

# Computerarchitecture - laboratory 3

Design Document

Radio-controlled Clock with DCF77 Interface

created by

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# 1 Laboratory Introduction

- Implementing a complex application
- Mixed programming in C and assembler

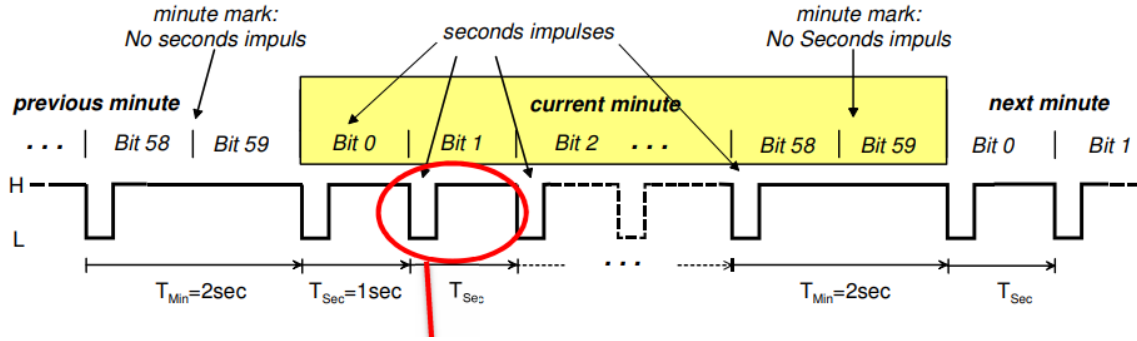
In the second lab we developed a clock. The clock was driven by a timer, which triggered an interrupt every 10ms. A software counter in the ISR create a 1s tick, from which minutes and hours were derived. Unfortunately, this clock loses its time value, when turned off, and thus must be set manually when turned on. Additionally, because the quartz oscillator's precision is limited, the time will drift slightly, when the clock programs runs a long time. Another drawback is that the clock must be manually set when time changes from standard time (MEZ) to daylight savings time (MESZ) and vice versa.

In lab 3 setting the clock shall be done automatically by using the DCF77 radio signal, which transmits time and date information. In the Corona Edition of this lab the DCF77 radio signal will be simulated.

## 2 Introduction to the format of the DCF77 Signal

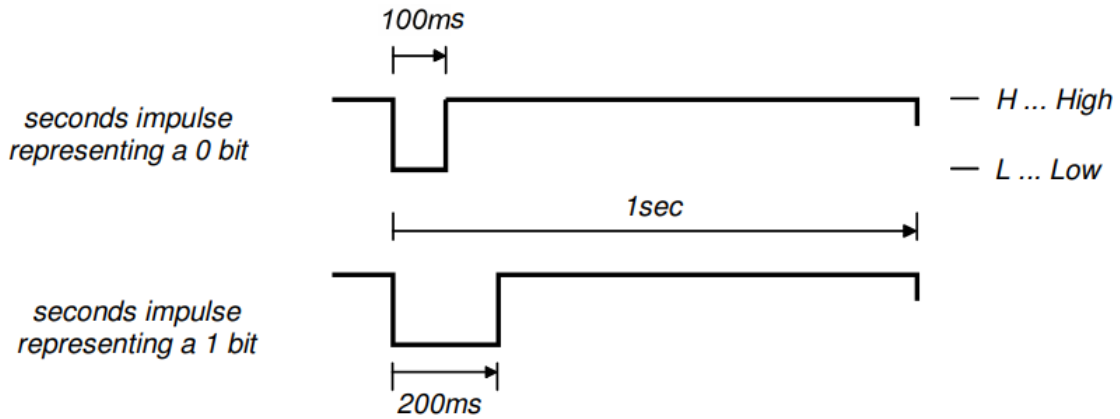
DCF77 is a low frequency radio transmitter, operated by the PTB. The transmitter is located near Frankfurt. Its signal can be received in most parts of Europe. The signal uses a digital amplitude modulation, which can be received by a simple antenna and decoded with a low pass filter and a comparator. In our lab we use an antenna mounted at the windows of the room and a decoder, which outputs a pulse signal, which contains the time and date information in serial BCD code. In the Corona Edition this signal is simulated as close as possible to the real antenna signal. Decoding this information must be done by the software.

When idle, the digital DCF77 signal is H (High). Every second the pulse goes to L (Low) (seconds impulses). Each L impulse contains 1bit of the time and date information. To mark the begin of a new minute, the last seconds (bit 59) before the begin of a minute (bit 0) is missing (minutes mark).



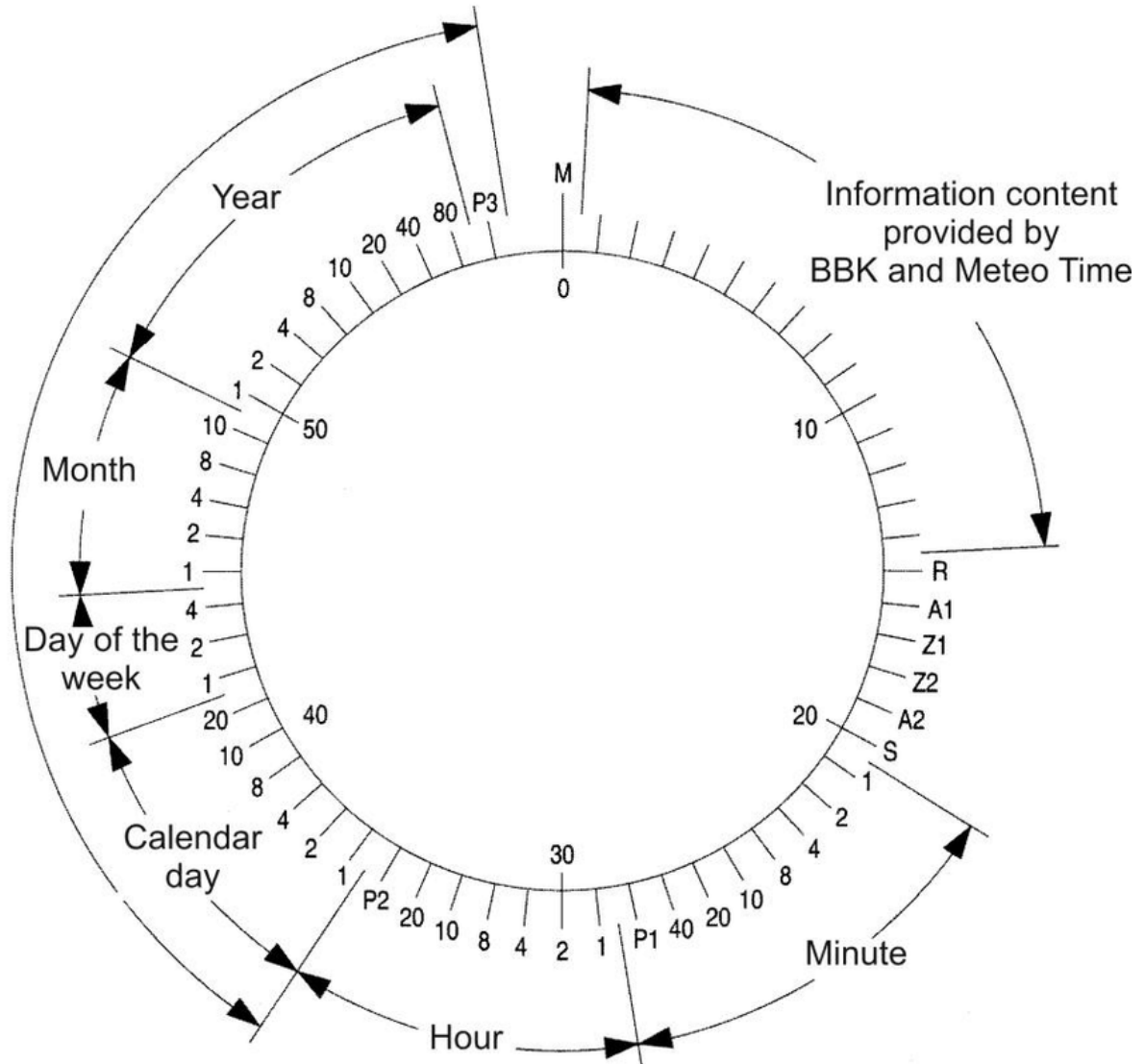
**Figure 1:** Overview of the second impulses and minute marks

the bits of the time and date information are coded via the length of the L-phase of the seconds impulses. A short L-impulse of approximately 100ms codes a '0' bit, a longer L-impulse of approx. 200ms stands for a '1' bit.



**Figure 2:** Coding of 0 and 1 in second impulses

The 59 data bits transmitted each minute contain the current date and time plus additional control information:



**Figure 3:** Overview of the coding scheme of the DCF77 time code frame

### 3 Requirements

The requirements for the radio-controlled clock are:

- The first line of the Dragon12s LCD display shall show the time in the following format:  
**hours : minutes : seconds**  
The second line shall display the date in the following format:  
**day . month . year**
- Because of the DCF77 transmission fails sometimes (bda radio signal is massice steel-concrete

buildings, transmitter maintenance etc.), the basis concept of 11b 2's clock is still used, i.e. the clock is driven by the timer clock. The DCF77 radio information fails, the clock shall continue to run based on the timer clock.

- The timer clock shall be used to toggle the LED on [port B.0 once per second.
- The LED on port B.1 shall be turned on, when the DCF77 signal is Low and turned off, when the DCF77 signal is High. Thus, when the DCF77 signal is received, this LED will also toggle once per second.
- LED on port B.3 shall be turned on, when a complete and correct DCF77 date and time information has been decoded and turned off at once, when no or wrong data has been received. Check, if hours are in 0 ... 23, minutes and seconds in the 0 ... 59, days in the 1 ... 32 and months in the 1 ... 12 range. Parity checks are required, When an error is detected, your program shall turn on LED on port B.2, until valid data is received again.
- The DCF77 pulse signal on the real Dragon12 board is connected to port H.0 on the Dragon12 board. As the real DCF77 antenna signal may include spikes and the signal edges may jitter, the signal should be polled every 10ms rather than using port H's interrupt.

