

The Crouzeix-Raviart Finite Element Method for a Nonconforming Formulation of the Rudin-Osher-Fatemi Model Problem

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Let U be an open subset of \mathbb{R}^d . A function $v \in L^1(U)$ is a function of bounded variation iff

$$|v|_{\text{BV}(U)} := \sup_{\substack{\phi \in C_c^1(U; \mathbb{R}^d) \\ \|\phi\|_{L^\infty(U)} \leq 1}} \int_U v \operatorname{div}(\phi) \, dx < \infty.$$

The space of all such functions is denoted by $\text{BV}(U)$.

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We have $W^{1,1}(\Omega) \subset \text{BV}(\Omega)$ with $\|v\|_{\text{BV}(\Omega)} = \|v\|_{W^{1,1}(\Omega)}$ for all $v \in W^{1,1}(\Omega)$.

Hedy Attouch, Giuseppe Buttazzo, and Gérard Michaille.

Variational Analysis in Sobolev and BV Spaces. Applications to PDEs and Optimization. Second Edition. Vol. 17.

MOS-SIAM Series on Optimization. Philadelphia: Society for Industrial and Applied Mathematics, Mathematical Optimization Society, 2014. ISBN: 978-1-611973-47-1

Lawrence C. Evans and Ronald F. Gariepy. **Measure Theory and Fine Properties of Functions.** CRC Press, 1992. ISBN: 0-8493-7157-0

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Let $\Omega \subset \mathbb{R}^2$ be a bounded polygonal Lipschitz domain.

Rudin-Osher-Fatemi (ROF) model problem

For a parameter $\alpha \in \mathbb{R}_+$ and an input signal $g \in L^2(\Omega)$ minimize the functional

$$I(v) := |v|_{BV(\Omega)} + \frac{\alpha}{2} \|v - g\|_{L^2(\Omega)}^2$$

amongst all $v \in BV(\Omega) \cap L^2(\Omega)$.

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Leonid I. Rudin, Stanley Osher, and Emad Fatemi. “Nonlinear total variation based noise removal algorithms”. In: **Physica D: Nonlinear Phenomena**. Vol. 60. 1-4. 1992, pp. 259–268. DOI: [10.1016/0167-2789\(92\)90242-F](https://doi.org/10.1016/0167-2789(92)90242-F). URL: [https://doi.org/10.1016/0167-2789\(92\)90242-F](https://doi.org/10.1016/0167-2789(92)90242-F)

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Original picture⁰



⁰<https://homepages.cae.wisc.edu/~ece533/images/cameraman.tif>

Original picture⁰



Input signal



The input signal was created by adding AWGN with a SNR of 20 to the original picture.

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$$I(v) := |v|_{\text{BV}(\Omega)} + \frac{\alpha}{2} \|v - g\|_{L^2(\Omega)}^2$$

Original picture



Input signal

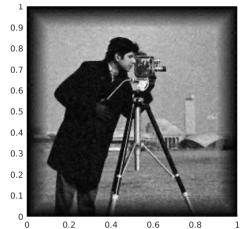


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Original picture



Input signal



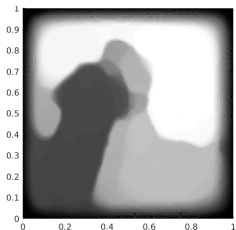
$\alpha = 50000$

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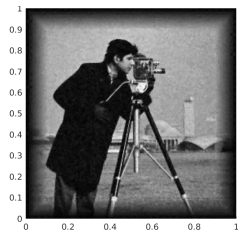
Original picture



Input signal



$\alpha = 100$



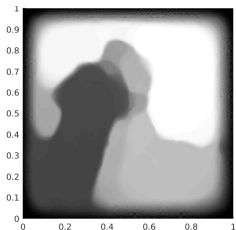
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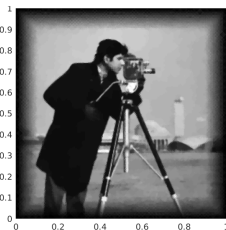
Original picture



Input signal



$\alpha = 100$



$\alpha = 5000$



$\alpha = 50000$

Pascal Getreuer. “Rudin-Osher-Fatemi Total Variation Denoising using Split Bregman”. In: **Image Processing On Line** 2 (2012), pp. 74–95. URL: <https://doi.org/10.5201/ipol.2012.g-tvd>

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Continuous problem

For a parameter $\alpha \in \mathbb{R}_+$ and an input signal $f \in L^2(\Omega)$ minimize the functional

$$E(v) := \frac{\alpha}{2} \|v\|^2 + |v|_{\text{BV}(\Omega)} + \|v\|_{L^1(\partial\Omega)} - \int_{\Omega} f v \, dx$$

amongst all $v \in \text{BV}(\Omega) \cap L^2(\Omega)$.

