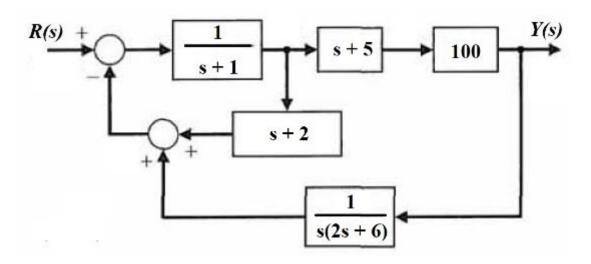
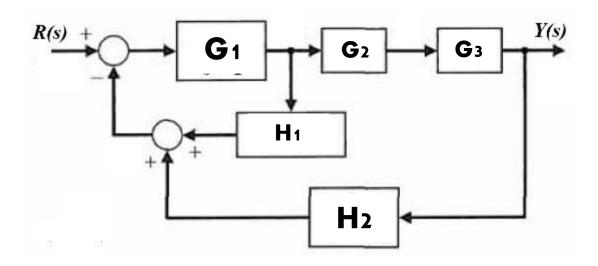
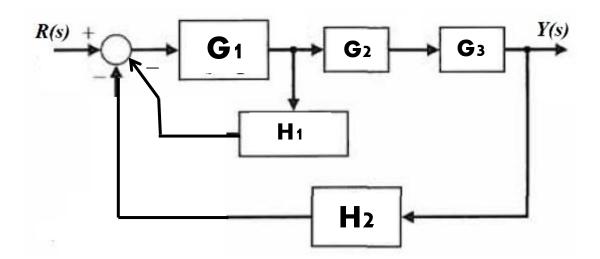


CONTROL SYSTEMS

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1. Define each block of the block diagram.

```
Command Window
  >> clear all
  >> num1=[1];
  >> den1=[1 1];
  >> G1=tf(num1,den1)
  G1 =
     1
    s + 1
  Continuous-time transfer function.
  >> num2=[1 5];
  >> den2=[1];
  >> G2=tf(num2,den2)
  G2 =
   s + 5
  Continuous-time transfer function.
  >> num3=[100];
  >> den3=[1];
  >> G3=tf(num3,den3)
  G3 =
    100
  Static gain.
```

```
Command Window
  >> num4=[1 2];
  >> den4=[1];
  >> H1=tf(num4,den4)
  H1 =
    s + 2
  Continuous-time transfer function.
  >> num5=[1];
  >> den5=[2 6 0];
  >> H2=tf(num5,den5)
  H2 =
         1
    2 s^2 + 6 s
  Continuous-time transfer function.
```

2. Set the relation between each block such as (parallel, series, feedback, etc...)

```
<u># NOTE #</u>
```

- *H1 is feedback for G1=(sys1)
- *G2 and G3 are series=(sys2)
- *sys1 and sys2 are series=(sys3)
- *H2 is feedback for the syst3=(transfer_function)

```
Command Window
```

```
>> sys1=feedback(G1,H1,-1)
sys1 =
  2s + 3
Continuous-time transfer function.
>> sys2=series(G2,G3)
svs2 =
  100 s + 500
Continuous-time transfer function.
>> sys3=series(sys1,sys2)
sys3 =
  100 s + 500
   2 s + 3
```

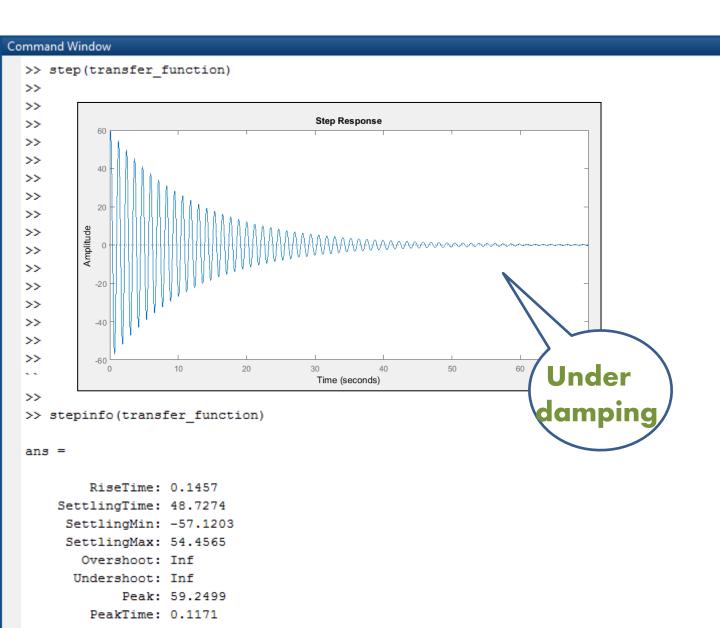
Continuous-time transfer function.

3. Find the transfer function.

Command Window

Continuous-time transfer function.

4. Find the response of the system to a unit step input.



5. Find the impulse response of the system. (impulse input signal)

