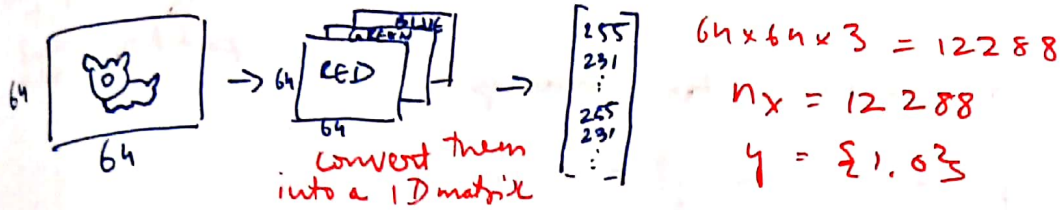


## Week 2: Basics of NN programming

### Binary classification:

(exa: cat(1) or noncat(0))



$$(x, y) \quad x \in \mathbb{R}^{n_x}, \quad y = \{0, 1\}$$

m training examples:  $\{(x^{(1)}, y^{(1)}), (x^{(2)}, y^{(2)}), \dots, (x^{(m)}, y^{(m)})\}$

$M_{\text{train}}$  - no. of training examples

$M_{\text{test}}$  - no. of test examples

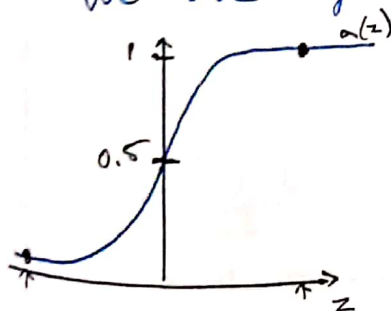
$$X = \begin{bmatrix} | & | & & | \\ x^{(1)} & x^{(2)} & \dots & x^{(m)} \\ | & | & & | \end{bmatrix} \quad X \in \mathbb{R}^{n_x \times m}$$

$$Y = [y^{(1)} \quad y^{(2)} \quad \dots \quad y^{(m)}] \quad Y \in \mathbb{R}^{1 \times m}$$

### Logistic regression:

Given  $x$ , we want  $\hat{y} = P(y=1|x)$  where  $0 \leq \hat{y} \leq 1$

$\therefore$  We use sigmoid function  $\hat{y} = \alpha(\hat{z})$



$$\alpha(z) = \frac{1}{1 + e^{-z}}$$

If  $z$  large,  $\alpha(z) \approx \frac{1}{1+0} = 1$

If  $z$  large negative number,  $\alpha(z) \approx \frac{1}{1+\infty} \approx 0$

Notation:

$$\theta = \begin{bmatrix} \theta_0 \\ \theta_1 \\ \theta_2 \\ \vdots \\ \theta_{n_x} \end{bmatrix} \quad \begin{matrix} \text{real number} \\ \downarrow \\ b \in \mathbb{R} \end{matrix}$$
$$\quad \begin{matrix} \uparrow \\ w \in \mathbb{R}^{n_x} \\ \uparrow \\ n_x \text{ dimension} \\ \text{vector} \end{matrix}$$

Logistic regression cost function:

$$\hat{y}^{(i)} = \sigma(w^T x^{(i)} + b) \text{ where } \sigma(z^{(i)}) = \frac{1}{1 + e^{-z^{(i)}}}$$

Given  $\{(x^{(1)}, y^{(1)}), \dots, (x^{(m)}, y^{(m)})\}$ , want  $\hat{y}^{(i)} \approx y^{(i)}$   
↑ prediction ↑ real value

∴ Loss (error) function: - for 1 example

$$L(\hat{y}, y) = - (y \log \hat{y} + (1-y) \log (1-\hat{y}))$$

If  $y=1$ ,  $L(\hat{y}, y) = -\log \hat{y} \leftarrow$  we want  $\log \hat{y}$  large ∴  $\hat{y}$  large

