

Surround-View Images

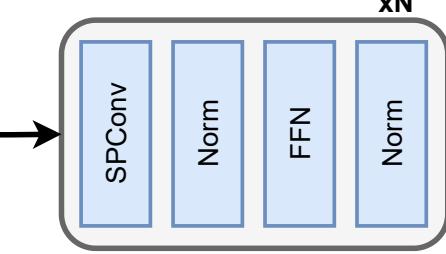


2D Encoder

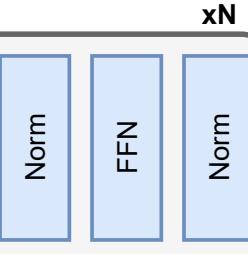
Camera Features

View Feature Aggregation

Gauss Initializer



Entropy Based Smoothing



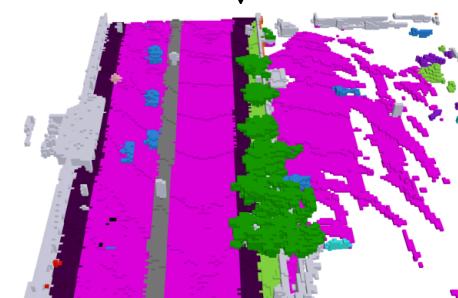
x_N

Camera-LiDAR Adaptive Fusion



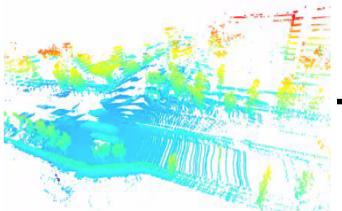
x_M

Gauss-Mamba Head



Semantic Occupancy

LiDAR Points

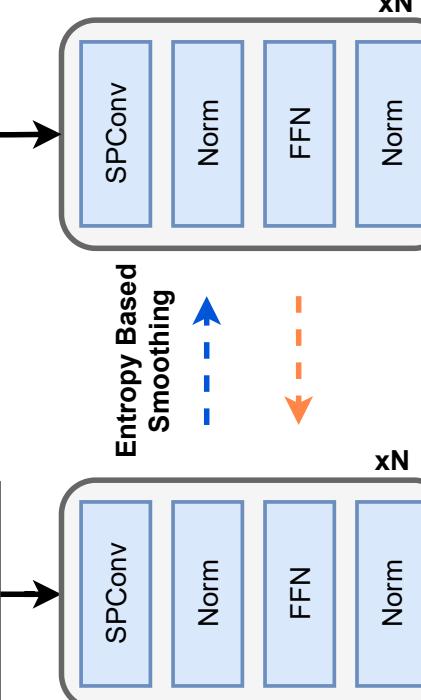


3D Encoder

LiDAR Voxel Features

Depth Feature Aggregation

Gauss Initializer



x_N

