

M. Enes İnanc

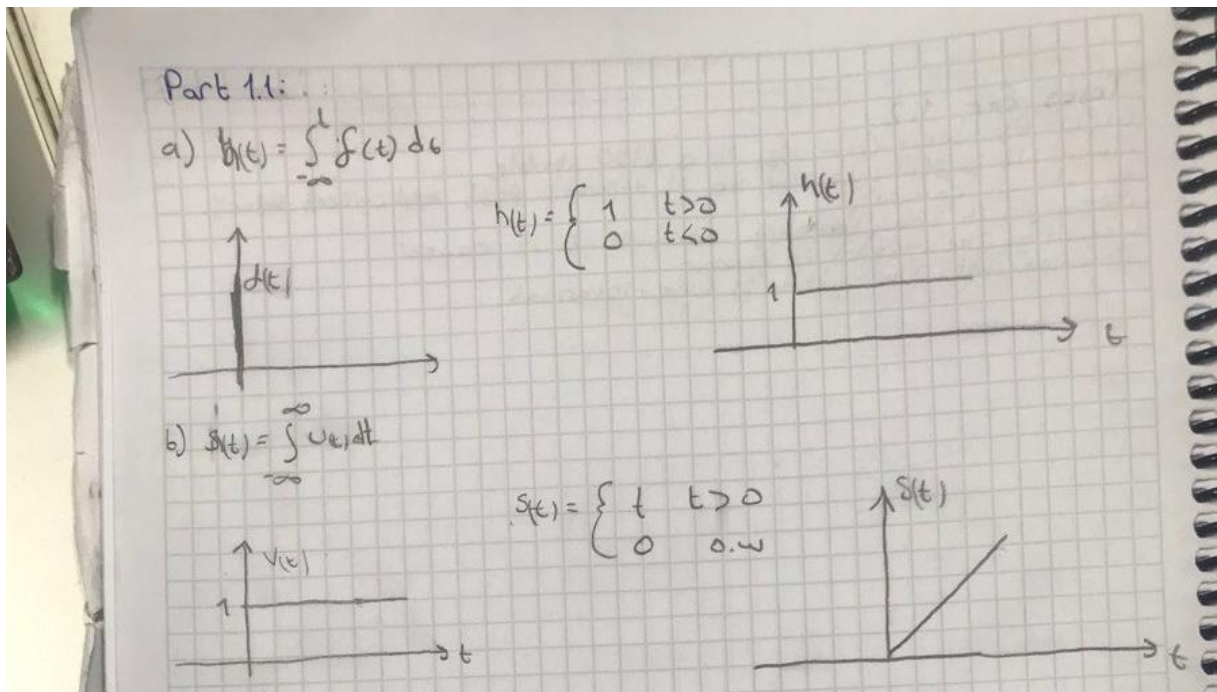
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23.03.2024

EEE-321 Lab-3

Part 1:

Part 1.1



Tests for 1.1:

Linearity: The system is linear because superposition holds,

$$y_1(t) = \int_{-\infty}^t x_1(\tau) d\tau, y_2(t) = \int_{-\infty}^t x_2(\tau) d\tau$$

$$ay_1 + by_2 = \int_{-\infty}^t ax_1(\tau) + bx_2(\tau) d\tau$$

Causal: The system is causal because it depends just past and current values.

Memory: It has memory because it is causal.

BIBO: As shown $s(t)$ is ramp function, it isn't bounded so system isn't BIBO stable.

Time invariance: $x_2(t) = x_1(t + \alpha)$

$$y_2(t) = \int_{-\infty}^t x_1(\tau - \alpha) d\tau$$

$$y_2(t) = \int_{-\infty}^{t+\alpha} x_1(\alpha) d\alpha = y_1(t+\alpha) \quad \text{it is time invariant,}$$

Part 1.2:

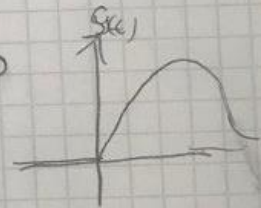
Part 1.2:

$$h(t) = \begin{cases} e^{-at} & t > 0 \\ 0 & t \leq 0 \end{cases}$$

$$u(t) * h(t) = g(t)$$

$$g(t) = \int_{-\infty}^{\infty} u(\tau) h(t-\tau) d\tau$$

$$g(t) = \begin{cases} \frac{e^{-at}}{-a} & t > 0 \\ 0 & t \leq 0 \end{cases}$$



Tests for 1.2:

BIBO: As seen from $g(t)$ it is BIBO stable

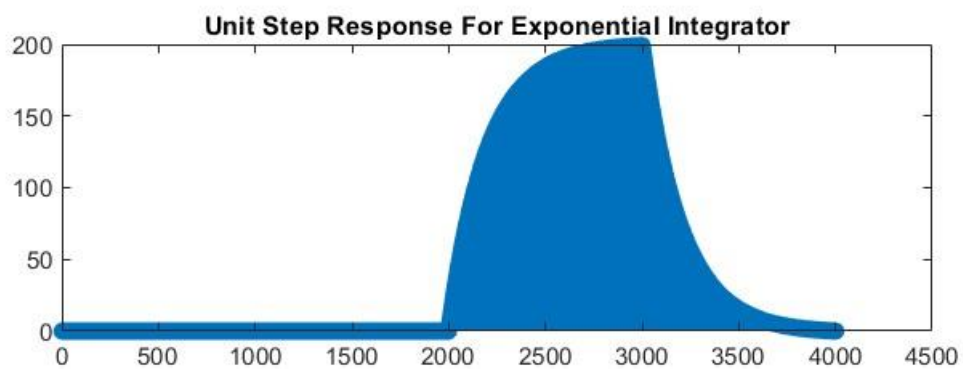
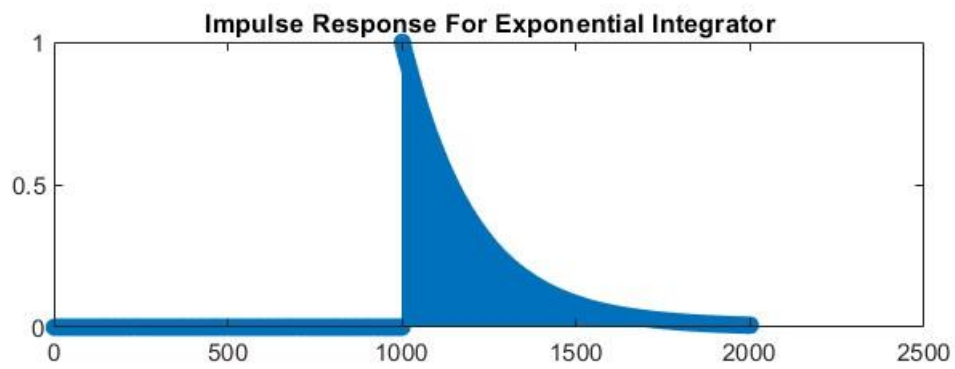
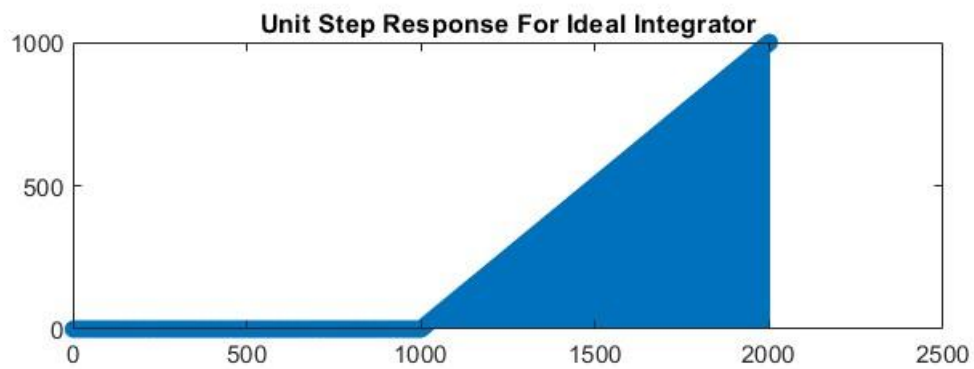
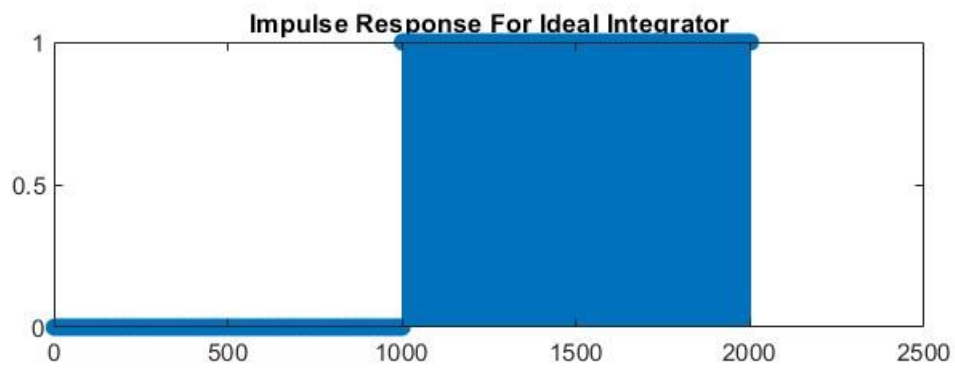
Causal: It is still integrator so it depends past and current values so it is causal

