## ARTIFICIAL INTELLIGENCE(UNTI-1)

#### CONCEPT OF AI:

The definition of artificial intelligence is the theory and development of computer programs that are able to be tasks and solve problems that usually require human intelligence.

Artificial intelligence is the simulation of human intelligence processes by machines especially computer systems.

#### WHO WROTE THE CONCEPT OF AL.

The term "AI" could be attributed to JOHN Mccarthy of MIT, which Marvin Minsky defines as " the construction of computer programs that engage in tasks that are currently more satisfactionrily performed by human beings because they require high-level

#### WHAT ARE THE COMPONENTS OF AI:

As such, the five basic components of artificial intellegence include Learning, Reasoning, Problem-Solving, Perception, and language understanding.

#### WHAT ARE THE FOUR CONCEPTS OF AI?

Most people focus on the results of Al. For those of us who like to look under the hood, there are four foundational elements to understand:Categorization, Classification, Machine learning, and Collaborative filtering. These four pillars also represent steps in an analytical process.

## HISTORY OF ARTIFICIAL INTELLEGENCE

Artificial Intelligence is not a new word and not a new technology for researchers. This technology is much older than you would imagine. Even there are the myths of Mechanical men in Ancient Greek and Egyptian Myths. Following are some milestones in the history of AI which defines the journey from the AI generation to till date development.

#### Maturation of Artificial Intelligence (1943-1952)

#### Year 1943

The first work which is now recognized as AI was done by Warren McCulloch and Walter pits in 1943. They proposed a model of artificial neurons.

#### Year 1949:

Donald Hebb demonstrated an updating rule for modifying the connection strength between neurons. His rule is now called Hebbian learning.

#### Year 1950:

The Alan Turing who was an English mathematician and pioneered Machine learning in 1950. Alan Turing publishes "Computing Machinery and Intelligence" in which he proposed a test. The test can check the machine's ability to exhibit intelligent behavior equivalent to human intelligence, called a Turing test.

## The birth of Artificial Intelligence (1952-1956)

#### Year 1955:

An Allen Newell and Herbert A. Simon created the "first artificial intelligence program" Which was named as "Logic Theorist". This program had proved 38 of 52 Mathematics theorems, and find new and more elegant proofs for some theorems.

#### Year 1956:

The word "Artificial Intelligence" first adopted by American Computer scientist John McCarthy at the Dartmouth Conference. For the first time, AI coined as an academic field.

At that time high-level computer languages such as FORTRAN, LISP, or COBOL were invented. And the enthusiasm for AI was very high at that time.

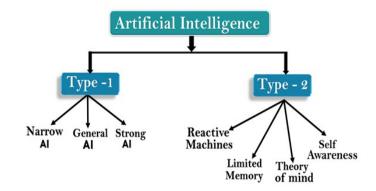
### 3 types of AI periods invented by Pref. Peter Jackson

- 1) CLASSICAL PERIOD: It was stared from 1950. In 1956, the concept of artificial intelligence came into existence. During this period, the main research work carried out includes game playing, theorem proving and concept of state space approach for solving a problem.
- 2)ROMATIC PERIOD: It was started from the mid 1960 and continues until the mid 1970. During this period people were interested in making machine understad, that is usually mean the understading of natural language. During this period the knowledge representation technique "semantic net" was developed.
- 3) MODERN PERIOD : Artificial intelligence is fundamentally intelligence behavior displayed by machines instead of humans.

People who have studied computer science are needed in creating AI because they should observe how the machine reacts to certain variables.

#### TYPES OF ARTIFICIAL INTELLIGENCE

Artificial Intelligence can be divided in various types, there are mainly two types of main categorization which are based on capabilities and based on functionally of AI. Following is flow diagram which explain the types of AI.



#### 1. Weak Al or Narrow Al:

a) Narrow AI is a type of AI which is able to perform a dedicated task with intelligence.The most common and currently

available AI is Narrow AI in the world of Artificial Intelligence

- b) Narrow AI cannot perform beyond its field or limitations, as it is only trained for one specific task. Hence it is also termed as weak AI. Narrow AI can fail in unpredictable ways if it goes beyond its limits
- c) Apple Siriis a good example of Narrow AI, but it operates with a limited pre-defined range of functions
- d) IBM's Watson supercomputer also comes under Narrow AI, as it uses an Expert system approach combined with Machine learning and natural language processing
- e) Some Examples of Narrow Al are playing chess, purchasing suggestions on e-commerce site, self-driving cars, speech recognition, and image recognition.

