



Minimization of a Functional on the Space of BV Functions and Nonconforming Discretization of the Problem

I. Theoretical Basics and Characterization of Minimizers

Enrico Bergmann

Humboldt-Universität zu Berlin

January 6, 2021

Table of Contents

① Introduction

② Continuous Problem

Existence of Minimizers

Uniqueness and Stability

③ Discrete Problem

Equivalent Saddle Point Problem

Characterization of Minimizers

④ Outlook

Table of Contents

1 Introduction

2 Continuous Problem

Existence of Minimizers

Uniqueness and Stability

3 Discrete Problem

Equivalent Saddle Point Problem

Characterization of Minimizers

4 Outlook

Sören Bartels. **Numerical Methods for Nonlinear Partial Differential Equations.** Vol. 47. Springer Series in Computational Mathematics. Springer International Publishing, 2015. ISBN: 978-3-319-13796-4. DOI: 10.1007/978-3-319-13797-1, Chapter 10, p. 297-319

Sören Bartels. **Numerical Methods for Nonlinear Partial Differential Equations**. Vol. 47. Springer Series in Computational Mathematics. Springer International Publishing, 2015. ISBN: 978-3-319-13796-4. DOI: 10.1007/978-3-319-13797-1, Chapter 10, p. 297-319

Let $\Omega \subset \mathbb{R}^n$ be a bounded polyhedral Lipschitz domain.

For given $g \in L^2(\Omega)$ and $\alpha > 0$ minimize the functional

$$I(v) = |v|_{\text{BV}(\Omega)} + \frac{\alpha}{2} \|v - g\|^2$$

amongst all $v \in \text{BV}(\Omega) \cap L^2(\Omega)$.

Functions of Bounded Variation

A function $v \in L^1(\Omega)$ with distributional derivative $Dv : C_c^\infty(\Omega; \mathbb{R}^n) \rightarrow \mathbb{R}$ is said to be of bounded variation if there exists $c > 0$ such that

$$\langle Dv, \phi \rangle := - \int_{\Omega} v \operatorname{div}(\phi) \, dx \leq c \|\phi\|_{L^\infty(\Omega)}$$

for all $\phi \in C_c^1(\Omega; \mathbb{R}^n)$.

Functions of Bounded Variation

A function $v \in L^1(\Omega)$ with distributional derivative $Dv : C_c^\infty(\Omega; \mathbb{R}^n) \rightarrow \mathbb{R}$ is said to be of bounded variation if there exists $c > 0$ such that

$$\langle Dv, \phi \rangle := - \int_{\Omega} v \operatorname{div}(\phi) \, dx \leq c \|\phi\|_{L^\infty(\Omega)}$$

for all $\phi \in C_c^1(\Omega; \mathbb{R}^n)$.

The minimal constant $c \geq 0$ satisfying this property is called total variation of Dv and is given by

$$|v|_{\operatorname{BV}(\Omega)} = \sup_{\substack{\phi \in C_c^1(\Omega; \mathbb{R}^n) \\ \|\phi\|_{L^\infty(\Omega)} \leq 1}} - \int_{\Omega} v \operatorname{div}(\phi) \, dx.$$

Functions of Bounded Variation

A function $v \in L^1(\Omega)$ with distributional derivative $Dv : C_c^\infty(\Omega; \mathbb{R}^n) \rightarrow \mathbb{R}$ is said to be of bounded variation if there exists $c > 0$ such that

$$\langle Dv, \phi \rangle := - \int_{\Omega} v \operatorname{div}(\phi) \, dx \leq c \|\phi\|_{L^\infty(\Omega)}$$

for all $\phi \in C_c^1(\Omega; \mathbb{R}^n)$.

The minimal constant $c \geq 0$ satisfying this property is called total variation of Dv and is given by

$$|v|_{\operatorname{BV}(\Omega)} = \sup_{\substack{\phi \in C_c^1(\Omega; \mathbb{R}^n) \\ \|\phi\|_{L^\infty(\Omega)} \leq 1}} - \int_{\Omega} v \operatorname{div}(\phi) \, dx.$$

The space of all such functions is denoted by $\operatorname{BV}(\Omega)$.

