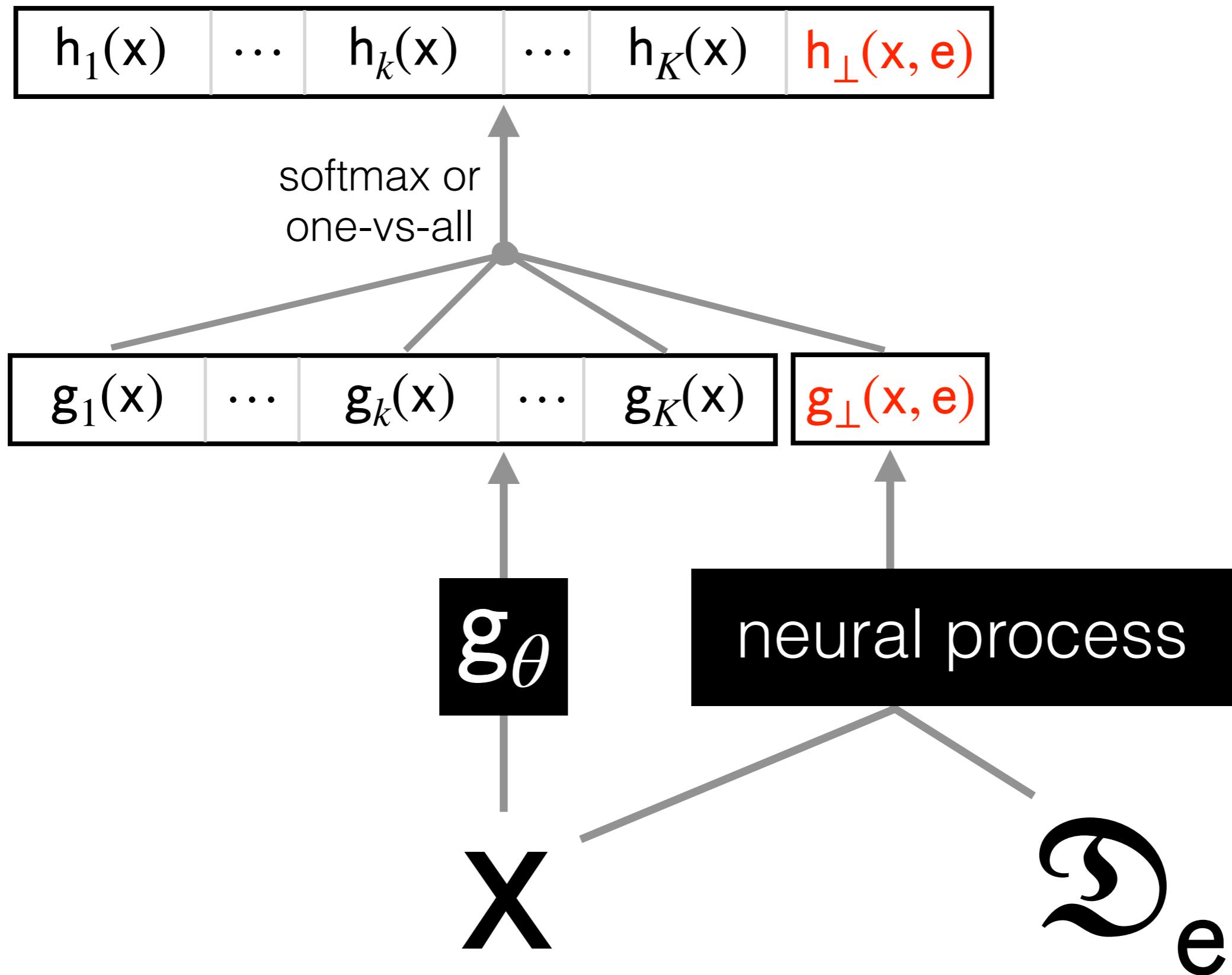
meta-learning implementation



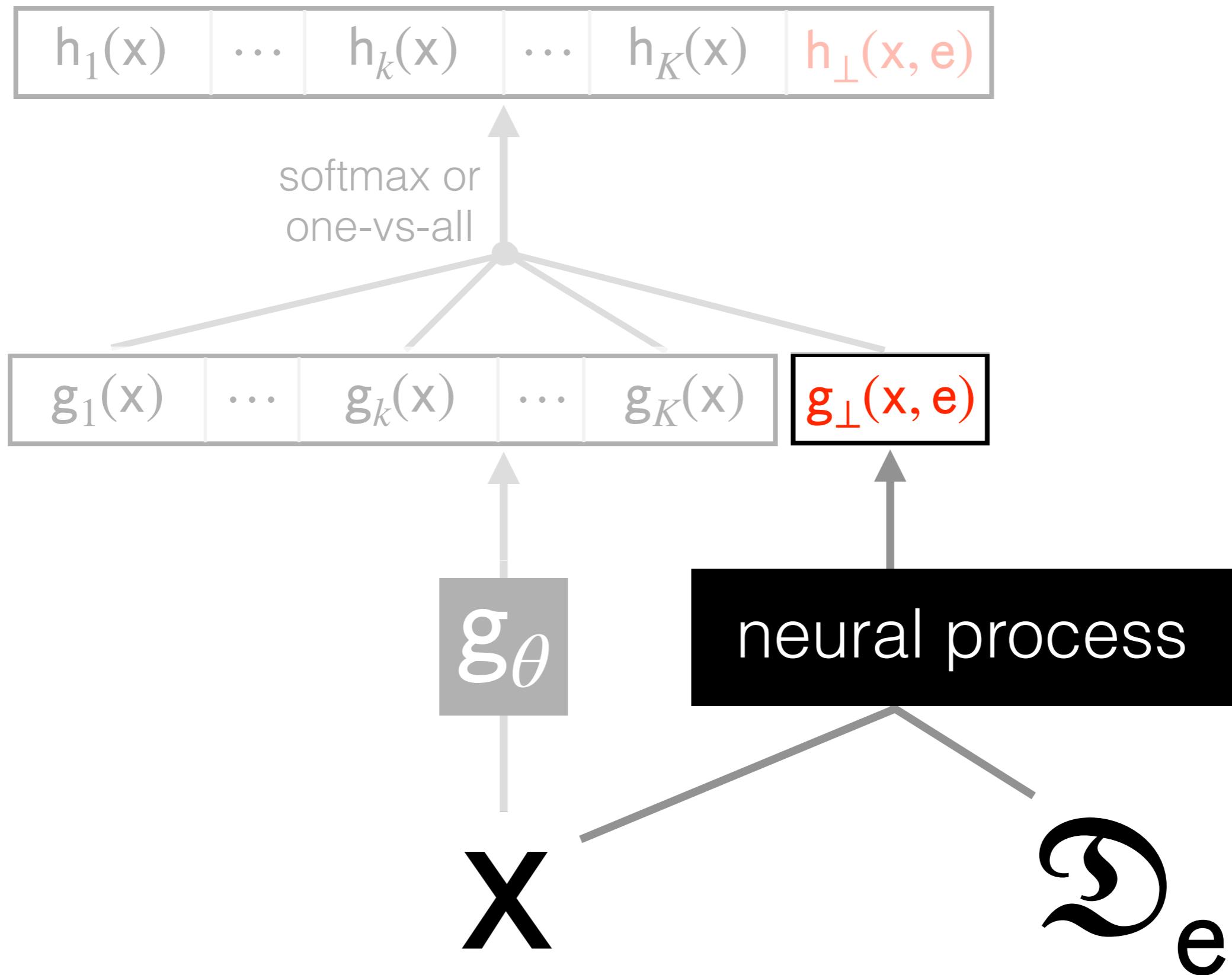
meta-learning implementation



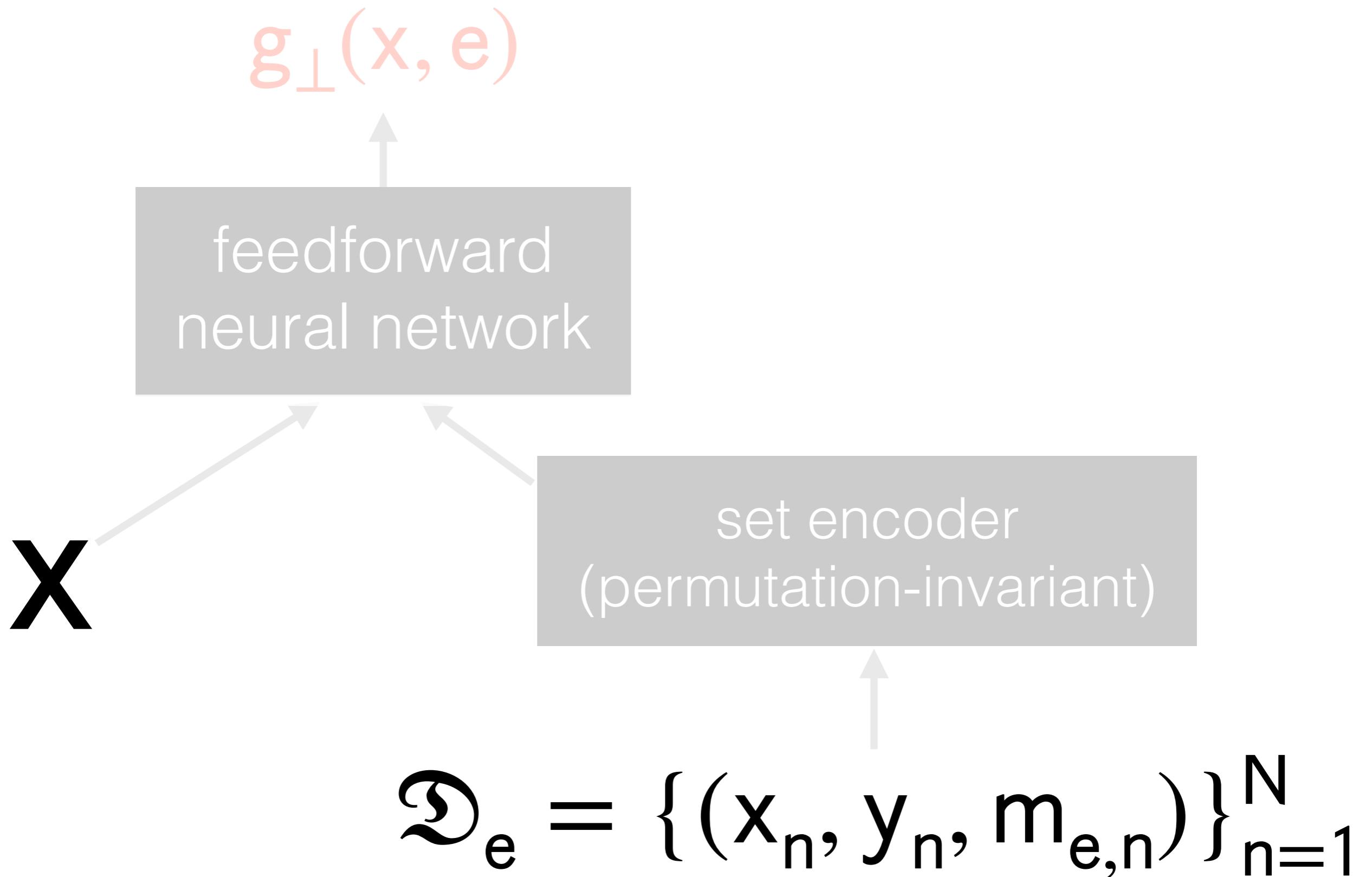
meta-learning implementation



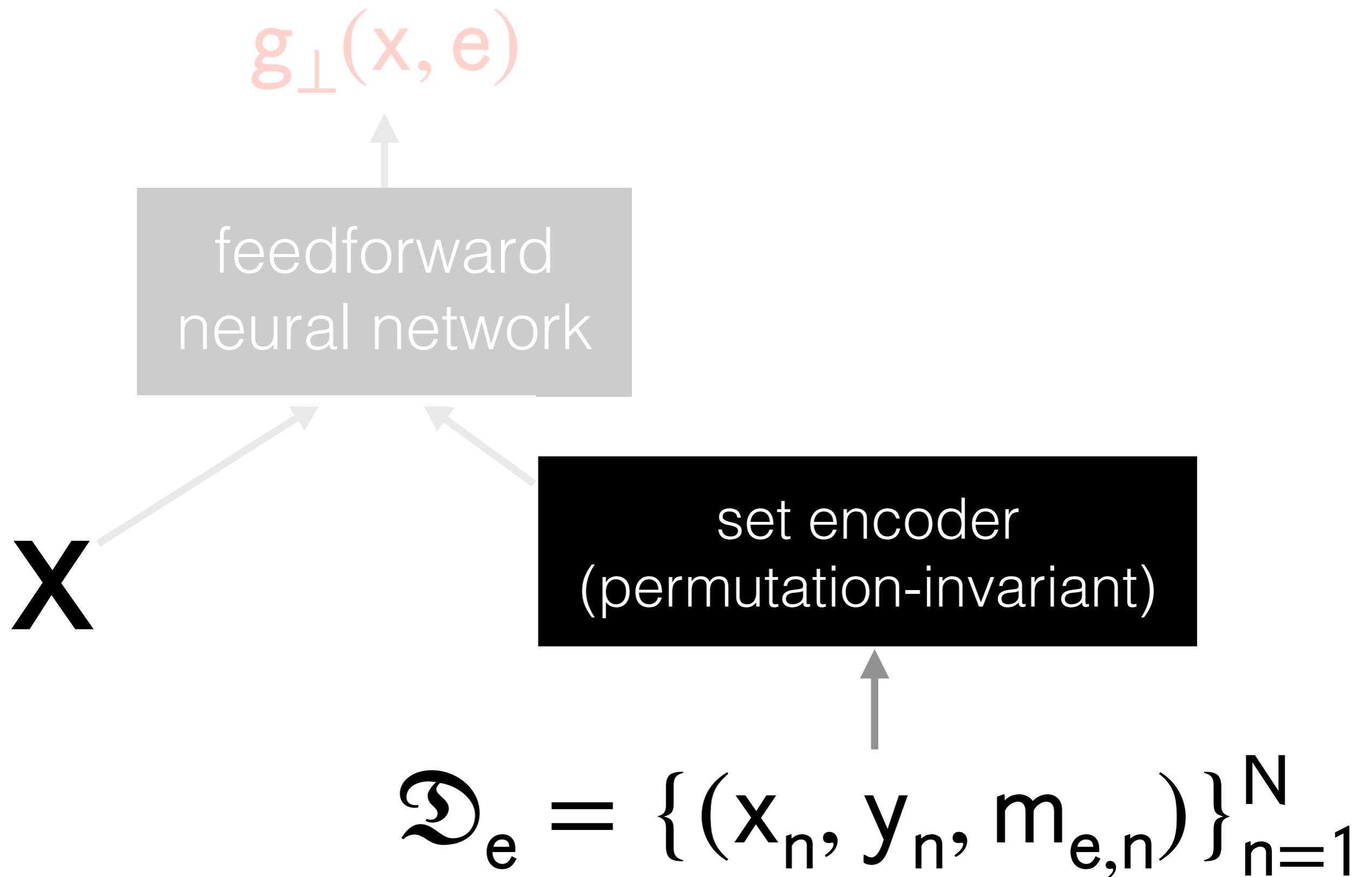
meta-learning implementation



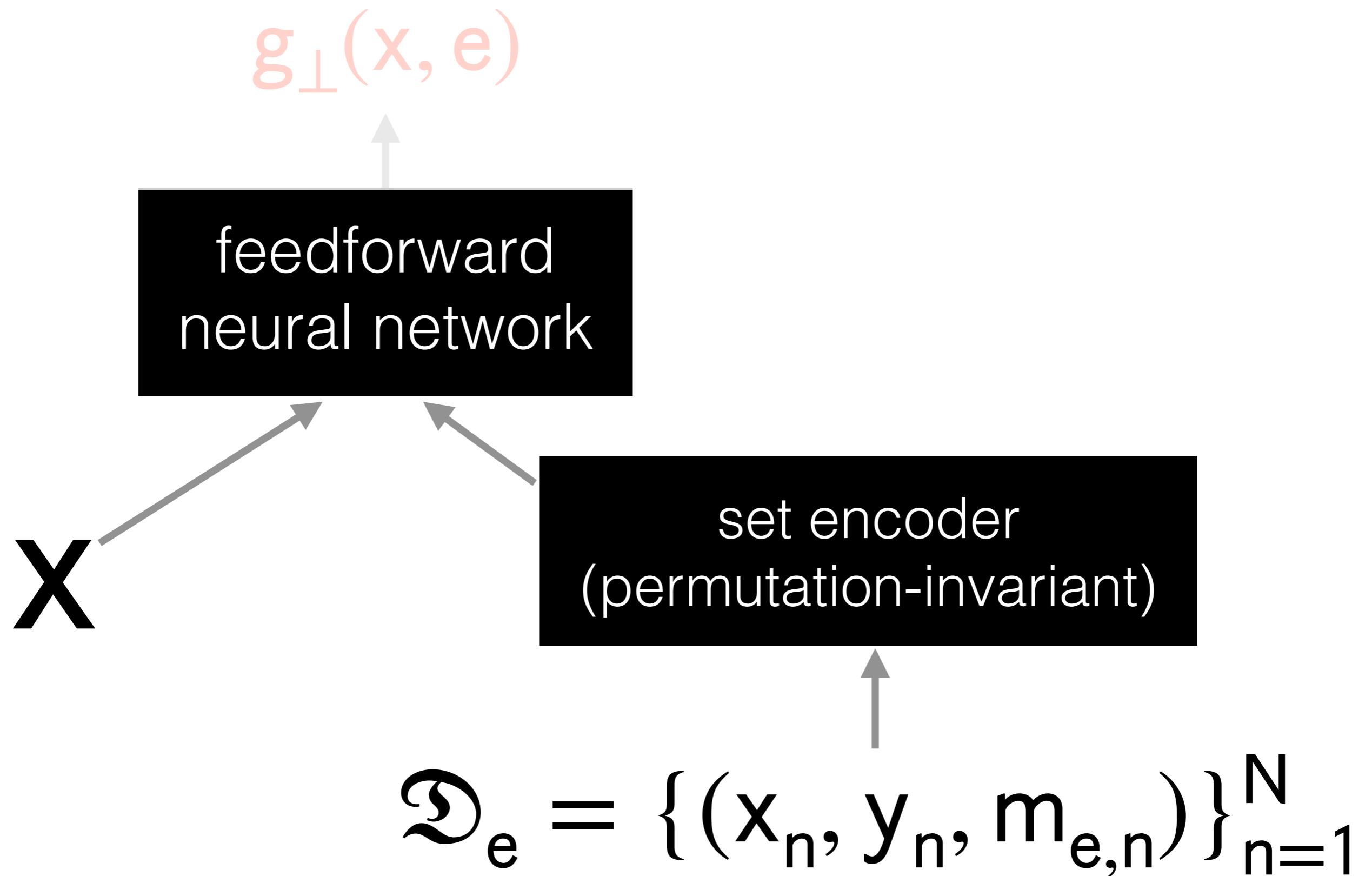
neural process rejector



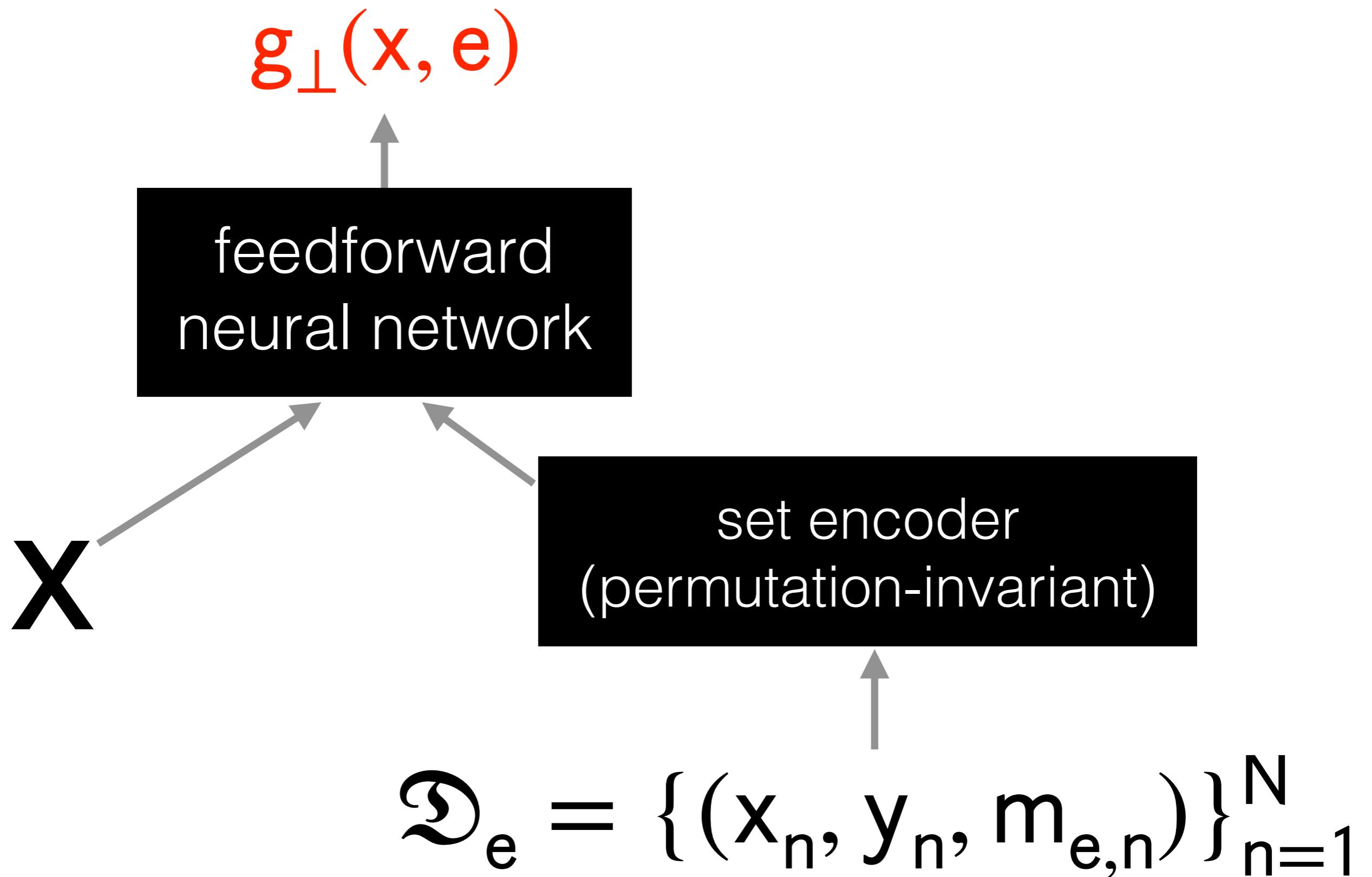
neural process rejector



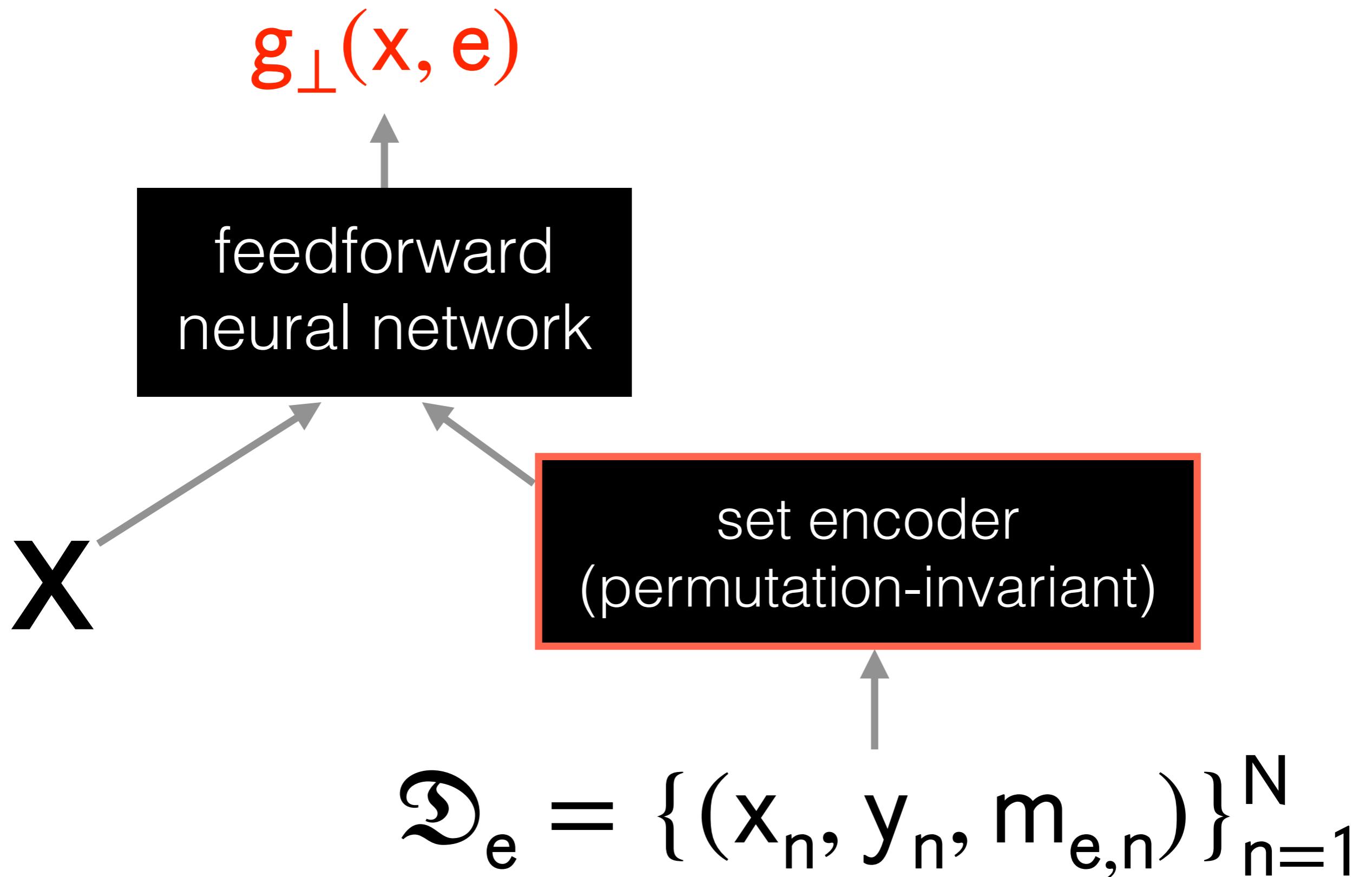
neural process rejector



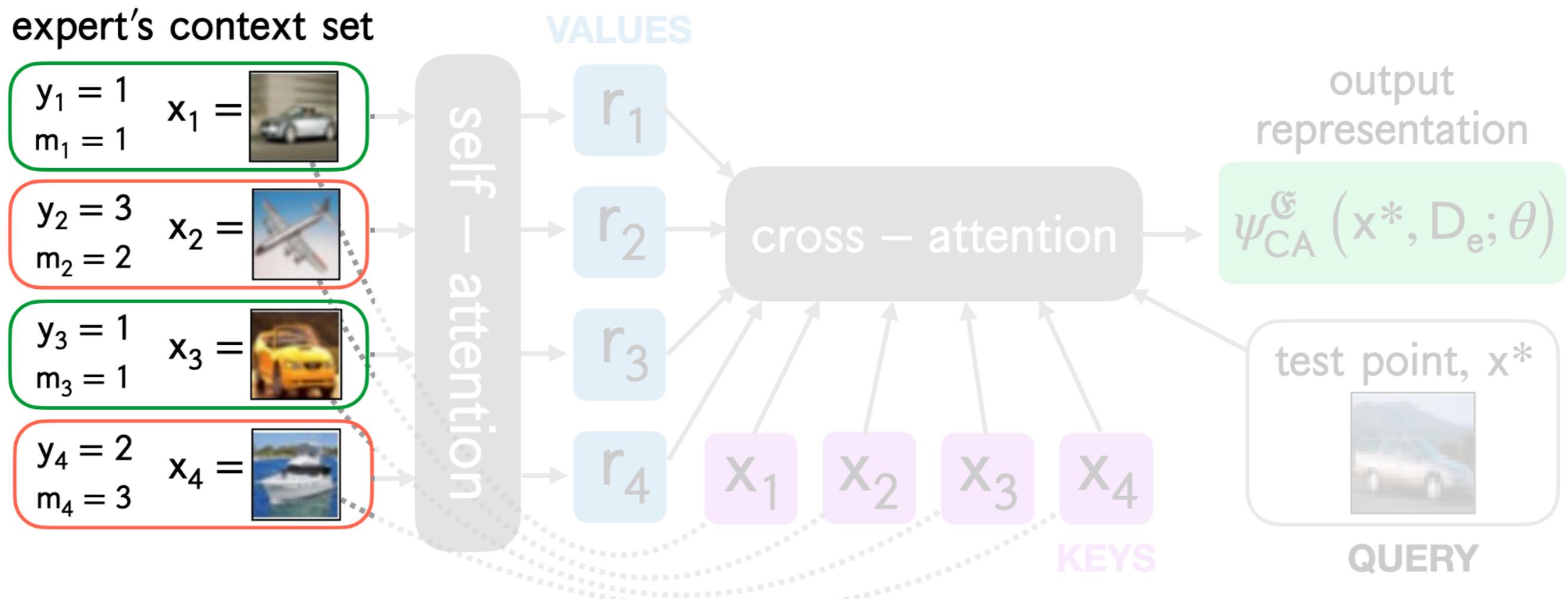
neural process rejector



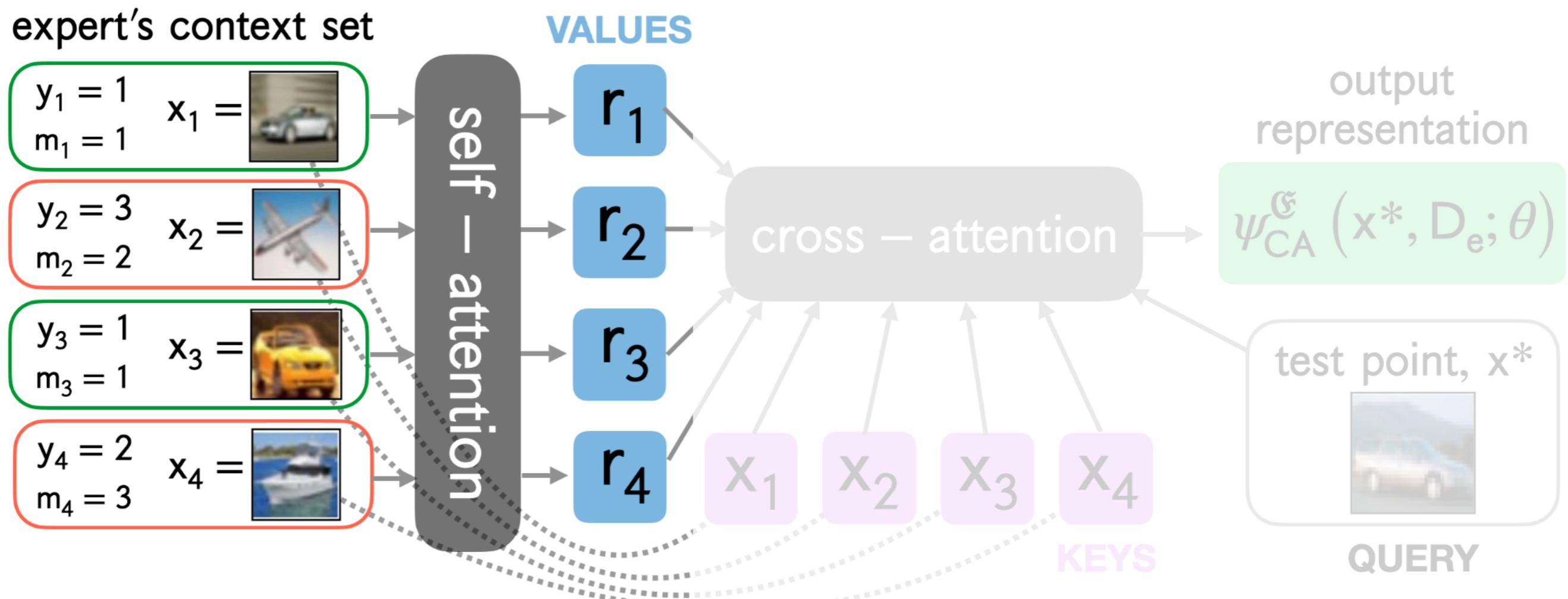
neural process rejector



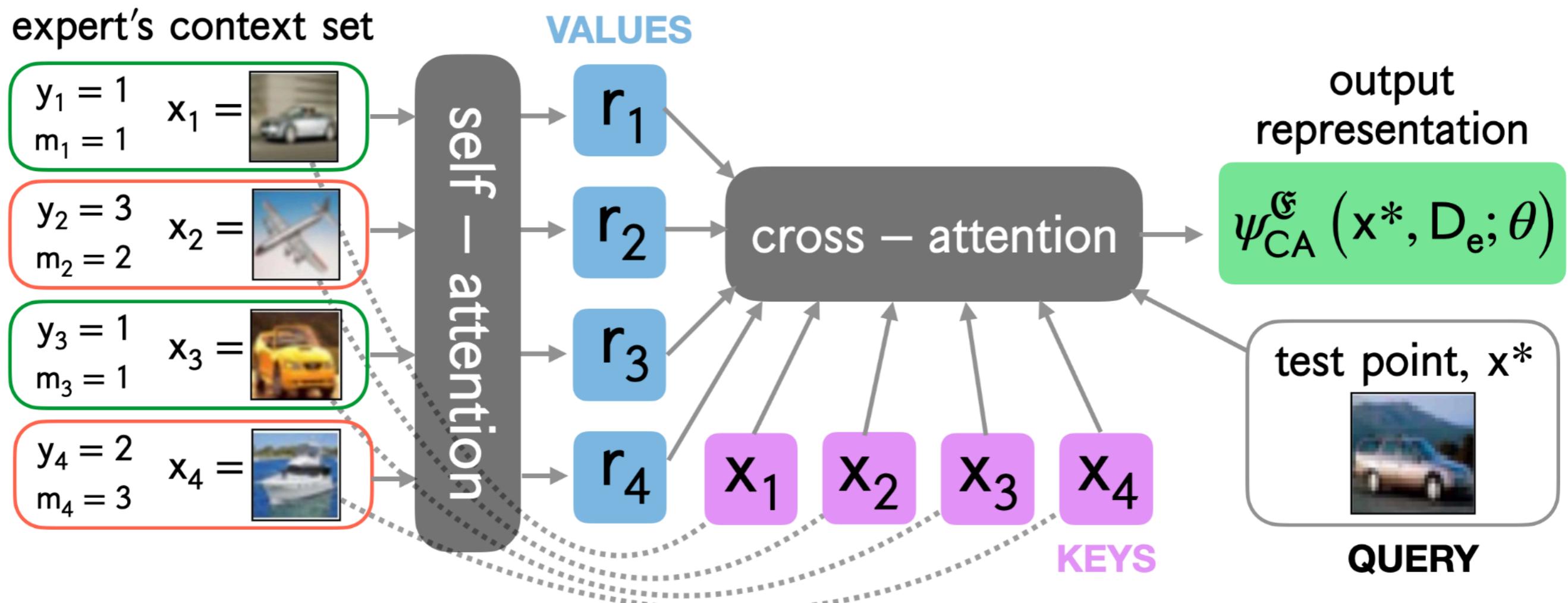
neural process rejector



neural process rejector

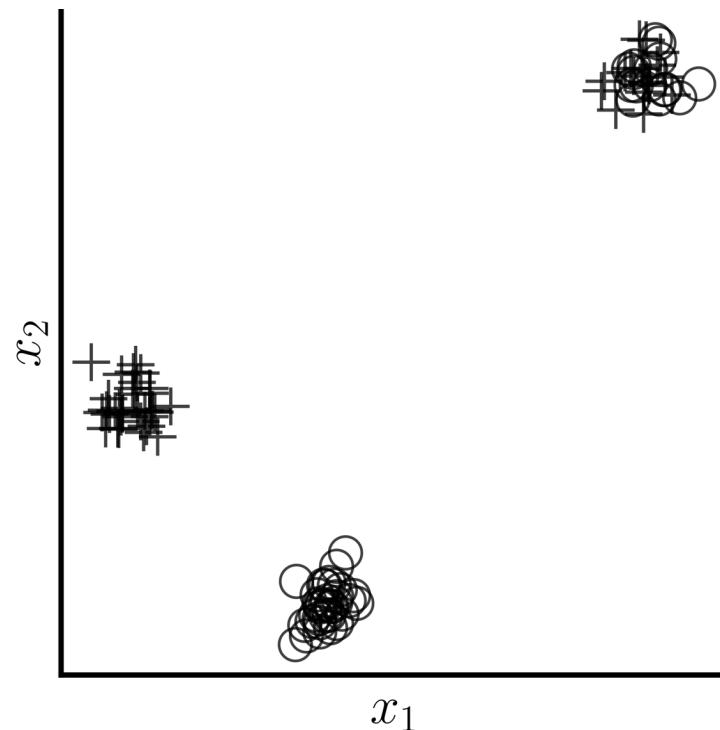