Memory: it has memory because it is causal

Linearity: The system is linear

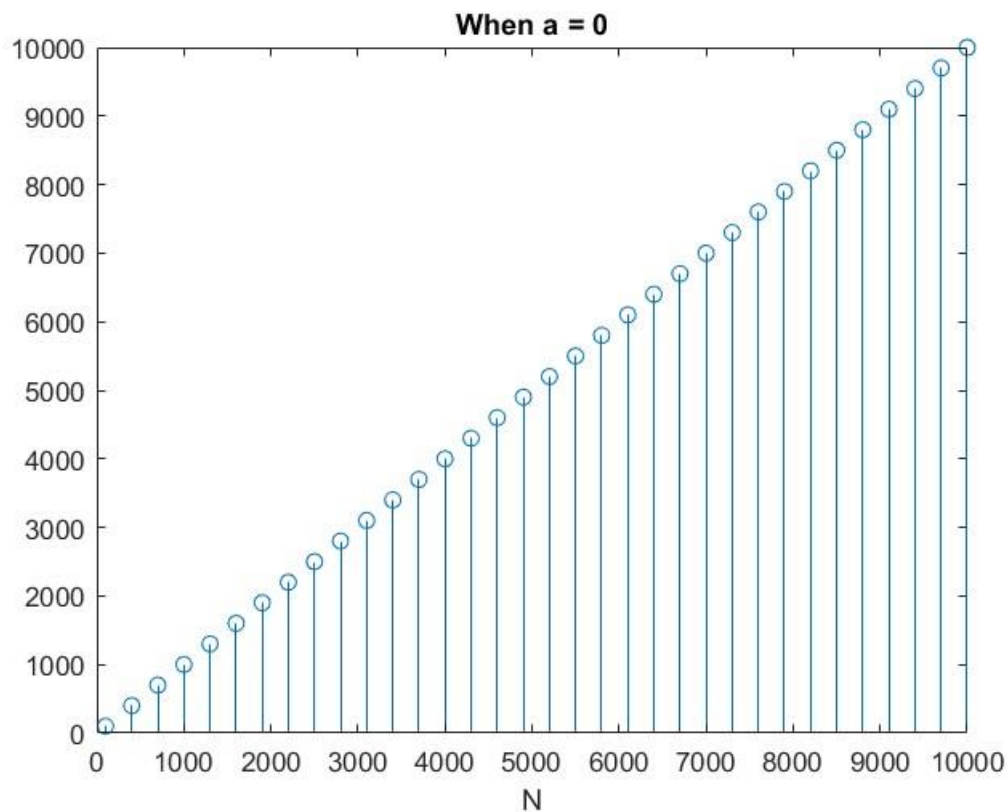
Time-invariant: The system is time-invariant.

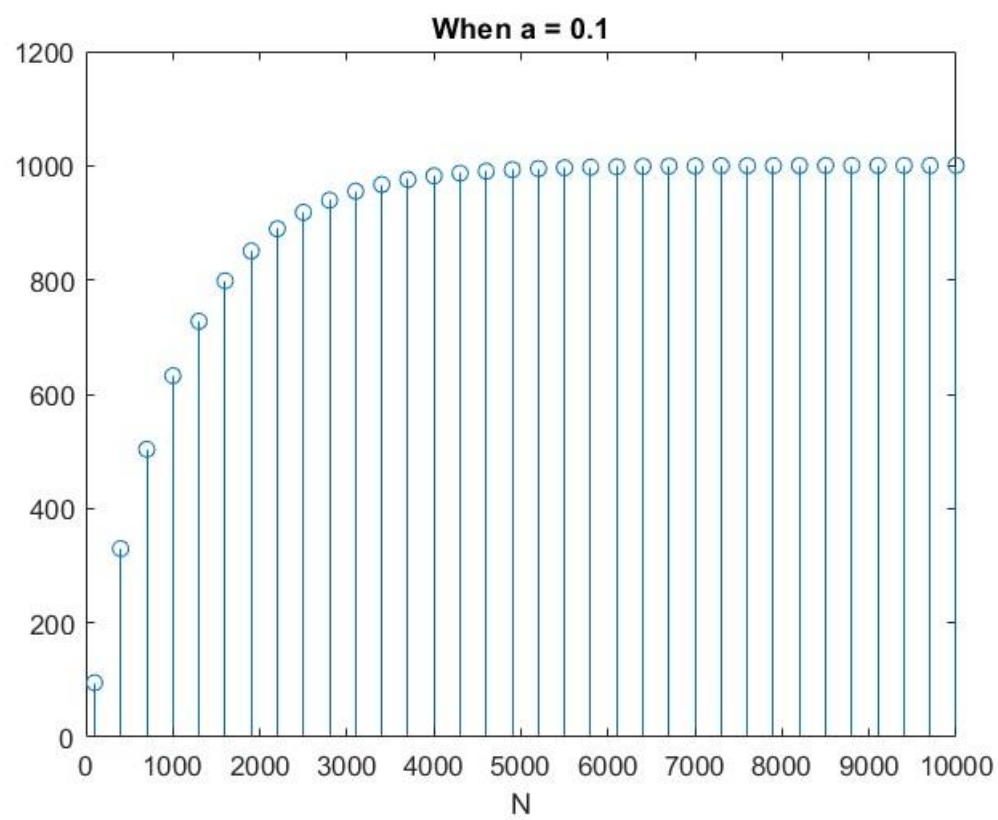
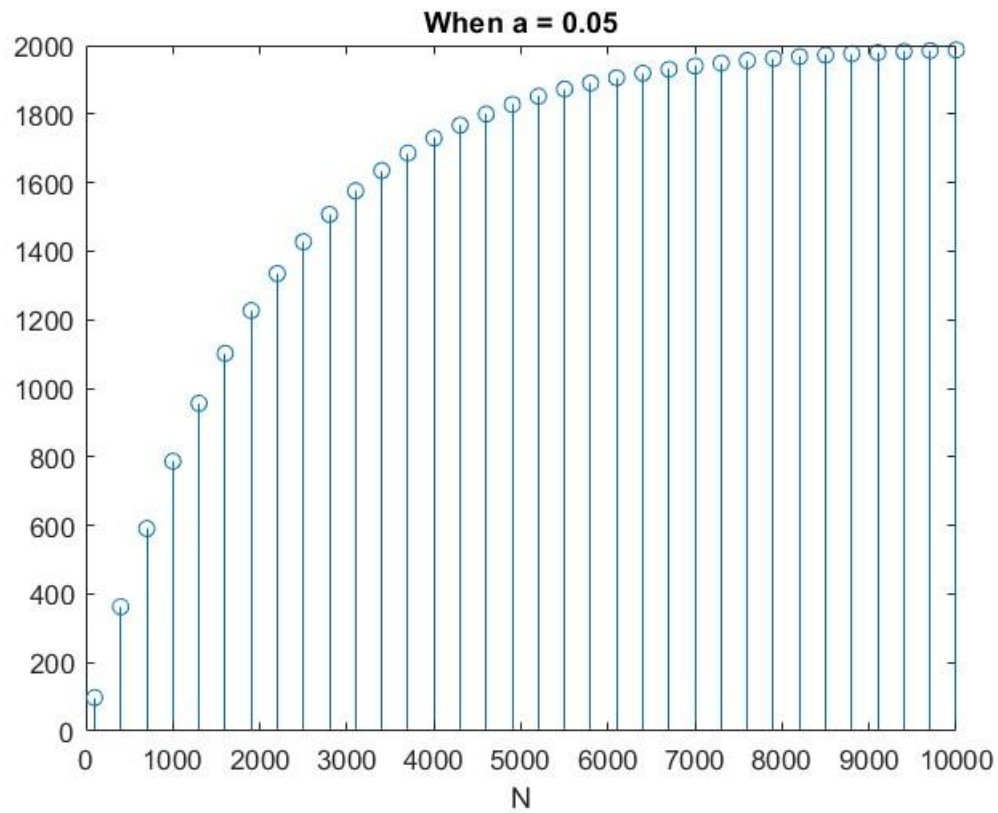
Part 1.3:

