

# ENES DEMİRAĞ

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## EDUCATION

### Istanbul Technical University, Master of Science

Computer Engineering

Istanbul, Turkey

Feb. 2021 – 2024 (incomplete)

### Istanbul Technical University, Bachelor of Engineering

Electronics and Communication Engineering – [thesis](#)

Istanbul, Turkey

Sep. 2016 – Feb. 2021

### Liverpool John Moores University

Erasmus Student Exchange Program

Liverpool, UK

Jan. – June 2019

### Ümraniye Anatolian High School

Istanbul, Turkey

2012 – 2016

## EXPERIENCE

### Chooch

MLOps Engineer

July 2022 – Present

Chooch is a computer vision company based in Silicon Valley. I developed a real-time inference engine, deployed Generative AI models and wrote backend APIs.

### Baykar Defence

Software Engineer

Aug. 2020 – July 2022

Baykar Defence is a private Turkish defence company specialising in armed UAVs. I developed an augmented reality system and a real-time video decoding system. I also developed many image processing, video enhancement and filtering techniques. Managed more than 10 different vision based projects as a lead engineer.

## PROJECTS

### Ravinspect Tech. | [Intern](#) | [repo](#)

July – Sep. 2018

This start-up company is developing drones for visual inspection. I developed a ROS package for point cloud filtering and real-time mapping, worked on stereo vision and visual odometry using ROS environment.

### ITU AUV Team | [Software Team Member](#) | [website](#) | [repo](#)

Sept. 2018 – Apr. 2020

ITU AUV Team is an underwater robotics team, that came together to prepare a fully autonomous underwater vehicle. I prepared custom dataset for our needs, applied data augmentation, applied training and fine-tuning and deployed on a Nvidia Jetson computer.

### ITU ROV Team | [Software Team Leader](#) | [website](#)

Oct. 2016 – Sept. 2018

This is a university team project which we founded with my friends to develop and spread underwater robots in Turkey. We build a Remotely Operated Underwater Vehicle. I managed the software development process as a team leader and worked on computer vision tasks.

### ITU Formula Team | [Autonomous Systems Team Member](#) | [website](#)

Sept. 2017 – Aug. 2018

At Advanced Vehicle Technologies, Autonomous and Power Systems Laboratory of my faculty, I worked as a research assistant working on autonomous driving technologies. Worked with LiDAR systems, SLAM and point cloud processing on a self driving car.

## SKILLS

• Computer Vision • Machine Learning • Autonomous Systems • Linux Systems • Python • C++ • OpenCV • OpenGL • PyTorch • Tensorflow • Yolo • FFmpeg • Docker • Kafka • FastAPI • Jupiter Notebooks • Deepstream • Tritonserver • Minio • Celery • Redis • Git • Github Actions • ROS

## LANGUAGES

**Turkish** : Native

**English** : Advanced