neural process rejector



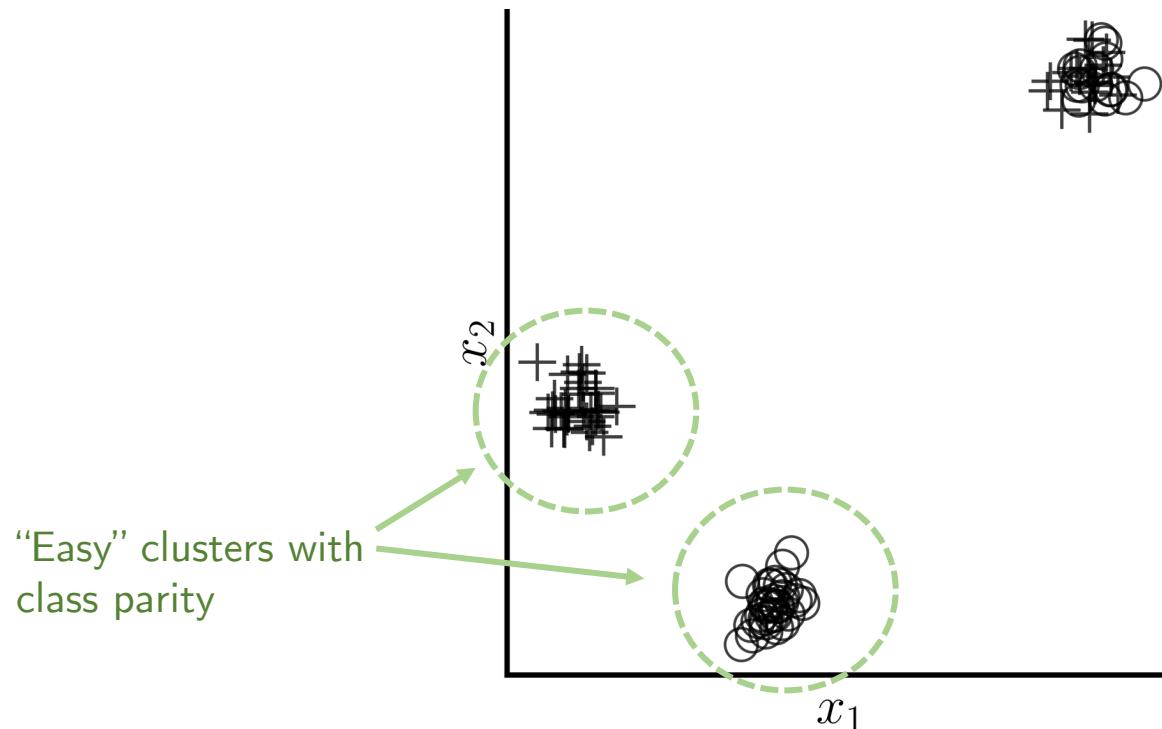
Experiment: Synthetic data

$+$: class 0 O : class 1

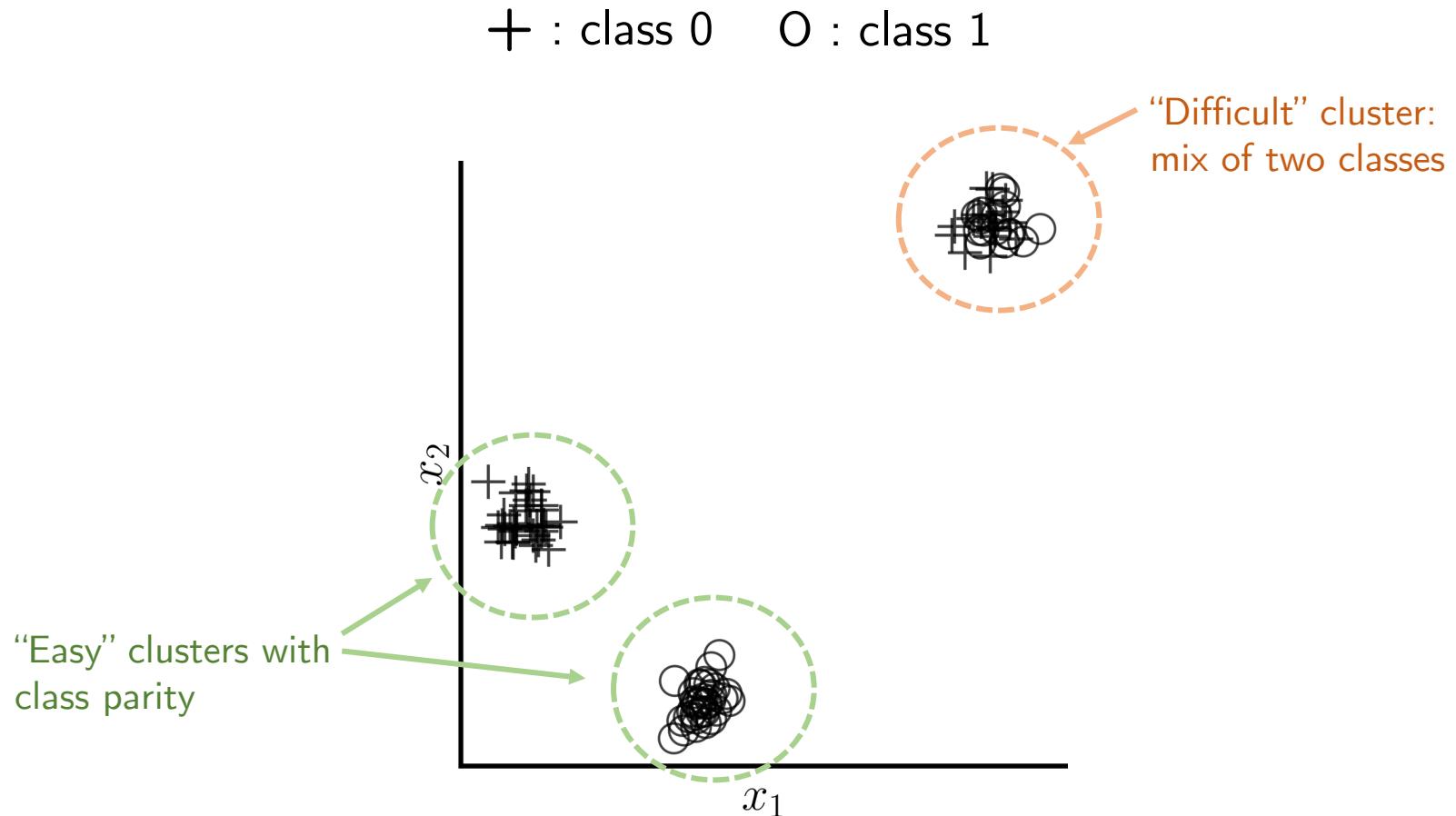


Experiment: Synthetic data

$+$: class 0 O : class 1



Experiment: Synthetic data



Experiment: Synthetic data

+ : class 0 O : class 1

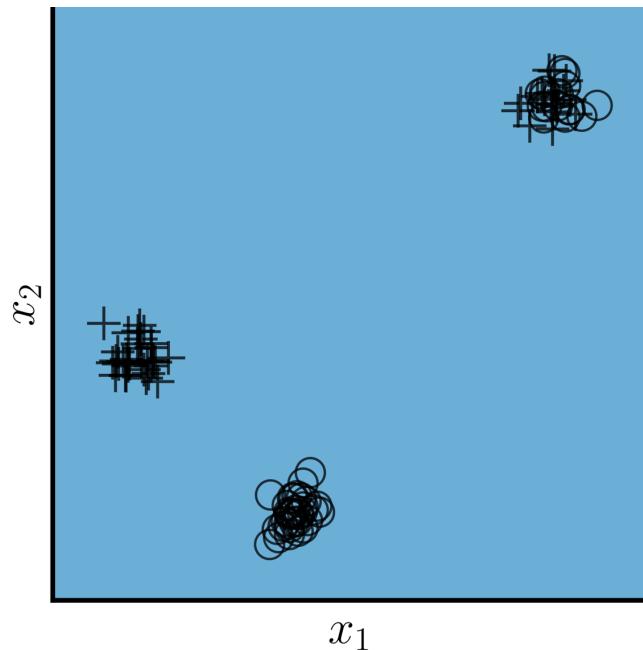


L2D-Pop
classifier region

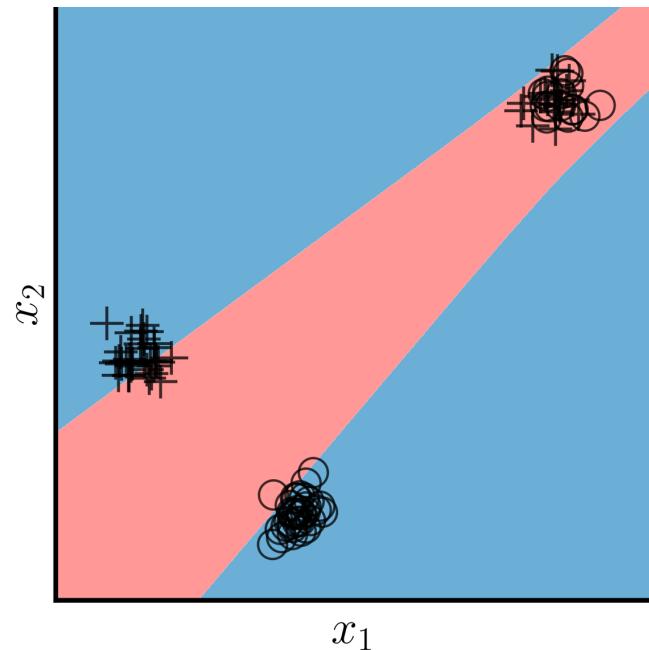


L2D-Pop deferral
region

Unskilled expert (1% accuracy)



Skilled expert (95% accuracy)



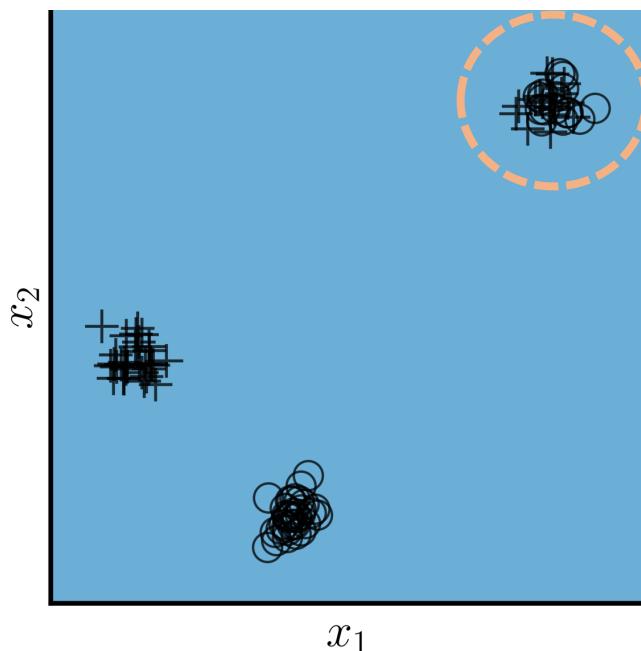
Experiment: Synthetic data

+ : class 0 O : class 1

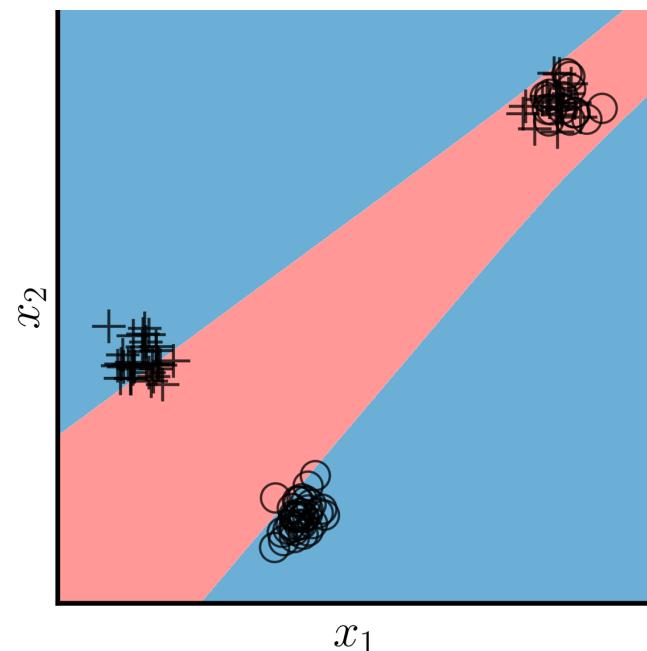
L2D-Pop
classifier region

L2D-Pop deferral
region

Unskilled expert (1% accuracy)



Skilled expert (95% accuracy)