<i>Event</i>	<i>Signal edge</i>	<i>Purpose and condition</i>
NODCF77EVENT	No	Signal did not change since last polling
VALIDSECOND	Negative	Valid second impulse, if $T_{Pulse}=1s \pm 100ms$ . The tolerance window is required, as the DCF77 signals period and/or the timer interrupt period may jitter.
VALIDMINUTE	Negative	Valid minute mark, if $T_{Pulse}=2s \pm 100ms$ .
VALIDZERO	Positive	Valid 0 bit, if $T_{Low}=100ms \pm 30ms$
VALIDONE	Positive	Valid 1 bit, if $T_{Low}=200ms \pm 30ms$
INVALID	Negative Positive	If $T_{Pulse}$ is outside of the tolerance window. If $T_{Low}$ is outside of the tolerance window.

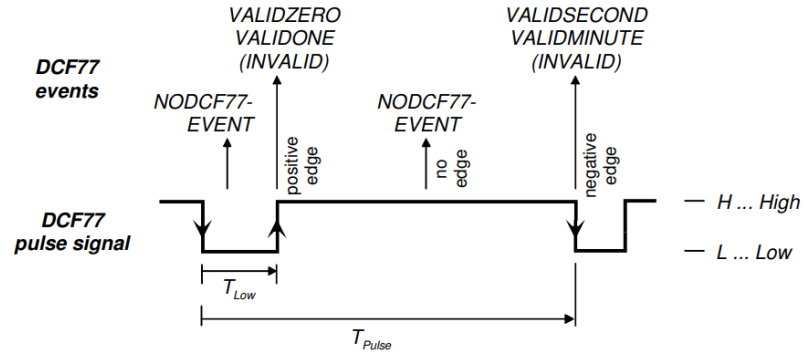


Figure 4: DCF77 events

## 4 Overview of the clock program

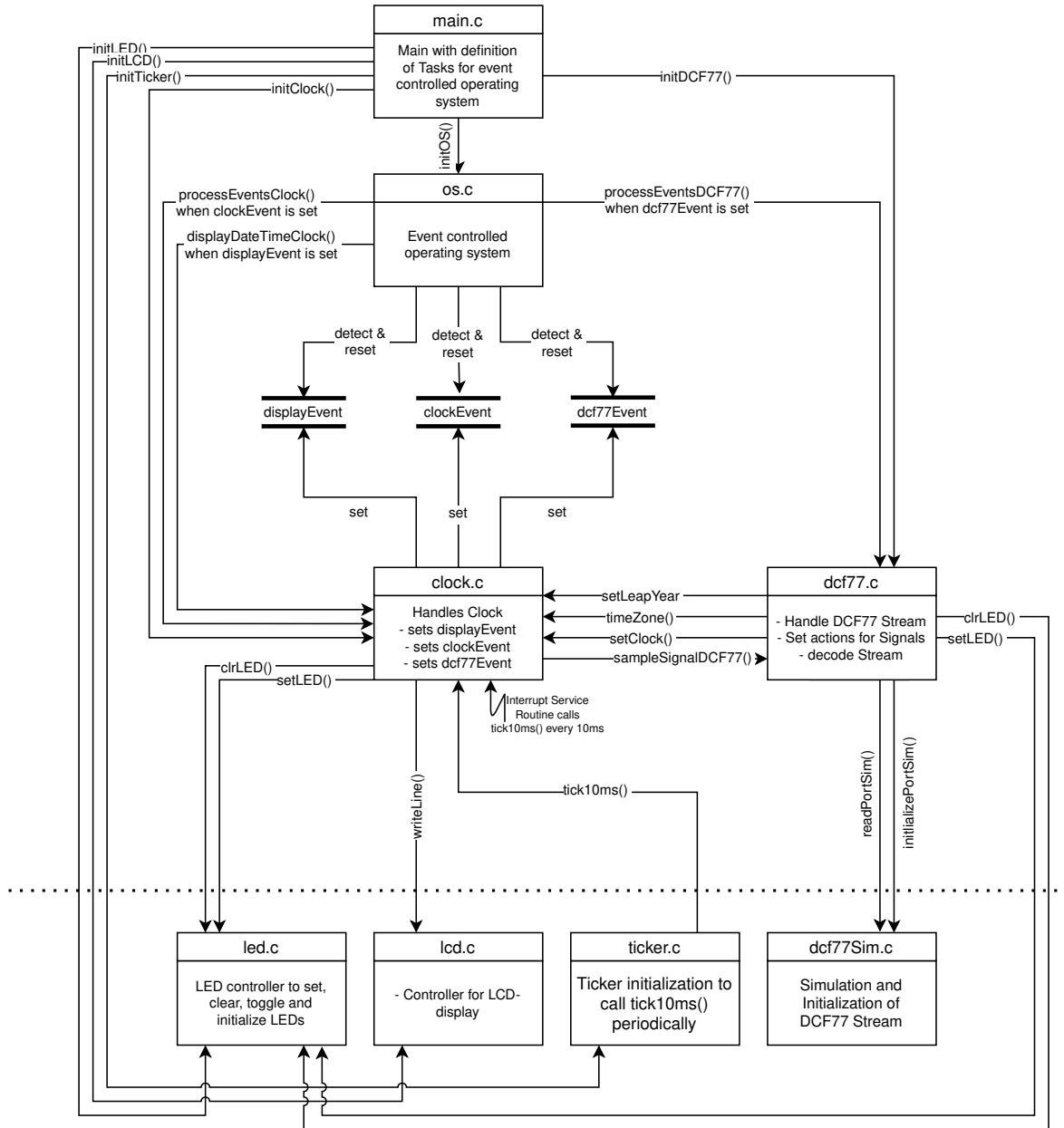


Figure 5: overview

## 5 Variables

### 5.1 Global Variables

location	name	description
clock.c	CLOCKEVENT clockEvent	Event for os to trigger processEventsClock()
clock.c	DISPLAYEVENT      displayEvent	Event fo os to trigger displayDateTimeClock()
clock.c	char *weekdays	Pointer to reference days of the week
clock.c	char *descZone	Pointer to reference the Timezone of the clock
clock.c	int zone	Used to differentiate in which zone the clock is set to
clock.c	int weekDecoder	Used to map weekdays into String representing weekdays
clock.c	int maxDayOfMonths[]	Used to differentiate the maximum days of a month
dcf77.c	int tLowCounter	Counter to validate a low period
dcf77.c	int minuteCounter	Counter variable to indivate the minute period
dcf77.c	int secondCounter	Counter to validate a second period
dcf77.c	position	Referrer to index the bit-sequence
dcf77.c	invalid	Variable to indicate a invalid bit-sequence
dcf77.c	bits[59]	Array to store the BCD-bit-sequence

### 5.2 static Variables

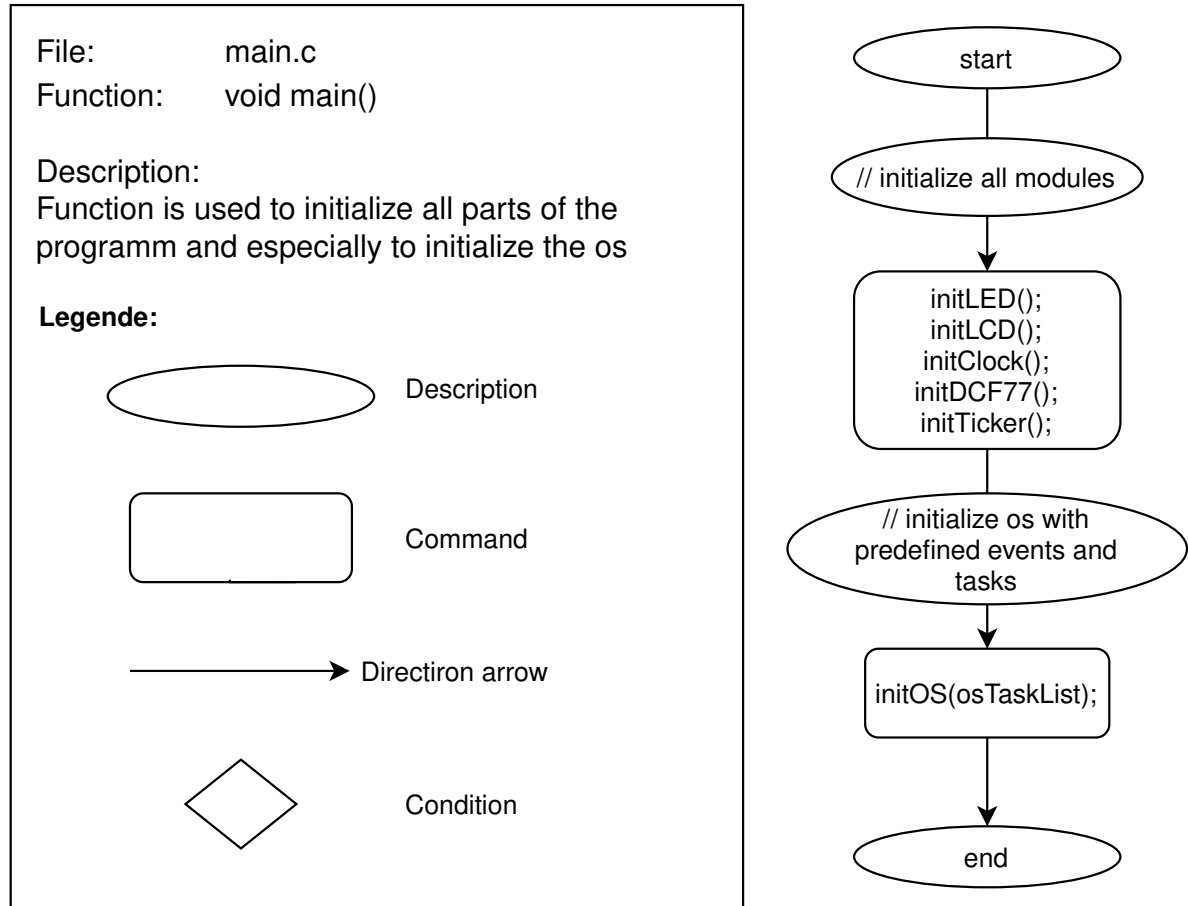
location	name	description
clock.c	char days	representation of the date
clock.c	char months	*
clock.c	char years	*
clock.c	char hrs	representation of the time
clock.c	char mins	*
clock.c	char secs	*
clock.c	char uptime	used to store the cpu time
clock.c	char ticks	Counter variable for ticker to indicate 200 ms
dcf77.c	int minutes	Variable to store the minutes of bit-sequence
dcf77.c	int hours	Variable to store the hours of bit-sequence
dcf77.c	int day	Variable to store the day of bit-sequence
dcf77.c	int month	Variable to store the month of bit-sequence
dcf77.c	int year	Variable to store the year of bit-sequence
dcf77.c	int weekDecoder	Variable to store the weekDecoder of bit-sequence
dcf77.c	int lastSignal	Variable to store the lastSignal of bit-sequence



