# GEODOME MIDS Capstone Project

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## Background

- Earth observation (EO) data allows to understand and plan around infrastructure system and flow of resources at global scale
- Access to labeled satellite imagery is expensive and public datasets are rare.
- Deep learning models do not generalize well when trained on images with limited geographical diversity



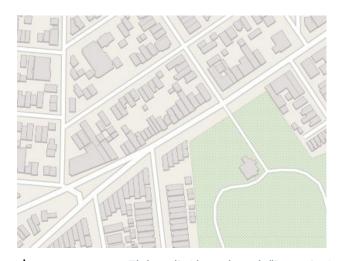


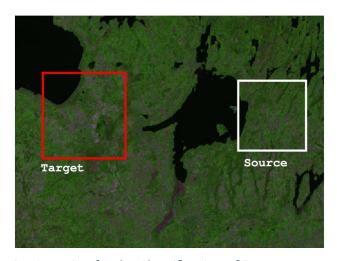


Imagery Source: Google Maps - Maxar Technologies

## **Project Objectives**

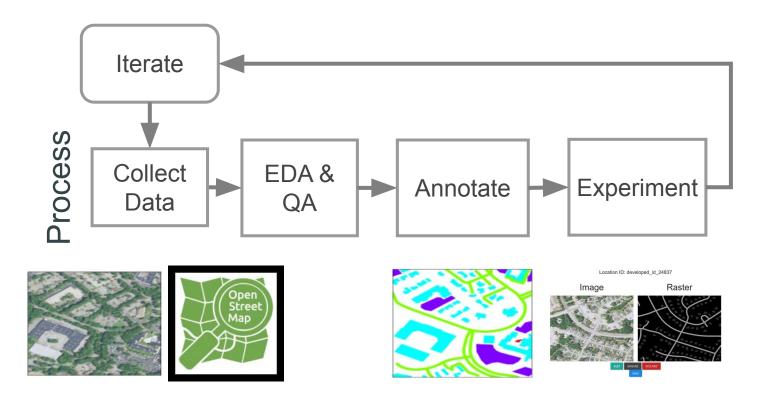
- Create a tool to develop and expand a training dataset for EO data with existing infrastructure labels
- Create a new benchmark dataset for the EO computer vision community
- Stretch goal: Design and execute domain adaptation experiments



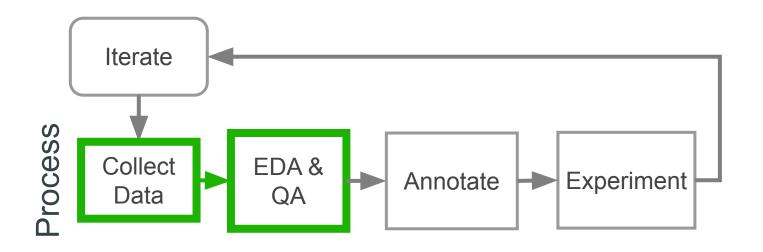


**Image source**: Elshamli, Ahmed et al. "Domain Adaptation Using Representation Learning for the Classification of Remote Sensing Images." *IEEE Journal of Selected Topics in Applied Earth Observations and Remote Sensing* 10 (2017): 4198-4209.