$y=0$ ,  $L(\hat{y}, y) = -\log (1-\hat{y}) \leftarrow$  we want  $\log (1-\hat{y})$  large ∴  $\hat{y}$  small

∴ Cost function: - for  $m$  examples

$$J(w, b) = \frac{1}{m} \sum_{i=1}^m L(\hat{y}^{(i)}, y^{(i)}) = -\frac{1}{m} \sum_{i=1}^m [y^{(i)} \log \hat{y}^{(i)} + (1-y^{(i)}) \log (1-\hat{y}^{(i)})]$$

Gradient Descent:

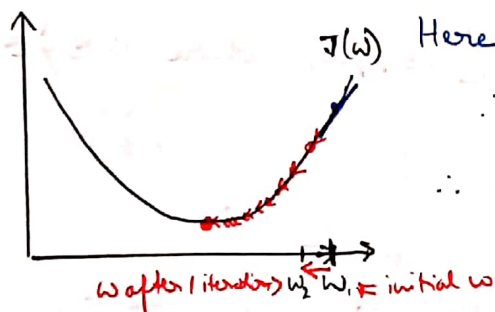
Repeat (till convergence) {

$$w := w - \alpha \frac{dJ(w)}{dw}$$

}

learning rate

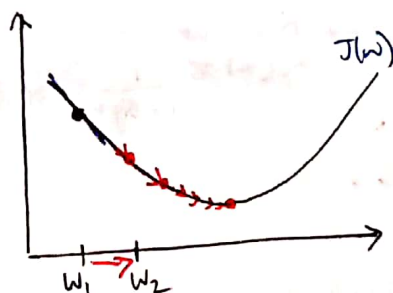
This can be written as  $dw$  while coding and for  $b$ ,  $db$



Here slope is +ve ∴  $\frac{dJ(w)}{dw} > 0$

$$\therefore w := w - \alpha \cdot \text{something}$$

∴  $w$  reduces



Here slope is -ve ∴  $\frac{dJ(w)}{dw} < 0$

$$\therefore w := w - \alpha \cdot \text{something}$$

$$= w := w + \alpha \cdot \text{something}$$

∴  $w$  increases

For  $J(w, b)$ ,

Repeat {

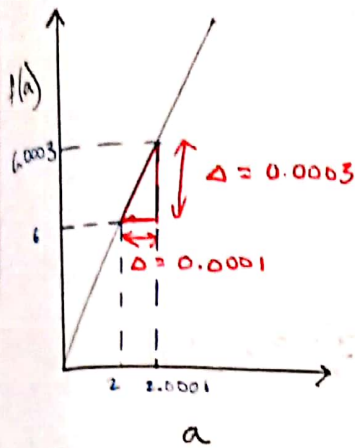
$$w := w - \alpha \frac{\partial J(w, b)}{\partial w}$$

$$b := b - \alpha \frac{\partial J(w, b)}{\partial b}$$

}

we use  $\partial$  (partial derivation) instead of  $d$  when there are more than 1 variables (Ex: here there is  $w$  and  $b$ )

# Derivatives:



$$f(a) = 3a$$

$$\text{when } a = 2, f(a) = 6$$

$$a = 2.0001, f(a) = 6.0003$$

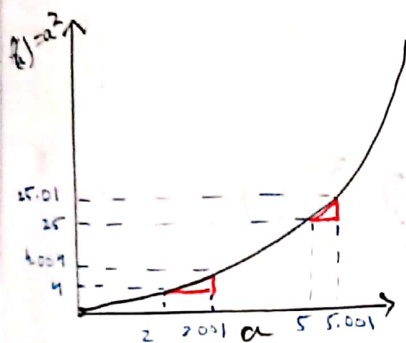
Slope/derivative of  $f(a)$

$$= \frac{\text{height}}{\text{width}} = \frac{0.0003}{0.0001} = 3$$

$$\therefore \frac{df(a)}{da} \text{ or } \boxed{\frac{d}{da} f(a) = 3 \text{ constant}} \therefore \frac{d}{da} f(a) = 3a$$