## 6 Module specific flowchart diagrams

### 6.1 Main (Main.c)

#### 6.1.1 void main()

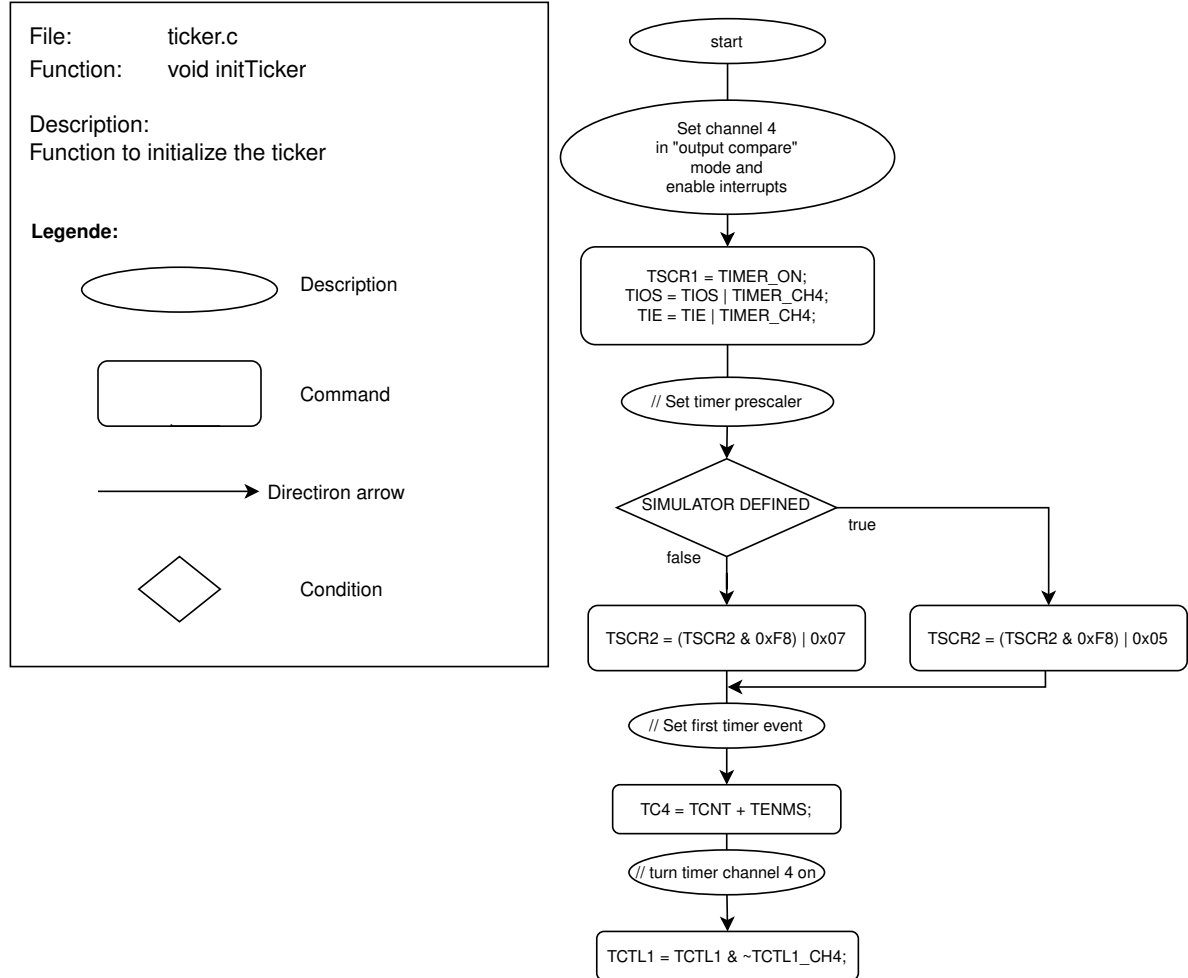


**Figure 6:** Flowchart diagramm of function `main()`

The main is used as the starting point for the whole programm. First of all, all the components e.g. LED, LCD, clock, DCF77 and ticker need to be initialized. After all we need to initialize the *operating system*. The initialization function of the os takes a array which consists of a combinations of a function and a associated event. Whenever the event is set, the associated function will be called and the associated event will be reset.

## 6.2 Ticker (ticker.c)

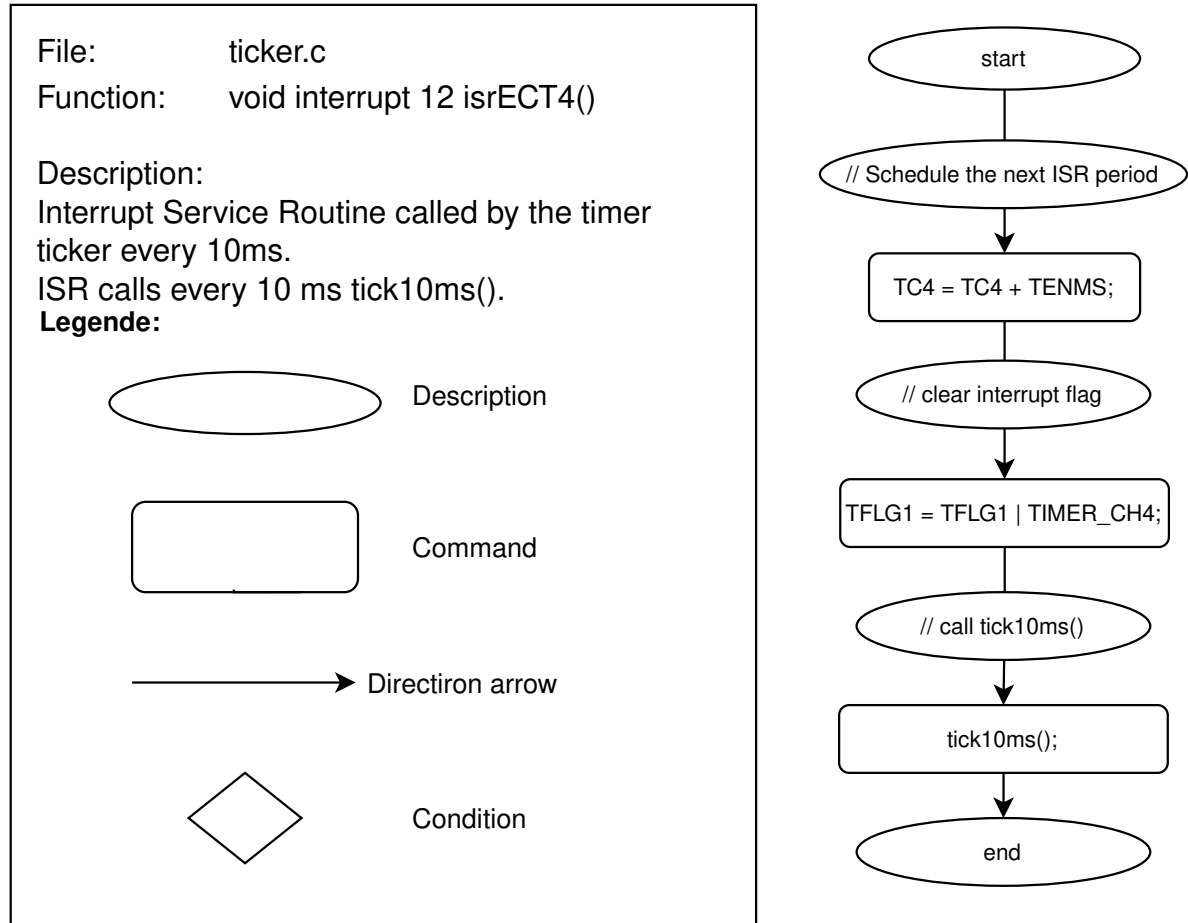
### 6.2.1 void initTicker(void)



**Figure 7:** Flowchart diagram of function *initTicker()*

This function was not written by the laboratory participants either, but was provided by professor Zimmermann. However, most of the commands are used to configure the ticker. We set the channel 4 to output compare mode, set the timer prescaler dependent on the definition of the simulator and to complete the process, we set the first timer event and turn timer channel 4 on.