### **Process**



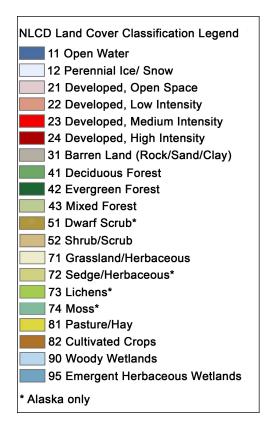
#### **Data Sources**

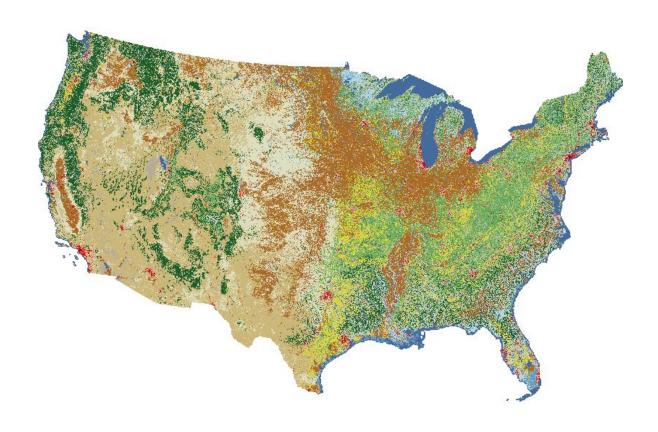


#### **Data Source: NAIP**

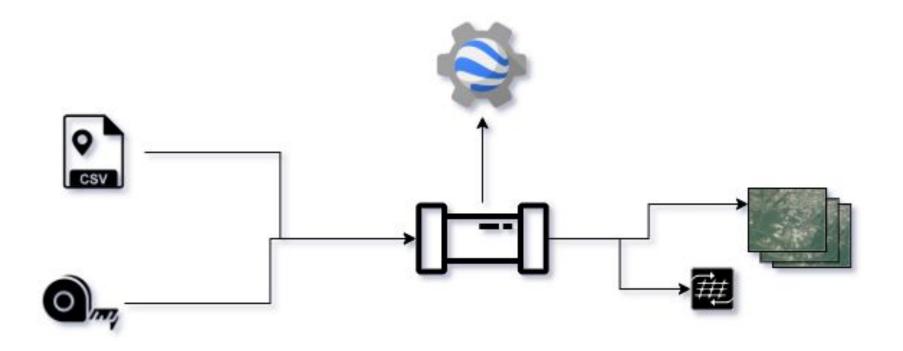
- USDA program
- High image resolution (<1 m)</li>
- 4 bands
  - Natural Color (RGB)
  - Near infrared (N)
- There is plenty geographical diversity within the US

#### **Data Source: NLCD**



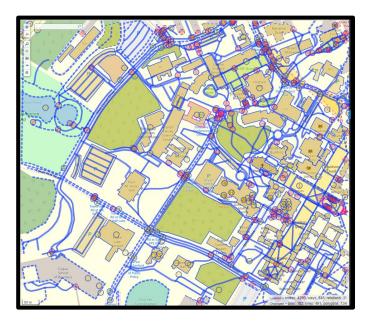


## **TOOL: Satellite Imagery Download**



Data Sources: OpenStreetMaps

 Open and collaborative project to create a publicly available and editable map of the world