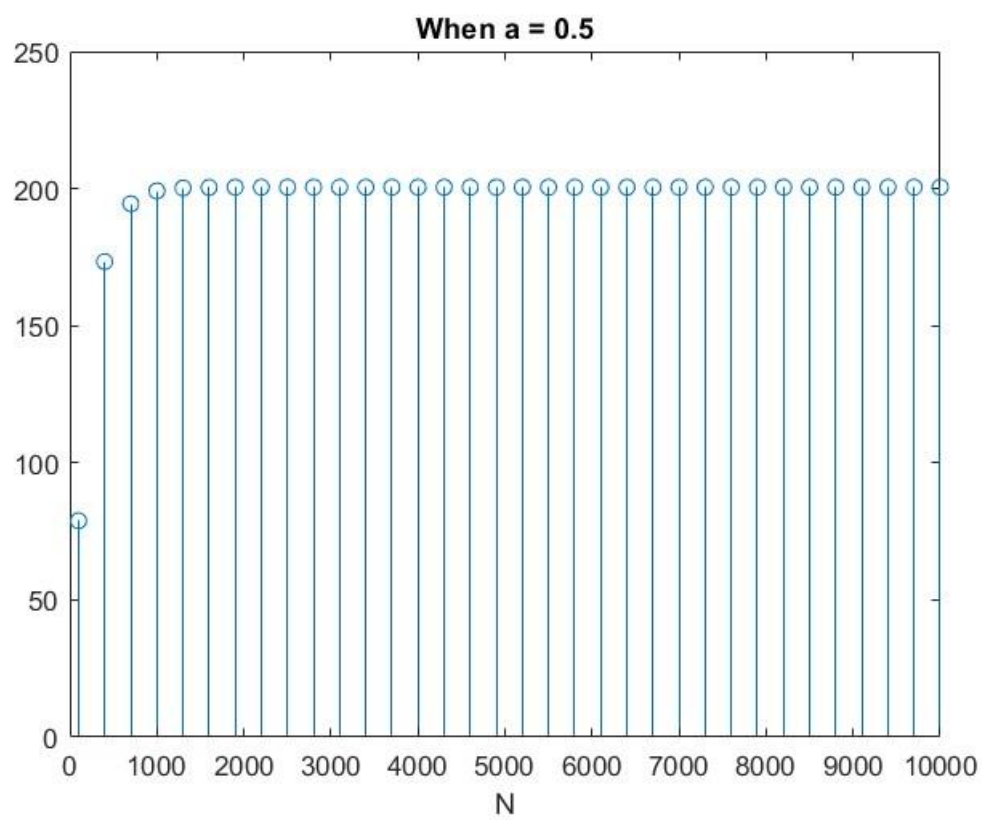
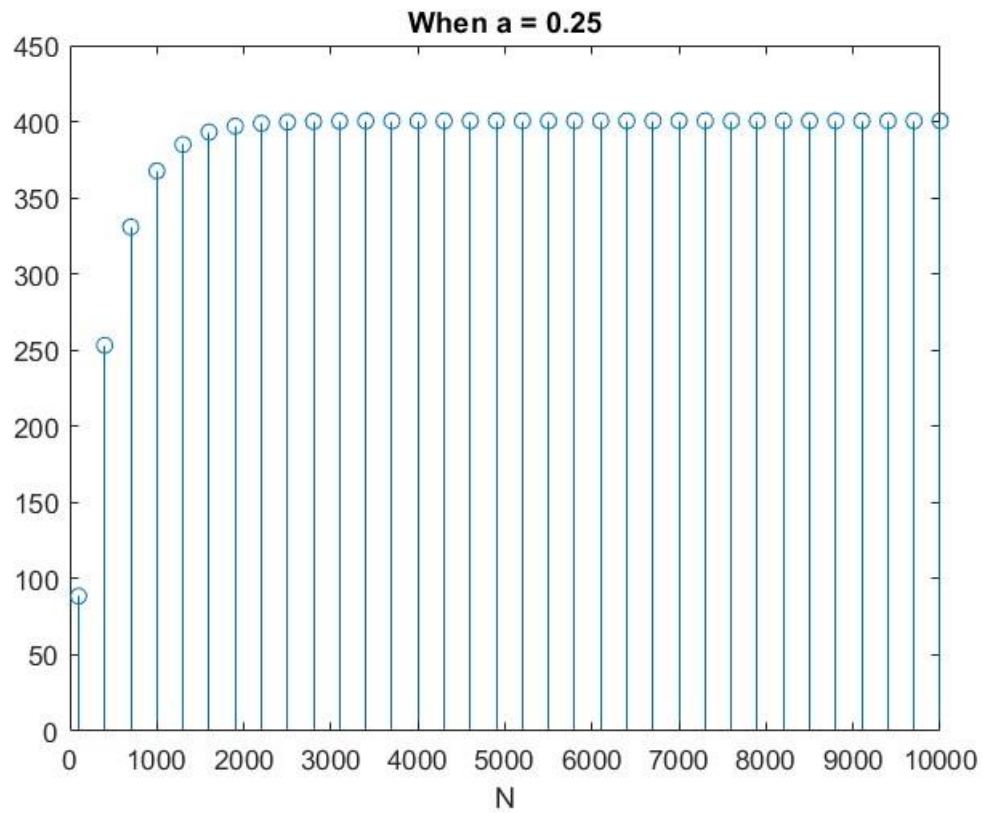