### 6.2.2 void interrupt 12 isrECT4()

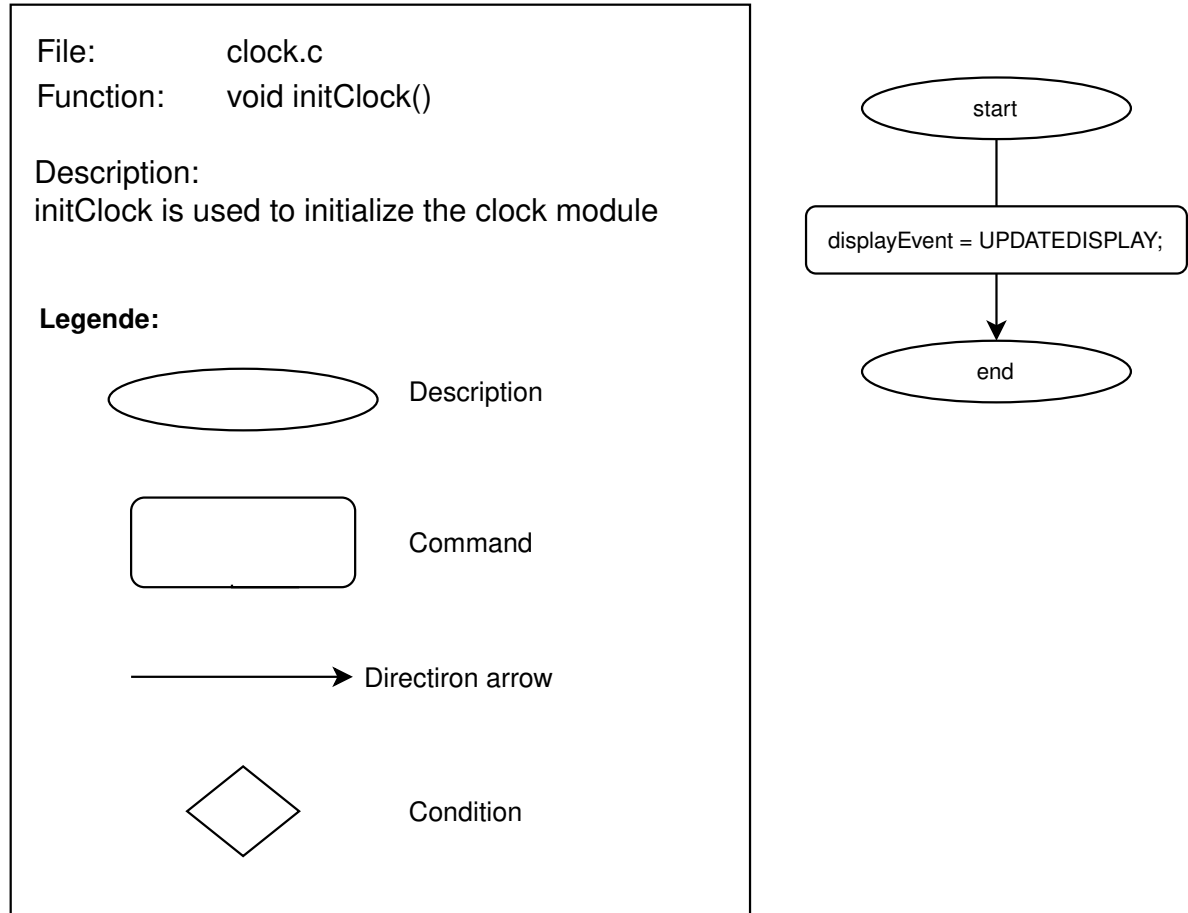


**Figure 8:** Flowchart diagramm of ticker interrupt service routine.

Again, this function was not written by the laboratory participants either, but was provided by professor Zimmermann. However, this ISR has a easy build up. We schedule the next interrupt by incrementing `TC4` with 10 ms, clear the output flag and then call a function `tick10ms()`.

## 6.3 Clock (clock.c)

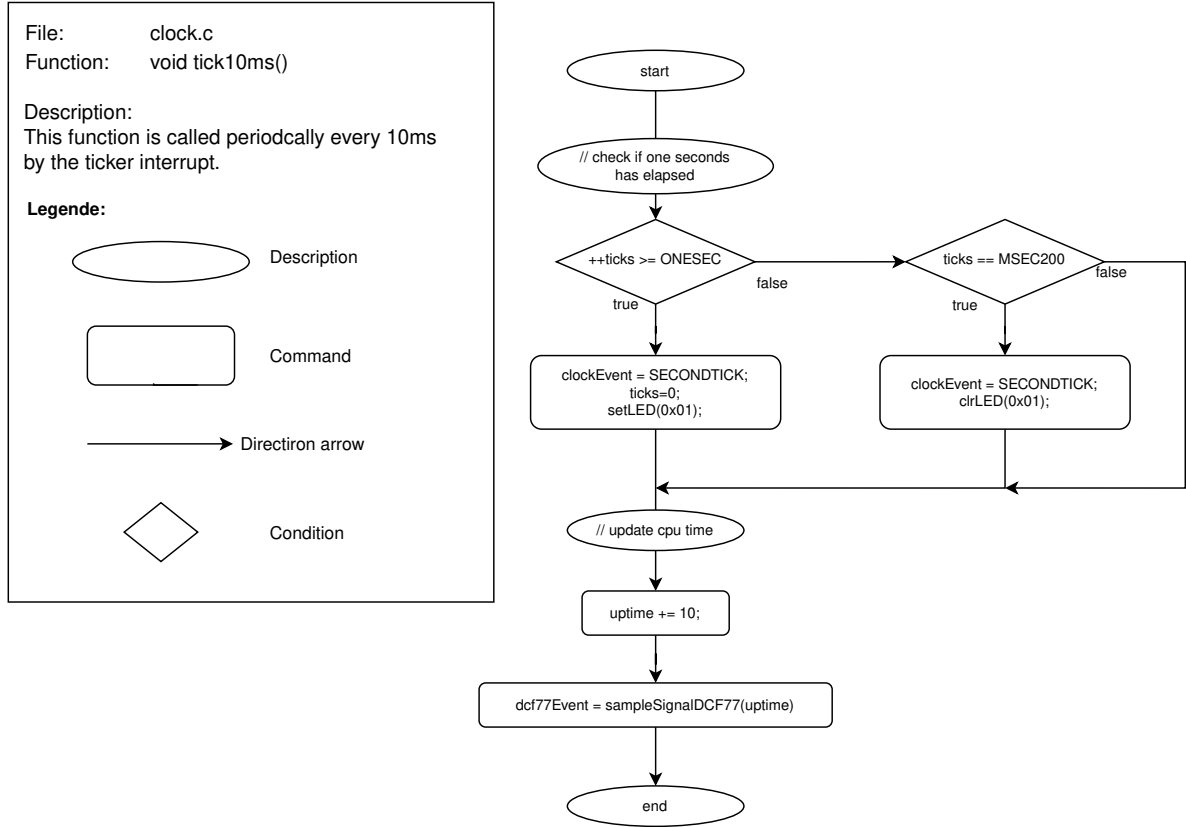
### 6.3.1 void initClock()



**Figure 9:** Flowchart diagramm of function *initClock*

This very complex function is used to initialize the clock module. It sets the displayEvent to *UPDATEDISPLAY*

### 6.3.2 void tick10ms()

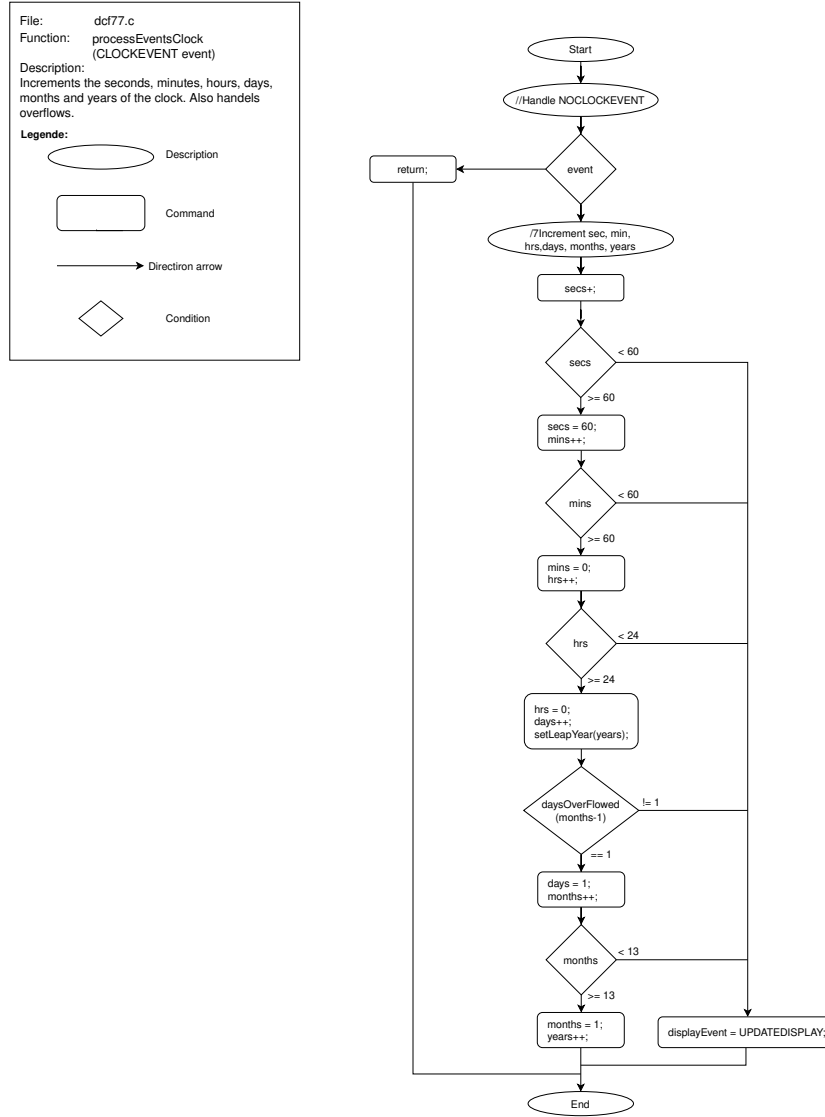


**Figure 10:** Flowchart diagramm of function *tick10ms()*

This function is called periodically every 10ms by the interrupt. In this function we increment the ticks of the ticker and check if one second has elapsed. If one second has elapsed, the clockEvent is updated, ticks are reset and the LED on PORT B.0 needs to be set. In case of ticks equals 200 ms, we clear the LED on PORT B.0.

