

1.5

BASES AND DIMENSION

DEFINITION: A finite set of vectors $\{\vec{v}_1, \dots, \vec{v}_m\}$ is called a basis for a vector space V , if the set spans V and is linearly independent.

Intuitively, a basis is an efficient set for characterizing a vector space, in that any vector can be expressed as a linear combination of the basis vectors, and the basis vectors are independent of one another.

Example: The set of 'n' vectors $\{(1,0, \dots, 0), (0,1,0, \dots, 0), \dots, (0, \dots, 0, 1)\}$ is a basis for \mathbb{R}^n . This basis is called the standard basis for \mathbb{R}^n .

THEOREM: Let $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$ be a basis for a vector space V . If $\{\vec{\omega}_1, \vec{\omega}_2, \dots, \vec{\omega}_m\}$ is a set of more than n vectors in V , then this set is linearly dependent.

Proof: We examine the identity $c_1 \vec{\omega}_1 + \dots + c_m \vec{\omega}_m = 0 \dots (1)$

We will show that values of c_1, \dots, c_m , not all zero, exist, satisfying this identity and proving that the vectors are linearly dependent.

Since the set $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$ is a basis for V , each of the vectors $\{\vec{\omega}_1, \vec{\omega}_2, \dots, \vec{\omega}_m\}$ can be expressed as a linear combination of $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$

Let
$$\vec{\omega}_1 = a_{11} \vec{v}_1 + a_{12} \vec{v}_2 + \dots + a_{1n} \vec{v}_n$$

$$\omega_2 = a_{21}\vec{v}_1 + a_{22}\vec{v}_2 + \cdots + a_{2n}\vec{v}_n$$

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$$\omega_m = a_{m1}\vec{v}_1 + a_{m2}\vec{v}_2 + \cdots + a_{mn}\vec{v}_n$$

Substituting these values in (1) we get

$$c_1(a_{11}\vec{v}_1 + a_{12}\vec{v}_2 + \cdots + a_{1n}\vec{v}_n) + \cdots + c_m(a_{m1}\vec{v}_1 + a_{m2}\vec{v}_2 + \cdots + a_{mn}\vec{v}_n) = 0$$

Rearranging, we get

$$(c_1a_{11} + c_2a_{21} + \cdots + c_ma_{m1})\vec{v}_1 + \cdots + (c_1a_{1n} + c_2a_{2n} + \cdots + c_ma_{mn})\vec{v}_n = 0$$

Since $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$ are linearly independent, we get

$$a_{11}c_1 + a_{21}c_2 + \cdots + a_{m1}c_m = 0$$

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$$a_{1n}c_1 + a_{2n}c_2 + \cdots + a_{mn}c_m = 0$$

Thus finding c 's that satisfy equation (1) reduces to finding solutions to this system of n ' equations in m ' variables. Since $m > n$, the number of variables is greater than the number of equations. We know that such a system of homogeneous equations has many solutions.

Therefore, there are non-zero values of c 's that satisfy equation(1). Thus the set $\{\vec{\omega}_1, \vec{\omega}_2, \dots, \vec{\omega}_m\}$ is linearly dependent.

THEOREM: Any two bases for a vector space V consist of the same number of vectors.

Proof: Let $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$ and $\{\vec{\omega}_1, \vec{\omega}_2, \dots, \vec{\omega}_m\}$ be two bases for V . If we interpret $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$ as a basis for V and $\{\vec{\omega}_1, \vec{\omega}_2, \dots, \vec{\omega}_m\}$ as a set of linearly independent vectors in V , then the previous theorem tells us that $m \leq n$. conversely, if we interpret $\{\vec{\omega}_1, \vec{\omega}_2, \dots, \vec{\omega}_m\}$ as a basis for V and $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$ as a set of linearly independent vectors in V , then $n \leq m$. Thus $n = m$, proving that both the bases consists of same number of vectors.

DEFINITION: If a vector space V has a basis consisting of ' n ' vectors, then the dimension of V is said to be n . we write $\dim(V)$ for dimension of V .

EXAMPLE: The set of ' n ' vectors $\{(1,0, \dots, 0), \dots, (0, \dots 0,1)\}$ forms a basis (the stranded basis) for \mathbb{R}^n . Thus the dimension of \mathbb{R}^n is ' n '.

