



NVIDIA Instant NeRF

Using neural radiance fields to generate
new views of 2D



Instant NGP

▶ Instant Neural Graphics Primitives with a Multiresolution Hash Encoding

▶ 2022, SIGGRAPH

▶ Best paper award

Instant Neural Graphics Primitives with a Multiresolution Hash Encoding

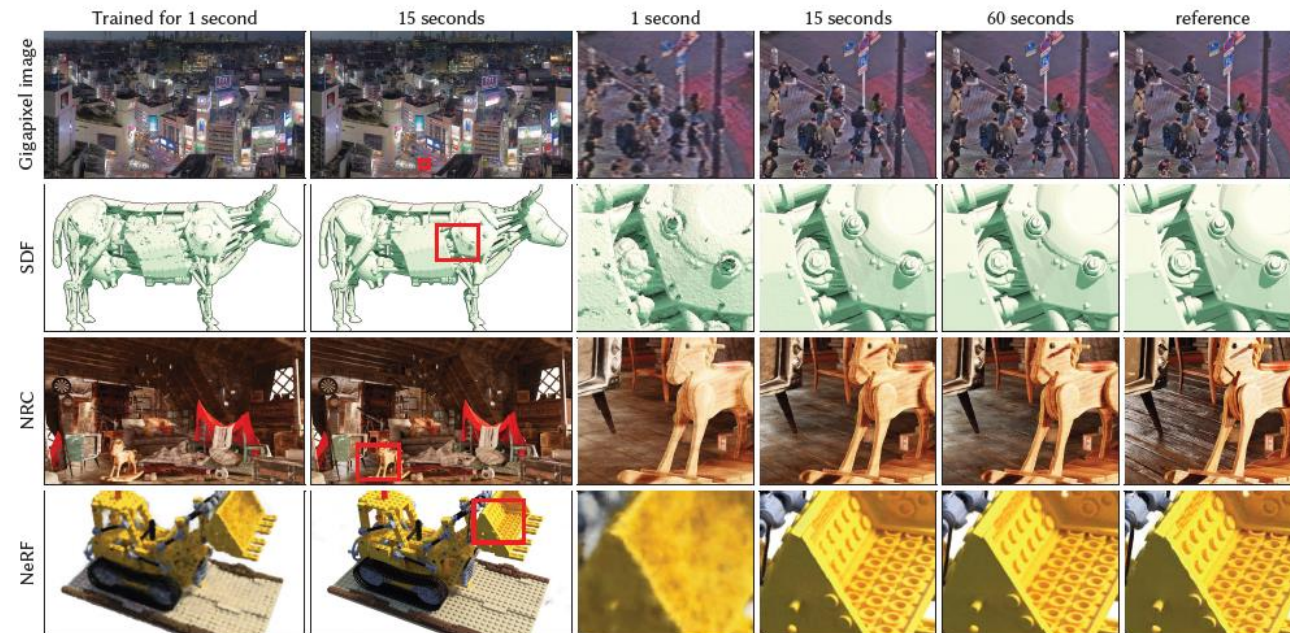
THOMAS MÜLLER, NVIDIA, Switzerland

ALEX EVANS, NVIDIA, United Kingdom

CHRISTOPH SCHIED, NVIDIA, USA

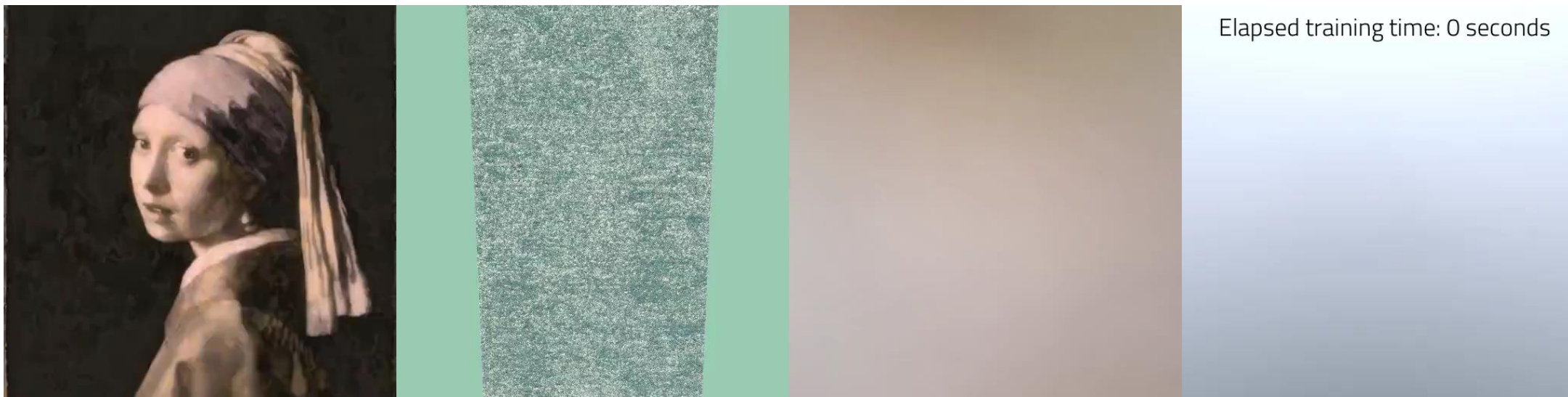
ALEXANDER KELLER, NVIDIA, Germany

<https://nvlabs.github.io/instant-ngp>



Instant NGP

- ▶ Neural Graphics Primitives의 4가지 Task
 - ▶ Gigapixel image
 - ▶ SDF (Signed Distance Function)
 - ▶ **NeRF (Neural Radiance Field)**
 - ▶ NRC (Neural Radiance Caching)



Gigapixel image

SDF

NeRF

NRC





NeRF

- ▶ NeRF : Representing Scenes as Neural Radiance Fields for View Synthesis