- L2D-Pop (adaptive) ✓ Doesn't defer when the expert is poor

Experiment: Synthetic data

+ : class 0 O : class 1

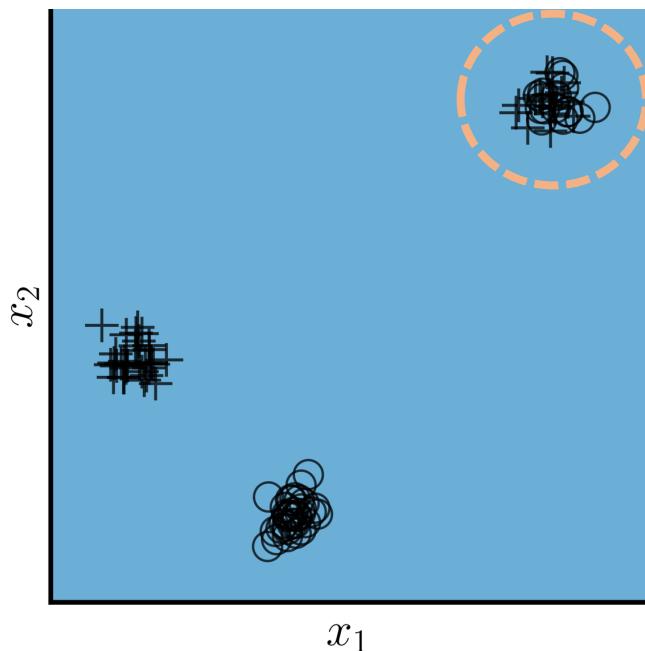


L2D-Pop
classifier region



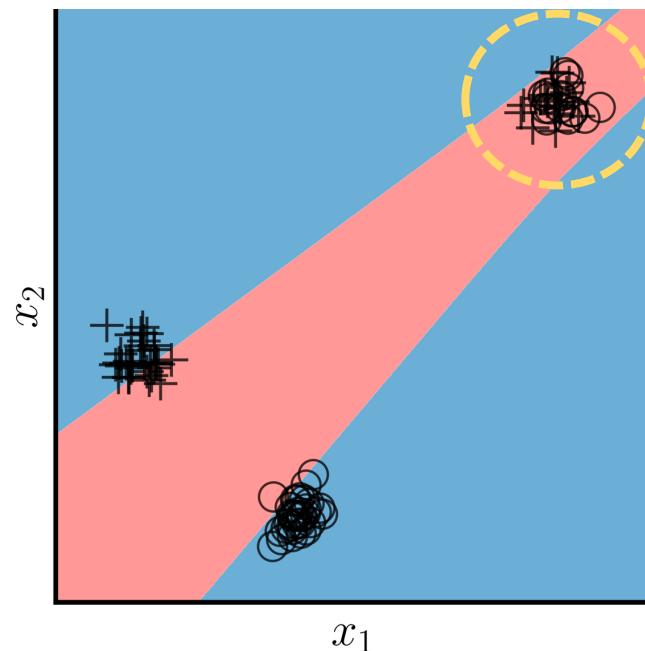
L2D-Pop deferral
region

Unskilled expert (1% accuracy)



L2D-Pop
(adaptive) ✓ Doesn't defer when the expert is poor

Skilled expert (95% accuracy)



✓ Defers whole of difficult cluster when expert is good

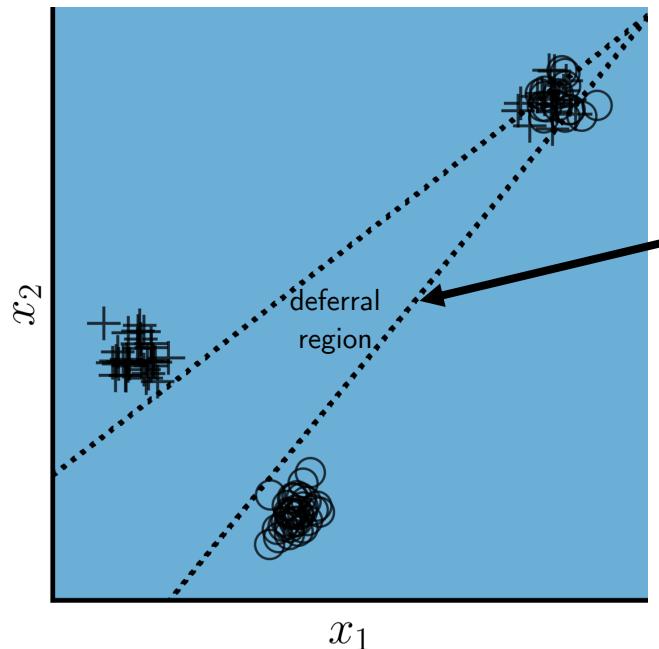
Experiment: Synthetic data

+ : class 0 O : class 1

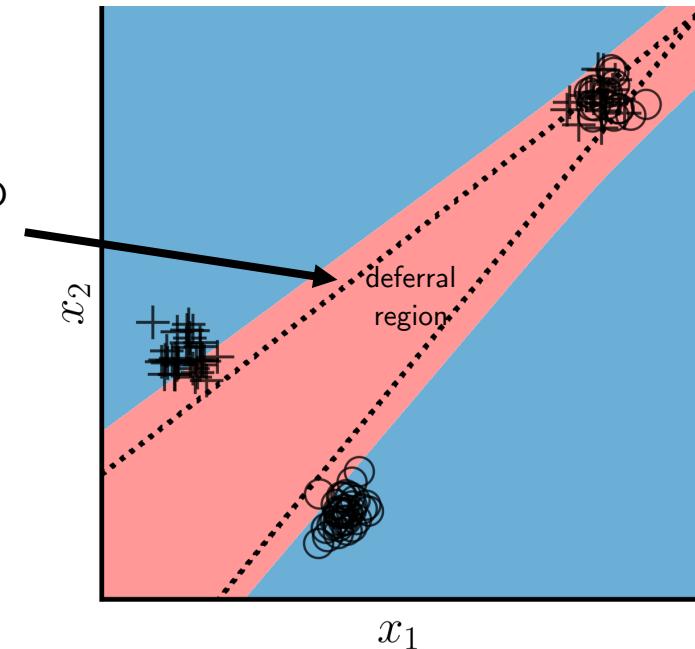
L2D-Pop
classifier region

L2D-Pop deferral
region

Unskilled expert (1% accuracy)



Skilled expert (95% accuracy)



L2D-Pop
(adaptive)

✓ Doesn't defer when the expert is poor

✓ Defers whole of difficult cluster when expert is good

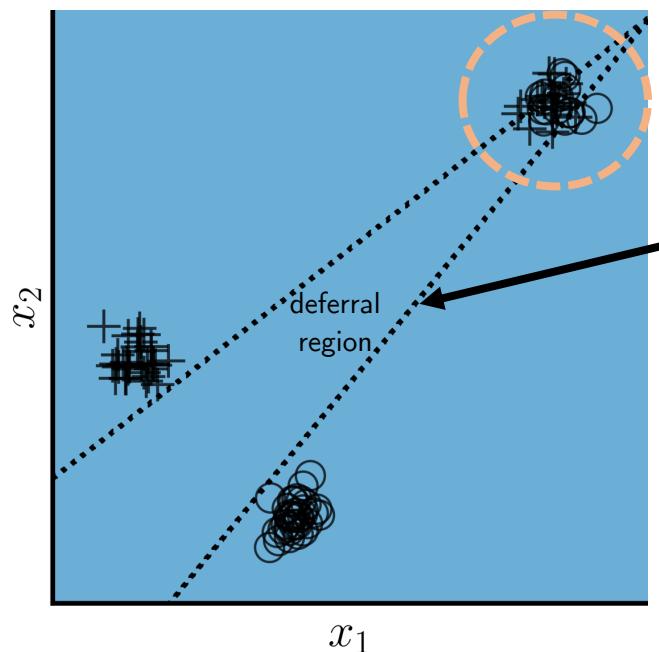
Experiment: Synthetic data

+ : class 0 O : class 1

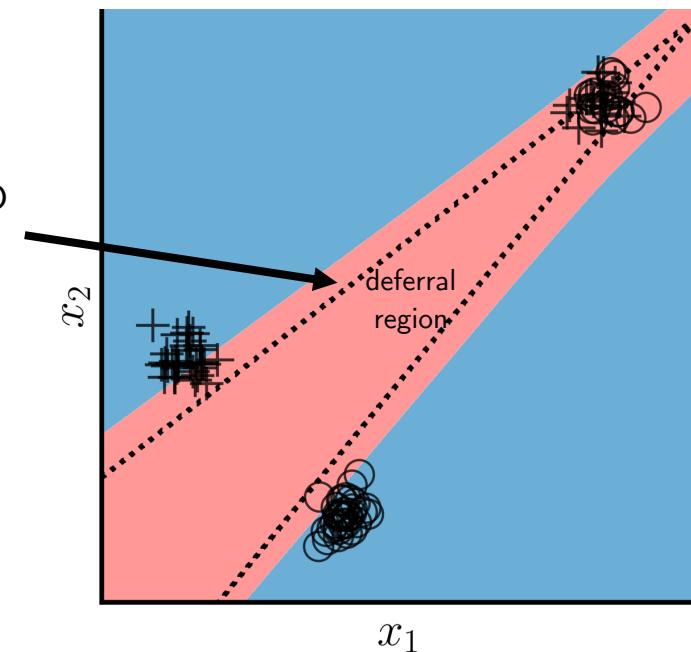
L2D-Pop
classifier region

L2D-Pop deferral
region

Unskilled expert (1% accuracy)



Skilled expert (95% accuracy)



L2D-Pop
(adaptive) ✓ Doesn't defer when the expert is poor

single-L2D
(constant) ✗ Over-defers as expert does worse than random on difficult cluster

✓ Defers whole of difficult cluster when expert is good

Experiment: Synthetic data

+ : class 0 O : class 1

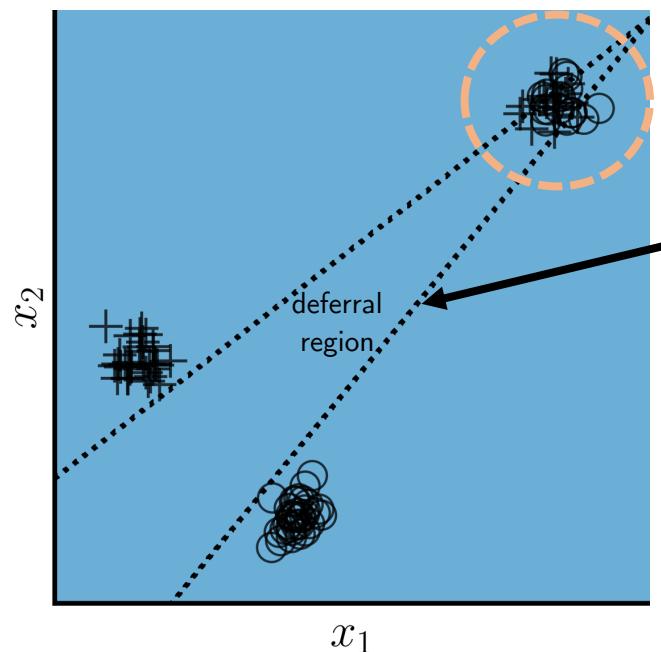


L2D-Pop
classifier region

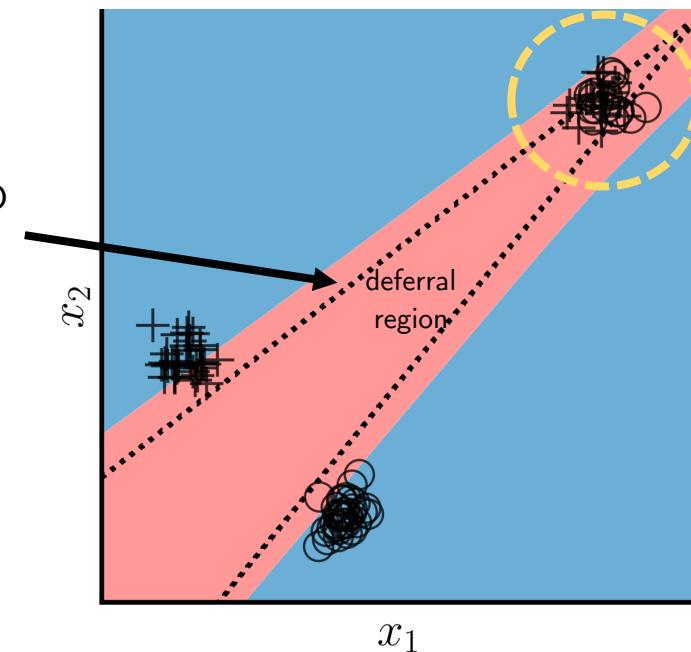


L2D-Pop deferral
region

Unskilled expert (1% accuracy)



Skilled expert (95% accuracy)

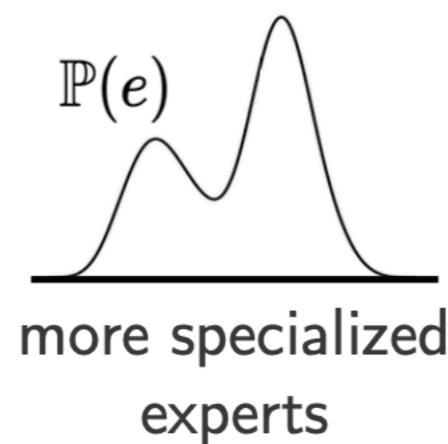
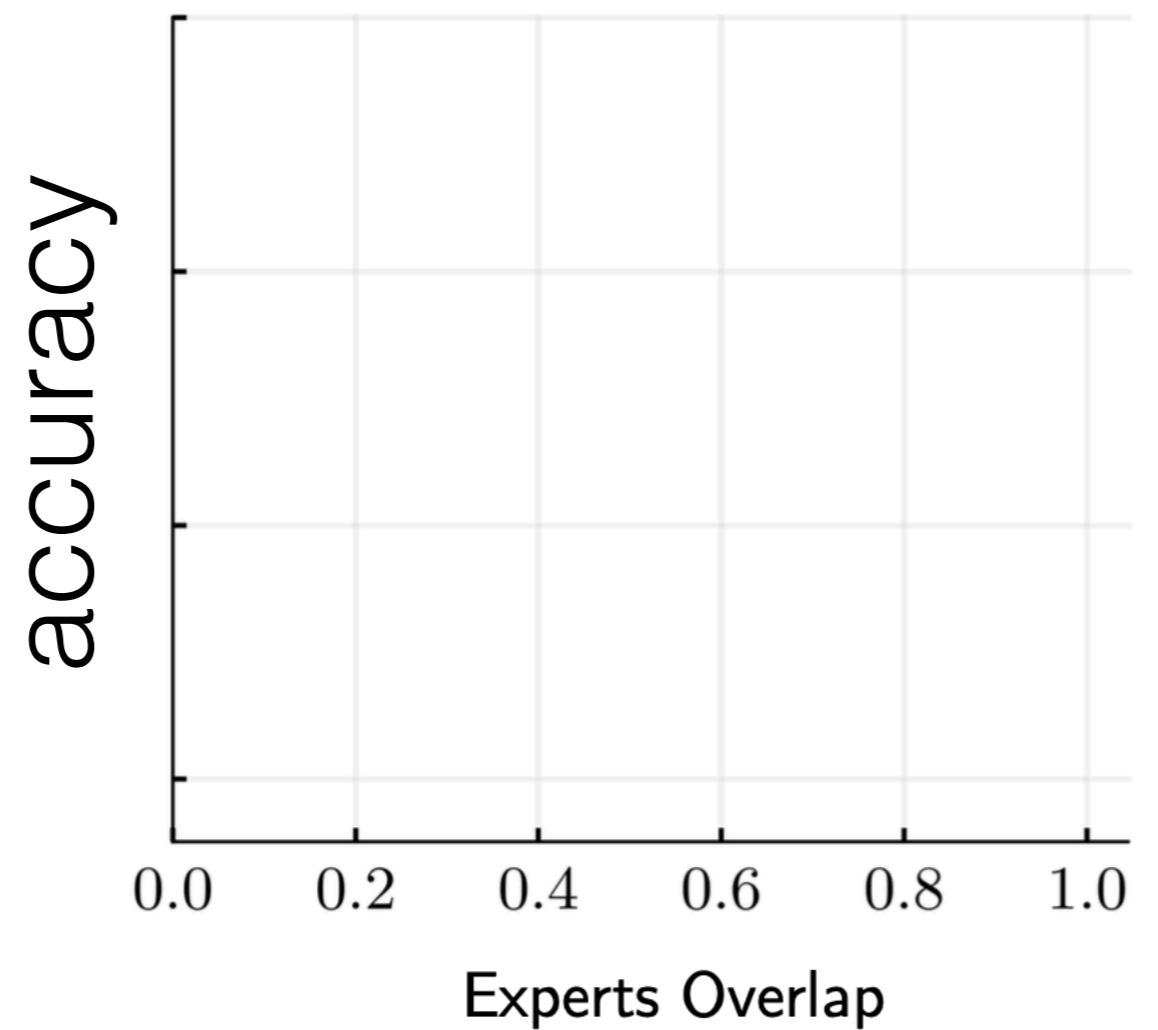


L2D-Pop
(adaptive) ✓ Doesn't defer when the expert is poor

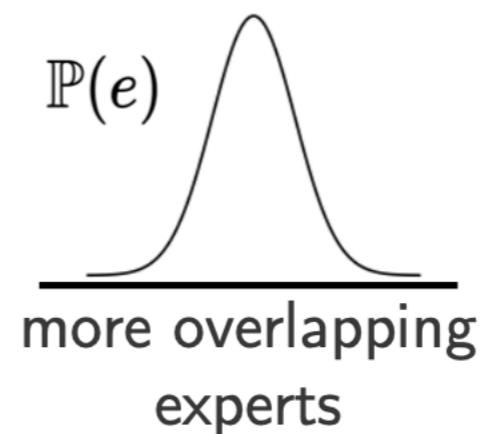
single-L2D
(constant) ✗ Over-defers as expert does worse than random on difficult cluster

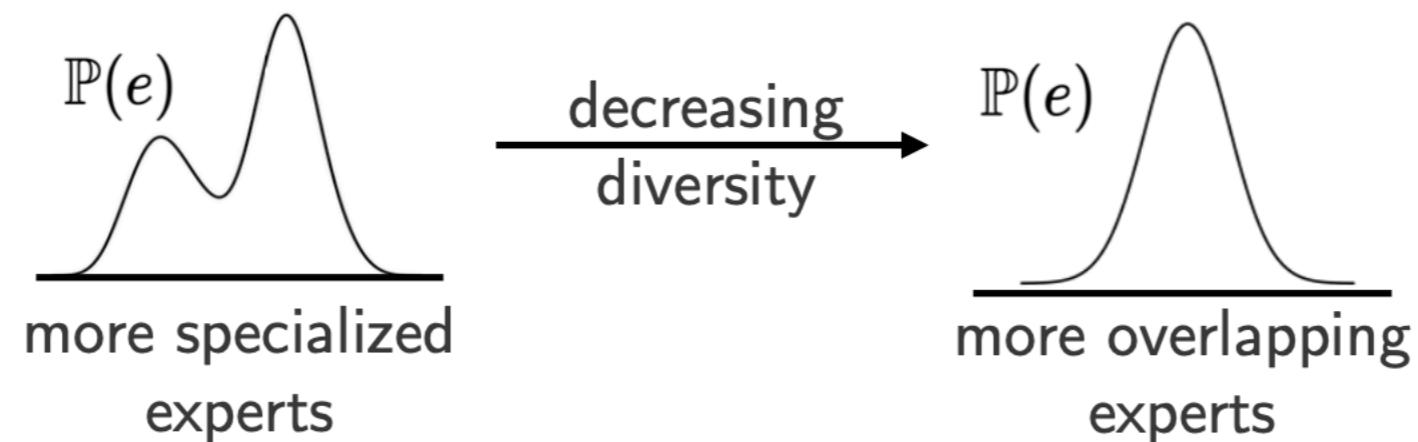
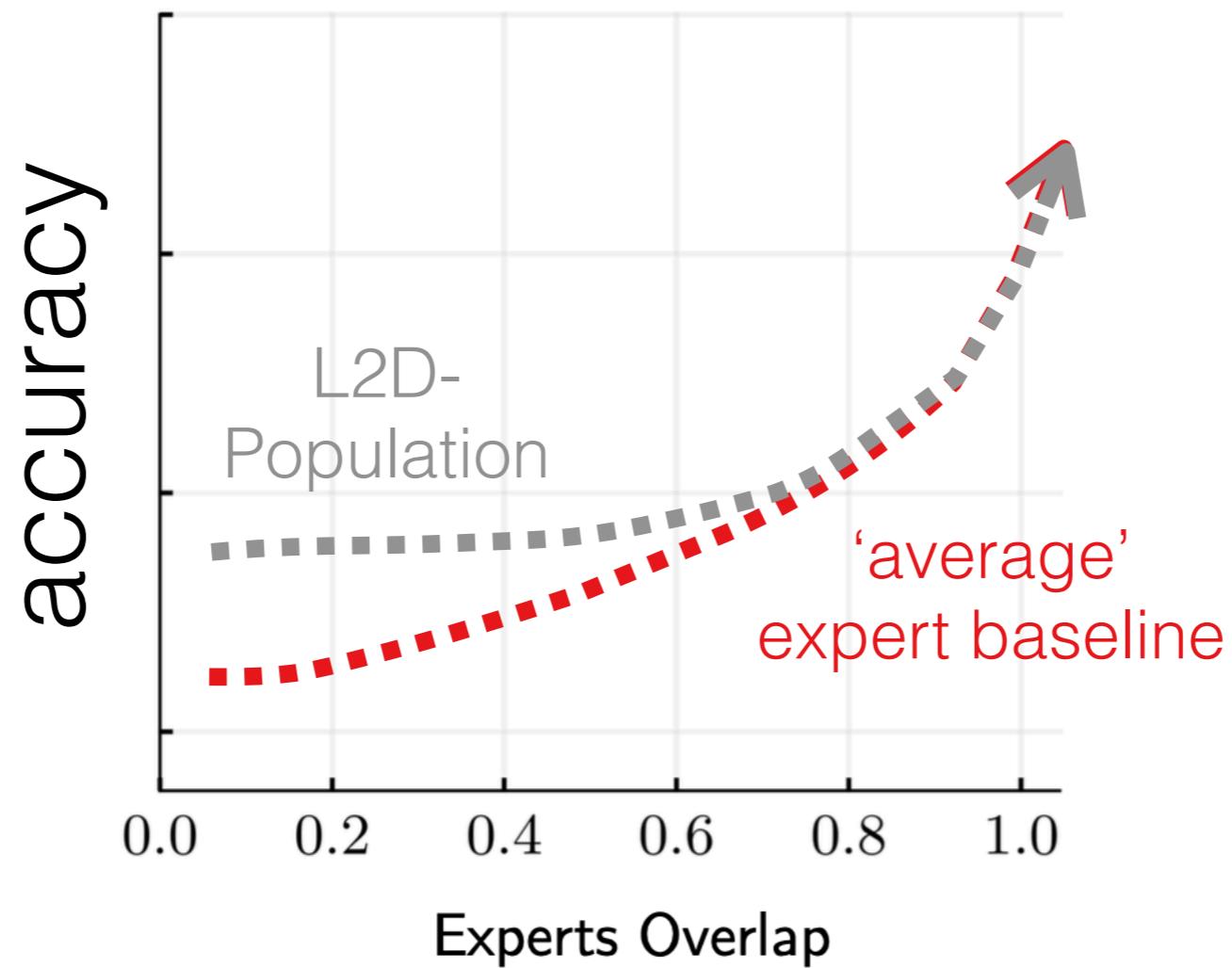
✓ Defers whole of difficult cluster when expert is good

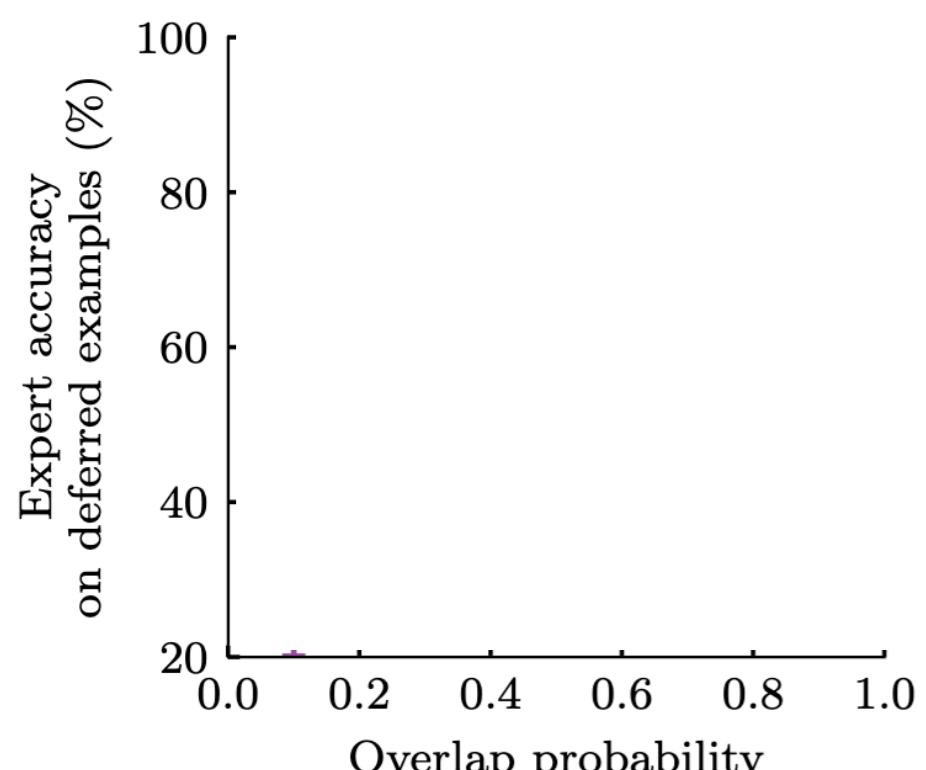
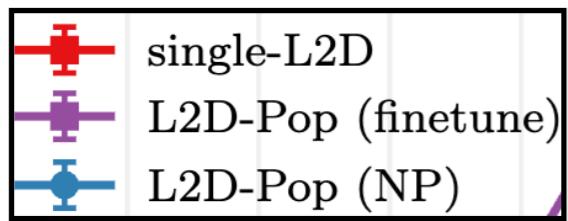
✗ Under-defers as classifier only has random chance of being correct on difficult cluster