Note that we have defined a basis for a vector space to be a finite set of vectors that spans the space and is linearly independent. Such a set does not exist for all vector spaces. When such a finite set exists, we say that the vector space is finite dimensional. If such a finite set does not exist, we say that the vector space is infinite dimensional.

THEOREM: Let $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$ be a basis for a vector space V . Then each vector in V can be expressed uniquely as a linear combination of these vectors.

Proof: Let v be a vector in V . Since $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$ is a basis, we can express v as a linear combination of these vectors.

Suppose we can write

$$v = a_1 \vec{v}_1 + a_2 \vec{v}_2 + \dots + a_n \vec{v}_n \text{ and}$$

$$v = b_1 \vec{v}_1 + b_2 \vec{v}_2 + \dots + b_n \vec{v}_n \text{ then}$$

$$a_1 \vec{v}_1 + a_2 \vec{v}_2 + \dots + a_n \vec{v}_n = b_1 \vec{v}_1 + b_2 \vec{v}_2 + \dots + b_n \vec{v}_n$$

$$\Rightarrow (a_1 - b_1) \vec{v}_1 + (a_2 - b_2) \vec{v}_2 + \dots + (a_n - b_n) \vec{v}_n = 0$$

Since $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$ is a basis, the vectors $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$ are linearly independent. Thus $(a_1 - b_1) = 0, \dots, (a_n - b_n) = 0$ implying that $a_1 = b_1, \dots, a_n = b_n$

Therefore there is only one way of expressing v as a linear combination of the basis.

Lemma. Let S be a linearly independent subset of a vector space V . Suppose β is a vector in V which is not in the subspace spanned by S . Then the set obtained by adjoining β to S is linearly independent.

Proof: Suppose $\alpha_1, \dots, \alpha_m$ are distinct vectors in S and that $c_1 \alpha_1 + \dots + c_m \alpha_m + b \beta = 0$.

Then $b = 0$; for otherwise,

$$\beta = \left(-\frac{c_1}{b}\right) \alpha_1 + \dots + \left(-\frac{c_m}{b}\right) \alpha_m$$

and β is in the subspace spanned by S . Thus $c_1 \alpha_1 + \dots + c_m \alpha_m = 0$, and since S is a linearly independent set each $c_i = 0$.

Theorem: If W is a subspace of finite-dimensional vector space V , every linearly independent subset of W is finite and is part of a basis for W .

Proof: Suppose S_0 is a linearly independent subset of W . If S is a linearly independent subset of W containing S_0 , then S is also a linearly independent subset of V ; since V is finite-dimensional, S contains no more than $\dim V$ elements.

We extend S_0 , to a basis for W , as follows. If S_0 spans W , then S_0 is basis for W and we are done. If S_0 does not span W , we use the preceding lemma to find a vector β_1 in W such that the set $S_1 = S_0 \cup \{\beta_1\}$ is independent. If S_1 spans W , fine. If not, apply the lemma to obtain a vector β_2 in W such that $S_2 = S_1 \cup \{\beta_2\}$ is independent. If we continue in this way, then (in not more than $\dim V$ steps) we reach a set

$$S_m = S_0 \cup \{\beta_1, \dots, \beta_m\}$$

Which is a basis for W .

Suppose that a vector space is known to be a dimension n . The following theorem tells us that we do not have to check both linear independence and spanning conditions to see if a given set is a basis.

THEOREM: Let V be a vector space of dimension n .

- a) If $S = \{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$ is a set of n linearly independent vectors in V , then S is a basis for V .

b) If $S = \{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$ is a set of n vectors that spans V , then S is a basis for V .

Proof: (a) part is clear from the above theorem and the fact that every basis of V contains n number of elements.

(b) It is enough to show that S is linearly independent.

Let $\{\vec{u}_1, \vec{u}_2, \dots, \vec{u}_n\}$ be a basis of V . If we give a proof similar to the first theorem of this material and by using the fact that a homogeneous system of linear equations with equal number of variables and equations will have unique solution, we can prove that $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$ is linearly independent.