 - ▶ ECCV 2020 Oral, Best Paper Honorable Mention

v2 [cs.CV] 3 Aug 2020

NeRF: Representing Scenes as Neural Radiance Fields for View Synthesis

Ben Mildenhall^{1*} Pratul P. Srinivasan^{1*} Matthew Tancik^{1*}
Jonathan T. Barron² Ravi Ramamoorthi³ Ren Ng¹

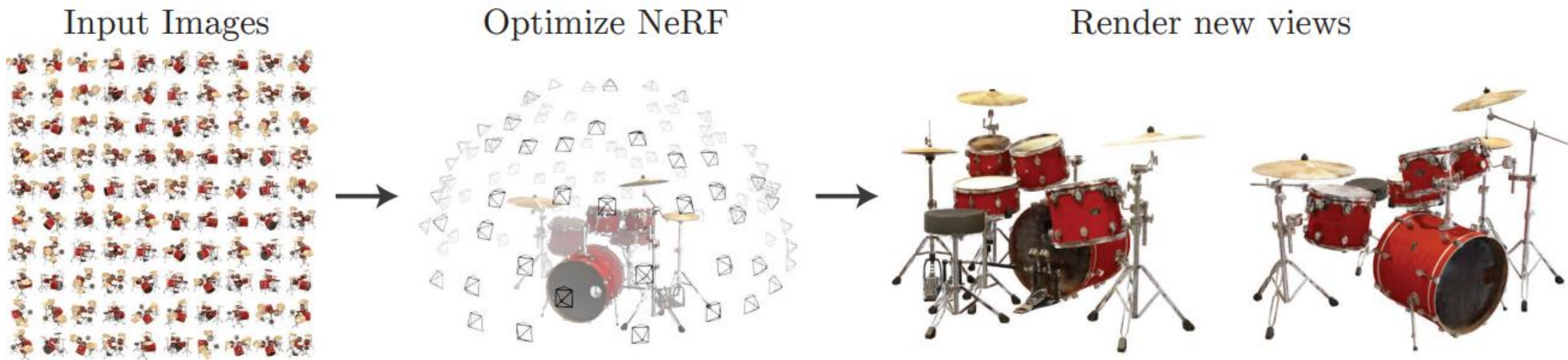
¹UC Berkeley ²Google Research ³UC San Diego

Abstract. We present a method that achieves state-of-the-art results for synthesizing novel views of complex scenes by optimizing an underlying continuous volumetric scene function using a sparse set of input views. Our algorithm represents a scene using a fully-connected (non-convolutional) deep network, whose input is a single continuous 5D coordinate (spatial location (x, y, z) and viewing direction (θ, ϕ)) and whose

NeRF

▶ 목표

- ▶ 1. 다양한 위치와 방향에서 사진 촬영.
- ▶ 2. Structure from Motion을 통해 카메라 파라미터 추출.
- ▶ 3. 학습 및 렌더링을 통해 새로운 시점에서의 장면을 생성.



