

# **LONG QUESTIONS**

### Define Translatory motion and its types. (LHR 2011, 2012, 2013 GRW 2013, 2015) 0.1

Such type of motion in which a body moves along a line without any rotation. The line Ans: may be straight or curved.

# **Examples**

- Motion of a car in straight line
- Motion of electron around the nucleus
- Motion of gas molecules
- Aeroplane moving straight is in translational motion

# **Types of Translatory Motion**

There are three types of translatory motion.

(i) Linear motion

(LHR 2014)

- (ii) Circular motion
- (iii)Random motion

(LHR 2013, 2014)

#### (i) Linear motion

If the motion of a body is in straight line, it is known as linear motion.

## Examples

- The motion of freely falling bodies
- A car moving along the straight line

#### Circular motion (ii)

If a body moves in a circle then its motion is known as circular motion.

# **Examples**

- A stone attached with thread, when whirled, it will move along a circular path.
- A toy train moving on a circular track.
- A bicycle or car moving along a circular track
- Earth moving around the sun in solar system

### (iii) Random motion

The disordered or irregular motion of an object is called random motion.

## **Examples**

- The flight of an insect and birds
- Brownian motion of gas or liquid molecules
- Motion of dust or smoke particles in air



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# Q.2 Explain Distance – time Graph.

Ans: The term distance and displacement are used interchangeably when the motion is in straight line. Similarly, if the motion is in a straight line then speed and velocity are also used interchangeably.

In distance – time graph, time is taken along horizontal axis while the vertical axis shows the distance covered by the object.

# **Object at Rest**

In the graph shown in figure, the distance moved by the object with time is zero. That is the object is at rest. Thus a horizontal line parallel to time axis on a distance – time graph shows that speed of the object is zero.

# Object moving with Constant Speed

The speed of an object is said to be constant if it covers equal distances in equal intervals of time. The distance – time graph as shown in figure is a straight line. Its slope gives the speed of the object.

# Object moving with variable speed

When an object does not cover equal distances in equal intervals of time then its speed is not constant. In this case the distance – time graph is not a straight line as shown in figure. The slope of the curve at any point can be found from the slope of the tangent at that point.

# Q.3 Explain Speed – Time Graph.

**Ans:** In a speed – time graph, time is taken along x – axis and speed is taken along y–axis.

## Object moving with constant speed

When speed of an object is constant with time, then the speed – time graph will be a horizontal line parallel to time – axis as shown in figure. In other words, a straight line parallel to time axis represents constant speed of the object.

# Object moving with uniformly changing speed (uniform acceleration)

Let the speed of an object be changing uniformly. In such a case speed is changing at constant rate. Thus its speed-time graph would be a straight line as shown in figure. A straight line means that the object is moving with uniform acceleration. Slope of the line gives the magnitude of its acceleration.

## Distance travelled by a moving object

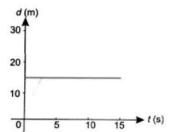


Figure 2.18: Distance-time graph when the object is at rest.

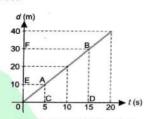


Figure 2.19: Distance-time graph showing constant speed.

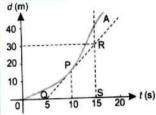


Figure 2.20: Distance-time graph showing variable speed.

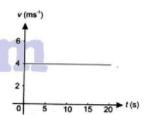


Figure 2.22: Speed-time graph showing constant speed.

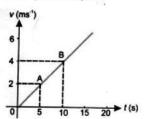


Figure 2.23: Graph of an object moving with uniform acceleration

The area under a speed – time graph represents the distance travelled by the object. If the motion is uniform then the area can be calculated using appropriate formula for geometrical shapes represented by the graph.

# Q.4 Derive first equation of motion using speed time graph.

(GRW 2013)

## Ans: Proof:

Suppose a body is moving with initial velocity  $v_i$  in a straight line with uniform acceleration a. Its velocity becomes  $v_f$  after time t. The motion of the body is described by speed – time graph as shown in figure.

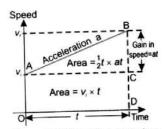


Figure 2.26: Speed-time graph. Area under the graph gives the distance covered by the body.

Slope of line AB = 
$$\frac{BC}{AC}$$

We know that slope of line in speed-time graph gives the magnitude of acceleration.

$$\therefore \text{ Acceleration} = \frac{BC}{AC}$$

$$a = \frac{BC}{AC}$$

As 
$$AC = OD$$
 and  $BC = BD - CD$ 

So, 
$$\mathbf{a} = \frac{BD - CD}{OD}$$

As 
$$BD = v_f$$
,  $CD = v_i$  and  $OD = t$ 

Hence  $a = \frac{vf - v}{v}$ 

Hence  $a = \frac{1}{t}$ 

Or  $v_f - v_i = at$  Therefore,  $v_f = v_i + at$ 

# which is required first equation of motion. O.5 Derive second equation of motion using speed-time graph.

(LHR 2012, 2013)

# Ans: Proof:

Suppose a body is moving with initial velocity  $v_i$  in a straight line with uniform acceleration a. Its velocity becomes  $v_f$  after time t. The motion of the body is described by speed – time graph as shown in figure.

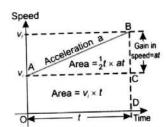


Figure 2.26: Speed-time graph. Area under the graph gives the distance covered by the body.

In speed – time graph the total distance s travelled by the body is equal to the total area of trapezium OABD under the graph. i.e.

Area of the rectangle  $OACD = OA \times OD$ 

$$= v_i \times t$$

Area of trapezium OABD = area of rectangle OACD + area of triangle ABC Putting the values in the above equation, we get

$$s = v_i t + \frac{1}{2} \ at^2$$

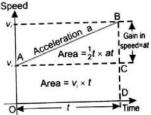
which is required second equation of motion.

## Q.6 Derive third equation of motion using speed-time graph.

(GRW 2015)

#### Proof: Ans:

Suppose a body is moving with initial velocity v<sub>i</sub> in a straight line with uniform acceleration a. Its velocity becomes v<sub>f</sub> after time t. The motion of the body is described by speed – time graph as shown in figure.



In speed – time graph the total distance s travelled by the body is equal to the total area of trapezium OABD under the graph.

Area of trapezium OABD= $\frac{1}{2}$  [sum of parallel sides] [Perpendicular distance between parallel sides]

$$s = \frac{1}{2}(BD + OA)(OD)$$

$$2S = (BD + OA)(OD)$$

Or

Multiply both sides by  $\frac{BC}{QD}$ , we get

$$(as \frac{BC}{QD} = a)$$

$$2\left(\frac{BC}{OD}\right)S = (BD + OA)(OD)\left(\frac{BC}{OD}\right)$$
$$2\left(\frac{BC}{OD}\right)S = (BD + OA)(BC)$$
$$2\left(\frac{BC}{OD}\right)S = (BD + OA)(BD - CD)$$
$$As OA = CD = Vi$$

$$\frac{BC}{OD} = a,$$

and

$$BD = v_f$$

Putting the values in the in the above equation, we have

$$2 \text{ aS} = (v_f + v_i) (v_f - v_i)$$

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$$2aS = v_f^2 - v_i^2$$

Which is required third equation of motion.

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