THEOREM: If W_1 and W_2 are finite-dimensional subspaces of a vector space V , then $W_1 + W_2$ is finite-dimensional and

$$\dim W_1 + \dim W_2 = \dim (W_1 \cap W_2) + \dim(W_1 + W_2)$$

Proof. By Theorem 5 and its corollaries, $W_1 \cap W_2$ has a finite basis $\{\alpha_1, \dots, \alpha_k\}$ which is part of a basis

$$\{\alpha_1, \dots, \alpha_k, \beta_1, \dots, \beta_m\} \text{ for } W_1$$

and part of basis

$$\{\alpha_1, \dots, \alpha_k, \gamma_1, \dots, \gamma_n\} \text{ for } W_2.$$

The subspace $W_1 + W_2$ is spanned by the vectors

$\alpha_1, \dots, \alpha_k, \beta_1, \dots, \beta_m, \gamma_1, \dots, \gamma_n$ and these vectors form an independent set. For suppose

$$\sum x_i \alpha_i + \sum y_j \beta_j + \sum z_r \gamma_r = 0.$$

Then

$$-\sum z_r \gamma_r = \sum x_i \alpha_i + \sum y_j \beta_j$$

which shows that $\sum z_r \gamma_r$ belongs to W_1 . As $\sum z_r \gamma_r$ Also belongs to W_2 it follows that

$$\sum z_r \gamma_r = \sum c_i \alpha_i$$

for certain scalars c_1, \dots, c_k . Because the set

$$\{\alpha_1, \dots, \alpha_k, \gamma_1, \dots, \gamma_n\}$$

is independent, each of the scalars $z_r = 0$. Thus,

$$\sum x_i \alpha_i + \sum y_j \beta_j = 0$$

and since

$$\{\alpha_1, \dots, \alpha_k, \beta_1, \dots, \beta_m\}$$

is also an independent set, each $x_i = 0$ and each $y_j = 0$.

Thus $\{\alpha_1, \dots, \alpha_k, \beta_1, \dots, \beta_m, \gamma_1, \dots, \gamma_n\}$

is a basis for $W_1 + W_2$. Finally

$$\dim W_1 + \dim W_2 = (k + m) + (k + n)$$

$$= k + (m + k + n)$$

$$= \dim(W_1 \cap W_2) + \dim(W_1 + W_2).$$

Problem 1: Show that the set $\{(1,0,-1), (1,1,1), (1,2,4)\}$ is a basis for \mathbb{R}^3 .

Solution: Let us first show that the set spans \mathbb{R}^3 .

Let (x_1, x_2, x_3) be an arbitrary element of \mathbb{R}^3 .

We try to find scalars a_1, a_2, a_3 such that $(x_1, x_2, x_3) = a_1(1,0,-1) + a_2(1,1,1) + a_3(1,2,4)$. This identity leads to the system of equations.

$$a_1 + a_2 + a_3 = x_1$$

$$a_2 + 2a_3 = x_2$$

$$-a_1 + a_2 + 4a_3 = x_3$$

This system of equations has the solution

$$a_1 = 2x_1 - 3x_2 + x_3$$

$$a_2 = -2x_1 + 5x_2 - 2x_3$$

$$a_3 = x_1 - 2x_2 + x_3$$

Thus the set spans the space. We now show that the set is linearly independent.

Consider the identity

$$b_1(1,0,-1) + b_2(1,1,1) + b_3(1,2,4) = (0,0,0)$$

This identity leads to the system of equations.

$$b_1 + b_2 + b_3 = 0$$

$$b_2 + 2b_3 = 0$$

$$-b_1 + b_2 + 4b_3 = 0$$

This system has the unique solution $b_1 = 0, b_2 = 0$, and $b_3 = 0$. Thus the set is linearly independent.

Therefore $\{(1,0,-1), (1,1,1), (1,2,4)\}$ forms a basis for \mathbb{R}^3 .

Problem 2: Prove that the set $\{(1,3,-1), (2,1,0), (4,2,1)\}$ is a basis for \mathbb{R}^3

Solution: The dimension of \mathbb{R}^3 is three. Thus a basis of \mathbb{R}^3 consists of three vectors. We have the correct number of vectors for a basis.

