14.9: Taylor's Formula for f(x,y)

Taylor Polynomial (recap)

If function f has n derivatives at point where x = a, then the nth Taylor Polynomial for f at a is:

$$P_n(x) = \sum_{k=0}^n rac{f^{(k)}(a)(x-a)^k}{k!}$$

The theorem

If f has n+1 derivatives on an open interval containing a, then for every x in that open interval, we have:

$$f(x) = P_n(x) + \underbrace{rac{f^{(n+1)}(c)}{(n+1)!}(x-a)^{n+1}}_{ ext{error term}}$$

for some (estimated) value c between a and x that maximizes that term.

The absolute value of last term is called the error when using $P_n(x)$ to approximate f(x).

$$ext{error} = |f(x) - P_n(x)| = rac{|f^{(n+1)}(c)|}{(n+1)!} |x-a|^{n+1}$$

Give an error estimate for the approximation of $\cos(2x)$ by $P_{\underline{10}}(x)$ for an arbitrary x between 0 and $\pi/4$ centered at x=0.

error
$$\leq \frac{|f^{(n+1)}(c)|}{(n+1)!} (x-a)^{n+1}$$

$$f'(x) = -2 \sin(2x)$$

$$f''(x) = -\frac{1}{2} \cos(2x)$$

$$f'''(x) = 8 \sin(2x)$$

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(I believe this was done in BC)

Two Variables

Suppose f(x,y) and its partials through order n+1 are continuous throughout open rectangular region R centered around (a,b).

Then, throughout R:

$$f(a+h,b+k) = \sum_{i=0}^n rac{1}{i!}igg(hrac{\partial}{\partial x} + krac{\partial}{\partial y}igg)^i figg|_{(a,b)} + E(a+h,b+k)$$

The last term E(a+h,b+k) is the error term. It is evaluated at the point on the line segment connecting (a,b) and (a+h,b+k) that maximizes the error term.

This error term is defined as:

$$E(a+h,b+k) = rac{1}{(n+1)!}igg(hrac{\partial}{\partial x} + krac{\partial}{\partial y}igg)^{(n+1)}figg|_{(a+ch,b+ck)}$$

Expanded form

$$egin{aligned} f(a+h,b+k) &= f(a,b) + (hf_x + kf_y)|_{(a,b)} \ &+ rac{1}{2!}(h^2f_{xx} + 2hkf_{xy} + k^2f_{yy})|_{(a,b)} \ &+ rac{1}{3!}(h^3f_{xxx} + 3h^2kf_{xxy} + 3hk^2f_{xyy} + k^3f_{yyy})|_{(a,b)} \ &+ \cdots \ &+ rac{1}{n!}igg(hrac{\partial}{\partial x} + krac{\partial}{\partial y}igg)^n figg|_{(a,b)} \end{aligned}$$

Wait, isn't the two-variable Taylor's formula an extension of single-variable Taylor's? Where's the (x-a) term?

Note that in the single-variable Taylor's formula, x represents... just x.

However, two-variable Taylor's does not use x. It defines h and k, which represent a *relative* distance from a and b.

You can also write single-variable Taylor's in the form of the evaluation point x = a and a relative distance h from that evaluation point (i.e. let x = a + h):

$$f(a+h) = \sum_{k=0}^n rac{h^k f^{(k)}(a)}{k!} + \underbrace{rac{h^{n+1} f^{(n+1)}(c)}{(n+1)!}}_{ ext{error term}}$$

This aligns much more closely to the two-variable formula.

14.10: Partial Derivatives w/ Constraints

Previous <u>partial derivatives</u> assumed all variables were independent, but what if some of the variables have known relationships?

The notation $\left(\frac{\partial w}{\partial y}\right)_{z,t}$ represents the partial derivative of w with respect to y, given that z and t are independent of y.

To evaluate a partial derivative with constraints:

1. Decide which variables are dependent & independent

- 2. Eliminate the other dependent variables
- 3. Differentiate and solve

Example

If
$$w=x^2+y-z+\sin(t)$$
 and $x+y=t$, find $\left(rac{\partial w}{\partial y}
ight)_{z,t}$

Method 1: Eliminating other independent variables first.

Since x + y = t, substitute x = t - y into w, resulting in:

$$w = (t-y)^2 + y - z + \sin(t)$$

All of the variables are now independent, so just compute the partial.

$$rac{\partial w}{\partial y} = -2(t-y) + 1$$

Method 2: Deriving on the go.

We know x is dependent on y, so $\frac{\partial x}{\partial y}$ must be non-zero.

$$rac{\partial w}{\partial y} = 2xrac{\partial x}{\partial y} + 1$$

Then, since x = t - y,

$$\frac{\partial x}{\partial y} = -1$$

Substitute $\frac{\partial x}{\partial y}$ and x , you get the answer from before.

#module2 #week6