After every call, we increment the uptime with 10ms and set the dcf77Event with the return value of function call *sampleSignalDCF77()*.

### 6.3.3 void processEventsClock(CLOCKEVENT event)



**Figure 11:** Flowchart diagramm of function *processEventsClock()*

This function is used to process the clock itself. Whenever the event isn't *NOCLOCKEVENT* we increment the clock. For that we need to check if the seconds, minutes, hours, days, months and the year overflow. When this process finished, we update the *displayEvent*, so the operating system can call the print method to update the clock on the LCD display.

### 6.3.4 void setClock(...)

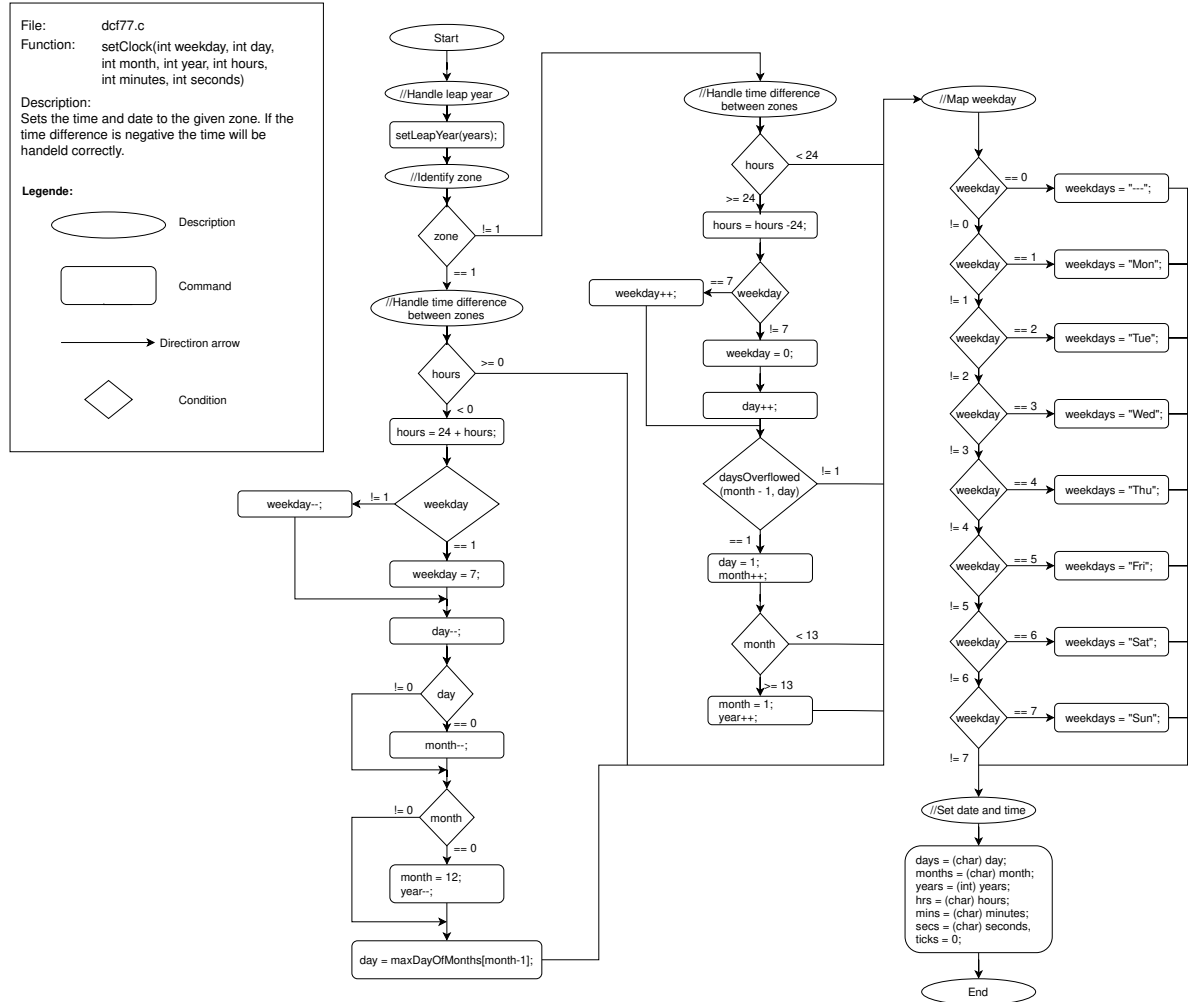


Figure 12: Flowchart diagram of function setClock()

First of all, this diagram can be a little bit confusing. However, we'll go through them step by step. First of all, we set the leapYear by calling the function *setLeapYear*. Now we have two Cases:

- Case one occurs, when zone equals to 1. In this case, we check, if we need to handle an underflow of the hours. If this is needed, we subtract the underflow from the actual hours and check, if we need to handle a underflow of the weekdays. If this is necessary, we set the weekday to 7, otherwise, we just decrement the weekday regularly. Now we need to check, if we need to handle an underflow of the day. For that we decrement the days and then check, if the days equals 0. In that case, we decrement the months and therefore check if we need to handle an underflow too. After handling an underflow of the years, we can set our days to the maximum value of the month before and leave the function, by updating the global variables with the new calculated values.
- The other case occurs, if the zone equals to 0. This case pretty much equals the first case with

the exception that we now handle overflows: If the hours have been overflowed, we subtract the overflow from 24 and check if weekday has been overflowed. In that case of an overflow, we reset the days to 0, otherwise we just increment the weekday with 1. After that we increment the days of a month and check, if the days have reached the maximum value of the associated month. In that case, we reset the day to 1 and check if the months have been overflowed. In case of an overflow, we reset the months to 1 and increment the years. After that we leave the function by configuring the global variables with the new specified time and adjust the printed weekday.

### 6.3.5 void displayDateTimeClock(DISPLAYEVENT event)

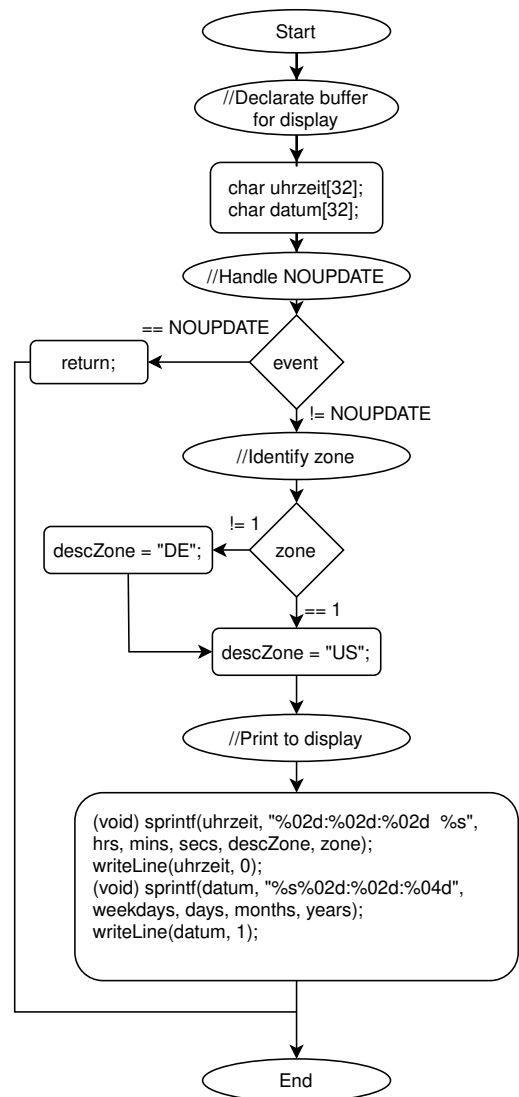
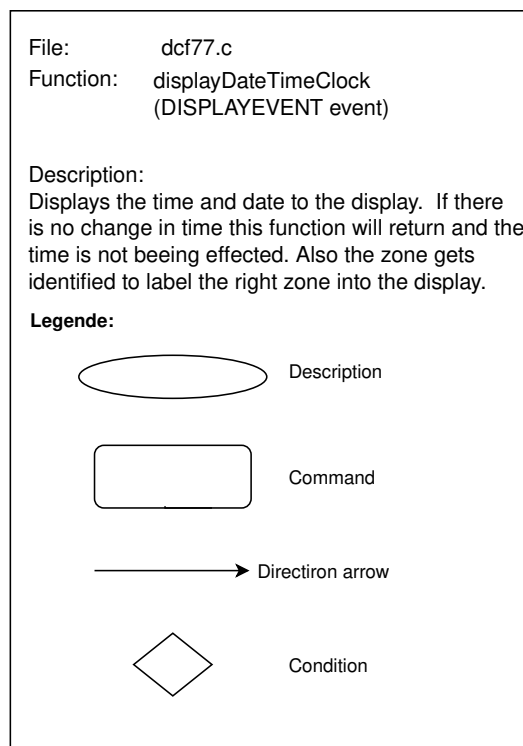
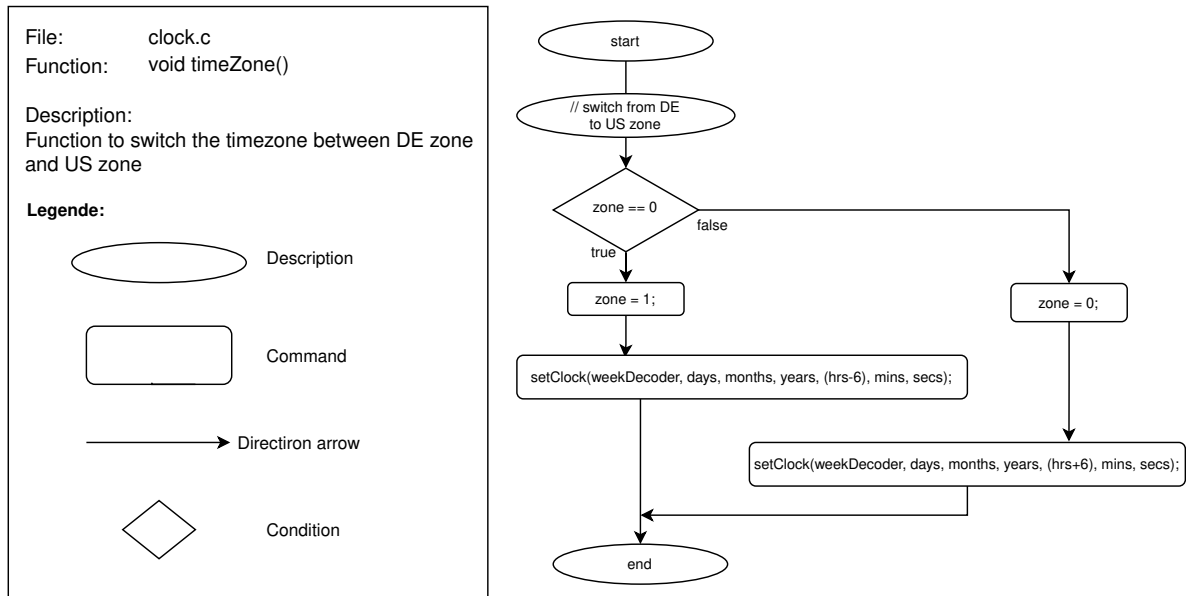


