16.5: Surfaces and Area

Parameterized Surfaces

A parametrized surface is given by: $\vec{r}(u,v) = f(u,v)\mathbf{i} + g(u,v)\mathbf{j} + h(u,v)\mathbf{k}$.

The domain is the set of points in the uv-plane that can be substituted into \vec{r} .

Sphere: $x^2 + y^2 + z^2 = a^2$

 $\vec{r}(\phi,\theta) = a\sin\phi\cos\theta\mathbf{i} + a\sin\phi\sin\theta\mathbf{j} + a\cos\phi\mathbf{k}$ (pretty straightforward mapping of spherical coordinates)

$$(0 \le \phi \le \pi, 0 \le \theta \le 2\pi)$$

Cylinder: $x^2 + y^2 = a^2, 0 \le z \le b$

 $\vec{r}(\theta,z) = a\cos\theta \mathbf{i} + a\sin\theta \mathbf{j} + z\mathbf{k}$ (pretty straightforward mapping of cylindrical coordinates) $(0 \le \theta \le 2\pi, 0 \le z \le b)$

Cone: $z = \sqrt{x^2 + y^2}, 0 \le z \le b$ $\vec{r}(r, \theta) = r \cos \theta \mathbf{i} + r \sin \theta \mathbf{j} + r \mathbf{k}$

$$(0 < r < b, 0 < \theta < 2\pi)$$

Example

Find the parametrization for $z=4-x^2-y^2, z\geq 0$.

$$z=4-x^2-y^2 \ =4-r^2$$

$$\therefore r \leq 2$$

The parametrization:

$$ec{r}(r, heta) = r\cos heta \mathbf{i} + r\sin heta \mathbf{j} + (4-r^2)\mathbf{k}$$

$$(0 \le r \le 2, 0 \le \theta < 2\pi)$$

Surface Area

A parametrized surface $\vec{r}(u,v)=f(u,v)\mathbf{i}+g(u,v)\mathbf{j}+h(u,v)\mathbf{k}$ is **smooth** if \vec{r}_u and \vec{r}_v are continuous and $\vec{r}_u \times \vec{r}_v \neq 0$ on the interior of the parameter domain.

SA of Parametrized Surfaces

Given smooth surface $\vec{r}(u,v)=f(u,v)\mathbf{i}+g(u,v)\mathbf{j}+h(u,v)\mathbf{k}, a\leq u\leq b, c\leq v\leq d$:

$$\sigma = \iint_R |ec{r}_u imes ec{r}_v| \, dA = \int_c^d \int_a^b |ec{r}_u imes ec{r}_v| \, du \, dv$$

Why?

For a small rectangular area $\Delta \sigma$ on the surface,

$$egin{aligned} \Delta\sigma &= |(ec{r}_u\cdot\Delta u) imes(ec{r}_v\cdot\Delta v)| \ &= |ec{r}_u imesec{r}_v|\Delta u\Delta v \end{aligned}$$

So, $d\sigma = |\vec{r}_u imes \vec{r}_v| \, du \, dv$.

SA of Implicit Surfaces

Area of surface F(x, y, z) = c over closed & bounded region R:

$$\sigma = \iint_R rac{\|
abla F\|}{|
abla F \cdot \hat{p}|} \, dA$$

(where $\hat{p}=\mathbf{i},\mathbf{j}, \text{ or } \mathbf{k}$ is normal to R and $abla F\cdot\hat{p}
eq 0$)

Why?

Create \mathfrak{shadow} region R (a projection of the surface onto a coordinate plane), and let \hat{p} be the normal vector of R.

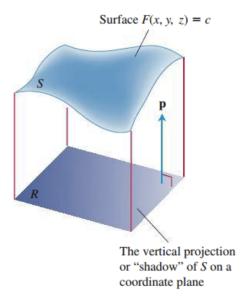


FIGURE 16.47 As we soon see, the area of a surface S in space can be calculated by evaluating a related double integral over the vertical projection or "shadow" of S on a coordinate plane. The unit vector \mathbf{p} is normal to the plane.

Assume surface is smooth and require $\nabla \cdot \hat{p} \neq 0$.

