

# Image Processing (using OpenCV-Python)

2016年4月12日 星期二

# 型態學轉換

此範例說明如何使用OpenCV的型態學轉換

## 程式碼

import cv2

import numpy as np

from matplotlib import pyplot as plt

img = cv2.imread('d:\images\s.png',0)

kernel = np.ones((5,5),np.uint8)

erosion = cv2.erode(img,kernel,iterations = 1) #只執行一次

dilation = cv2.dilate(img,kernel,iterations = 1)

img2 = cv2.imread('d:\images\s1.png',0)

# opening 相當於先做erosion再做dilation,可移除雜訊

opening = cv2.morphologyEx(img2, cv2.MORPH\_OPEN, kernel)

# closing 相當於先做dilation再做erosion,可將物件中的小洞補起來

 ${\sf closing = cv2.morphologyEx(img2, cv2.MORPH\_CLOSE, kernel)}$ 

plt.subplot(2,3,1),plt.imshow(img,'gray') plt.subplot(2,3,2),plt.imshow(erosion,'gray')

plt.subplot(2,3,3), plt.imshow(dilation, 'gray')

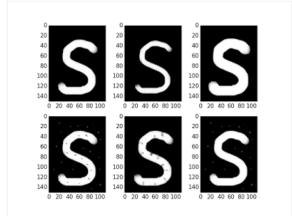
plt.subplot(2,3,4), plt.imshow(img2, 'gray')

plt.subplot(2,3,5),plt.imshow(opening,'gray')

plt.subplot(2,3,6), plt.imshow(closing, 'gray')

plt.show()

# 執行結果







- 1. s.png和s1.png兩張圖形顯示如上。
- 2. 可利用getStructuringElement產生所需要的Structuring Element,

例如下列程式產生相同的kernel

#kernel = np.ones((5,5),np.uint8)

 $kernel = cv2.getStructuringElement(cv2.MORPH\_RECT, (5,5))$ 

3. 下列程式可分別產生橢圓形與十字之Structuring Element cv2.getStructuringElement(cv2.MORPH\_ELLIPSE,(5,5))

cv2.getStructuringElement(cv2.MORPH\_CROSS,(5,5))

## 關於我自己



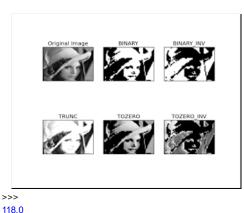


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2016年4月8日 星期五
Thresholding
此範例說明如何使用簡單的thresholding和Otsu's thresholding
程式碼
import cv2
import numpy as np
from matplotlib import pyplot as plt
img = cv2.imread('d:\images\lena6040.bmp'.0)
# BINARY th=127, maxval=255, des=maxval if src>th; otherwise, des = 0
ret,thresh1 = cv2.threshold(img,127,255,cv2.THRESH_BINARY)
# BINARY_INV th=127, maxval=255, des=0 if src>th; otherwise, des = maxval
ret,thresh2 = cv2.threshold(img,127,255,cv2.THRESH_BINARY_INV)
            th=127, maxval=255, des=th if src>th; otherwise, des = src
ret,thresh3 = cv2.threshold(img,127,255,cv2.THRESH TRUNC)
# TOZERO th=127, maxval=255, des=src if src>th; otherwise, des = 0
ret,thresh4 = cv2.threshold(img,127,255,cv2.THRESH_TOZERO)
# TOZERO_INV th=127, maxval=255, des=0 if src>th; otherwise, des = src
ret,thresh5 = cv2.threshold(img,127,255,cv2.THRESH_TOZERO_INV)
titles = ['Original Image', 'BINARY', 'BINARY_INV', 'TRUNC', 'TOZERO', 'TOZERO_INV']
images = [img, thresh1, thresh2, thresh3, thresh4, thresh5]
for i in xrange(6):
  plt.subplot(2,3,i+1),plt.imshow(images[i],'gray')
  plt.title(titles[i])
  plt.xticks([]),plt.yticks([])
plt.show()
# Otsu's thresholding
#回傳值ret為最佳之門檻值
# 若以ret來當Canny edge detection的high threshold,
# 0.5*ret當low threshold, 通常可以得到很好之邊緣偵測結果
ret, th2 = cv2.threshold(img, 0,255,cv2.THRESH_BINARY+cv2.THRESH_OTSU)
print ret
plt.imshow(th2,'gray')
plt.show()
```

# 執行結果



2016年4月6日 星期三

# Histograms - 1

此範例說明如何找到圖形的histogram,並且畫出來。

## 程式碼

import cv2 import numpy as np import matplotlib.pyplot as plt

# # Read an image

img = cv2.imread('d:\images\lena.bmp')
img\_g = cv2.imread('d:\images\lena.bmp',0) # grayscale image

# #直接利用Matplotlib之pyplot的hist函式畫出histogram

plt.hist(img\_g.ravel(),256,[0,256]); plt.show()