Note: Here slope remains constant (always 3)

remember derivative of  $3a$  was 3?



$$\textcircled{1} \text{ when } a = 2, f(a) = 4$$

$$a = 2.001, f(a) = 4.004$$

$\therefore$  slope/derivative of  $f(a)$  at  $a = 2$  is 4

$$\frac{d}{da} f(a) = 4 \text{ when } a = 2$$

$$\textcircled{2} \text{ when } a = 5, f(a) = 25$$

$$a = 5.001, f(a) = 25.01$$

$\therefore$  slope/derivative of  $f(a)$  at  $a = 5$  is 10

$$\frac{d}{da} f(a) = 10 \text{ when } a = 5$$

$$\therefore \frac{d}{da} f(a) = \boxed{\frac{d}{da} a^2 = 2a}$$

More examples:

$$f(a) = a^3 \quad \frac{d}{da} f(a) = 3a^2$$

$\Leftarrow$

$$a = 2 \quad f(a) = 8$$

$$a = 2.001 \quad f(a) = 8.012$$

$$3 \times 2^2 = 12$$

$$\Delta = 12$$

$$f(a) = \log(a) \text{ or } \ln(a) \quad \frac{d}{da} f(a) = \frac{1}{a}$$

$\Leftarrow$

$$a = 2 \quad f(a) = 0.69315$$

$$a = 2.001 \quad f(a) = 0.69365$$

$$\frac{1}{2} = 0.0005$$

$$\Delta = 0.0005$$

# Computation Graph:

$$J(a, b, c) = 3(a + \underbrace{bc}_u)$$

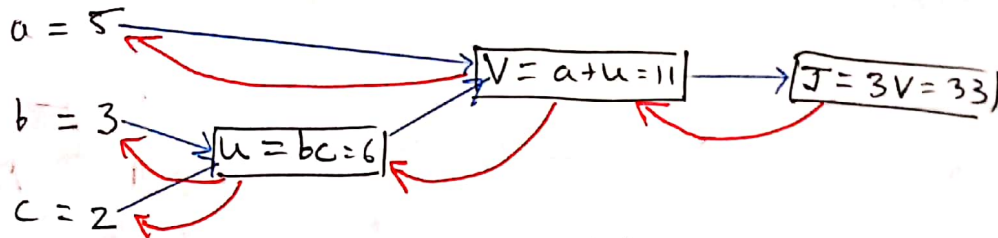
$$\underbrace{\quad\quad\quad}_v$$

$$J$$

$$\therefore u = bc$$

$$v = a + u$$

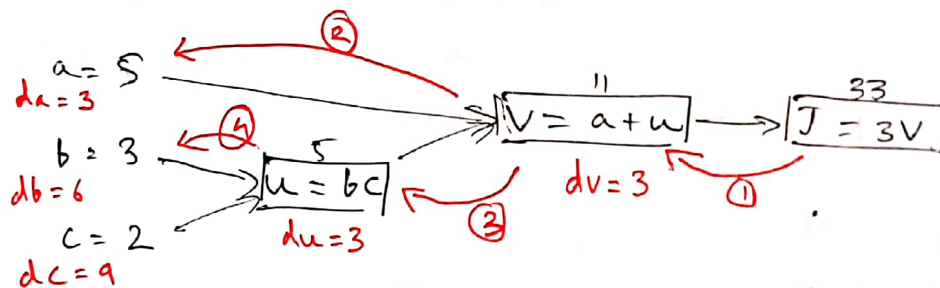
$$J = 3v$$



• Left-to-right pass

• Right-to-left pass  $\leftarrow$  To find derivative

Finding derivatives:



①  $\frac{dT}{dV} = ?$   $J = 3V$   
 $V = 11 \rightarrow 11.001$   
 $J = 33 \rightarrow 33.003$   
 $\therefore \frac{dT}{dV} = 3$

$\leftarrow$  Similar to  $f(a) = 3a$   
 $\frac{df(a)}{da} = 3$  from previous example

②  $\frac{dT}{da} = ?$   $a = 5 \rightarrow 5.001$   
 $V = 11 \rightarrow 11.001$   
 $J = 33 \rightarrow 33.001$   
 $\therefore \frac{dT}{da} = 3 = \frac{dT}{dV} \cdot \frac{dV}{da}$

Chain rule.

