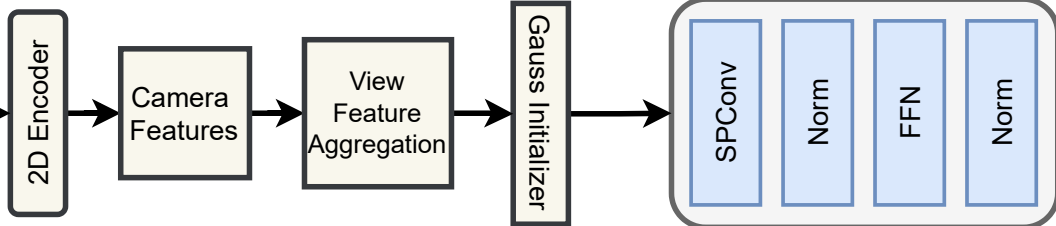
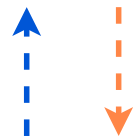


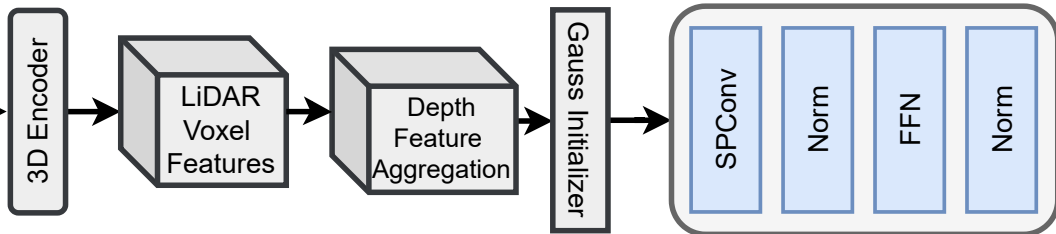
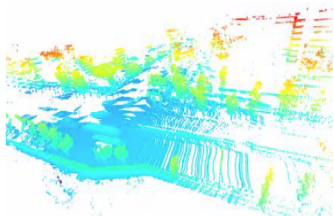
Surround-View Images



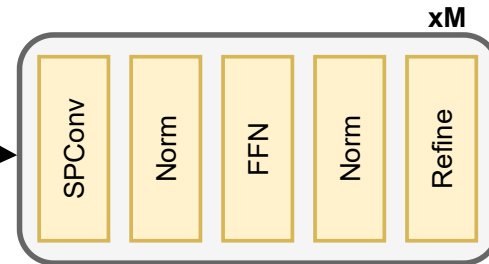
Entropy Based
Smoothing



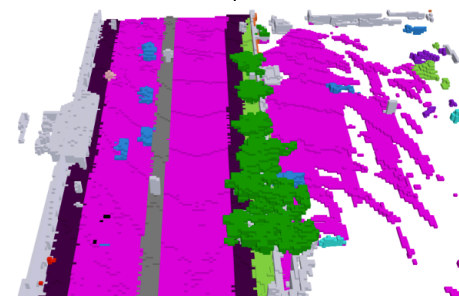
LiDAR Points



Camera-LiDAR
Adaptive Fusion



Gauss-Mamba
Head



Semantic Occupancy