Let R be the xy-plane (then $\hat{p} = \mathbf{k}$). The curve is parametrized as:

$$ec{r}(x,y) = x \mathbf{i} + y \mathbf{j} + z(x,y) \mathbf{k}$$

(note that z(x, y) is not explicitly known)

$$egin{aligned} ec{r}_x &= \mathbf{i} + rac{\partial z}{\partial x} \mathbf{k} = \mathbf{i} - rac{F_x}{F_z} \mathbf{k} \ ec{r}_y &= \mathbf{j} + rac{\partial z}{\partial y} \mathbf{k} = \mathbf{j} - rac{F_y}{F_z} \mathbf{k} \end{aligned}$$

(recall F(x, y, z(x, y)) = 0, so <u>implicit chain rule</u> can be applied)

Then:

$$ec{r}_x imes ec{r}_y = rac{F_x}{F_z} \mathbf{i} + rac{F_y}{F_z} \mathbf{j} + \mathbf{k} \, .$$

(i'm too lazy to show the determinant but just scroll down like 1 scroll, there's a similar cross prod.)

$$egin{align} ec{r}_x imes ec{r}_y &= rac{1}{F_z} (F_x \mathbf{i} + F_y \mathbf{j} + F_z \mathbf{k}) \ &= rac{
abla F}{F_z} \ &= rac{
abla F}{
abla F \cdot \hat{m{n}}}
onumber \end{array}$$

Plug back in and bam equation.

SA for
$$z = f(x, y)$$

$$\sigma = \iint_R \sqrt{f_x^2 + f_y^2 + 1} \, dx \, dy$$

Why?

z=f(x,y) can be parametrized as $ec{r}(x,y)=x\mathbf{i}+y\mathbf{j}+f(x,y)\mathbf{k}.$

Then:

$$egin{aligned} ec{r}_x &= \mathbf{i} + f_x \mathbf{k} \ ec{r}_y &= \mathbf{j} + f_y \mathbf{k} \ ec{r}_x imes ec{r}_y &= egin{bmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \ 1 & 0 & f_x \ 0 & 1 & f_y \ \end{bmatrix} = -f_x \mathbf{i} - f_y \mathbf{j} + \mathbf{k} \end{aligned}$$

So:

$$\sigma = \iint_{R} \left| ec{r}_{u} imes ec{r}_{v}
ight| dA = \sqrt{f_{x}^{2} + f_{y}^{2} + 1} \, dx \, dy$$

16.6: Surface Integrals

Definition

Surface area differential:

$$d\sigma = |ec{r}_u imes ec{r}_v| \, du \, dv$$

Surface integral of G over surface S

$$\iint_S G(x,y,z)\,d\sigma = \lim_{n o\infty} \sum_{k=1}^n G(x_k,y_k,z_k) \Delta\sigma_k$$

Surface integrals of scalar functions

You can substitute $d\sigma$ for the surface area formulas above (<u>Surface Area</u>) depending on which condition you meet.

Parametrized surface

Given smooth surface $\vec{r}(u,v)=f(u,v)\mathbf{i}+g(u,v)\mathbf{j}+h(u,v)\mathbf{k}, (u,v)\in R$

$$\iint_S G(x,y,z) d\sigma = \iint_R G(f(u,v),g(u,v),h(u,v)) |ec{r}_u imes ec{r}_v| \, du \, dv$$

Implicit surface

$$\iint_S G(x,y,z) d\sigma = \iint_R G(x,y,z) rac{\|
abla F\|}{|
abla F \cdot \hat{p}|} \, dA$$

(S lies above its closed & bounded shadow region R in the coordinate plane beneath it) (where $\hat{p} = \mathbf{i}, \mathbf{j}$, or \mathbf{k} is normal to R and $\nabla F \cdot \hat{p} \neq 0$)

For
$$z=f(x,y)$$

$$\iint_S G(x,y,z)d\sigma = \iint_R G(x,y,f(x,y)) \sqrt{f_x^2+f_y^2+1}\,dx\,dy$$

(R is the region on the xy-plane)

Surface integrals of vector fields

Let \vec{F} be a vector field in 3D space with continuous components defined over a smooth surface S, with normal unit vectors \hat{n} orienting S.

The surface integral of \vec{F} over S:

$$\iint_S \vec{F} \cdot \hat{n} \, d\sigma$$

This integral is also called the **flux** of the vector field \vec{F} across S.

If the surface being integrated over can be written as g(x,y,z)=c,

$$\hat{n} = \pm rac{
abla g}{\|
abla g\|}$$

If the surface being integrated over can be parametrized as $\vec{r}(u,v)$, the surface integral can be calculated as:

$$\iint_S ec{F} \cdot (ec{r}_u imes ec{r}_v) \, du \, dv$$

Mass & Moment

Same as 15.6 Apps of Double & Triple Integrals > Physics Definitions, but with:

$$dm = \delta d\sigma$$

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