If  $a$  affects  $V$  affects  $J$ ,  
 Then  $\frac{dT}{da} \leftarrow$  effect of  $a$  on  $J$   
 $= \frac{dT}{dV} \cdot \frac{dV}{da}$  - effect of  $a$  on  $V$

we found this in step ①  $\rightarrow 3 \cdot 1 = 3$  effect of  $V$  on  $J$

③  $\frac{dT}{du} = \frac{dT}{dV} \cdot \frac{dV}{du} = 3 \cdot 1 = 3$

$u = 6 \rightarrow 6.001$   
 $V = 11 \rightarrow 11.001$   
 $J = 33 \rightarrow 33.003$

④  $\frac{dT}{db} = \frac{dT}{du} \cdot \frac{du}{db} = 3 \cdot 2 = 6$

$b = 3 \rightarrow 3.001$   $3.001 \times 2$   
 $u = b \cdot c \rightarrow 6 \rightarrow 6.002$   $C = 2$  here only  $b$  is  $\uparrow$

⑤  $\frac{dT}{dc} = \frac{dT}{du} \cdot \frac{du}{dc} = 3 \cdot 3 = 9$

$c = 2 \rightarrow 2.001$   
 $u = b \cdot c = 6 \rightarrow 6.003 \leftarrow 2.001 \times 3$

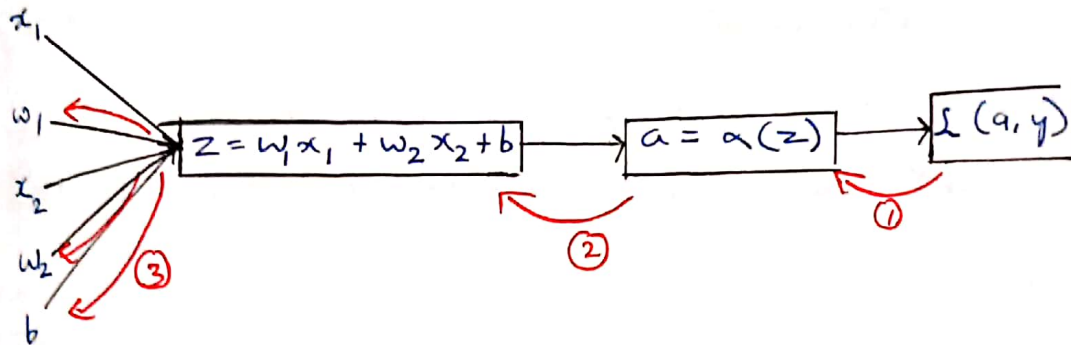


## Logistic Regression Gradient Descent:

$$z = w^T x + b$$

$$\hat{y} = a = \sigma(z)$$

$$L(a, y) = -(y \log(a) + (1-y) \log(1-a))$$



$$\textcircled{1} \quad da = \frac{dL(a, y)}{da} = -\frac{y}{a} + \frac{1-y}{1-a} //$$

$$\textcircled{2} \quad \frac{dz}{dz} = \frac{dL}{da} \cdot \frac{da}{dz} \stackrel{a(1-a)}{=} = a - y //$$

$$\textcircled{3} \quad dw_1 = \frac{dL}{dw_1} = x_1 dz$$

$$dw_2 = \frac{dL}{dw_2} = x_2 dz$$

$$db = \frac{dL}{db} = dz$$

$\therefore$  Gradient descent (one step):

$$w_1 := w_1 - \alpha dw_1$$

$$w_2 := w_2 - \alpha dw_2$$

$$b := b - \alpha db$$

## Gradient Descent for $m$ examples:

The cost function for logistic regression is,

$$J(w, b) = \frac{1}{m} \sum_{i=1}^m L(a^{(i)}, y^{(i)})$$

$$\text{where } a^{(i)} = \hat{y}^{(i)} = \sigma(z^{(i)}) = \sigma(w^T x^{(i)} + b)$$