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amongst all $v \in \text{BV}(\Omega) \cap L^2(\Omega)$.

For $f = \alpha g$ the functional E has the same minimizers as

$$I(v) := |v|_{\text{BV}(\Omega)} + \frac{\alpha}{2} \|v - g\|_{L^2(\Omega)}^2$$

in $\{v \in \text{BV}(\Omega) \cap L^2(\Omega) \mid \|v\|_{L^1(\partial\Omega)} = 0\}$.

nochmal Existenz und Eindeutigkeitsaussagen zeigen und gaaaanz grob beschreiben, wie die bewiesen werden

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vielleicht in eigener Section: noch die Aussagen aus der Arbeit verarbeiten, die über Existenz und Eindeutigkeit hinausgehen

Sören Bartels. **Numerical Methods for Nonlinear Partial Differential Equations**. Vol. 47. Springer Series in Computational Mathematics. Springer International Publishing, 2015. ISBN: 978-3-319-13796-4. DOI: 10.1007/978-3-319-13797-1, Chapter 10, p. 297-319

Properties of $BV(\Omega)$

Notions of convergence on $BV(\Omega)$

Let $(v_n)_{n \in \mathbb{N}} \subset BV(\Omega)$ and $v \in BV(\Omega)$ such that $v_n \rightarrow v$ in $L^1(\Omega)$ as $n \rightarrow \infty$.

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- (i) $(v_n)_{n \in \mathbb{N}}$ converges intermediately or strictly to v if $|v_n|_{BV(\Omega)} \rightarrow |v|_{BV(\Omega)}$ as $n \rightarrow \infty$.

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- (i) $(v_n)_{n \in \mathbb{N}}$ converges intermediately or strictly to v if $|v_n|_{BV(\Omega)} \rightarrow |v|_{BV(\Omega)}$ as $n \rightarrow \infty$.
- (ii) $(v_n)_{n \in \mathbb{N}}$ converges weakly to v if $\langle Dv_n, \phi \rangle \rightarrow \langle Dv, \phi \rangle$ for all $\phi \in C_0(\Omega; \mathbb{R}^n)$ as $n \rightarrow \infty$.

Further Properties of $BV(\Omega)$

$C^\infty(\overline{\Omega})$ and $C^\infty(\Omega) \cap BV(\Omega)$ are dense in $BV(\Omega)$ with respect to intermediate convergence.

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The embedding $BV(\Omega) \rightarrow L^p(\Omega)$ is continuous for $1 \leq p \leq n/(n-1)$ and compact for $1 \leq p < n/(n-1)$.

There exists a linear operator $T : BV(\Omega) \rightarrow L^1(\partial\Omega)$ such that $T(v) = v|_{\partial\Omega}$ for all $v \in BV(\Omega) \cap C(\overline{\Omega})$.

T is continuous with respect to intermediate convergence in $BV(\Omega)$ but not with respect to weak convergence in $BV(\Omega)$.

Algorithmus und mglw LGS dazu, siehe Arbeit
wohl auch Konvergenztheorem aufführen, Bereich für τ kurz
erläutern, vielleicht beim groben erläutern der Beweisidee

drüber nachdenken, was hier gezeigt werden soll. Idealerweise viele subsections mit Themenbereichen (f01, cam, termCrit, tau...)
termination criteria experiments only in the end if questions arise, only mention the possible termination criteria and that they seem equally valid (except for energy difference)
show tau experiments
energy during a iteration (convergence of subsequences from above, i.e. also choose one example with oscillating convergence)
find good alpha for denoising
show adaptive mesh for cameraman and maybe for square to show the working of the refinement indicator

ten schicken spätestens am Wochenende vor der Präsi, CC vor der Präsi die fertige Präsi + aktueller Stand der Arbeit schicken