Properties of $BV(\Omega)$

$BV(\Omega)$ is a nonseparable Banach space equipped with the norm

$$\|v\|_{BV(\Omega)} := \|v\|_{L^1(\Omega)} + |v|_{BV(\Omega)} \quad \text{for all } v \in BV(\Omega).$$

Properties of $BV(\Omega)$

$BV(\Omega)$ is a nonseparable Banach space equipped with the norm

$$\|v\|_{BV(\Omega)} := \|v\|_{L^1(\Omega)} + |v|_{BV(\Omega)} \quad \text{for all } v \in BV(\Omega).$$

$W^{1,1}(\Omega) \subset BV(\Omega)$ with $\|v\|_{BV(\Omega)} = \|v\|_{W^{1,1}(\Omega)}$ for all $v \in W^{1,1}(\Omega)$.

Notions of convergence on $BV(\Omega)$

Let $(v_n)_{n \in \mathbb{N}} \subset BV(\Omega)$ and $v \in BV(\Omega)$ such that $v_n \rightarrow v$ in $L^1(\Omega)$ as $n \rightarrow \infty$.

- (i) $(v_n)_{n \in \mathbb{N}}$ converges intermediately or strictly to v if $|v_n|_{BV(\Omega)} \rightarrow |v|_{BV(\Omega)}$ as $n \rightarrow \infty$.

Notions of convergence on $BV(\Omega)$

Let $(v_n)_{n \in \mathbb{N}} \subset BV(\Omega)$ and $v \in BV(\Omega)$ such that $v_n \rightarrow v$ in $L^1(\Omega)$ as $n \rightarrow \infty$.

- (i) $(v_n)_{n \in \mathbb{N}}$ converges intermediately or strictly to v if $|v_n|_{BV(\Omega)} \rightarrow |v|_{BV(\Omega)}$ as $n \rightarrow \infty$.
- (ii) $(v_n)_{n \in \mathbb{N}}$ converges weakly to v if $\langle Dv_n, \phi \rangle \rightarrow \langle Dv, \phi \rangle$ for all $\phi \in C_0(\Omega; \mathbb{R}^n)$ as $n \rightarrow \infty$.

Further Properties of $BV(\Omega)$

$C^\infty(\overline{\Omega})$ and $C^\infty(\Omega) \cap BV(\Omega)$ are dense in $BV(\Omega)$ with respect to intermediate convergence.

Further Properties of $BV(\Omega)$

$C^\infty(\overline{\Omega})$ and $C^\infty(\Omega) \cap BV(\Omega)$ are dense in $BV(\Omega)$ with respect to intermediate convergence.

The embedding $BV(\Omega) \rightarrow L^p(\Omega)$ is continuous for $1 \leq p \leq n/(n-1)$ and compact for $1 \leq p < n/(n-1)$

Further Properties of $BV(\Omega)$

$C^\infty(\overline{\Omega})$ and $C^\infty(\Omega) \cap BV(\Omega)$ are dense in $BV(\Omega)$ with respect to intermediate convergence.

The embedding $BV(\Omega) \rightarrow L^p(\Omega)$ is continuous for $1 \leq p \leq n/(n-1)$ and compact for $1 \leq p < n/(n-1)$

There exists a linear operator $T : BV(\Omega) \rightarrow L^1(\partial\Omega)$ such that $T(v) = v|_{\partial\Omega}$ for all $v \in BV(\Omega) \cap C(\overline{\Omega})$.

T is continuous with respect to intermediate convergence in $BV(\Omega)$ but not with respect to weak convergence in $BV(\Omega)$.

Table of Contents

1 Introduction

2 Continuous Problem

Existence of Minimizers

Uniqueness and Stability

3 Discrete Problem

Equivalent Saddle Point Problem

Characterization of Minimizers

4 Outlook

For given $f \in L^2(\Omega)$ and $\alpha > 0$ minimize the functional

$$E(v) := \frac{\alpha}{2} \|v\|_{L^2(\Omega)}^2 + |v|_{\text{BV}(\Omega)} + \|v\|_{L^1(\partial\Omega)} - \int_{\Omega} f v \, dx$$

amongst all $v \in \text{BV}(\Omega) \cap L^2(\Omega)$.