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2012
         <node id="2332369211" lat="36.0037885" lon="-78.9407602"/>
         <node id="2332369212" lat="36.0035995" lon="-78.9408196"/>
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2014
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         <node id="2332369214" lat="36.0036075" lon="-78.9408372"/>
2015
2016
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         <node id="2332369216" lat="36.0040077" lon="-78.9412738"/>
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2018
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2019
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2029
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2030
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2031
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2032
         <node id="2669004989" lat="35.9994145" lon="-78.9475874">
2033
2034
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2035
           <tag k="capacity" v="42"/>
           <tag k="covered" v="no"/>
2036
           <tag k="name" v="Fugua School of Business Bike Rack"/>
2037
         </node>
```

## OpenStreetMaps Labels

- Analyzed each one of the 682 labels to
  - discard those that are not relevant
  - discard those that are not visible
  - merge those that refer to the same or very similar features
- Created a new 'taxonomy': a dictionary to translate the original labels into our new classification

## OpenStreetMaps Labels

#### Merged Labels



church



place of worship

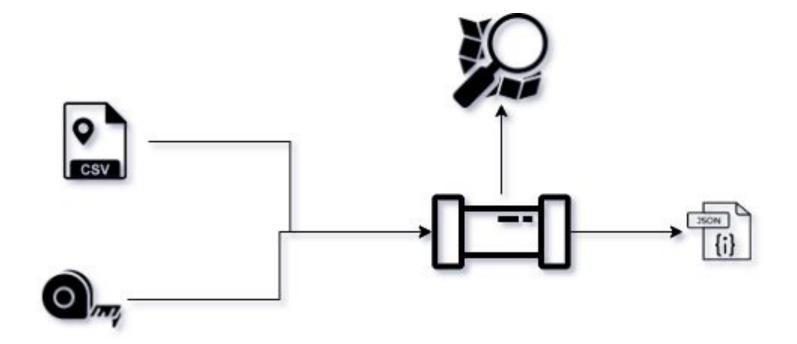


university

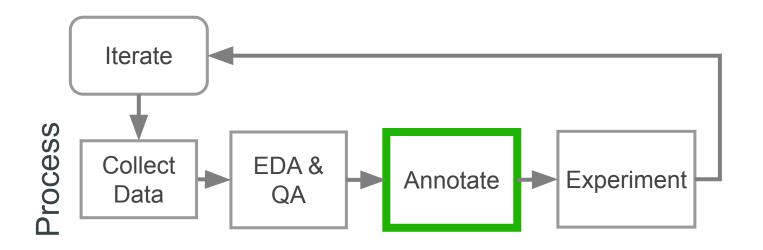


college

## **TOOL: OSM Label Pipeline**



#### **Annotation**



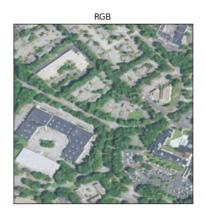
#### **Annotation**

- Aerial imagery is not always an orthogonal top-down view
- Developed tools that align the orthogonal label layout to match the view of the aerial image
- Turn the labels from vectors into pixels (rasterize)
- Verified that the structure coordinates aligned correctly from both sources



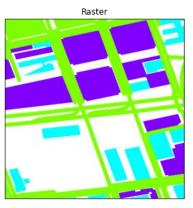
## **TOOL: Rasterization Pipeline**

- Takes the output of the first 2 tools
- Collapses them into the labels of interest
- Assigns a 'depth' value for each polygon
- Uses the meta information to align the shapefile with the satellite image
- Burns the polygons as pixels to use as labels

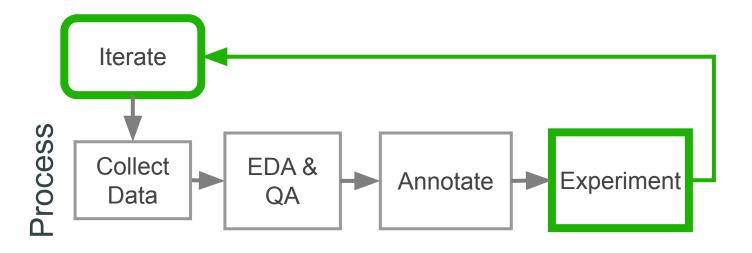








## **Experiments**



## **Image Segmentation Experiments**

- Goal: Classify each pixel in an RGB image
- Architecture: ResNet50 encoder + U-Net decoder
- Metrics:
  - Intersection over Union (IoU): measures similarity between prediction and raster
  - Class metrics: Precision, Recall, NPV, Sensitivity, Specificity, Accuracy
- GEODOME Dataset:
  - 15,668 patches: RGB + raster