#### 2. General AI:

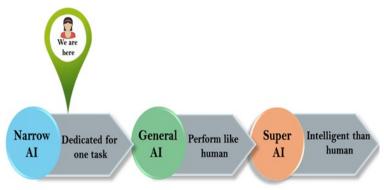
- a)General AI is a type of intelligence which could perform any intellectual task with efficiency like a human.
- b)The idea behind the general AI to make such a system which could be smarter and think like a human by its own.
- c) Currently, there is no such system exist which could come under general Al and can perform any task as perfect as a human.
- d) The worldwide researchers are now focused on developing  $\,$  machines with General AI  $\,$
- e) As systems with general AI are still under research, and it will take lots of efforts and time to develop such systems.

## 3. Super AI:

a)Super Al is a level of Intelligence of Systems at which machines could surpass human intelligence, and can perform any task better than human with cognitive properties. It is an outcome of general Al.

b)Some key characteristics of strong Al include capability include the ability to think, to reason, solve the puzzle, make judgments, plan, learn, and communicate by its own.

c)Super AI is still a hypothetical concept of Artificial Intelligence. Development of such systems in real is still world changing task.



Artificial Intelligence type-2: Based on functionality

- 1. Reactive Machines:
- a)Purely reactive machines are the most basic types of Artificial Intelligence

- b) Such AI systems do not store memories or past experiences for future actions.
- c) These machines only focus on current scenarios and react on it as per possible best action.
- d) IBM's Deep Blue system is an example of reactive machines.
- e) Google's AlphaGo is also an example of reactive machines.

#### 2. Limited Memory:

- a)Limited memory machines can store past experiences or some data for a short period of time.
- b) These machines can use stored data for a limited time period only.
- c) Self-driving cars are one of the best examples of Limited Memory systems. These cars can store recent speed of nearby cars, the distance of other cars, speed limit, and other information to navigate the road.
- 3. Theory of Mind
- a) Theory of Mind AI should understand the human emotions, people, beliefs, and be able to interact socially like humans.
- b) This type of Al machines are still not developed, but researchers are making lots of efforts and improvement for developing such Al machines.

### 4. Self-Awareness

- a)Self-awareness Al is the future of Artificial Intelligence. These machines will be super intelligent, and will have their own consciousness, sentiments, and self-awareness.
- b)These machines will be smarter than human mind.
- c)Self-Awareness AI does not exist in reality still and it is a hypothetical concept.

#### APPLICATIONS OF ARTIFICAL INTELLIGENCE

Artificial Intelligence has various applications in today's society. It is becoming essential for today's time because it can solve complex problems with an efficient way in multiple industries, such as Healthcare, entertainment, finance, education, etc. Al is making our daily life more comfortable and fast.

Following are some sectors which have the application of Artificial Intelligence:

#### 1. Al in Astronomy

Artificial Intelligence can be very useful to solve complex universe problems. Al technology can be helpful for understanding the universe such as how it works, origin, etc.

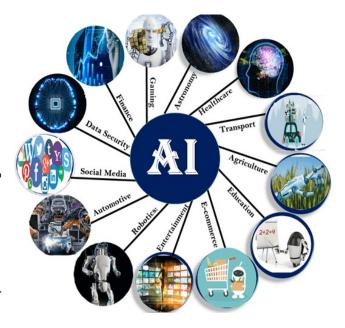
## 2. Al in Healthcare

a) In the last, five to ten years, Al becoming more advantageous for the healthcare industry and going to have a significant impact on this industry.

b)Healthcare Industries are applying AI to make a better and faster diagnosis than humans. AI can help doctors with diagnoses and can inform when patients are worsening so that medical help can reach to the patient before hospitalization.

### 3. Al in Gaming

Al can be used for gaming purpose. The Al machines can play strategic games like chess, where the machine needs to think of a large number of possible places.



#### 4. Al in Finance

Al and finance industries are the best matches for each other. The finance industry is implementing automation, chatbot, adaptive intelligence, algorithm trading, and machine learning into financial processes.

