CSE306 - ASSIGNMENT 2

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In this second assignment, I have implemented the following tools and features.

- Voronoi diagram solver, using Sutherland-Hodgman polygon clipping algorithm:
- A small header-only library for kd-tree to speed up the Voronoi diagram solver:
- Extension to Power diagram and weight optimisation with L-BFGS;
- Semi-discrete optimal transport fluid simulator with free surfaces;

The assignment was done in 734 lines of code, including 16 lines of code in $\mathtt{main.cpp}$ and 718 lines of code from 6 files in ./classes. The project was compiled with C++20, and the following compiler flags

-fopenmp -03 -fcf-protection=none -march=native -mtune=native -fno-math-errno

The rendering was done one a laptop with Intel Core i7-10710 CPU, 12 cores with 1.6 GHz. No GPU was used for the rendering in this report.

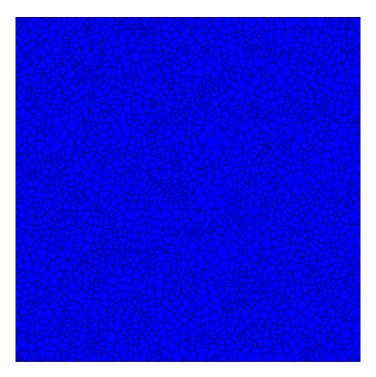


FIGURE 1. Voronoi diagram of 3000 points. Runtime was 0.058 with kd-tree, and 0.738 seconds without kd-tree.

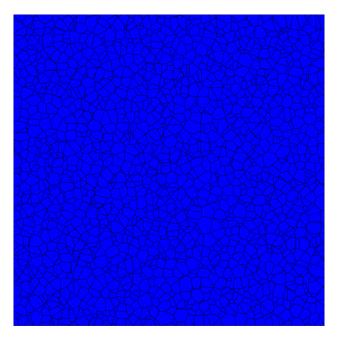


FIGURE 2. Power diagram of the same 3000 points as in Figure 1 but with random weights. Runtime was 0.068 seconds with kd-tree, and 0.869 seconds without kd-tree.

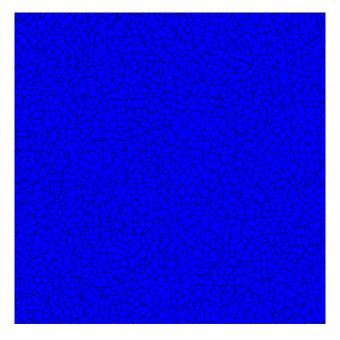


FIGURE 3. Power diagram of the same 3000 points as in Figure 1 but with weights optimised with Optimal transport and L-BFGS. Runtime was 0.725 with kd-tree, and 42.841 seconds without kd-tree.

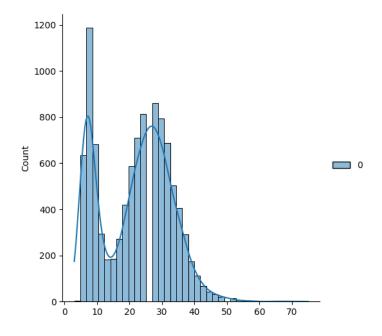


Figure 4. Number of neighbours needed to be requested from kd-tree for a typical set of 300 points.

I also conduct some experiments to find the optimal value for k, the number of nearest neighbor to be requested from kd-tree. Experiments show that the distribution of number of neighbours needed for a given point is independent from the number of points in the set, thus assuming there is a fixed discrete distribution p, such that p_n is the probability that we need n neighbours.

Let C(k) be the cost to request k nearest neighbours from kd-tree. Carrying out complexity analysis should show that $C(k) = A + Bk \log k$ where A is the cost of traversing through the kd-tree, and $Bk \log k$ is the cost of maintaining the priority queue. Then, approximating C(mk) = mC(k) for integers m, and let D(n) be the cost of finding neighbours until having at least n neighbours, modulo some rounding, we have $D(mk) = C(k) + C(2k) + \dots + C(mk) = \frac{m(m+1)}{2}C(k)$, or $D(n) = \frac{n(n+k)}{2k^2}C(k).$ Then

$$\mathbb{E}(D(n)) = \sum_{n} p_n D(n) = \sum_{n} p_n \frac{n(n+k)}{2k^2} C(k)$$

$$= C(k) \left(\sum_{n} p_n \frac{n(n+k)}{2k^2} \right) = \frac{C(k)}{2} \left(\frac{1}{k^2} \sum_{n} p_n n^2 + \frac{1}{k} \sum_{n} p_n n \right)$$

$$= \frac{A + Bk \log k}{2} \left(\frac{1}{k^2} C + \frac{1}{k} D \right),$$

where A, B, C, D are all constants and independent of k. This final formula suggests that there should be a fixed optimal value for k. Some more experiments show that k = 15 gives better performances than other values tested.