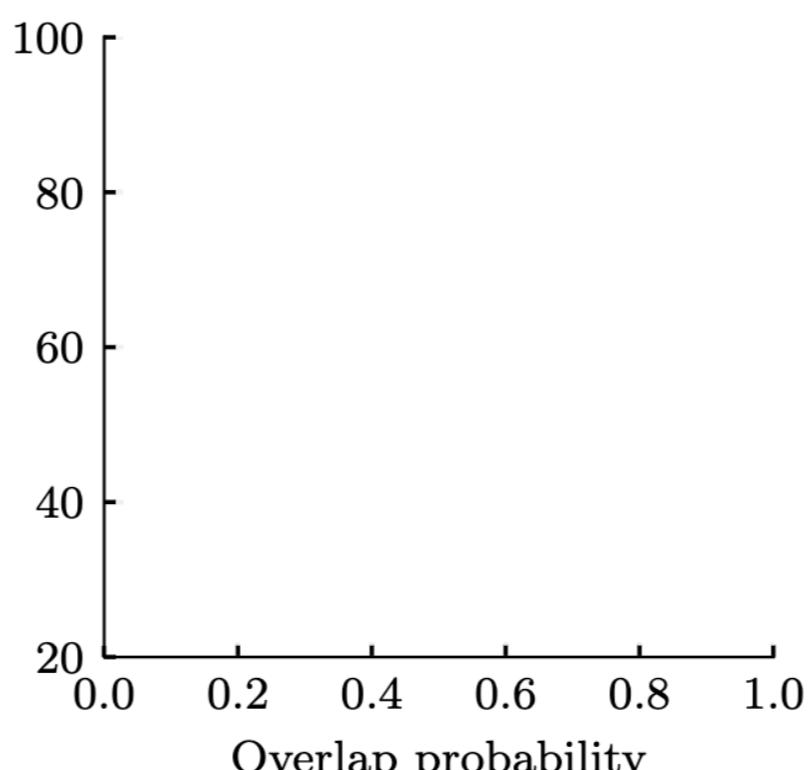
decreasing
diversity



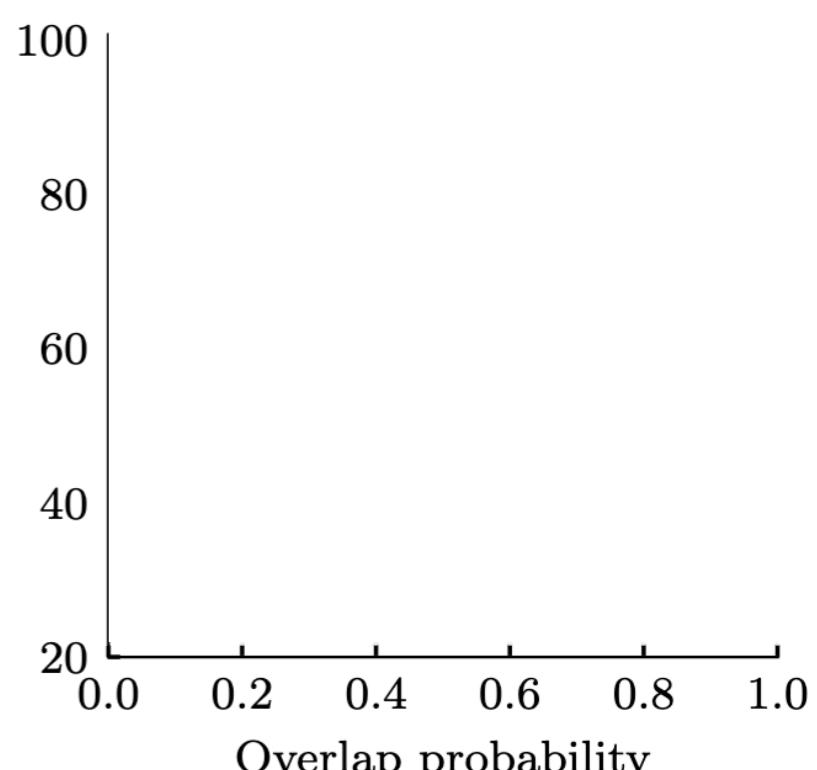




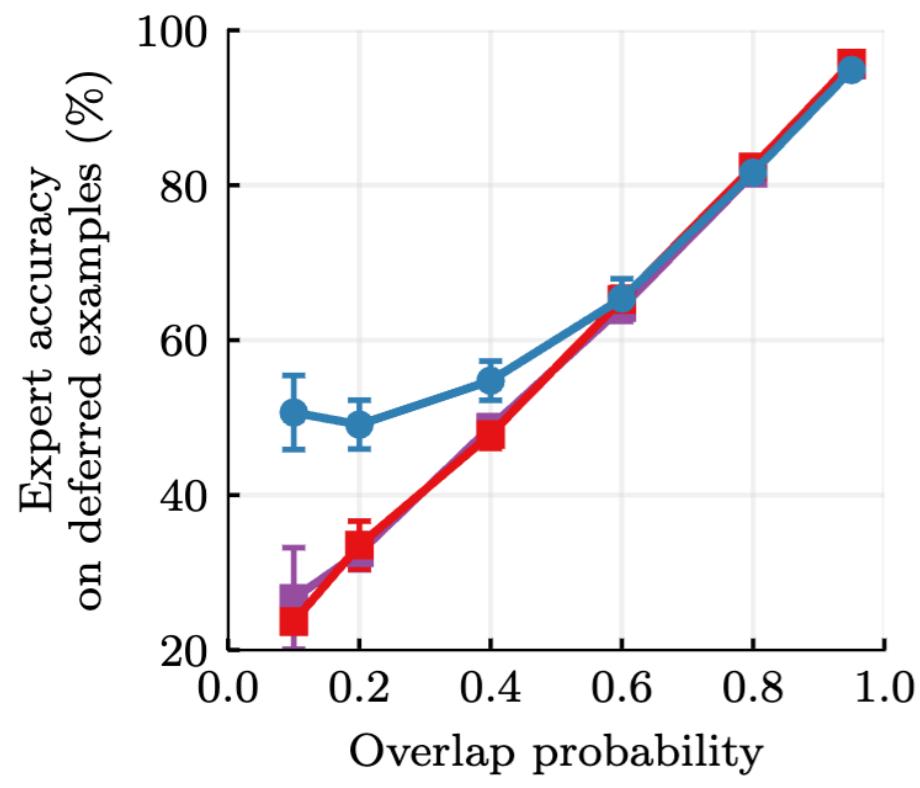
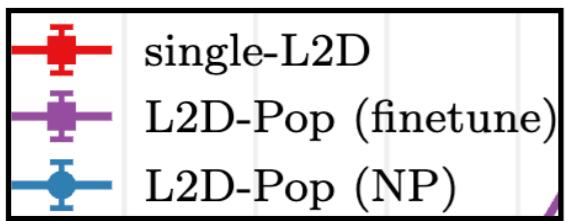
(a) Traffic Signs



