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## **Experience**

Mov.ai- Robotics engine: 2021-now

**Backend team leader:** Develop the **core** components of the platform, including the backend web server, services, **orchestration** system, **communication** systems, **security** features, **logging**, **DBs**, **HW**, and **ROS** interfaces and our SDK/ API Also contribute and manage our open source - <u>Movai-flow</u>, <u>Flow-init</u>, <u>DAL</u>, <u>shared</u>, <u>backend</u>, <u>node</u>
Written (and optimize performance) in **python**, to run robotics and perception **algorithms** with best performance

NeuroBlade LTD: 2019-2021

**Simulator Engineer:** Develop simulator based **QEmu open source in C**, simulated new system and all of its components (DMA, Mem, Network) worked with new linux driver and FW on the modulated chip and linux app that run on simulator

Al *Compiler Engineer:* Develop compiler and tools (based on **ONNX** format) for a new accelerate **deep neural networks** chip, in addition to HW validation. Worked with python Al libs (mainly **T.F and PyTorch**), and **OnnxRunTime** open source

Helped to develop the product for accelerating video streaming Android Apps (C++ core SW, and Java for the SDK), In addition, developed Automation testing system (In **Python** with **Jenkins**)

Mellanox LTD: 2014 - 2018

**Development tools and compilers for internal and outer use**: Joined tools team, worked in ongoing projects like: FW 64-bit *LLVM* Compiler and simulator, HW and FW VM **QEMU** Simulator; and other wanted tools mainly in Python (worked with **C++**, **Django**, **ScaPy** and other **Python** libs)

**Development infrastructure in Microsoft new Switch OS in Seattle**: Sent from Mellanox to Microsoft in Seattle for development new open source OS for Open Networking in the Cloud (AKA SONIC), and platform that connect different HW devices as Switch Abstraction Interface (AKA SAI)

Firmware verification and Hardware validation Engineer: Developing test environment in C++ under Linux with a reference model that includes the FW and HW, complicated management model for code coverage and function coverage, and a traffic generator and traffic checker for all the different Eth, TCP, IP and InfiniBand protocols.

Biosense medical Ltd: System Engineer

Planned the architecture that includes the mechanical, electronic and software aspects, and programmed all the product software in **C# on the .NET** environment.

Ben Gurion University: **Programmer** 2012 – 2013

Worked in the DARPA CHALLENGE, in the Israel team.

Programmed in C++ with ROS (Robot Operating System) in Linux, for computer vision tasks

## **Education**

Tel Aviv University M.Sc in Electrical engineering Graduating in 2024

Ben Gurion University B.Sc in Electrical and computer engineering Graduated in 2014

Ort Hermelin College Practical Engineer in Mechanical Engineer Graduated in 2006

Aviv High school Control system and robotics studies Graduated in 2004

Won the second place in the world contest of firefighting robots competition

**Army service**Israel Air Force

UAV technician, team leader in the system department, top secret security clearance 2006 – 2009

C++ C# Java Python Bash IS

Redis SQL InfluxDB Ros Docker QEmu

Comms Compiler Simulation Drivers Linux

AI Vision Arch Optimization FW BE server Security

Tech leader
Team leader
Sys designer
Deep debug
Autodidact
Problem
solver
Vim wizard
Git master
Tech
enthusiast

Just the guy that make it works!

2013 - 2014



