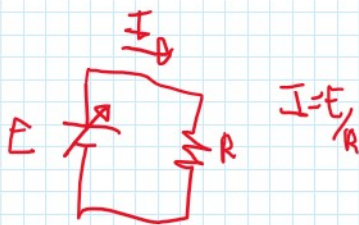


→ MODELAGEM

→ ANÁLISE

→ PROJETO

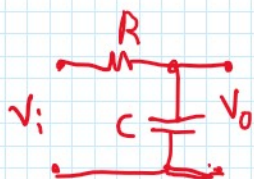


FUNÇÃO TRANSFERÊNCIA
DIAGRAMAS E BLOCOS

TRANSITÓRIA
ERRO
ESTABILIDADE
LUGAR DAS RAÍZES
DIAGRAMA DE BODE

→ IMPLEMENTAÇÃO

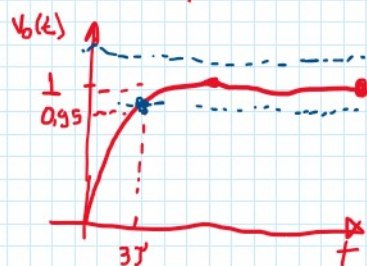
CIRCUITO RC



$$G(s) = \frac{V_o(s)}{V_i(s)} = \frac{1}{Ts + 1}$$

$$T = R \cdot C$$

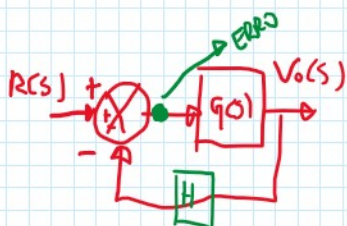
DEGRAU



$$T_{50\%} = 3T = 3s$$

$$R = 1\Omega$$

$$C = 1F$$



$$FTMF = \frac{G}{1 + GH} = \frac{1}{Ts + 1} \cdot \frac{1}{1 + \frac{1}{Ts + 1} \cdot 1} = \frac{1}{Ts + 2} = \frac{0.5}{\frac{T}{2}s + 1}$$

ERRO REG. PERM.

$$e_{ss} = 0.5$$

Tipo
ENTRADA

$$\begin{cases} K_p \rightarrow \frac{1}{1 + K_p} \\ K_v \rightarrow \frac{1}{K_v} \\ K_a \rightarrow \frac{1}{K_a} \end{cases}$$

LUGAR RAÍZES

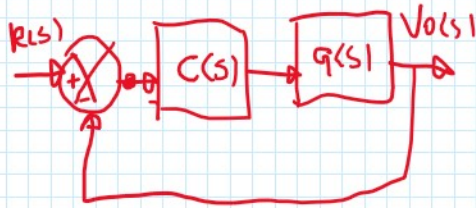
$$1 + GH = 0 \quad \begin{cases} \text{Módulo} \\ \text{Ângulo} \end{cases}$$

PROJETO

$$C(s) = K_p + K_i = K_i \left(\frac{K_p}{K_i} s + 1 \right)$$

$$\gamma \cdot K_p /$$

PROJETO



$$G(s) = K_p + \frac{K_i}{s} = \frac{K_i \left(\frac{K_p}{K_i} s + 1 \right)}{s} \rightarrow J = K_p / K_i$$

$$F.T.L.A. = \frac{K_i}{s} = \frac{K_i \left(\frac{K_p}{K_i} s + 1 \right)}{s} \cdot \frac{1}{\left(\frac{K_p}{K_i} s + 1 \right)}$$

$$F.T.M.F. = \frac{\frac{K_i}{s}}{1 + \frac{K_i}{s}} = \frac{K_i}{s + K_i} = \frac{1}{\frac{s}{K_i} + 1}$$

$$J_N = \frac{1}{K_i}$$

$$\tau_{s\%} = 1s \rightarrow J_N = \frac{1}{3} \rightarrow K_i = 3 \rightarrow K_p = 3$$