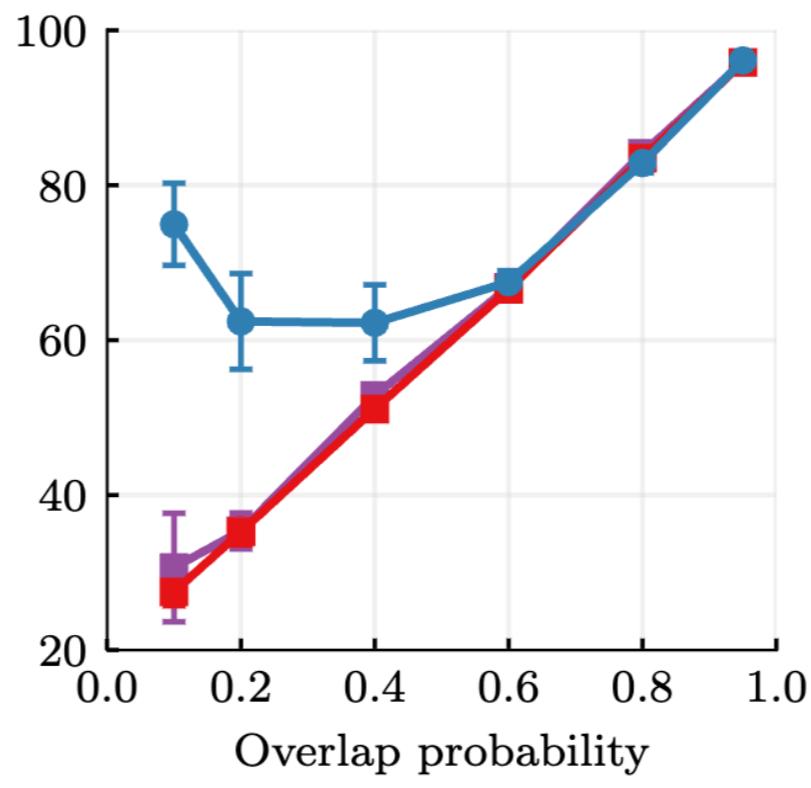
(b) CIFAR-10



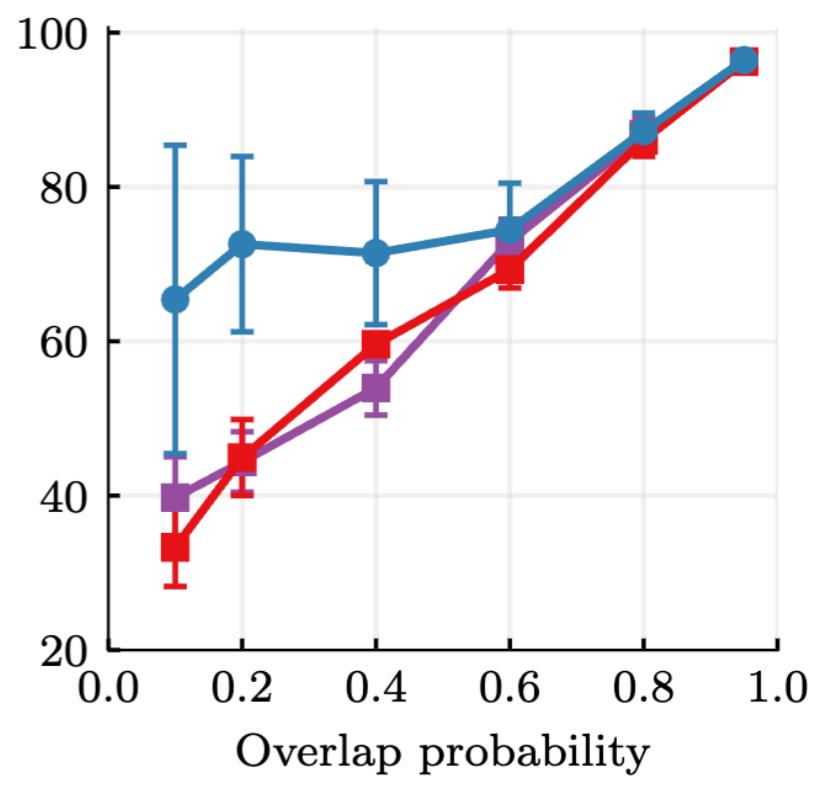
(c) HAM10000



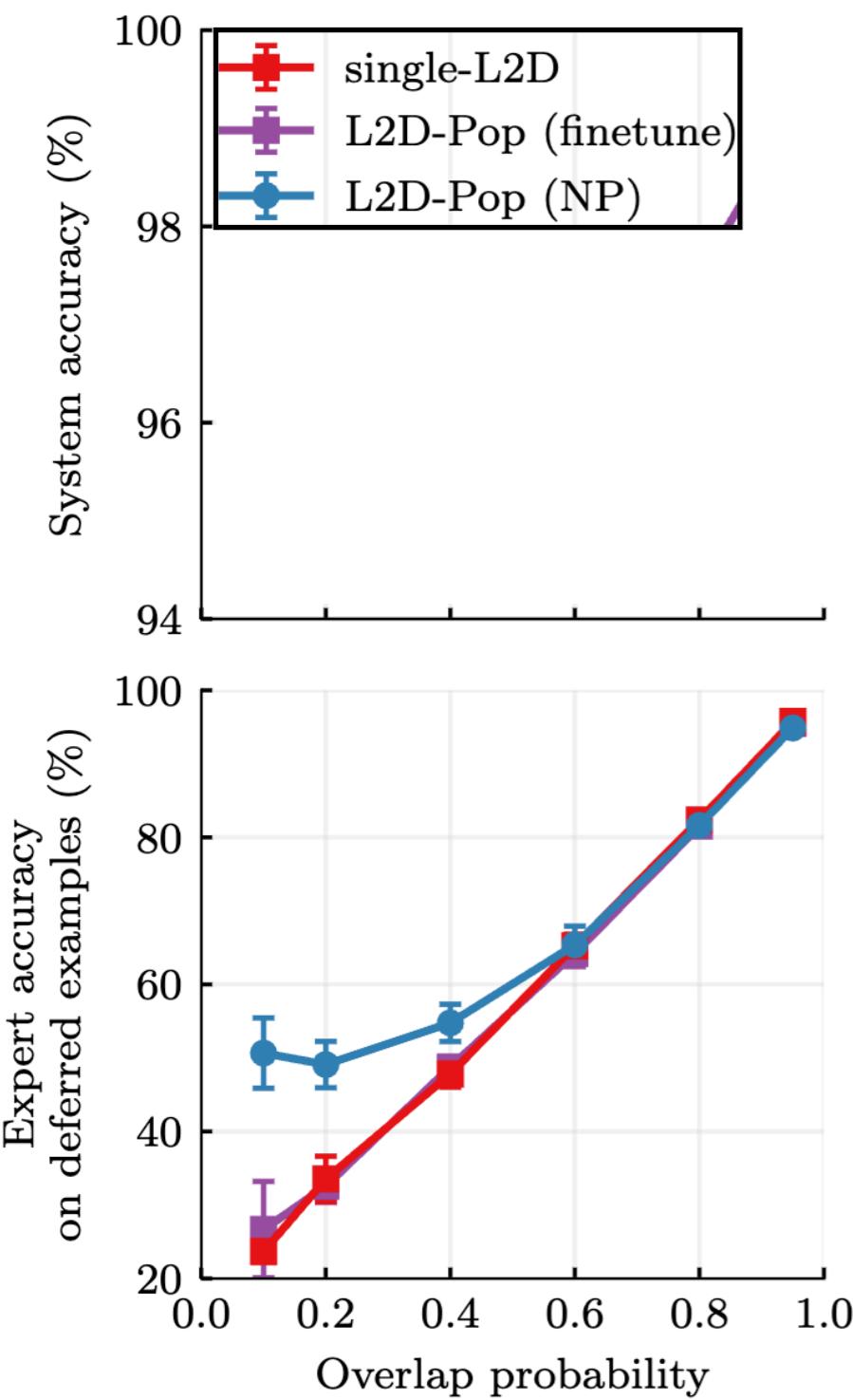
(a) Traffic Signs



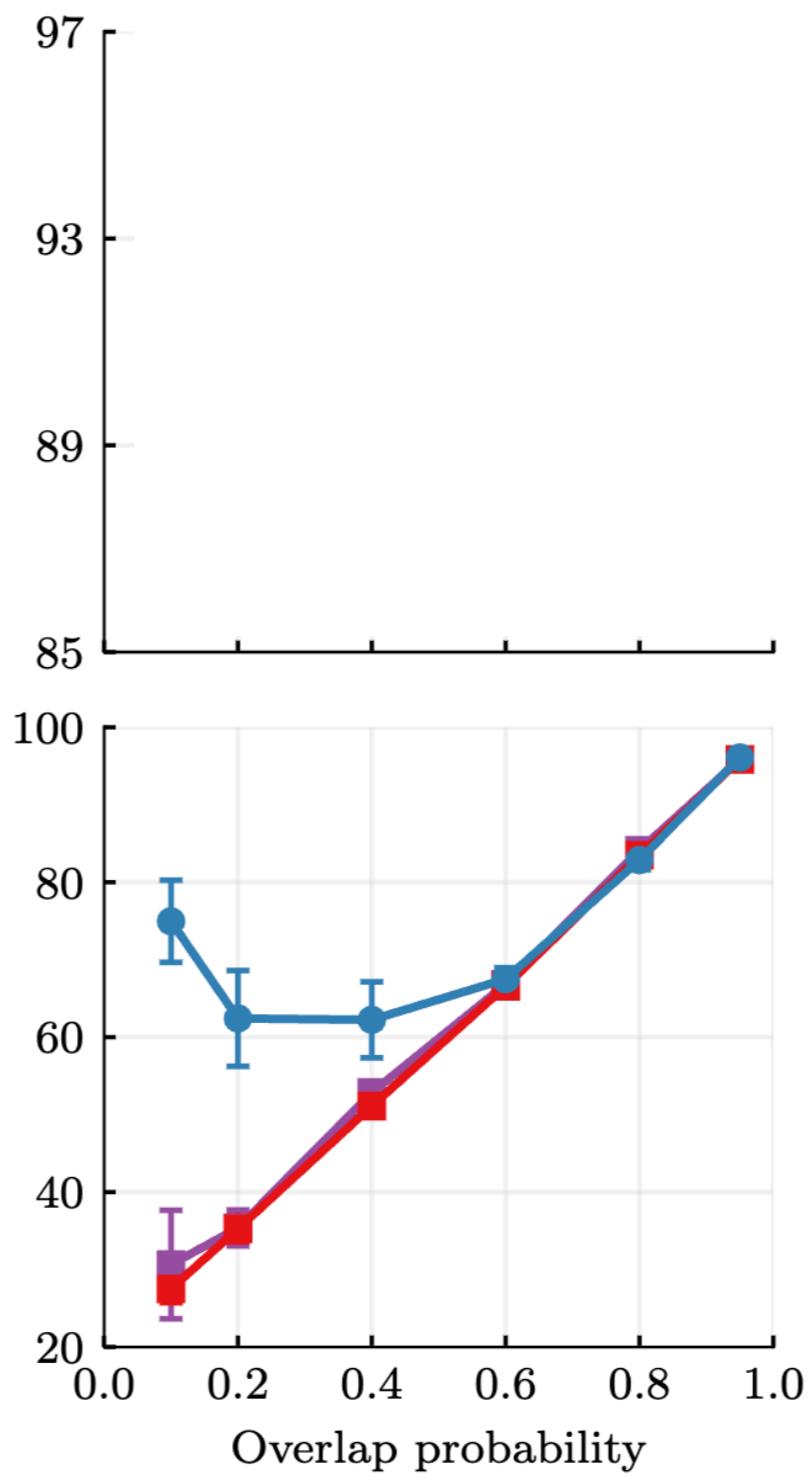
(b) CIFAR-10



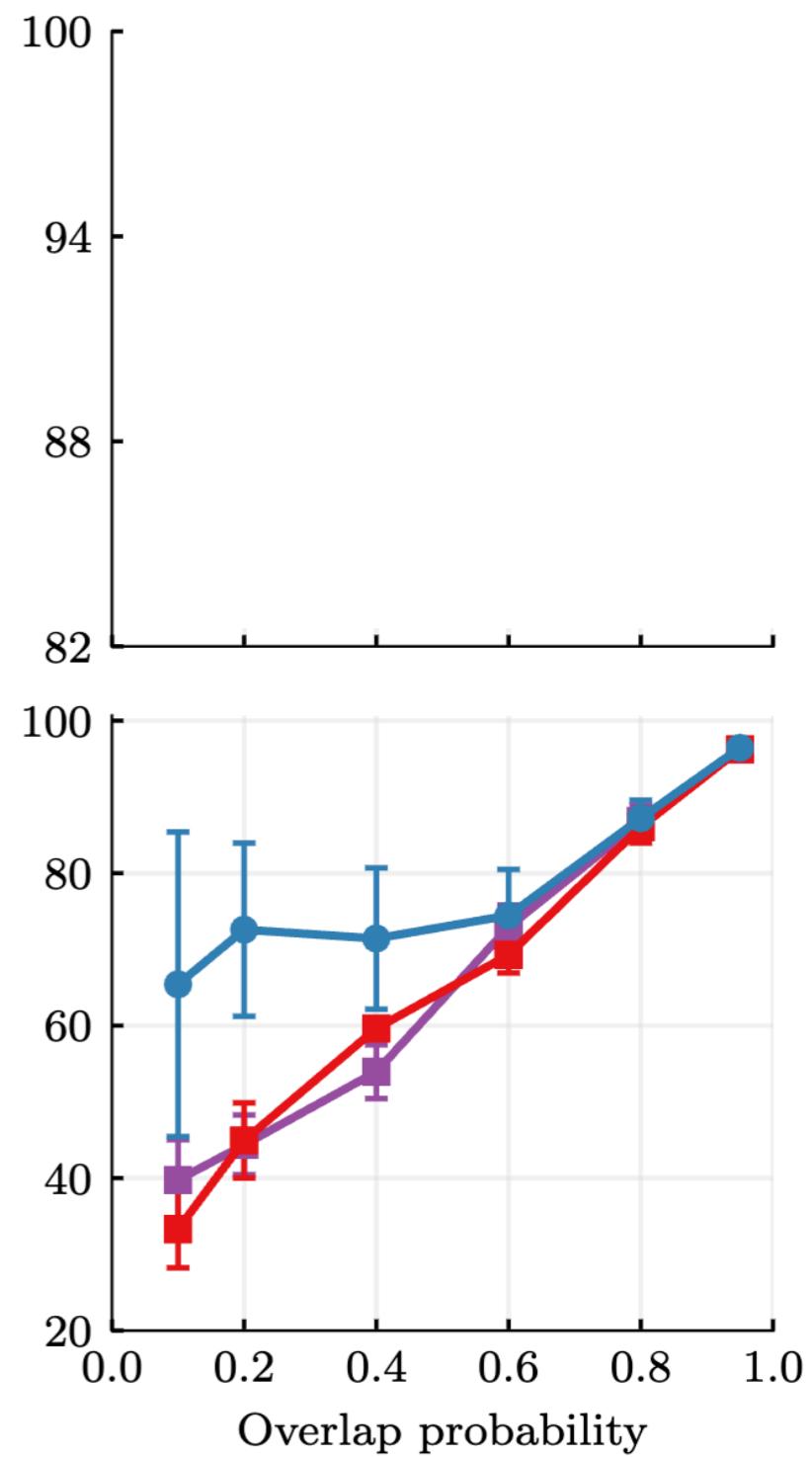
(c) HAM10000



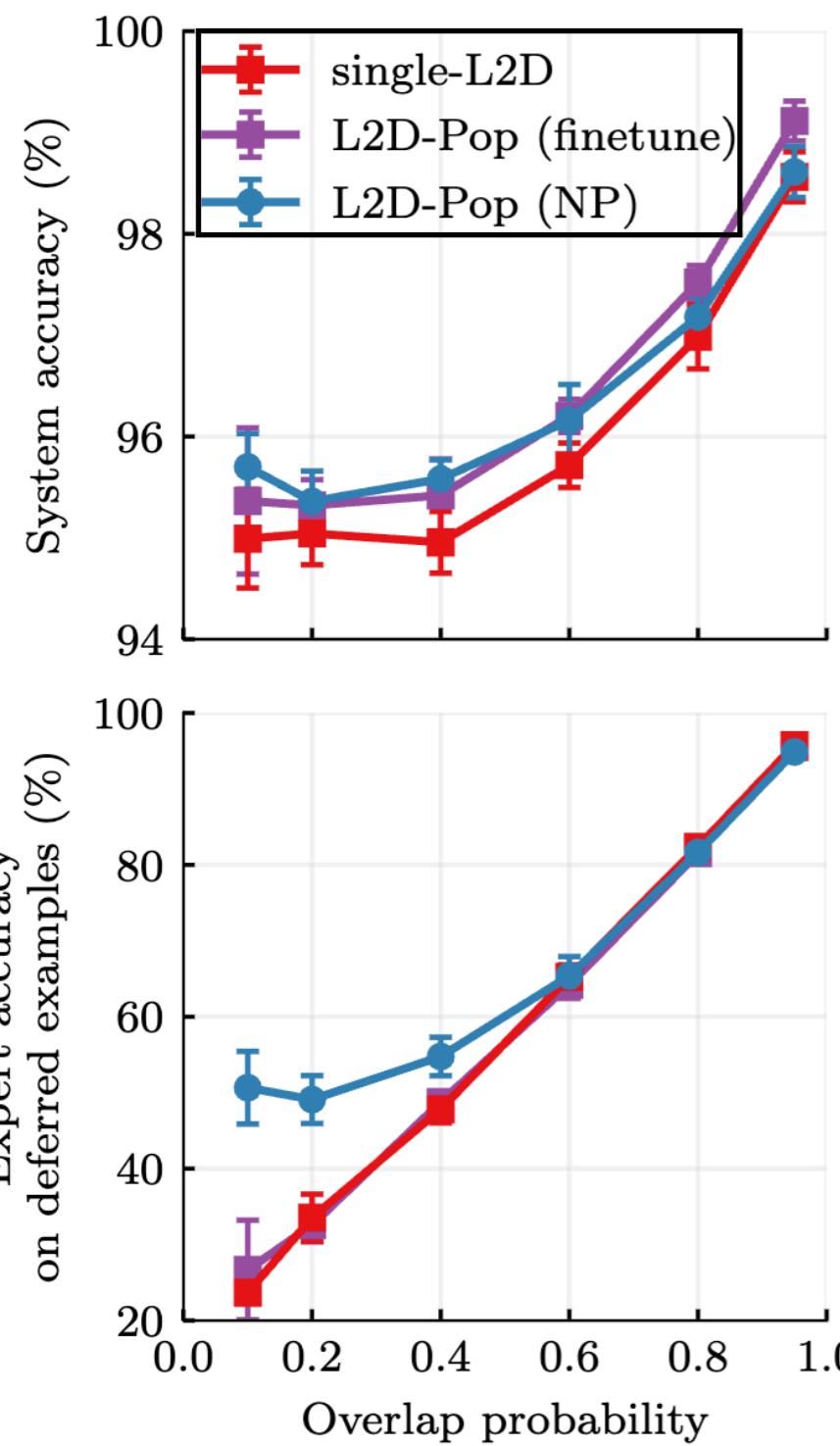
(a) Traffic Signs



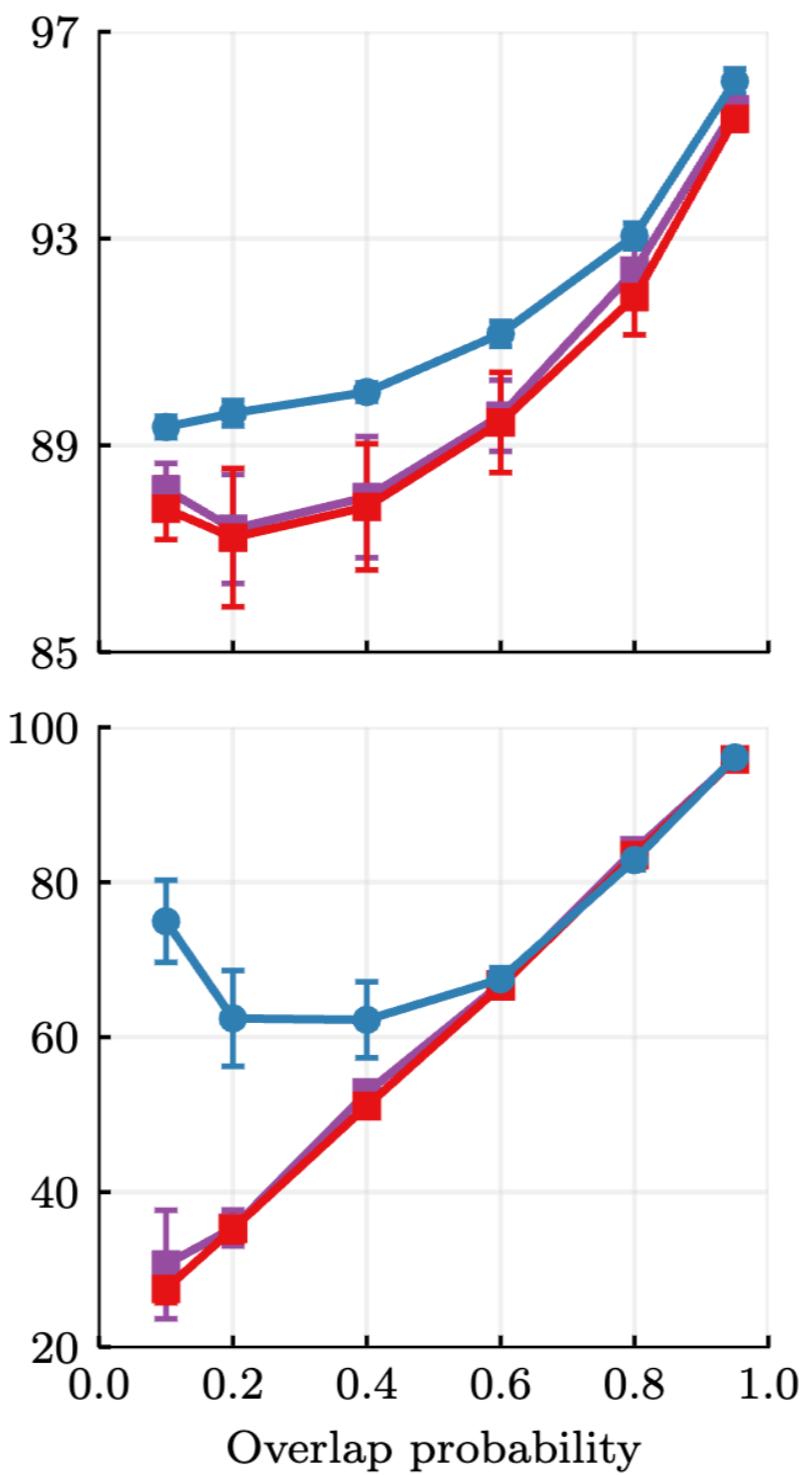
(b) CIFAR-10



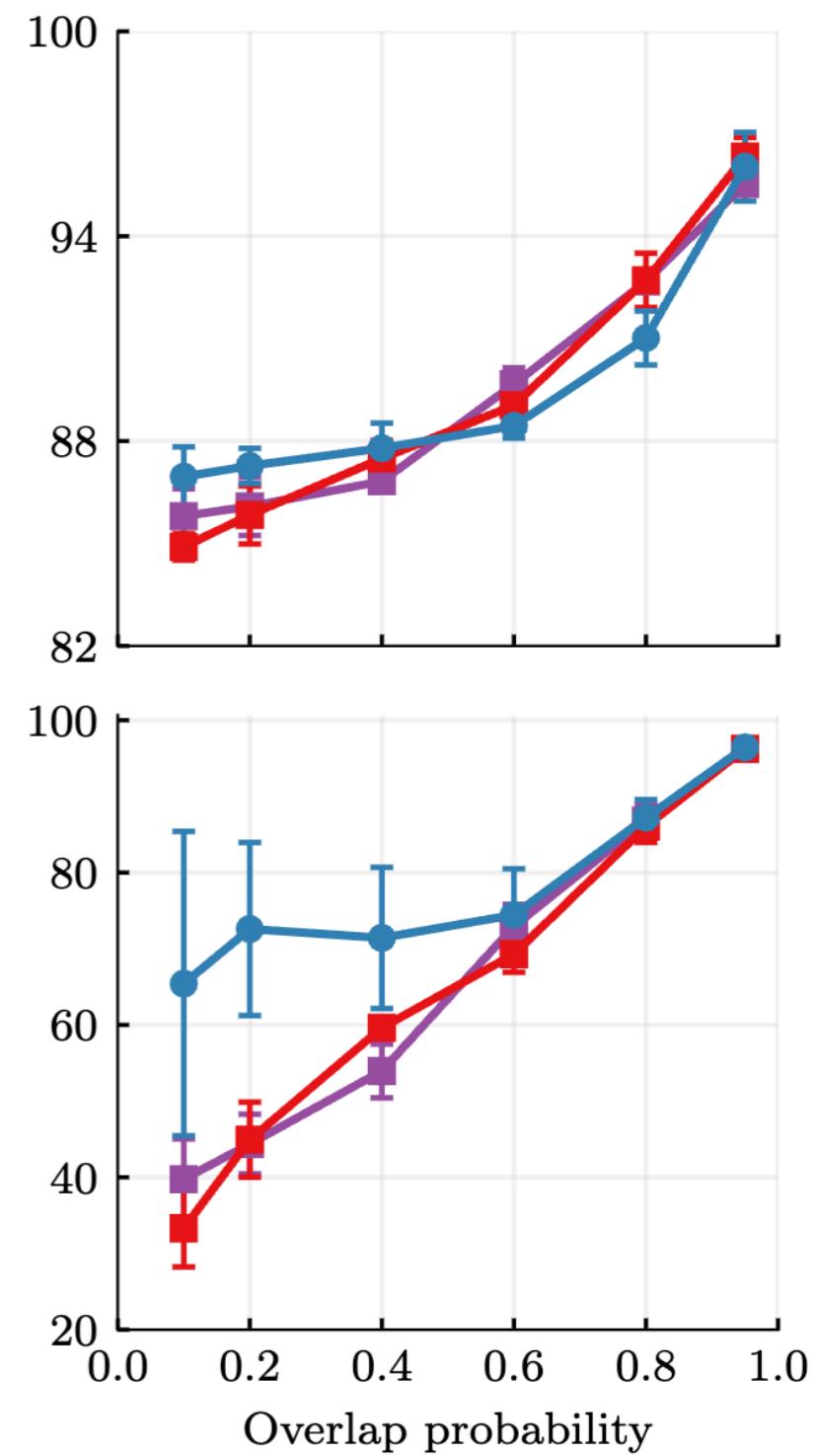
(c) HAM10000



(a) Traffic Signs



(b) CIFAR-10



(c) HAM10000

- ⊗ single expert
 - ⊗ softmax surrogate loss
 - ⊗ improving calibration via one-vs-all
- ⊗ multiple experts
 - ⊗ surrogate losses
 - ⊗ conformal sets of experts
- ⊗ population of experts
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- ⊗ multiple experts
 - ⊗ surrogate losses
 - ⊗ conformal sets of experts
- ⊗ population of experts
 - ⊗ surrogate losses
 - ⊗ meta-learning a rejector

input
features



allocation
mechanism

classifier

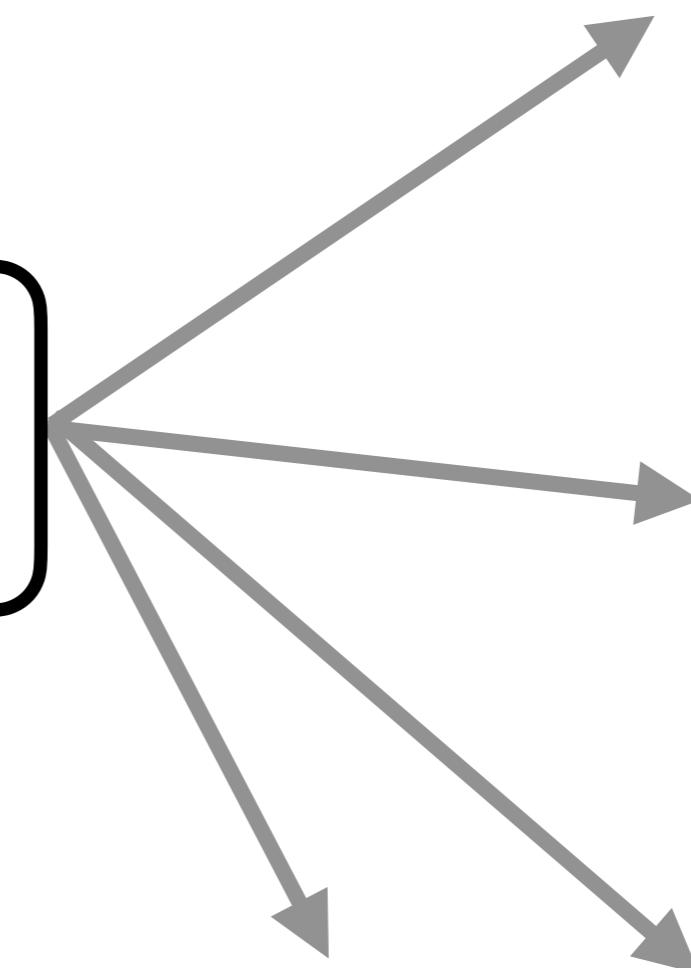


expert

input
features



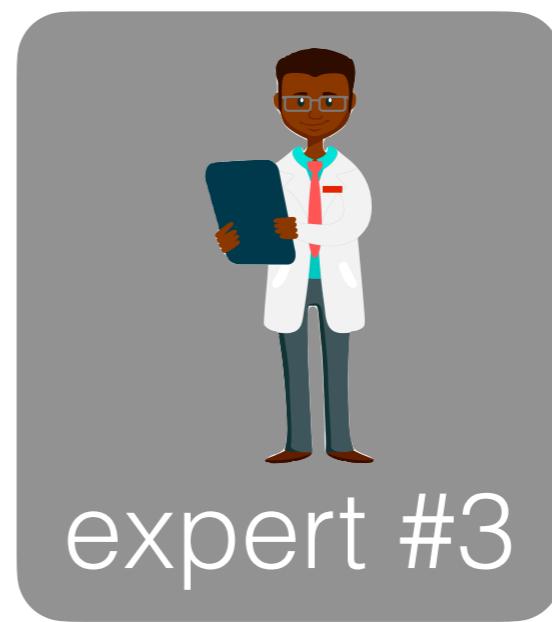
allocation
mechanism



classifier



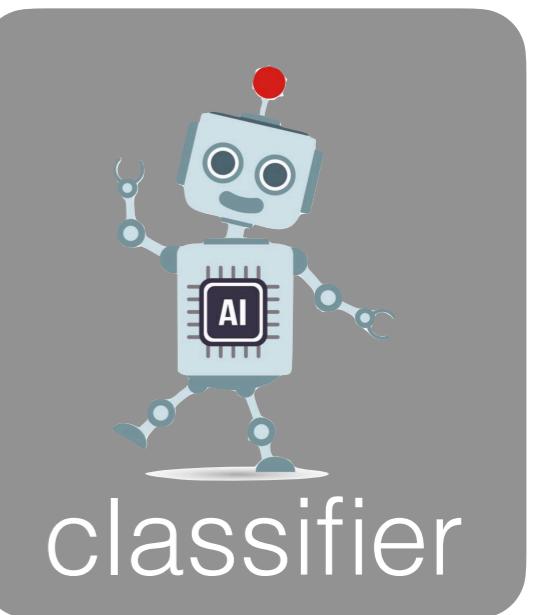
expert #1



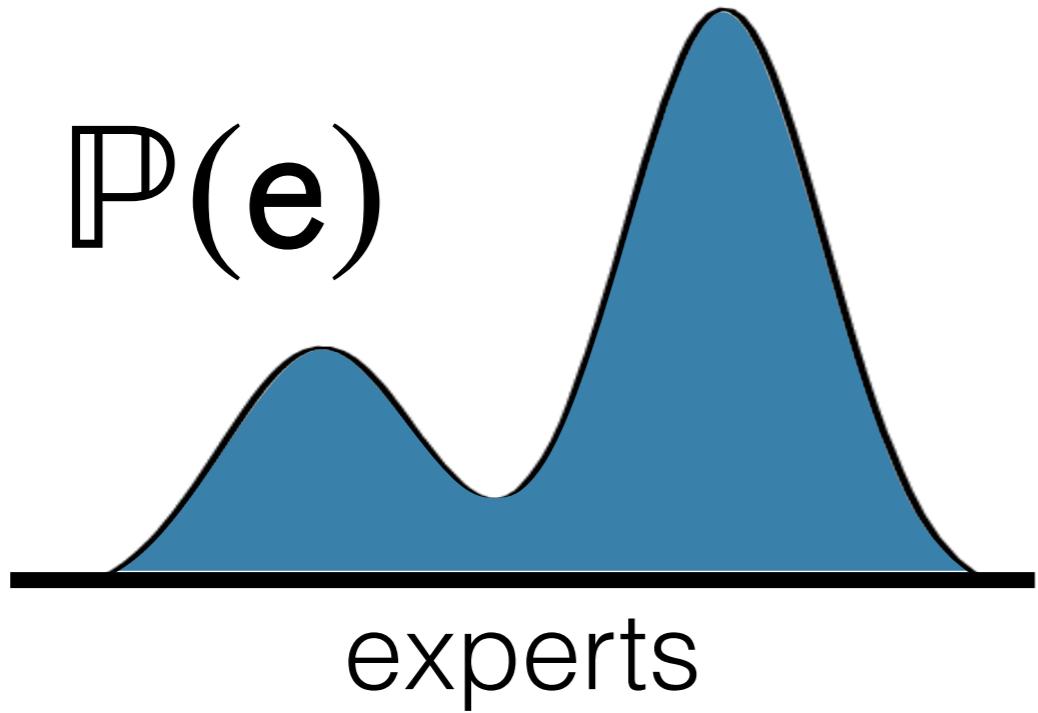
input
features



allocation
mechanism



$P(e)$

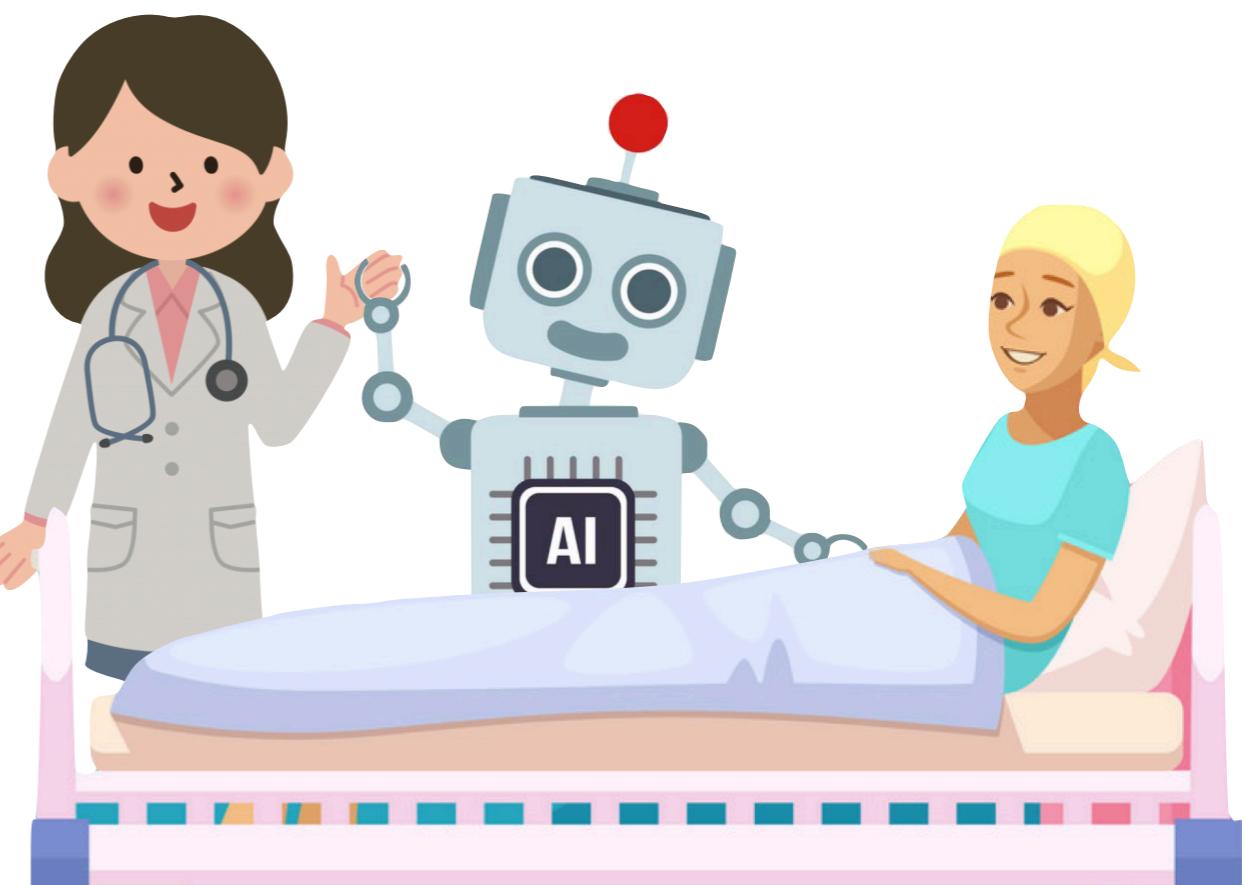
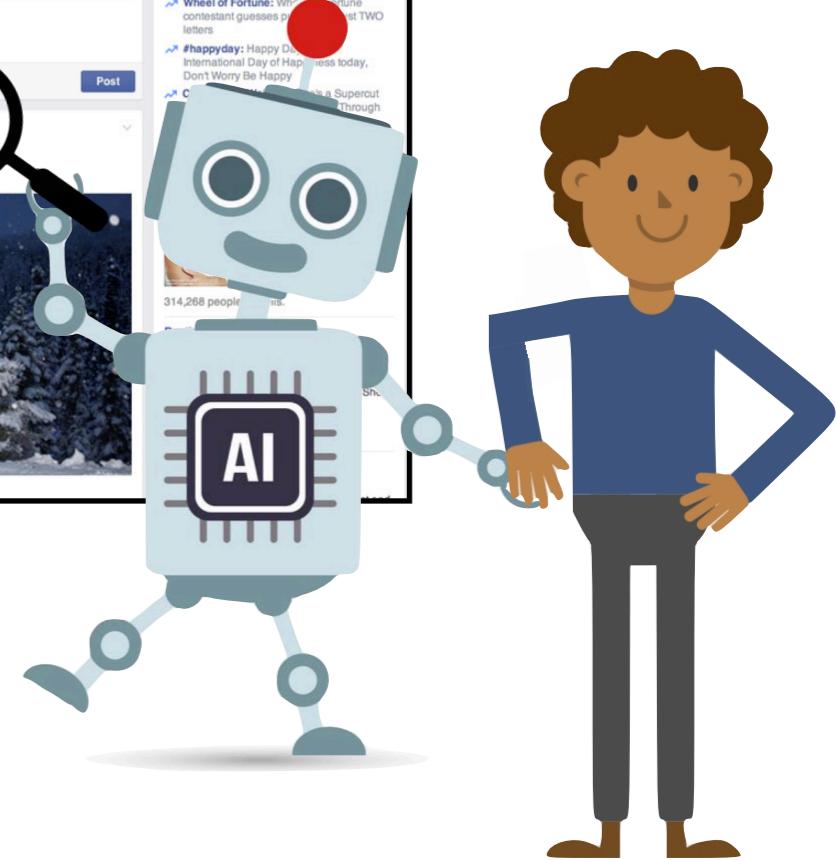
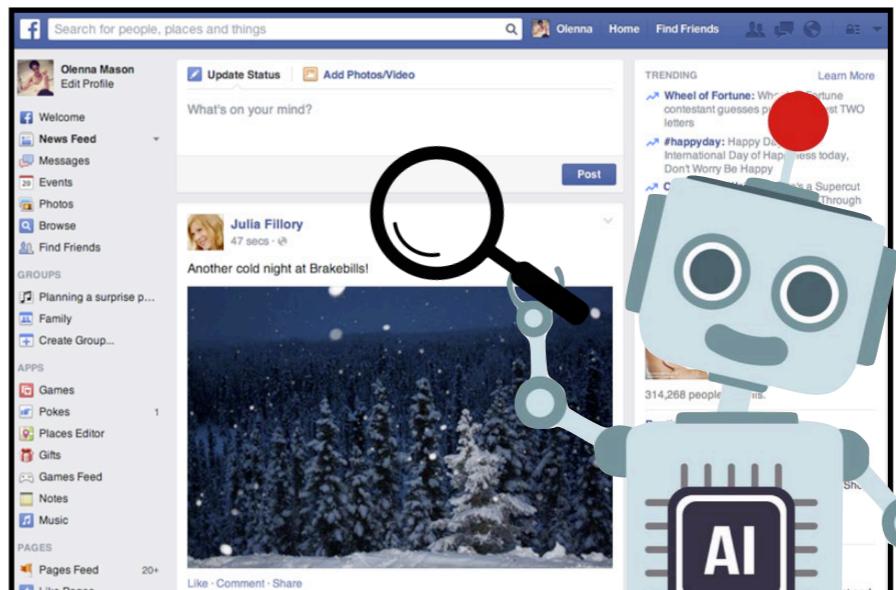
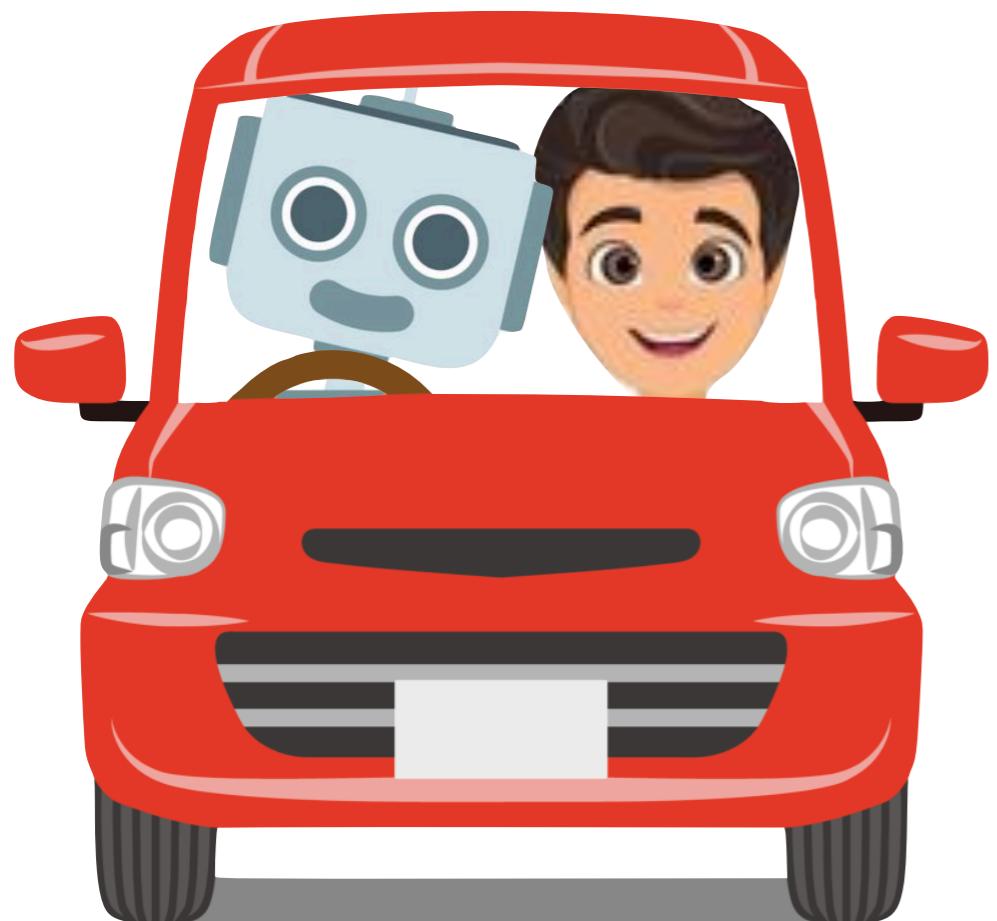