Part 2:

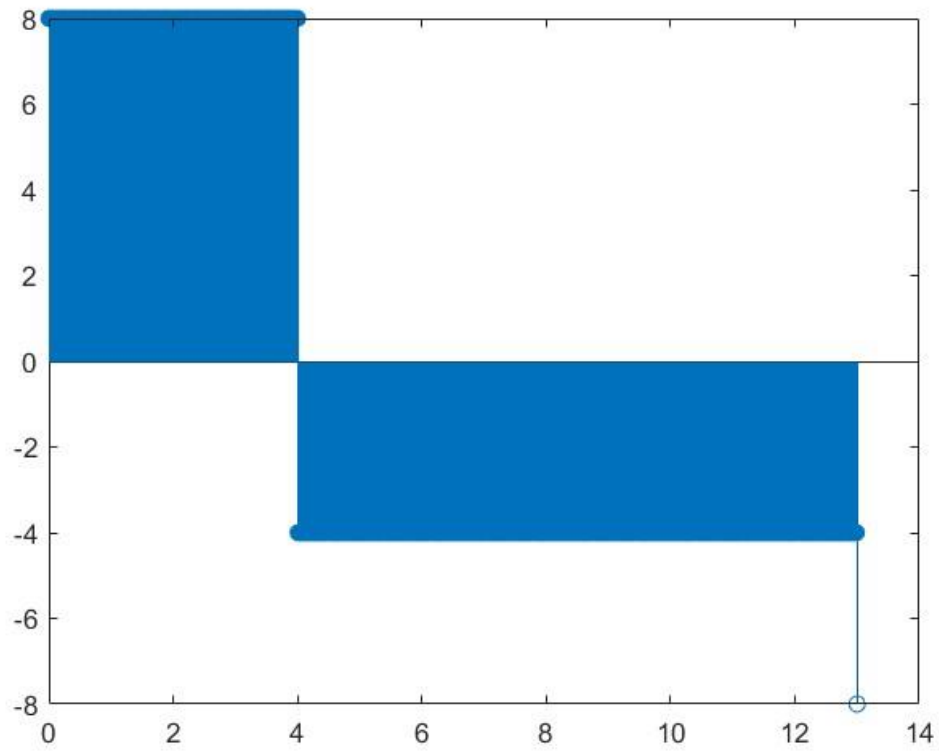
To determine whether a system is BIBO stable or not, we can sum its abs of impulse response as given Equation 2. We can observe whether the unit step response remains bounded. By building Equation 2 on MATLAB we can analyze it. If the summation converges to a finite value as the interval increases, we can conclude that the system is BIBO stable. The results which are asked for this lab task is following.



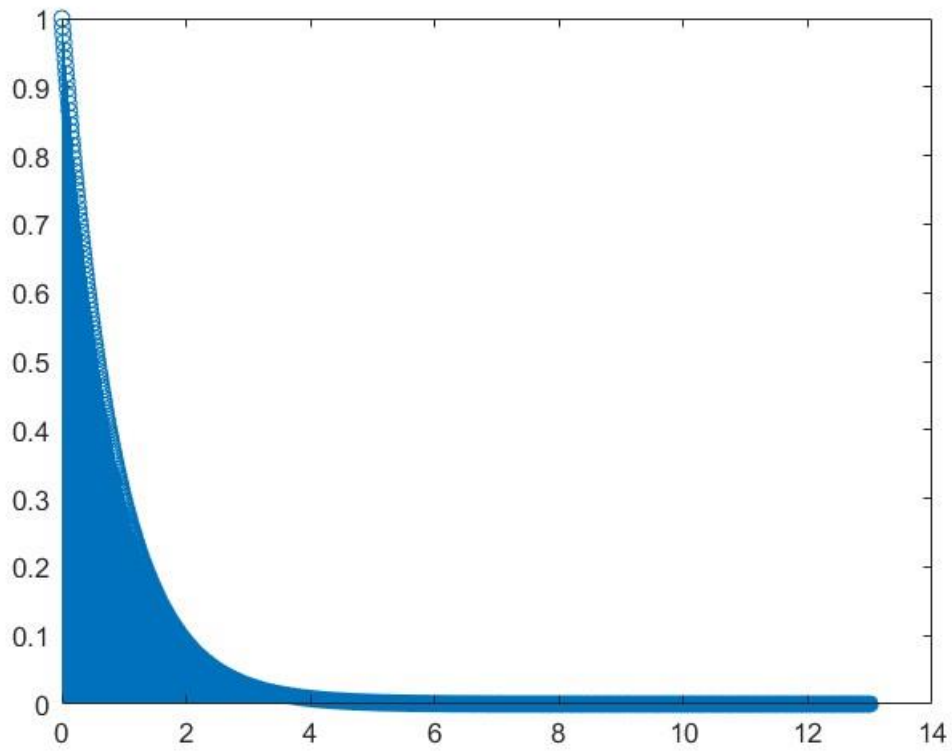




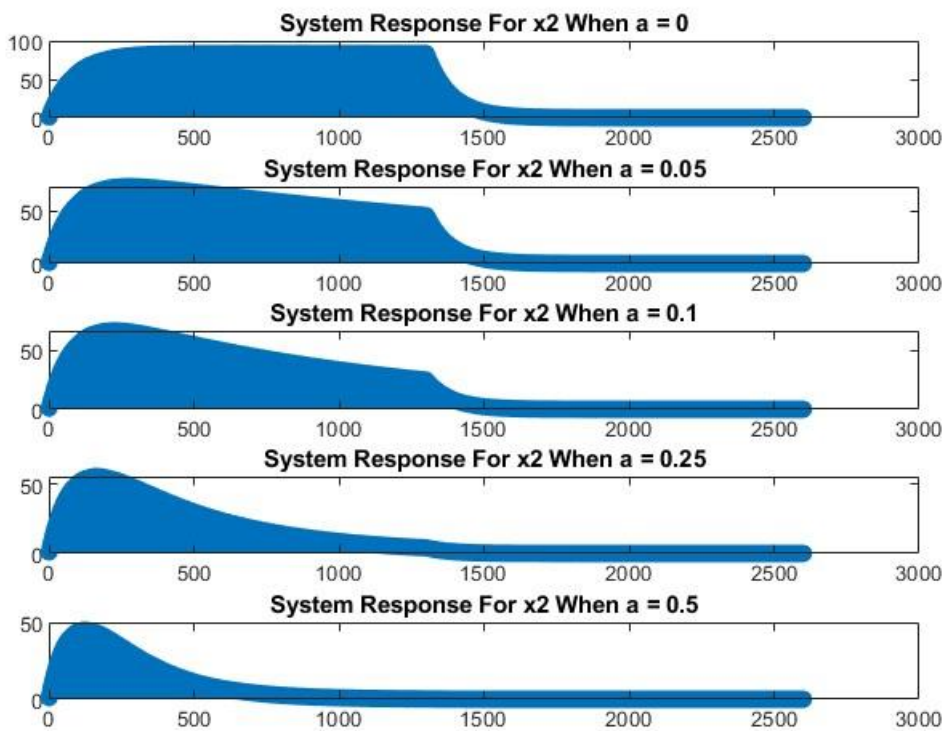
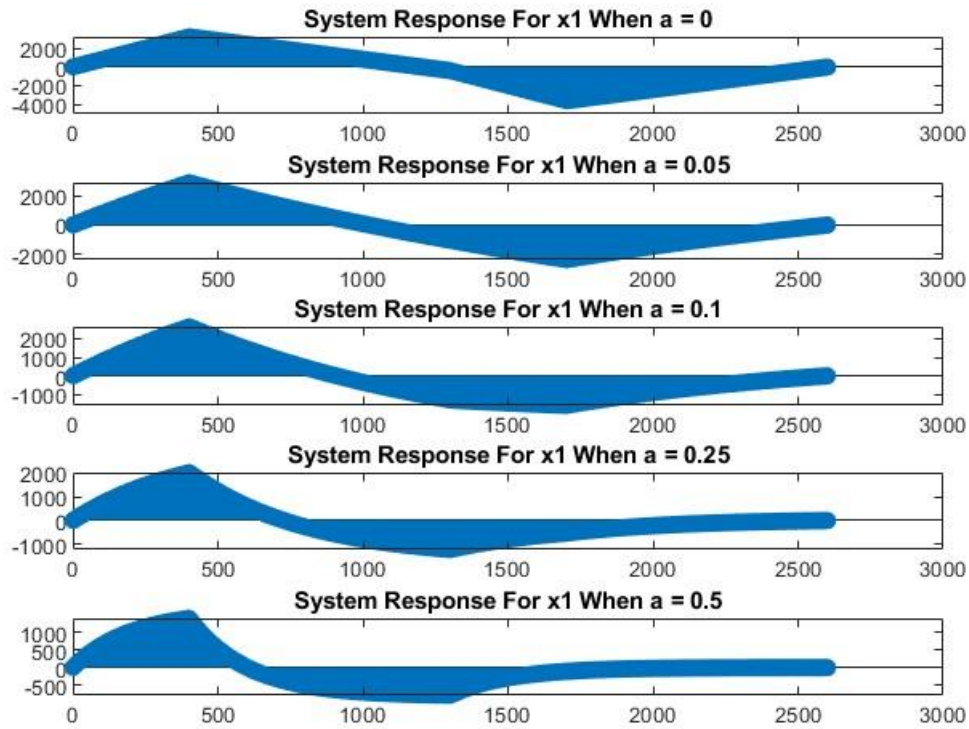
Part 3:

