

Enes Savli

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A Short Summary of MsC Research Period

Enes Savli

Thesis : Posteriori MOR Strategies for Seismic Applications in Geophysics

March 8, 2019

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I am a open-minded and curious Mechanical Engineer who;

- was born in Istanbul at 1989,
- is a life-long student, good learner and self motivated person,
- likes seas and literature also is a cine guru,

- Got the BsC Degree in 2011 in Mechanical Engineering (3.02/4)
- Final Poject : Exergy/Energy Analysis of an Active Co-generation System in ERDEMIR
- Technical interests are computational mechanics, numerical analysis...

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- Called Modeling for Science and Engineering given by Applied Mathematics division of UAB
- Interdisciplinary program is based on two pillars;
 - Modeling of Systems
 - Numerical simulation or Resolution of Systems

- Taken classes like Optimization, Dynamical Systems Modeling, Parallel Programming, Applied Modeling and Simulation
- Various small/mid scale projects on science/computer science and engineering.

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- BSC is the national super-computing centre in Spain which specialise in HPC and manage MareNostrum, one of the most powerful supercomputers in Europe.
- With a total staff of more than 500 researchers and professionals focuses on four main fields: Computer, Life, Earth Sciences and Applications in Engineering and 24 sub-areas.



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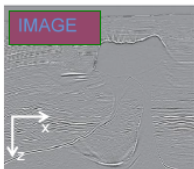
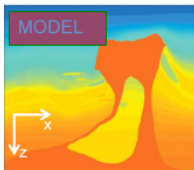
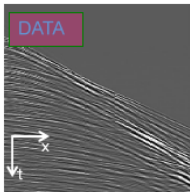
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- Seismic applications requires repetitive expensive solutions
 - Seismic Imaging
 - Reverse Time Migration
 - Inversion Techniques
- In Geosciences Applications Group of BSC, ROM techniques have been already conducting for some years.
- Group was specialized in a-priori methods mainly PDG (Proper Generalized Decompositions) [1] [2]

Thesis plan & Objectives

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In broad manner objectives were;

- Exploring on various posteriori methods which are much more easy to implement than PDG
- Seeking for possibility to adaptation to the high fidelity solver of BSC

- At first sight due to dealing with huge data, POD-SVD methods have been chosen
- For latter, Pereyra's strategies has been planned for implementation and comparison.[4, 5, 3]

In particular objectives were;

- Building the surrogate models of large parameterized wave propagation models by using ROM.
- Analyze the snapshot method (SVD) advantages and drawbacks and discuss the cost of offline stage.
- Get over the burden by implementations of cheaper QR representations [5]
- Test different parameterizations.(frequency,positions)

Overview of Reduced Order Modeling

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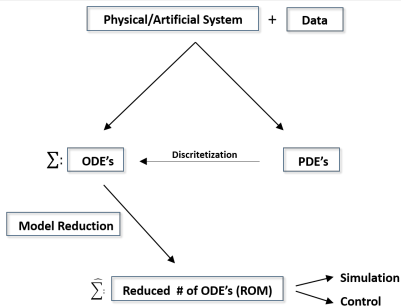
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- Approximates the high order model in low order one by preserving structure.
- In general, projection on to the reduced basis
- Expensive step is computation of reduced basis a.k.a "Offline Stage"

Why POD?

- Data dependent, non-intrusive implementation, guarantees the optimality
- More stable, compatibility to larger data-sets (PCA relation)

Workflow of POD Snapshot Method

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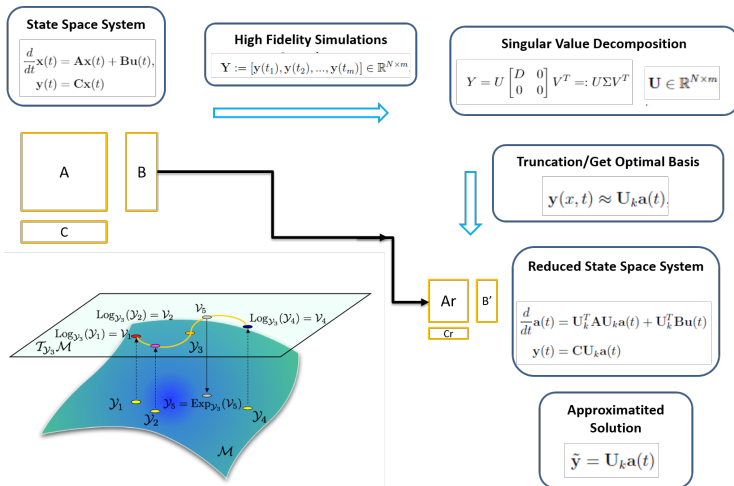
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First trials have been done in;

- 1D Frequency Domain FE model with frequency parameterization.
- 2D Time domain high order FD schemes with source and time parameterization.