$e \sim P(e)$



?

expert



papers & code



funding provided by



co-authors



Rajeev
Verma



Daniel
Barrejón



Dharmesh
Tailor



Putra
Manggala



Aditya
Patra

Appendix

0-1 loss

$$\ell(r, h; \mathcal{D}) =$$

$$\sum_n (1 - r(x_n)) \mathbb{I}[h(x_n) \neq y_n] + r(x_n) \mathbb{I}[m_n \neq y_n]$$

classifier loss

expert loss

estimators

single expert

softmax:

$$\hat{p}(m = y | x) = \frac{h_{\perp}(x)}{1 - h_{\perp}(x)}$$

one-vs-all:

$$\hat{p}(m = y | x) = h_{\perp}(x)$$

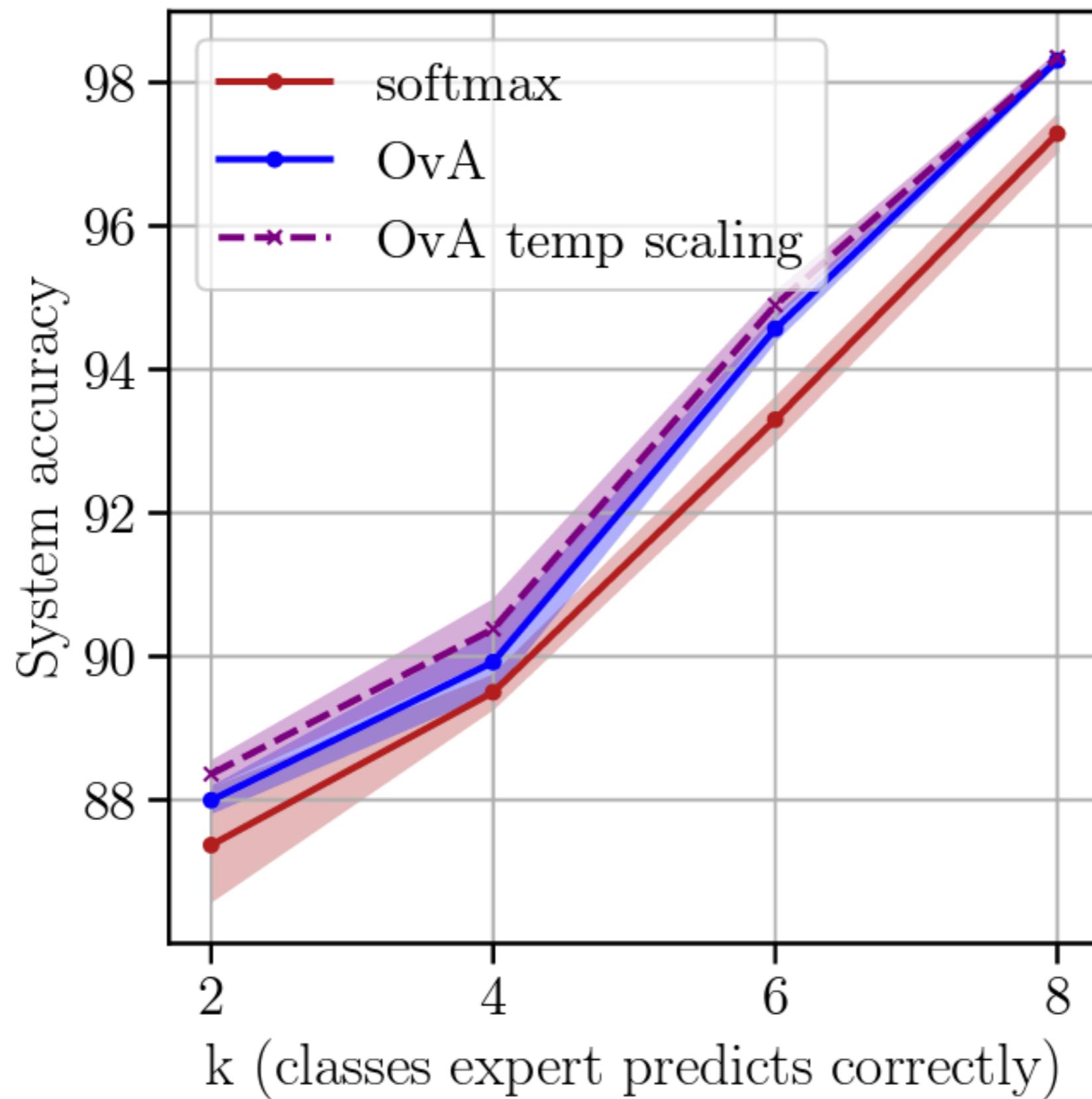
multi-expert

softmax:

$$\hat{p}(m_j = y | x) = \frac{h_{\perp,j}(x)}{1 - \sum_{e=1}^J h_{\perp,e}(x)}$$

one-vs-all:

$$\hat{p}(m_j = y | x) = h_{\perp,j}(x)$$

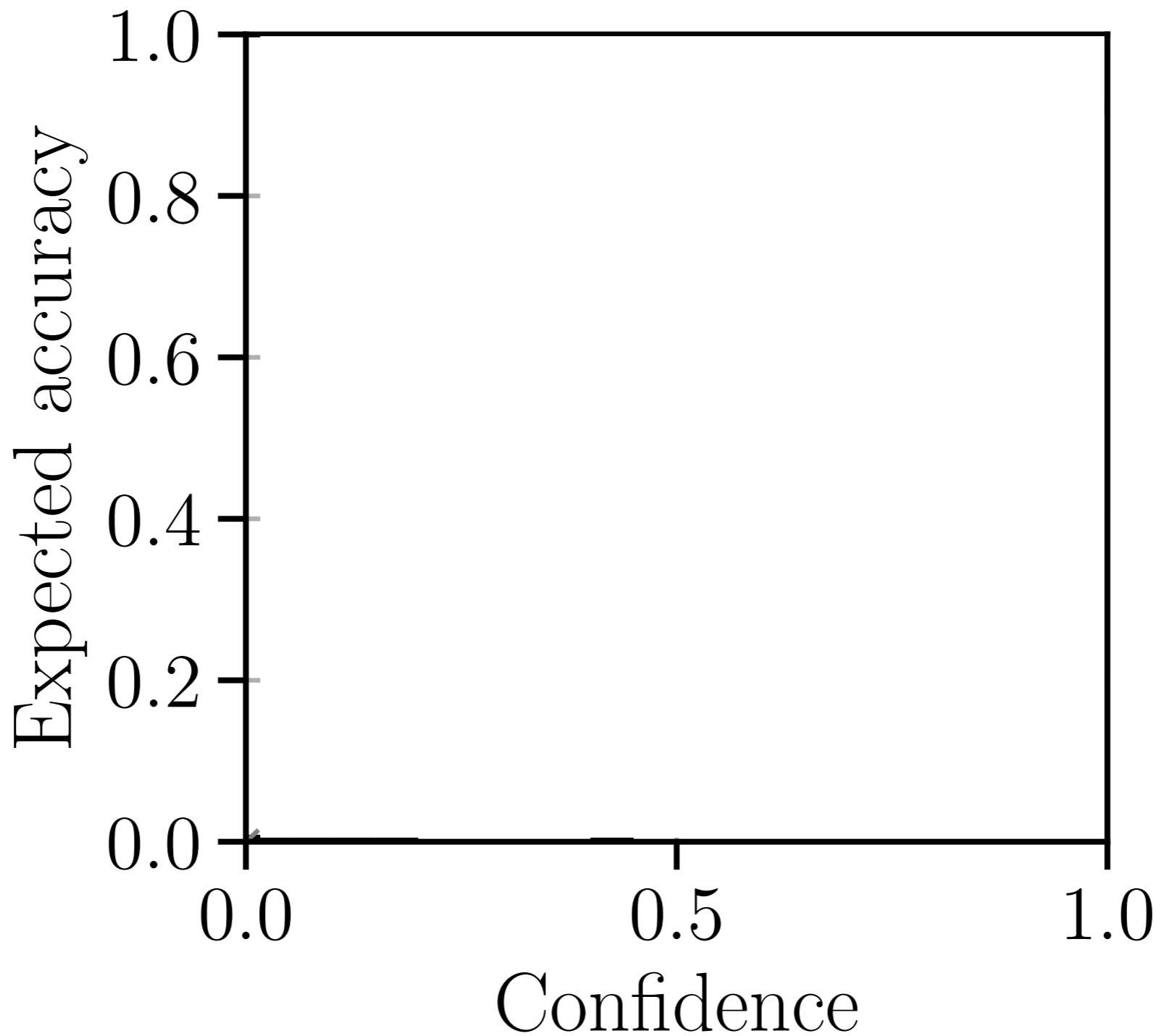


hate speech detection

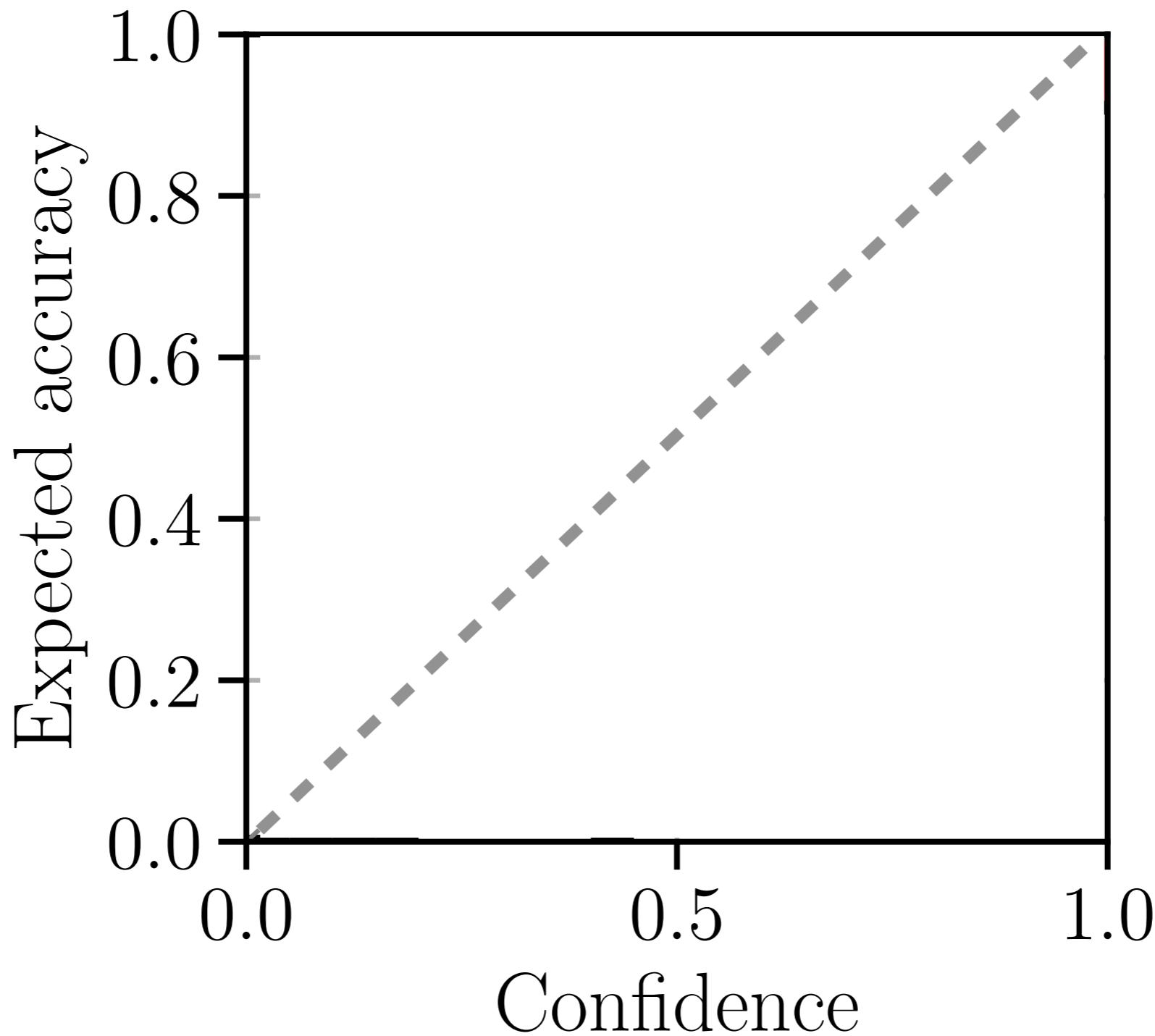


[Davidson et al., ICWSM 2017]

hate speech detection



hate speech detection



hate speech detection

softmax

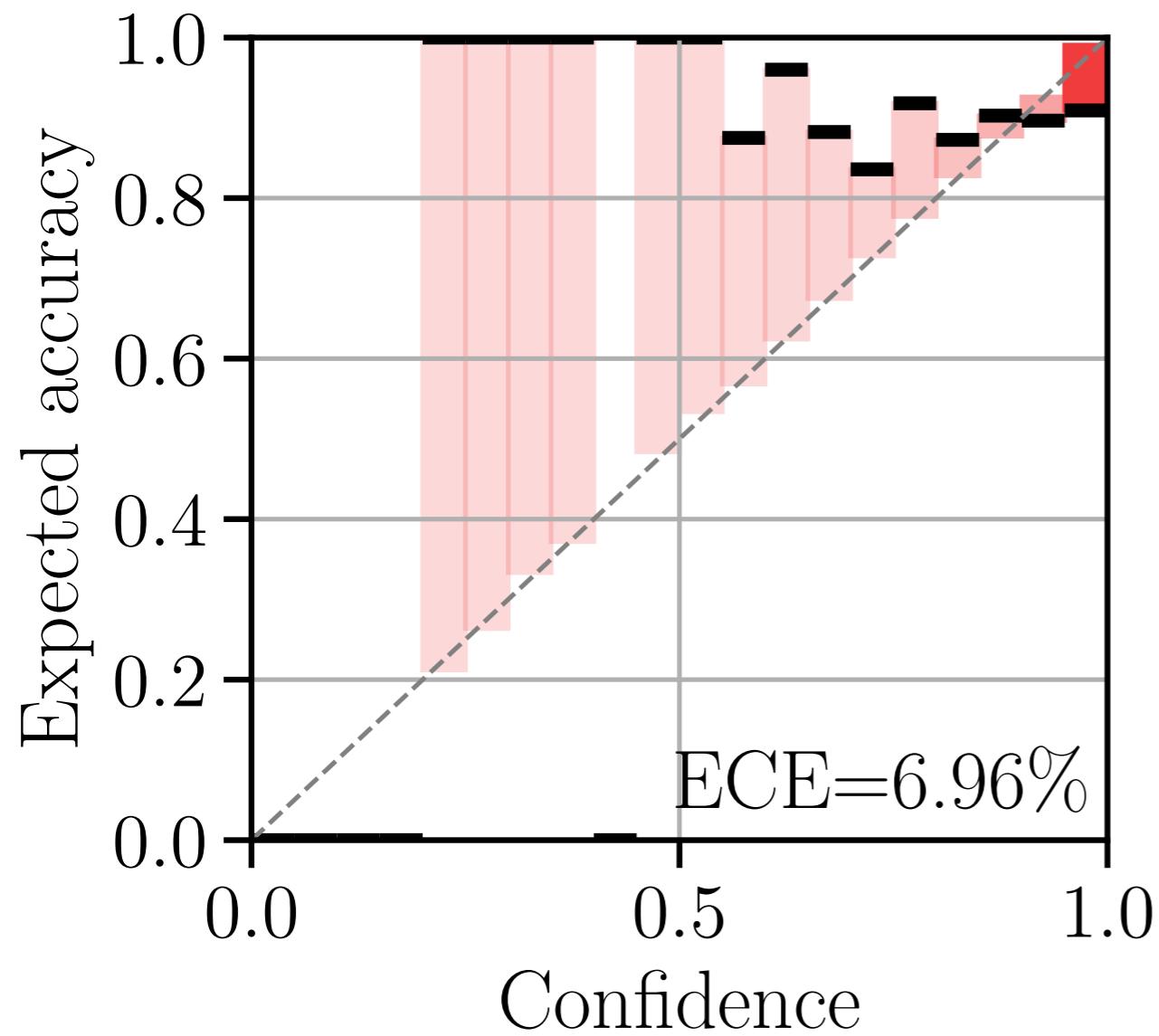
one-vs-all (ours)



hate speech detection

softmax

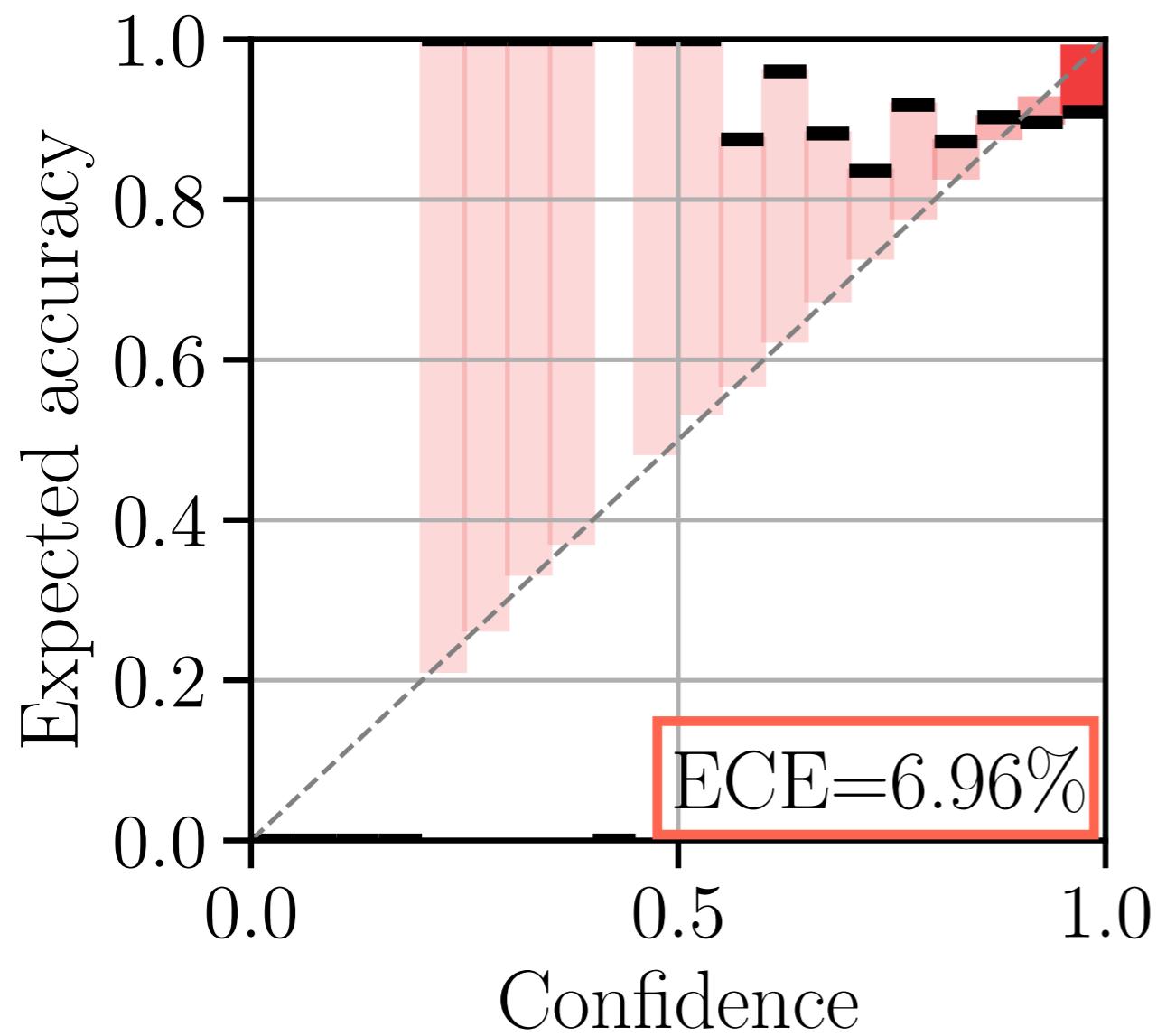
one-vs-all (ours)



hate speech detection

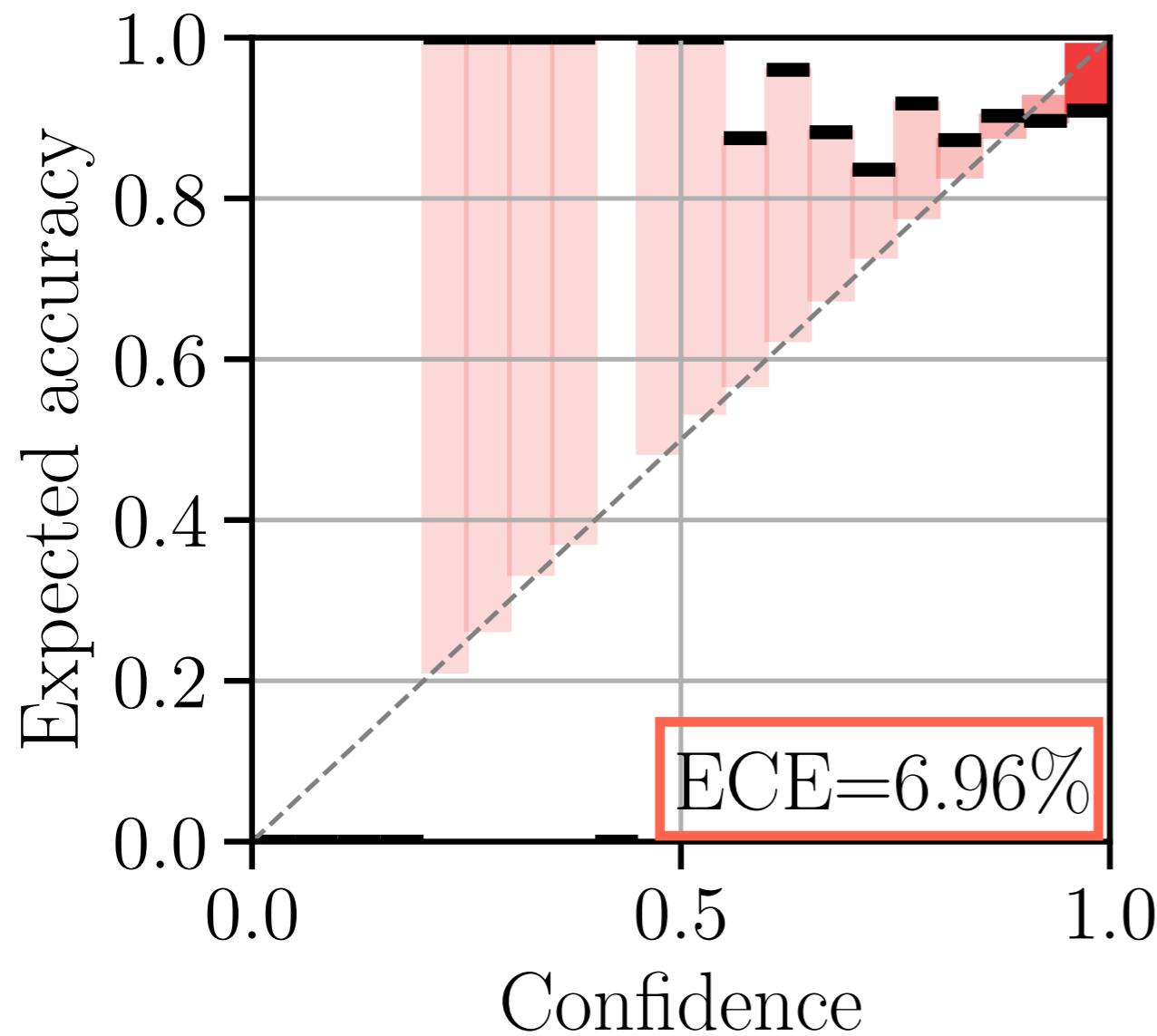
softmax

one-vs-all (ours)

