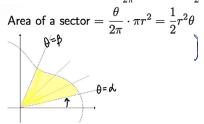
15.4: Double Integrals in Polar Form

Area of a polar region is based on the area of a sector of a circle.

- Area of a circle: πr^2
- Area of a sector: $rac{ heta}{2\pi} \cdot \pi r^2 = rac{1}{2} r^2 heta$



$$egin{aligned} ext{Area of polar region} &= \int_{lpha}^{eta} rac{1}{2} r^2 \, d heta \ &= \int_{lpha}^{eta} \int_{a}^{b} r \, dr \, d heta \ &= \iint_{R} r \, dr \, d heta \end{aligned}$$

(Note that $\int_a^b r\,dr=rac{1}{2}r^2ig|_a^b$

$$dA = r dr d\theta = dx dy$$

Given $F(r, \theta)$ is continuous on $\Gamma : a \le r \le b, \alpha \le \theta \le \beta$:

$$\iint_{\Gamma} F(r, heta) r \, dr \, d heta = \int_{lpha}^{eta} \int_{a}^{b} F(r, heta) r \, dr \, d heta$$

Given $F(r,\theta)$ is continuous on $\Omega: \alpha \leq \theta \leq \beta, \rho_1(\theta) \leq r \leq \rho_2(\theta)$:

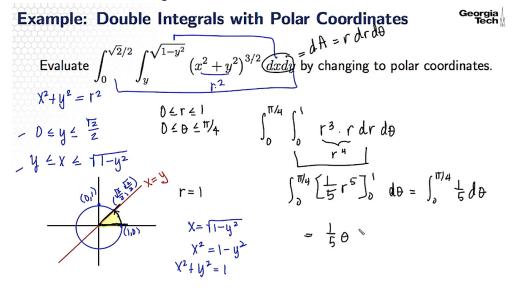
$$\iint_{\Omega} F(r, heta) r \, dr \, d heta = \int_{lpha}^{eta} \int_{
ho_1(heta)}^{
ho_2(heta)} F(r, heta) r \, dr \, d heta$$

(Same applies for other orientations of this)

If $F(r,\theta) \geq 0$ over region R, then volume with R as base, bounded above by $F(r,\theta)$ is:

$$V = \iint_R F(r, heta) r \, dr \, d heta$$

(same as double integrals above)



15.5: Triple Integrals

Instead of working with two variables continuous over a plane, THREE variables!

Integration over a box

Given f(x,y,z) continuous on box $B: a_x \leq x \leq b_x, a_y \leq y \leq b_y, a_z \leq z \leq b_z$

$$\iiint_B f(x,y,z)\,dV = \int_{a_z}^{b_z} \int_{a_y}^{b_y} \int_{a_x}^{b_x} f(x,y,z)\,dx\,dy\,dz$$

Bounds are the same idea for general regions, too

Volume

$$V = \iiint_D dV$$

Average Value

The average value of a function F over region D in space is:

Average Value of
$$F$$
 over $D = \frac{1}{\text{Volume of } D} \iiint_D F \, dV$

15.6: Applications of Double & Triple Integrals

Mass and First Moments

In three dimensions

Mass:

$$M = \iiint_D
ho \, dV$$

First moments about the coordinate planes:

$$egin{aligned} M_{yz} &= \iiint_D x
ho \, dV \ M_{xz} &= \iiint_D y
ho \, dV \ M_{xy} &= \iiint_D z
ho \, dV \end{aligned}$$

Center of mass:

$$egin{aligned} ar{x} &= rac{M_{yz}}{M} \ ar{y} &= rac{M_{xz}}{M} \ ar{z} &= rac{M_{xy}}{M} \end{aligned}$$

When density of solid object is constant ($\rho = 1$), the center of mass is called the **centroid** of the object.

In two dimensions

Mass:

$$M=\iint_D \sigma\,dA$$

First moments about the coordinate planes:

$$M_x = \iint_D x \sigma \, dA \ M_y = \iint_D y \sigma \, dA$$

Center of mass:

$$ar{x} = rac{M_y}{M} \ ar{y} = rac{M_x}{M}$$

Moments of Inertia

In three dimensions

$$I = \iiint r^2
ho \, dV$$

(Around x-axis, r^2 is (y^2+z^2) , etc etc)

In two dimensions

$$I = \iint r^2 \sigma \, dA$$

About origin:

$$I_O = \iint (x^2+y^2)\sigma\,dA = I_x + I_y$$

Joint Probability Density

Joint probability density function f is a function that satisfies:

- 1. $f(x,y)\geq 0$ 2. $\int_{\infty}^{\infty}\int_{\infty}^{\infty}f(x,y)\,dx\,dy=1$ 3. $P((X,Y)\in R)=\iint_Rf(x,y)\,dx\,dy$