#### 5. Al in Data Security

The security of data is crucial for every company and cyber-attacks are growing very rapidly in the digital world. Al can be used to make your data more safe and secure. Some examples such as AEG bot, Al2 Platform, are used to determine software bug and cyber-attacks in a better way.

#### 6. Al in Social Media

Social Media sites such as Facebook, Twitter, and Snapchat contain billions of user profiles, which need to be stored and managed in a very efficient way. Al can organize and manage massive amounts of data. Al can analyze lots of data to identify the latest trends, hashtag, and requirement of different users.

#### 7. Al in Travel & Transport

Al is becoming highly demanding for travel industries. Al is capable of doing various travel related works such as from making travel arrangement to suggesting the hotels, flights, and best routes to the customers. Travel industries are using Al-powered chatbots which can make human-like interaction with customers for better and fast response.

#### 8. Al in Robotics:

a) Artificial Intelligence has a remarkable role in Robotics. Usually, general robots are programmed such that they can perform some repetitive task, but with the help of AI, we can create intelligent robots which can perform tasks with their own experiences without preprogrammed.

b)Humanoid Robots are best examples for Al in robotics, recently the intelligent Humanoid robot named as Erica and Sophia has been developed which can talk and behave like humans.

#### 9. Al in Agriculture:

Agriculture is an area which requires various resources, labor, money, and time for best result. Now a day's agriculture is becoming digital, and Al is emerging in this field. Agriculture is applying Al as agriculture robotics, solid and crop monitoring, predictive analysis. Al in agriculture can be very helpful for farmers.

### 10. Al in education:

- a) Al can automate grading so that the tutor can have more time to teach. Al chatbot can communicate with students as a teaching assistant.
- b) Al in the future can be work as a personal virtual tutor for students, which will be accessible easily at any time and any place.

## Agents in Artificial Intelligence

An AI system can be defined as the study of the rational agent and its environment. The agents sense the environment through sensors and act on their environment through actuators. An AI agent can have mental properties such as knowledge, belief, intention, etc.

## What is an Agent?

An agent can be anything that perceiveits environment through sensors and act upon that environment through actuators. An Agent runs in the cycle of **perceiving**, **thinking**, and **acting**. An agent can be:

**Human-Agent:** A human agent has eyes, ears, and other organs which work for sensors and hand, legs, vocal tract work for actuators.

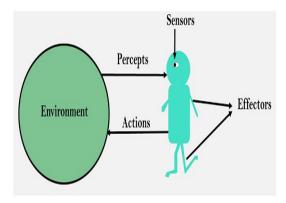
**Robotic Agent:** A robotic agent can have cameras, infrared range finder, NLP for sensors and various motors for actuators.

**Software Agent:**Software agent can have keystrokes, file contents as sensory input and act on those inputs and display output on the screen.

Sensor:Se information to other electronic devices. An agent observes its environensor is a device which detects the change in the environment and sends thment through sensors.

**Actuators:** Actuators are the component of machines that converts energy into motion. The actuators are only responsible for moving and controlling a system. An actuator can be an electric motor, gears, rails, etc.

**Effectors:**Effectors are the devices which affect the environment. Effectors can be legs, wheels, arms, fingers, wings, fins, and display screen.



## Structure of an Al Agent

The task of AI is to design an agent program which implements the agent function. The structure of an intelligent agent is a combination of architecture and agent program. It can be viewed as:

Agent = Architecture + Agent program

Following are the main three terms involved in the structure of an AI agent:

Architecture: Architecture is machinery that an AI agent executes on.

Agent Function: Agent function is used to map a percept to an action.

**Agent program:** Agent program is an implementation of agent function. An agent program executes on the physical architecture to produce function f.