For given $f \in L^2(\Omega)$ and $\alpha > 0$ minimize the functional

$$E(v) := \frac{\alpha}{2} \|v\|_{L^2(\Omega)}^2 + |v|_{\text{BV}(\Omega)} + \|v\|_{L^1(\partial\Omega)} - \int_{\Omega} f v \, dx$$

amongst all $v \in \text{BV}(\Omega) \cap L^2(\Omega)$.

For $f = \alpha g$ we have

$$I(v) = |v|_{\text{BV}(\Omega)} + \frac{\alpha}{2} \|v - g\|^2 = E(v) - \|v\|_{L^1(\partial\Omega)} + \frac{\alpha}{2} \|g\|_{L^2(\Omega)}^2$$

for all $v \in \text{BV}(\Omega) \cap L^2(\Omega)$.

For given $f \in L^2(\Omega)$ and $\alpha > 0$ minimize the functional

$$E(v) := \frac{\alpha}{2} \|v\|_{L^2(\Omega)}^2 + |v|_{\text{BV}(\Omega)} + \|v\|_{L^1(\partial\Omega)} - \int_{\Omega} f v \, dx$$

amongst all $v \in \text{BV}(\Omega) \cap L^2(\Omega)$.

For $f = \alpha g$ we have

$$I(v) = |v|_{\text{BV}(\Omega)} + \frac{\alpha}{2} \|v - g\|^2 = E(v) - \|v\|_{L^1(\partial\Omega)} + \frac{\alpha}{2} \|g\|_{L^2(\Omega)}^2$$

for all $v \in \text{BV}(\Omega) \cap L^2(\Omega)$.

I and E have the same minimizers in
 $\{v \in \text{BV}(\Omega) \cap L^2(\Omega) \mid \|v\|_{L^1(\partial\Omega)} = 0\}.$

Table of Contents

1 Introduction

2 Continuous Problem

Existence of Minimizers

Uniqueness and Stability

3 Discrete Problem

Equivalent Saddle Point Problem

Characterization of Minimizers

4 Outlook

$$E(v) = \frac{\alpha}{2} \|v\|_{L^2(\Omega)}^2 + |v|_{\text{BV}(\Omega)} + \|v\|_{L^1(\partial\Omega)} - \int_{\Omega} f v \, dx$$

$$\begin{aligned}
E(v) &= \frac{\alpha}{2} \|v\|_{L^2(\Omega)}^2 + |v|_{\text{BV}(\Omega)} + \|v\|_{L^1(\partial\Omega)} - \int_{\Omega} f v \, dx \\
&\geq \frac{\alpha}{2} \|v\|_{L^2(\Omega)}^2 + |v|_{\text{BV}(\Omega)} + \|v\|_{L^1(\partial\Omega)} - \|f\|_{L^2(\Omega)} \|v\|_{L^2(\Omega)}
\end{aligned}$$

$$\begin{aligned}
E(v) &= \frac{\alpha}{2} \|v\|_{L^2(\Omega)}^2 + |v|_{\text{BV}(\Omega)} + \|v\|_{L^1(\partial\Omega)} - \int_{\Omega} f v \, dx \\
&\geq \frac{\alpha}{2} \|v\|_{L^2(\Omega)}^2 + |v|_{\text{BV}(\Omega)} + \|v\|_{L^1(\partial\Omega)} - \|f\|_{L^2(\Omega)} \|v\|_{L^2(\Omega)} \\
&\geq \frac{\alpha}{2} \|v\|_{L^2(\Omega)}^2 + |v|_{\text{BV}(\Omega)} + \|v\|_{L^1(\partial\Omega)} - \frac{1}{\alpha} \|f\|_{L^2(\Omega)}^2 - \frac{\alpha}{4} \|v\|_{L^2(\Omega)}^2
\end{aligned}$$