네트워크 구조

▶ 9개의 Fully Connected Layer

▶ ReLU

▶ 256차원으로 구성된 Feature

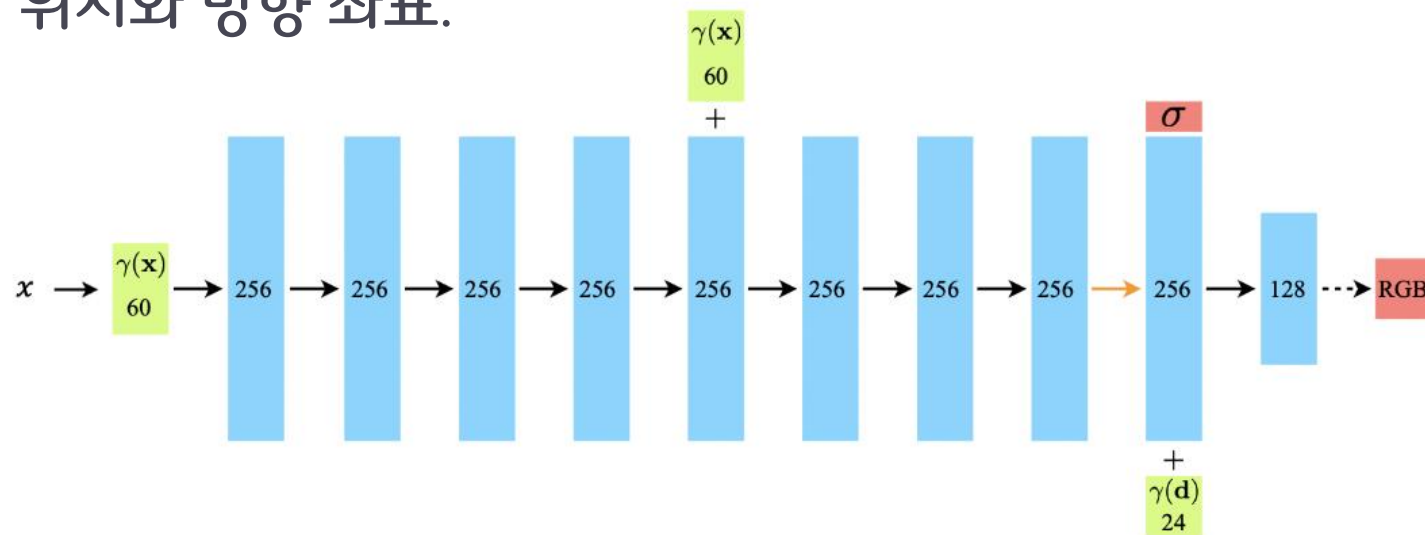
▶ Green box

$$\gamma(p) = (\sin(2^0 \pi p), \cos(2^0 \pi p), \dots, \sin(2^{L-1} \pi p), \cos(2^{L-1} \pi p))$$

▶ **Positional encoding**된 위치와 방향 좌표.

▶ Red box

▶ Color와 Density를 출력.

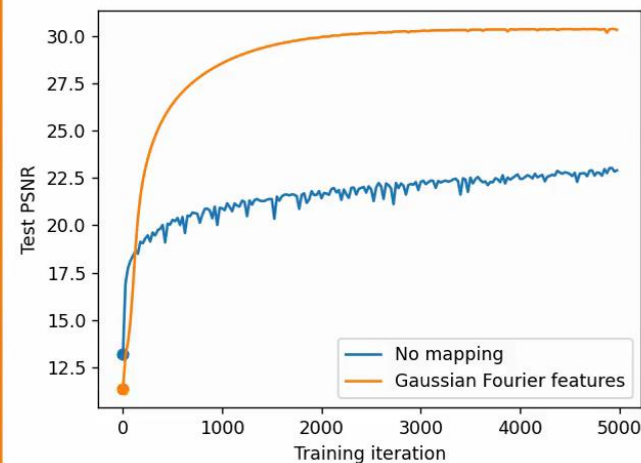
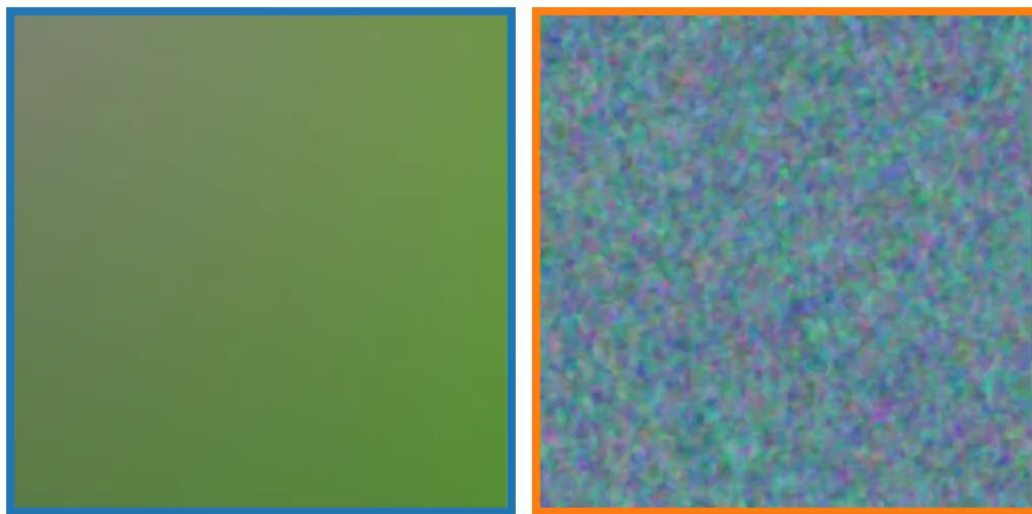
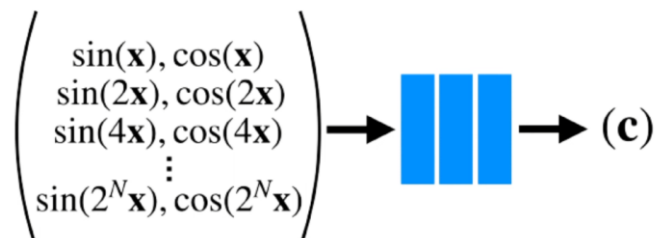