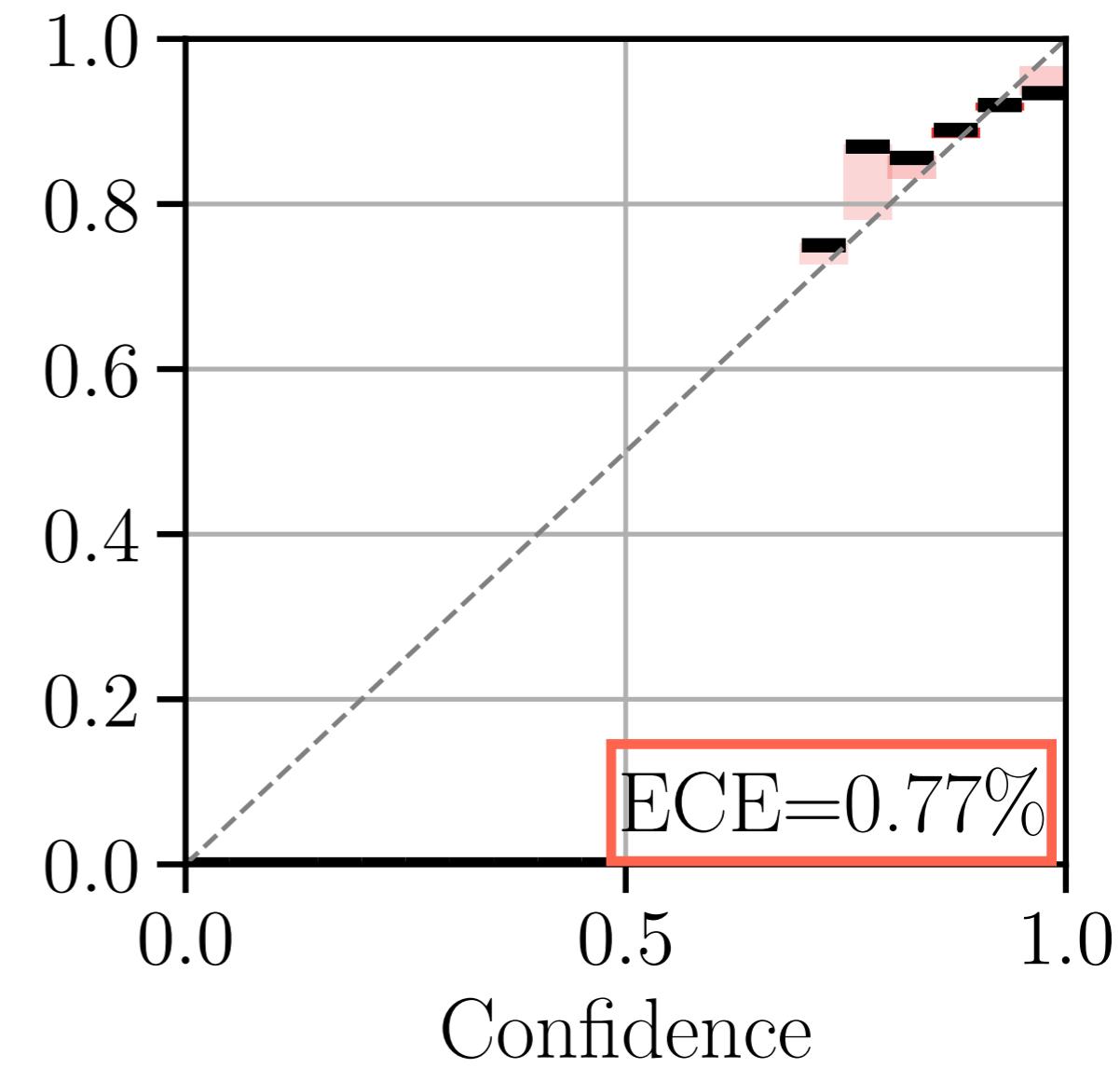


hate speech detection

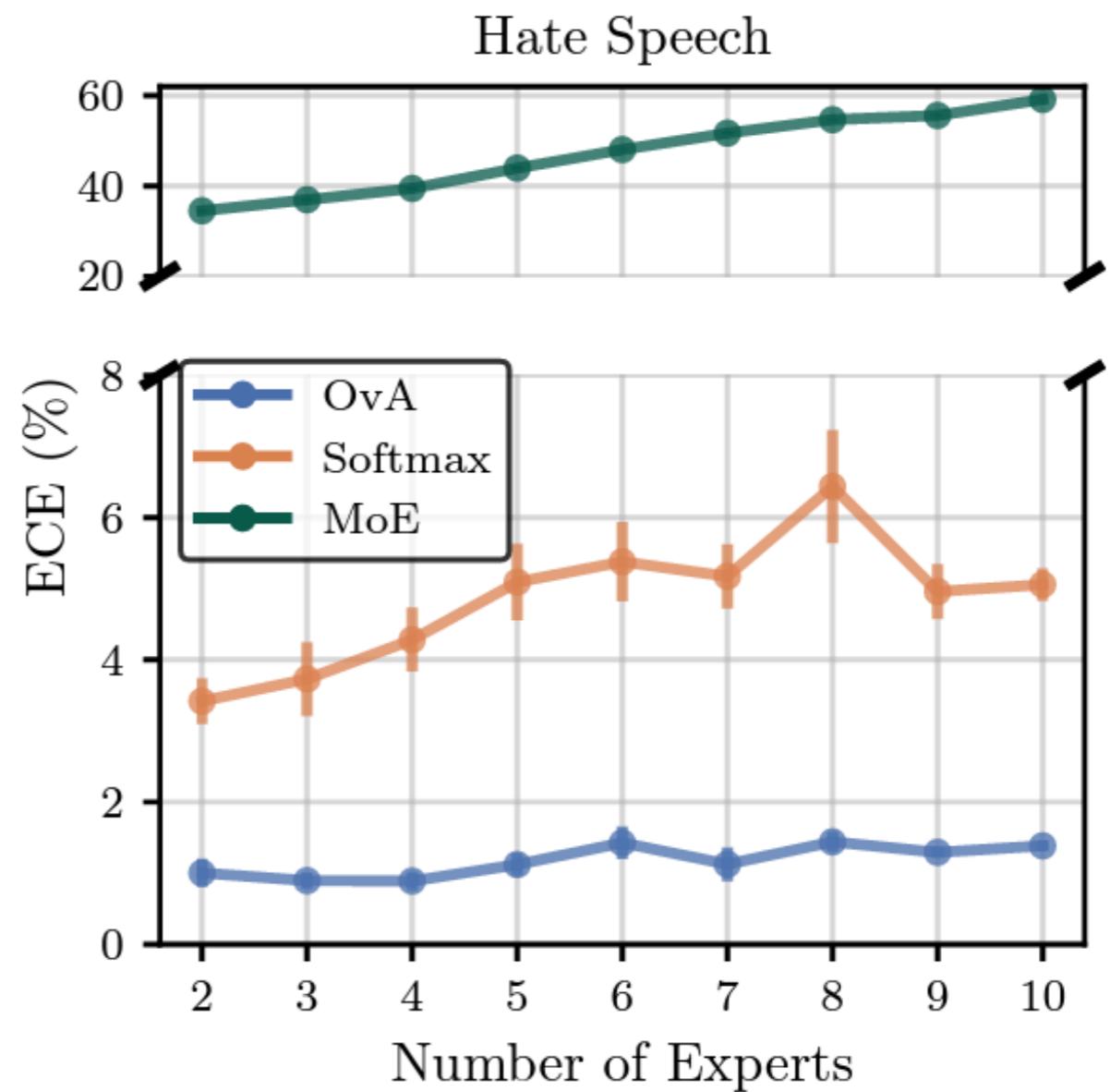
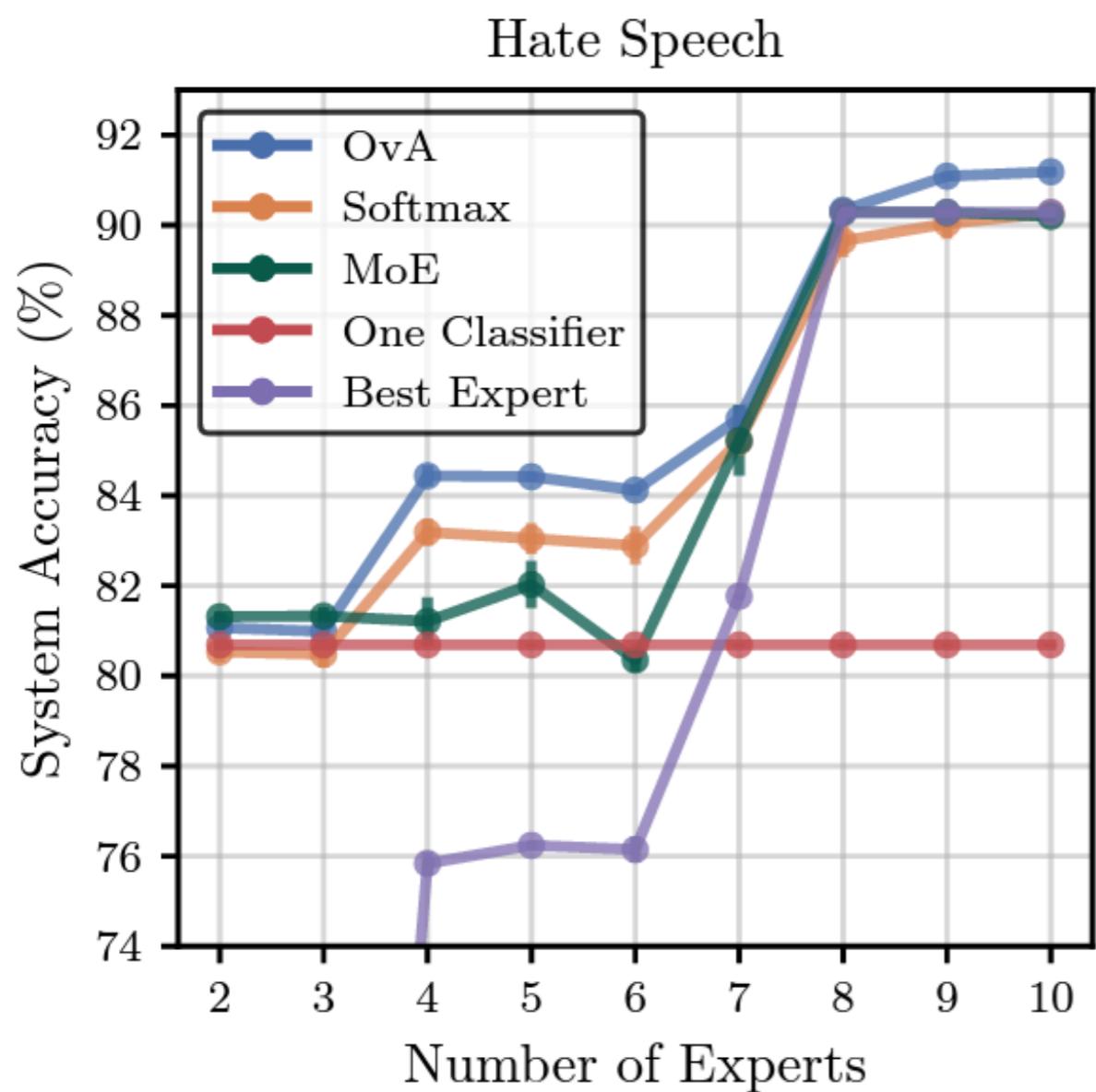
softmax



one-vs-all (ours)