```
color = ('b', 'g', 'r')
for i,col in enumerate(color): #的值為0,1,2; col的值為'b', 'g', 'r'
histr =cv2.calcHist([img],[i],None,[256],[0,256])
plt.plot(histr,color=col) #分別畫出b, g, r平面的histogram
plt.xlim([0,256]) #根制x軸的範圍為0~255
```

plt.show()

# 說明

cv2.calcHist(images, channels, mask, histSize, ranges[, hist[, accumulate]]) 參數

images: 影像來源, uint8 or float32格式, 必須以中括號的格式給定"[img]" channels: 灰階影像為[0], 彩色影像為[0], [1], or [2]分別求[0], r的histogram

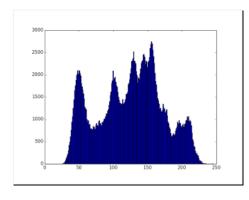
mask: 整張影像設定為None, 部分影像可設定區域

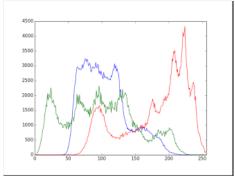
histSize: 即BIN值, 若是全部值則設定為"[256]", 若只要16個值(0~15, 16~31, 32~47, ...)則設定為"

[16]"

ranges: intensity值的範圍, 若是所有的灰階值則設定為"[0,256]"

# 執行結果





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張貼者: Michael Su 於 上午5:57 沒有留言:
2016年4月2日 星期六
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# **Face detection**

此範例說明如何利用Haar cascade進行人臉偵測及眼睛偵測

## 程式碼

import numpy as np import cv2

# #利用OpenCV已訓練好之人臉和眼睛之分類器

# 這兩個分類器存放在OpenCV3.0.0\sources\data\haarcascades

face\_cascade = cv2.CascadeClassifier('haarcascade\_frontalface\_default.xml') eye\_cascade = cv2.CascadeClassifier('haarcascade\_eye.xml')

# #讀取divergent電影之宣傳海報檔

img = cv2.imread('d:\images\divergent2.jpg') gray = cv2.cvtColor(img, cv2.COLOR\_BGR2GRAY) faces = face\_cascade.detectMultiScale(gray, 1.3, 5) for (x,y,w,h) in faces: cv2.rectangle(img,(x,y),(x+w,y+h),(255,0,0),2) # 畫藍色矩形 roi\_gray = gray[y:y+h, x:x+w] #設定人臉之ROI位置  $roi\_color = img[y:y+h, x:x+w]$ eyes = eye\_cascade.detectMultiScale(roi\_gray) # 眼睛偵測 for (ex,ey,ew,eh) in eyes: cv2.rectangle(roi\_color,(ex,ey),(ex+ew,ey+eh),(0,255,0),2) cv2.imshow('img',img) cv2.imwrite('d:\images\divergent\_dt.jpg',img) #儲存影像 cv2.waitKey(0)

# 執行結果

cv2.destroyAllWindows()



由上圖可知, 最右邊的人

# 臉並沒有偵測到

只有三個人的眼睛有被偵測到, 且女主角的眼睛只偵測到右眼 因此,人的頭和眼睛面積太小,可能會偵測不到

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張貼者: Michael Su 於 上午4:54 沒有留言:
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2016年3月29日 星期二

# K-means

此範例說明如何利用K-means做分群

# 程式碼

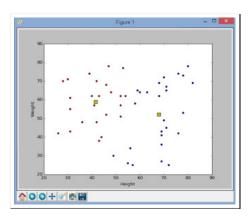
import numpy as np import cv2 from matplotlib import pyplot as plt

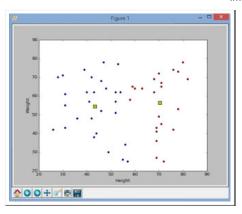
# # 1D case

x = np.random.randint(25,100,25)y = np.random.randint(175,255,25) #產生25個隨機變數,每個數的值介於(175,255)之間 z = np.hstack((x,y))