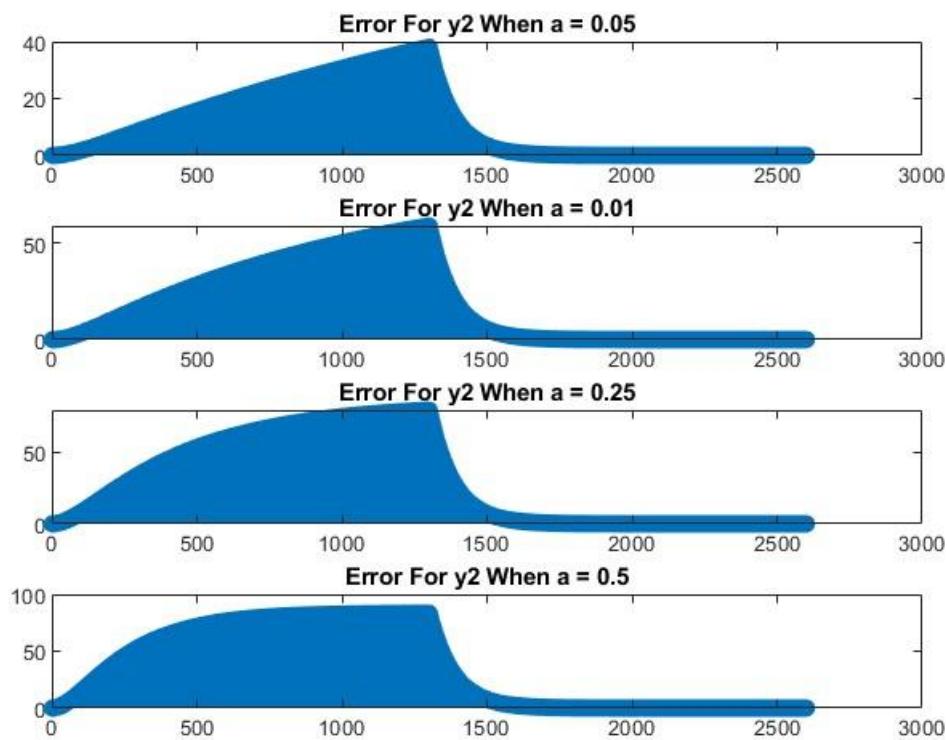
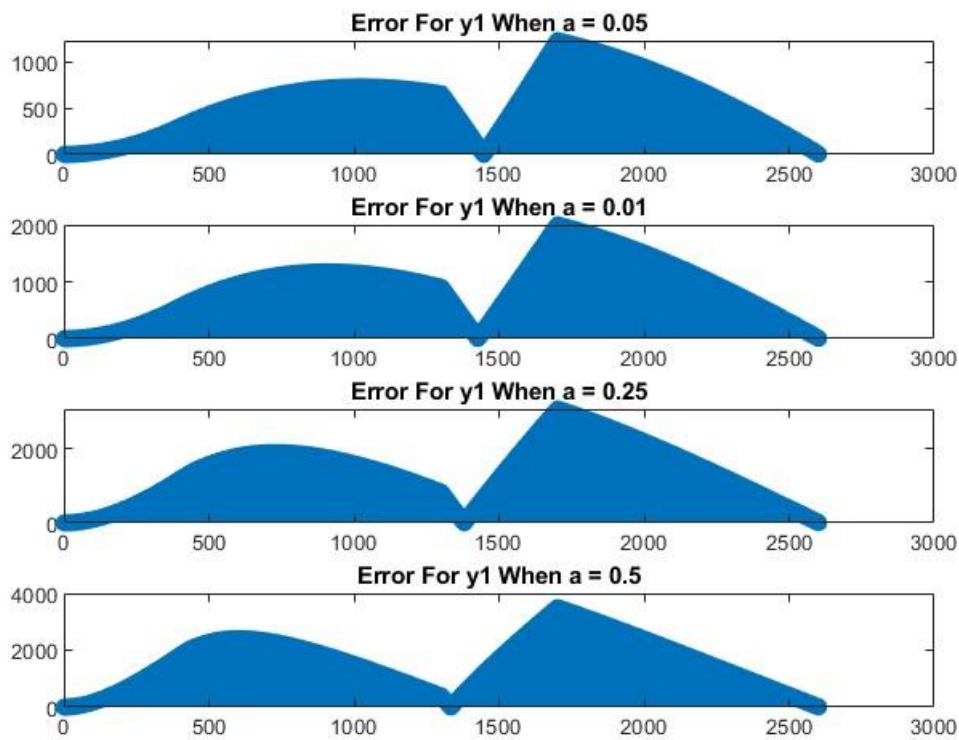


x_1



X2





Part 4:

Part 4.1:

Part 4.1.1

$$y(t) = \frac{dx(t)}{dt} \approx \frac{x(t) - x(t-\Delta t)}{\Delta t}$$

from definition

$$y_{bnd}[n] = x[n] - x[n-1]$$

Namely; $x'[n] = x[n] - x[n-1]$

$$(x'[n])' = (x[n] - x[n-1])'$$

$$x''[n] = x'[n] - x'[n-1]$$

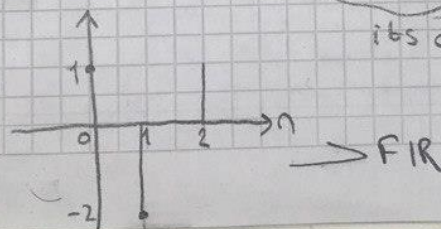
$$x''[n] = x[n] - x[n-1] - (x[n-1] - x[n-2]) = x[n] - 2x[n-1] + x[n-2]$$

