16.1, 16.2: Line Integrals

in Scalar Fields

If f is defined on a curve C given parametrically by $\vec{r}(t) = x(t)\mathbf{i} + y(t)\mathbf{j} + z(t)\mathbf{k}$, the line integral of f over C is:

$$\int_C f(x,y,z)\,ds = \lim_{n o\infty} \sum_{k=1}^n f(x_k,y_k,z_k) \Delta s_k$$

To integrate a continuous function f(x, y, z) over a curve C:

1. Find a smooth parametrization of *C*:

$$ec{r}(t) = x(t)\mathbf{i} + y(t)\mathbf{j} + z(t)\mathbf{k}\$\$(where\$a \leq t \leq b\$)$$

2. Evaluate the integral as:

$$\int_C f(x,y,z)\,ds = \int_a^b f(x(t),y(t),z(t)) |ec{v}(t)|\,dt$$

(recall
$$rac{ds}{dt} = |ec{v}|$$
)

Mass and Moment Calculations

Suppose we need to find the mass & moment for coil springs and then rods lying along a smooth curve C in space.

Recall physics definitions from 15.6.

They apply here, too.

Mass

$$m=\int_C \lambda\, ds$$

(this is a pretty straightforward extension of 15.6 so I don't think there needs to be notes here)

in Vector Fields

Let \vec{F} be a vector field with continuous components defined along smooth curve C parametrized by $\vec{r}(t), a \leq t \leq b$.

The line integral of \vec{F} along C is:

$$\int_C ec{F} \cdot ec{T} \, ds = \int_C \left(F \cdot rac{dec{r}}{ds}
ight) \! ds = \int_C ec{F} \cdot dec{r} \, .$$

To evaluate, write \vec{F} and $d\vec{r}$ in terms of t and apply dot product.

Line integrals may also be written as:

$$egin{aligned} &\int_C M\,dx + \int_C N\,dy + \int_C P\,dz \ &= \int_C M(x,y,z)\,dx + \int_C N(x,y,z)\,dy + \int_C P(x,y,z)\,dz \end{aligned}$$

(same idea, write everything in terms of t)

Example

Evaluate $\int_C \vec{F} \cdot dr$, where $\vec{F} = \langle xy, x^2z, xyz \rangle$ along $y = x^2$ from (0,0,0) to (1,1,0) followed by the straight-line segment from (1,1,0) to (1,1,1).

$$C_1:ec{r}_1(t)=\langle t,t^2,0
angle \ ec{r}_1'(t)=\langle 1,2t,0
angle$$

$$C_2:ec{r}_2(t)=\langle 1,1,t
angle \ ec{r}_2'(t)=\langle 0,0,1
angle$$

$$egin{aligned} &\int_C ec{F} \cdot dec{r} \ &= \int_0^1 \langle (t)(t^2),0,0
angle \cdot \langle 1,2t,0
angle \, dt + \int_0^1 \langle (1)(1),(1)^2(t),(1)(1)(t)
angle \cdot \langle 0,0,1
angle \, dt \ &= \int_0^1 \langle t^3,0,0
angle \cdot \langle 1,2t,0
angle \, dt + \int_0^1 \langle 1,t,t
angle \cdot \langle 0,0,1
angle \, dt \end{aligned}$$

Applications to Physics

Work

$$W = \int_C ec{F} \cdot dec{r}$$

• \vec{F} is force

Flow

$$ext{Flow} = \int_C ec{F} \cdot ec{T} \, ds$$

• \vec{F} is velocity

This integral is called a **flow integral**. If the curve starts and ends at the same point, the flow is called the *circulation* around the curve.

Flux (across a smooth simple closed plane curve)

$$\Phi = \int_C ec F \cdot \hat n \, ds$$

- ullet $ec{F}$ is a vector field in the plane, $M(x,y)\mathbf{i}+N(x,y)\mathbf{j}$
- C is a smooth simple closed curve (starts & ends at same place and does not cross itself)
- \hat{n} is the outward-pointing unit vector normal to C

Alternative form:

$$\Phi ext{ across } C = \oint M \, dy - N \, dx$$

(Integral is evaluated at any parametrization \vec{r} that traces C counterclockwise exactly once)

Why?

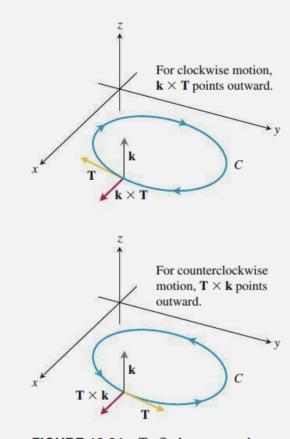


FIGURE 16.24 To find an outward unit normal vector for a smooth simple curve C in the xy-plane that is traversed counterclockwise as t increases, we take $\mathbf{n} = \mathbf{T} \times \mathbf{k}$. For clockwise motion, we take $\mathbf{n} = \mathbf{k} \times \mathbf{T}$.

Assuming counterclockwise,

$$\hat{n}=ec{T} imes \mathbf{k}=egin{bmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \ rac{dx}{ds} & rac{dy}{ds} & 0 \ 0 & 0 & 1 \end{bmatrix}=rac{dy}{ds}\mathbf{i}-rac{dx}{ds}\mathbf{j}$$

Then:

$$egin{aligned} \Phi &= \int_C ec F \cdot \hat n \, ds \ &= \int_C \langle M, N
angle \cdot \left\langle rac{dy}{ds}, rac{-dx}{ds}
ight
angle \, ds \ &= \oint M \, dy - N \, dx \end{aligned}$$

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