# 14.5: Directional Derivatives and the Gradient

### **Directional Derivatives**

 $f'_{\vec{u}}(x_0,y_0)$  or  $D_{\vec{u}}f(P_0)$  gives the **directional derivative** of f in the direction of  $\vec{u}$  at the point  $P_0=(x_0,y_0)$ .

• The rate of change of f in the  $\vec{u}$  direction.

If  $ec{u}=u_1\mathbf{i}+u_2\mathbf{j}$  , then

$$D_{ec{u}}f(P_0) = \lim_{s o 0}rac{f(x_0+su_1,y_0+su_2)-f(x_0,y_0)}{s}$$

provided that the limit exists.

### **Example**

Example: Find the directional derivative of  $f(x,y) = x^2 + xy^2$  at the point P(1,1) in the direction of i-j.  $\|\bar{\imath} - \bar{\jmath}\| = \sqrt{2}$   $\|\bar{\imath} - \bar{\jmath}\| = \sqrt{2}$ 

### **Gradients**

**Gradient** of a function f(x, y) is vector

$$abla f(x,y) = rac{\partial f}{\partial x} \mathbf{i} + rac{\partial f}{\partial y} \mathbf{j}$$

You can imagine how to extend this into 3+ dimensions.

### **Properties**

$$egin{aligned} 
abla(f(ec{x})+g(ec{x})) &= 
abla f(ec{x}) + 
abla g(ec{x}) \ 
abla(lpha f(ec{x})) &= lpha 
abla f(ec{x}) \ 
abla(f(ec{x})g(ec{x})) &= f(ec{x}) 
abla g(ec{x}) + 
abla f(ec{x})g(ec{x}) \end{aligned}$$

#### **Directional Derivative**

**Directional derivative** of f in the direction of  $\vec{u}$  at point  $P_0 = (x_0, y_0)$  can be written as:

$$f'_{\vec{u}}(P_0) = 
abla f(P_0) \cdot \hat{u} = \|
abla f(P_0)\| \cos \theta$$

#### **Properties**

- 1. At P, function f increases most rapidly in the direction of its gradient vector.
- 2. Function f decreases most rapidly in the direction of  $-\nabla f$ .
- 3. Any direction  $\vec{u}$  orthogonal to gradient  $\nabla f \neq 0$  is a direction of zero change in f.

### **Examples**

Find the gradient of  $f(x,y) = 2e^x \sin(x^2 + y)$ 

$$egin{aligned} 
abla f(x,y) &= (4xe^x\cos(x^2+y) + 2e^x\sin(x^2+y))\mathbf{i} \ &+ 2e^x\cos(x^2+y)\mathbf{j} \end{aligned}$$

Find a unit vector in the direction in which f increases most rapidly at P and give the rate of change of f in that direction.

$$f(x,y) = y^{-2}e^{2x} \text{ at } P(0,1)$$

$$\nabla f = \underbrace{\frac{1}{y^2}}_{y^2} \dot{t} - \underbrace{\frac{1}{y^3}}_{y^3} \dot{f}$$

$$||\nabla f(0,1)|| = \sqrt{8} = \underbrace{\frac{1}{\sqrt{2}}}_{y^4} \dot{t} - \frac{1}{\sqrt{2}} \dot{f}$$

$$||\nabla f(0,1)|| = \sqrt{8} = \underbrace{\frac{1}{\sqrt{2}}}_{y^4} \dot{t} - \frac{1}{\sqrt{2}} \dot{f}$$

# **Tangent Lines to Level Curves**

The tangent line to level curve f(x,y)=c at point  $(x_0,y_0)$  is

$$egin{aligned} f_x(x_0,y_0)(x-x_0) + f_y(x_0,y_0)(y-y_0) &= 0 \ rac{\partial f}{\partial x}igg|_{(x_0,y_0)}(x-x_0) + rac{\partial f}{\partial y}igg|_{(x_0,y_0)}(y-y_0) &= 0 \end{aligned}$$

(Can be derived from implicit differentiation rule)

# **Derivative Along a Path**

if  $\vec{r}(t) = x(t)\mathbf{i} + y(t)\mathbf{j} + z(t)\mathbf{k}$  is a smooth path C and  $w = f(\vec{r}(t))$  is a scalar function evaluated along C, then the derivative along that path is

$$rac{d}{dt}f(ec{r}(t)) = 
abla f(ec{r}(t)) \cdot ec{r}'(t)$$

# 14.6: Tangent Planes & Differentials

# **Tangent Planes & Normal Lines**

**Tangent plane** to level surface f(x, y, z) = c of a differentiable function f at point  $P_0(x - 0, y_0, z_0)$  where the gradient is not zero is the plane through  $P_0$  normal to  $\nabla f(x_0, y_0, z_0)$ .