Positional encoding 이 하는 일.

No Positional encoding



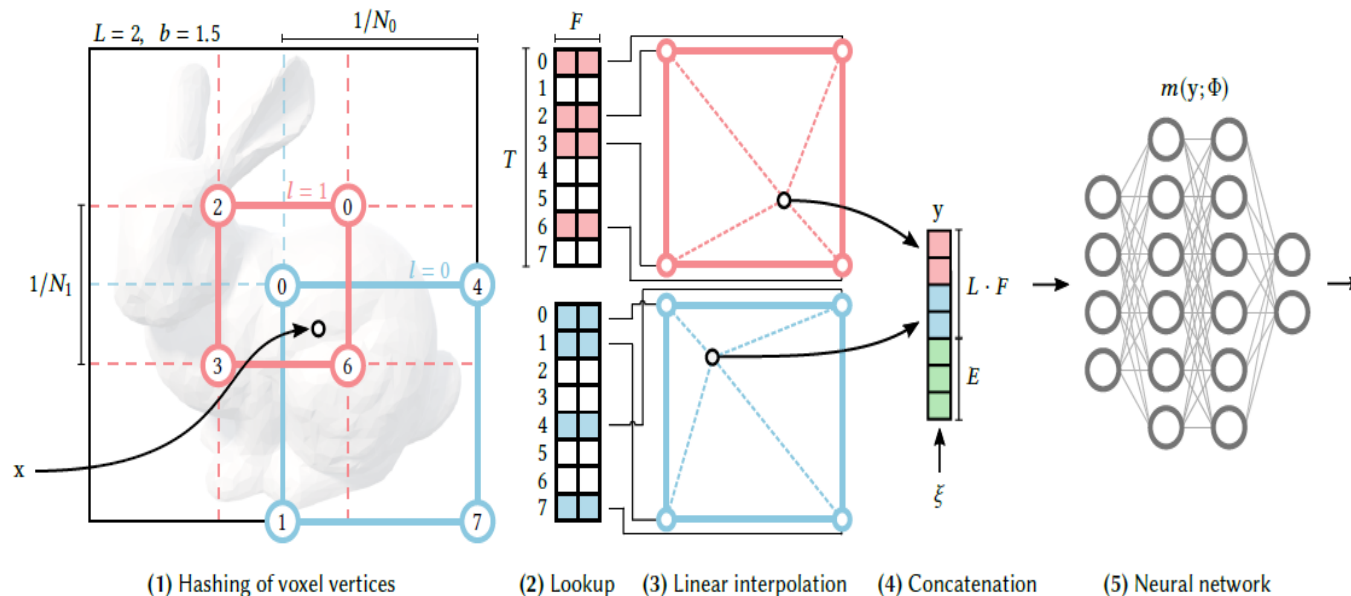
Positional encoding



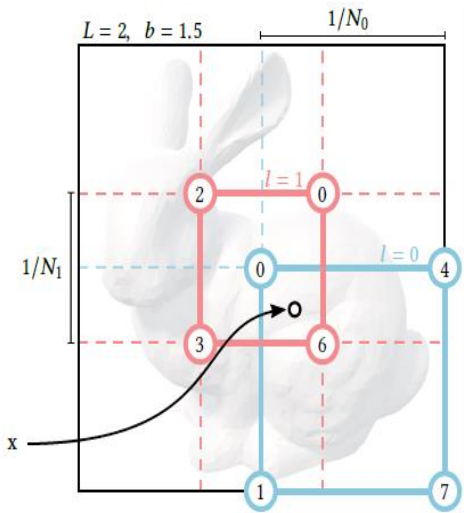
No Positional encoding **Positional encoding**