$$\begin{aligned}
E(v) &= \frac{\alpha}{2} \|v\|_{L^2(\Omega)}^2 + |v|_{\text{BV}(\Omega)} + \|v\|_{L^1(\partial\Omega)} - \int_{\Omega} f v \, dx \\
&\geq \frac{\alpha}{2} \|v\|_{L^2(\Omega)}^2 + |v|_{\text{BV}(\Omega)} + \|v\|_{L^1(\partial\Omega)} - \|f\|_{L^2(\Omega)} \|v\|_{L^2(\Omega)} \\
&\geq \frac{\alpha}{2} \|v\|_{L^2(\Omega)}^2 + |v|_{\text{BV}(\Omega)} + \|v\|_{L^1(\partial\Omega)} - \frac{1}{\alpha} \|f\|_{L^2(\Omega)}^2 - \frac{\alpha}{4} \|v\|_{L^2(\Omega)}^2 \\
&\geq \frac{\alpha}{4} \|v\|_{L^2(\Omega)}^2 + |v|_{\text{BV}(\Omega)} + \|v\|_{L^1(\partial\Omega)} - \frac{1}{\alpha} \|f\|_{L^2(\Omega)}^2
\end{aligned}$$

$$\begin{aligned}
E(v) &= \frac{\alpha}{2} \|v\|_{L^2(\Omega)}^2 + |v|_{\text{BV}(\Omega)} + \|v\|_{L^1(\partial\Omega)} - \int_{\Omega} f v \, dx \\
&\geq \frac{\alpha}{2} \|v\|_{L^2(\Omega)}^2 + |v|_{\text{BV}(\Omega)} + \|v\|_{L^1(\partial\Omega)} - \|f\|_{L^2(\Omega)} \|v\|_{L^2(\Omega)} \\
&\geq \frac{\alpha}{2} \|v\|_{L^2(\Omega)}^2 + |v|_{\text{BV}(\Omega)} + \|v\|_{L^1(\partial\Omega)} - \frac{1}{\alpha} \|f\|_{L^2(\Omega)}^2 - \frac{\alpha}{4} \|v\|_{L^2(\Omega)}^2 \\
&\geq \frac{\alpha}{4} \|v\|_{L^2(\Omega)}^2 + |v|_{\text{BV}(\Omega)} + \|v\|_{L^1(\partial\Omega)} - \frac{1}{\alpha} \|f\|_{L^2(\Omega)}^2 \\
&\geq \frac{\alpha}{4|\Omega|} \|v\|_{L^1(\Omega)}^2 + |v|_{\text{BV}(\Omega)} + \|v\|_{L^1(\partial\Omega)} - \frac{1}{\alpha} \|f\|_{L^2(\Omega)}^2
\end{aligned}$$

$$\begin{aligned}
E(v) &= \frac{\alpha}{2} \|v\|_{L^2(\Omega)}^2 + |v|_{\text{BV}(\Omega)} + \|v\|_{L^1(\partial\Omega)} - \int_{\Omega} f v \, dx \\
&\geq \frac{\alpha}{2} \|v\|_{L^2(\Omega)}^2 + |v|_{\text{BV}(\Omega)} + \|v\|_{L^1(\partial\Omega)} - \|f\|_{L^2(\Omega)} \|v\|_{L^2(\Omega)} \\
&\geq \frac{\alpha}{2} \|v\|_{L^2(\Omega)}^2 + |v|_{\text{BV}(\Omega)} + \|v\|_{L^1(\partial\Omega)} - \frac{1}{\alpha} \|f\|_{L^2(\Omega)}^2 - \frac{\alpha}{4} \|v\|_{L^2(\Omega)}^2 \\
&\geq \frac{\alpha}{4} \|v\|_{L^2(\Omega)}^2 + |v|_{\text{BV}(\Omega)} + \|v\|_{L^1(\partial\Omega)} - \frac{1}{\alpha} \|f\|_{L^2(\Omega)}^2 \\
&\geq \frac{\alpha}{4|\Omega|} \|v\|_{L^1(\Omega)}^2 + |v|_{\text{BV}(\Omega)} + \|v\|_{L^1(\partial\Omega)} - \frac{1}{\alpha} \|f\|_{L^2(\Omega)}^2 \\
&\geq -\frac{1}{\alpha} \|f\|_{L^2(\Omega)}^2.
\end{aligned}$$

