Mercer's Theorem Contra diction.

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Define kernel as

$$K(X,t) = \langle Y(X), Y(t) \rangle$$
 (1)

Given 0; as the it eigenfunction Mercer's theorem states

$$\mathcal{H}(x,t) = \sum_{i=1}^{\infty} \lambda_i \phi_i(x) \phi_i(t) \qquad (2)$$

Since ϕ is a function in RBHS \rightarrow $\phi(x) = \langle \phi, \psi(x) \rangle$ Therefore, Mercer's theorem implies

$$K(X,t) = \sum_{i=1}^{\infty} \lambda_i, \ Y(X)^{T} p_i, \phi_i, \ Y(t)$$
$$= \Psi(X)^{T} \left[\sum_{i=1}^{\infty} \lambda_i, \phi_i, \phi_i, \ Y(t) \right]$$

Since $K(x,t) = \psi(x)^T \psi(t)$, $K(x,t) \neq \psi(x)^T \left[\sum_{i=1}^{\infty} \lambda_i \cdot \varphi^i, T\right] \psi(t)$ This result suggests that mercers theorem is wrong, what happened?

Resolving the contradiction,

when Mercer's theorem states that $\mathcal{H}(x,t) = \sum_{i=1}^{\infty} \lambda_i \phi_i(x) \phi_i(t)$ the eigenfunctions is defined as the orthogonal bases from the integral operator \mathcal{L} where

If $(x) = \int_{-\infty}^{\infty} K(x,t) f(t) d\mu(t)$ The function space is defined on $L^2(X,P)$, that is, squared integrable functions and NOT RKHS.

Correspondingly, the eigenfunctions in mercer's theorem is in L'(X,P) NOT RKHS. Therefore, the reproducing property is Not allowed, cita,

 $\mu(x,t) = \sum_{i=1}^{N} \lambda_i \phi_i(x) \phi_i(t) \neq \sum_{i=1}^{N} \lambda_i \langle \Psi(x), \phi_i \rangle \langle \Psi(t), \phi_i \rangle$

The corresponding Operator that does reside in RKHS is defined as $T_{n} = \frac{1}{n} \sum_{i=1}^{N} \psi(X_{i}) \psi(X_{i})^{T}$

We denote its eigenfunctions as & v,, vz, v3,... } According to Rosasco Tr has identical eigenvalues as L And their eigenvectors are related by

$$\phi_i = \frac{1}{\sqrt{k_i}} v_i$$

Therefore, with mercer's theorem in RKHS, it should be

$$\mathcal{X}(X,Y) = \sum_{i=1}^{2} \lambda_{i} \left[\frac{1}{\Lambda_{i}} \mathcal{V}_{i}(X) \right] \left[\frac{1}{\Lambda_{i}} \mathcal{V}_{i}(Y) \right]$$

We are now "allowed" to apply the reproducing property.

$$\begin{aligned} \mathcal{X}(X,Y) &= \sum_{i=1}^{N} \frac{\lambda_{i}}{\lambda_{i}} U_{i}(X) V_{i}(Y)^{T} \\ &= \psi(X)^{T} \left[\sum_{i=1}^{N} V_{i} V_{i}^{T} \right] \psi(Y) \quad \angle \quad \text{Since } \left[\sum_{i=1}^{N} V_{i}^{T} V_{i}^{T} \right] \\ &= \psi(X)^{T} \psi(Y) \quad \text{matrix, the inner product is not impo} \\ &= \langle \psi(X), \psi(Y) \rangle \end{aligned}$$

is a rotation matrix, the inver product is not impacted.