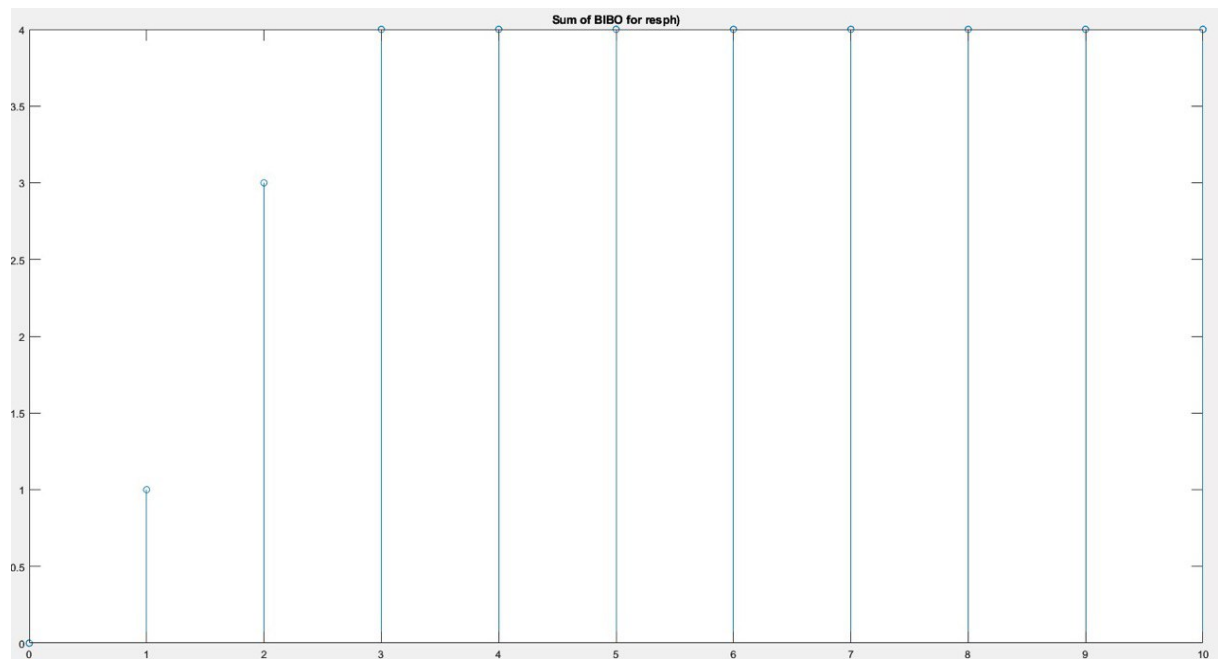
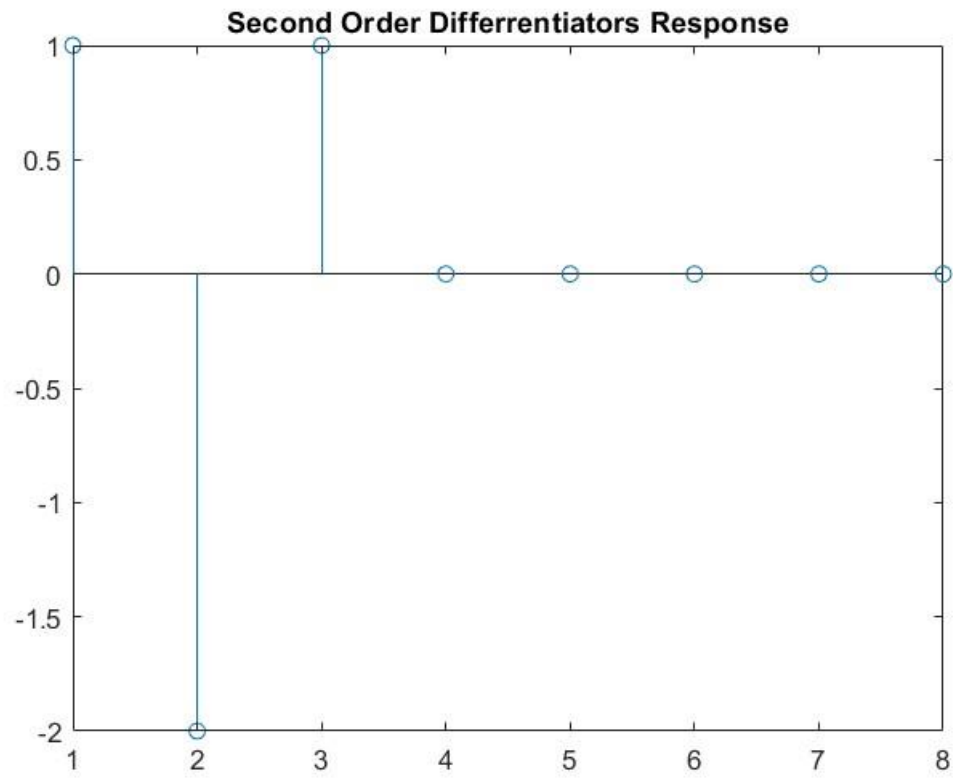
So the system of sec. diff. \rightarrow
when output $(x[n] = \delta[n])$

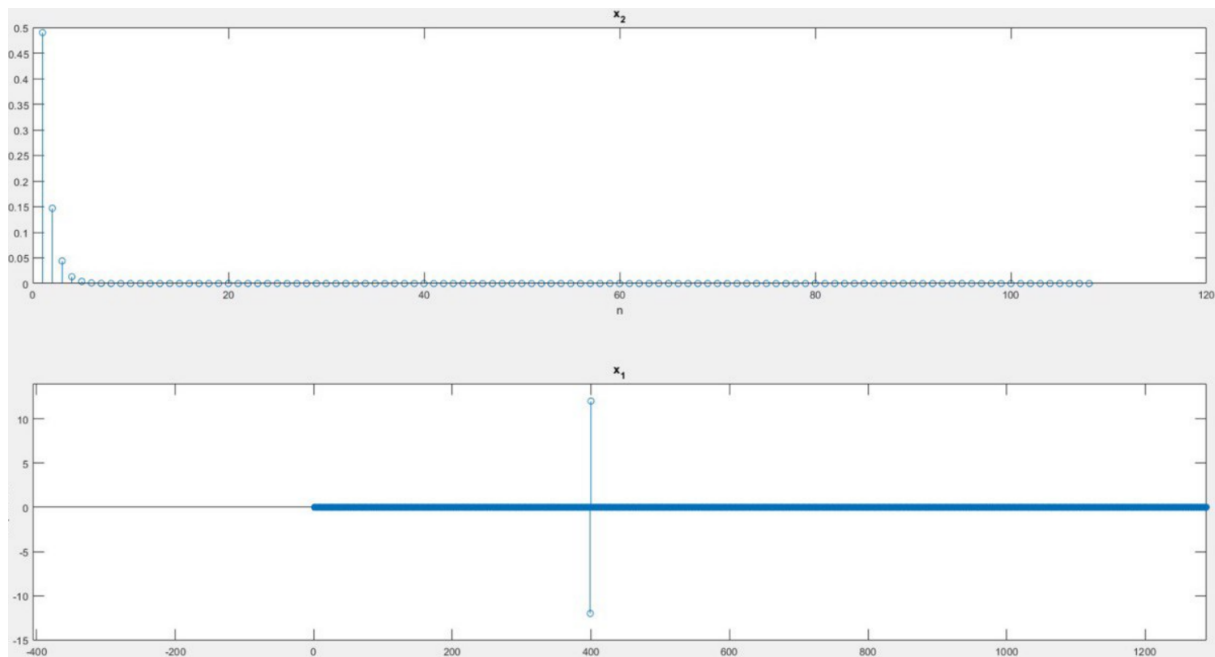
$$h[n] = \delta[n] - 2\delta[n-1] + \delta[n-2]$$

