

Textbook sections: 4.1, 4.4

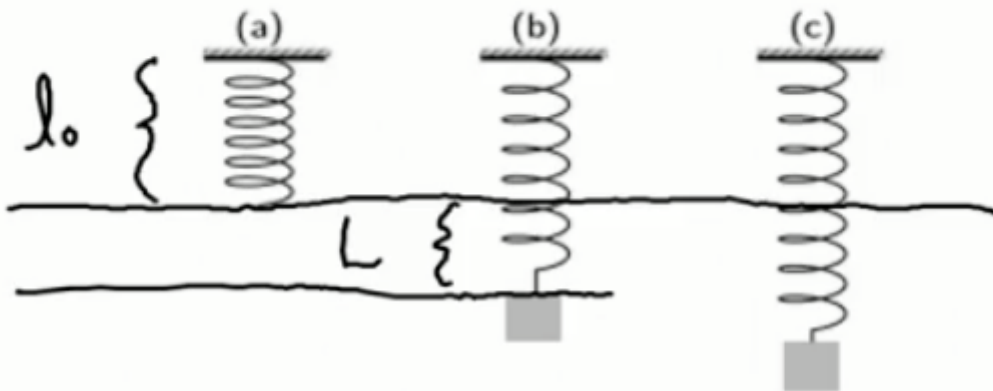
## Examples of 2nd Order LDEs (4.1)

### Spring-Mass Systems

1. Spring of natural length  $l_0$  attached to horizontal surface
2. Mass  $m$ , attached to spring, spring length in equilibrium position is  $L + l_0$
3. Same as (2), but external force extended length of spring

Three cases:

- (a) Spring of natural length  $l_0$  attached to horizontal surface
- (b) Mass  $m$ , attached to spring, spring length in equilibrium position is  $L + l_0$
- (c) Same as (b) except an external force has extended length of spring



For case (2),

$$\begin{aligned}F_g - F_s &= 0 \\mg - kL &= 0\end{aligned}$$

For case (3),

if external force is  $f(t)$ , then

$$\begin{aligned}ma &= F_g - F_s + F \\my'' &= mg - k(L + y) + F \\my'' &= -ky + F\end{aligned}$$

### Forces

forces	equation
gravitational	$mg$
spring	$kL$
external	$f(t)$
damping	$\gamma y'$

## Mechanical Vibrations (4.4)

### Undamped Motion

Consider a vertical spring with undamped motion:

$$mg - kx = ma$$

or

$$\begin{aligned} ma + kx &= 0 \\ mx'' + kx &= 0 \end{aligned}$$

Solve the equation, draw a component plot, and characterize the motion in terms of amplitude, frequency, and phase.

### Solving

Then,  $x = e^{\lambda t}$ , where  $m\lambda^2 + k = 0$ . Then,  $\lambda = \pm i\sqrt{\frac{k}{m}}$ .

Thus, the complete solution is  $x = c_1 \cos\left(\sqrt{\frac{k}{m}}t\right) + c_2 \sin\left(\sqrt{\frac{k}{m}}t\right)$ .

### Characterization

Let  $c_1 = R \cos \delta$ ,  $c_2 = R \sin \delta$ .

Then,

$$\begin{aligned} x &= c_1 \cos\left(\sqrt{\frac{k}{m}}t\right) + c_2 \sin\left(\sqrt{\frac{k}{m}}t\right) \\ &= R \cos \delta \cos\left(\sqrt{\frac{k}{m}}t\right) + R \sin \delta \sin\left(\sqrt{\frac{k}{m}}t\right) \\ &= R \cos\left(\sqrt{\frac{k}{m}}t - \delta\right) \end{aligned}$$

$R$  = amplitude

$\sqrt{\frac{k}{m}}$  = frequency

$d$  = phase shift

## Damped Motion

Adding damping to the equation:

$$my'' + \gamma y' + ky = 0$$

Determine an expression for the roots of the characteristic equation as a function of  $k, m, \gamma$ .

Characteristic equation is  $m\lambda^2 + \gamma\lambda + k = 0$ .

Then,

$$\lambda = -\frac{\gamma}{2m} \pm \frac{\sqrt{\gamma^2 - 4mk}}{2m}$$

<b>motion</b>	<b>occurs when</b>	<b>motion</b>
no damping	$\gamma = 0$	underdamped, with $\alpha = 0$
underdamped	$\gamma - 4mk < 0$	$e^{\alpha t} \cos(\beta t), e^{\alpha t} \sin(\beta t)$ where $\lambda = \alpha + i\beta$
critically damped	$\gamma - 4mk = 0$	$e^{\lambda t}, te^{\lambda t}$
overdamped	$\gamma - 4mk > 0$	$e^{\lambda_1 t}, e^{\lambda_2 t}$