Main contribution in Instant NeRF

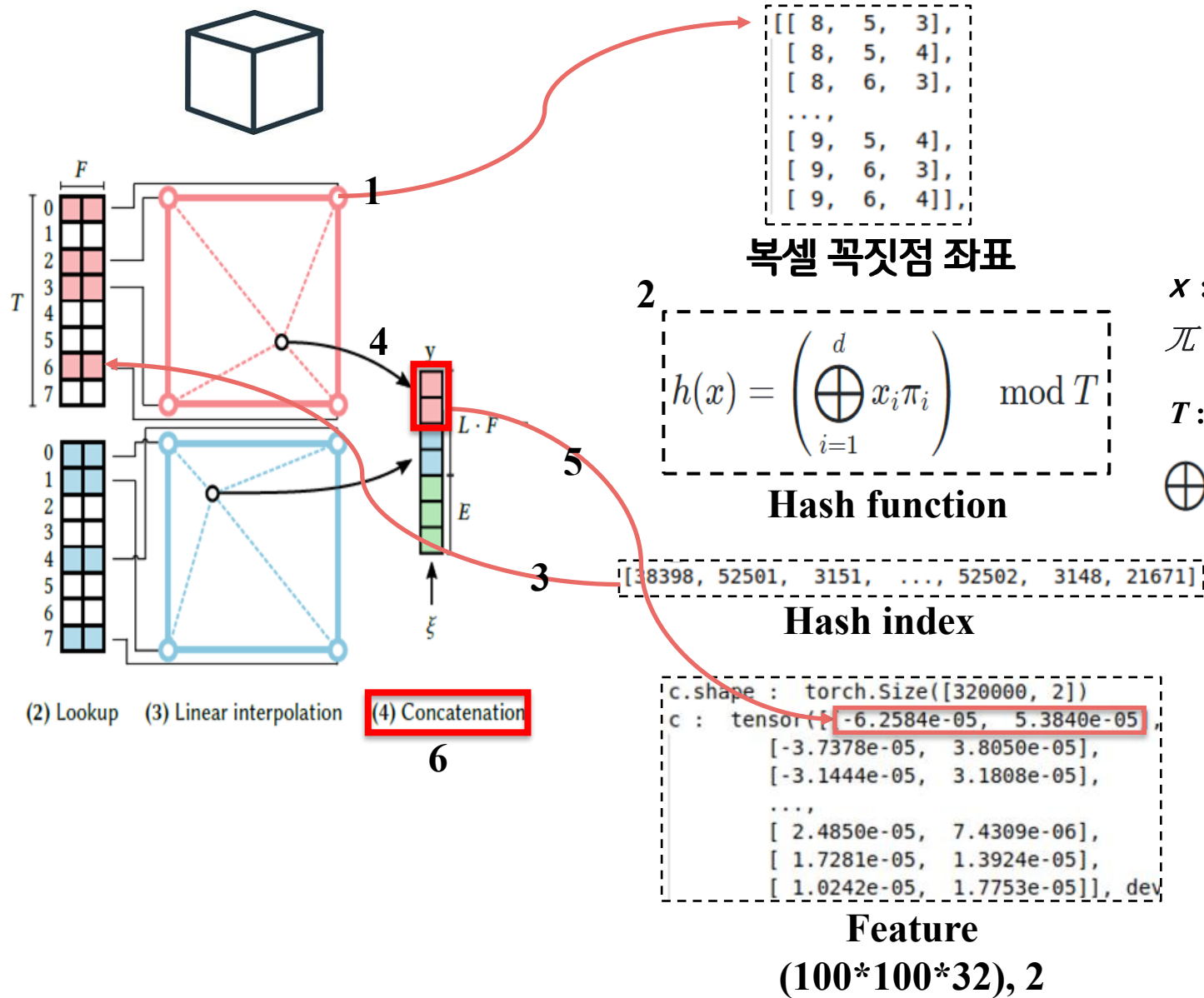
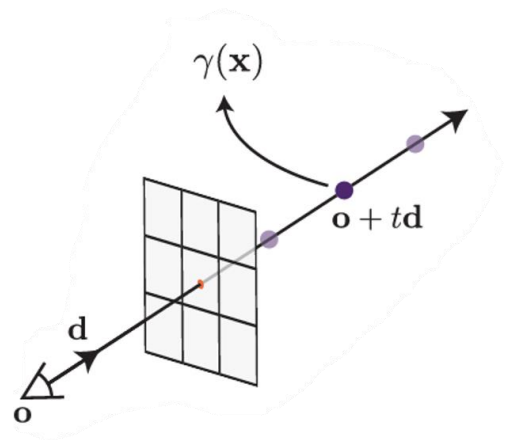
- ▶ **Positional encoding 대신에 Multi-resolution Hash Encoding 적용**
 - ▶ 보다 빠르게 NeRF를 학습하고 해상도를 높임.
 - ▶ 추가로, CUDA, C++ 기반의 cuda-tiny-nn library와 Simple MLP를 통해 더 빠른 속도 가능.