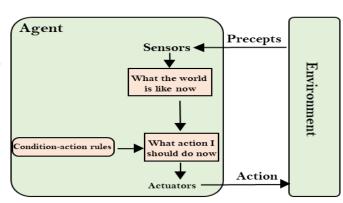
## Types of Al Agents

Agents can be grouped into five classes based on their degree of perceived intelligence and capability. All these agents can improve their performance and generate better action over the time. These are given below:

- a)Simple Reflex Agent
- b)Model-based reflex agent
- c)Goal-based agents
- d)Utility-based agent
- e)Learning agent

## 1. Simple Reflex agent:

- a) The Simple reflex agents are the simplest agents. These agents take decisions on the basis of the current percepts and ignore the rest of the percept history.
- b) These agents only succeed in the fully observable environment.
- c)The Simple reflex agent does not consider any part of percepts history during their decision and action process.
- d)The Simple reflex agent works on Condition-action rule, which means it maps the current state to action. Such as a Room Cleaner agent, it works only if there is dirt in the room.
- e)Problems for the simple reflex agent design approach:
- 1)They have very limited intelligence
- 2)They do not have knowledge of non-perceptual parts of the current state
- 3)Mostly too big to generate and to store
- 4)Not adaptive to changes in the environment.



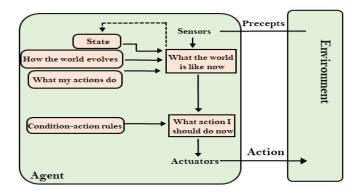
## 2. Model-based reflex agent

- 1)The Model-based agent can work in a partially observable environment, and track the situation.
- 2)A model-based agent has two important factors:
- 3) Model:It is knowledge about "how things happen in the world," so it is called a Model-based agent.
- 4) Internal State: It is a representation of the current state based on percept history.

These agents have the model, "which is knowledge of the world" and based on the model they perform actions.

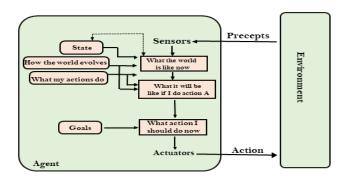
Updating the agent state requires information about:

- a)How the world evolves
- b)How the agent's action affects the world.



# 3. Goal-based agents

- 1)The knowledge of the current state environment is not always sufficient to decide for an agent to what to do.
- 2)The agent needs to know its goal which describes desirable situations.
- 3)Goal-based agents expand the capabilities of the model-based agent by having the "goal" information.
- 4) They choose an action, so that they can achieve the goal.
- 5)These agents may have to consider a long sequence of possible actions before deciding whether the goal is achieved or not. Such considerations of different scenario are called searching and planning, which makes an agent proactive.

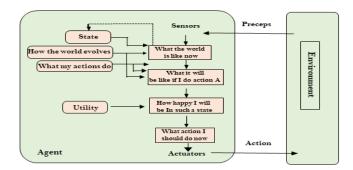


## 4. Utility-based agent

a)These agents are similar to the goal-based agent but provide an extra component of utility measurement which makes them different by providing a measure of success at a given state.

b)Utility-based agent act based not only goals but also the best way to achieve the goal.

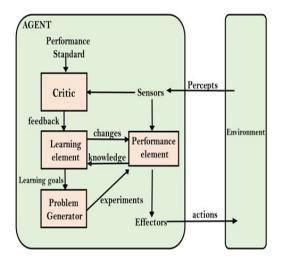
- c)The Utility-based agent is useful when there are multiple possible alternatives, and an agent has to choose in order to perform the best action.
- d)The utility function maps each state to a real number to check how efficiently each action achieves the goals.



## 5. Learning Agents

- a)A learning agent in AI is the type of agent which can learn from its past experiences, or it has learning capabilities.
- b) It starts to act with basic knowledge and then able to act and adapt automatically through learning.
- c) A learning agent has mainly four conceptual components, which are:
  - 1.Learning element:It is responsible for making improvements by learning from environment
  - 2.Critic:Learning element takes feedback from critic which describes that how well the agent is doing with respect to a fixed performance standard.
  - 3.Performance element:It is responsible for selecting external action
  - **4.Problem generator:**This component is responsible for suggesting actions that will lead to new and informative experience.

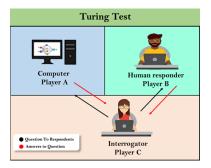
d)Hence, learning agents are able to learn, analyze performance, and look for new ways to improve the performance.



# Turing Test in Al

In 1950, Alan Turing introduced a test to check whether a machine can think like a human or not, this test is known as the Turing Test. In this test, Turing proposed that the computer can be said to be an intelligent if it can mimic human response under specific conditions.

Turing Test was introduced by Turing in his 1950 paper, "Computing Machinery and Intelligence," which considered the question, "Can Machine think?"