Figure 13: Flowchart diagramm of function displayDateTimeClock



This function is used to fill the buffers of line 0 and line 1. For that, we write the time and the date into the buffers. After that we can write them onto the LCD display.

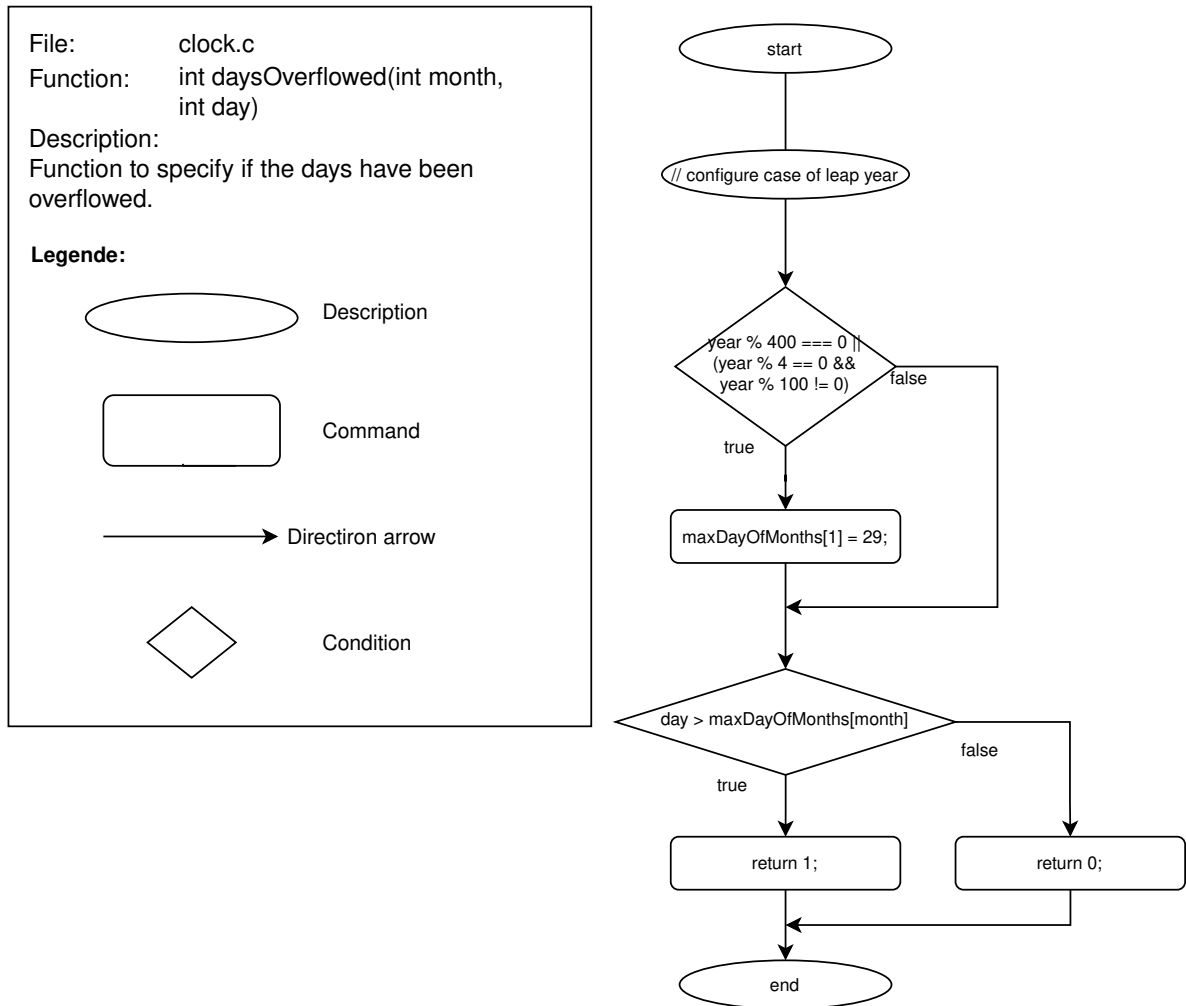
### 6.3.6 void timeZone()



**Figure 14:** Flowchart diagramm of function *timezone*

This function is used to change change the timeZone of the clock. Note that in each case we need to add or subtract 6 hours from the displayed time. When the time is changed we need change our variable zone too.

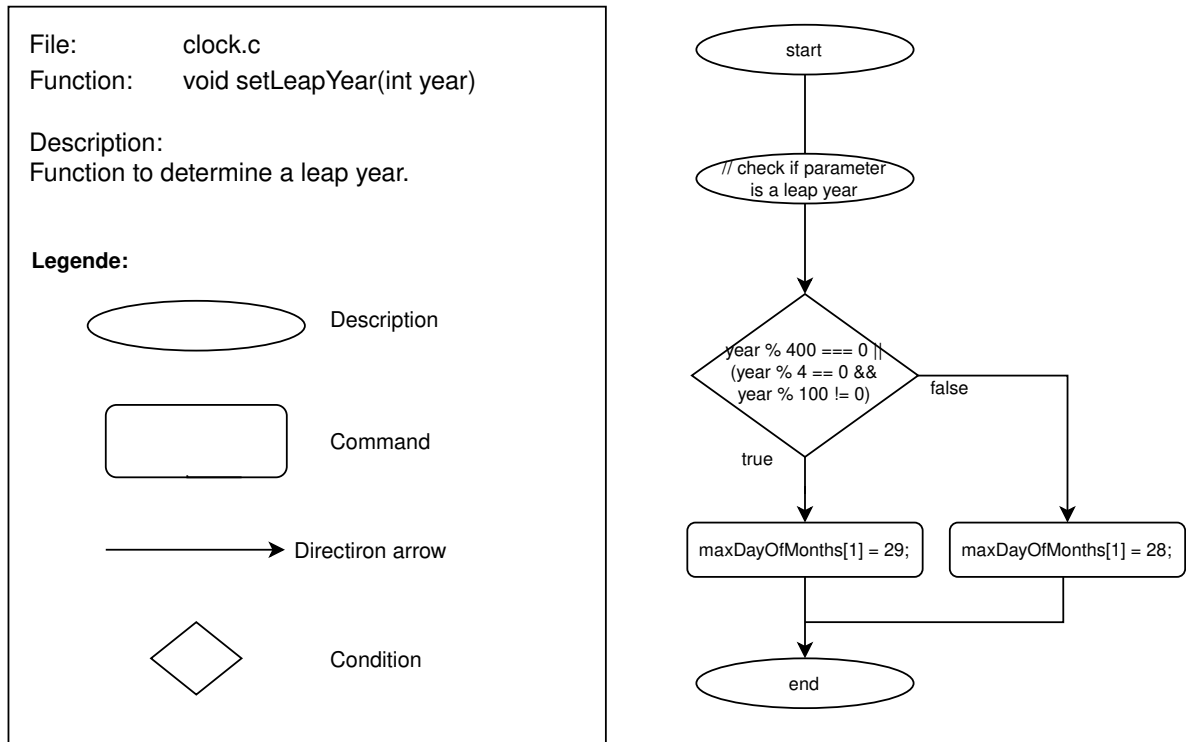
### 6.3.7 int daysOverflowed(int month, int day)



**Figure 15:** Flowchart diagramm of function *daysOverflowed*

This function is used to specify if the days have been overflowed or not. Before we check the overflow, we need to configure the case of an leap year. If the day and month combination indicates an overflow, we return 1 (true), if not we return 0 (false).