Multi-resolution Hash Encoding



(1) Hashing of voxel vertices



x : 샘플 포인트 x, y, z 위치 값

π : 매우 큰 소수 값

ex) 2,654,435,761

T : Hash의 크기 제한

ex) 2^{16}

\oplus : Exclusive OR

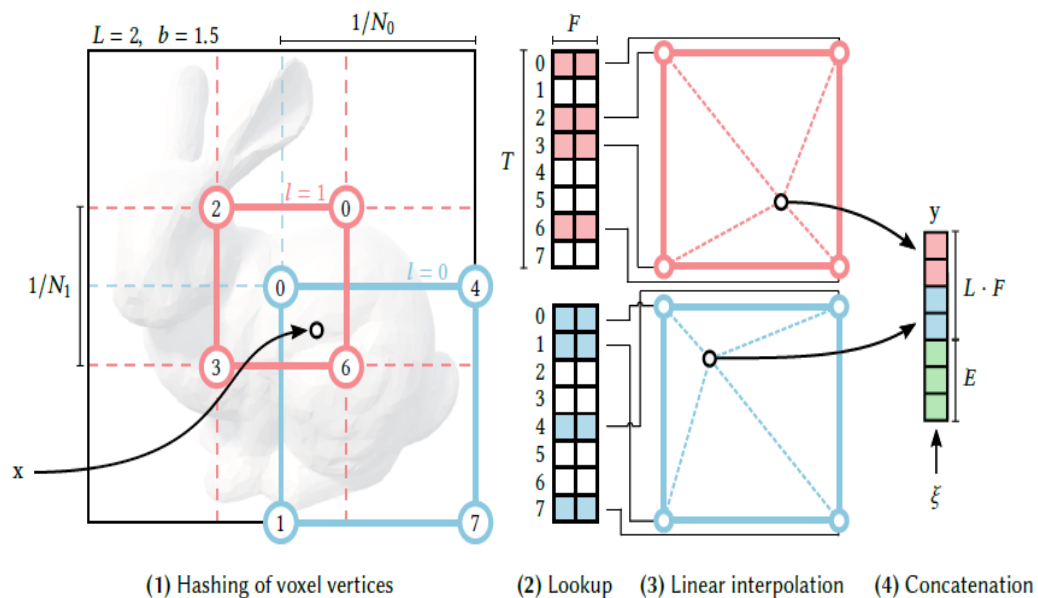


Table 1. Hash encoding parameters and their ranges in our results. Only the hash table size T and max. resolution N_{\max} need to be tuned to the task.

Parameter	Symbol	Value
Number of levels	L	16
Max. entries per level (hash table size)	T	2^{14} to 2^{24}
Number of feature dimensions per entry	F	2
Coarsest resolution	N_{\min}	16
Finest resolution	N_{\max}	512 to 524288