The Turing test is based on a party game "Imitation game," with some modifications. This game involves three players in which one player is Computer, another player is human responder, and the third player is a human Interrogator, who is isolated from other two players and his job is to find that which player is machine among two of them.

Consider, Player A is a computer, Player B is human, and Player C is an interrogator. Interrogator is aware that one of them is machine, but he needs to identify this on the basis of questions and their responses.

The conversation between all players is via keyboard and screen so the result would not depend on the machine's ability to convert words as speech.

The test result does not depend on each correct answer, but only how closely its responses like a human answer. The computer is permitted to do everything possible to force a wrong identification by the interrogator.

The questions and answers can be like:

Interrogator: Are you a computer?

PlayerA (Computer):No

Interrogator: Multiply two large numbers such as (256896489\*456725896)

Player A:Long pause and give the wrong answer.

In this game, if an interrogator would not be able to identify which is a machine and which is human, then the computer passes the test successfully, and the machine is said to be intelligent and can think like a human.

"In 1991, the New York businessman Hugh Loebner announces the prize competition, offering a \$100,000 prize for the first computer to pass the Turing test. However, no Al program to till date, come close to passing an undiluted Turing test".

## Agent Environment in Al

An environment is everything in the world which surrounds the agent, but it is not a part of an agent itself. An environment can be described as a situation in which an agent is present.

The environment is where agent lives, operate and provide the agent with something to sense and act upon it. An environment is mostly said to be non-feministic.

# Features of Environment

As per Russell and Norvig, an environment can have various features from the point of view of an agent:

- 1. Fully observable vs Partially Observable
- 2.2)Static vs Dynamic
- 3.Discrete vs Continuous

- 4. Deterministic vs Stochastic
- 5.Single-agent vs Multi-agent
- 6.Episodic vs sequential
- 7.Known vs Unknown
- 8.Accessible vs Inaccessible

## 1. Fully observable vs Partially Observable:

a)If an agent sensor can sense or access the complete state of an environment at each point of time then it is **a fully observable** environment, else it is **partially observable** 

b)A fully observable environment is easy as there is no need to maintain the internal state to keep track history of the world.

c)An agent with no sensors in all environments then such an environment is called as unobservable.

## 2. Deterministic vs Stochastic:

1)If an agent's current state and selected action can completely determine the next state of the environment, then such environment is called a deterministic environment.

2)A stochastic environment is random in nature and cannot be determined completely by an agent.

3)In a deterministic, fully observable environment, agent does not need to worry about uncertainty.

## 3. Episodic vs Sequential:

a)In an episodic environment, there is a series of one-shot actions, and only the current percept is required for the action.

b)However, in Sequential environment, an agent requires memory of past actions to determine the next best actions.

## 4. Single-agent vs Multi-agent

1)If only one agent is involved in an environment, and operating by itself then such an environment is called single agent environment.

2)However, if multiple agents are operating in an environment, then such an environment is called a multi-agent environment.

3)The agent design problems in the multi-agent environment are different from single agent environment.

## 5. Static vs Dynamic:

a) If the environment can change itself while an agent is deliberating then such environment is called a dynamic environment else it is called a static environment.

b)Static environments are easy to deal because an agent does not need to continue looking at the world while deciding for an action.

c)However for dynamic environment, agents need to keep looking at the world at each action.

d)Taxi driving is an example of a dynamic environment whereas Crossword puzzles are an example of a static environment.

### 6. Discrete vs Continuous:

1)

If in an environment there are a finite number of percepts and actions that can be performed within it, then such an environment is called a discrete environment else it is called continuous environment.

- 2) A chess gamecomes under discrete environment as there is a finite number of moves that can be performed.
- 3) A self-driving car is an example of a continuous environment.

## 7. Known vs Unknown

a)Known and unknown are not actually a feature of an environment, but it is an agent's state of knowledge to perform an action.

b)In a known environment, the results for all actions are known to the agent. While in unknown environment, agent needs to learn how it works in order to perform an action.

c)It is quite possible that a known environment to be partially observable and an Unknown environment to be fully observable.

#### 8. Accessible vs Inaccessible

a)If an agent can obtain complete and accurate information about the state's environment, then such an environment is called an Accessible environment else it is called inaccessible.

b)An empty room whose state can be defined by its temperature is an example of an accessible environment.

c)Information about an event on earth is an example of Inaccessible environment.