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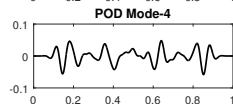
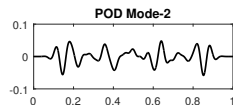
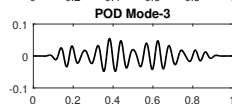
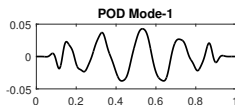
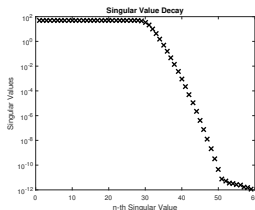
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Some Results on Validation Phase

- All the steps have been examined and shown in deeper aspects in both models.
- POD method in Acoustic Wave Propagation models have been explored and validated.
- It is shown that SVD is not a feasible option for large scale seismic applications for high memory requirement and complexity $\mathcal{O}(\min(mn^2, m^2n))$.

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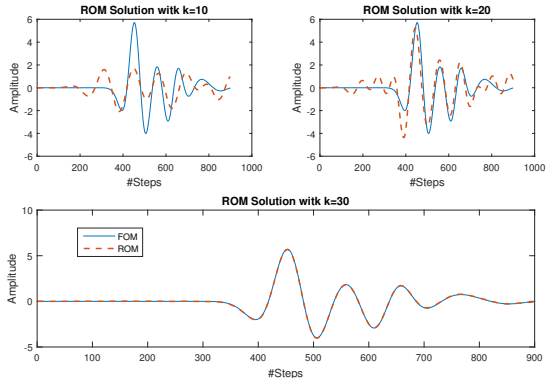
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- A novel algorithm proposed by Victor Pereyra (2011) claimed as a replacement of SVD
- It is progressive because it advances with the high fidelity simulation
- It is adaptive because selects the y_i snapshot according to angle between existing basis and snapshot y_i .
- Storing snapshot matrix is not required and evaluation of \mathbf{Q} is just a backward accumulation. \Rightarrow cheaper!
- Projection with $\tilde{\mathbf{p}} = \mathbf{Q}\mathbf{a}(t)$ instead of $\tilde{\mathbf{p}} = \mathbf{U}\mathbf{a}(t)$

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Algorithm 1: Adaptive QR Algorithm

Input: $\mathbf{X} \in \mathbb{R}^m$ Solution at t timestep, $V \in \mathbb{R}^{m \times k}$ Computed Householder vectors, Threshold δ ;

Output: Q orthogonal basis;

At the k th step;

for $i = 1, \dots, k$ **do**

Householder Transition until $\mathbf{X}_{1:k}$;
 $\mathbf{X} = \mathbf{X} - 2 * V(:, i) * (V(:, i))^T * \mathbf{X}$

Calculate the $\alpha = -\text{sign}(\mathbf{X}_{k:\text{end}}(1)) * \|\mathbf{X}_{k:\text{end}}\|_2$ (Diagonal term of R);

Compute the threshold $\mu = \|\alpha\| / \|\mathbf{X}\|_2$;

if $\mu > \delta$ **then**

Compute the new snapshot's HH vector and save it;
 $v = (\mathbf{X}_{k:\text{end}} - \alpha * e) / \|\mathbf{X}\|_2$, where $e^T = (1, 0, \dots, 0)$;
 $v \rightarrow V$;
 $k++ = 1$;

else

Try next snapshot;

Compute the Orthogonal Basis $Q \in \mathbb{R}^{m \times n}$ ($n \ll m$) by backward accumulation of $V \in \mathbb{R}^{m \times n}$

Householder Vectors **for** $j = n, n-1, \dots, 2$ **do**

$\mathbf{Q} = \mathbf{Q} - 2 * V(:, j) * (V(:, j))^T * \mathbf{Q}$

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- QR-I has limitations too and some manipulations to system might be done to make QR applicable.
- Proposed application is "skeletonization" by reducing the size of the "saved" entities $N \Rightarrow N_r$ with arbitrary $\mathbf{C} \in \mathbb{R}^{N_r \times N}$. This reduction provides new snapshots $\tilde{\mathbf{Y}} = \mathbf{C}\mathbf{Y}$.
- Then we can't use direct orthogonal parts as $\mathbf{Q}^Y \neq \mathbf{Q}^{\tilde{\mathbf{Y}}}$.
- Idea comes from "Oblique Projections". Using $\tilde{\mathbf{y}} = \tilde{\mathbf{Y}}\mathbf{a}(\mathbf{t})$ instead $\tilde{\mathbf{y}} = \mathbf{Q}\mathbf{a}(\mathbf{t})$ and interpolate back!