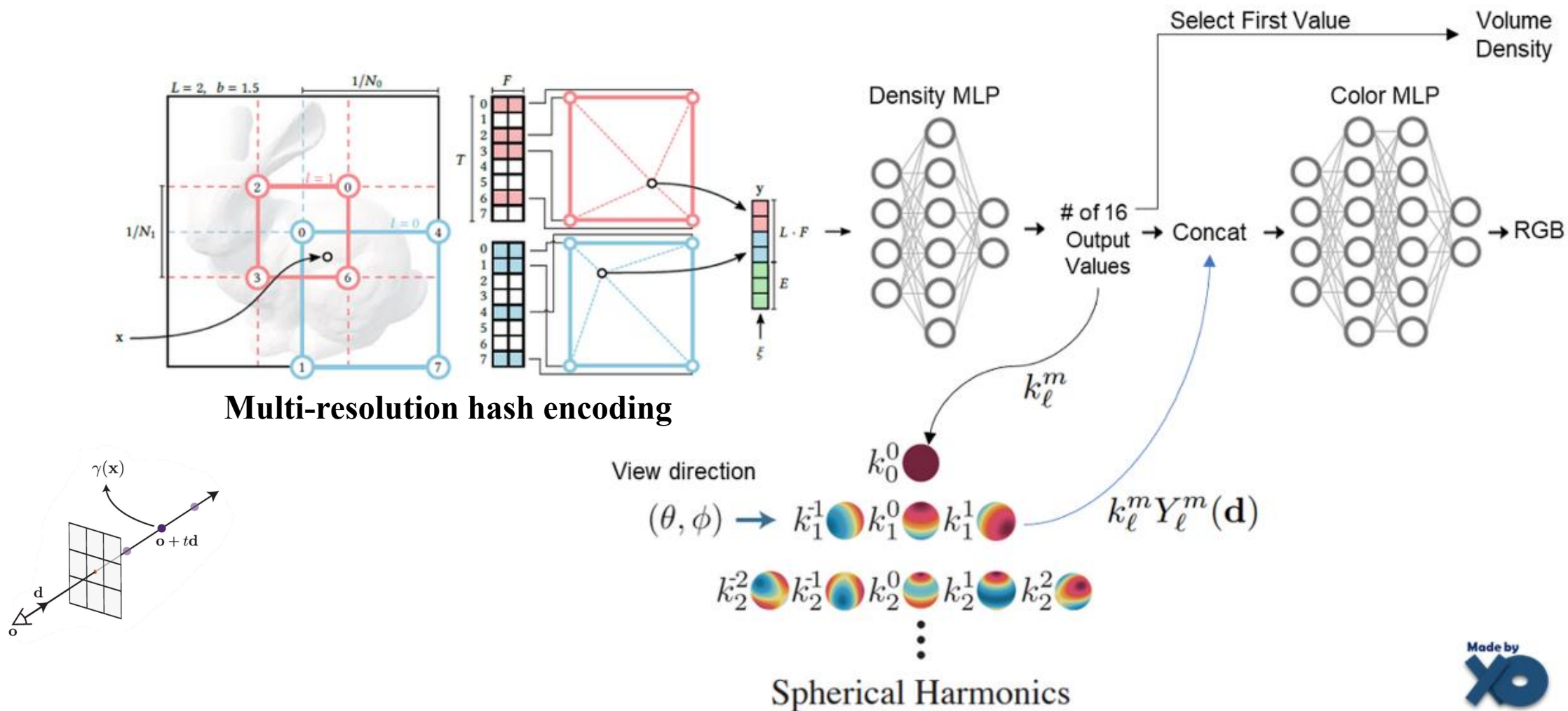
$L :=$ Number of Levels

$N_{\min} :=$ Coarsest Resolution

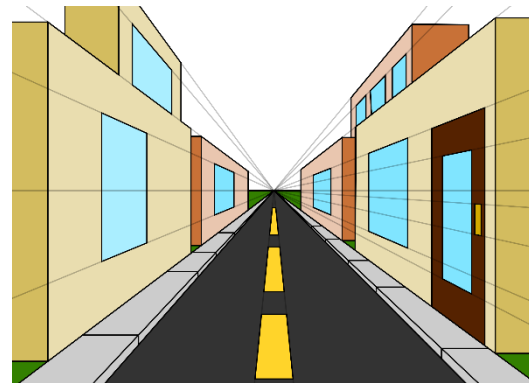
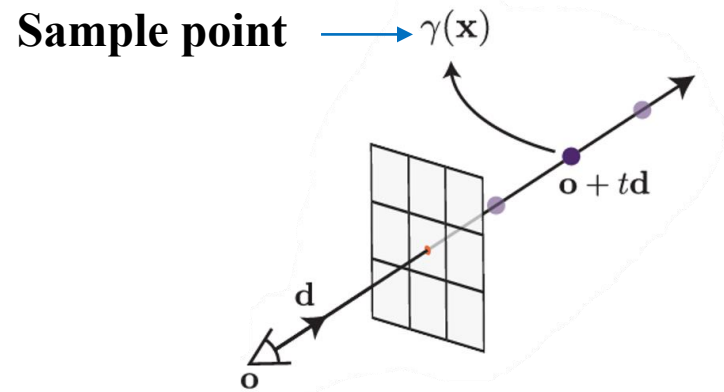
$N_{\max} :=$ Finest Resolution