```
z = z.reshape((50,1))
                                      #合併成一個序列
z = np.float32(z)
                                     #轉成浮點數,以便輸入至kmeans
plt.hist(z,256,[0,256]),plt.show()
# Define criteria = ( type, max_iter = 10 , epsilon = 1.0 ) # max_iter 或epsillon任一條件滿足即停止
criteria = (cv2.TERM_CRITERIA_EPS + cv2.TERM_CRITERIA_MAX_ITER, 10, 1.0)
# Set flags (Just to avoid line break in the code)
flags = cv2.KMEANS_RANDOM_CENTERS
# Apply KMeans (在此K=2, 分兩群)
compactness, labels, centers = cv2.kmeans(z, 2, None, criteria, 10, flags)
A = z[labels==0]
B = z[labels==1]
# Now plot 'A' in red, 'B' in blue, 'centers' in yellow
plt.hist(A,256,[0,256],color = 'r')
plt.hist(B,256,[0,256],color = 'b')
plt.hist(centers, 32, [0, 256], color = 'y')
plt.show()
# 2D case
X = np.random.randint(25,80,(25,2)) #產生25個2維的隨機變數,每個數的值介於(25,80)之間
Y = np.random.randint(40,85,(25,2))
Z = np.vstack((X,Y))
# convert to np.float32
Z = np.float32(Z)
# apply kmeans()
#執行5次,以便觀察flags因設定成KMEANS_RANDOM_CENTERS的分類結果
for i in range(5):
  ret, label, center = cv2. kmeans (Z, 2, None, criteria, 1, flags) \\
  # Now separate the data, Note the flatten()
  A = Z[label.ravel()==0]
  B = Z[label.ravel()==1]
  # Plot the data
  plt.scatter(A[:,0],A[:,1]) \\
  plt.scatter(B[:,0],B[:,1],c = 'r')
  plt.scatter(center[:,0],center[:,1],s = 80,c = 'y', \ marker = 's')
  plt.xlabel('Height'),plt.ylabel('Weight')
  plt.show()
```

# 執行結果 (2D case)





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張貼者: Michael Su 於下午8:26
                      沒有留言:
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```

# K-Nearest Neighbour

此範例說明如何利用kNN做分類

# 程式碼

import cv2 import numpy as np import matplotlib.pyplot as plt

# Feature set containing (x,y) values of 20 known/training data # 每個random number的值介於(0,100), 20個2維的數值 trainData = np.random.randint(0,100,(20,2)).astype(np.float32)

# Labels each one either Red or Blue with numbers 0 and 1 #任意指定20個值為0或1

responses = np.random.randint(0,2,(20,1)).astype(np.float32)

# Take Red families and plot them; 0 表示紅色 red = trainData[responses.ravel()==0] plt.scatter(red[:,0],red[:,1],80,'r','^')

# Take Blue families and plot them; 1 表示藍色

blue = trainData[responses.ravel()==1] plt.scatter(blue[:,0],blue[:,1],80,'b','s')

# #產生一個值介於(0,100)的2維數值

newcomer = np.random.randint(0,100,(1,2)).astype(np.float32) plt.scatter(newcomer[:,0],newcomer[:,1],80,'g','o')

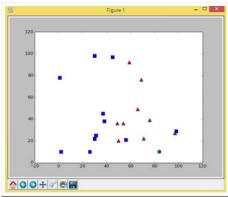
knn = cv2.KNearest()

#k=3,找出距離newcomer最近的3個點 knn.train(trainData,responses) ret, results, neighbours ,dist = knn.find\_nearest(newcomer, 3)

print "result: ", results," $\n$ " print "neighbours: ", neighbours, "\n" print "distance: ", dist

plt.show()

# 執行結果



result: [[ 0.]]

neighbours: [[ 0. 0. 1.]]

distance: [[ 313. 458. 557.]]

由結果可知, newcomer(綠色點)被歸類為紅色(result: 0), 其中最近的k(k=3)個neighbors, 有2個紅色1個藍色。事實上, k可設成偶數, 例如k=4, 若有2個紅色2個藍色距離最近, 則會根據加總後的距離來判斷最後的結果, 最少者為其分類結果

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張貼者: Michael Su 於 上午12:01 沒有留言:
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2016年3月28日 星期一

# 畫圖函式

此範例說明如何利用OpenCV的畫圖函式畫圖。

### 程式碼

import numpy as np import cv2

# # Create a black image

img = np.zeros((450,450,3), np.uint8)

# # Draw a diagonal red line with thickness of 3 px

img = cv2.line(img,(10,10),(200,200),(0,0,255),3) # (B, G, R)

# # Drawing rectangle

img = cv2.rectangle(img,(20,50),(100,250),(0,255,0),3)

# # Drawing circle

img = cv2.circle(img,(200,100), 50, (255,0,0), -1)

## # Drawing ellipse

img = cv2.ellipse(img,(300,300),(100,50),0,0,180,255,-1)

# # Drawing polygon

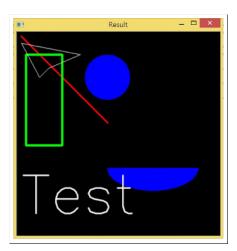
pts = np.array([[10,25],[140,50],[70,80],[50,100]], np.int32)
pts = pts.reshape((-1,1,2)) #ROWSx1x2 在此ROWS等於4,有4個頂點,格式必須是int32
img = cv2.polylines(img,[pts],True,(255,255,255)) #white

# # Adding text

font = cv2.FONT\_HERSHEY\_SIMPLEX cv2.putText(img,'Test',(10,400), font, 4,(255,255,255),2,cv2.LINE\_AA)

cv2.imshow('Result',img) cv2.waitKey(0) cv2.destroyAllWindows()

# 執行結果



# 存取Video

此範例說明如何利用OpenCV的模組,存取Video。

# 程式碼