Original System;

$$\mathbf{y}_{tt} = \mathbf{A}\mathbf{y} + \mathbf{B}\mathbf{u}(\mathbf{t}) \text{ introducing } \mathbf{y} = \mathbf{Y}\mathbf{a}(\mathbf{t});$$

$$\mathbf{C}\mathbf{Y}\mathbf{a}_{tt} = \mathbf{C}\mathbf{A}\mathbf{Y}\mathbf{a} + \mathbf{C}\mathbf{b}\mathbf{u}(\mathbf{t})$$

and we can substitute $\mathbf{C}\mathbf{Y} = \mathbf{Q}\mathbf{R}$;

$$\mathbf{Q}\mathbf{R}\mathbf{a}_{tt} = \mathbf{C}\mathbf{A}\mathbf{Y}\mathbf{a} + \mathbf{C}\mathbf{b}\mathbf{u}(\mathbf{t}) \text{ and finally;}$$

$$\mathbf{a}_{tt} = \mathbf{R}^{-1}\mathbf{Q}^t\mathbf{C}\mathbf{A}\mathbf{Y}\mathbf{a} + \mathbf{R}^{-1}\mathbf{Q}^t\mathbf{C}\mathbf{b}\mathbf{u}(\mathbf{t})$$

and;

$$\mathbf{y} = \mathbf{C}\mathbf{Y}\mathbf{a}.$$

- As seen, \mathbf{R}^{-1} term occurs in reduced system.
- Well-conditioned \mathbf{R}^{-1} is needed.
- Adaptive QR decomposition II is proposed focusing on condition number κ of \mathbf{R} by using modified scheme of QR-I.
- Advancing in time is modified to avoid from systematic skipping.

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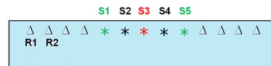
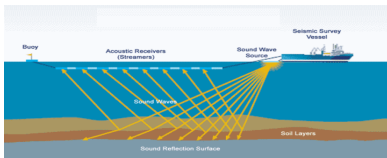
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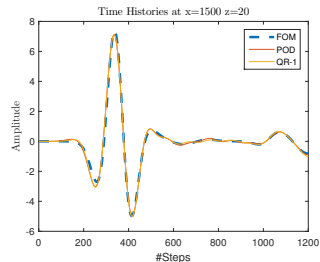
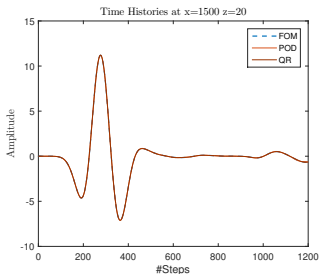
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- Tests are done as figures above parameterization of source to be realistic with miscellaneous domain sizes.



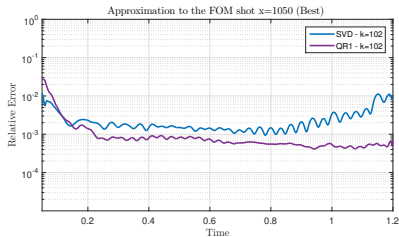
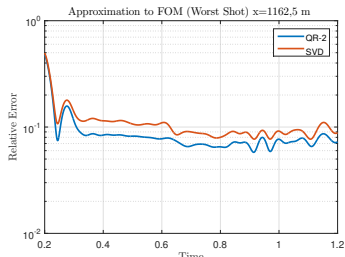
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Criteria	Basis Selection
$\epsilon = 0.9999$	$k=71$
$\phi = 7$	$k=102$
Initial Criteria : 10^8	$k=164$



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As claimed that two of QR decomposition for replacement SVD, one synthetically example in homogeneous media is derived;

- Total solution matrix would be size 4410000×1300 for 2 shot

Table: Calculation Times

Algorithm	POD-SVD	QR-I	QR-II
Time(s)	N/A	9760	11080
# Basis	N/A	221	378

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- It is shown that a-posteriori methodology is a satisfactory phenomena and it is worthwhile to do further developments.
- All the methods gauged carefully and high compression ratios are obtained.
- It is shown that usage of POD method is an option for seismic applications.
- To get over the possible drawbacks (computational load of offline stage, memory), original and modified version of novel adaptive QR algorithm are introduced and implemented successfully.

- During this work, i have been contracted in BSC as Research Intern.
- In all works, in-house high fidelity models have been used as template.
- All related implementations are realized by me from the scratch.
- Matlab and Pyhton programming languages have been used.
- Apart this work, POD for non-linear models and some error estimation methods have been researched.
- Real life applications leaved as future works.

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Thank You!!