$$b := \exp \left(\frac{\ln N_{\max} - \ln N_{\min}}{L - 1} \right)$$

Instant NeRF 의 Pipeline



Volume rendering and Loss Function



▶ Volume rendering

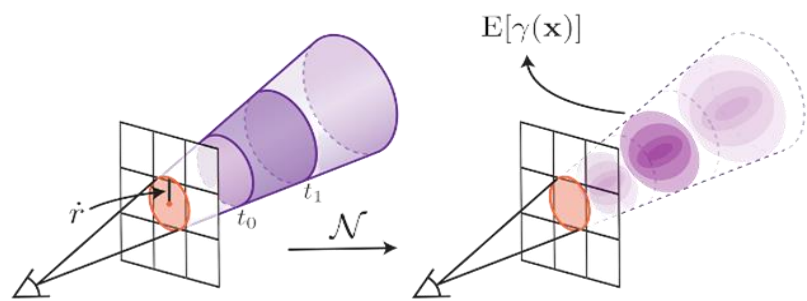
$$C(\mathbf{r}) = \int_{t_n}^{\text{far}} \underbrace{T(t)}_{\text{Transmittance}} \underbrace{\sigma(\mathbf{r}(t))}_{\text{Density}} \underbrace{\mathbf{c}(\mathbf{r}(t), \mathbf{d})}_{\text{Color}} dt, \quad \text{where } T(t) = \exp\left(-\int_{t_n}^t \sigma(\mathbf{r}(s)) ds\right)$$

Color near Density Color

▶ Loss Function

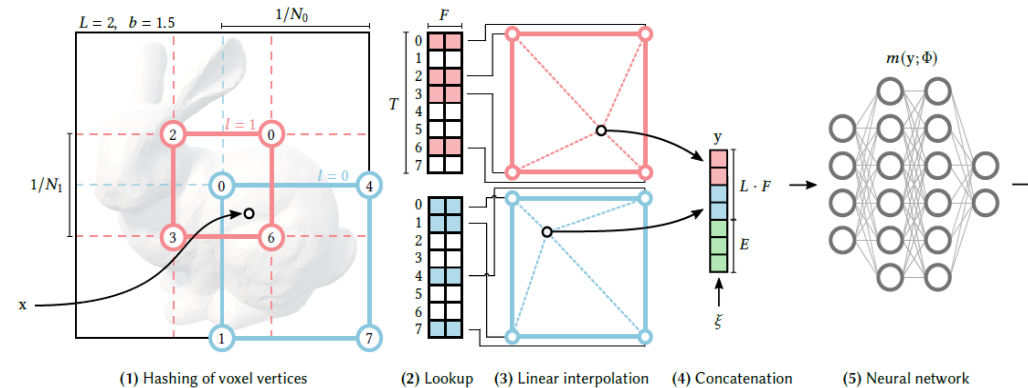
$$\mathcal{L} = \sum_{\mathbf{r} \in \mathcal{R}} \left[\left\| \underbrace{\hat{C}_c(\mathbf{r})}_{\text{Coarse}} - C(\mathbf{r}) \right\|_2^2 + \left\| \underbrace{\hat{C}_f(\mathbf{r})}_{\text{Fine}} - C(\mathbf{r}) \right\|_2^2 \right]$$

현재의 SOTA, Zip-NeRF

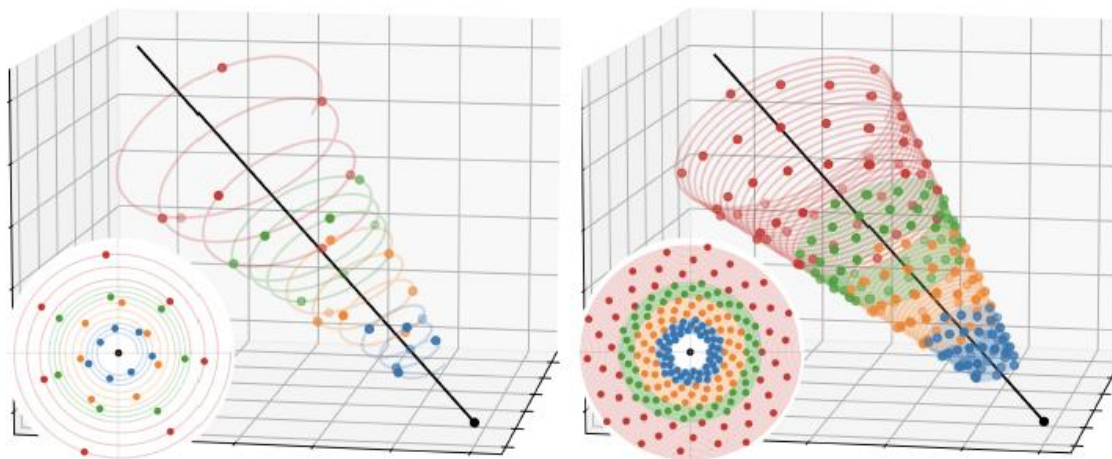


**Cone Tracing
in Mip-NeRF360**

+



**Multi-resolution hash encoding
in Instant NGP**



**Zip-NeRF
arXiv, April 2023**