```
import cv2
import numpy as np
```

## # Read from camera

```
cap = cv2.VideoCapture(0)
# Read from file
# cap = cv2.VideoCapture('akiyo.avi')
```

```
# Define the codec and create VideoWrither object
fcc = cv2.VideoWriter_fourcc(*'MJPG') # MJPG, XVID, X264, WMV1, WMV2
out = cv2.VideoWriter('test1.avi',fcc,20.0,(640,480))
while (cap.isOpened()):
  ret, frame = cap.read()
  if ret==True:
    frame = cv2.flip(frame,0) # 畫面上下巓倒
     out.write(frame)
                                # 將frame儲存至test1.avi
     cv2.imshow('image',frame)
     if cv2.waitKey(1) & 0xFF == ord('q'):
       break
```

# #Release everything

else: break

```
cap.release()
out.release()
cv2.destroyAllWindows()
```

# 說明

利用FourCC指定編解碼的格式,並利用VideoWriter存檔

# 執行結果



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# 存取images

此範例說明如何利用OpenCV的模組,存取影像。

# 程式碼

import cv2 import numpy as np import matplotlib.pyplot as plt

# # Read an image

img = cv2.imread('d:\images\lena.bmp')  $img\_g = cv2.imread('d:\images\ensuremath{\mbox{lena.bmp'}},0) \# grayscale image$ 

# # Display an image

cv2.imshow('gray image',img\_g) cv2.waitKey(0)

cv2.destroyAllWindows()

# # Use Matplotlib

## Color image loaded by OpenCV is in BGR mode ## But Matplotlib displays in RGB mode

b,g,r = cv2.split(img)

img2 = cv2.merge([r,g,b])

plt.subplot(121);plt.imshow(img) # expects distorted color plt.subplot(122);plt.imshow(img2) # expect true color

plt.show()

# # Write an image

cv2.imshow('bgr image',img) # expects true color cv2.imshow('rgb image',img2) # expects distorted color k = cv2.waitKey(0)

if k == 27: # wait for ESC key to exit

cv2.destroyAllWindows()

elif k == ord('s'): # wait for 's' key to save and exit

cv2.imwrite('d:\images\lena\_t.jpg',img)

cv2.destroyAllWindows()

## 說明

- 1. 先利用import載入cv2, numpy(底下用np表示), 和matplotlib.pyplot(底下用plt表示)模組
- 2. 利用cv2.imread讀取彩色影像lena.bmp
- 3. 利用cv2.imread讀取lena.bmp的灰階值
- 4. 顯示img\_g影像, 並且等待按鍵
- 5. 取出img之[b, g, r]成分,並且組成[r, g, b]之img2影像以便利用Matplotlib顯示影像
- 6. 利用subplot分割畫面,顯示結果如下
- 7. 利用cv2.imshow分別顯示img, 和img2
- 8. 等待按鍵, 並將值存在變數k
- 9. 當按鍵是Esc時, 則exit, 否則, 將img另存成新檔lena\_t.jpg

# 執行結果



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