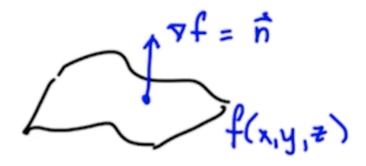
$$egin{aligned} f_x(P_0)(x-x_0)+f_y(P_0)(y-y_0)+f_z(P_0)(z-z_0)&=0\ & 
abla f(P_0)\cdot \overrightarrow{P_0P}&=0 \end{aligned}$$

**Normal line** to level surface f(x, y, z) = c is the line through  $P_0$  parallel to  $\nabla f(x_0, y_0, z_0)$ .

$$x = x_0 + f_x(P_0)t$$
  
 $y = y_0 + f_y(P_0)t$   
 $z = z_0 + f_z(P_0)t$ 

or

$$\vec{r}(t) = P_0 + t \nabla f(P_0)$$



### **Differentials**

#### Linearization

The **linearization** of differentiable function f(x, y) at  $(x_0, y_0)$  is:

$$egin{aligned} L(x,y) &= f(x_0,y_0) + f_x(x_0,y_0)(x-x_0) + f_y(x_0,y_0)(y-y_0) \ L(x,y) &= f(x_0,y_0) + rac{\partial f}{\partial x} \Delta x + rac{\partial f}{\partial y} \Delta y \end{aligned}$$

The approximation  $f(x,y) \approx L(x,y)$  is called the **standard linear approximation** of f at the point.

The **total differential of** f is the resulting change from  $(x_0, y_0)$  to  $(x_0 + dx, y_0, dy)$ 

$$df = f_x(x_0, y_0)dx + f_y(x_0, y_0)dy$$

Error in standard linear approximation when using L to approximate f:

$$|E| \leq rac{1}{2} M (|x-x_0| + |y-y_0|)^2$$

M represents the upper bound of the second partials on the rectangle centered at  $P_0$ .

Extension of above formulas to more dimensions is trivial.

### **More Differentials**

They also help in estimating change in a function in a particular direction.

To estimate the change in value of a differentiable function f when moving a small distance, ds, from point  $P_0$  in the direction of the unit vector  $\hat{u}$ ,

$$df = f_{\hat{u}}'(P_0) ds = (
abla f(P_0) \cdot \hat{u}) ds$$

# 14.7: Extreme Values

#### **Local Extrema**

Let f(x,y) be defined on a region R containing point (a,b). Then:

- 1. f(a,b) is a **local maximum** of f if  $f(a,b) \ge f(x,y)$  for all domain points (x,y) in an open disk around (a,b).
- 2. f(a,b) is a **local minimum** of f if  $f(a,b) \le f(x,y)$  for all domain points (x,y) in an open disk around (a,b).

**First Derivative Test**: If f(x,y) has a local extremum at interior point (a,b), then  $\nabla f(a,b) = \vec{0}$  (all the partial derivatives are 0).

• Critical Points: remember single variable calc?

**Saddle point**: Critical point that isn't a local extremum (some points are greater, some are less)

Second partials test (analogous to the 2nd derivative test):

Used to determine if a critical point is a saddle point or a local min or max

$$egin{aligned} A &= f_{xx}(x_0, y_0) \ B &= f_{xy}(x_0, y_0) \ C &= f_{yy}(x_0, y_0) \ D &= egin{bmatrix} A & B \ B & C \end{bmatrix} = AC - B^2 \end{aligned}$$

- 1. If D < 0,  $(x_0, y_0)$  is a saddle point.
- 2. If D > 0 and A > 0, local minimum.
- 3. If D > 0 and A < 0, local minimum.
- 4. If D = 0, test is inconclusive.

#### **Absolute Extrema**

**Absolute maximum:** Greatest value f(x,y) for all  $(x,y) \in D$ **Absolute maximum:** Smallest value f(x,y) for all  $(x,y) \in D$ 

Process for finding absolute extrema:

- 1. Find critical points in *D*.
- 2. Find extreme points on boundary of D.
- 3. Evaluate f at candidates.
- 4. Yeah.