### 6.3.8 void setLeapYear(int year)

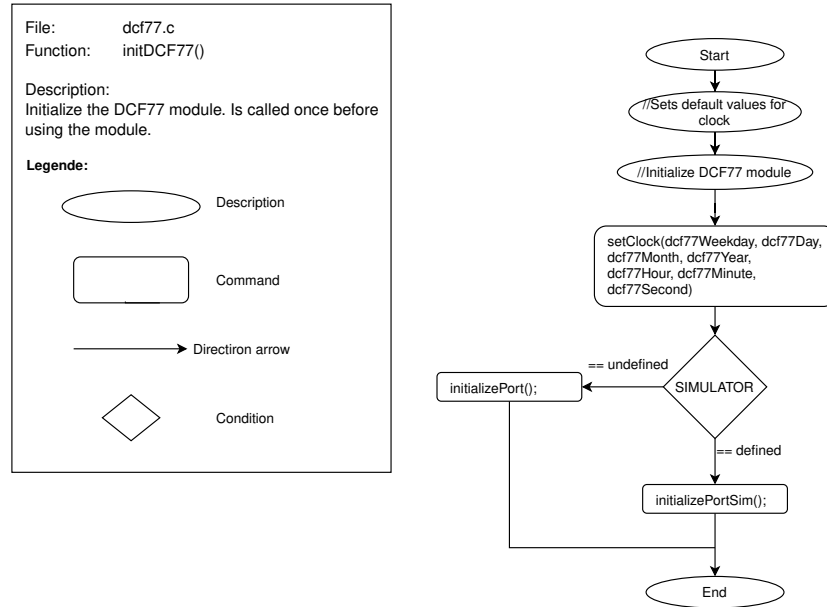


**Figure 16:** Flowchart diagramm of function *setLeapYear*

This function is used to set leap years. In case of a leap year, we set the last day of february to 29 in the global variable *maxDayOfMonth[]*.

## 6.4 DCF77 (dcf77.c)

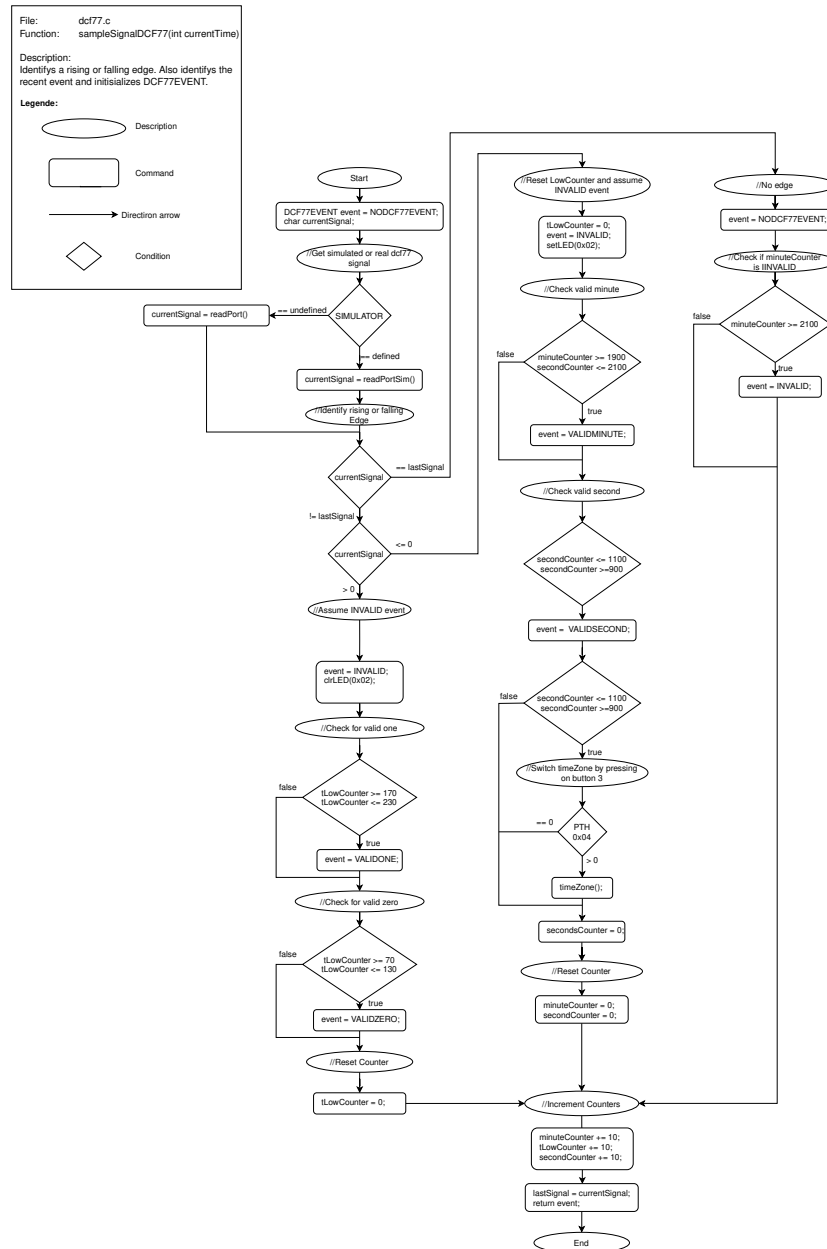
### 6.4.1 void initDCF77(void)



**Figure 17:** Flowchart diagramm of function *initDCF77*

Sets default values for the clock. Also initializes the DCF77 module.

### 6.4.2 DCF77EVENT sampleSignalDCF77(int currentTime)



**Figure 18:** Flowchart diagramm of function `sampleSignalDCF77`

This function is used to specify the events on the actual signal. This seems a little be overwhelming but we will got through it step by step. First of all, we call the function `readPortSim()`, that returns the actual value of the signal. For what we will look are falling and rising edges:

The first step is to check if the currentSignal has changed to the last received signal. In this is the case, we will specify if we have rising or falling edges:

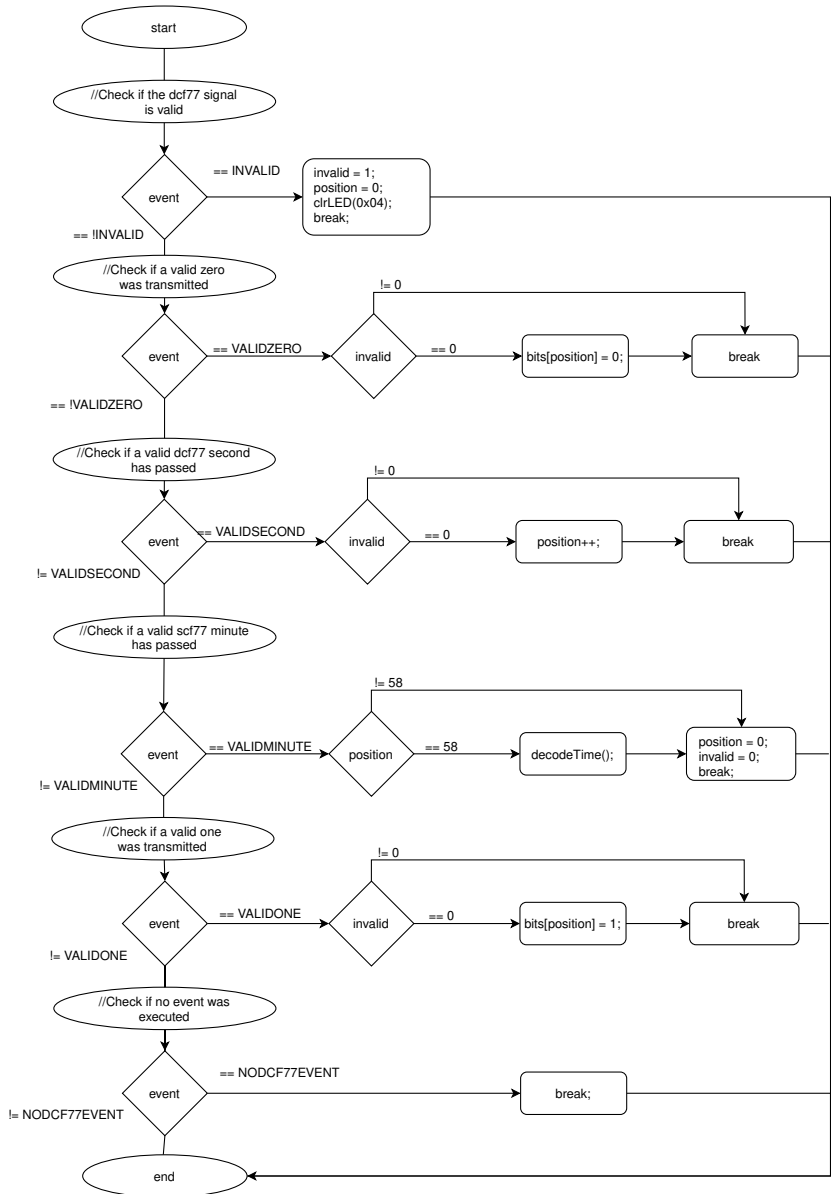
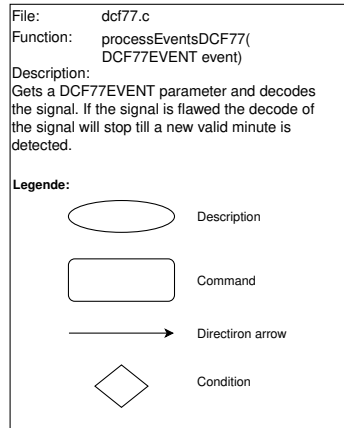
- In case of rising edges we assume that the event is invalid. Now we clear the LED on PORT B.1 and check if we have a valid one signal or a valid zero signal. A one signal is valid, if the

signal stays low for 170 to 230 ms. In that case, we set the event variable to VALIDONE. A zero signal is valid, if the signal stays low for 70 to 130 ms. In that case, we set the event variable to VALIDZERO. After we have validated a rising edge we need to reset the lowCounter.

- In case of falling edges we assume that the event is invalid, too. For that, we set the LED on PORT B.1 on. Here we need to check, if we have a valid minute or a valid second. A valid minute events needs to be set, if the signal stays high for 1900 to 2100 ms. A valid second instead needs to be stay high for 900 to 1100 ms. Especially in case of a valid second, we check, if the button 3 on PORTH has been pressed and therefore switch the timeZone from DE to US and vice versa.