  - 59 classes (initially)



**RGB** 

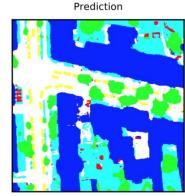
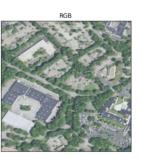


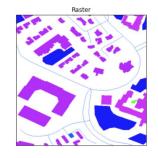
Image source:

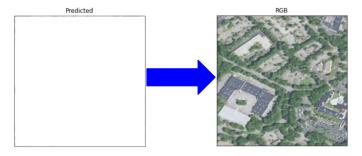
https://www.azavea.com/blog/2017/05/30/deep-learning-on-aerial-im agery/

## **Experiment Results**

Experiment	Train IoU	Class 0 Precision	Class 0 Specificity	Roads Precision	Roads Specificity	Buildings Precision	Buildings Specificity
1	0.947	0.9108	0.0194	-	1.0000	0.2977	1.0000
2	0.676	0.9138 ↑	0.6847 ↑	-	1.0000	0.4117 ↑	0.8670
3	0.770	0.9439 ↑	0.8316 ↑	0.8442 ↑	0.9817	0.8514 ↑	0.9812









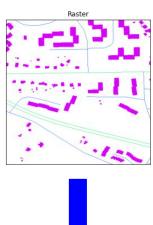


**Experiment 1** 

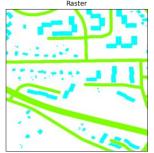
Experiment 3

## What Went Wrong?

- Problems:
  - 96.75% of pixels of class 0
  - Unlabeled objects
  - Too many classes
  - Roads 1 pixel thick
- Solutions:
  - Handpicked dataset
  - Made roads thicker
  - Reduced to 4 classes
    - (class 0, buildings, parking, roads)







## **Fixing Our Dataset**

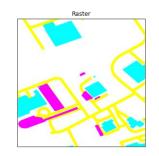
- Automated filtering of RGB-raster pairs
  - Method 1 [30.55% kept]: ≥2 classes and raster mean >0.08
  - Method 2 [7.47% kept]: ≥3 classes and raster mean >0.08
  - Method 3 [13.72% kept]: KNN classifier
  - Method 4 [2.34% kept]: Logistic regression

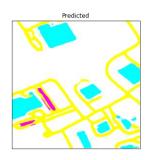
Method	Train Accuracy	Valid Accuracy
1 (2 classes)	47.2%	46.7%
2 (3 classes)	81.6%	83.3%
3 (knn)	88.4%	56.0%
4 (lr)	81.6%	66.0%

## **Experiment Results**

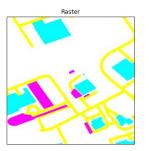
Dataset Filter	Train IoU	Train IoU with Inria	Valid IoU	Valid IoU with Inria
1 (2 classes)	0.7079	0.9179 ↑	0.7200	0.7646 ↑
2 (3 classes)	0.7262	0.8583 ↑	0.7077	0.7415 ↑
3 (knn)	0.9059	0.9253 ↑	0.7252	0.7378 ↑
4 (lr)	0.7262	0.7451 ↑	0.7077	0.7321 ↑

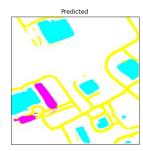












Filter 1 Filter 4

## **Key Takeaways**

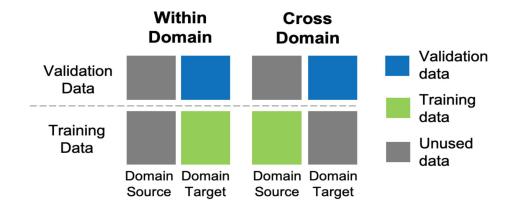
- Developing a systematic approach to improve data quality is better than chasing the state-of-the-art models with low-quality data.
- OSM labels are of better quality when the data source is supported by a large scale organization (government agencies) or the tags are high profile.

"If 80 percent of our work is data preparation, then ensuring data quality is the important work of a machine learning team."

Andrew Ng

#### **Future Work**

- Automate filtering of quality RGB-raster pairs
- Train baseline "within domain" model with training and validation data of the same domain
- Compare performance vs. "cross domain" models with training data of increasing domains to assess how adding domain diversity can help overcome the domain adaptation challenge
- Alternate use cases: partially labeled datasets



## Acknowledgments

- Project Manager: Wei (Wayne) Hu
- Project Partner: Kyle Bradbury, PhD