its causal

it has memory





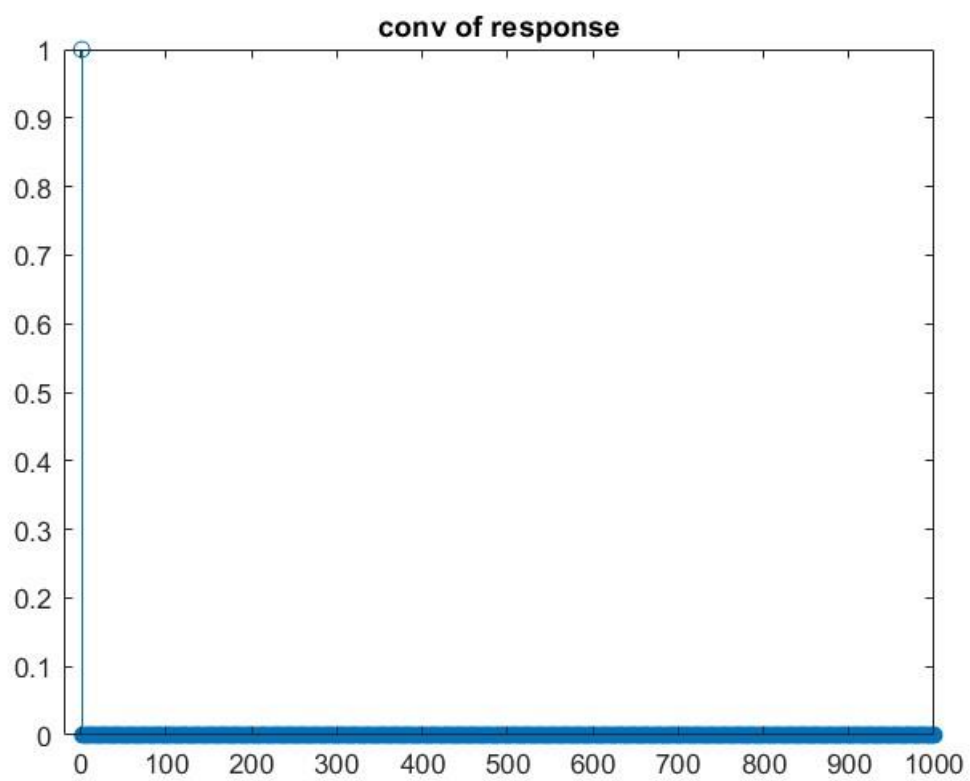
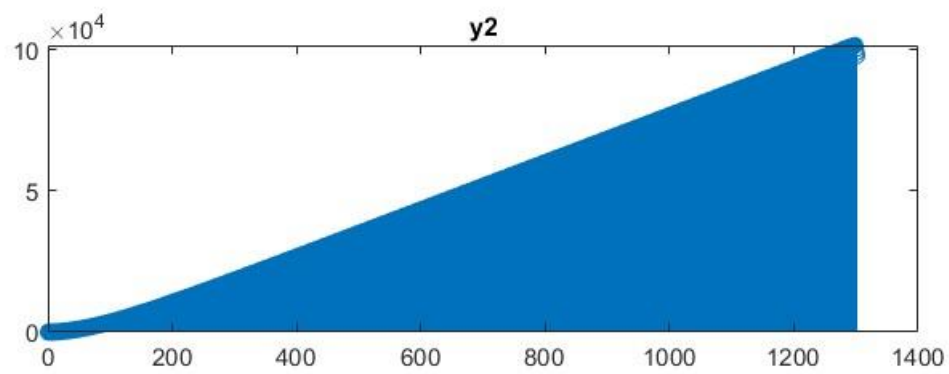
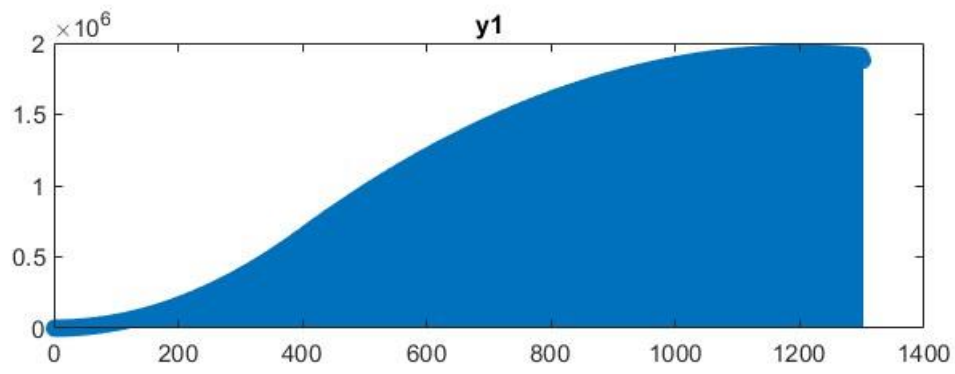


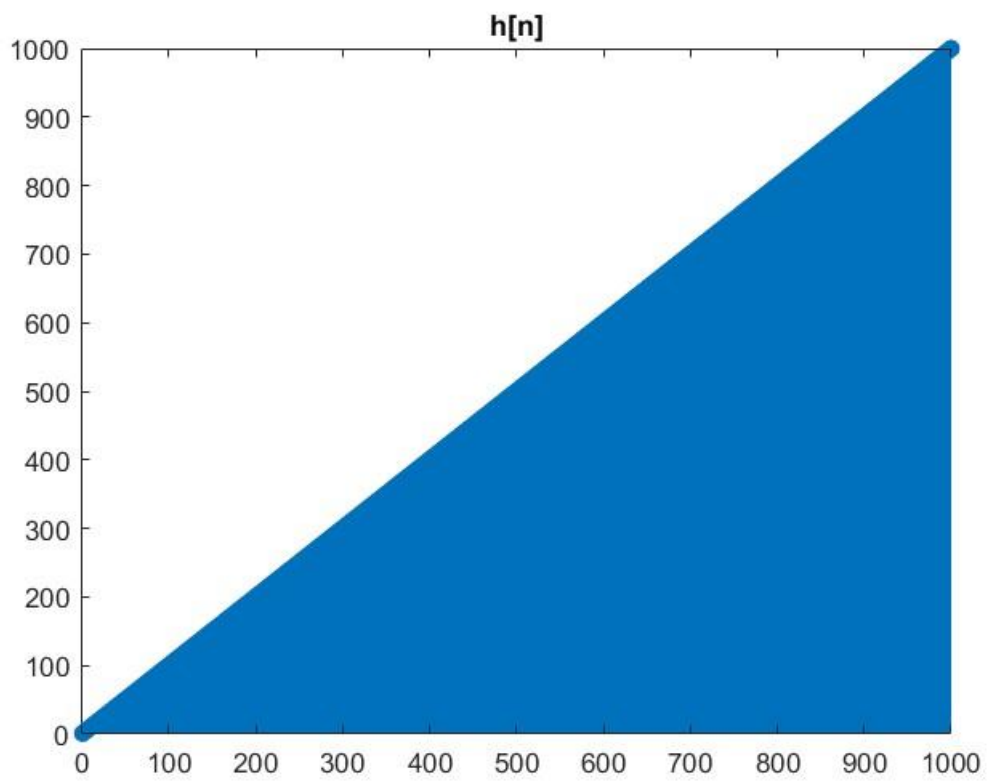
Part 4.2

As given in the hint

function you get. Comment on this. (**Hint:** To obtain the inverse system, you may use the fact that $h[n] * h^{-1}[n] = \delta[n]$.)