In case of the signal hasn't been changed from the previous one, we signal that no event has been occurred. After that we increment all counters for the next pass and set the lastSignal to the currentSignal.

### 6.4.3 void processEventsDCF77(DCF77EVENT event)



**Figure 19:** Flowchart diagramm of function processEventsDCF77

This function handles the current event and actually decodes the signal into 1s and 0s which are stored in an array called "bits".

**INVALID event:**

Sets the global variable invalid to 1 and the global variable position to 0. So we ensure that the current transmitted minute will be rejected. Also clearing the LED on Port (0x04).

VALIDZERO event:

Sets a 0 in the bits array with the index of position which represent the current second. Only if the global variable invalid isn't set to 0 this function will set a valid 0.

VALIDDONE event:

Sets a 1 in the bits array with the index of position which represent the current second. Only if the global variable invalid isn't set to 0 this function will set a valid 1.

VALIDSECOND event:

Increments position which represent one second of the DCF77 signal. This will only be done when the variable invalid is 0.

VALIDMINUTE event:

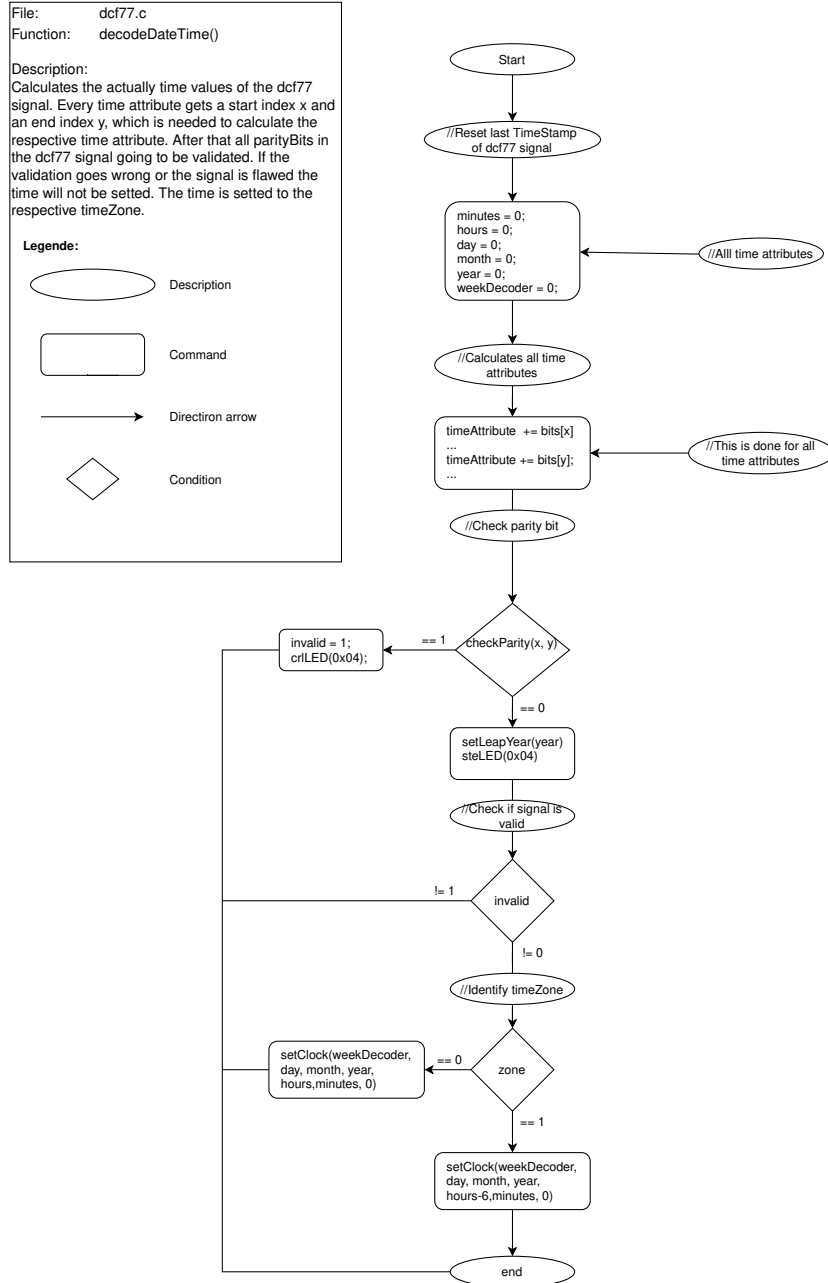
Calls the method `decodeDateTime()` which updates the clock with the transmitted time of the DCF77 signal. Only if the position equals 58 this function will be called because when the position reaches 58 we can ensure that a full and valid DCF77 signal was transmitted. Also the variable position and invalid are reseted to 0 so we can start to receive a new valid minute with the help of the DCF77 signal.

NODCF77EVENT event:

When the last event and the current event are the same this event will be thrown and nothing will happen.



#### 6.4.4 void decodeDateTime()

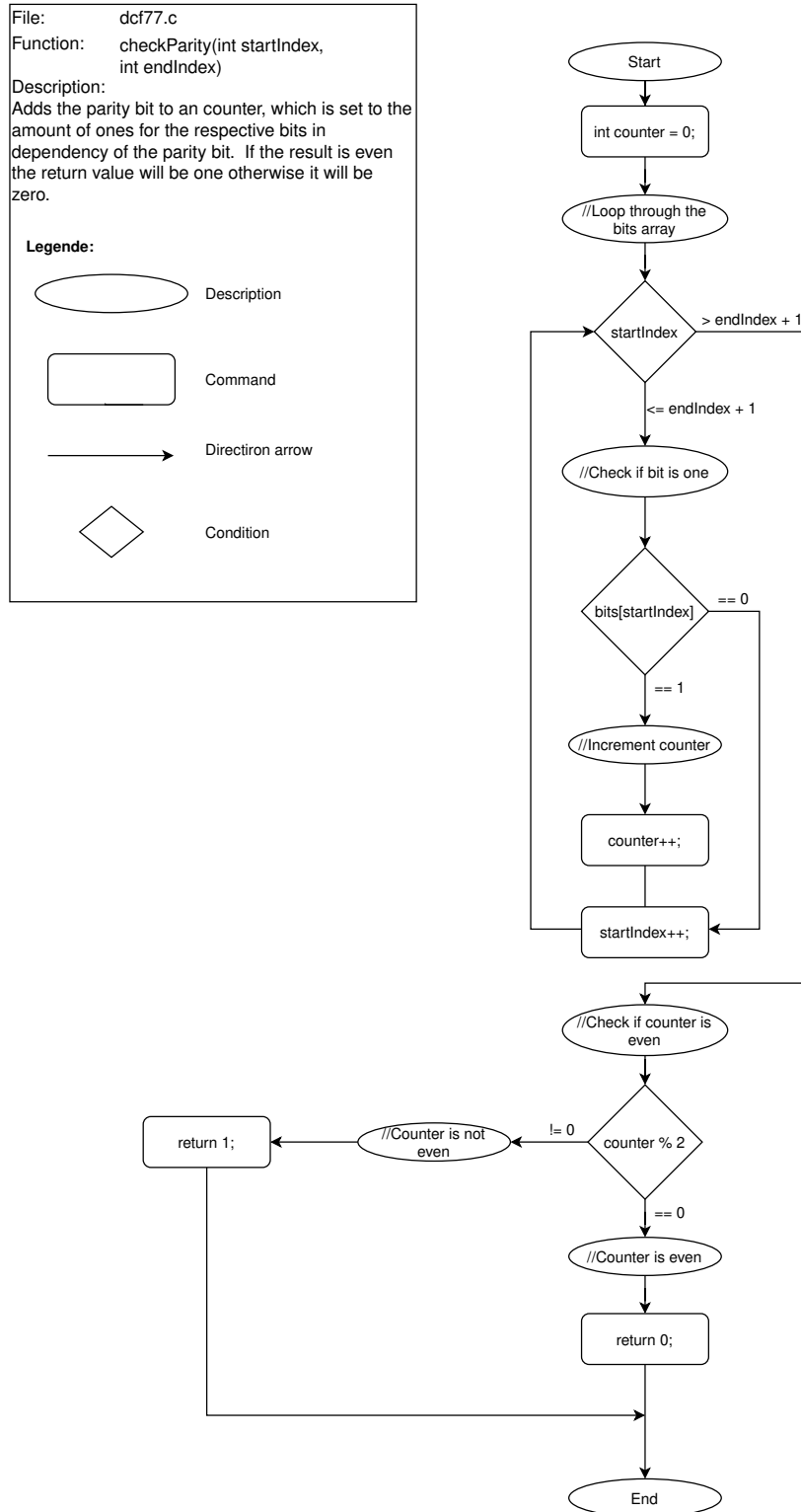


**Figure 20:** Flowchart diagramm of function *decodeDateTime*

This function is used to decode the BCD bit stream. The position of the minutes, hours, day, month, year and weekDay have a fixed position in the stream. Index 21-27 is used for the minutes, 29-34 is used for the hours, 36-41 is used for the day of month, 45-49 is used for the month, 50-57 is used for the last two digits of the year. Additionally we need to add 2000 to the BCD encoded year. After that we check the even parity bits at position 28 for the minutes, 35 for the hours and bit at position 58 for the date. In case of a valid date and time, we set the LED on PORT B.2 to on and call the function

setClock(), to update the date and time of the internal clock. In case of an invalid date and/or time, we clear the LED on Port B.2.

#### 6.4.5 int checkParity(int startIndex, int endIndex)



**Figure 21:** Flowchart diagramm of function checkParity

Checks the parity bit to the given startIndex and endIndex. The counter is set to the amount of ones included in the given bit sequence including the parity bit. If the amount of ones is even this function will return zero otherwise it will return one.