Normally, we would have to show that this set is linearly independent and that it spans \mathbb{R}^3

Since \mathbb{R}^3 is finite dimensional vector space, we need to check only one of these two conditions. Let us check for linear independence. We get $c_1(1,3,-1) + c_2(2,1,0) + c_3(4,2,1) = (0,0,0)$. This identity leads to the system of equations.

$$c_1 + 2c_2 + 4c_3 = 0$$

$$3c_1 + c_2 + 2c_3 = 0$$

$$-c_1 + 4c_3 = 0$$

This system has unique solution $c_1 = 0, c_2 = 0, c_3 = 0$

Thus the vectors are linearly independent. The set $\{(1,3,-1), (2,1,0), (4,2,1)\}$ is therefore a basis for \mathbb{R}^3 .

Problem 3: State (with a brief explanation) whether the following statements are true or false.

(a) The vectors $(1, 2)$, $(-1, 3)$, $(5, 2)$ are linearly dependent in \mathbb{R}^2 .

(b) The vectors $(1, 0, 0)$, $(0, 2, 0)$, $(1, 2, 0)$ span \mathbb{R}^3 .

(c) $\{(1, 0, 2), (0, 1, -3)\}$ is a basis for the subspace of \mathbb{R}^3 consisting of vectors of the form $(a, b, 2a-3b)$.

(d) Any set of two vectors can be used to generate a two-dimensional subspace of \mathbb{R}^3 .

Solution:

(a) True: The dimension of \mathbb{R}^2 is two. Thus any three vectors are linearly dependent.

(b) False: The three vectors are linearly dependent. Thus they cannot span a three-dimensional space.

(c) True: The vectors span the subspace since

$$(a, b, 2a-3b) = a(1, 0, 2) + b(0, 1, -3)$$

The vectors are also linearly independent since they are not collinear.

(d) False: The two vectors must be linearly independent.

Exercise

1. Prove that the subspace of \mathbb{R}^3 generated by the vectors $(-1, 2, 1)$, $(2, -1, 0)$, and $(1, 4, 3)$ is a two dimensional subspace of \mathbb{R}^3 and give a basis for this subspace.
2. Find a basis for \mathbb{R}^3 that includes the vectors $(1, 1, 1)$ and $(1, 0, -2)$.
3. Determine a basis for each of the following subspaces of \mathbb{R}^3 . Give the dimension of each subspace.
 - a) The set of vectors of the form (a, a, b) .
 - b) The set of vectors of the form $(a, b, a + b)$
 - c) The set of vectors of the form (a, b, c) , where $a + b + c = 0$.
4. Which of the following sets of vectors are bases for \mathbb{R}^2 ?
(a) $\{(3, 1), (2, 1)\}$ (b) $\{(1, -3), (-2, 6)\}$
5. Which of the following sets are bases for \mathbb{R}^3 ?
(a) $\{(1, -1, 2), (2, 0, 1), (3, 0, 0)\}$
(b) $\{(2, 1, 0), (-1, 1, 1), (3, 3, 1)\}$
6. Prove that the vector $(1, 2, -1)$ lies in the two dimensional subspace of \mathbb{R}^3 generated by the vectors $(1, 3, 1)$ and $(1, 4, 3)$.
7. Let $\{v_1, v_2\}$ be a basis for a vector space V . Show that the set of vectors $\{u_1, u_2\}$, where $u_1 = v_1 + v_2, u_2 = v_1 - v_2$, is also a basis for V .
8. Let V be a vector space of dimension n . Prove that no set of $n - 1$ vectors can span V .
9. Let V be a vector space, and let W be a subspace of V . If $\dim(V) = n$ and $\dim(W) = m$, prove that $m \leq n$.

Answers

1. $\{(-1, 2, 1), (2, -1, 0)\}$ is a basis.
2. $\{(1, 1, 1), (1, 0, -2), (1, 0, 0)\}$.
3. a) Basis = $\{(1, 1, 0), (0, 0, 1)\}$, dimension = 2.
b) Basis = $\{(1, 0, 1), (0, 1, 1)\}$, dimension = 2.
c) Basis = $\{(1, 0, -1), (0, 1, -1)\}$, dimension = 2.
4. (a) Basis (b) Not a basis
5. (a) Basis (b) Not a basis
6. $(1, 2, -1) = 2(1, 3, 1) - (1, 4, 3)$.