So from hint and our knowledge we get Dirac Delta Function if we integrate of the second order derivative is second order integral. The results are following.





Appendices:

Codes For Part 1.3:

```
samp = 0.01
t = -10:samp:10
dir = zeros(size(t))
dir(1001)=1

stepfunc = zeros(size(t))
stepfunc(1001:end)=1

ydir = zeros(size(t))
ystep = zeros(size(t))

for n=2:(length(t))
    ydir(n) = ydir(n-1)+dir(n)
    ystep(n) = ystep(n-1)+stepfunc(n)
end
subplot(2,1,1);
stem(ydir);
title('Impulse Response For Ideal Integrator');

subplot(2,1,2);
stem(ystep)
title('Unit Step Response For Ideal Integrator');

a=0.5
impulseres = exp((-a)*t).*stepfunc
exposstep = conv(impulseres,stepfunc)
figure;
subplot(2,1,1);
stem(impulseres);
title('Impulse Response For Exponential Integrator');

subplot(2,1,2);
stem(exposstep)
title('Unit Step Response For Exponential Integrator');
```

Codes for Part 2:

a is changed manually for % a= 0, 0.05, 0.10, 0.25, and 0.

```
N_range = 100:300:10000
orreut = sumElements(N_range)
stem(N_range,orreut);
title('When a = 0.25');
xlabel('N');
% a= 0, 0.05, 0.10, 0.25, and 0.

function [sum_array] = sumElements(N_range)
    sum_array = zeros(1,length(N_range));
    uzuNran = length(N_range);
    a = 0.25;
    for i=1:uzuNran
        t = 0:0.01:N_range(i);
        h = exp((-a)*t);
```



```

        sum_array(i) = sum(abs(h(1:N_range(i))));
    end
end

```

Codes for Part 3:

```

samp = 0.01
t = 0:samp:13
stepfunc = ones(size(t))
stepfuncmin4 = stepfunc
stepfuncmin4(1:401) = 0;
stepfuncmin13 = stepfunc
stepfuncmin13(1:1300) = 0
x1 = (8*stepfunc) - (12*stepfuncmin4) - (4*stepfuncmin13)
x2 = 0:1:100;
x2 = (0.3).^t;

```

```

respa0 = exp((-0)*t)
respa005 = exp((-0.05)*t)
respa01 = exp((-0.1)*t)
respa025 = exp((-0.25)*t)
respa05 = exp((-0.5)*t)

```

```

resx1a0 = conv(respa0,x1)
resx1a005 = conv(respa005,x1)
resx1a01 = conv(respa01,x1)
resx1a025 = conv(respa025,x1)
resx1a05 = conv(respa05,x1)

```

```

resx2a0 = conv(respa0,x2)
resx2a005 = conv(respa005,x2)
resx2a01 = conv(respa01,x2)
resx2a025 = conv(respa025,x2)
resx2a05 = conv(respa05,x2)

```

```

figure;
stem(t,x1)

```

```

figure;
stem(t,x2)

```

```

figure;
subplot(5,1,1);
stem(resx1a0);
title('System Response For x1 When a = 0');

```

```

subplot(5,1,2);
stem(resx1a005);
title('System Response For x1 When a = 0.05');

```

```

subplot(5,1,3);
stem(resx1a01);
title('System Response For x1 When a = 0.1');

```

```

subplot(5,1,4);
stem(resx1a025);

```

```
title('System Response For x1 When a = 0.25');

subplot(5,1,5);
stem(resx1a05);
title('System Response For x1 When a = 0.5');
```

```
figure;
subplot(5,1,1);
stem(resx2a0);
title('System Response For x2 When a = 0');

subplot(5,1,2);
stem(resx2a005);
title('System Response For x2 When a = 0.05');

subplot(5,1,3);
stem(resx2a01);
title('System Response For x2 When a = 0.1');

subplot(5,1,4);
stem(resx2a025);
title('System Response For x2 When a = 0.25');

subplot(5,1,5);
stem(resx2a05);
title('System Response For x2 When a = 0.5');
```

```
figure;
subplot(4,1,1);
stem(abs(resx1a0-resx1a005));
title('Error For y1 When a = 0.05');

subplot(4,1,2);
stem(abs(resx1a0-resx1a01));
title('Error For y1 When a = 0.01');

subplot(4,1,3);
stem(abs(resx1a0-resx1a025));
title('Error For y1 When a = 0.25');

subplot(4,1,4);
stem(abs(resx1a0-resx1a05));
title('Error For y1 When a = 0.5');
```

```
figure;
subplot(4,1,1);
stem(abs(resx2a0-resx2a005));
title('Error For y2 When a = 0.05');

subplot(4,1,2);
stem(abs(resx2a0-resx2a01));
title('Error For y2 When a = 0.01');

subplot(4,1,3);
stem(abs(resx2a0-resx2a025));
title('Error For y2 When a = 0.25');
```

```

subplot(4,1,4);
stem(abs(resx2a0-resx2a05));
title('Error For y2 When a = 0.5');

```

Part 4.1

```

N_range = 0:1:10
resph = zeros(1,10)
resph(3)=1
resph = diff(resph,2)

samp = 0.01
t = 0:samp:13
stepfunc = ones(size(t));
stepfuncmin4 = stepfunc
stepfuncmin4(1:401) = 0;
stepfuncmin13 = stepfunc
stepfuncmin13(1:1300) = 0;
x1 = (8*stepfunc) - (12*stepfuncmin4) - (4*stepfuncmin13);
x2 = (0.3).^t;

secdiffconvforx1 = conv(x1,resph);
secdiffconvforx2 = conv(x2,resph);

figure;
stem(resph)
title('Second Order Differentiators Response')

figure;
stem(N_range, sumElements(N_range));
title('Sum of BIBO for resph');

figure;
subplot(2,1,1);
stem(secdiffconvforx1);
title('x1');

subplot(2,1,2);
stem(secdiffconvforx2);
title('x2');

```

Part 4.2

```

ts=0.01
t=0:ts:13
toflen=length(t)
ocaas = zeros(1, toflen);
ourimp = ones(1, toflen);
ourimp(toflen+1)=0
ourimp(toflen+2)=0
ourimp=zeros(4,toflen+2)
ourimp(1)=0
ourimp(2)=0
ourimp(3)=1

```

```

for i = 3:1300
    ocaas(i) = 2*ocaas(i-1) - ocaas(i-2) + ourimp(i);
end

stepfunc = ones(size(t));
stepfuncmin4 = stepfunc
stepfuncmin4(1:401) = 0;
stepfuncmin13 = stepfunc
stepfuncmin13(1:1300) = 0;
ourimp_1 = (8*stepfunc) - (12*stepfuncmin4) - (4*stepfuncmin13);

h=zeros(1,10);
h(1)=1
h(2)=-2
h(3)=1
impconv = conv(ocaas,h);
impconv = impconv(3:end-4);
imp = ocaas(3:end);
ourimp_2 = (0.3).^t;
iska = conv(imp,ourimp_1);
lasc = conv(imp,ourimp_2);

figure;
subplot(2,1,1);
stem(iska(1:toflen));
title('y1');
subplot(2,1,2);
stem(lasc(1:toflen));
title('y2');
figure;
stem(impconv);
title("conv of response");
figure;
stem(imp);
title("h[n]");

```