15.8: Integration by Substitution

Jacobians

Jacobian determinate or **Jacobian** of the coordinate transformation x = g(u, v), y = h(u, v):

$$J(u,v) = \left| rac{\partial(x,y)}{\partial(u,v)}
ight| = \left| egin{array}{cc} rac{\partial x}{\partial u} & rac{\partial x}{\partial v} \ rac{\partial y}{\partial v} & rac{\partial y}{\partial v} \end{array}
ight| = rac{\partial x}{\partial u} rac{\partial y}{\partial v} - rac{\partial y}{\partial u} rac{\partial x}{\partial v}$$

The two coordinate systems are related by:

$$dx\,dy=\left|rac{\partial(x,y)}{\partial(u,v)}
ight|du\,dv$$

Why?

The Jacobian transform maps the uv-coordinate system onto the xy-coordinate system. In a mapping from uv to xy, the area du dv will be multiplied by a factor of the determinant of the transform (recall from linear algebra) to get the corresponding area dx dy.

Extension into 3D

Jacobians can also be extended pretty trivially to 3 dimensions. Given x = g(u, v, w), y = h(u, v, w), z = k(u, v, w),

$$J(u,v,w) = \left| rac{\partial(x,y,z)}{\partial(u,v,w)}
ight| = \left| egin{array}{cccc} rac{\partial x}{\partial u} & rac{\partial x}{\partial v} & rac{\partial x}{\partial w} \ rac{\partial y}{\partial u} & rac{\partial y}{\partial v} & rac{\partial y}{\partial w} \ rac{\partial z}{\partial u} & rac{\partial z}{\partial v} & rac{\partial z}{\partial w} \end{array}
ight|$$

Double Integrals

Suppose f(x,y) is continuous over region R. Let G be preimage of R under transform x=g(u,v),y=h(u,v) (assumed to be one-to-one on interior of G). If functions g and h have continuous 1st partial derivatives within interior of G:

$$\iint_R f(x,y)\,dx\,dy = \iint_G f(g(u,v),h(u,v)) \overbrace{\left|rac{\partial(x,y)}{\partial(u,v)}
ight|}^{ ext{Jacobian}} du\,dv$$

Triple Integrals

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$$egin{aligned} &\iiint_R f(x,y,z)\,dx\,dy\,dz \ &= \iiint_G f(g(u,v,w),h(u,v,w),k(u,v,w)) \left|rac{\partial(x,y,z)}{\partial(u,v,w)}
ight|du\,dv\,dw \end{aligned}$$

Derivation of Spherical Triple Integral by Jacobians

Spherical coordinates:

$$x = \rho \sin \phi \cos \theta$$

 $y = \rho \sin \phi \sin \theta$
 $z = \rho \cos \phi$

Derivation:

$$dx\,dy\,dz = \overbrace{\left|rac{\partial(x,y,z)}{\partial(
ho,\phi, heta)}
ight|} d
ho\,d\phi\,d heta$$

$$\begin{split} \frac{\partial(x,y,z)}{\partial(\rho,\phi,\theta)} &= \begin{vmatrix} \frac{\partial x}{\partial \rho} & \frac{\partial x}{\partial \phi} & \frac{\partial x}{\partial \theta} \\ \frac{\partial y}{\partial \rho} & \frac{\partial y}{\partial \phi} & \frac{\partial y}{\partial \theta} \\ \frac{\partial z}{\partial \rho} & \frac{\partial z}{\partial \phi} & \frac{\partial z}{\partial \theta} \end{vmatrix} \\ &= \begin{vmatrix} \sin\phi\cos\theta & \rho\cos\phi\cos\theta & -\rho\sin\phi\sin\theta \\ \sin\phi\sin\theta & \rho\cos\phi\sin\theta & \rho\sin\phi\cos\theta \\ \cos\phi & -\rho\sin\phi & 0 \end{vmatrix} \end{split}$$

$$=\cos\phi(
ho^2\sin\phi\cos\phi\cos^2 heta+
ho^2\sin\phi\cos\phi\sin^2 heta) \ +
ho\sin\phi(
ho\sin^2\phi\cos^2 heta+
ho^2\sin\phi^2\sin^2 heta)$$

$$=\cos\phi(
ho^2\sin\phi\cos\phi) \ +
ho\sin\phi(
ho\sin^2\phi)$$

$$=
ho^2\sin\phi\cos^2\phi+
ho^2\sin\phi\sin^2\phi$$

$$=
ho^2\sin\phi$$

Therefore, $dV=dx\,dy\,dz=
ho^2\sin\phi\,d\rho\,d\phi\,d\theta$

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