In the previous example we find  $dw_1^{(i)}$ ,

$dw_2^{(i)}$ ,  $db^{(i)}$  for a single training example  $(x^{(i)}, y^{(i)})$

$$\frac{\partial}{\partial w_1} J(w, b) = \frac{1}{m} \sum_{i=1}^m \underbrace{\frac{\partial}{\partial w_1} L(a^{(i)}, y^{(i)})}_{dw_1^{(i)} \text{ for } (x^{(i)}, y^{(i)})}$$

Algorithm:

$$J = 0; dw_1 = 0; dw_2 = 0; db = 0$$

For  $i = 1$  to  $M$

Forward propagation

$$\begin{cases} z^{(i)} = w^T x^{(i)} + b \\ a^{(i)} = \sigma(z^{(i)}) \\ J += -[y^{(i)} \log a^{(i)} + (1 - y^{(i)}) \log (1 - a^{(i)})] \end{cases}$$

Backward propagation

$$\begin{cases} dz^{(i)} = a^{(i)} - y^{(i)} \\ dw_1 += x_1^{(i)} dz^{(i)} \\ dw_2 += x_2^{(i)} dz^{(i)} \\ db += dz^{(i)} \end{cases} \quad \left. \vphantom{\begin{cases} dw_1 += x_1^{(i)} dz^{(i)} \\ dw_2 += x_2^{(i)} dz^{(i)} \\ db += dz^{(i)} \end{cases}} \right\} \begin{array}{l} \text{For } n=2, \text{ otherwise} \\ \text{we would find } dw_1, dw_2 \\ dw_3, dw_4 \dots dw_n \end{array}$$

$$J /= m$$

$$dw_1 /= m$$

$$dw_2 /= m$$

$$db /= m$$

Using for loops is inefficient, so we use vectorization.

## Vectorization:

We need to compute  $z = w^T x + b$

where  $w = \begin{bmatrix} \vdots \end{bmatrix}$   $x = \begin{bmatrix} \vdots \end{bmatrix}$   $w \in \mathbb{R}^{n \times 1}$   
 $x \in \mathbb{R}^{n \times 1}$

Non-vectorized

$$z = 0$$

for  $i$  in range( $n-x$ ):

$$z += w[i] * x[i]$$

$$z += b$$

Vectorized

$$z = \underbrace{\text{np.dot}(w, x)}_{w^T x} + b$$

## Code

import numpy as np

$a = \text{np.array}([1, 2, 3, 4])$  - initialise array

$u = \text{np.exp}(v)$

- you can use np functions that'll take effect on all the vector

$\text{np.log}(v)$   $\text{np.abs}(v)$   $\text{np.maximum}(v_0)$  values

→ Here we will need a loop, instead we can use vectorization

$$dw += x^{(i)} dz^{(i)}$$

However even here, we use a for loop to iterate through all the training examples. Instead we can vectorize

$$\begin{bmatrix} z^{(1)} & z^{(2)} & \dots & z^{(m)} \end{bmatrix} \rightarrow z = \text{np.dot}(w^T, x) + b$$

$\uparrow$  With broadcasting it'll become

$$\begin{bmatrix} x^{(1)} & x^{(2)} & \dots & x^{(m)} \\ 1 & 1 & \dots & 1 \end{bmatrix}$$