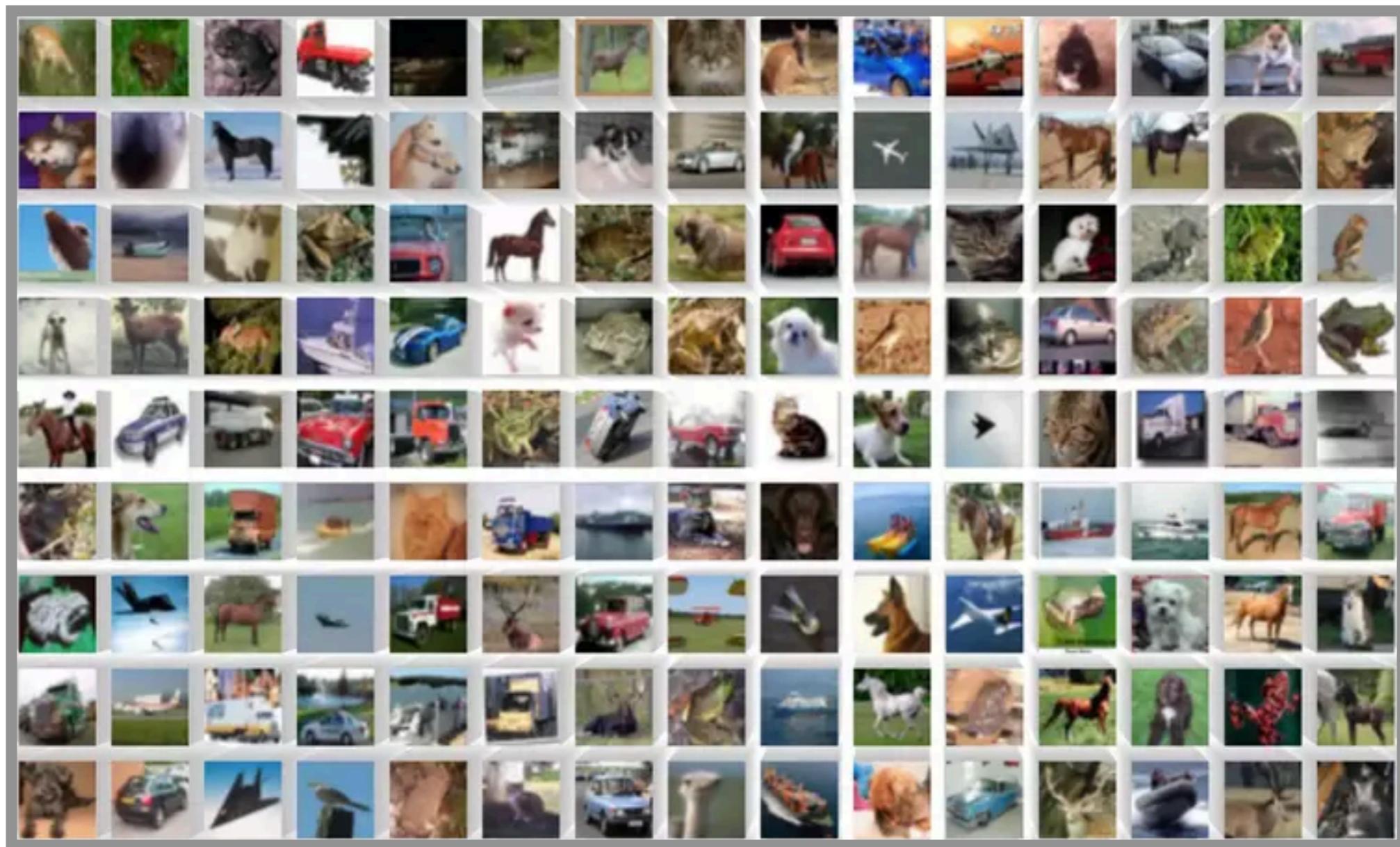


Gap Accuracy

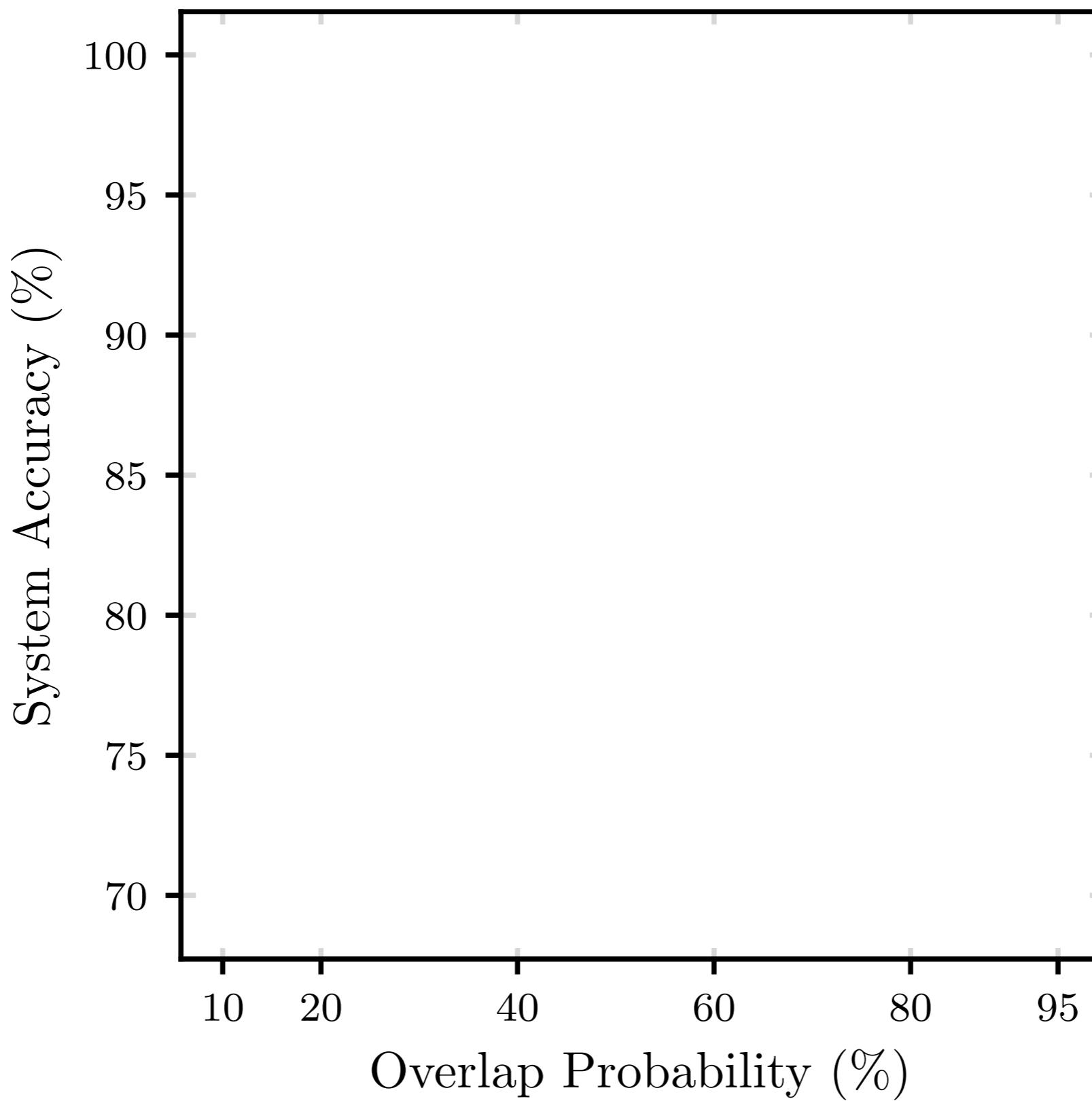


conformal: downstream performance

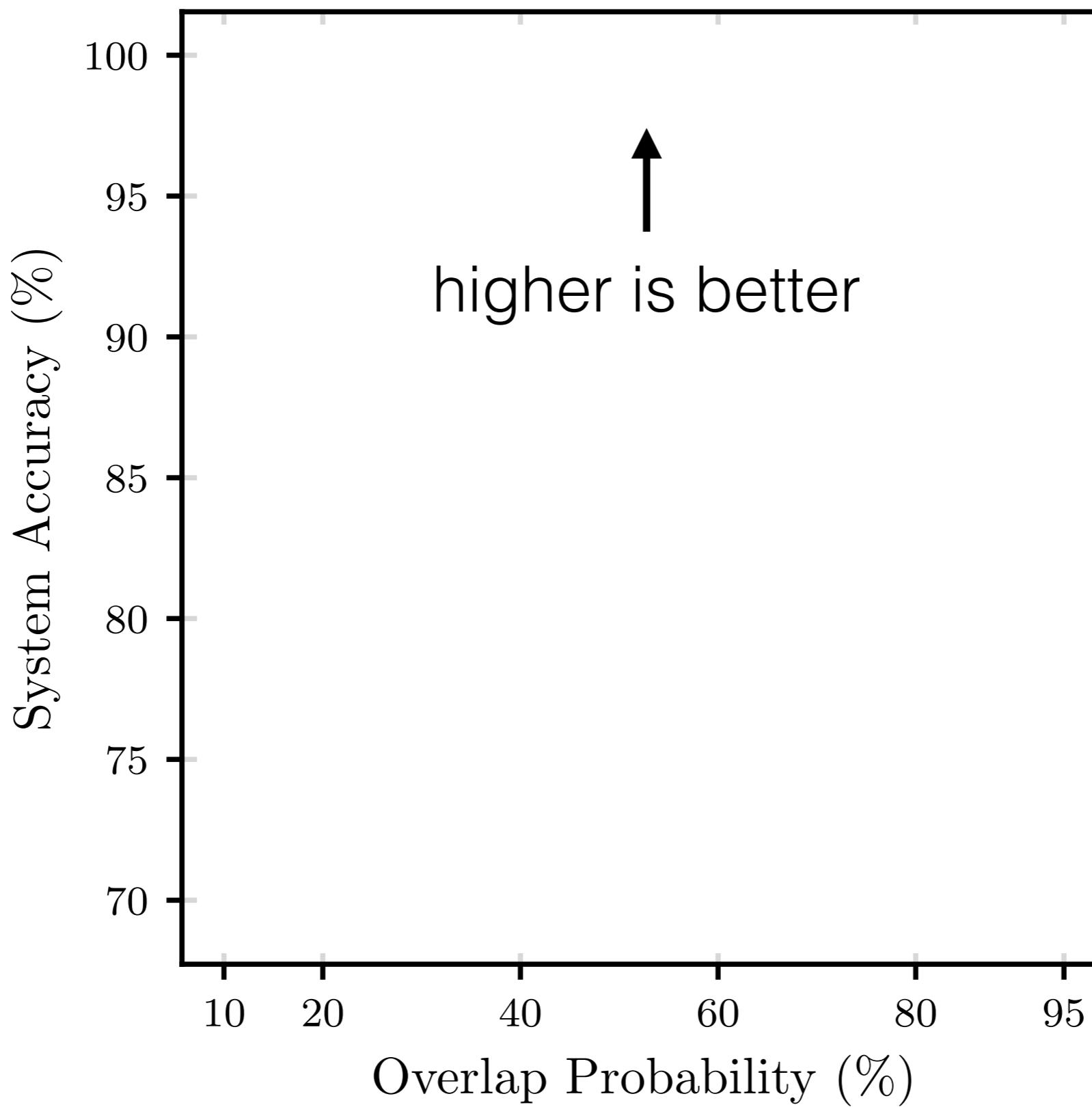
CIFAR-10



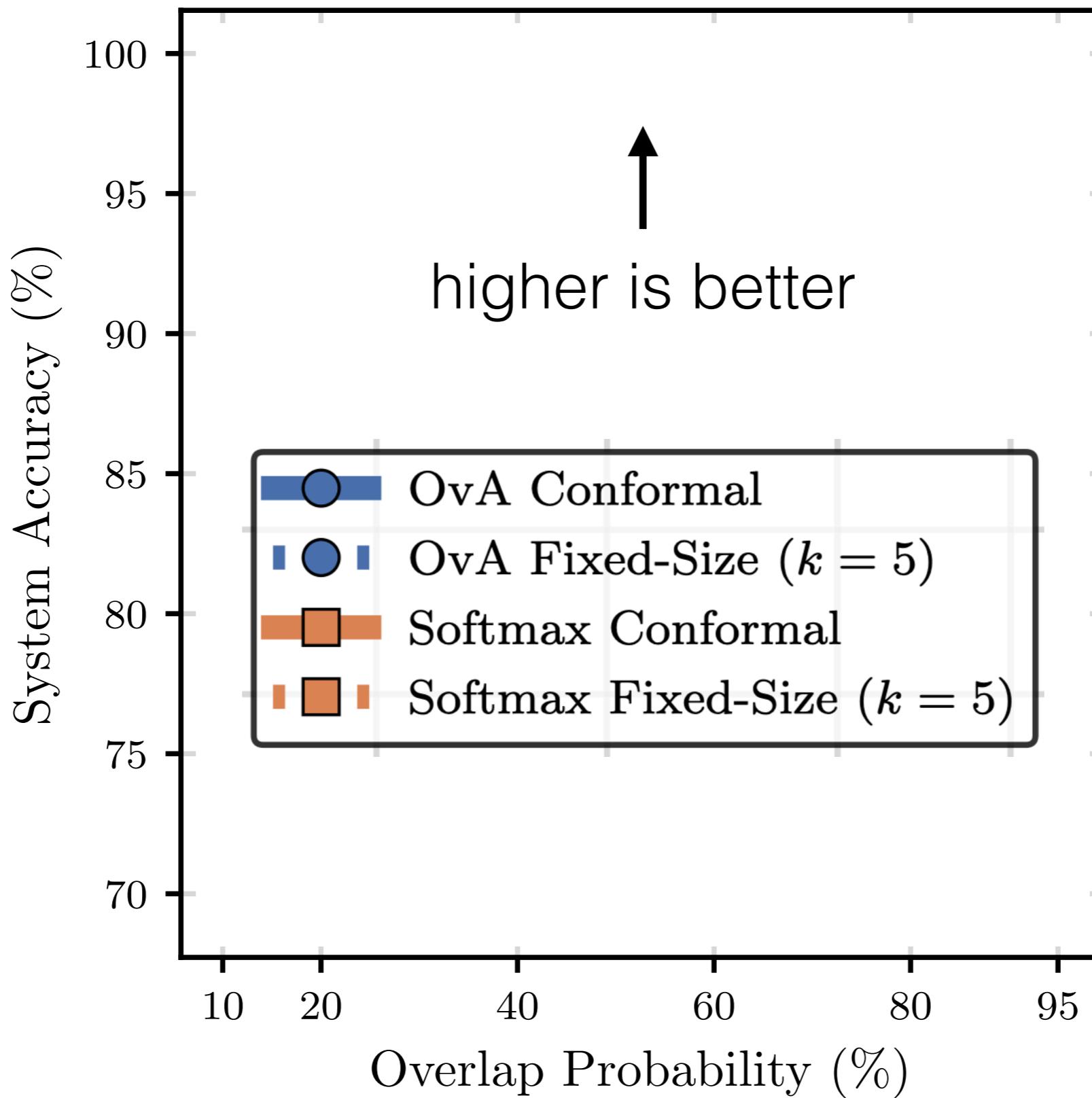
downstream performance



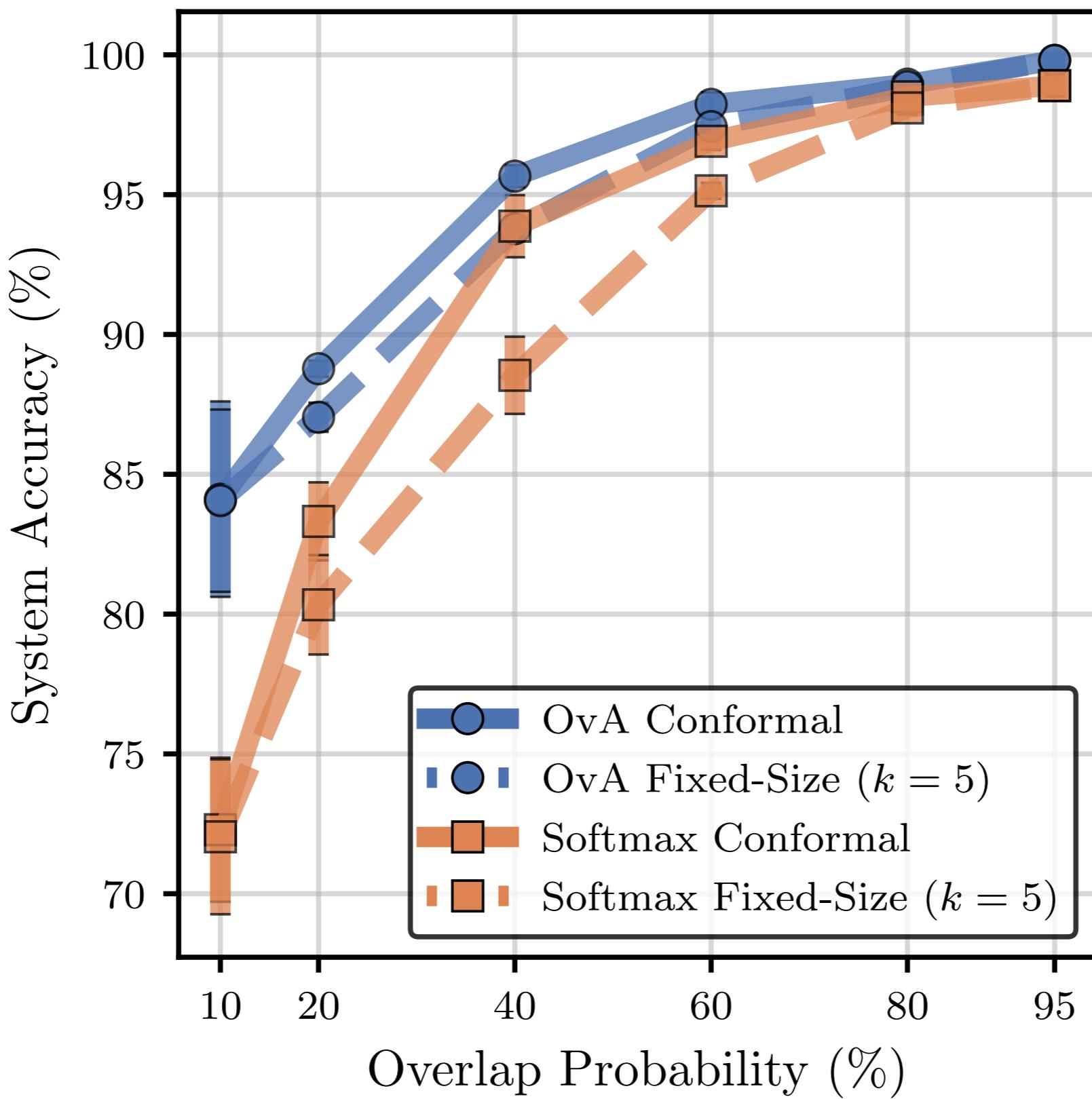
downstream performance



downstream performance



downstream performance



simulated experts:

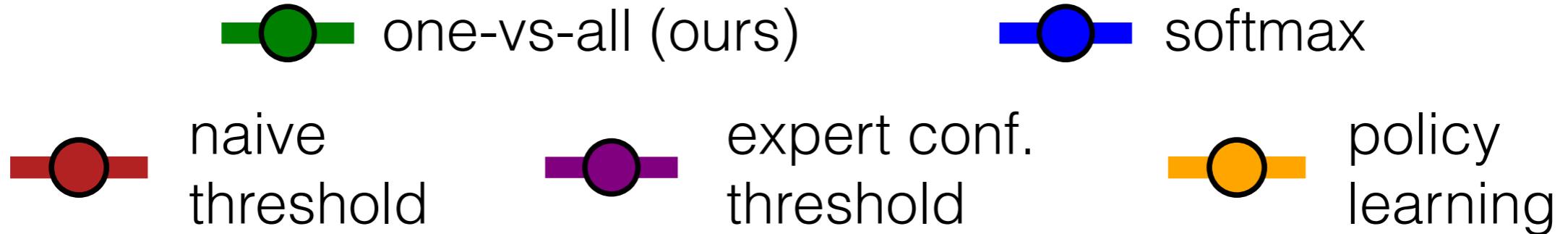
Table 2: HAM10000 experts configuration.

	Expert configuration	p_{in} [%]	p_{out} [%]	Diagnostic Category [in]
1	Random Expert	-	-	[nv, bkl, df, vasc, mel, bcc, akiec]
2	Dermatologist for malign	25	15	[mel, bcc, akiec]
3	Dermatologist for benign	25	15	[nv, bkl, df, vasc]
4	Specialized dermatologist in nv	50	15	[nv]
5	Specialized dermatologist in vasc	70	15	[vasc]
6	Specialized dermatologist in mel	75	15	[mel]
7	Dermatologist for benign	75	25	[nv, bkl, df, vasc]
8	MLP Mixer	-	-	[nv, bkl, df, vasc, mel, bcc, akiec]
9	Experienced dermatologist	80	50	[nv, bkl, df, vasc, mel, bcc, akiec]
10	Experienced dermatologist	80	60	[nv, bkl, df, vasc, mel, bcc, akiec]

simulated experts:

Table 1: Hate Speech and Galaxy-Zoo experts configuration.

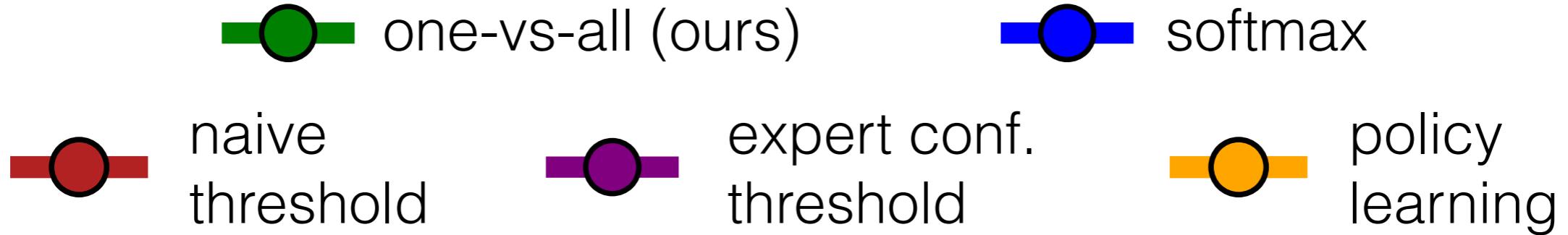
	Expert configuration	$p_{\text{flip}} [\%]$	$P_{\text{annotator}} [\%]$
1	Random Expert	-	-
2	Probabilistic Expert	-	10
3	Flipping Human Expert	50	-
4	Probabilistic Expert	-	75
5	Flipping Human Expert	30	-
6	Flipping Human Expert	20	-
7	Probabilistic Expert	-	85
8	Human Expert	-	-
9	Probabilistic Expert	-	50
10	Human Expert	-	-



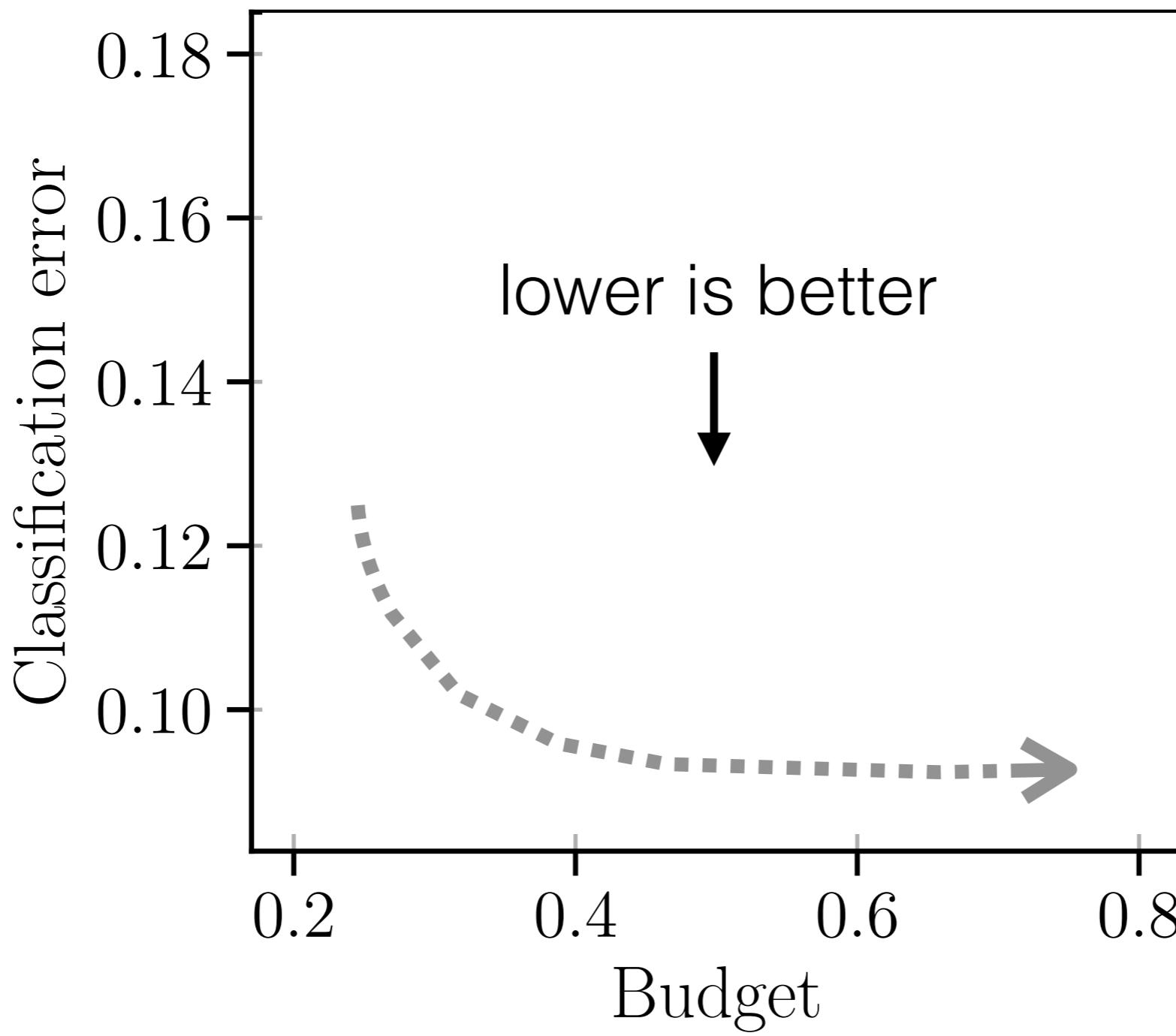
hate speech detection



[Davidson et al., ICWSM 2017]

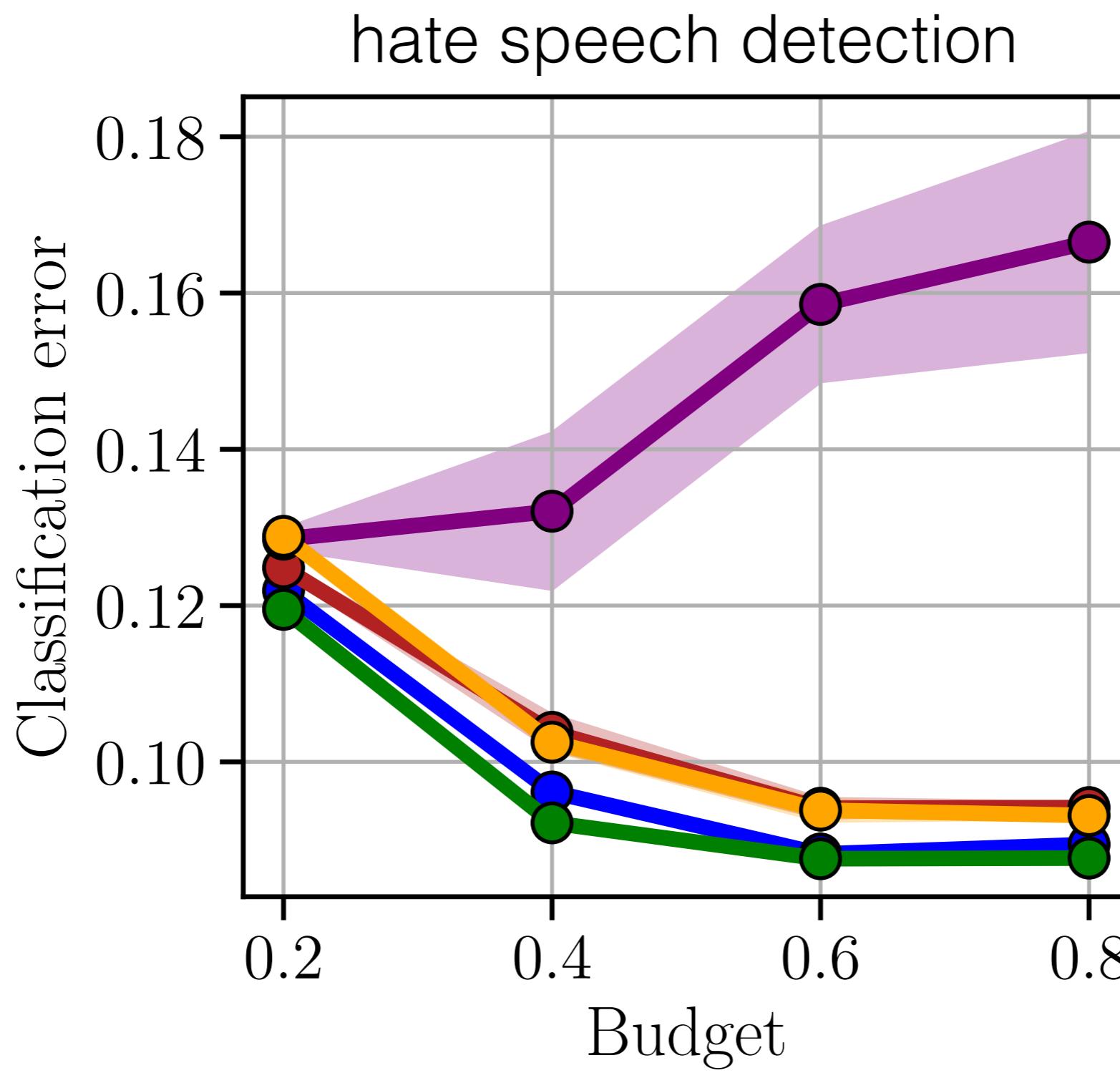


hate speech detection



one-vs-all (ours) softmax

naive threshold expert conf. threshold policy learning



conformal inference: train-time



expert #1



expert #2



expert #3

conformal inference: train-time



expert #1



expert #2



expert #3

$$h_{\perp,1}(x)$$

$$h_{\perp,2}(x)$$

$$h_{\perp,3}(x)$$

conformal inference: train-time



expert #1



expert #2



expert #3

$$h_{\perp,1}(x)$$

$$h_{\perp,2}(x)$$

$$h_{\perp,3}(x)$$

using validation data, compute the
(1- α)-quantile of a conformity statistic:

$$\hat{q}_{1-\alpha}$$

conformal inference: test-time



expert #1



expert #2



expert #3

$$h_{\perp,1}(x)$$

$$h_{\perp,2}(x)$$

$$h_{\perp,3}(x)$$

conformal inference: test-time



expert #3



expert #1



expert #2

$$h_{\perp,3}(x) > h_{\perp,1}(x) > h_{\perp,2}(x)$$

conformal inference: test-time



expert #3



expert #1



expert #2

$$h_{\perp,3}(x) > h_{\perp,1}(x) > h_{\perp,2}(x)$$

$$C(x) = \left\{ \quad \right.$$

check if:

$$\sum_{e \in C(x)} h_{\perp,e}(x) \stackrel{?}{\geq} \hat{q}_{1-\alpha}$$

conformal inference: test-time



expert #1



expert #2

$$h_{\perp,3}(x) > h_{\perp,1}(x) > h_{\perp,2}(x)$$

$$C(x) = \left\{ \begin{array}{c} \text{Illustration of a doctor holding a clipboard} \end{array} \right\}$$

check if:

$$h_{\perp,3} \stackrel{?}{\geq} \hat{q}_{1-\alpha}$$

conformal inference: test-time



expert #1



expert #2

$$h_{\perp,3}(x) > h_{\perp,1}(x) > h_{\perp,2}(x)$$

$$C(x) = \left\{ \begin{array}{c} \text{Illustration of a doctor holding a clipboard} \end{array} \right\}$$

check if:

$$h_{\perp,3} \overset{\text{X}}{\geq} \hat{q}_{1-\alpha}$$

conformal inference: test-time



$$h_{\perp,3}(x) > h_{\perp,1}(x) > h_{\perp,2}(x)$$

$$C(x) = \left\{ \begin{array}{c} \text{Illustration of a doctor holding a clipboard} \\ , \\ \text{Illustration of a female doctor gesturing} \end{array} \right\}$$

check if:

$$h_{\perp,3} + h_{\perp,1} \stackrel{?}{\geq} \hat{q}_{1-\alpha}$$

conformal inference: test-time



$$h_{\perp,3}(x) > h_{\perp,1}(x) > h_{\perp,2}(x)$$

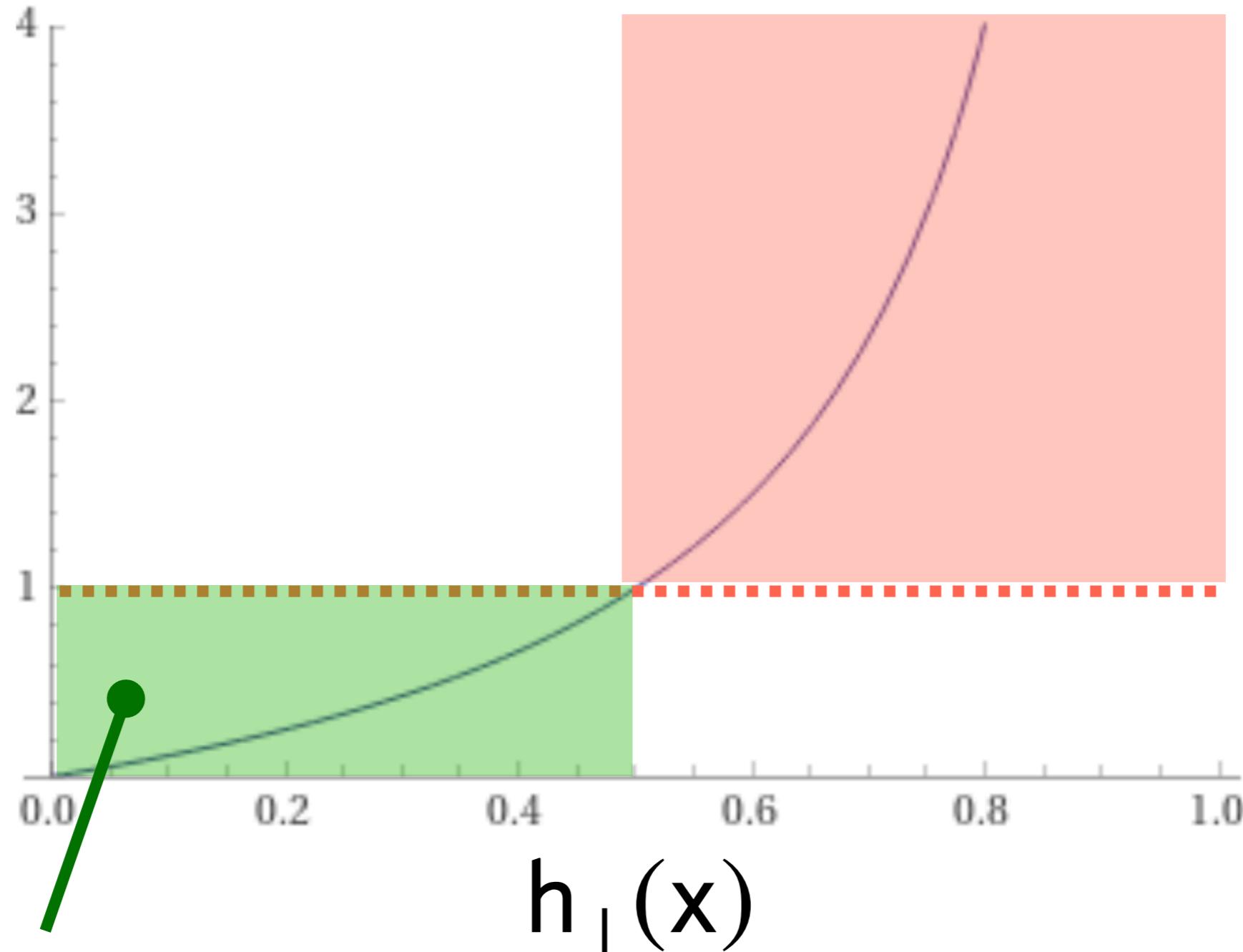
$$C(x) = \left\{ \begin{array}{c} \text{Illustration of a doctor holding a clipboard} \\ , \\ \text{Illustration of a female doctor gesturing} \end{array} \right\}$$

check if:

$$h_{\perp,3} + h_{\perp,1} \geq \hat{q}_{1-\alpha}$$
A green checkmark indicating that the condition has been met.

Estimating $P(m = y | x)$

$\hat{p}(m = y | x)$



valid confidences