$$\begin{aligned}
E(v) &\geq \frac{\alpha}{4} \|v\|_{L^2(\Omega)}^2 + |v|_{\text{BV}(\Omega)} + \|v\|_{L^1(\partial\Omega)} - \frac{1}{\alpha} \|f\|_{L^2(\Omega)}^2 \\
&\geq \frac{\alpha}{4|\Omega|} \|v\|_{L^1(\Omega)}^2 + |v|_{\text{BV}(\Omega)} + \|v\|_{L^1(\partial\Omega)} - \frac{1}{\alpha} \|f\|_{L^2(\Omega)}^2 \\
&\geq -\frac{1}{\alpha} \|f\|_{L^2(\Omega)}^2.
\end{aligned}$$

$$\begin{aligned}
E(v) &\geq \frac{\alpha}{4} \|v\|_{L^2(\Omega)}^2 + |v|_{\text{BV}(\Omega)} + \|v\|_{L^1(\partial\Omega)} - \frac{1}{\alpha} \|f\|_{L^2(\Omega)}^2 \\
&\geq \frac{\alpha}{4|\Omega|} \|v\|_{L^1(\Omega)}^2 + |v|_{\text{BV}(\Omega)} + \|v\|_{L^1(\partial\Omega)} - \frac{1}{\alpha} \|f\|_{L^2(\Omega)}^2 \\
&\geq -\frac{1}{\alpha} \|f\|_{L^2(\Omega)}^2.
\end{aligned}$$

- $\exists (u_n)_{n \in \mathbb{N}} \subset \text{BV}(\Omega) \cap L^2(\Omega)$ infimizing sequence of E
- $\|u_n\|_{\text{BV}(\Omega)} \rightarrow \infty$ as $n \rightarrow \infty \Rightarrow E(u_n) \rightarrow \infty$ as $n \rightarrow \infty$
- $(u_n)_{n \in \mathbb{N}}$ bounded

Lawrence C. Evans and Ronald F. Gariepy. **Measure Theory and Fine Properties of Functions**. CRC Press, 1992. ISBN: 0-8493-7157-0, p. 183, Theorem 1

Let $v \in BV(\Omega)$. For all $x \in \mathbb{R}^n$ define

$$\tilde{v}(x) := \begin{cases} v(x) & \text{if } x \in \Omega, \\ 0 & \text{if } x \in \mathbb{R}^n \setminus \Omega. \end{cases}$$

Then $\tilde{v} \in BV(\mathbb{R}^n)$ and $|\tilde{v}|_{BV(\mathbb{R}^n)} = |v|_{BV(\Omega)} + \|v\|_{L^1(\partial\Omega)}$.

Table of Contents

1 Introduction

2 Continuous Problem

Existence of Minimizers

Uniqueness and Stability

3 Discrete Problem

Equivalent Saddle Point Problem

Characterization of Minimizers

4 Outlook

Table of Contents

1 Introduction

2 Continuous Problem

Existence of Minimizers

Uniqueness and Stability

3 Discrete Problem

Equivalent Saddle Point Problem

Characterization of Minimizers

4 Outlook

Table of Contents

1 Introduction

2 Continuous Problem

Existence of Minimizers

Uniqueness and Stability

3 Discrete Problem

Equivalent Saddle Point Problem

Characterization of Minimizers

4 Outlook

Table of Contents

1 Introduction

2 Continuous Problem

Existence of Minimizers

Uniqueness and Stability

3 Discrete Problem

Equivalent Saddle Point Problem

Characterization of Minimizers

4 Outlook

Table of Contents

- ① Introduction
- ② Continuous Problem
 - Existence of Minimizers
 - Uniqueness and Stability
- ③ Discrete Problem
 - Equivalent Saddle Point Problem
 - Characterization of Minimizers
- ④ Outlook