$\mathbb{R}^{n \times m}$

$$\begin{bmatrix} b & b & \dots & b \end{bmatrix}$$

$\mathbb{R}^{1 \times m}$

$a = \sigma(z)$

$$\begin{bmatrix} a^{(1)} & a^{(2)} & \dots & a^{(m)} \end{bmatrix}$$

$$dz = A - Y \leftarrow [y^{(1)} \dots y^{(m)}]$$

$$\uparrow \quad \uparrow$$

$$[dz^{(1)} dz^{(2)} \dots dz^{(m)}] \quad [a^{(1)} a^{(2)} \dots a^{(m)}]$$

$$db = \frac{1}{m} \text{np.sum}(dz)$$

$$dw = \frac{1}{m} X dz^T$$

After that we update  $w$  and  $b$ :

$$w := w - \alpha dw$$

$$b := b - \alpha db$$

Full algorithm:

for iter in range(1000):

$$z = \text{np.dot}(w.T, X) + b$$

$$A = \sigma(z)$$

$$dz = A - Y$$

$$dw = \frac{1}{m} X dz^T$$

$$db = \frac{1}{m} \text{np.sum}(dz)$$

$$w := w - \alpha dw$$

$$b := b - \alpha db$$

← running gradient descent 1000 times  
(we can't vectorise this)



## Broadcasting in Python

Python automatically rescales variables to fit the array/vector calculation

$$① \begin{bmatrix} 1 \\ 2 \\ 3 \\ n \end{bmatrix} + 100 \Rightarrow \begin{bmatrix} 1 \\ 2 \\ 3 \\ n \end{bmatrix} + \begin{bmatrix} 100 \\ 100 \\ 100 \\ 100 \end{bmatrix} = \begin{bmatrix} 101 \\ 102 \\ 103 \\ 10n \end{bmatrix}$$

$$② \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix} + \begin{bmatrix} 100 & 200 & 300 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix} + \begin{bmatrix} 100 & 200 & 300 \\ 100 & 200 & 300 \end{bmatrix} = \begin{bmatrix} 101 & 202 & 303 \\ 104 & 205 & 306 \end{bmatrix}$$

$$③ \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix} + \begin{bmatrix} 100 \\ 200 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix} + \begin{bmatrix} 100 & 100 & 100 \\ 200 & 200 & 200 \end{bmatrix} = \begin{bmatrix} 101 & 102 & 103 \\ 204 & 205 & 206 \end{bmatrix}$$

## Common Bugs

① While initialising vectors, declare both the no. of rows & columns.

$$a = \text{np.random.randn}(5, 1) \quad \text{or} \quad (1, 5)$$

column vector      row vector

If you do  $a = \text{np.random.randn}(5)$ , then  $a$  won't work and  $\text{np.dot}(a, a^T)$  won't work as expected

② You can use  $a = a.\text{reshape}((5, 1))$

## Derivation for Logistic Regression Cost Function (Optional)

$$\text{If } y = 1, \quad P(y|x) = \hat{y} \quad - ①$$

$$\text{If } y = 0, \quad P(y|x) = 1 - \hat{y} \quad - ②$$

$$P(y|x) = \hat{y}^y (1 - \hat{y})^{(1-y)}$$

$$\text{If } y = 1, \quad P(y|x) = \hat{y}^1 (1 - \hat{y})^0 = \hat{y} \quad - ①$$

$$\text{If } y = 0, \quad P(y|x) = \hat{y}^0 (1 - \hat{y})^1 = 1 - \hat{y} \quad - ②$$

↖ This equation is verified

$$\uparrow \text{maximise this} \quad \log P(y|x) = \log \hat{y}^y (1 - \hat{y})^{(1-y)}$$

$$= y \log \hat{y} + (1 - y) \log (1 - \hat{y})$$

$$= -\mathcal{L}(\hat{y}, y) \quad \downarrow \text{To minimise loss} \quad (\downarrow \text{since we added } -)$$

$$\mathcal{J}(w, b) = \frac{1}{m} \sum_{i=1}^m \mathcal{L}(\hat{y}^{(i)}, y^{(i)})$$

For  $m$  training examples